

# Quantitative homogenization for combustion in random media

Yuming Paul Zhang and Andrej Zlatoš

**Abstract.** We obtain the first quantitative stochastic homogenization result for reaction–diffusion equations, for ignition reactions in dimensions  $d \leq 3$  that either have finite ranges of dependence or are close enough to such reactions, and for solutions with initial data that approximate characteristic functions of general convex sets. We show an algebraic rate of convergence of these solutions to their homogenized limits, which are (discontinuous) viscosity solutions of certain related Hamilton–Jacobi equations.

## 1. Introduction

A basic model of combustion processes in random media is the reaction–diffusion equation

$$u_t = \Delta u + f(x, u, \omega) \tag{1.1}$$

with  $(t, x) \in (0, \infty) \times \mathbb{R}^d$  and  $\omega$  an element of some probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . Its solutions  $u$  represent normalized temperature of the combusting medium, taking values between 0 and 1, and the reaction function  $f$  is of *ignition type*, satisfying  $f(\cdot, u, \cdot) \equiv 0$  whenever  $u \in [0, \theta_1] \cup \{1\}$ , for some  $\theta_1 \in (0, 1)$ .

This model, with homogeneous reactions  $f(x, u, \omega) = f(u)$ , goes back to pioneering works by Kolmogorov, Petrovskii, and Piskunov [8] and Fisher [7]. In this case it is well known that solutions to (1.1) propagate ballistically in all directions at a constant speed  $c^*$  in the sense that a solution with initial data close to the characteristic function of some (not too small) set  $A \subseteq \mathbb{R}^d$  is in a sense close to the characteristic function of the set  $A + c^*tB_1(0)$  at any large time  $t > 0$ . We refer to [3, 4] for various results in the homogeneous reaction case, and to the reviews [5, 16, 18] for other related developments and references.

The setting of heterogeneous reactions is much more complicated as one cannot expect the same propagation speed in all directions – or indeed any propagation speed at all – for general  $f$ . However, when an environment is random, and sufficiently so (e.g., when  $f$  is i.i.d. in space in some sense or, more generally, stationary ergodic), large space-time scale dynamics of physical processes occurring inside it frequently appear as if the environment

were homogeneous (albeit non-isotropic). This phenomenon, called *homogenization*, is a result of large-scale averaging of the random heterogeneities in the medium, and in the setting of (1.1) would also mean existence of direction-dependent asymptotic propagation speeds of solutions.

While existence of homogenization has long been known in various settings, in particular for (first-order as well as “viscous” second-order) Hamilton–Jacobi equations (the literature is vast; the reader can consult [2, 9–13, 15, 17] and references therein), until recently it has been proved for reaction–diffusion equations only in one spatial dimension  $d = 1$ , even in the simplest heterogeneous setting of spatially periodic reactions  $f$ . The main reason for this is that in the case of reaction–diffusion equations, the (homogenized) large-space-time limits of solutions to (1.1) are in fact expected to be (discontinuous) characteristic functions of time-expanding regions, which are also (viscosity) solutions to a very different PDE, the (first-order) Hamilton–Jacobi equation (1.4) below with some  $f$ -dependent “speed”  $c^*: \mathbb{S}^{d-1} \rightarrow (0, \infty)$ . When this fact is coupled with complications caused by potentially very non-trivial geometries of the boundaries of these regions in dimensions  $d \geq 2$ , it is not surprising that the question of homogenization in this setting becomes substantially more challenging.

In fact, the first proofs of stochastic homogenization for (1.1) in dimensions  $d \geq 2$  have only been provided recently and only for ignition reactions (we also note that a homogenization result for *KPP reactions*, satisfying  $f(\cdot, 0, \cdot) \equiv f(\cdot, 1, \cdot) \equiv 0$ , and  $0 < f(x, u, \omega) \leq f_u(x, 0, \omega)u$  when  $u \in (0, 1)$ , was stated without proof in [13] by Lions and Souganidis). First, Lin and the second author obtained a number of conditional homogenization results for general reactions, and showed that the hypotheses in these apply, in particular, to isotropic stationary ergodic ignition reactions in dimensions  $d \leq 3$  [10]. We then showed that homogenization also holds for general stationary ignition reactions in dimensions  $d \leq 3$  that either have finite ranges of dependence (which is a continuous version of an i.i.d. environment) or are in some sense close to such reactions [19] (we refer to [10, 19, 21] for further discussion on this, including the reason for the not-just-technical and physically relevant limitation to  $d \leq 3$ , which we also briefly mention after Definition 1.2 below). Hypotheses (H1)–(H4) below in fact mirror those from [19], although for the sake of simplicity we will not consider here the most general form of the hypotheses in [19].

We also note that when it comes to *periodic* reactions (i.e.,  $f(x, u, \omega) = f(x, u)$  and periodic in  $x$ ), homogenization was proved for *monostable* ones (as KPP but without requiring  $f(x, u) \leq f_u(x, 0)u$ , so KPP reactions are included) by Alfaro and Giletti [1] for initial data with smooth convex supports. This was extended to general convex supports in [10], where homogenization was also proved for periodic ignition reactions and quite general initial data in any dimension. We also refer to Majda and Souganidis [14] for the case of (1.1) with homogeneous KPP reactions and periodic first-order advection terms.

Given how recent the above results are, it is no surprise that until now no *quantitative estimates* on the speed of convergence of solutions to (1.1) to their homogenized limits have been obtained. The goal of this paper is to address this question for the random

ignition reactions considered in [19] (see Theorem 1.3 below). This involves the study of the large-space-time-scale version of (1.1), that is,

$$(u_\varepsilon)_t = \varepsilon \Delta u_\varepsilon + \varepsilon^{-1} f(\varepsilon^{-1}x, u_\varepsilon, \omega) \quad (1.2)$$

with a small  $\varepsilon > 0$ , so that solutions  $u$  to (1.1) give rise to those for (1.2) via

$$u_\varepsilon(t, x, \omega) := u(\varepsilon^{-1}t, \varepsilon^{-1}x, \omega). \quad (1.3)$$

Our main result in [19] is that if initial data for (1.2) sufficiently well approximate the characteristic function of some open set  $A \subseteq \mathbb{R}^d$  as  $\varepsilon \rightarrow 0$ , then the solutions  $u_\varepsilon$  almost surely converge to the characteristic function of a set  $\Theta^{A, c^*} \subseteq (0, \infty) \times \mathbb{R}^d$ , in the sense of locally uniform convergence on the complement of  $\partial \Theta^{A, c^*}$  (i.e., where this characteristic function is continuous). In fact, as is shown in [10],  $\chi_{\Theta^{A, c^*}}$  is a viscosity solution with initial data  $\chi_A$  to the deterministic homogeneous (non-isotropic) Hamilton–Jacobi equation

$$\bar{u}_t = c^* \left( -\frac{\nabla \bar{u}}{|\nabla \bar{u}|} \right) |\nabla \bar{u}|, \quad (1.4)$$

where  $c^*(e) > 0$  is a (deterministic asymptotic) *front speed* for (1.1) in direction  $e \in \mathbb{S}^{d-1}$ , which exists for each  $e$  and the function  $c^*: \mathbb{S}^{d-1} \rightarrow (0, \infty)$  is Lipschitz [19].

One can therefore view (1.4) as the homogenization limit of (1.2). We then show in Theorem 1.3 below that when the initial set  $A$  is bounded and convex, then convergence to this limit is algebraic in  $\varepsilon$  (with some power  $\sigma > 0$ ), with a probability that exponentially converges to 1 as  $\varepsilon \rightarrow 0$ . Specifically, we refer here to convergence of the  $\theta$ -super-level set

$$\Gamma_{u_\varepsilon, \theta}(t, \omega) := \{x \in \mathbb{R}^d \mid u_\varepsilon(t, x, \omega) \geq \theta\}$$

of  $u_\varepsilon(\cdot, t, \omega)$  to  $\Theta^{A, c^*}(t) := \{x \in \mathbb{R}^d \mid (t, x) \in \Theta^{A, c^*}\}$ , for each fixed  $\theta \in (0, 1)$  and uniformly on bounded time intervals. We also note that in this convex  $A$  case, the set  $\Theta^{A, c^*}(t)$  is also convex and was in fact shown in [10, Theorem 1.4 (iii)] to have the relatively simple form

$$\Theta^{A, c^*}(t) = \bigcap_{e \in \mathbb{S}^{d-1}} \{x \in \mathbb{R}^d \mid x \cdot e < \sup_{y \in A} y \cdot e + c^*(e)t\}. \quad (1.5)$$

Theorem 1.3 is hence a *quantitative stochastic homogenization* result for (1.1), which is to the best of our knowledge the first one for reaction–diffusion equations. Our analysis is based on results from our paper [19], primarily those in Proposition 2.7 below. These are quantitative estimates on the fluctuations of arrival times at any point in  $\mathbb{R}^d$  of special solutions to (1.1) with half-space-like initial data, and were obtained via a method inspired by related pioneering results of Armstrong and Cardaliaguet [2] for Hamilton–Jacobi equations with non-convex finite-range-of-dependence Hamiltonians. We note that in the case of Hamilton–Jacobi homogenization, the limiting PDE is again a Hamilton–Jacobi equation; this differs from our reaction–diffusion case, where the homogenization limit of (1.2) is (1.4) (see [10] for further discussion concerning this relationship).

We note that while we could prove our results in more generality, in particular, also include in Theorem 1.3 reactions that are less well approximated by those with finite ranges of dependence (see in particular [19, hypothesis (H4') & Example 1.6]), we chose not to do so here for the sake of clarity.

Let us now move to precise statements of our hypotheses, which are from [19], and to our main result. We start with the definition of stationary reactions.

**Definition 1.1.** Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space that is endowed with a group of measure-preserving bijections  $\{\Upsilon_y: \Omega \rightarrow \Omega\}_{y \in \mathbb{R}^d}$  such that for all  $y, z \in \mathbb{R}^d$ ,

$$\Upsilon_y \circ \Upsilon_z = \Upsilon_{y+z}.$$

A reaction function  $f: \mathbb{R}^d \times [0, 1] \times \Omega \rightarrow [0, \infty)$ , with the random variables  $X_{x,u} := f(x, u, \cdot)$  being  $\mathcal{F}$ -measurable for all  $(x, u) \in \mathbb{R}^d \times [0, 1]$ , is called *stationary* if for each  $(x, y, u, \omega) \in \mathbb{R}^{2d} \times [0, 1] \times \Omega$  we have

$$f(x, u, \Upsilon_y \omega) = f(x + y, u, \omega).$$

The *range of dependence* of such  $f$  is the infimum of all  $r \in \mathbb{R}^+ \cup \{\infty\}$  such that

$$\mathcal{E}(U) \text{ and } \mathcal{E}(V) \text{ are } \mathbb{P}\text{-independent}$$

for any  $U, V \subseteq \mathbb{R}^d$  with  $d(U, V) \geq r$ , where  $\mathcal{E}(U)$  is the  $\sigma$ -algebra generated by the family of random variables  $\{X_{x,u} \mid (x, u) \in U \times [0, 1]\}$  and  $d(\cdot, \cdot)$  is the standard distance in  $\mathbb{R}^d$ .

Since we are interested in ignition reactions, we assume the following hypothesis.

(H1) The reaction  $f$  is stationary, Lipschitz in both  $x$  and  $u$  with constant  $M \geq 1$ , and there are  $\theta_1 \in (0, \frac{1}{2})$ ,  $m_1 > 1$ , and  $\alpha_1 > 0$  such that  $f(\cdot, u, \cdot) \equiv 0$  for  $u \in [0, \theta_1] \cup \{1\}$ ,  $f(\cdot, u, \cdot) \geq \alpha_1(1 - u)^{m_1}$  for  $u \in [1 - \theta_1, 1)$ , and  $f$  is non-increasing in  $u \in [1 - \theta_1, 1)$ .

In fact, we need to assume slightly more, since one cannot hope for general reactions satisfying (H1) to lead to homogenization for (1.1) as described above, even for homogeneous reactions  $f(x, u, \omega) = f(u)$ . Indeed, if  $f$  is allowed to vanish at some intermediate value  $\theta' \in (\theta_1, 1 - \theta_1)$  and is also “sufficiently larger” on  $(\theta_1, \theta')$  than on  $(\theta', 1)$ , solutions typically form “plateaus” at value  $\theta'$  (or another intermediate value) whose widths grow linearly in time, and so these plateaus will not disappear as  $\varepsilon \rightarrow 0$  and the scaling (1.3) is applied (see [20, 21] for more details). To avoid this scenario, we make the following definition.

**Definition 1.2.** A reaction  $f$  satisfying (H1) is a stationary *pure ignition* reaction if for each  $\eta > 0$  we have

$$\inf_{\substack{(x, \omega) \in \mathbb{R}^d \times \Omega \\ \theta_{x, \omega} + \eta < 1 - \theta_1}} f(x, \theta_{x, \omega} + \eta, \omega) > 0,$$

where the *ignition temperature*  $\theta_{x,\omega}$  is defined by

$$\theta_{x,\omega} := \sup\{\theta \geq 0 \mid f(x, u, \omega) = 0 \text{ for all } u \in [0, \theta]\} \quad (\in [\theta_1, 1 - \theta_1]).$$

As the second author showed in [21], the linearly growing plateaus scenario may occur even for pure ignition reactions, but only in dimensions  $d \geq 4$  (this relates to transience of Brownian motion in  $\mathbb{R}^{d-1}$ ). Therefore our main hypothesis on the reaction  $f$  is the following.

(H2)  $f$  is a stationary pure ignition reaction and  $d \leq 3$ .

Finally, we will assume that  $f$  either has a finite range of dependence, or is close enough to such reactions and has certain uniform decay in  $u$  near  $u = 1$ . The following two hypotheses relate to the second alternative:

(H3) There are  $m_3 \geq 1$  and  $\alpha_3 > 0$  such that for all  $\eta \in (0, \frac{1}{2}\theta_1]$  we have

$$\inf_{\substack{(x,\omega) \in \mathbb{R}^d \times \Omega \\ u \in [1-\theta_1/2, 1]}} (f(x, u - \eta, \omega) - f(x, u, \omega)) \geq \alpha_3 \eta^{m_3}.$$

(H4) There are  $m_4, n_4, \alpha_4 > 0$  such that for each  $n \geq n_4$ , there exists a stationary reaction  $f_n$  with range of dependence  $\leq n$  and  $\|f_n - f\|_\infty \leq \alpha_4 n^{-m_4}$ .

We are now ready to state our main result. In it we denote  $B_r(A) := A + (B_r(0) \cup \{0\})$  and  $A_r^0 := A \setminus \overline{B_r(\partial A)}$  for  $A \subseteq \mathbb{R}^d$  and  $r \geq 0$  (in particular,  $A_0^0$  is the interior of  $A$ ). Note that if  $A$  is convex, so are  $B_r(A)$  and  $A_r^0$ . We also let  $\tilde{\sigma} := \min\{\frac{1}{8m_1}, \frac{m_4}{4m_3+8m_4}\}$ , where we ignore the second term when  $f$  is assumed to have a finite range of dependence (and so (H3)–(H4) is not assumed).

**Theorem 1.3.** *Assume that  $f$  satisfying (H2) either has a finite range of dependence or satisfies (H3)–(H4). There is a Lipschitz function  $c^*: \mathbb{S}^{d-1} \rightarrow (0, \infty)$  such that if  $u_\varepsilon$  solves (1.2) and for some open bounded convex set  $A \subseteq \mathbb{R}^d$  and some  $\nu > 0$  we have*

$$(1 - \theta_1)\chi_{A_\varepsilon^0} \leq u_\varepsilon(0, \cdot, \omega) \leq \chi_{B_{\varepsilon\nu}(A)}$$

for each  $\varepsilon > 0$ , then the following holds with  $\sigma := \frac{1}{2} \min\{\tilde{\sigma}, \nu\}$ : for any  $\theta \in (0, 1)$  and  $T_0 > 0$ , there are constants  $C_0 = C_0(M, \theta_1, m_1, \alpha_1, A, \theta)$  and  $\varepsilon_0 > 0$  such for all  $\varepsilon \in (0, \varepsilon_0]$  we have

$$\mathbb{P}[(\Theta^{A, c^*}(t))_{\varepsilon^\sigma}^0 \subseteq \Gamma_{u_\varepsilon, \theta}(t, \cdot) \subseteq B_{\varepsilon^\sigma}(\Theta^{A, c^*}(t))] \geq 1 - \exp(-\varepsilon^{-2\sigma}).$$

**Remarks.** (1) The limitation of the above estimate to times  $t \geq C_0\varepsilon$  is necessary because if  $\theta$  is close to 1, it takes time  $O(\varepsilon)$  for  $u_\varepsilon$  to reach the value  $\theta$ . If  $\theta < 1 - \theta_1$ , then it is not difficult to show that Theorem 1.3 extends to include  $t \in [0, T_0]$  in the statement because both inclusions then hold for all  $(t, \omega) \in [0, C_0\varepsilon] \times \Omega$  when  $\varepsilon > 0$  is small enough.

- (2) We can also determine on which parameters  $\varepsilon_0$  depends. It turns out that there is some  $\eta_* = \eta_*(M, \theta_1, m_1, \alpha_1) > 0$  such that if for some  $\xi > 0$  we have

$$\inf_{\substack{(x,\omega) \in \mathbb{R}^d \times \Omega \\ u \in [\theta_{x,\omega} + \eta_*, 1 - \theta_1]}} f(x, u, \omega) \geq \xi, \quad (1.6)$$

then  $\varepsilon_0$  can be chosen to depend only on  $A, v, \theta, T_0$  plus on

$$M, \theta_1, m_1, \alpha_1, \xi, \quad (1.7)$$

and either  $\rho$  or  $m_3, \alpha_3, m_4, n_4, \alpha_4,$

depending on whether we assume (H2) plus  $f$  having range of dependence at most  $\rho \in [1, \infty)$ , or we assume (H2)–(H4). See the proof of Theorem 1.3 for details on this.

- (3) Lemma 2.4 below shows that if  $A$  is unbounded (but still convex), then Theorem 1.3 holds locally uniformly, that is, with  $(\Theta^{A,c^*}(t))_{\varepsilon\sigma}^0$  and  $\Gamma_{u_\varepsilon, \theta}(t, \cdot)$  replaced by their intersections with  $B_N(0)$ , for any  $N \in \mathbb{N}$  ( $C_0$  and  $\varepsilon_0$  then also depend on  $N$ ).
- (4) We make no attempt here to optimize the power  $\sigma$  in Theorem 1.3.

### 1.1. Organization of the paper

In Section 2 we collect several important preliminary results as well as most of the notation used later. In Section 3 we construct certain regularized approximations of the sets  $\Theta^{A,c^*}$ , which are then used in the proof of Theorem 1.3 in Section 4.

## 2. Preliminaries and notation

Most of the results in this section are from [19], and we reproduce them here for the reader's convenience. Many of them hold uniformly in  $\omega$  and even without assuming stationarity of the reaction, and in these we will therefore replace (H1) by the following weaker hypothesis:

(H1')  $f$  satisfies (H1) except possibly the stationarity hypothesis.

We collect the needed results assuming (H1') in the following subsection.

### 2.1. General ignition reactions

Let us start with a basic lower bound which shows that general solutions to (1.1) propagate with speed no less than some  $c_0 > 0$  (see [21]). Consider the largest  $M$ -Lipschitz function  $F_0: [0, 1] \rightarrow [0, \infty)$  such that  $F_0(u) \leq \alpha_1(1-u)^{m_1} \chi_{[1-\theta_1, 1]}(u)$  for all  $u \in [0, 1]$ , which of course guarantees that  $f(x, \cdot, \omega) \geq F_0$  for all  $\omega \in \Omega$  when  $f$  satisfies (H1'). Then  $F_0$  is a homogeneous pure ignition reaction, and we let  $c_0 > 0$  be its traveling front speed

(i.e., such that the PDE  $u_t = u_{xx} + F_0(u)$  in one spatial dimension has a *traveling front* solution  $u(t, x) = U(x - c_0 t)$ , with  $U(-\infty) = 1$  and  $U(\infty) = 0$ ).

**Lemma 2.1.** *There exists  $\theta_2 = \theta_2(M, \theta_1, m_1, \alpha_1) < 1$  such that for each  $c < c_0$  and  $\theta < 1$ , there is  $\kappa_0 = \kappa_0(M, \theta_1, m_1, \alpha_1, c, \theta) \geq 1$  such that the following holds: If  $u: (0, \infty) \times \mathbb{R}^d \rightarrow [0, 1]$  is a solution to (1.1) with  $f$  satisfying (H1') and with some  $\omega \in \Omega$ , and if  $u(t_0, y) \geq \theta_2$  for some  $t_0 \geq 1$  and  $y \in \mathbb{R}^d$ , then for all  $t \geq t_0 + \kappa_0$ ,*

$$\inf_{|x-y| \leq c(t-t_0)} u(t, x) \geq \theta.$$

If also  $u_t \geq 0$ , then this clearly holds with any  $t_0 \geq 0$  (and  $\kappa_0$  increased by 1).

Let

$$\theta^* := \frac{\min\{1 - \theta_2, \theta_1\}}{4}. \quad (2.1)$$

The next few results are from [19], and are stated there with  $\theta_2 = \theta_2(M, \frac{1}{2}\theta_1, m_1, \alpha_1(1 - \frac{1}{8}\theta_1)^{m_1-1})$  in the definition of  $\theta^*$ ; however, the remark after [19, Lemma 2.1] explains that they also hold with (2.1) and  $\theta_2 = \theta_2(M, \theta_1, m_1, \alpha_1)$  (moreover, this distinction will be of no consequence here). The first of these is [19, Lemma 2.8], which provides an upper bound on  $\kappa_0(M, \theta_1, m_1, \alpha_1, \frac{c_0}{4}, \theta)$  from Lemma 2.1 as  $\theta \rightarrow 1$ .

**Lemma 2.2.** *Let  $u: [0, \infty) \times \mathbb{R}^d \rightarrow [0, 1]$  solve (1.1) with  $f$  satisfying (H1') and some  $\omega \in \Omega$ . There is  $D_1 = D_1(M, \theta_1, m_1, \alpha_1)$  such that if  $u(t_0, y) \geq 1 - \theta^*$  for some  $t_0 \geq 1$  and  $y \in \mathbb{R}^d$ , then for any  $\theta \in [1 - \theta^*, 1)$  and  $t \geq t_0 + D_1(1 - \theta)^{1-m_1}$  we have*

$$\inf_{|x-y| \leq c_0(t-t_0)/4} u(t, x) \geq \theta.$$

Throughout the rest of the paper we will primarily use Lemma 2.1 with  $c = \frac{c_0}{2}$  and  $\theta = 1 - \theta^*$ , hence we define

$$\kappa_0 := \kappa_0(M, \theta_1, m_1, \alpha_1, \frac{c_0}{2}, 1 - \theta^*).$$

We note that while the two lemmas appear similar, since the latter was stated in [19] with  $c = \frac{c_0}{4}$  inside  $\kappa_0$  instead, we will not try to unify them here for the sake of brevity.

The next result is [19, Lemma 2.2], which constructs smooth initial data  $u_{0,S}$  that approximate  $(1 - \theta^*)\chi_S$  and the corresponding solutions satisfy  $u_t \geq 0$ .

**Lemma 2.3.** *There is  $R_0 = R_0(M, \theta_1, m_1, \alpha_1) \geq 1$  such that for any  $f$  satisfying (H1') and  $S \subseteq \mathbb{R}^d$ , there is a smooth function  $u_{0,S}$  satisfying*

$$\Delta u_{0,S} + F_0(u_{0,S}) \geq 0,$$

and

$$(1 - \theta^*)\chi_S \leq u_{0,S} \leq (1 - \theta^*)\chi_{B_{R_0}(S)}.$$

The following counterpart to Lemma 2.1 (see [10, Lemma 2.2] and [19, Lemma 2.5]) yields an upper bound on the speed of propagation of perturbations of solutions to (1.1).

**Lemma 2.4.** *Let  $u_1, u_2: [0, \infty) \times \mathbb{R}^d \rightarrow [0, 1]$  be, respectively, a subsolution and a supersolution to (1.1) with some  $f$  satisfying (H1') and some  $\omega \in \Omega$ , and let  $r > 0$  and  $y \in \mathbb{R}^d$ . If  $u_1(0, \cdot) \leq u_2(0, \cdot)$  on  $B_r(y)$ , then for all  $(t, x) \in [0, \infty) \times \mathbb{R}^d$  we have*

$$u_1(t, x) \leq u_2(t, x) + 2de^{\sqrt{M/d}(|x-y|-r+2\sqrt{M}dt)}.$$

This estimate yields the following two results. The first of them is just [19, Corollary 2.6], and in the second we let

$$T_u(x) := \inf\{t \geq 0 \mid u(t, x) \geq 1 - \theta^*\}.$$

**Corollary 2.5.** *If  $u: [0, \infty) \times \mathbb{R}^d \rightarrow [0, 1]$  solves (1.1) with some  $f$  satisfying (H1') and some  $\omega \in \Omega$ , then for any  $t \geq 0$  we have*

$$\{x \in \mathbb{R}^d \mid u(t, x) \geq 1 - \theta_1\} \subseteq B_{c_1 t + \kappa_1}(\{x \in \mathbb{R}^d \mid u(0, x) \geq \theta_1\}),$$

where

$$c_1 := 2\sqrt{Md} > c_0 \quad \text{and} \quad \kappa_1 := 1 + \sqrt{d/M} \ln \frac{2d}{1 - 2\theta_1}.$$

**Corollary 2.6.** *Let  $u_1, u_2: [0, \infty) \times \mathbb{R}^d \rightarrow [0, 1]$  solve (1.1) with  $f$  satisfying (H1') and some  $\omega \in \Omega$ . There is  $D_2 = D_2(M, \theta_1, m_1, \alpha_1) \geq 1$  such that if  $u_1(0, \cdot) \leq u_2(t_0, \cdot)$  on  $B_R(0)$  for some  $t_0 \geq 0$  and  $R \geq D_2(1 + T_{u_1}(0))$ , then*

$$T_{u_1}(0) \geq T_{u_2}(0) - t_0 - \kappa_0.$$

*Proof.* By Lemma 2.4 we have

$$u_1(t, 0) \leq u_2(t + t_0, 0) + 2de^{2Mt - \sqrt{M/d}R}$$

for all  $t \geq 0$ . Hence,

$$u_2(T_{u_1}(0) + t_0, 0) \geq u_1(T_{u_1}(0), 0) - \theta^* \geq 1 - 2\theta^*$$

as long as

$$R \geq 2\sqrt{Md}T_{u_1}(0) + \sqrt{d/M} \ln \frac{2d}{\theta^*},$$

which will be guaranteed if we let  $D_2 := 2\sqrt{Md} \ln \frac{2d}{\theta^*}$ . But then Lemma 2.1 yields

$$u_2(T_{u_1}(0) + t_0 + \kappa_0, 0) \geq 1 - \theta^*$$

and the result follows. ■



## 2.2. Stationary ignition reactions

Identification of the front speeds  $c^*(e)$  for (1.1) with a stationary reaction  $f$  is based on the analysis of the dynamics of special solutions starting from approximate characteristic functions of half-spaces. Specifically, for any  $e \in \mathbb{S}^{d-1}$  let  $\mathcal{H}_e^- := \{x \in \mathbb{R}^d \mid x \cdot e \leq 0\}$ , and for any  $y \in \mathbb{R}^d$  let  $u = u(t, x, \omega; e, y)$  be the solution to

$$\begin{aligned} u_t &= \Delta u + f(x, u, \omega) && \text{on } (0, \infty) \times \mathbb{R}^d, \\ u(0, \cdot, \omega; e, y) &= u_{0, \mathcal{H}_e^- + y} && \text{on } \mathbb{R}^d, \end{aligned} \quad (2.2)$$

where  $u_{0, \mathcal{H}_e^- + y}$  satisfies Lemma 2.3 with  $S := \mathcal{H}_e^- + y$ . Then for any  $(x, \omega) \in \mathbb{R}^d \times \Omega$  let

$$T(x, \omega; e, y) := \inf\{t \geq 0 \mid u(t, x, \omega; e, y) \geq 1 - \theta^*\},$$

which one can think of as the arrival time of the solution from (2.2) at  $x$ . Now, [19, Corollary 2.7 & Propositions 3.8, 4.2, and 5.1] (see also [19, estimate (5.5)]) yield the following fluctuation estimate for  $y = 0$ , which immediately extends to all  $y \in \mathbb{R}^d$  by stationarity of  $f$ .

**Proposition 2.7.** *Let  $f$  satisfying (H2) either have range of dependence at most  $\rho \in [1, \infty)$  or satisfy (H3)–(H4). Then there is  $\bar{C} \geq 1$  such that if in the former case we let*

$$\beta := 1 - \frac{1}{2m_1}, \quad (2.3)$$

and in the latter case we let

$$\beta := 1 - \min\left\{\frac{1}{2m_1}, \frac{m_4}{m_3 + 2m_4}\right\}, \quad (2.4)$$

then for each  $e \in \mathbb{S}^{d-1}$ ,  $\lambda \geq 0$ , and  $x, y \in \mathbb{R}^d$  with  $(x - y) \cdot e \geq 1$ , we have

$$\mathbb{P}[|T(x, \cdot; e, y) - \mathbb{E}[T(x, \cdot; e, y)]| \geq \lambda] \leq 2 \exp(-\bar{C}^{-2} \lambda^2 ((x - y) \cdot e)^{-2\beta}).$$

Moreover, there is  $\bar{T}(e) \in [\frac{1}{c_1}, \frac{1}{c_0}]$  (depending on  $f$ ) and for each  $\delta > 0$  there is  $C_\delta \geq 1$  such that for all  $l \geq 1$  we have

$$\left| \frac{\mathbb{E}[T(le + y, \cdot; e, y)]}{l} - \bar{T}(e) \right| \leq C_\delta l^{-1+\beta+\delta}.$$

Finally,  $\bar{C}$  and  $C_\delta$  can be chosen to only depend on (1.7) (and  $C_\delta$  also on  $\delta$ ).

Note that  $\beta \in (\frac{1}{2}, 1)$ . Also, see the discussion at the start of Section 4 below for the last claim. Next we state the definition of deterministic front speeds from [10].

**Definition 2.8.** Let  $f$  satisfy (H1) and let  $e \in \mathbb{S}^{d-1}$ . If there is  $c^*(e) \in \mathbb{R}$  and  $\Omega_e \subseteq \Omega$  with  $\mathbb{P}(\Omega_e) = 1$  such that for each  $\omega \in \Omega_e$  and compact  $K \subseteq \{x \in \mathbb{R}^d \mid x \cdot e > 0\}$  we

have

$$\begin{aligned} \lim_{t \rightarrow \infty} \inf_{x \in (c^*(e)e - K)t} u(t, x, \omega; e, 0) &= 1, \\ \lim_{t \rightarrow \infty} \sup_{x \in (c^*(e)e + K)t} u(t, x, \omega; e, 0) &= 0, \end{aligned}$$

then we say that  $c^*(e)$  is a *deterministic front speed* in direction  $e$  for (1.1).

The comparison principle shows that this definition is independent of the choice of  $u_0, \mathcal{H}_e^-$  in (2.2) with  $y = 0$ , as long as it satisfies Lemma 2.3 (and  $c^*(e)$  is clearly unique if it exists). It was shown in [19, Proposition 6.2] that under the hypotheses of Proposition 2.7, deterministic front speeds for  $f$  exist for all  $e \in \mathbb{S}^{d-1}$ , and in fact they are  $c^*(e) = \bar{T}(e)^{-1} \in [c_0, c_1]$ . Moreover, [19, Theorems 1.3 and 1.4] show that  $c^*$  is Lipschitz continuous on  $\mathbb{S}^{d-1}$ .

If  $A$  is open convex, then we have the very useful formula (1.5). It will be convenient to let (1.5) in fact be the definition of  $\Theta^{A, c^*}(t)$  for any continuous  $c^*: \mathbb{S}^{d-1} \rightarrow (0, \infty)$  (with open convex  $A$ ), and we note that then  $\Theta^{A, c^*}(t)$  is also open convex for each  $t \geq 0$  (openness follows from continuity of  $c^*$ ). Now if  $c: \mathbb{S}^{d-1} \rightarrow (0, \infty)$  is continuous and  $c \leq c^*$ , then clearly  $\Theta^{A, c}(t) \subseteq \Theta^{A, c^*}(t)$  for each  $t \geq 0$ . In particular, if  $c_0 \leq c^* \leq c_1$  for some  $c_0, c_1 \in (0, \infty)$ , then for all  $t \geq 0$  we have

$$B_{c_0 t}(A) \subseteq \Theta^{A, c^*}(t) \subseteq B_{c_1 t}(A). \quad (2.5)$$

Finally, we have the semigroup property

$$\Theta^{A, c^*}(t + s) = \Theta^{\Theta^{A, c^*}(t), c^*}(s) \quad (2.6)$$

for all  $t, s \geq 0$ . The inclusion  $\supseteq$  is trivial, so let us now consider any  $x \in \Theta^{A, c^*}(t + s)$ . Take any  $e \in \mathbb{S}^{d-1}$ , and then  $y_e \in \partial A$  such that  $y_e \cdot e = \sup_{z \in A} z \cdot e$ . Then define

$$x_e := x - \frac{s}{t+s}(x - y_e) = y_e + \frac{t}{t+s}(x - y_e)$$

and note that  $x \in \Theta^{A, c^*}(t + s)$  implies for any  $e' \in \mathbb{S}^{d-1}$  that

$$x_e \cdot e' < y_e \cdot e' + \frac{t}{t+s} c^*(e')(t + s) = \sup_{z \in A} z \cdot e' + c^*(e')t.$$

Hence  $x_e \in \Theta^{A, c^*}(t)$ , which together with  $(x - y_e) \cdot e < c^*(e)(t + s)$  yields

$$x \cdot e < x_e \cdot e + \frac{s}{t+s} c^*(e)(t + s) < \sup_{z \in \Theta^{A, c^*}(t)} z \cdot e + c^*(e)s.$$

Since this holds for all  $e \in \mathbb{S}^{d-1}$ , we can see that  $x \in \Theta^{A, c^*}(t + s)$ , and (2.6) is proved.

### 3. An approximation lemma

In this section we construct a perturbation  $(A', c')$  of  $(A, c^*)$  such that the sets  $\Theta^{A', c'}(t)$  from (1.5) satisfy an interior ball condition on a large time interval. We will use this in the proof of Theorem 1.3 in the following section.

We say that an open set  $U \subseteq \mathbb{R}^d$  satisfies the  $r$ -interior ball condition for some  $r > 0$  if for any  $x \in \partial U$  there is  $y \in U$  such that  $B_r(y) \subseteq U$  and  $x \in \partial B_r(y)$ . We also recall that  $U \subseteq \mathbb{R}^d$  is *strictly convex* if for all  $x, y \in U$ , the line segment connecting  $x$  and  $y$  lies in  $U_0^0 \cup \{x, y\}$ .

**Lemma 3.1.** *Let  $A \subseteq \mathbb{R}^d$  be an open bounded convex set, and let  $c^*: \mathbb{S}^{d-1} \rightarrow (0, \infty)$  be continuous. If  $c_0, c_1 \in (0, \infty)$  are such that  $c_0 \leq c^* \leq c_1$  and  $r > 0$ , then for any  $T \geq \frac{2r}{c_0}$  there is open convex  $A' \subseteq \mathbb{R}^d$  and a continuous function  $c': \mathbb{S}^{d-1} \rightarrow (0, \infty)$  such that*

- (i)  $c' \leq c^*$ ;
- (ii)  $A' \subseteq B_r(A)$  and  $\Theta^{A, c^*}(T) \subseteq B_{c_1 r / c_0}(\Theta^{A', c'}(T))$ ;
- (iii)  $\Theta^{A', c'}(t)$  satisfies the  $r$ -interior ball condition for all  $t \in [0, T]$ .

*Proof.* Since  $A$  is convex, by [6, Theorem 5.4], the signed distance function  $h_A$  of  $A$  (i.e.,  $h_A(x) := d(x, \partial A)$  if  $x \in A^c$ , and  $h_A(x) := -d(x, \partial A)$  otherwise) is a convex function. Take any  $x_0 \in A$  and  $\delta > 0$  such that  $\sup_{x \in A} \delta |x - x_0|^2 < r$ . Then

$$A_1 := \{x \in \mathbb{R}^d \mid h_A(x) + \delta |x - x_0|^2 < 0\}$$

is open, convex, with  $\overline{A_1}$  strictly convex and satisfying  $\overline{A_1} \subseteq A \subseteq B_r(A_1) =: A'$ . Then  $A'$ , which clearly satisfies the  $r$ -interior ball condition, also has strictly convex closure and

$$A \subseteq A' \subseteq \overline{A'} \subseteq B_r(A). \quad (3.1)$$

Since  $A'$  satisfies the  $r$ -interior ball condition and  $\overline{A'}$  is strictly convex, for each  $e \in \mathbb{S}^{d-1}$  there is a unique  $x_e(0) \in \partial A'$  such that the outer unit normal vector to  $\partial A'$  at  $x_e(0)$  is  $e$ , and  $\partial A' = \bigcup_{e \in \mathbb{S}^{d-1}} \{x_e(0)\}$ . Moreover, we have

$$x \cdot e < x_e(0) \cdot e \quad \text{for all } x \in \overline{A'} \setminus x_e(0). \quad (3.2)$$

Similarly, replacing  $A$  in the above argument by  $(\Theta^{A, c^*}(T))_r^0$ , we can find an open, bounded, convex set  $A''$  satisfying the  $r$ -interior ball condition, having strictly convex closure, and

$$(\Theta^{A, c^*}(T))_r^0 \subseteq A'' \subseteq \overline{A''} \subseteq B_r((\Theta^{A, c^*}(T))_r^0) \subseteq (\Theta^{A, c^*}(T)). \quad (3.3)$$

Moreover, for each  $e \in \mathbb{S}^{d-1}$ , there is again a unique  $x_e(T) \in \partial A''$  such that the outer unit normal at  $x_e(T)$  is  $e$ , we have  $\partial A'' = \bigcup_{e \in \mathbb{S}^{d-1}} \{x_e(T)\}$ , as well as

$$x \cdot e < x_e(T) \cdot e \quad \text{for all } x \in \overline{A''} \setminus x_e(T). \quad (3.4)$$

From  $T \geq \frac{2r}{c_0}$ ,  $c^* \geq c_0$ , and (2.5) we now obtain

$$B_r(A) \subseteq B_{c_0 T - r}(A) = (B_{c_0 T}(A))_r^0 \subseteq (\Theta^{A, c^*}(T))_r^0 \subseteq A''. \quad (3.5)$$

Notice also that for any  $x \in \Theta^{A, c^*}(T - \frac{r}{c_0})$ , we have  $B_r(x) \subseteq \Theta^{A, c^*}(T)$  due to (2.6) and (2.5). Therefore  $\Theta^{A, c^*}(T - \frac{r}{c_0}) \subseteq (\Theta^{A, c^*}(T))_r^0$ , and it follows that

$$\Theta^{A, c^*}(T) \subseteq B_{c_1 r / c_0}(\Theta^{A, c^*}(T - c_0^{-1} r)) \subseteq B_{c_1 r / c_0}((\Theta^{A, c^*}(T))_r^0) \subseteq B_{c_1 r / c_0}(A''). \quad (3.6)$$

Now define  $c': \mathbb{S}^{d-1} \rightarrow \mathbb{R}$  by

$$c'(e) := \frac{(x_e(T) - x_e(0)) \cdot e}{T}.$$

Then  $c' > 0$  because  $\overline{A'} \subseteq A''$  by (3.1) and (3.5), and it is also continuous because  $\overline{A'}$  and  $\overline{A''}$  are strictly convex. Since  $A'' \subseteq \Theta^{A, c^*}(T)$  and  $A \subseteq A'$  by (3.3) and (3.1), by using (1.5) and (3.2) we obtain

$$x_e(0) \cdot e + c'(e)T = x_e(T) \cdot e \leq \sup_{y \in A} y \cdot e + c^*(e)T \leq x_e(0) \cdot e + c^*(e)T$$

for each  $e \in \mathbb{S}^{d-1}$ , so (i) holds. Moreover, from (1.5), (3.2), and (3.4) we see that

$$\begin{aligned} \Theta^{A', c'}(T) &= \bigcap_{e \in \mathbb{S}^{d-1}} \{x \in \mathbb{R}^d \mid x \cdot e < x_e(0) \cdot e + c'(e)T\} \\ &= \bigcap_{e \in \mathbb{S}^{d-1}} \{x \in \mathbb{R}^d \mid x \cdot e < x_e(T) \cdot e\} = A''. \end{aligned}$$

This, (3.1), and (3.6) yield (ii).

It remains to show that  $\Theta^{A', c'}(t)$  satisfies the  $r$ -interior ball condition for all  $t \in [0, T]$ . For any  $e \in \mathbb{S}^{d-1}$  and  $t \in [0, T]$ , let

$$x_e(t) := (1 - T^{-1}t)x_e(0) + T^{-1}tx_e(T). \quad (3.7)$$

Then

$$x_e(t) \cdot e = x_e(0) \cdot e + c'(e)t, \quad (3.8)$$

and (3.2) and (3.4) show for all  $e' \in \mathbb{S}^{d-1} \setminus \{e\}$  that

$$x_e(t) \cdot e' < (1 - T^{-1}t)x_{e'}(0) \cdot e' + T^{-1}tx_{e'}(T) \cdot e' = x_{e'}(0) \cdot e' + c'(e')t \quad (= x_{e'}(t) \cdot e').$$

Therefore  $x_e(t) \in \partial\Theta^{A', c'}(t)$  by (1.5), and  $x_e(t) \neq x_{e'}(t)$  for all  $e' \in \mathbb{S}^{d-1} \setminus \{e\}$ .

Since  $\Theta^{A', c'}(t)$  is bounded and convex by (1.5), it has a supporting hyperplane for each (outer) direction  $e \in \mathbb{S}^{d-1}$ . From  $x_e(t) \in \partial\Theta^{A', c'}(t)$ , (3.8), and (1.5) we see that this hyperplane is precisely  $\{x \cdot e = x_e(t) \cdot e\}$ . Since  $x_{e'}(t) \cdot e < x_e(t) \cdot e$  for all  $e' \in \mathbb{S}^{d-1} \setminus \{e\}$  and  $x_{e'}(t)$  is continuous in  $e'$  for each  $t \in [0, T]$  (because it is for  $t = 0, T$ , by strict convexity of  $A', A''$ ), it follows that for each  $\varepsilon > 0$ , there is  $\delta \in (0, 1)$  such

that if  $0 < |e' - e| < \delta$ , then the supporting hyperplane  $\{x \cdot e' = x_{e'}(t) \cdot e'\}$  contains the point  $x_{e'}(t)$  satisfying  $x_{e'}(t) \cdot e < x_e(t) \cdot e$  and  $|x_{e'}(t) - x_e(t)| < \varepsilon$ . This and  $x_e(t) \cdot e' < x_{e'}(t) \cdot e'$  show that the closest point to  $x_e(t)$  that lies in the intersection of the two hyperplanes, which is  $x_e(t) + s_{e'} \frac{e' - (e' \cdot e)e}{|e' - (e' \cdot e)e|}$  for some  $s_{e'} \in \mathbb{R}$ , must have  $s_{e'} \in (0, \varepsilon)$ . But since the points from  $\{x \cdot e = x_e(t) \cdot e\}$  that satisfy  $x \cdot e' \leq x_{e'}(t) \cdot e'$  are precisely those with  $(x - x_e(t)) \cdot \frac{e' - (e' \cdot e)e}{|e' - (e' \cdot e)e|} \leq s_{e'}$ , and this holds for all  $e'$  with  $|e' - e| < \delta$ , we see that  $\partial \Theta^{A', c'}(t) \cap \{x \cdot e = x_e(t) \cdot e\} \subseteq B_\varepsilon(x_e(t))$ . Taking  $\varepsilon \rightarrow 0$  shows that  $\partial \Theta^{A', c'}(t) \cap \{x \cdot e = x_e(t) \cdot e\} = \{x_e(t)\}$ , and so

$$\partial \Theta^{A', c'}(t) = \bigcup_{e \in \mathbb{S}^{d-1}} \{x_e(t)\}.$$

Now fix any  $t \in [0, T]$  and  $x \in \partial \Theta^{A', c'}(t)$ , and let  $e \in \mathbb{S}^{d-1}$  be such that  $x_e(t) = x$ . Since  $A'$  and  $A''$  satisfy the  $r$ -interior ball condition, there are  $y_0, y_T$  such that  $B^0 := B_r(y_0)$  and  $B^T := B_r(y_T)$  satisfy  $B^0 \subseteq A'$ ,  $B^T \subseteq A''$ ,  $x_e(0) \in \partial B^0$ , and  $x_e(T) \in \partial B^T$ . Now if

$$B^t := B_r((1 - T^{-1}t)y_0 + T^{-1}ty_T),$$

then (3.7) shows that  $x = x_e(t) \in \partial B^t$ . It therefore remains to show that  $B^t \subseteq \Theta^{A', c'}(t)$ . For any  $z \in B^t$ , there are  $z_0 \in B^0$  and  $z_T \in B^T$  such that  $z = (1 - T^{-1}t)z_0 + T^{-1}tz_T$ . It follows from (3.2) and (3.4) that for any  $e' \in \mathbb{S}^{d-1}$  we have

$$\begin{aligned} z \cdot e' &< (1 - T^{-1}t)x_{e'}(0) \cdot e' + T^{-1}tx_{e'}(T) \cdot e' = x_{e'}(0) \cdot e' + c'(e')t \\ &= \sup_{y \in A'} y \cdot e' + c'(e')t, \end{aligned}$$

and hence  $z \in \Theta^{A', c'}(t)$  by (1.5). Thus  $B^t \subseteq \Theta^{A', c'}(t)$ , finishing the proof.  $\blacksquare$

## 4. Proof of Theorem 1.3

We will do the proof simultaneously for  $f$  satisfying (H2) and having finite range of dependence (then we assume this range to be at most  $\rho \in [1, \infty)$ ), and for  $f$  satisfying (H2)–(H4). This is because Proposition 2.7 applies in both these cases, with definitions (2.3) and (2.4), respectively (we will use these below). We also let  $c^*$  be the deterministic front speed for (1.1).

Before we start, for any solution  $u: [0, \infty) \times \mathbb{R}^d \rightarrow [0, 1]$  to (1.1) and any  $0 < \eta < \theta < 1$ , we let the *width of the transition zone* of  $u$  from  $\eta$  to  $\theta$  (at any time  $t \geq 0$ ) be (see [21])

$$L_{u, \eta, \theta}(t, \omega) := \inf\{L > 0 \mid \Gamma_{u, \eta}(t, \omega) \subseteq B_L(\Gamma_{u, \theta}(t, \omega))\}. \quad (4.1)$$

It follows from [19, Remark 2 after Definition 2.3] and [19, Lemma 2.4] that if  $f$  satisfies (H2), then there are  $\mu_*, \kappa_* > 0$  such that if  $u$  solves (1.1) with some  $\omega \in \Omega$  and initial

data satisfying Lemma 2.3 for some  $S \subseteq \mathbb{R}^d$ , then

$$\begin{aligned} \sup_{t \geq 0, \eta \in (0, 1 - \theta^*)} \frac{L_{u, \eta, 1 - \theta^*}(t)}{1 + |\ln \eta|} &\leq \mu_*^{-1}, \\ \inf_{\substack{(t, x) \in [\kappa_*, \infty) \times \mathbb{R}^d \\ u(t, x) \in [\theta^*, 1 - \theta^*]}} u_t(t, x) &\geq \mu_*. \end{aligned} \quad (4.2)$$

We will in fact only need this in the first part of this proof, for  $S$  being half-spaces (so for the solutions from (2.2)).

Moreover, it follows from the above results in [19] that there is  $\eta_* = \eta_*(M, \theta_1, m_1, \alpha_1) > 0$  such that  $\mu_*, \kappa_*$  can be chosen to depend only on  $M, \theta_1, m_1, \alpha_1$  from (H1) and  $\xi > 0$  from (1.6). Similarly,  $\bar{C}$  and  $C_\delta$  in Proposition 2.7 can be chosen to depend only on (1.7) (and  $C_\delta$  also depends on  $\delta$ ) because they depend on the constants from [19, list (2.10)] (plus  $\rho$  in the finite range of dependence setting), which is (1.7) without  $\xi, \rho$  and also with  $\mu_*, \kappa_*, m_2, \alpha_2, m'_4$ . But when we assume (H2), we can simply let  $m_2 := 1$  and  $\alpha_2 := 0$  in [19] because  $1 + |\ln \eta| \leq \eta^{-1}$  for  $\eta \in (0, 1)$ ; and when we also assume (H4), in which case  $m'_4$  also plays a role in [19], we can let  $m'_4 := \infty$ .

In the rest of this section, constants that include  $C$  will again depend on (1.7), while any other dependence will be explicitly declared in the notation (e.g.,  $C'_{\varepsilon, T}$  also depends on  $\varepsilon, T$ ). These constants may also vary from one expression to the next.

We are now ready for the proof of Theorem 1.3, which we split into two main parts. Without loss, we will assume that  $T_0 \geq 1$ .

#### 4.1. Proof of the ‘‘upper bound’’

In this part we will prove (4.19) below for all small  $\varepsilon > 0$ . Let us pick

$$\sigma' := \min\left\{\frac{1 - \beta}{4}, v\right\} = 2\sigma, \quad (4.3)$$

and some  $\varepsilon_0 \in (0, \frac{1}{2})$  such that

$$\max\left\{(1 + |\ln(\theta - \varepsilon_0^{1/m_1})|)\mu_*^{-1}\varepsilon_0^{1-2\sigma'}, ((\theta^*)^{-1} + 4C')\varepsilon_0^{\sigma'}\right\} \leq 1, \quad (4.4)$$

with  $C' \geq 1$  to be determined later. Note that this  $\varepsilon_0$  depends only on (1.7) and  $v, \theta$ . Fix any  $y \in \partial A$  and  $e_y \in \mathbb{S}^{d-1}$  such that  $A \subseteq \mathcal{H}_{e_y}^- + y$  (such an  $e_y$  always exists because  $A$  is convex, and we call it an outer normal to  $\partial A$  at  $y$ ). Then let

$$v_y^\varepsilon(t, x, \omega) := u(t, x, \omega; e_y, \varepsilon^{-1}y),$$

with the right-hand-side function defined in (2.2). If we now let  $u^\varepsilon(t, x, \omega) := u_\varepsilon(\varepsilon t, \varepsilon x, \omega)$ , then Lemmas 2.1 and 2.2 yield

$$v_y^\varepsilon(\tau_\varepsilon, \cdot, \omega) \geq (1 - \varepsilon^{1/m_1})\chi_{\mathcal{H}_{e_y}^- + \varepsilon^{-1}(y + \varepsilon^v e_y)} \geq u^\varepsilon(0, \cdot, \omega) - \varepsilon^{1/m_1} \quad (4.5)$$

with

$$\tau_\varepsilon := \kappa_0 + 2c_0^{-1}\varepsilon^{\nu-1} + D_1\varepsilon^{(1-m_1)/m_1}$$

(then also  $\tau_\varepsilon \leq C\varepsilon^{\sigma'-1}$  for some  $C > 0$  due to (4.3) and  $\nu \geq \sigma'$ ).

It follows from (4.5) and the last claim in [19, Lemma 3.7] with  $f_2 = f_1 = f$  (this extends [19, Lemma 2.9] from initial data approximating characteristic functions of balls to those in (2.2), which instead approximate characteristic functions of half-spaces) that if we extend  $f$  to  $\mathbb{R}^d \times (1, \infty) \times \Omega$  by 0, then with  $M_* := \frac{1+M}{\mu_*}$  we have that

$$v_y^\varepsilon((1 + M_*\varepsilon^{1/m_1})t + \tau_\varepsilon, x, \omega) + \varepsilon^{1/m_1}$$

is a supersolution to (1.1) for  $(t, x) \in (\kappa_*, \infty) \times \mathbb{R}^d$ . Hence, if we let  $\tau'_\varepsilon := \tau_\varepsilon + (1 + M_*\varepsilon^{1/m_1})\kappa_*$  and use  $(v_y^\varepsilon)_t \geq 0$  (by Lemma 2.3) and (4.5), we obtain from the comparison principle that

$$w_y^\varepsilon(t, x, \omega) := v_y^\varepsilon((1 + M_*\varepsilon^{1/m_1})t + \tau'_\varepsilon, x, \omega) + \varepsilon^{1/m_1} \geq u^\varepsilon(t, x, \omega)$$

for all  $(t, x) \in (0, \infty) \times \mathbb{R}^d$ . Therefore,

$$w_{\varepsilon, y}(\cdot, \cdot, \omega) := w_y^\varepsilon(\varepsilon^{-1}\cdot, \varepsilon^{-1}\cdot, \omega) \geq u_\varepsilon(\cdot, \cdot, \omega) \quad (4.6)$$

on  $(0, \infty) \times \mathbb{R}^d$ . We can now use this estimate to prove (4.19).

Let us first obtain a crude  $\omega$ -uniform bound. Corollary 2.5 yields

$$\Gamma_{v_y^\varepsilon, 1-\theta^*}(t, \omega) \subseteq \Gamma_{v_y^\varepsilon, 1-\theta_1}(t, \omega) \subseteq \mathcal{H}_e^- + \varepsilon^{-1}y + (R_0 + \kappa_1 + c_1t)e_y,$$

and so from  $R_0 + \kappa_1 + c_1[(1 + M_*\varepsilon^{1/m_1})t + \tau'_\varepsilon] \leq C(t + \varepsilon^{\sigma'-1})$  for some  $C > 0$ , we obtain

$$\Gamma_{w_{\varepsilon, y}, 1-\theta^*}(t, \omega) \subseteq \mathcal{H}_e^- + y + C(t + \varepsilon^{\sigma'})e_y$$

for all  $t \geq 0$ . From (4.2) and (4.4) we see that  $\sup_{t \geq 0} L_{v_y^\varepsilon, \theta - \varepsilon^{1/m_1}, 1-\theta^*}(t) \leq \varepsilon^{2\sigma'-1}$ , hence

$$\sup_{t \geq 0} L_{w_{\varepsilon, y}, \theta, 1-\theta^*}(t) \leq \varepsilon \sup_{t \geq 0} L_{v_y^\varepsilon, \theta - \varepsilon^{1/m_1}, 1-\theta^*}(t) \leq \varepsilon^{2\sigma'}. \quad (4.7)$$

So in view of (4.6), for all  $t \geq 0$  we get

$$\Gamma_{u_{\varepsilon, \theta}}(t, \omega) \subseteq \Gamma_{w_{\varepsilon, y}, \theta}(t, \omega) \subseteq \mathcal{H}_e^- + y + C(t + \varepsilon^{\sigma'})e_y. \quad (4.8)$$

Since this holds for all  $y \in \partial A$  and all normal directions  $e_y$  at  $y$ , there exists  $C > 0$  such that for all  $t \geq 0$  and  $\omega \in \Omega$  we have

$$\Gamma_{u_{\varepsilon, \theta}}(t, \omega) \subseteq B_{C(t + \varepsilon^{\sigma'})}(A). \quad (4.9)$$

Now fix any  $T \geq \varepsilon^{\sigma'} (> \varepsilon)$ , so we have

$$\Gamma_{u_{\varepsilon, \theta}}(T, \omega) \subseteq B_{\tilde{C}T}(A), \quad (4.10)$$

with  $\tilde{C} := 2 \max\{C, c_1\}$ . Next, take any  $\bar{y} \in B_{\tilde{C}T}(A) \setminus \overline{\Theta^{A, c^*}(T)}$ , let  $y$  be the unique projection of  $\bar{y}$  onto  $\partial A$ , let  $e_y := \frac{\bar{y}-y}{|\bar{y}-y|}$  (which is then an outer normal to  $\partial A$  at  $y$ ), and define  $v_y^\varepsilon$ ,  $w_y^\varepsilon$ , and  $w_{\varepsilon, y}$  as above. Then the definition of  $\Theta^{A, c^*}(\cdot)$  yields

$$c^*(e_y)T \leq |\bar{y} - y| \leq \tilde{C}T. \quad (4.11)$$

Consider the arrival times

$$\begin{aligned} T_\varepsilon^w(\bar{y}, \omega) &:= \inf\{t \geq 0 \mid w_{\varepsilon, y}(t, \bar{y}, \omega) \geq 1 - \theta^*\}, \\ T_\varepsilon^v(\bar{y}, \omega) &:= \varepsilon^{-1} \inf\{t \geq 0 \mid v_y^\varepsilon(t, \varepsilon^{-1}\bar{y}, \omega) \geq 1 - \theta^*\}, \end{aligned}$$

both of which are  $\leq CT$  for some  $C > 0$  by (4.11) and Lemma 2.1. Since (4.3) and (4.4) yield  $\varepsilon^{1/m_1} \leq \theta^*$  (and so  $1 - \theta^* - \varepsilon^{1/m_1} \geq \theta_2$ ), Lemma 2.1,  $\sigma' < \frac{1}{m_1}$ , and  $\varepsilon\tau'_\varepsilon \leq C\varepsilon^{\sigma'}$  imply

$$T_\varepsilon^v(\bar{y}, \omega) \leq T_\varepsilon^w(\bar{y}, \omega) + C\varepsilon^{1/m_1}T + \varepsilon\tau'_\varepsilon + \varepsilon\kappa_0 \leq T_\varepsilon^w(\bar{y}, \omega) + C(1+T)\varepsilon^{\sigma'}. \quad (4.12)$$

Next, after applying Proposition 2.7 to  $v_y^\varepsilon$  with  $\delta := \sigma'$  and  $l := |\bar{y} - y| = (\bar{y} - y) \cdot e_y$ , and using  $c^*(e_y) = \bar{T}(e_y)^{-1}$  and  $\beta \leq 1 - 4\sigma'$ , we get

$$\left| \frac{\mathbb{E}[T_\varepsilon^v(\bar{y}, \cdot)]}{|\bar{y} - y|} - \frac{1}{c^*(e_y)} \right| \leq C(\varepsilon^{-1}|\bar{y} - y|)^{-3\sigma'}$$

(here we call the constant  $C_\delta = C_{\sigma'}$  just  $C$ ). This and (4.11) yield

$$T - \mathbb{E}[T_\varepsilon^v(\bar{y}, \cdot)] \leq C|\bar{y} - y|^{1-3\sigma'}\varepsilon^{3\sigma'} \leq C(1+T)\varepsilon^{3\sigma'}. \quad (4.13)$$

Using (4.11) again, it follows from Proposition 2.7 that for all  $\lambda \geq 0$ ,

$$\begin{aligned} \mathbb{P}[|T_\varepsilon^v(\bar{y}, \cdot) - \mathbb{E}[T_\varepsilon^v(\bar{y}, \cdot)]| > \varepsilon\lambda] &\leq 2 \exp(-C^{-2}\lambda^2(\varepsilon^{-1}|\bar{y} - y|)^{-2\beta}) \\ &\leq 2 \exp(-C^{-2}\lambda^2 T^{-2\beta}\varepsilon^{2\beta}). \end{aligned} \quad (4.14)$$

Now take  $\lambda := CT^\beta\varepsilon^{-\beta-\sigma'}$  with  $C$  from the last expression, and then  $\lambda \leq CT\varepsilon^{2\sigma'-1}$  by  $\beta \leq 1 - 4\sigma'$  and  $T \geq \varepsilon^{\sigma'}$ . Hence (4.13) and (4.14) show that there is  $C > 0$  such that

$$\mathbb{P}[T_\varepsilon^v(\bar{y}, \cdot) \leq T - C(1+T)\varepsilon^{2\sigma'}] \leq 2 \exp(-\varepsilon^{-2\sigma'}).$$

Using (4.12) yields, with some  $C > 0$  and  $C_{\varepsilon, T} := C(1+T)\varepsilon^{\sigma'}$ ,

$$\mathbb{P}[w_{\varepsilon, y}(T - C_{\varepsilon, T}, \bar{y}, \cdot) \geq 1 - \theta^*] = \mathbb{P}[T_\varepsilon^w(\bar{y}, \cdot) \leq T - C_{\varepsilon, T}] \leq 2 \exp(-\varepsilon^{-2\sigma'}). \quad (4.15)$$

Now let  $r := \varepsilon^{2\sigma'} \in (\varepsilon, T)$  because  $\sigma' \in (0, \frac{1}{8})$ , and note that (4.7) implies

$$L_\varepsilon := r + \sup_{z \in \partial A} \sup_{t \geq 0} L_{w_{\varepsilon, z}, \theta, 1-\theta^*}(t, \omega) \leq 2\varepsilon^{2\sigma'}. \quad (4.16)$$



Next let  $G_{\varepsilon,T} \subseteq B_{\tilde{C}_T}(A) \setminus \Theta^{A,c^*}(T)$  be some set containing one point from each cube in  $\mathbb{R}^d$  with side length  $rd^{-1/2}$  and all vertices in  $rd^{-1/2}\mathbb{Z}^d$  that has a non-empty intersection with  $B_{\tilde{C}_T}(A) \setminus \Theta^{A,c^*}(T)$ . Note that then  $B_{\tilde{C}_T}(A) \setminus \Theta^{A,c^*}(T) \subseteq B_r(G_{\varepsilon,T})$ .

Let us now consider any  $\bar{y} \in G_{\varepsilon,T}$ . If we have  $w_{\varepsilon,y}(t, x, \omega) \geq \theta$  for some  $x \in B_r(\bar{y})$  and  $t \geq 0$ , then (4.1) shows that there is  $x' \in B_{L_\varepsilon}(\bar{y})$  such that  $w_{\varepsilon,y}(t, x', \omega) \geq 1 - \theta^*$ . Applying Lemma 2.1 to  $v_y^\varepsilon$  then implies  $w_{\varepsilon,y}(t + 2c_0^{-1}L_\varepsilon + \varepsilon\kappa_0, \bar{y}, \omega) \geq 1 - \theta^*$ . Since

$$C_{\varepsilon,T} + 2c_0^{-1}L_\varepsilon + \varepsilon\kappa_0 \leq C'(1+T)\varepsilon^{\sigma'} =: C'_{\varepsilon,T}$$

by (4.16) (with some  $C' \geq 1$ , that will then also be the number in (4.4)), from (4.15) we get

$$\mathbb{P}[w_\varepsilon(T - C'_{\varepsilon,T}, x, \cdot) \geq \theta \text{ for some } x \in B_r(\bar{y})] \leq 2\exp(-\varepsilon^{-2\sigma'}) \quad (4.17)$$

(with the understanding that this probability is 0 when  $T - C'_{\varepsilon,T} < 0$ ). Then (4.10), (4.17),  $w_{\varepsilon,y} \geq u_\varepsilon$ ,  $(w_{\varepsilon,y})_t \geq 0$ , and the fact that  $|G_{\varepsilon,T}| \leq C_A T^d r^{-d}$  for some  $C_A > 0$  (depending only on the diameter of  $A$  and (1.7)) yield

$$\begin{aligned} & \mathbb{P}\left[\bigcup_{t \in [0, T - C'_{\varepsilon,T}]} \Gamma_{u_\varepsilon, \theta}(t, \cdot) \not\subseteq \Theta^{A,c^*}(T)\right] \\ & \leq \sum_{\bar{y} \in G_{\varepsilon,T}} \mathbb{P}[w_\varepsilon(T - C'_{\varepsilon,T}, x, \cdot) \geq \theta \text{ for some } x \in B_r(\bar{y})] \\ & \leq 2C_A T^d r^{-d} \exp(-\varepsilon^{-2\sigma'}). \end{aligned} \quad (4.18)$$

From (4.4) and  $T_0 \geq 1$  we now have  $C'_{\varepsilon,T_0} < \frac{T_0}{2}$ . So for any  $t \in [C'_{\varepsilon,T_0}, T_0]$ , there is a unique  $T \in (t, 2t)$  such that  $t = T - C'_{\varepsilon,T}$ . Then  $C'_{\varepsilon,T} \leq 2C'_{\varepsilon,T_0}$  and so

$$\Theta^{A,c^*}(T) \subseteq B_{3c_1 C'_{\varepsilon,T_0}}(\Theta^{A,c^*}(t - C'_{\varepsilon,T_0}))$$

by  $c^* \leq c_1$ . Then (4.18) yields

$$\begin{aligned} & \mathbb{P}[\Gamma_{u_\varepsilon, \theta}(s, \cdot) \not\subseteq B_{3c_1 C'_{\varepsilon,T_0}}(\Theta^{A,c^*}(s)) \text{ for some } s \in [t - C'_{\varepsilon,T_0}, t]] \\ & \leq 2^{d+1} C_A T_0^d \varepsilon^{-2d\sigma'} \exp(-\varepsilon^{-2\sigma'}), \end{aligned}$$

and so from  $\lceil T_0(C'_{\varepsilon,T_0})^{-1} \rceil \leq 2\varepsilon^{-\sigma'}$  we obtain

$$\begin{aligned} & \mathbb{P}[\Gamma_{u_\varepsilon, \theta}(s, \cdot) \not\subseteq B_{3c_1 C'_{\varepsilon,T_0}}(\Theta^{A,c^*}(s)) \text{ for some } s \in [0, T_0]] \\ & \leq 2^{d+2} C_A T_0^d \varepsilon^{-(2d+1)\sigma'} \exp(-\varepsilon^{-2\sigma'}). \end{aligned}$$

If we make  $\varepsilon_0 > 0$  smaller yet, depending on the constants mentioned after (4.4) as well as  $A$  and  $T_0$ , then for all  $\varepsilon \in (0, \varepsilon_0)$  this shows

$$\mathbb{P}[\Gamma_{u_\varepsilon, \theta}(t, \cdot) \subseteq B_{\varepsilon^\sigma}(\Theta^{A,c^*}(t)) \text{ for all } t \in [0, T_0]] \geq 1 - \exp(-\varepsilon^{-2\sigma}). \quad (4.19)$$

## 4.2. Proof of the “lower bound”

The second part of this proof is considerably more involved than the first. This is because a lower bound for the solution  $u_\varepsilon$  is needed here, but the solutions  $u(\cdot, \cdot, \cdot; e, y)$  with front-like initial data cannot serve as global barriers from below. We overcome this problem by using them as approximate local barriers on short time intervals, making use of Lemma 3.1 in the process.

Our goal is now to prove a counterpart to (4.19), namely

$$\mathbb{P}[(\Theta^{A,c^*}(t))_{\varepsilon^\sigma}^0 \subseteq \Gamma_{u_\varepsilon, \theta}(t, \cdot) \text{ for all } t \in [C_{\theta,A}\varepsilon, T_0]] \geq 1 - \exp(-\varepsilon^{-2\sigma}) \quad (4.20)$$

for all  $\varepsilon \in (0, \varepsilon_0)$ , with some  $C_{\theta,A}$  and with  $\varepsilon_0 > 0$  depending on the constants mentioned after (4.4) as well as  $A$  and  $T_0$ . Of course, this will then finish the proof.

We will simplify our task a little, so we only have to study  $(1 - \theta^*)$ -level sets of a special solution  $\tilde{u}^\varepsilon$  to (1.1) with initial data  $\tilde{u}_0^\varepsilon$  satisfying Lemma 2.3 with  $S = \varepsilon^{-1}(A_{\varepsilon^\nu}^0) =: A^\varepsilon$ . We again let  $\tilde{u}_\varepsilon(t, x, \omega) := \tilde{u}^\varepsilon(\frac{t}{\varepsilon}, \frac{x}{\varepsilon}, \omega)$ , and claim that for some  $\tau_0 = \tau_0(M, \theta_1, m_1, \alpha_1, \theta, A) > 0$  we have

$$\Gamma_{\tilde{u}_\varepsilon, 1-\theta^*}(t - \tau_0\varepsilon, \omega) \subseteq \Gamma_{u_\varepsilon, \theta}(t, \omega) \quad (4.21)$$

for all  $t \geq \tau_0\varepsilon$ . Indeed, let  $U: [0, \infty) \rightarrow [0, 1]$  be a solution to  $U' = F_0(U)$  with initial data  $U(0) = 1 - \theta_1$ . Since  $F_0(u) > 0$  for all  $u \in [1 - \theta_1, 1)$ , there is  $\tau_1 = \tau_1(m_1, \alpha_1) > 0$  such that  $U(\tau_1) \geq 1 - \frac{1}{2}\theta^*$ . It follows from Lemma 2.4 with  $u_1(t, x) := U(t)$ ,  $u_2 := u^\varepsilon$ , and  $r := 2\sqrt{Md}\tau_1 + \sqrt{d/M} \ln \frac{4d}{\theta^*}$  that

$$u^\varepsilon(\tau_1, \cdot, \omega) \geq U(\tau_1) - 2de^{\sqrt{M/d}(-r+2\sqrt{Md}\tau_1)} \geq 1 - \theta^*$$

on  $(A^\varepsilon)_r^0$  (which is non-empty if  $\varepsilon_0 > 0$  is small enough, depending on  $A, \nu$ ). Next let

$$\tau_2 := \tau_1 + 2c_0^{-1}r' + 2c_0^{-1}R_0 + \kappa_0,$$

where  $B_{r'}((A^\varepsilon)_r^0) \supseteq A^\varepsilon$  for all small enough  $\varepsilon > 0$  (such an  $r' = r'(A, r)$  exists because  $A$  is convex and hence  $\partial A$  is Lipschitz). Then  $u^\varepsilon(\tau_2, \cdot, \omega) \geq 1 - \theta^*$  on  $B_{R_0}(A^\varepsilon)$  by Lemma 2.1, so  $u^\varepsilon(\tau_2, \cdot, \omega) \geq \tilde{u}^\varepsilon(0, \cdot, \omega)$ . Thus for all  $(t, \omega) \in [0, \infty) \times \Omega$  we obtain

$$\Gamma_{\tilde{u}_\varepsilon, 1-\theta^*}(t, \omega) \subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t + \tau_2\varepsilon, \omega).$$

When  $\theta \leq 1 - \theta^*$ , this immediately yields (4.21) with  $\tau_0 := \tau_2$ . When  $\theta \in (1 - \theta^*, 1)$ , this and Lemma 2.2 yield (4.21) with  $\tau_0 := \tau_2 + 1 + D_1(1 - \theta)^{1-m_1}$ .

Now let  $\sigma'$  be from (4.3). We claim that (4.20) will follow once we show that there is  $\tilde{C} > 0$  such that for all  $T_0 \geq 1$  and  $\varepsilon > 0$  small enough (depending on the constants after (4.4) and  $A, T_0$ ) we have

$$\mathbb{P}[(\Theta^{\varepsilon A^\varepsilon, c^*}(t))_{\tilde{C}T_0\varepsilon^{\sigma'}}^0 \subseteq \Gamma_{\tilde{u}_\varepsilon, 1-\theta^*}(t, \cdot) \text{ for all } t \in [0, T_0]] \geq 1 - \exp(-\varepsilon^{-\sigma'}). \quad (4.22)$$

Indeed, for all small  $\varepsilon > 0$  we have

$$(\Theta^{A, c^*}(t))_{2\varepsilon^{\sigma'}}^0 \subseteq \Theta^{\varepsilon A^\varepsilon, c^*}(t - \tau_0\varepsilon)$$

for all  $t \geq \tau_0 \varepsilon$  due to the convexity of  $A$ , (1.5), and (4.3). This and (4.21) now show that if  $(\Theta^{\varepsilon A^\varepsilon, c^*}(t))_{\tilde{C} T_0 \varepsilon^{\sigma'}}$  is contained in  $\Gamma_{\tilde{u}_\varepsilon, 1-\theta^*}(t, \omega)$  for all  $t \in [0, T_0]$ , then

$$(\Theta^{A, c^*}(t))_{(2+\tilde{C} T_0) \varepsilon^{\sigma'}} \subseteq \Gamma_{u_\varepsilon, \theta}(t, \omega)$$

for all  $t \in [\tau_0 \varepsilon, T_0]$ . So again, if we make  $\varepsilon_0 > 0$  smaller yet, depending on the constants mentioned after (4.4) as well as  $A$  and  $T_0$ , then (4.22) will indeed imply (4.20) with  $C_{\theta, A} := \tau_0$ .

So let us now prove (4.22). In the proof, we will write  $u_\varepsilon$  and  $A$  in place of  $\tilde{u}_\varepsilon$  and  $\varepsilon A^\varepsilon$  (so  $(u_\varepsilon)_t \geq 0$ ), and denote

$$\sigma'' := \frac{1-\beta}{2(2-\beta)} \in (\sigma', \frac{1}{6}) \quad \text{and} \quad r_\varepsilon := \varepsilon^{\sigma''} \quad (4.23)$$

(recall that  $\beta \in (\frac{1}{2}, 1)$ ). Let us also pick  $\varepsilon_0 \in (0, \frac{1}{2})$  such that

$$\max\{2c_0^{-1} \varepsilon_0^{\sigma'' - \sigma'}, D_2(1 + \kappa_0 + c_1(1 + 4c_0^{-1})) \varepsilon_0^{\sigma''}\} \leq 1 \quad (4.24)$$

(where  $\kappa_0$  is from Lemma 2.1 and  $D_2$  from Corollary 2.6); we will need to further decrease  $\varepsilon_0$  later. For any  $u: [0, \infty) \times \mathbb{R}^d \times \Omega \rightarrow [0, 1]$ , let us denote by

$$T_u(x, \omega) := \inf\{t \geq 0 \mid u(t, x, \omega) \geq 1 - \theta^*\}$$

the arrival time at  $x \in \mathbb{R}^d$ .

Now we fix any  $\varepsilon \in (0, \varepsilon_0]$  and  $T \in [\varepsilon^{\sigma'}, T_0]$ , and pick  $A', c'$  as in Lemma 3.1 with  $r = r_\varepsilon$  (then  $T \geq \frac{2r}{c_0}$  by (4.24)). Then let  $\Theta_{\varepsilon, T}^k := \Theta^{A', c'}(kr_\varepsilon^2)$  for each  $k \in \mathbb{N}$ , and

$$t_k(\omega) := \inf\{t \geq 0 \mid u_\varepsilon(t, \cdot, \omega) \geq (1 - \theta^*) \chi_{\Theta_{\varepsilon, T}^k}\}$$

for each  $\omega \in \Omega$ . Note that from Lemmas 2.1 and 3.1 (ii) we obtain

$$t_0(\cdot) \leq 2c_0^{-1} r_\varepsilon + \kappa_0 \varepsilon. \quad (4.25)$$

Let  $K := \lceil Tr_\varepsilon^{-2} \rceil$ , so that clearly  $\Theta^{A', c'}(T) \subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t_K(\omega), \omega)$  for all  $\omega \in \Omega$ . Our goal is now to prove (4.36) below, which is a high-probability upper bound on  $t_{k+1}(\cdot) - t_k(\cdot)$  for each  $k = 0, 1, \dots, K-1$ . Adding these will then yield a high-probability upper bound on  $t_K(\cdot)$ , and therefore also estimate (4.37) below, which is very close to (4.22) for the single time  $T$  instead of all  $t \in [0, T_0]$ . We will then upgrade this to (4.22).

Fix any  $x_0 \in \Theta_{\varepsilon, T}^{k+1} \setminus \Theta_{\varepsilon, T}^k$  and  $\omega \in \Omega$ . Since  $\Theta_{\varepsilon, T}^k$  is convex, there is  $x_1 \in \partial \Theta_{\varepsilon, T}^k$  such that  $d(x_0, \Theta_{\varepsilon, T}^k) = |x_0 - x_1|$ , and  $e := \frac{x_0 - x_1}{|x_0 - x_1|}$  is an outer normal to  $\partial \Theta_{\varepsilon, T}^k$  at  $x_1$ . Then

$$d_0 := |x_0 - x_1| \leq c'(e) r_\varepsilon^2 \leq c^*(e) r_\varepsilon^2 \quad (4.26)$$

by (2.6) and Lemma 3.1 (i). Since  $\Theta_{\varepsilon, T}^k$  satisfies the  $r_\varepsilon$ -interior ball condition by Lemma 3.1 (iii),  $e$  is the unique outer normal to  $\partial \Theta_{\varepsilon, T}^k$  at  $x_1$  and

$$B_{r_\varepsilon}(x_1 - r_\varepsilon e) \subseteq \Theta_{\varepsilon, T}^k \subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t_k(\omega), \omega).$$

So if we let  $w_k^\varepsilon(t, x, \omega) := u_\varepsilon(t_k + \varepsilon t, x_0 + \varepsilon x, \omega)$ , then clearly

$$B_{\varepsilon^{-1}r_\varepsilon}(-\varepsilon^{-1}(d_0 + r_\varepsilon)e) \subseteq \Gamma_{w_k^\varepsilon, 1-\theta^*}(0, \omega). \quad (4.27)$$

Let us now define  $d_1 := c_1 r_\varepsilon^2 + D_2((1 + \kappa_0)\varepsilon + 4c_0^{-1}c_1 r_\varepsilon^2)$ , with  $D_2 \geq 1$  from Corollary 2.6. Then  $d_1 > \max\{r_\varepsilon^2, d_0\}$  by (4.26), and  $d_1 < \min\{r_\varepsilon, C r_\varepsilon^2\}$  for some  $C > 0$  by  $2\sigma'' < 1$  and (4.24). We also let

$$d_2 := \frac{d_1^2 + d_0^2 + 2d_0 r_\varepsilon}{2(d_0 + r_\varepsilon)},$$

so then  $d_1 - d_2 = \frac{(d_1 - d_0)(2r_\varepsilon - d_1 + d_0)}{2(d_0 + r_\varepsilon)} > 0$  and  $d_2 - d_0 = \frac{d_1^2 - d_0^2}{2(d_0 + r_\varepsilon)} > 0$ . Hence,

$$0 \leq d_0 < d_2 < d_1 \leq \min\{r_\varepsilon, C r_\varepsilon^2\} \quad \text{and} \quad d_2 - d_0 \leq C r_\varepsilon^3, \quad (4.28)$$

with some  $C > 0$ . We then have

$$\{x \in \mathbb{R}^d \mid x \cdot e < -\varepsilon^{-1}d_2\} \cap B_{\varepsilon^{-1}d_1}(0) \subseteq B_{\varepsilon^{-1}r_\varepsilon}(-\varepsilon^{-1}(d_0 + r_\varepsilon)e), \quad (4.29)$$

which follows from (4.28) and the fact that the spherical cap on the left has axis  $e$  and the radius of its base is  $\sqrt{d_1^2 - d_2^2}$ , which equals  $\sqrt{r_\varepsilon^2 - (r_\varepsilon + d_0 - d_2)^2}$  due to the definition of  $d_2$ .

Now let

$$v(\cdot, \cdot, \omega) := u(\cdot, \varepsilon^{-1}x_0 + \cdot, \omega; e, \varepsilon^{-1}(x_0 - d_2e)),$$

where  $u$  is from (2.2). Then  $v$  and  $w_k^\varepsilon$  both satisfy (1.1) with  $f$  shifted in space by  $\frac{x_0}{\varepsilon}$ , and  $\text{supp } v(0, \cdot, \omega) \subseteq \mathcal{H}_e^- + (R_0 - \frac{d_2}{\varepsilon})e$ . This, (4.27), (4.29), and Lemma 2.1 yield

$$v(0, \cdot, \omega) \leq w_k^\varepsilon(\tau_3, \cdot, \omega)$$

on  $B_{\varepsilon^{-1}d_1}(0)$ , where  $\tau_3 := \frac{2R_0}{c_0} + \kappa_0$ . Since  $v(0, \cdot, \omega) \geq (1 - \theta^*)\chi_{\mathcal{H}_e^- - \varepsilon^{-1}d_2e}$ , from Lemma 2.1 we also obtain  $T_v(0, \omega) \leq 2(\varepsilon c_0)^{-1}d_2 + \kappa_0$ , so the definition of  $d_1$ , (4.26), and (4.28) yield

$$\varepsilon^{-1}d_1 \geq D_2(1 + \kappa_0 + 4(\varepsilon c_0)^{-1}c_1 r_\varepsilon^2) \geq D_2(1 + T_v(0, \omega)),$$

provided  $\varepsilon_0 > 0$  is small enough (depending on (1.7)) so that  $d_2 \leq c^*(e)r_\varepsilon^2 + C r_\varepsilon^3 \leq 2c_1 r_\varepsilon^2$ . So Corollary 2.6 with

$$u_1 := v(\cdot, \cdot, \omega), \quad u_2 := w_k^\varepsilon(\cdot, \cdot, \omega), \quad t_0 := \tau_3, \quad \text{and} \quad R := \varepsilon^{-1}d_1,$$

yields

$$T_v(0, \omega) \geq T_{w_k^\varepsilon}(0, \omega) - \tau_3 - \kappa_0. \quad (4.30)$$

We next apply both claims in Proposition 2.7, with  $\delta := \sigma'$  and  $l := \varepsilon^{-1}d_2$  (also recall that  $\bar{T}(e) = c^*(e)^{-1}$ ), to obtain

$$\begin{aligned} \mathbb{P}[|T_v(0, \cdot) - (\varepsilon c^*(e))^{-1}d_2| \geq C(\varepsilon^{-1}d_2)^{\beta + \sigma'} + \lambda] \\ \leq 2 \exp(-\bar{C}^{-2}\lambda^2(\varepsilon^{-1}d_2)^{-2\beta}) \end{aligned} \quad (4.31)$$

for some  $C > 0$  and all  $\lambda \geq 0$ . Let us then take  $\lambda := \bar{C}(\varepsilon^{-1}d_2)^\beta \varepsilon^{-\sigma'}$ . We get from (4.23) and (4.28) that

$$(\varepsilon^{-1}d_2)^{\beta+\sigma'} \leq (\varepsilon^{-1}d_2)^\beta \varepsilon^{-\sigma'} \leq C\varepsilon^{3\sigma''-1}, \quad (4.32)$$

because (4.23) yields

$$3\sigma'' + \sigma' - 2\sigma''\beta \leq \sigma''(4 - 2\beta) \leq 1 - \beta.$$

Then (4.31) and  $d_2 \leq c^*(\varepsilon)r_\varepsilon^2 + Cr_\varepsilon^3$  show that with some  $C > 0$  we have

$$\mathbb{P}[T_v(0, \cdot) \geq \varepsilon^{2\sigma''-1} + C\varepsilon^{3\sigma''-1}] \leq 2\exp(-\varepsilon^{-2\sigma'}). \quad (4.33)$$

Hence (4.30),  $3\sigma'' \leq 1$ , and the definition of  $w_k^\varepsilon$  yield with some  $C > 0$ ,

$$\mathbb{P}[T_{u_\varepsilon}(x_0, \cdot) - t_k(\cdot) \geq \varepsilon^{2\sigma''} + C\varepsilon^{3\sigma''}] \leq 2\exp(-\varepsilon^{-2\sigma'}). \quad (4.34)$$

In order to upgrade this to (4.36), let  $G_{\varepsilon,T}^k \subseteq \Theta_{\varepsilon,T}^{k+1} \setminus \Theta_{\varepsilon,T}^k$  be a set containing one point from each cube in  $\mathbb{R}^d$  with side length  $\varepsilon d^{-1/2}$  and all vertices in  $\varepsilon d^{-1/2}\mathbb{Z}^d$  that has a non-empty intersection with  $\Theta_{\varepsilon,T}^{k+1} \setminus \Theta_{\varepsilon,T}^k$  (recall that  $d \leq 3$  is the spatial dimension). Then clearly  $\Theta_{\varepsilon,T}^{k+1} \setminus \Theta_{\varepsilon,T}^k \subseteq B_\varepsilon(G_{\varepsilon,T}^k)$ . If  $x_0 \in G_{\varepsilon,T}^k$ , applying Lemma 2.1 to  $u^\varepsilon = u_\varepsilon(\varepsilon, \varepsilon, \omega)$  yields

$$T_{u_\varepsilon}(x_0, \omega) \geq \sup_{x \in B_\varepsilon(x_0)} T_{u_\varepsilon}(x, \omega) - (2c_0^{-1} + \kappa_0)\varepsilon. \quad (4.35)$$

This, (4.34), and the fact that  $|G_{\varepsilon,T}^k| \leq C_A T^{d-1} r_\varepsilon^2 \varepsilon^{-d}$  for some  $C_A > 0$  yield with some  $C > 0$ ,

$$\begin{aligned} & \mathbb{P}[t_{k+1}(\cdot) - t_k(\cdot) \geq \varepsilon^{2\sigma''} + C\varepsilon^{3\sigma''}] \\ &= \mathbb{P}[\sup_{x \in \Theta_{\varepsilon,T}^{k+1} \setminus \Theta_{\varepsilon,T}^k} T_{u_\varepsilon}(x, \cdot) - t_k(\omega) \geq \varepsilon^{2\sigma''} + C\varepsilon^{3\sigma''}] \\ &\leq 2C_A T^{d-1} \varepsilon^{2\sigma''-d} \exp(-\varepsilon^{-2\sigma'}). \end{aligned} \quad (4.36)$$

Next recall that  $K = \lceil T\varepsilon^{-2\sigma''} \rceil$ , and  $T_0 \geq \max\{T, 1\}$ . Then for  $C' := 1 + 2C + 2c_0^{-1} + \kappa_0$ , with  $C$  from (4.36), we have

$$K(\varepsilon^{2\sigma''} + C\varepsilon^{3\sigma''}) + 2c_0^{-1}\varepsilon^{\sigma''} + \kappa_0\varepsilon \leq T + C'T_0\varepsilon^{\sigma''}.$$

This, (4.36), and (4.25) imply that

$$\begin{aligned} \mathbb{P}[t_K(\cdot) \geq T + C'T_0\varepsilon^{\sigma''}] &\leq \sum_{k=0}^{K-1} \mathbb{P}[t_{k+1}(\cdot) - t_k(\cdot) \geq \varepsilon^{2\sigma''} + C\varepsilon^{3\sigma''}] \\ &\leq 4C_A T_0^d \varepsilon^{-d} \exp(-\varepsilon^{-2\sigma'}). \end{aligned}$$

Now (1.5) and Lemma 3.1 (ii) show that

$$B_{c_1\varepsilon^{\sigma''}/c_0}(\Theta^{A,c^*}(T - c_1c_0^{-2}\varepsilon^{\sigma''})) \subseteq \Theta^{A,c^*}(T) \subseteq B_{c_1\varepsilon^{\sigma''}/c_0}(\Theta^{A',c'}(T)).$$

Then the convexity of  $A$  implies  $\Theta^{A,c^*}(T - c_1 c_0^{-2} \varepsilon^{\sigma''}) \subseteq \Theta^{A',c'}(T)$  (note that both these sets are also convex), so the definition of  $t_K(\omega)$  yields

$$\begin{aligned} & \mathbb{P}[\Theta^{A,c^*}(T - c_1 c_0^{-2} \varepsilon^{\sigma''}) \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(T + C'T_0 \varepsilon^{\sigma''}, \cdot)] \\ & \leq \mathbb{P}[\Theta^{A',c'}(T) \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(T + C'T_0 \varepsilon^{\sigma''}, \cdot)] \\ & \leq \mathbb{P}[t_K(\cdot) \geq T + C'T_0 \varepsilon^{\sigma''}]. \end{aligned}$$

Therefore

$$\begin{aligned} & \mathbb{P}[\Theta^{A,c^*}(T - c_1 c_0^{-2} \varepsilon^{\sigma''}) \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(T + C'T_0 \varepsilon^{\sigma''}, \cdot)] \\ & \leq 4C_A T_0^d \varepsilon^{-d} \exp(-\varepsilon^{-2\sigma'}). \end{aligned} \quad (4.37)$$

Now let

$$T_\varepsilon := \varepsilon^{\sigma'} + C'T_0 \varepsilon^{\sigma''} \quad \text{and} \quad C'' := c_1 C' + c_1^2 c_0^{-2}.$$

If  $t \in [T_\varepsilon, T_0]$ , it follows from (4.37) with  $T := t - C'T_0 \varepsilon^{\sigma''}$ , and from  $(\Theta^{A,c^*}(t))_{c_1 s}^0 \subseteq \Theta^{A,c^*}(t - s)$  for any  $s \in [0, t]$ , that (recall also  $T_0 \geq 1$ , so  $C''T_0 \geq c_1(C'T_0 + c_1 c_0^{-2})$ )

$$\mathbb{P}[(\Theta^{A,c^*}(t))_{C''T_0 \varepsilon^{\sigma''}}^0 \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t, \cdot)] \leq 4C_A T_0^d \varepsilon^{-d} \exp(-\varepsilon^{-2\sigma'}). \quad (4.38)$$

On the other hand, if  $t \in [0, T_\varepsilon]$ , then from  $c^* \leq c_1$  and  $(u_\varepsilon)_t \geq 0$  we obtain

$$(\Theta^{A,c^*}(t))_{c_1 T_\varepsilon}^0 \subseteq A \subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t, \omega). \quad (4.39)$$

The last two estimates will now yield (4.22). For any  $t \geq s \geq 0$  we clearly have  $\Theta^{A,c^*}(s) \subseteq \Theta^{A,c^*}(t)$ , and also  $\Gamma_{u_\varepsilon, 1-\theta^*}(s, \cdot) \subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t, \cdot)$  because  $(u_\varepsilon)_t \geq 0$ . Then (4.39) and

$$\tilde{C}T_0 \varepsilon^{\sigma'} \geq \max\{c_1 T_\varepsilon, C''T_0 \varepsilon^{\sigma''} + c_1 \varepsilon^{\sigma'}\},$$

with  $\tilde{C} := C'' + c_1$ , show that

$$\begin{aligned} & \mathbb{P}[(\Theta^{A,c^*}(t))_{\tilde{C}T_0 \varepsilon^{\sigma'}}^0 \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t, \cdot) \text{ for some } t \in [0, T_0]] \\ & \leq \mathbb{P}[(\Theta^{A,c^*}(t))_{C''T_0 \varepsilon^{\sigma''} + c_1 \varepsilon^{\sigma'}}^0 \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(t, \cdot) \text{ for some } t \in [T_\varepsilon, T_0]] \\ & \leq \sum_{j=\lceil T_\varepsilon \varepsilon^{-\sigma'} \rceil - 1}^{\lceil T_0 \varepsilon^{-\sigma'} \rceil - 1} \mathbb{P}[(\Theta^{A,c^*}((j+1)\varepsilon^{\sigma'}))_{C''T_0 \varepsilon^{\sigma''} + c_1 \varepsilon^{\sigma'}}^0 \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(j\varepsilon^{\sigma'}, \cdot)]. \end{aligned}$$

Again using  $(\Theta^{A,c^*}(t))_{c_1 s}^0 \subseteq \Theta^{A,c^*}(t - s)$  for  $t \geq s \geq 0$ , and then (4.38), we can continue this estimate via

$$\begin{aligned} & \leq \sum_{j=\lceil T_\varepsilon \varepsilon^{-\sigma'} \rceil - 1}^{\lceil T_0 \varepsilon^{-\sigma'} \rceil - 1} \mathbb{P}[(\Theta^{A,c^*}(j\varepsilon^{\sigma'}))_{C''T_0 \varepsilon^{\sigma''}}^0 \not\subseteq \Gamma_{u_\varepsilon, 1-\theta^*}(j\varepsilon^{\sigma'}, \cdot)] \\ & \leq 4C_A T_0^{d+1} \varepsilon^{-d-\sigma'} \exp(-\varepsilon^{-2\sigma'}). \end{aligned}$$

Recalling that we wrote  $u_\varepsilon$  and  $A$  in place of  $\tilde{u}_\varepsilon$  and  $\varepsilon A^\varepsilon$ , this yields (4.22) after we let  $\varepsilon_0 > 0$  be small enough (it will then depend on the constants mentioned after (4.4) as well as  $A$  and  $T_0$ ). The proof is thus finished.

**Funding.** YPZ acknowledges partial support by an AMS-Simons Travel Grant. AZ acknowledges partial support by NSF grant DMS-1900943 and by a Simons Fellowship.

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Received 2 June 2022; accepted 13 October 2022.

**Yuming Paul Zhang**

Department of Mathematics & Statistics, Auburn University, Auburn, AL 36849, USA;  
[yzhangpaul@auburn.edu](mailto:yzhangpaul@auburn.edu)

**Andrej Zlatoš**

Department of Mathematics, University of California San Diego, La Jolla, CA 92093, USA;  
[zlatos@ucsd.edu](mailto:zlatos@ucsd.edu)