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Remarks on critical exponents for Hessian operators

by

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ABSTRACT. – The critical exponent for the k-th Hessian operator $(k=2, \ldots, n)$ is determined and the solvability of the associated Dirichlet problem with sub-critical nonhomogeneous term is discussed.

Key words : Hessian operators, Critical exponent, Associated Dirichlet problem.

RÉSUMÉ. – On détermine l'exposant critique pour les opérateurs de Hess, et l'on étudie le problème de Dirichlet associé, avec un terme non homogène sous-critique.

INTRODUCTION

Let Ω be a bounded domain in \mathbb{R}^n , $n \ge 2$. It is well-known that the Sobolev exponent $\frac{n+2}{n-2}$ plays a critical role concerning the solvability of the Dirichlet problem

 $\Delta u + u^p = 0$ in Ω , u = 0 on $\partial \Omega$.

Namely, this problem admits no positive solutions in a star-shaped Ω when $p \ge \frac{n+2}{n-2}$ and it has a positive solution in any Ω when $\frac{n+2}{n-2} > p > 0$

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and p is not equal to one. In a previous work [6] we have studied a corresponding problem for the Monge-Ampère operator on a convex Ω :

det
$$\nabla^2 u = (-u)^p$$
 in Ω , $u = 0$ on $\partial \Omega$.

We found that in contrast to the semilinear case this problem admits nonzero convex solutions provided p is positive and is not equal to n. Since the Laplace operator and the Monge-Ampère operator are respectively the first and the last Hessian operators, we are led to the question of determining the "critical exponents" for the remaining Hessian operators.

Let $S_k(\nabla^2 u)$, $k=1, \ldots, n$, be the k-th Hessian operator, *i.e.*, it is the k-th elementary symmetric function of the Hessian matrix of u. Consider

$$S_{k}(\nabla^{2} u) = (-u)^{p} \text{ in } \Omega,$$

$$u = 0 \text{ on } \partial\Omega.$$

$$(1)$$

In this note we shall establish the following result:

THEOREM. – Let
$$\Omega$$
 be a ball and let $\gamma(k) = \begin{cases} \frac{(n+2)k}{n-2k} & 1 \le k < \frac{n}{2} \\ \infty & \frac{n}{2} \le k \le n \end{cases}$. Then

(i) (1) has no negative solution in $C^1(\overline{\Omega}) \cap C^4(\Omega)$ when $p \ge \gamma(k)$; (ii) It admits a negative solution which is radially symmetric and is in $C^2(\overline{\Omega})$ when 0 , p is not equal to k.

The non-existence result actually holds in more general situation. See Proposition 1 in the next section. Part (ii) of this theorem is contained in Propositions 2 (0) and 3 (<math>k) in Section 2. When <math>p=kone should study an eigenvalue problem. However, we shall not consider it here.

NOTATION. – Subscripts like those in u_i , u_{ij} , F_z , ..., stand for partial differentiations. Also, summation convention is always in effect.

SECTION 1. NON-EXISTENCE

Consider the following Dirichlet problem

Many authors have studied the existence of negative solutions for this problem in the case k=1. Negative solutions are sought because they are important in many applications. However, when k is greater than one, negative solutions will be sought not only as an analogue of the semilinear case but mainly because they are precisely the "admissible ones". When kis greater than one a Hessian operator is nonlinear and so its type depends on the Hessian of u. According to Caffarelli-Nirenberg-Spruck [1] a C^2 function u is called *admissible* (with respect to S_k , $k \ge 2$) if the eigenvalues of $\nabla^2 u(x)$, $x \in \Omega$, lie in the connected component Γ_k of the set $\{\lambda = (\lambda_1, \ldots, \lambda_n):$ The k-th elementary symmetric function of λ is positive} which contains the cone $\{\lambda : \lambda_i > 0 \text{ for all } i\}$. It can be shown that for an admissible $u \operatorname{S}_k(\nabla^2 u)$ is elliptic, *i. e.*, $\frac{\partial \operatorname{S}_k(\nabla^2 u)}{\partial r_{ij}} \xi_i \xi_j > 0$, for all ξ , $|\xi| > 0$, and $x \in \Omega$. We claim that any solution of (2) which belongs to $C(\overline{\Omega}) \cap C^2(\Omega)$ is admissible if and only if it is negative. For, at a nonnegative maximum of u, $S_k(\nabla^2 u)$ is non-positive. But since f is positive this is impossible. Conversely, if u is negative, it attains a minimum in Ω . At this minimum the eigenvalues of the Hessian of u lie in Γ_k . Hence by

the continuity of $\nabla^2 u$ and the positivity of f u is also admissible. The equation in (2) has a variational structure. To describe it

The equation in (2) has a variational structure. To describe it we need to express S_k in terms of the Newtonian tensor. Recall that for $k=0, \ldots, n-1$, the k-th Newtonian tensor is given by

$$T_{k} (\nabla^{2} u)_{ij} = \frac{1}{k!} \delta^{j_{1} \dots j_{k} j}_{i_{1} \dots i_{k} i} u_{i_{1} j_{1}} \dots u_{i_{k} j_{k}}.$$

Here $\delta_{i_1 \dots i_k i}^{j_1 \dots j_k j}$ is the generalised Kronecker delta: It is equal to 1 (resp. -1) if i_1, \dots, i_k , *i* are distinct and $\binom{j_1 \dots j}{i_1 \dots i}$ is an even (resp. odd) permutation; Otherwise it is equal to zero. A fundamental property of the Newtonian tensor is that it is of divergence free, *i.e.*,

$$\frac{\partial T_k (\nabla^2 u)_{ij}}{\partial x_j} = 0, \qquad i = 1, \dots, n.$$
(3)

 S_k is related to T_{k-1} via

$$\frac{\partial \mathbf{S}_{k}(\nabla^{2} u)}{\partial r_{ij}} = \mathbf{T}_{k-1} (\nabla^{2} u)_{ij}$$
(4)

and

$$S_{k}(\nabla^{2} u) = \frac{1}{k} T_{k-1} (\nabla^{2} u)_{ij} u_{ij}.$$
 (5)

(5) follows from Euler's identity. For proofs of (3) and (4) see Reilly [5].

Using (3)-(5) one readily verifies that the equation in (2) is the Euler-Lagrange equation for the functional

$$J_k(u) = \frac{-1}{k+1} \int_{\Omega} u S_k(\nabla^2 u) + \int_{\Omega} F(x, u)$$

where $F(x, z) = \int_0^z f(x, t) dt$.

Now, consider a general integrand $\mathscr{F}(x, z, r_{ij})$, $r_{ij} = r_{ji}$. Let u be a C⁴-solution of the Euler-Lagrange equation for \mathscr{F} . Then for any constant a the following identity holds:

$$\frac{\partial}{\partial x_i} \left[x_i \mathscr{F} + (x_k u_k + au) \frac{\partial \mathscr{F}_{r_{ij}}}{\partial x_j} - \frac{\partial}{\partial x_j} (x_k u_k + au) \mathscr{F}_{r_{ij}} \right] = n \mathscr{F} + x_i \mathscr{F}_{x_i} - au \mathscr{F}_z - (a+2) u_{ij} \mathscr{F}_{r_{ij}}.$$

This identity, which can be verified directly, was first obtained in Pucci-Serrin [3]. Applying this identity to $\mathscr{F} = \frac{-z S_k(r_{ij})}{k+1} + F(x, z)$, we have, by (3)-(5),

$$\frac{\partial}{\partial x_i} \left[x_i \left(\frac{-u \operatorname{S}_{\mathbf{k}} (\nabla^2 u)}{k+1} + \operatorname{F} (x, u) \right) + (x_k u_k + au) \left(\frac{-u_j \operatorname{T}_{\mathbf{k}-1} (\nabla^2 u)_{ij}}{k+1} \right) + \frac{\partial}{\partial x_j} (x_k u_k + au) \frac{u \operatorname{T}_{\mathbf{k}-1} (\nabla^2 u)_{ij}}{k+1} \right]$$
$$= \left[k \left(a+2 \right) + a - n \right] \frac{u \operatorname{S}_{\mathbf{k}} (\nabla^2 u)}{k+1} + n \operatorname{F} - auf + x_i \operatorname{F}_{x_i}.$$
(6)

Next we formulate the non-existence result. Recall that a bounded domain Ω is called star-shaped if for some x_0 , $\langle x-x_0, v \rangle \ge 0$ on $\partial \Omega$. (Here v is the unit outer normal and $\langle ., . \rangle$ is the Euclidean inner product.)

PROPOSITION 1. – Let Ω be a star-shaped C²-domain with x_0 being the origin. Suppose that f belongs to $C(\overline{\Omega} \times (-\infty, 0]) \cap C^1(\Omega \times (-\infty, 0))$, positive in $\Omega \times (-\infty, 0)$ and equal to zero on $\Omega \times \{0\}$. There are no negative solutions to (2) which belong to $C^1(\overline{\Omega}) \cap C^4(\Omega)$ if

$$n F(x, z) - \frac{n-2k}{k+1} z f(x, z) + x_i F_{x_i}(x, z) > 0$$
(7)

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in $\Omega \times (-\infty, 0)$. The same conclusion holds under

$$n F(x, z) - \frac{n-2k}{k+1} z f(x, z) + x_i F_{x_i}(x, z) \ge 0$$
(7)'

if $\langle x, v \rangle > 0$ on $\partial \Omega$.

Proof. – Let $\Omega_{\varepsilon} = \{x \in \Omega : u(x) < -\varepsilon\}$. By a strong maximum principle (see Lemma below) Ω_{ε} has C⁴-boundary for small $\varepsilon > 0$. Choose $a = \frac{n-2k}{k+1}$ so that k(a+2)+a-n=0 in (6) and then integrate both side of (6) over Ω_{ε} . By divergence theorem we have

$$\begin{split} \int_{\partial\Omega_{\epsilon}} \langle x, v \rangle &\left(\frac{\varepsilon \operatorname{S}_{k}(\nabla^{2} u)}{k+1} + \operatorname{F}(x, -\varepsilon) \right) - \frac{1}{k+1} \int_{\partial\Omega_{\epsilon}} x_{k} u_{k} u_{j} \operatorname{T}_{k-1} (\nabla^{2} u)_{ij} v_{i} \\ &- \varepsilon \int_{\partial\Omega_{\epsilon}} \frac{u_{j} \operatorname{T}_{k-1} (\nabla^{2} u)_{ij} v_{i}}{k+1} - \varepsilon \int_{\partial\Omega_{\epsilon}} \frac{x_{k} u_{kj} \operatorname{T}_{k-1} (\nabla^{2} u)_{ij} v_{i}}{k+1} \\ &= \int_{\Omega_{\epsilon}} \left(n \operatorname{F}(x, u) - \frac{n-2k}{k+1} u f(x, u) + x_{i} \operatorname{F}_{x_{i}}(x, u) \right). \end{split}$$

A repeated application of (3)-(5) gives

$$\int_{\partial \Omega_{\varepsilon}} u_j \operatorname{T}_{k-1} (\nabla^2 u)_{ij} v_i = k \int_{\Omega_{\varepsilon}} f(x, u)$$
(8)

and

$$\int_{\partial\Omega_{\varepsilon}} x_k u_{kj} \operatorname{T}_{k-1} \left(\nabla^2 u\right)_{ij} v_i = k \int_{\Omega_{\varepsilon}} f(x, u) + \int_{\Omega_{\varepsilon}} x_k \frac{\partial}{\partial x_k} \operatorname{S}_k \left(\nabla^2 u\right)$$
$$= (k-n) \int_{\Omega} f(x, u).$$

Consequently,

$$\lim_{\varepsilon \downarrow 0} \int_{\partial \Omega_{\varepsilon}} \langle x, v \rangle |\nabla u|^2 \operatorname{T}_{k-1} (\nabla^2 u)_{ij} v_i v_j$$

= -(k+1) $\int_{\Omega} \left(n \operatorname{F} - \frac{n-2k}{k+1} u f + x_i \operatorname{F}_{x_i} \right).$

If u is a negative solution of (2), $T_{k-1} (\nabla^2 u)_{ij} v_i v_j > 0$ by ellipticity. Hence the left hand side of the above identity is non-negative. However, this contradicts with (7). On the other hand, if $\langle x, v \rangle \geq \delta$ for some positive δ on $\partial \Omega$, by (8) and the lemma below the left hand side of the above

identity is positive. But then this contradicts with (7)'. Proposition 1 is thus proved.

LEMMA.
$$-\frac{\partial u}{\partial v} > 0$$
 on $\partial \Omega$.

Proof. – Let $x \in \partial \Omega$ and let B be a ball which is inscribed inside Ω and touches $\partial \Omega$ at x. For a non-negative radially symmetric function g with $g(|x|) \leq f(x, u(x))$ let w be the solution for

$$S_k(\nabla^2 w) = g$$
 in B, $w = 0$ on ∂B ,

w can be solved explicitly in terms of g; see (10) in the next section. By the maximum principle $w \ge u$ in B. Hence $\frac{\partial u}{\partial v}(x) \ge \frac{\partial w}{\partial v}(x) > 0$.

SECTION 3. EXISTENCE

Throughout this section Ω denotes a ball of radius R centered at the origin and f(x, z) in (2) is equal to g(r, z), r = |x|, where

$$g \in C([0, R] \times (-\infty, 0]), \quad g > 0 \text{ in } [0, R) \times (-\infty, 0].$$
 (9)

We shall look for radially symmetric solutions for (2). Denote such a solution by y(r). y satisfies

$$C_{k-1}^{n-1} \left(\frac{y'}{r}\right)^{k-1} y'' + C_k^{n-1} \left(\frac{y'}{r}\right)^k = g(r, y),$$

$$y(\mathbf{R}) = 0, \qquad y'(0) = 0.$$
 (10)

Here C_{k-1}^{n-1} and C_k^{n-1} are combinatorial constants. It is easy to see that whenever y solves (10), u(x) = y(|x|) is a solution for (3).

For a negative radially symmetric u, the functional $J_k(u)$ is equal to

$$\alpha \int_{0}^{R} (y')^{k+1} r^{n-k} + \tau \int_{0}^{R} G(r, y) r^{n-1}$$

where $G(r, z) = \int_0^z g(r, t) dt$, $\alpha = \frac{\tau}{k(k+1)} C_{k-1}^{n-1}$ and τ is the volume of the unit sphere in \mathbb{R}^n . It is more convenient to let J_k act on the whole space rather than on negative functions. To this end we extend g to be an even

function in z (maintaining the same notation) and consider the functional

$$j_{k}(y) = \alpha \int_{0}^{R} |y'|^{k+1} r^{n-k} + \tau \int_{0}^{R} G(r, y) r^{n-1}.$$

LEMMA 1. - Let $E = \{y \in C^1([0, R]) : y(R) = 0\}$ (i) For $1 \le k \le \frac{n}{2}$ and $0 < \delta < \gamma(k)$, there exists a constant $C = C(\delta, k, R, n)$ such that

$$\left(\int_{0}^{\mathbf{R}} |y|^{\delta+1} r^{n-1}\right)^{1/(\delta+1)} \leq \mathbf{C} \left(\int_{0}^{\mathbf{R}} |y'|^{k+1} r^{n-k}\right)^{1/(k+1)}$$

for all $y \in E$; (ii) For $n \ge k > \frac{n}{2}$, there exists a constant C = C(k, R, n) such that

$$||y||_{C^{0,\sigma}}([0, \mathbb{R}]) \leq C\left(\int_{0}^{\mathbb{R}} |y'|^{k+1} r^{n-k}\right)^{1/(k+1)}, \qquad \sigma = \frac{2k-n}{k+1}.$$

Proof. – Applying Hölder inequality to $y(r) = \int_{\mathbf{R}}^{r} y'(s) ds$ we have

$$|y(r)| \leq C r^{-(n-2k)/(k+1)} \left(\int_0^R |y'|^{k+1} r^{n-k} \right)^{1/(k+1)}$$

Raising both side to their $(\delta + 1)$ -th power, multiplying by r^{n-1} and then integrading from 0 to R we obtain (i). (ii) can be proved in a similar way.

Remark. – In fact, a sharper result holds: There exists a constant C = C(k, n) such that

$$C\left(\int_{0}^{R} |y'|^{k+1} r^{n-k}\right)^{1/(k+1)} \\ \geqq \begin{cases} \left(\int_{0}^{R} |y|^{\gamma(k)+1} r^{n-1}\right)^{1/(\gamma(k)+1)} & \text{if } k < \frac{n}{2} \\ \|y\|_{C([0, R])} & \text{if } k = \frac{n}{2} \\ \|y\|_{C^{0,\sigma}([0, R])}, & \sigma = \frac{2k-n}{k+1}, & \text{if } k > \frac{n}{2} \end{cases}$$

for all y in E. For a proof see Lin [2].

Let W_k be the Banach space obtained by completing E under the norm $\left(\int_0^R |y'|^{k+1} r^{n-k}\right)^{1/(k+1)}$. Using Lemma 1 one can easily show that the following lemma holds:

LEMMA 2. - (i) W_k is continuously embedded in $\{y \in C^{0, 1-(1/(k+1))}([r, R]): y(R)=0.\}$ for r>0; (ii) W_k is compactly embedded in $L^{p+1}(r^{n-1}dr)$ for $p < \gamma(k)$ when $k \leq \frac{n}{2}$ and in C([0, R]) when $k > \frac{n}{2}$. We also have

LEMMA 3. – Suppose g satisfies

$$|g(r, z)| \leq C(1+|z|^{p}), \quad 0 \leq r \leq R$$
 (11)

for some $p, 0 . Then <math>j_k$ belongs to $C^1(W_k; R)$. Moreover, $y \to \int_0^R G(r, y) r^{n-1}$ is weakly continuous on W_k .

The proof of this lemma is parallel to the proof for the corresponding result in the semilinear case; See Rabinowitz [4], Appendix B, for details. Any critical point of j_k will be called a *generalised solution* of (10). In other words, y is a generalised solution of (10) if and only if

$$(k+1) \alpha \int_0^R |y'|^{k-1} y' \phi' r^{n-k} + \tau \int_0^R g(r, y) \phi r^{n-1} = 0$$
(12)

for all φ in W_k. The regularity of such solutions is given in

LEMMA 4. – Under (9) and (11), any generalised solution of (10) is in $C^2([0, R])$, and solves (10) in classical sense. Moreover, it is negative in [0, R) unless it vanishes identically.

Proof. — We shall first show that any generalised solution is bounded. When k is greater than $\frac{n}{2}$ this follows from Lemma 1. So we assume k is less than or equal to $\frac{n}{2}$.

Let y be a generalised solution. For $s \ge 1$ and $N \ge 1$ we define a function Φ in C¹[1, ∞) by setting $\Phi(z) = z^s - 1$ for $z \in [1, N]$ and taking it to be linear for $z \ge N$. Select $\varphi = \int_{1}^{y^{+}+1} |\Phi'(z)|^{k+1} dt$ where $y^{+} = \max(y, 0)$

as a test function. Substituting φ into (12) we have

$$\int \left| \frac{d}{dr} \Phi(y^{+}+1) \right|^{k+1} r^{n-k} \leq C \int g(r, y) \left| \Phi'(y^{+}+1) \right|^{k+1} y^{+} r^{n-1}$$

after using $\varphi \leq |\Phi'(y^++1)|^{k+1}y^+$. It follows from Lemma 1, Hölder inequality and (11) that for a fixed β , max $(p, k) < \beta < \gamma(k)$,

$$\left(\int \Phi (y^{+}+1)^{\beta+1} r^{n-1}\right)^{1/(\beta+1)} \leq C \left(\int (\Phi' (y^{+}+1) (y^{+}+1))^{q+1} r^{n-1}\right)^{1/(q+1)}$$

where q=p if p > k and q=k if $p \le k$ and C is a constant depending on $||y||_{\mathbf{w}_k}$. Letting $N \to \infty$, we see that $y^+ \in L^{s(q+1)}(r^{n-1}dr)$ implies the stronger inclusion $y^+ \in L^{s(\beta+1)}(r^{n-1}dr)$. Also, we have

$$\|y^{+}+1\|_{L^{s_{x}(q+1)}(r^{n-1}dr)} \leq (Cs)^{1/s} \|y^{+}+1\|_{L^{s}(q+1)(r^{n-1}dr)}$$

where $\kappa = \frac{1+\beta}{1+q} > 1$. Setting $s = \kappa^m$, $m \ge 1$, an iteration yields $\sup y^+ \le C(1+||y||_{L^{q+1}(r^{n-1}dr)}).$

Similarly one can show that the above estimate holds for $y^- = -\min(y, 0)$ in place of y^+ . Thus y is bounded.

Take $\varphi = \int_{r}^{R} \eta(t) dt$ where η is smooth as a test function in (12). After an integration by parts, we have

$$(k+1) \alpha \int_0^{\mathbf{R}} |y'|^{k-1} y' \eta r^{n-k} dr = \tau \int_0^{\mathbf{R}} \int_0^r g(t, y) t^{n-1} dt \eta dr.$$

Henceforth

$$(k+1) \alpha r^{n-k} |y'|^{k-1} y' = \tau \int_0^r g(t, -y) t^{n-1} dt \quad \text{a.e}$$

Since g is non-negative, y is increasing (hence is negative) unless it vanishes identically. From this the desired conclusion of Lemma 4 can be drawn. \blacksquare

Now we can state the existence results.

PROPOSITION 2. - Under (9) and

$$\lim_{z \to \infty} \frac{g(r, z)}{z^p} = 0, \quad p < \gamma(k), \qquad \lim_{z \to 0} \frac{g(r, z)}{z^k} = \infty$$
(13)

uniformly on [0, R], (2) admits a negative radially symmetric solution in $C^2(\bar{\Omega})$.

This solution is obtained by minimizing j_k over W_k . (13) ensures that j_k is bounded from below and is negative somewhere. It follows from the direct method, which works in view of Lemma 3, that a non-zero absolute minimum exists.

PROPOSITION 3. – In addition to (9) and (11), suppose g satisfies $\lim_{z \to 0} \frac{g(r, z)}{z^k} = 0$ uniformly in [0, R], and, further, there exist $\theta \in (0, 1)$ and a positive constant M such that

$$\mathbf{G}(r, z) \leq \frac{\theta}{k+1} zg(r, z), \qquad 0 \leq r \leq \mathbf{R}, \quad |z| \geq \mathbf{M}.$$
(14)

Then (2) admits a negative radially symmetric solution which belongs to $C^2(\bar{\Omega})$.

(14) implies that j_k fulfills the Palais-Smale condition. Proposition 3 follows from the mountain pass lemma. For details see the corresponding proof for the semilinear case in [4], Chapter 2.

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