

# Contents

<b>1</b>	<b>Estimates for matrix operators</b>	1
1.0	Introduction	1
1.0.1	Description of results	1
1.0.2	Outline of the proof of the main result	5
1.1	Estimates for systems of ordinary differential operators on a semi-axis	12
1.1.1	Some assumptions and notation	12
1.1.2	Transformation of the basic inequality	13
1.1.3	The simplest lower bound of the constant $\Lambda$	14
1.1.4	On solutions of the system $\mathcal{P}_+(-i d/dt) I \varphi = 0$	15
1.1.5	Properties of the matrix $T(\tau)$	19
1.1.6	Integral representation for $\hat{S}(-i d/dt) \psi$	21
1.1.7	Properties of the matrix $G(\tau)$	24
1.1.8	A quadratic functional	27
1.1.9	Necessary and sufficient conditions for the validity of inequality (1.1.1)	29
1.1.10	On condition 4 of Theorem 1.1.19	32
1.1.11	Matrix $G(\tau)$ for estimates with a “large” number of boundary operators	35
1.1.12	Explicit representations of the matrix $G(\tau)$	37
1.1.13	Estimates for vector functions satisfying homogeneous boundary conditions	38
1.1.14	Estimates for vector functions without boundary conditions	39
1.2	Estimates in a half-space. Necessary and sufficient conditions	40
1.2.1	Basic assumptions and notation	41
1.2.2	Theorems on necessary and sufficient conditions for the validity of the estimates in a half-space	43
1.2.3	Matrix $G(\xi; \tau)$ and its properties	45
1.2.4	The case of a single boundary operator	48
1.2.5	The case of a polynomial $\mathcal{P}(\xi; \tau)$ with roots in the half-plane $\text{Im } \zeta \leq 0$	50
1.2.6	Estimates of the types (1.2.1), (1.2.12), (1.2.13) in the norms $\ \cdot\ _{\nu}$ and $\langle\langle \cdot \rangle\rangle_{\mu}$	50
1.2.7	The case, where the lower-order terms have no influence	53
1.3	Estimates in a half-space. Sufficient conditions	57
1.3.1	Sufficient condition for the validity of the estimate (1.3.1)	58
1.3.2	The case $\mathfrak{M}(\xi) = \mathcal{T}_+^{-1/2}(\xi)$	60
1.3.3	The case of the diagonal matrix $\mathfrak{M}(\xi)$	65
1.3.4	Sufficient conditions for the validity of the estimate (1.3.21)	66

1.4	Examples	69
1.4.1	Generalized-homogeneous quasielliptic systems	69
1.4.2	The Lamé system of the static elasticity theory	72
1.4.3	The Cauchy–Riemann system	74
1.4.4	The stationary linearized Navier–Stokes system	76
1.4.5	Hyperbolic systems	77
1.4.6	Operators of first order in the variable $t$ . Scalar case	80
1.4.7	An example of a second-order operator w.r.t. $t$	82
1.5	On well-posed boundary value problems in a half-space	84
1.6	Notes	89
<b>2</b>	<b>Boundary estimates for differential operators</b>	<b>93</b>
2.0	Introduction	93
2.0.1	Description of results	93
2.0.2	Outline of the proof of the main result	95
2.1	Estimates for ordinary differential operators on the semi-axis	99
2.1.1	A lemma on polynomials	100
2.1.2	A variational problem in finite-dimensional space	106
2.1.3	Reduction of the estimate for ordinary differential operators on the semi-axis to a variational problem in a finite-dimensional space	110
2.1.4	Two properties of the matrix $\mathfrak{B}$	114
2.1.5	An estimate without boundary operators in the right-hand side	115
2.1.6	Necessary and sufficient conditions for the validity of inequality (2.1.1)	117
2.1.7	Estimates for functions satisfying homogeneous boundary conditions	119
2.2	Estimates in a half-space. Necessary and sufficient conditions	122
2.2.1	Theorems on necessary and sufficient conditions for the validity of the estimates in a half-space	123
2.2.2	Corollaries	125
2.2.3	The case when the lower-order terms play no role	128
2.2.4	An example of estimate for operators of first order with respect to $t$	130
2.3	Description of the trace space	133
2.3.1	Preliminary results	133
2.3.2	Embedding and extensions theorems	137
2.3.3	On the extension of functions from $\mathcal{H}(\mathbb{R}^n)$ to $\mathcal{H}(\mathbb{R}_+^n)$	141
2.4	Notes	144
<b>3</b>	<b>Dominance of differential operators</b>	<b>145</b>
3.0	Introduction	145
3.0.1	Description of results	145
3.0.2	Remarks on the method of proving the main result	147

3.1	Estimates for ordinary differential operators on the semi-axis . . . . .	149
3.1.1	A variational problem in a finite-dimensional space . . . . .	150
3.1.2	The simplest lower bound for the constant $\Lambda$ . . . . .	153
3.1.3	Reduction of the estimates for ordinary differential operators on the semi-axis to variational problems in a finite-dimensional space . . . . .	154
3.1.4	Necessary and sufficient conditions for the validity of inequalities (3.1.1) and (3.1.1') . . . . .	158
3.1.5	Inequalities for functions without boundary conditions . . . . .	161
3.2	Estimates in a half-space. Necessary and sufficient conditions . . . . .	162
3.2.1	Necessary and sufficient conditions for the validity of the estimates (3.0.1), (3.0.2), and (3.0.1') . . . . .	162
3.2.2	On the minimal number and algebraic properties of the boundary operators; formulas for $\beta_\alpha(\xi; \eta)$ . . . . .	165
3.2.3	Estimates for polynomials whose $\tau$ -roots lie in the lower complex half-plane . . . . .	168
3.3	Examples . . . . .	169
3.3.1	The theorem of N. Aronszajn on necessary and sufficient conditions for the coercivity of a system of operators . . . . .	169
3.3.2	The case $m = 1$ , $N = N(\xi)$ in Theorems 3.2.2, 3.2.3, and 3.2.4	170
3.3.3	Examples of estimates for operators of first order with respect to $t$ . . . . .	174
3.4	Notes . . . . .	177
<b>4</b>	<b>Estimates for a maximal operator . . . . .</b>	<b>179</b>
4.0	Introduction . . . . .	179
4.1	Preliminary results . . . . .	181
4.1.1	Results concerning the estimate (4.0.1) . . . . .	181
4.1.2	Results concerning the estimate (4.0.2) . . . . .	185
4.2	Quasielliptic polynomials . . . . .	187
4.2.1	Polynomials with a generalized-homogeneous principal part . . . . .	187
4.2.2	The estimate (4.2.16) for quasielliptic polynomials of type $l \geq 1$ . . . . .	190
4.2.3	The estimate (4.2.19) for quasielliptic polynomials of type $l \geq 1$ . . . . .	192
4.3	Homogeneous polynomials with simple roots . . . . .	195
4.3.1	Asymptotic representations of the $\tau$ -roots of the polynomial $H_+(\xi; \tau)$ as $ \xi  \rightarrow \infty$ . . . . .	196
4.3.2	Necessary and sufficient conditions for the validity of the estimate (4.2.16) . . . . .	197
4.3.3	Necessary and sufficient conditions for the validity of the estimate (4.2.19) . . . . .	201
4.4	Some classes of nonhomogeneous polynomials with simple roots . . . . .	204
4.4.1	A formula for the function $\Lambda(\xi)$ . . . . .	205
4.4.2	Asymptotic representations as $N \rightarrow \infty$ for the $\tau$ -roots $\zeta_j(\xi)$ of the polynomial $H_+(\xi; \tau)$ . . . . .	205

4.4.3	An asymptotic representation of the function $\Lambda(\xi)$ as $N \rightarrow \infty$ for polynomials $P$ with the real $\tau$ -roots . . . . .	208
4.4.4	Necessary and sufficient conditions for the validity of the estimates (4.0.1), (4.0.2) for a polynomial $P$ with real $\tau$ -roots . . . . .	210
4.4.5	An asymptotic representation of the function $\Lambda(\xi)$ as $N \rightarrow \infty$ for a polynomial $P$ with the $\tau$ -roots lying in the half-plane $\text{Im } \zeta < 0$ . . . . .	211
4.4.6	Necessary and sufficient conditions for the validity of the estimates (4.0.1), (4.0.2) for a polynomial $P$ with the $\tau$ -roots lying in the half-plane $\text{Im } \zeta < 0$ . . . . .	213
4.4.7	An asymptotic representation of the function $\Lambda(\xi)$ as $N \rightarrow \infty$ for a polynomial $P$ with the $\tau$ -roots lying in the half-plane $\text{Im } \zeta > 0$ . . . . .	214
4.4.8	Necessary and sufficient conditions for the validity of the estimates (4.0.1), (4.0.2) for a polynomial $P$ with the $\tau$ -roots lying in the half-plane $\text{Im } \zeta > 0$ . . . . .	215
4.5	Second-order polynomials of $\tau$ . . . . .	217
4.5.1	Preliminary results . . . . .	217
4.5.2	The case $p_1(\xi) \equiv 0$ . . . . .	219
4.5.3	The case $\text{Im } p_k(\xi) \equiv 0$ ( $k = 0, 1, 2$ ) . . . . .	221
4.5.4	The estimate (4.2.16) in the case $\text{Re } p_1(\xi) \equiv 0, \text{Im } p_k(\xi) \equiv 0$ ( $k = 0, 2$ ) . . . . .	222
4.6	Space of traces of functions for the maximal operator . . . . .	226
4.6.1	The maximal operator as closure of its restriction on the set of functions infinitely differentiable up to the boundary . . . . .	227
4.6.2	Description of the “trace space” . . . . .	229
4.7	Notes . . . . .	233
<b>Notation</b> . . . . .		235
<b>Bibliography</b> . . . . .		239
<b>Index</b> . . . . .		243