

Chapter 8

Link surgery modules over \mathcal{K} and \mathcal{L}

In this chapter, we describe some basic link surgery modules over the algebras \mathcal{K} and \mathcal{L} . We begin by defining the type-D and type-A modules for a solid torus and the algebraic merge module. Subsequently, we interpret the knot and link surgery formulas as type-D modules over \mathcal{K} and \mathcal{L} .

8.1 The type-D module for a solid torus

If λ is an integer, we refer to the complement of a λ -framed unknot in S^3 as the λ -framed solid torus. We will define a type-D module $\mathcal{D}_\lambda^{\mathcal{K}}$ for the λ -framed solid torus as follows. We set

$$\mathcal{D}_\lambda^{\mathcal{K}} \cdot \mathbf{I}_0 = \langle \mathbf{x}^0 \rangle \quad \text{and} \quad \mathcal{D}_\lambda^{\mathcal{K}} \cdot \mathbf{I}_1 = \langle \mathbf{x}^1 \rangle,$$

where $\langle \mathbf{x}^\varepsilon \rangle = \mathbb{F}$, spanned by a generator \mathbf{x}^ε . Here, $\varepsilon \in \{0, 1\}$ denotes the idempotent. We define the structure map via the formula

$$\delta^1(\mathbf{x}^0) = \mathbf{x}^1 \otimes (\sigma + \mathcal{V}^n \tau).$$

8.2 The type-A module for a solid torus

Suppose that λ is an integer. We now define the type-A module $\mathcal{K}\mathcal{D}_\lambda$ for the solid torus as follows. We set

$$\mathbf{I}_0 \cdot \mathcal{D}_\lambda = \mathbb{F}[\mathcal{U}, \mathcal{V}] \quad \text{and} \quad \mathbf{I}_1 \cdot \mathcal{D}_\lambda = \mathbb{F}[\mathcal{U}, \mathcal{V}, \mathcal{V}^{-1}].$$

We define the type-A structure map m_j on \mathcal{D}_λ to be 0 unless $j = 2$. We define m_2 on \mathcal{D}_λ as follows. If $f \in \mathbf{I}_i \cdot \mathcal{K} \cdot \mathbf{I}_i$ and $x \in \mathbf{I}_j \cdot \mathcal{D}_j$, then we define $m_2(f, x)$ to be $f \cdot x$ (ordinary multiplication of polynomials) if $i = j$ and to be 0 otherwise. If $x \in \mathbf{I}_0 \cdot \mathcal{D}_\lambda$, we define

$$m_2(\sigma, x) = \phi^\sigma(x) \in \mathbb{F}[\mathcal{U}, \mathcal{V}, \mathcal{V}^{-1}] = \mathbf{I}_1 \cdot \mathcal{D}_\lambda,$$

where ϕ^σ is the canonical inclusion of localization. Similarly, we define

$$m_2(\tau, x) = \mathcal{V}^\lambda \cdot \phi^\tau(x) \in \mathbb{F}[\mathcal{U}, \mathcal{V}, \mathcal{V}^{-1}],$$

where \cdot denotes ordinary multiplication of polynomials.

We view \mathcal{D}_λ as being the direct sum of the 1-dimensional spans of monomials, and give \mathcal{D}_λ the product topology with respect to this decomposition. See Definition 5.6. With respect to this topology, the completion is given by

$$\mathbf{I}_0 \cdot \mathcal{D}_\lambda = \mathbb{F}[[\mathcal{U}, \mathcal{V}]], \quad \text{and} \quad \mathbf{I}_1 \cdot \mathcal{D}_\lambda = \mathbb{F}[[\mathcal{U}, \mathcal{V}, \mathcal{V}^{-1}]].$$

(Note that the latter object is defined only as a vector space, and not as a ring, since we are taking completions with respect to \mathcal{V} and \mathcal{V}^{-1} .)

Lemma 8.1. *The map*

$$m_2: \mathcal{K} \overset{\sim}{\otimes}_1 \mathcal{D}_\lambda \rightarrow \mathcal{D}_\lambda$$

is continuous.

Proof. Write \mathcal{D} for \mathcal{D}_λ . Continuity amounts to two claims. The first is that if $E \subseteq \mathcal{D}$ is an open subspace, then there is some n so that $m_2(J_n \otimes \mathcal{D}) \subseteq E$. Additionally, we need to show that if E is as above and $a \in \mathcal{K}$, then there is some open $V_a \subseteq \mathcal{D}$ so that $m_2(a \otimes V_a) \subseteq E$. By definition, we may assume that E is $\mathcal{D}_{\text{co}(S)}$ for some finite set of basis elements in \mathcal{D} . (Recall that $\mathcal{D}_{\text{co}(S)}$ is the span of the basis elements not in S .)

For the first claim, it suffices to show that if n is sufficiently large, then $J_n \otimes \mathcal{D}$ is mapped into $\mathcal{D}_{\text{co}(S)}$. This may be proven by considering each idempotent of \mathcal{K} separately. To ensure $(\mathbf{I}_0 \cdot J_n \cdot \mathbf{I}_0) \otimes \mathcal{D}$ is sent into $\mathcal{D}_{\text{co}(S)}$, it is sufficient to pick n larger than $\max(p, q)$ ranging over all monomials $\mathcal{U}^p \mathcal{V}^q$ appearing in $\mathbf{I}_0 \cdot S$. For $(\mathbf{I}_1 \cdot J_n \cdot \mathbf{I}_1) \otimes \mathcal{D}$ to be sent into $\mathcal{D}_{\text{co}(S)}$, we pick n larger than p for each monomial $\mathcal{U}^p \mathcal{V}^q$ appearing in $\mathbf{I}_1 \cdot S$. Finally, to ensure that $(\mathbf{I}_1 \cdot J_n \cdot \mathbf{I}_0) \otimes \mathcal{D}$ is sent into $\mathcal{D}_{\text{co}(S)}$, it is sufficient to pick n larger than $\max(p, q, 2p - q)$, ranging over monomials $\mathcal{U}^p \mathcal{V}^q$ appearing in a summand of $\mathbf{I}_1 \cdot S$. To see that this is sufficient, note that if $\mathcal{U}^i \mathcal{V}^j \tau \otimes \mathcal{U}^s \mathcal{V}^t \in J_n \otimes \mathcal{D}$, then $\max(i, 2i - j) \geq n$. We observe that $\mathcal{U}^i \mathcal{V}^j \tau \mathcal{U}^s \mathcal{V}^t = \mathcal{U}^{i+t} \mathcal{V}^{j-s+2t} \tau$ lies in $\mathcal{D}_{\text{co}(S)}$, since

$$\max(i + t, 2(i + t) - (j - s + 2t)) = \max(i + t, 2i - j + s) \geq \max(i, 2i - j) \geq n.$$

The fact that $\mathcal{U}^i \mathcal{V}^j \sigma \otimes \mathcal{U}^s \mathcal{V}^t \in J_n \otimes \mathcal{D}$ is sent into $\mathcal{D}_{\text{co}(S)}$ is similar.

Next, we need to show that if $a \in \mathcal{K}$ is fixed, then there is a finite subset T of generators of \mathcal{D} so that $a \otimes \mathcal{D}_{\text{co}(T)}$ is mapped into $\mathcal{D}_{\text{co}(S)}$. Without loss of generality, we assume that a is a monomial. We observe the following basic fact: if $a \in \mathbf{I}_\varepsilon \cdot \mathcal{K} \cdot \mathbf{I}_\varepsilon$ and $y \in \mathbf{I}_{\varepsilon'} \cdot \mathcal{D}$ are non-zero monomials, then there is at most 1 (in particular, finitely many) $x \in \mathbf{I}_\varepsilon \cdot \mathcal{D}$ such that $m_2(a, x) = y$. In particular, there exists a finite set of generators T such that $a \otimes \mathcal{D}_{\text{co}(T)}$ is sent into $\mathcal{D}_{\text{co}(S)}$, completing the proof. \blacksquare

Remark 8.2. Note that m_2 is *not* continuous as a map from $\mathcal{K} \overset{\sim}{\otimes} \mathcal{D}$ to \mathcal{D} . Compare Remark 7.6. In fact, m_2 does not induce a map from the completion of $\mathcal{K} \overset{\sim}{\otimes} \mathcal{D}_\lambda$

to \mathcal{D}_λ . For example, in the completion of $\mathcal{K} \otimes^! \mathcal{D}_\lambda$ the sum $\sum_{i=0}^\infty \mathcal{V}^i \otimes \mathcal{V}^{-i} i_1$ converges since $\mathcal{V}^{-i} i_1 \rightarrow 0$ in the topology of \mathcal{D}_λ , while m_2 cannot be defined on such infinite sums.

The module for a solid torus extends to a type-AA bimodule

$$\mathcal{K}[\mathcal{D}_\lambda]_{\mathbb{F}[U]}.$$

Here, we have U act on the right via polynomial multiplication with $\mathcal{U}\mathcal{V}$ (summed over both idempotents). Since $[\mathcal{U}\mathcal{V}, \tau] = 0$ and $[\mathcal{U}\mathcal{V}, \sigma] = 0$, the construction above defines an AA-bimodule structure on \mathcal{D}_λ . Note that only $m_{1,1,0}$ and $m_{0,1,1}$ are non-trivial.

Additionally, we can also think of the module for a solid torus as corresponding instead to a DA bimodule $\mathcal{K}[\mathcal{D}_\lambda]_{\mathbb{F}[U]}$, in such a way that

$$\mathcal{K}[\mathcal{D}_\lambda]_{\mathbb{F}[U]} \hat{\boxtimes}_{\mathbb{F}[U]} \mathbb{F}[U]_{\mathbb{F}[U]} \cong \mathcal{K}[\mathcal{D}_\lambda]_{\mathbb{F}[U]}.$$

For this description, the generators of $\mathbf{I}_0 \cdot \mathcal{K}[\mathcal{D}_\lambda]_{\mathbb{F}[U]}$ are \mathcal{U}^i and \mathcal{V}^j for $i, j \geq 0$. The generators of $\mathbf{I}_1 \cdot \mathcal{K}[\mathcal{D}_\lambda]_{\mathbb{F}[U]}$ are \mathcal{V}^i for $i \in \mathbb{Z}$. This module has $\delta_j^1 = 0$ unless $j = 2$. We illustrate the structure map δ_2^1 of $\mathcal{K}[\mathcal{D}_0]_{\mathbb{F}[U]}$ in Figure 8.1 and leave the structure relations to the reader for other framings.

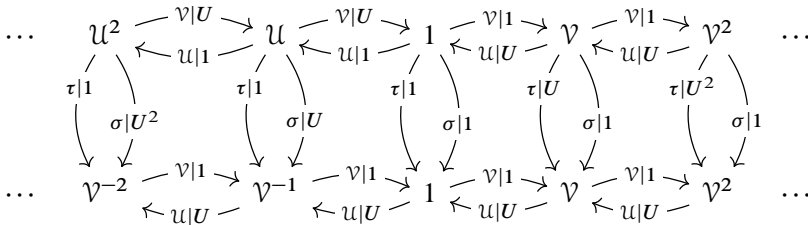


Figure 8.1. The DA bimodule $\mathcal{K}[\mathcal{D}_0]_{\mathbb{F}[U]}$. An arrow decorated with $a|b$ from \mathbf{x} to \mathbf{y} means that $\delta_2^1(a, \mathbf{x}) = \mathbf{y} \otimes b$.

8.3 The merge bimodule

In this section, we define a bimodule $\mathcal{K}_{|\mathcal{K}} M^{\mathcal{K}}$, which we call the *merge bimodule*.

Whenever R is a commutative algebra over \mathbb{F} , there is a morphism of algebras $\phi: R \otimes_{\mathbb{F}} R \rightarrow R$, given by $\phi(a \otimes b) = ab$. A ring homomorphism $\psi: A \rightarrow B$ always determines a bimodule ${}_A[\psi]^B$ whose underlying vector space is the ground ring, and has structure map $\delta_1^1 = 0$ and $\delta_2^1(a \otimes 1) = 1 \otimes \psi(a)$. In particular, there is a natural bimodule ${}_{R \otimes R}[\phi]^R$ for any commutative ring R .

The algebra \mathcal{K} is not commutative, though the bimodule ${}_{\mathcal{K}|\mathcal{K}}M^{\mathcal{K}}$ is somewhat analogous.

We now describe the bimodule M . To make the notation clear, in this section we will write $|$ for $\otimes_{\mathbb{F}}$ and \otimes for $\otimes_{\mathbb{I}}$.

As a vector space, M is $\mathbf{I} = \mathbf{I}_0 \oplus \mathbf{I}_1$. There is a left action of $\mathbf{I}|\mathbf{I}$, given by

$$(i_1|i_2) \cdot i = i_1 i_2 \cdot i.$$

The right \mathbf{I} -action is the standard action.

On M , only δ_2^1 and δ_3^1 are non-trivial. The map δ_2^1 is defined as follows. Suppose that $a_1|a_2$ is an elementary tensor in either

$$(\mathbf{I}_0|\mathbf{I}_0) \cdot (\mathcal{K}|\mathcal{K}) \cdot (\mathbf{I}_0|\mathbf{I}_0) \quad \text{or} \quad (\mathbf{I}_1|\mathbf{I}_1) \cdot (\mathcal{K}|\mathcal{K}) \cdot (\mathbf{I}_1|\mathbf{I}_1).$$

In this case, we set

$$\delta_2^1(a_1|a_2 \otimes i) = i \otimes a_1 a_2.$$

On any other elementary tensor, we set δ_2^1 to vanish.

We define δ_3^1 as follows. We set

$$\delta_3^1(1|\sigma, \sigma|1 \otimes i_0) = i_1 \otimes \sigma \quad \text{and} \quad \delta_3^1(1|\tau, \tau|1 \otimes i_0) = i_1 \otimes \tau.$$

More generally, if a, b, c, d are monomials concentrated in single idempotents, then we set

$$\delta_3^1(a|b\sigma, c\sigma|d, i_0) = i_0 \otimes abc\sigma d$$

and similarly for the τ terms. We set

$$\delta_3^1(\sigma|1, 1|\sigma \otimes i_0) = 0,$$

and similarly if τ replaces σ . The DA bimodule relations are straightforward to verify.

Lemma 8.3. *The merge module ${}_{\mathcal{K}|\mathcal{K}}M^{\mathcal{K}}$ is a split Alexander module (using the discrete partition on the two incoming algebra factors).*

Remark 8.4. The structure maps of the merge module are *not* continuous when we view the bimodule as a non-split module over $\mathcal{K} \otimes^! \mathcal{K}$ or $\mathcal{K} \otimes^* \mathcal{K}$, i.e., as ${}_{\mathcal{K} \otimes^! \mathcal{K}}M^{\mathcal{K}}$ or ${}_{\mathcal{K} \otimes^* \mathcal{K}}M^{\mathcal{K}}$. To see this, observe that discontinuity with respect to the topology on $\mathcal{K} \otimes_{\mathbb{F}}^* \mathcal{K}$ implies discontinuity with respect to $\mathcal{K} \otimes_{\mathbb{F}}^! \mathcal{K}$ since there is a continuous map $\mathcal{K} \otimes_{\mathbb{F}}^* \mathcal{K} \rightarrow \mathcal{K} \otimes_{\mathbb{F}}^! \mathcal{K}$. Note that a sequence of tensors

$$\mathbf{x}_n = (x_n|y_n) \otimes (z_n|w_n) \in (\mathcal{K} \otimes_{\mathbb{F}}^* \mathcal{K}) \otimes_{\mathbb{E}} (\mathcal{K} \otimes_{\mathbb{F}}^* \mathcal{K})$$

will converge to 0 if x_n is constant in n and $y_n \rightarrow 0$. In particular, we need not make any assumptions about z_n or w_n . We note that $\mathcal{V}^n \sigma \rightarrow 0$ in \mathcal{K} , as each of the ideals

J_m (which form a basis of open sets centered at 0 for our topology on \mathcal{K}) contains $\mathcal{V}^n \sigma$ for all sufficiently large n . Therefore,

$$(1|\mathcal{V}^n \sigma) \otimes (\mathcal{V}^{-n} \sigma|1) \rightarrow 0.$$

On the other hand,

$$\delta_3^1(1|\mathcal{V}^n \sigma, \mathcal{V}^{-n} \sigma|1, i_0) = i_1 \otimes \sigma \not\rightarrow 0,$$

so δ_3^1 is not continuous.

Proof of Lemma 8.3. We consider first δ_2^1 . In this case, the only non-trivial actions on i_0 or i_1 are from pairs $a|b$ where a and b are both in $\mathbf{I}_0 \cdot \mathcal{K} \cdot \mathbf{I}_0$ or both in $\mathbf{I}_1 \cdot \mathcal{K} \cdot \mathbf{I}_1$. In this case, the claim is clear.

We now consider δ_3^1 . Recall that verifying the split Alexander condition amounts to showing that δ_3^1 is continuous if we use the tree topology from Section 5.6 using the following tree:

$$\begin{array}{ccc} \mathcal{K} & \longrightarrow & \mathcal{K} & \searrow & & \mathbf{I} \\ & & & & \nearrow & \\ \mathcal{K} & \longrightarrow & \mathcal{K} & \nearrow & & \end{array}$$

We define a function

$$\tilde{\mu}: \mathcal{K} \otimes_{\mathbb{F}}^* \mathcal{K} \rightarrow \mathcal{K}$$

given on elementary tensors of monomials by

$$\tilde{\mu}(a\sigma, b\sigma) = ab\sigma \quad \text{and} \quad \tilde{\mu}(a\tau, b\tau) = ab\tau,$$

with $\tilde{\mu}$ vanishing on other elementary tensors of monomials. Additionally, we consider a map

$$\Pi: (\mathcal{K} \otimes_{\mathbf{I}} \mathcal{K}) \otimes_{\mathbb{F}} (\mathcal{K} \otimes_{\mathbf{I}} \mathcal{K}) \rightarrow (\mathcal{K} \otimes_{\mathbf{I}} \mathcal{K}) \otimes_{\mathbb{F}} (\mathcal{K} \otimes_{\mathbf{I}} \mathcal{K})$$

such that Π is the identity on the elementary tensors of monomials

$$(a\sigma \otimes a')|(b \otimes b'\sigma) \quad \text{and} \quad (a\tau \otimes a')|(b \otimes b'\tau),$$

and such that Π vanishes on other elementary tensors of monomials.

We observe that

$$\delta_3^1(\mathbf{a}, 1) = 1 \otimes (\tilde{\mu} \circ (\mu_2|\mu_2) \circ \Pi)(\mathbf{a}).$$

The map Π is clearly continuous with respect to the tree topology, and furthermore, $\mu_2|\mu_2$ is continuous by Propositions 7.5 and 5.24. Note that if we topologize $(\mathcal{K}|\mathcal{K}) \otimes_{\mathbf{I}|\mathbf{I}} \mathbf{I}$ with the tree topology, it is isomorphic to $\mathcal{K} \otimes_{\mathbb{F}}^* \mathcal{K}$. (See Remark 5.23.) Hence, it suffices to show that $\tilde{\mu}$ is continuous. This amounts to the following:

(m -1) For each $n \in \mathbb{N}$, there are $k, m \in \mathbb{N}$ so that

$$\tilde{\mu}(J_k \otimes J_m) \subseteq J_n.$$

(m-2) For each $n \in \mathbb{N}$ and $x \in \mathcal{K}$, there is an $m \in \mathbb{N}$ so that

$$\tilde{\mu}(x \otimes J_m) \subseteq J_n \quad \text{and} \quad \tilde{\mu}(J_m \otimes x) \subseteq J_n.$$

Both of the arguments are elementary, and we illustrate the idea. Recall that by our construction in Definition 7.3, $\mathcal{U}^i \mathcal{V}^j \sigma \in J_n$ if and only if $i \geq 0$ and $\max(i, j) \geq n$. If $\mathcal{U}^i \mathcal{V}^j \sigma$ and $\mathcal{U}^s \mathcal{V}^t \sigma$ are two monomials in J_n , then at least one of two situations occurs: both $j, t \geq n$; or one of i and s is at least n . If $j, t \geq n$, then $\mathcal{U}^{i+s} \mathcal{V}^{j+t} \sigma \in J_n$ since $j + t \geq 2n$. If one of i and s is at least n , then $i + s \geq n$. A symmetric analysis holds for the multiples of τ , and we see that

$$\tilde{\mu}(J_n \otimes J_n) \subseteq J_n,$$

so (m-1) holds. A similar and elementary argument implies (m-2). ■

There is an asymmetry in the merge module. Recall that we set

$$\delta_3^1(1|\sigma, \sigma|1, i_0) = i_1 \otimes \sigma \quad \text{and} \quad \delta_3^1(\sigma|1, 1|\sigma, i_0) = 0.$$

We define a different module ${}_{\mathcal{K}|\mathcal{K}}N^{\mathcal{K}}$ by instead setting

$$\delta_3^1(1|\sigma, \sigma|1, i_0) = 0 \quad \text{and} \quad \delta_3^1(\sigma|1, 1|\sigma, i_0) = i_1 \otimes \sigma.$$

We make a similar change to the map δ_3^1 on τ inputs.

This construction turns out to produce homotopy equivalent bimodules.

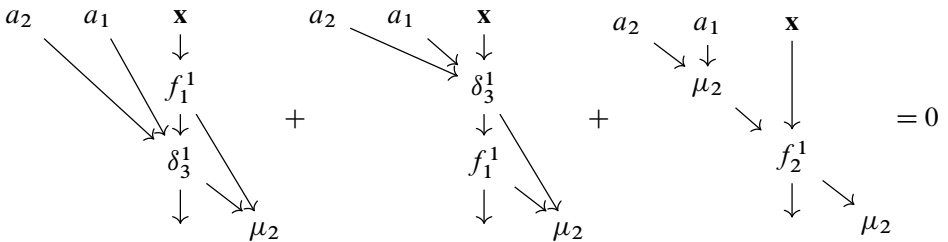
Lemma 8.5. *There is a homotopy equivalence of DA bimodules*

$${}_{\mathcal{K}|\mathcal{K}}M^{\mathcal{K}} \simeq {}_{\mathcal{K}|\mathcal{K}}N^{\mathcal{K}}.$$

Proof. We construct a morphism f_{j+1}^1 between the two bimodules. We set $f_1^1(\mathbf{x}) = \mathbf{x} \otimes 1$. The only other non-vanishing term is f_2^1 . This map is determined by the relations

$$f_2^1(\sigma|\sigma, i_0) = i_1 \otimes \sigma \quad \text{and} \quad f_2^1(\tau|\tau, i_0) = i_1 \otimes \tau.$$

The DA bimodule morphism structure relations for two algebra inputs which both change idempotent are given by the schematic



which is easily verified. The structure relations for $n \neq 2$ algebra inputs are also easily verified. ■

8.4 The type-A identity bimodule

It is helpful to introduce another bimodule, which we denote by

$$\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}] := \mathcal{K}|\mathcal{K}M^{\mathcal{K}} \hat{\boxtimes} \mathcal{K}\mathcal{D}_0.$$

We call $\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}]$ the *type-A identity module*. We will use $\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}]$ to transform type-D actions into type-A actions. The type-A module $\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}]$ appears in the pairing theorem, stated in Theorem 1.4.

There is a further refinement which takes into account the right $\mathbb{F}[U]$ -action on \mathcal{D}_0 . We define

$$\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}]_{\mathbb{F}[U]} := \mathcal{K}|\mathcal{K}M^{\mathcal{K}} \hat{\boxtimes} \mathcal{K}[\mathcal{D}_0]_{\mathbb{F}[U]}.$$

Verifying the pairing theorem with the bimodule $\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}]_{\mathbb{F}[U]}$ turns out to be more subtle than for $\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}]$. Nonetheless, we prove the pairing theorem with $\mathcal{K}|\mathcal{K}[\mathbb{I}^\mathfrak{D}]_{\mathbb{F}[U]}$ in Section 15.3 once we introduce the pair-of-pants bimodules.

8.5 The knot surgery formula over \mathcal{K}

We now describe how to view the mapping cone formula of Ozsváth and Szabó in terms of the algebra \mathcal{K} .

Recall that Ozsváth and Szabó's mapping cone formula [43, Theorem 1.1] states that if λ is an integral framing on $K \subseteq S^3$, then

$$\mathbf{CF}^-(S_\lambda^3(K)) \cong \mathbb{X}_\lambda(K) = \text{Cone}(\mathbb{A}(K) \xrightarrow{v+h_\lambda} \mathbb{B}(K)).$$

Recall, as in Lemma 6.5, that $\mathbb{A}(K)$ may be identified with a completion of $\mathcal{CFK}(K)$ and $\mathbb{B}(K)$ may be identified with a completion of $\mathcal{V}^{-1}\mathcal{CFK}(K)$.

We will describe the following algebraic perspectives of the mapping cone formula:

- (1) A chain complex $\mathbb{X}_\lambda(K)$ over $\mathbb{F}[U]$.
- (2) A right type-D module $\mathcal{X}_\lambda(K)^{\mathcal{K}}$.
- (3) A left type-A module ${}_{\mathcal{K}}\mathcal{X}_\lambda(K)$.

These will satisfy the following relations:

$$\mathbb{X}_\lambda(K) \cong \mathcal{X}_\lambda(K)^{\mathcal{K}} \hat{\boxtimes} \mathcal{K}[\mathcal{D}_0] \simeq \mathcal{D}_0^{\mathcal{K}} \hat{\boxtimes} {}_{\mathcal{K}}\mathcal{X}_\lambda(K).$$

We begin with the description as a type-D module. Let $\mathbf{x}_1, \dots, \mathbf{x}_n$ be a free basis of $\mathcal{CFK}(K)$ over $\mathbb{F}[U, V]$. We declare the underlying \mathbf{I} -module of $\mathcal{X}_\lambda(K)^{\mathcal{K}}$ to be

$$\mathcal{X}_\lambda(K)^{\mathcal{K}} = \text{Span}_{\mathbb{F}}(\mathbf{x}_1, \dots, \mathbf{x}_n) \otimes_{\mathbb{F}} \mathbf{I}.$$

In particular, over \mathbb{F} each \mathbf{x}_i contributes one generator in each idempotent. We denote these generators by \mathbf{x}_i^0 and \mathbf{x}_i^1 .

The map δ^1 on $\mathcal{X}_\lambda(K)^{\mathcal{K}}$ is as follows. Firstly, there are internal δ^1 summands from the differential of $\mathcal{CFK}(K)$. If $\partial(\mathbf{x})$ contains a summand of $\mathbf{y} \cdot \mathcal{U}^n \mathcal{V}^m$, then $\delta^1(\mathbf{x}^\varepsilon)$ contains a summand of $\mathbf{y}^\varepsilon \otimes \mathcal{U}^n \mathcal{V}^m$, for $\varepsilon \in \{0, 1\}$.

In Ozsváth and Szabó's mapping cone formula, v is the canonical inclusion of $\mathcal{CFK}(K)$ into $\mathcal{V}^{-1}\mathcal{CFK}(K)$. Correspondingly, $\delta^1(\mathbf{x}^0)$ contains a summand of the form $\mathbf{x}^1 \otimes \sigma$.

If $\mathbf{y} \cdot \mathcal{U}^i \mathcal{V}^j$ is a summand of $h_\lambda(\mathbf{x})$ then we define $\delta^1(\mathbf{x}^0)$ to have a summand of the form

$$\mathbf{y}^1 \otimes \mathcal{U}^i \mathcal{V}^j \tau.$$

Lemma 8.6. $\mathcal{X}_\lambda(K)^{\mathcal{K}}$ is a type-D module.

Proof. The proof is a formal consequence of the fact that $\partial^2 = 0$ on $\mathcal{CFK}(K)$, that v and h_λ are chain maps, and that v and h_λ satisfy the equivariance properties of Lemma 6.7.

In more detail, suppose that $\mathbf{x}_1, \dots, \mathbf{x}_n$ is a free basis of $\mathcal{CFK}(K)$, and consider

$$((\text{id}_{\mathcal{X}} \otimes \mu_2) \circ (\delta^1 \otimes \text{id}_{\mathcal{K}}) \circ \delta^1)(\mathbf{x}_i^\varepsilon) \quad (8.1)$$

For concreteness, consider the case when $\varepsilon = 0$. There are three sources of terms in the above expression: those arising from two applications of ∂ , those arising from one v and one ∂ , and those arising from one h_λ and one ∂ . Consider the terms with two ∂ terms. Write $\partial(\mathbf{x}_i) = \sum_{j=1}^n \mathbf{x}_j \cdot f_{j,i}$. The terms with two ∂ terms are simply

$$\sum_{k=1}^n \mathbf{x}_k^0 \otimes \left(\sum_{j=1}^n f_{k,j} f_{j,i} \right),$$

which is 0 since $\partial^2 = 0$ on $\mathcal{CFK}(K)$. Similarly, the terms corresponding to one ∂ and one v are given by the formula

$$\sum_{j=1}^n \mathbf{x}_j^1 \otimes (\sigma f_{j,i} + f_{j,i} \sigma),$$

which vanishes because $\sigma f_{j,i} = f_{j,i} \sigma$ in \mathcal{K} .

Finally, we consider the terms corresponding to one ∂ and one h_λ . Write $h_\lambda(\mathbf{x}_i) = \sum_{j=1}^n \mathbf{x}_j \cdot g_{j,i}$, where $g_{j,i} \in \mathbb{F}[\mathcal{U}, \mathcal{V}, \mathcal{V}^{-1}]$. The corresponding terms of equation (8.1) are

$$\sum_{k=1}^n \mathbf{x}_k^1 \otimes \left(\sum_{j=1}^n g_{k,j} \tau f_{j,i} + f_{k,j} g_{j,i} \tau \right) = \sum_{k=1}^n \mathbf{x}_k^1 \otimes \left(\sum_{j=1}^n g_{k,j} \phi^\tau(f_{j,i}) + f_{k,j} g_{j,i} \right) \tau. \quad (8.2)$$

However, $\sum_{j=1}^n g_{k,j} \phi^\tau(f_{j,i}) + f_{k,j} g_{j,i}$ is the \mathbf{x}_k coefficient of $[\partial, h_\lambda](\mathbf{x}_i)$, since h_λ satisfies $h_\lambda(\mathbf{x} \cdot a) = h_\lambda(\mathbf{x}) \cdot \phi^\tau(a)$, by Lemma 6.7. In particular, equation (8.2) vanishes. The case when $\varepsilon = 1$ is similar. \blacksquare

Having defined the type-D module $\mathcal{X}_\lambda(K)^{\mathcal{K}}$, we may now define the type-A module

$${}_{\mathcal{K}} \mathcal{X}_\lambda(K) := \mathcal{X}_\lambda(K)^{\mathcal{K}} \widehat{\boxtimes}_{\mathcal{K}|\mathcal{K}} [\mathbb{I}^{\boxplus}].$$

8.6 The link surgery formula over \mathcal{L}

In this section, we describe how to view Manolescu and Ozsváth’s link surgery formula as a type-D module.

Recall that we define

$$\mathcal{L}_\ell := \mathcal{K}_1 \otimes_{\mathbb{F}} \cdots \otimes_{\mathbb{F}} \mathcal{K}_\ell,$$

where each \mathcal{K}_i denotes a copy of \mathcal{K} .

Let L be an ℓ -component link in S^3 with integral framing Λ . The link surgery complexes require a choice of auxiliary data, which we call a *system of arcs* \mathcal{A} . We will discuss these in detail in Section 9.1 below. If \mathcal{A} is chosen, Manolescu and Ozsváth’s construction produces a chain complex $\mathcal{C}_\Lambda(L, \mathcal{A})$ over $\mathbb{F}[U_1, \dots, U_\ell]$. In this section, we will describe how to construct a type-D module

$$\mathcal{X}_\Lambda(L, \mathcal{A})^{\mathcal{L}_\ell},$$

based on their construction of $\mathcal{C}_\Lambda(L, \mathcal{A})$.

We view the link algebra \mathcal{L}_ℓ as being an algebra over the idempotent ring

$$\mathbf{E}_\ell := \underbrace{\mathbf{I} \otimes_{\mathbb{F}} \cdots \otimes_{\mathbb{F}} \mathbf{I}}_{\ell}.$$

We can view \mathbf{E}_ℓ as being a ring with 2^ℓ elementary idempotents, each identified with a point in the cube \mathbb{E}_ℓ . If $\varepsilon \in \mathbb{E}_\ell$, we write

$$\mathbf{E}_\ell := \mathbf{I}_{\varepsilon_1} \otimes \cdots \otimes \mathbf{I}_{\varepsilon_\ell} \cong \mathbb{F}$$

for the corresponding idempotent.

If $\varepsilon' \geq \varepsilon$, we can understand $\mathbf{E}_{\varepsilon'} \cdot \mathcal{L}_\ell \cdot \mathbf{E}_\varepsilon$ as follows. Write $I_{\varepsilon', \varepsilon} = \{i_1, \dots, i_n\} = (\varepsilon' - \varepsilon)^{-1}(1)$, i.e., the set of indices i where $\varepsilon'_i > \varepsilon$. Then $\mathbf{E}_{\varepsilon'} \cdot \mathcal{L}_\ell \cdot \mathbf{E}_\varepsilon$ is generated by elements of the form

$$\alpha_1 \cdots \alpha_\ell \phi_{i_1} \cdots \phi_{i_n},$$

where

- (1) a_i is in $\mathbb{F}[\mathcal{U}_i, \mathcal{V}_i]$ if $\varepsilon'_i = 0$,
- (2) a_i is in $\mathbb{F}[\mathcal{U}_i, \mathcal{V}_i, \mathcal{V}_i^{-1}]$ if $\varepsilon'_i = 1$,
- (3) each ϕ_{i_j} is either σ_{i_j} or τ_{i_j} .

If $\mathbf{x}_1, \dots, \mathbf{x}_n$ is a free basis of $\mathcal{CF}\mathcal{L}(L)$ over $\mathbb{F}[\mathcal{U}_1, \dots, \mathcal{U}_\ell, \mathcal{V}_1, \dots, \mathcal{V}_\ell]$, then we define the generators of $\mathcal{X}_\Lambda(L, \mathcal{A})^{\mathcal{L}\ell}$ to be

$$\text{Span}_{\mathbb{F}}(\mathbf{x}_1, \dots, \mathbf{x}_n) \otimes_{\mathbb{F}} \mathbf{E}_\ell.$$

In particular, if \mathbf{x} is a basis element of $\mathcal{CF}\mathcal{L}(L)$, we have a generator \mathbf{x}^ε for each $\varepsilon \in \mathbb{E}_\ell$.

If $M \subseteq L$, write $\varepsilon(M) \in \mathbb{E}_\ell$ for the coordinate such that $\varepsilon(M)_i = 0$ if $L_i \notin M$ and $\varepsilon(M)_i = 1$ if $L_i \in M$.

Suppose that \mathbf{x} is a basis element of $\mathcal{CF}\mathcal{L}(L)$ and $M \subseteq L$. By Lemma 6.5, we may view $\mathbf{x}^{\varepsilon(M)}$ as an element of the group $\mathcal{C}_\Lambda(L, \mathcal{A}) = \prod_{\mathbf{s} \in \mathbb{H}(L)} \mathfrak{X}(\mathcal{H}^{L \setminus M}, \psi^M(\mathbf{s}))$. Suppose also that \vec{N} is an oriented sublink of $L \setminus M$, and that $\Phi^{\vec{N}}(\mathbf{x}^{\varepsilon(M)})$ has a summand of $\mathbf{y}^{\varepsilon(M \cup N)} \cdot f$, where we view f as an element of the 2ℓ -variable polynomial ring, localized at the variables \mathcal{V}_i such that $L_i \subseteq N$. We may naturally view f as being an element of

$$\mathbf{E}_{\varepsilon(M \cup N)} \cdot \mathcal{L}_\ell \cdot \mathbf{E}_{\varepsilon(M \cup N)}.$$

There is an algebra element

$$t_{\varepsilon(M), \varepsilon(M \cup N)}^{\vec{N}} \in \mathbf{E}_{\varepsilon(M \cup N)} \cdot \mathcal{L}_\ell \cdot \mathbf{E}_{\varepsilon(M)}$$

which is the tensor of σ_i for i such that $L_i \subseteq \vec{N}$ and L_i is oriented the same as L , τ_i for i such that $L_i \subseteq \vec{N}$ and L_i is oriented oppositely from L , and 1 for i such that $L_i \notin N$. With this notation, we declare $\delta^1(\mathbf{x}^{\varepsilon(M)})$ to have the summand

$$\mathbf{y}^{\varepsilon(M \cup N)} \otimes f \cdot t_{\varepsilon(M), \varepsilon(M \cup N)}^{\vec{N}}.$$

Lemma 8.7. $\mathcal{X}_\Lambda(L, \mathcal{A})^{\mathcal{L}\ell}$ is a type-D module.

Proof. The proof is similar to Lemma 8.6. We can decompose the structure map δ^1 as

$$\delta^1 = \sum_{\vec{M} \subseteq L} \delta_{\vec{M}}^1,$$

where $\delta_{\vec{M}}^1$ consists of all terms which are weighted by idempotent-preserving multiples of the algebra element $t^{\vec{M}}$.

The map $\delta_{\vec{M}}^1$ encodes the map $\Phi^{\vec{M}}$ on the surgery formula, in the sense that if $\Phi^{\vec{M}}(\mathbf{x})$ has a summand $a \cdot \mathbf{y}$ for some monomial a in the \mathcal{U}_i and $\mathcal{V}_i^{\pm 1}$, then $\delta_{\vec{M}}^1$ has a summand $\mathbf{y} \otimes at^{\vec{M}}$.

Let $\vec{N} \subseteq L$ be an oriented link, and consider the components of

$$((\text{id}_{\mathcal{X}} \otimes \mu_2) \circ (\delta^1 \otimes \text{id}_{\mathcal{X}_\ell}) \circ \delta^1)(\mathbf{x}^\varepsilon)$$

whose algebra elements are weighted by idempotent-preserving multiples of $t^{\vec{N}}$. These can be identified with

$$\sum_{\substack{\vec{M}_1 \cup \vec{M}_2 = \vec{N}, \\ \vec{M}_1 \cap \vec{M}_2 = \emptyset}} (\mathbb{I}_{\mathcal{X}} \otimes \mu_2) \circ (\delta_{\vec{M}_2}^1 \otimes \mathbb{I}_{\mathcal{X}}) \circ \delta_{\vec{M}_1}^1. \quad (8.3)$$

We consider a component of the above map corresponding to sublinks \vec{M}_1 and \vec{M}_2 , applied to some generator \mathbf{x} . Suppose that $\delta_{\vec{M}_1}^1(\mathbf{x})$ contains a summand $\mathbf{y} \otimes at^{\vec{M}_1}$. Such a summand corresponds to a summand of $\mathbf{y} \cdot a$ in $\Phi^{\vec{M}_1}(\mathbf{x})$. Next, consider a summand $\mathbf{z} \otimes bt^{\vec{M}_2}$ in $\delta_{\vec{M}_2}^1(\mathbf{y})$. In the composition appearing in equation (8.3), there is a corresponding term of

$$\mathbf{z} \otimes bt^{\vec{M}_2} at^{\vec{M}_1} = \mathbf{z} \otimes b\phi^{\vec{M}_2}(a)t^{\vec{N}}.$$

(The second equality follows from the definition of the algebra \mathcal{L}_ℓ .) Using Lemma 6.7, which states that $\Phi^{\vec{M}_2}(a\mathbf{y}) = \phi^{\vec{M}_2}(a) \cdot \Phi^{\vec{M}_2}(\mathbf{y})$, we see that there is a corresponding summand in $(\Phi^{\vec{M}_2} \circ \Phi^{\vec{M}_1})(\mathbf{x})$ of $\mathbf{z} \cdot b\phi^{\vec{M}_2}(a)$. Therefore, the fact equation (8.3) vanishes follows from the fact that

$$\sum_{\substack{\vec{M}_1 \cup \vec{M}_2 = \vec{N}, \\ \vec{M}_1 \cap \vec{M}_2 = \emptyset}} \Phi^{\vec{M}_2} \circ \Phi^{\vec{M}_1} = 0,$$

which is proven in [32, Proposition 9.4]. ■

Given a collection of integers $\Lambda = (\lambda_1, \dots, \lambda_\ell)$, there is a type-A module

$$\mathcal{L}_\ell \mathcal{D}_\Lambda$$

defined by taking the external tensor product of the modules $\mathcal{K}[\mathcal{D}_{\lambda_i}]$ from Section 8.2. There is also a right action of $\mathbb{F}[U_1, \dots, U_\ell]$, and \mathcal{D}_Λ may be viewed as an AA-bimodule

$$\mathcal{L}_\ell [\mathcal{D}_\Lambda]_{\mathbb{F}[U_1, \dots, U_\ell]}.$$

The following is immediate from the definition of $\mathcal{X}_\Lambda(L, \mathcal{A})^{\mathcal{L}_\ell}$.

Proposition 8.8. *There is a chain isomorphism*

$$\mathcal{C}_\Lambda(L)_{\mathbb{F}[U_1, \dots, U_\ell]} \cong \mathcal{X}_\Lambda(L)^{\mathcal{L}_\ell} \hat{\boxtimes} \mathcal{L}_\ell [\mathcal{D}_{(0, \dots, 0)}]_{\mathbb{F}[U_1, \dots, U_\ell]}.$$

We will also need to consider type-A and type-DA versions of the link surgery formula. An important special case is when we have a distinguished component $K_i \subseteq L$. We define a bimodule ${}_{\mathcal{K}}\mathcal{X}_{\Delta}(L)^{\mathcal{L}^{\ell-1}}$, where the \mathcal{K} -input corresponds to K_i by setting

$${}_{\mathcal{K}}\mathcal{X}_{\Delta}(L)^{\mathcal{L}^{\ell-1}} := \mathcal{X}_{\Delta}(L)^{\mathcal{L}^{\ell}} \hat{\boxtimes} {}_{\mathcal{K}|\mathcal{K}}[\mathbb{I}^{\mathfrak{D}}],$$

where the tensor product is taken along the algebra component corresponding to K_i . In the above equation, ${}_{\mathcal{K}|\mathcal{K}}[\mathbb{I}^{\mathfrak{D}}]$ is the bimodule from Section 8.4. More generally, we may turn more algebra components from type-D to type-A by tensoring additional copies of ${}_{\mathcal{K}|\mathcal{K}}[\mathbb{I}^{\mathfrak{D}}]$.