

Appendix A

Absolute continuity with respect to the shifted measure

A.1 Preliminary lemmas

In this appendix, we prove that the Φ_3^3 -measure ρ in the weakly nonlinear regime ($|\sigma| \ll 1$), constructed in Theorem 1.2.1 (i), is absolutely continuous with respect to the shifted measure $\text{Law}(Y(1) + \sigma \mathfrak{Z}(1) + \mathcal{W}(1))$, where Y is as in (3.1.2), \mathfrak{Z} is defined as the limit of the antiderivative of $\dot{\mathfrak{Z}}^N$ in (3.2.3) as $N \rightarrow \infty$, and the auxiliary process \mathcal{W} is defined by

$$\mathcal{W}(t) = (1 - \Delta)^{-1} \int_0^t \langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} (\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} Y(t'))^5 dt' \quad (\text{A.1.1})$$

for some small $\varepsilon > 0$. For the proof, we construct a drift as in the discussion in [4, Section 3]. See also [54, Appendix C]. The coercive term \mathcal{W} is introduced to guarantee global existence of a drift on the time interval $[0, 1]$. See Lemma A.1.2 below. We closely follow the presentation in Appendix C of our previous work [54].

First, we recall the following general lemma, giving a criterion for absolute continuity. See [54, Lemma C.1] for the proof.

Lemma A.1.1. *Let μ_n and ρ_n be probability measures on a Polish space X . Suppose that μ_n and ρ_n converge weakly to μ and ρ , respectively. Furthermore, suppose that for every $\varepsilon > 0$, there exist $\delta(\varepsilon) > 0$ and $\eta(\varepsilon) > 0$ with $\delta(\varepsilon), \eta(\varepsilon) \rightarrow 0$ as $\varepsilon \rightarrow 0$ such that for every continuous function $F : X \rightarrow \mathbb{R}$ with $0 < \inf F \leq F \leq 1$ satisfying*

$$\mu_n(\{F \leq \varepsilon\}) \geq 1 - \delta(\varepsilon)$$

for any $n \geq n_0(F)$, we have

$$\limsup_{n \rightarrow \infty} \int F(u) d\rho_n(u) \leq \eta(\varepsilon).$$

Then, ρ is absolutely continuous with respect to μ .

By regarding $\dot{\mathfrak{Z}}^N$ in (3.2.3) and \mathcal{W} in (A.1.1) as functions of Y , we write them as

$$\begin{aligned} \dot{\mathfrak{Z}}^N(Y)(t) &= (1 - \Delta)^{-1} : Y_N^2(t) :, \\ \mathcal{W}(Y)(t) &= (1 - \Delta)^{-1} \int_0^t \langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} (\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} Y(t'))^5 dt' \end{aligned} \quad (\text{A.1.2})$$

and we set $\dot{\mathfrak{Z}}_N(Y) = \pi_N \dot{\mathfrak{Z}}^N(Y)$. Then, from (A.1.2), we have

$$\dot{\mathfrak{Z}}_N(Y + \Theta) - \dot{\mathfrak{Z}}_N(Y) = (1 - \Delta)^{-1} \pi_N (2\Theta_N Y_N + \Theta_N^2), \quad (\text{A.1.3})$$

where $\Theta_N = \pi_N \Theta$. We also define $\mathcal{W}_N(Y)(t)$ by

$$\mathcal{W}_N(Y)(t) = (1 - \Delta)^{-1} \pi_N \int_0^t \langle \nabla \rangle^{-\frac{1}{2} - \varepsilon} (\langle \nabla \rangle^{-\frac{1}{2} - \varepsilon} Y_N(t'))^5 dt'. \quad (\text{A.1.4})$$

Next, we state a lemma on the construction of a drift Θ .

Lemma A.1.2. *Let $\sigma \in \mathbb{R}$ and $\dot{\Upsilon} \in L^2([0, 1]; H^1(\mathbb{T}^3))$. Then, given any $N \in \mathbb{N}$, the Cauchy problem for Θ :*

$$\begin{cases} \dot{\Theta} + \sigma(1 - \Delta)^{-1} \pi_N (2\Theta_N Y_N + \Theta_N^2) + \mathcal{W}_N(Y + \Theta) - \dot{\Upsilon} = 0 \\ \Theta(0) = 0 \end{cases} \quad (\text{A.1.5})$$

is almost surely globally well-posed on the time interval $[0, 1]$ such that a solution Θ belongs to $C([0, 1]; H^1(\mathbb{T}^3))$. Moreover, if $\|\dot{\Upsilon}\|_{L^2([0, \tau]; H_x^1)}^2 \leq M$ for some $M > 0$ and for some stopping time $\tau \in [0, 1]$, then, for any $1 \leq p < \infty$, there exists $C = C(M, p) > 0$ such that

$$\mathbb{E}[\|\dot{\Theta}\|_{L^2([0, \tau]; H_x^1)}^p] \leq C(M, p), \quad (\text{A.1.6})$$

where $C(M, p)$ is independent of $N \in \mathbb{N}$.

A.2 Absolute continuity

In this section, we prove the absolute continuity of the Φ_3^3 -measure ρ with respect to $\text{Law}(Y(1) + \sigma \mathfrak{Z}(1) + \mathcal{W}(1))$ by assuming Lemma A.1.2. We present the proof of Lemma A.1.2 at the end of this appendix. For simplicity, we use the same shorthand notations as in Chapters 3 and 4, for instance, $Y = Y(1)$, $\mathfrak{Z} = \mathfrak{Z}(1)$, $\mathcal{W} = \mathcal{W}(1)$, and $\mathcal{W}_N = \mathcal{W}_N(1)$.

Given $L \gg 1$, let $\delta(L)$ and $R(L)$ satisfy $\delta(L) \rightarrow 0$ and $R(L) \rightarrow \infty$ as $L \rightarrow \infty$, which will be specified later. In view of Lemma A.1.1, it suffices to show that if $G : \mathcal{C}^{-100}(\mathbb{T}^3) \rightarrow \mathbb{R}$ is a bounded continuous function with $G > 0$ and

$$\mathbb{P}(\{G(Y + \sigma \mathfrak{Z}_N + \mathcal{W}_N) \geq L\}) \geq 1 - \delta(L), \quad (\text{A.2.1})$$

then we have

$$\limsup_{N \rightarrow \infty} \int \exp(-G(u)) d\rho_N(u) \leq \exp(-R(L)), \quad (\text{A.2.2})$$

where ρ_N denotes the truncated Φ_3^3 -measure defined in (1.2.11). Here, think of $\text{Law}(Y + \sigma \mathfrak{Z}_N + \mathcal{W}_N)$ as the measure μ_N , weakly converging to $\mu = \text{Law}(Y + \sigma \mathfrak{Z} + \mathcal{W})$.

By the Boué–Dupuis variational formula (Lemma 3.1.1) and the change of variables (3.2.4), we have

$$\begin{aligned}
 & -\log\left(\int \exp(-G(u) - R_N^\diamond(u))d\mu(u)\right) \\
 &= \inf_{\dot{\Upsilon}^N \in \mathbb{H}_a^1} \mathbb{E}\left[G(Y + \Upsilon^N + \sigma\mathfrak{Z}_N) + \widehat{R}_N^\diamond(Y + \Upsilon^N + \sigma\mathfrak{Z}_N) \right. \\
 &\quad \left. + \frac{1}{2} \int_0^1 \|\dot{\Upsilon}^N(t)\|_{H_x^1}^2 dt\right],
 \end{aligned}$$

where \widehat{R}_N^\diamond is as in (3.2.25). We proceed as in Section 3.2, using Lemmas 3.2.2 and 3.2.3 with Lemma 3.1.2, (3.2.17), and the smallness of $|\sigma|$. See (3.2.9), (3.2.16), and (3.2.19). Thus, we have

$$\begin{aligned}
 & -\log\left(\int \exp(-G(u) - R_N^\diamond(u))d\mu(u)\right) \\
 & \geq \inf_{\dot{\Upsilon}^N \in \mathbb{H}_a^1} \mathbb{E}\left[G(Y + \Upsilon^N + \sigma\mathfrak{Z}_N) + \frac{1}{20} \int_0^1 \|\dot{\Upsilon}^N(t)\|_{H_x^1}^2 dt\right] - C_1 \quad (\text{A.2.3})
 \end{aligned}$$

for some constant $C_1 > 0$. For $\dot{\Upsilon}^N \in \mathbb{H}_a^1$, let Θ^N be the solution to (A.1.5) with $\dot{\Upsilon}$ replaced by $\dot{\Upsilon}^N$. For any $M > 0$, define the stopping time τ_M as

$$\begin{aligned}
 \tau_M = \min\left(1, \min\left\{\tau : \int_0^\tau \|\dot{\Upsilon}^N(t)\|_{H_x^1}^2 dt = M\right\}, \right. \\
 \left. \min\left\{\tau : \int_0^\tau \|\dot{\Theta}^N(t)\|_{H_x^1}^2 dt = 2C(M, 2)\right\}\right), \quad (\text{A.2.4})
 \end{aligned}$$

where $C(M, 2)$ is the constant appearing in (A.1.6) with $p = 2$. Let

$$\Theta_M^N(t) := \Theta^N(\min(t, \tau_M)). \quad (\text{A.2.5})$$

From (3.1.2), we have $Y(0) = 0$, while $\mathfrak{Z}^N(0) = 0$ by definition. Then, from the change of variables (3.2.4) with $\Theta(0) = 0$, we see that $\Upsilon^N(0) = 0$. We also have $\mathcal{W}_N(0) = 0$ from (A.1.4). Then, substituting (A.1.3) into (A.1.5) and integrating from $t = 0$ to 1 gives

$$Y + \Upsilon^N + \sigma\mathfrak{Z}_N = Y + \Theta_M^N + \sigma\mathfrak{Z}_N(Y + \Theta_M^N) + \mathcal{W}_N(Y + \Theta_M^N) \quad (\text{A.2.6})$$

on the set $\{\tau_M = 1\}$.

From the definition (A.2.5) with (A.2.4), we have

$$\|\dot{\Theta}_M^N\|_{L_t^2([0,1]; H_x^1)}^2 \leq 2C(M, 2) \quad (\text{A.2.7})$$

and thus the Novikov condition is satisfied. Then, Girsanov’s theorem [21, Theorem 10.14] yields that $\text{Law}(Y + \Theta_M^N)$ is absolutely continuous with respect to

Law(Y); see (A.2.10) below. Let $\mathbb{Q} = \mathbb{Q}^{\dot{\Theta}_M^N}$ the probability measure whose Radon–Nikodym derivative with respect to \mathbb{P} is given by the following stochastic exponential:

$$\frac{d\mathbb{Q}}{d\mathbb{P}} = e^{-\int_0^1 \langle \dot{\Theta}_M^N(t), dY(t) \rangle_{H_x^1} - \frac{1}{2} \int_0^1 \|\dot{\Theta}_M^N(t)\|_{H_x^1}^2 dt} \quad (\text{A.2.8})$$

such that, under this new measure \mathbb{Q} , the process

$$W^{\dot{\Theta}_M^N}(t) = W(t) + \langle \nabla \rangle \dot{\Theta}_M^N(t) = \langle \nabla \rangle (Y + \dot{\Theta}_M^N)(t)$$

is a cylindrical Wiener process on $L^2(\mathbb{T}^3)$. By setting

$$Y^{\dot{\Theta}_M^N}(t) = \langle \nabla \rangle^{-1} W^{\dot{\Theta}_M^N}(t),$$

we have

$$Y^{\dot{\Theta}_M^N}(t) = Y(t) + \Theta_M^N(t). \quad (\text{A.2.9})$$

Moreover, from Cauchy–Schwarz inequality with (A.2.8) and the bound (A.2.7), and then (A.2.9), we have

$$\begin{aligned} \mathbb{P}(\{Y + \Theta_M^N \in E\}) &= \int \mathbf{1}_{\{Y + \Theta_M^N \in E\}} \frac{d\mathbb{P}}{d\mathbb{Q}} d\mathbb{Q} \leq C_M \left(\mathbb{Q}(\{Y^{\dot{\Theta}_M^N} \in E\}) \right)^{\frac{1}{2}} \\ &= C_M (\mathbb{P}(\{Y \in E\}))^{\frac{1}{2}} \end{aligned} \quad (\text{A.2.10})$$

for any measurable set E .

From (A.2.3), (A.2.6), and the non-negativity of G , we have

$$\begin{aligned} (\text{A.2.3}) &\geq \inf_{\dot{\Upsilon}^N \in \mathbb{H}_a^1} \mathbb{E} \left[\left(G(Y + \Theta_M^N + \sigma \mathfrak{Z}_N(Y + \Theta_M^N) + \mathcal{W}_N(Y + \Theta_M^N)) \right. \right. \\ &\quad \left. \left. + \frac{1}{20} \int_0^1 \|\dot{\Upsilon}^N(t)\|_{H_x^1}^2 dt \right) \mathbf{1}_{\{\tau_M=1\}} \right. \\ &\quad \left. + \left(G(Y + \Upsilon^N + \sigma \mathfrak{Z}_N) \right. \right. \\ &\quad \left. \left. + \frac{1}{20} \int_0^1 \|\dot{\Upsilon}^N(t)\|_{H_x^1}^2 dt \right) \mathbf{1}_{\{\tau_M < 1\}} \right] - C_1 \\ &\geq \inf_{\dot{\Upsilon}^N \in \mathbb{H}_a^1} \mathbb{E} \left[G(Y + \Theta_M^N + \sigma \mathfrak{Z}_N(Y + \Theta_M^N) + \mathcal{W}_N(Y + \Theta_M^N)) \cdot \mathbf{1}_{\{\tau_M=1\}} \right. \\ &\quad \left. + \frac{1}{20} \int_0^1 \|\dot{\Upsilon}^N(t)\|_{H_x^1}^2 dt \cdot \mathbf{1}_{\{\tau_M < 1\}} \right] - C_1. \end{aligned}$$

Then, using the definition (A.2.4) of the stopping time τ_M and applying (A.2.10) and (A.2.1), we have

$$\begin{aligned}
 (\text{A.2.3}) &\geq \inf_{\dot{\Upsilon}^N \in \mathbb{H}_a^1} \mathbb{E} \left[L \cdot \mathbf{1}_{\{\tau_M=1\} \cap \{G(Y+\Theta_M^N + \sigma \mathfrak{Z}_N(Y+\Theta_M^N) + \mathfrak{W}_N(Y+\Theta_M^N)) \geq L\}} \right. \\
 &\quad \left. + \frac{M}{20} \cdot \mathbf{1}_{\{\tau_M < 1\} \cap \left\{ \int_0^1 \|\dot{\Theta}_M^N(t)\|_{H_x^1}^2 dt < 2C(M,2) \right\}} \right] - C_1 \\
 &\geq \inf_{\dot{\Upsilon}^N \in \mathbb{H}_a^1} \left\{ L(\mathbb{P}(\{\tau_M = 1\}) - C_M \delta(L)^{\frac{1}{2}}) \right. \\
 &\quad \left. + \frac{M}{20} \mathbb{P} \left(\{\tau_M < 1\} \cap \left\{ \int_0^1 \|\dot{\Theta}_M^N(t)\|_{H_x^1}^2 dt < 2C(M,2) \right\} \right) \right\} - C_1.
 \end{aligned} \tag{A.2.11}$$

In view of (A.1.6) with (A.2.4) and (A.2.5), Markov's inequality gives

$$\mathbb{P} \left(\int_0^1 \|\dot{\Theta}_M^N(t)\|_{H_x^1}^2 dt = \int_0^{\tau_M} \|\dot{\Theta}_M^N(t)\|_{H_x^1}^2 dt \geq 2C(M,2) \right) \leq \frac{1}{2},$$

which yields

$$\mathbb{P} \left(\{\tau_M < 1\} \cap \left\{ \int_0^1 \|\dot{\Theta}_M^N(t)\|_{H_x^1}^2 dt < 2C(M,2) \right\} \right) \geq \mathbb{P}(\{\tau_M < 1\}) - \frac{1}{2}. \tag{A.2.12}$$

Now, we set $M = 20L$. Note from (A.2.4) that $\mathbb{P}(\{\tau_M = 1\}) + \mathbb{P}(\{\tau_M < 1\}) = 1$. Then, from (A.2.11) and (A.2.12), we obtain

$$\begin{aligned}
 &-\log \left(\int \exp(-G(u) - R_N^\diamond(u)) d\mu(u) \right) \\
 &\geq \inf_{\dot{\Upsilon}^N \in \mathbb{H}_a^1} \left\{ L(\mathbb{P}(\{\tau_M = 1\}) - C'_L \delta(L)^{\frac{1}{2}}) + L \left(\mathbb{P}(\{\tau_M < 1\}) - \frac{1}{2} \right) \right\} - C_1 \\
 &= L \left(\frac{1}{2} - C'_L \delta(L)^{\frac{1}{2}} \right) - C_1.
 \end{aligned}$$

Therefore, by choosing $\delta(L) > 0$ such that $C'_L \delta(L)^{\frac{1}{2}} \rightarrow 0$ as $L \rightarrow \infty$, this shows (A.2.2) with

$$R(L) = L \left(\frac{1}{2} - C'_L \delta(L)^{\frac{1}{2}} \right) - C_1 + \log Z,$$

where $Z = \lim_{N \rightarrow \infty} Z_N$ denotes the limit of the partition functions for the truncated Φ_3^3 -measures ρ_N .

A.3 Proof of Lemma A.1.2

We conclude this appendix by presenting the proof of Lemma A.1.2.

Proof of Lemma A.1.2. By Lemma 2.1.3 (ii) and Sobolev's inequality, we have

$$\begin{aligned}
 & \|(1 - \Delta)^{-1}(2\Theta_N Y_N + \Theta_N^2)(t)\|_{H_x^1} \\
 & \lesssim \|(2\Theta_N Y_N + \Theta_N^2)(t)\|_{H_x^{-1}} \\
 & \lesssim \|\Theta_N(t)\|_{H_x^{\frac{1}{2}+\varepsilon}} \|Y_N(t)\|_{W_x^{-\frac{1}{2}-\varepsilon,\infty}} + \|\Theta_N^2(t)\|_{L_x^{\frac{6}{5}}} \\
 & \lesssim \|\Theta_N(t)\|_{H_x^1} \|Y_N(t)\|_{W_x^{-\frac{1}{2}-\varepsilon,\infty}} + \|\Theta_N(t)\|_{H_x^1}^2 \tag{A.3.1}
 \end{aligned}$$

for small $\varepsilon > 0$. Moreover, from (A.1.1), we have

$$\begin{aligned}
 \|\dot{\mathcal{W}}_N(Y(t) + \Theta(t))\|_{H_x^1} & \lesssim \|\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} Y_N(t)\|_{L_x^\infty}^5 + \|\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} \Theta_N(t)\|_{L_x^\infty}^5 \\
 & \lesssim \|Y_N(t)\|_{W_x^{-\frac{1}{2}-\varepsilon,\infty}}^5 + \|\Theta_N(t)\|_{H_x^1}^5. \tag{A.3.2}
 \end{aligned}$$

Therefore, by studying the integral formulation of (A.1.5), a contraction argument in $L^\infty([0, T]; H^1(\mathbb{T}^3))$ for small $T > 0$ with (A.3.1) and (A.3.2) yields local well-posedness. Here, the local existence time T depends on $\|\Theta(0)\|_{H^1}$, $\|\dot{\Upsilon}\|_{L_T^2 H_x^1}$, and $\|Y_N\|_{L_T^6 W_x^{-\frac{1}{2}-\varepsilon,\infty}}$, where the last term is almost surely bounded in view of Lemma 3.1.2 and (2.1.4).

Next, we prove global existence on $[0, 1]$ by establishing an a priori bound on the H^1 -norm of a solution. From (A.1.5) with (A.1.4), we have

$$\begin{aligned}
 \frac{1}{2} \frac{d}{dt} \|\Theta(t)\|_{H^1}^2 & = -\sigma \int_{\mathbb{T}^3} (2\Theta_N(t)Y_N(t) + \Theta_N^2(t))\Theta_N(t) dx \\
 & \quad - \int_{\mathbb{T}^3} (\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} (Y_N(t) + \Theta_N(t)))^5 \cdot \langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} \Theta_N(t) dx \\
 & \quad + \int_{\mathbb{T}^3} \langle \nabla \rangle \Theta(t) \cdot \langle \nabla \rangle \dot{\Upsilon}(t) dx. \tag{A.3.3}
 \end{aligned}$$

The second term on the right-hand side of (A.3.3), coming from \mathcal{W} is a coercive term, allowing us to hide part of the first term on the right-hand side.

From Lemma 2.1.1 and Young's inequality, we have

$$\begin{aligned}
 & \left| \int_{\mathbb{T}^3} (2\Theta_N(t)Y_N(t) + \Theta_N^2(t))\Theta_N(t) dx \right| \\
 & \lesssim \|\Theta_N(t)\|_{H^1}^2 + \|\Theta_N(t)\|_{L^3}^3 + \|Y_N(t)\|_{C^{\frac{1}{2}-\varepsilon}}^c \tag{A.3.4}
 \end{aligned}$$

for small $\varepsilon > 0$ and some $c > 0$. We now estimate the second term on the right-hand side of (A.3.4). By (2.1.3), we have

$$\begin{aligned}
 \|\Theta_N(t)\|_{L^3}^3 & \lesssim \|\Theta_N(t)\|_{H^1}^{\frac{3+6\varepsilon}{3+2\varepsilon}} \|\Theta_N(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}}^{\frac{6}{3+2\varepsilon}} \\
 & \leq \|\Theta_N(t)\|_{H^1}^2 + \varepsilon_0 \|\Theta_N(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}}^6 + C_{\varepsilon_0} \tag{A.3.5}
 \end{aligned}$$

for small $\varepsilon, \varepsilon_0 > 0$. As for the coercive term, from (3.2.32) and Young's inequality, we have

$$\begin{aligned}
 & \int_{\mathbb{T}^3} (\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} (Y_N(t) + \Theta_N(t)))^5 \langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} \Theta_N(t) dx \\
 & \geq \frac{1}{2} \int_{\mathbb{T}^3} (\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} \Theta_N(t))^6 dx \\
 & \quad - c \int_{\mathbb{T}^3} |(\langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} Y_N(t))^5 \langle \nabla \rangle^{-\frac{1}{2}-\varepsilon} \Theta_N(t)| dx \\
 & \geq \frac{1}{2} \|\Theta_N(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}}^6 - c \|Y_N(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}}^5 \|\Theta_N(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}} \\
 & \geq \frac{1}{4} \|\Theta_N(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}}^6 - c \|Y_N(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}}^6. \tag{A.3.6}
 \end{aligned}$$

Therefore, putting (A.3.3), (A.3.4), (A.3.5), and (A.3.6) together we obtain

$$\frac{d}{dt} \|\Theta(t)\|_{H^1}^2 \lesssim \|\Theta(t)\|_{H^1}^2 + \|\dot{\Upsilon}(t)\|_{H^1}^2 + \|Y(t)\|_{\mathcal{C}^{-\frac{1}{2}-\varepsilon}}^c + \|Y(t)\|_{W^{-\frac{1}{2}-\varepsilon,6}}^6 + 1.$$

By Gronwall's inequality, we then obtain

$$\begin{aligned}
 \|\Theta(t)\|_{H^1}^2 & \lesssim \|\dot{\Upsilon}\|_{L^2([0,t];H_x^1)}^2 + \|Y_N\|_{L^c([0,1];\mathcal{C}_x^{-\frac{1}{2}-\varepsilon})}^c \\
 & \quad + \|Y\|_{L^6([0,1];W_x^{-\frac{1}{2}-\varepsilon,6})}^6 + 1, \tag{A.3.7}
 \end{aligned}$$

uniformly in $0 \leq t \leq 1$. The a priori bound (A.3.7) together with Lemma 3.1.2 allows us to iterate the local well-posedness argument, guaranteeing existence of the solution Θ on $[0, 1]$.

Lastly, we prove the bound (A.1.6). From (A.3.1), (A.3.2), and (A.3.7), we have

$$\begin{aligned}
 & \|\sigma(1 - \Delta)^{-1} (2\Theta_N Y_N + \Theta_N^2) + \dot{\mathcal{W}}_N(Y + \Theta)\|_{L^2([0,\tau];H_x^1)} \\
 & \lesssim \|\dot{\Upsilon}\|_{L^2([0,\tau];H_x^1)}^5 + \|Y_N\|_{L^q([0,1];\mathcal{C}_x^{-\frac{1}{2}-\frac{1}{2}\varepsilon})}^{c_0} + 1 \tag{A.3.8}
 \end{aligned}$$

for some finite $q, c_0 \geq 1$ and for any $0 \leq \tau \leq 1$. Then, using the equation (A.1.5), the bound (A.1.6) follows from (A.3.8), the bound on $\dot{\Upsilon}$, and the following corollary to Lemma 3.1.2:

$$\mathbb{E} \left[\|Y_N\|_{L^q([0,1];\mathcal{C}_x^{-\frac{1}{2}-\frac{1}{2}\varepsilon})}^p \right] < \infty$$

for any finite $p, q \geq 1$, uniformly in $N \in \mathbb{N}$. ■

Remark A.3.1. A slight modification of the argument presented above shows that the tamed Φ_3^3 -measure ν_δ constructed in Proposition 4.1.1 is absolutely continuous with respect to the shifted measure $\text{Law}(Y(1) + \sigma\mathfrak{Z}(1) + \mathcal{W}(1))$. In this setting, we

can use the analysis in Section 4.2 (Step 1 of the proof of Proposition 4.1.1) to arrive at (A.2.3). The rest of the argument remains unchanged. As a consequence, the σ -finite version $\bar{\rho}_\delta$ of the Φ_3^3 -measure defined in (4.1.9) is also absolutely continuous with respect to the shifted measure $\text{Law}(Y(1) + \sigma\mathfrak{Z}(1) + \mathcal{W}(1))$ for any $\delta > 0$.