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Tree-graded asymptotic cones

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Abstract. We study the bilipschitz equivalence type of tree-graded spaces, showing that asymptotic cones of relatively hyperbolic groups (resp. asymptotic cones of groups containing a cut-point) only depend on the bilipschitz equivalence types of the pieces in the standard (resp. minimal) tree-graded structure. In particular, the asymptotic cones of many relatively hyperbolic groups do not depend on the scaling factor. We also describe the asymptotic cones as above "explicitly". Part of these results were obtained independently and simultaneously by D. Osin and M. Sapir.

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Introduction

Relatively hyperbolic groups were first introduced in [12] as a generalization of hyperbolic groups. Equivalent definitions and further properties may be found in [2], [8], [3], [23], [16], [6]. They are modeled on the fundamental groups of finite volume complete manifolds of negative curvature (while hyperbolic groups are modeled on the fundamental groups of *compact* negatively curved manifolds). Other examples of relatively hyperbolic groups include free products of groups, which are hyperbolic relative to the factors, and fundamental groups of non-geometric Haken manifolds with at least one hyperbolic component, which are hyperbolic relative to the fundamental groups of the maximal graph manifold components and the fundamental groups of the tori or Klein bottles not bounding any graph manifold component.

Tree-graded spaces were introduced by Druţu and Sapir in [6] to describe the large scale geometry of relatively hyperbolic groups. These spaces have a distinguished family of subsets called *pieces* such that, very roughly, each path can be thought of as a concatenation of paths contained in some piece and paths in a real tree. The tree-graded structure on the large scale has been used in [6], for example, to prove rigidity theorems and to study the automorphisms of certain relatively hyperbolic groups.

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The link between tree-graded spaces and relatively hyperbolic groups is provided by asymptotic cones. The asymptotic cones of a metric space X are defined in order to keep track of the large scale geometry of X. In fact, they are obtained rescaling the metric on X by an "infinitesimal factor", so that "infinitely far away" points become close.

Tree-graded spaces describe the large scale geometry of relatively hyperbolic groups in the sense that the asymptotic cones of a relatively hyperbolic group can be endowed with a natural tree-graded structure.

The idea behind asymptotic cones was introduced by Gromov to prove that groups of polynomial growth are virtually nilpotent in [11], where the notion of Gromov–Hausdorff convergence is used to define them. Later, a more general and somehow easier to handle definition was given by Van den Dries and Wilkie in [22], using nonstandard methods. However, instead of using nonstandard methods, asymptotic cones are nowadays defined in terms of ultrafilters. Since [11], asymptotic cones have been used in several ways, for example to prove quasi-isometric rigidity results, see [15], [13], [14], [1], [9].

We will use a nonstandard definition of asymptotic cones which is a restatement of the one based on ultrafilters. We will do that because the formalism is much lighter and, much more important, some elementary properties of nonstandard extensions turn out to be very powerful tools in studying asymptotic cones, as we will see. Indeed, most proofs involving the ultrafilter based definition of asymptotic cones contain the proof of some particular cases of these properties. Also, the nonstandard definition of asymptotic cones is closer to the idea of looking at a metric space from infinitely far away than the ultrafilter based one, which is closer to the original concept due to Gromov of convergence of rescaled metric spaces. This convergence is more difficult to "visualize".

Main results. We consider groups hyperbolic relative to a collection of proper subgroups and, more generally, groups with asymptotic cones having global cut-points. For the latter type of asymptotic cones we consider the *minimal* tree-graded structure as defined in [6] (i.e., a structure in which the pieces are all the connected subsets which consist of a single point or do not contain global cut-points). We refer to the cases mentioned above as the relatively hyperbolic case and the minimal case, respectively.

We will provide a simple condition for relatively hyperbolic groups to have bilipschitz equivalent asymptotic cones (Theorem 3.3) and for asymptotic cones endowed with the minimal tree-graded structure to be bilipschitz equivalent (Theorem 0.2). The condition for relatively hyperbolic groups is also necessary in the case of groups hyperbolic relative to unconstricted subgroups (see Remark 3.2). A simplified version of the statement of Theorem 3.3 is provided below. In what follows, the asymptotic cone of a group *G* with scaling factor ν will be denoted by $C(G, \nu)$. **Theorem 0.1.** Let G_0 , G_1 be groups hyperbolic relative to their proper subgroups H_0 , H_1 , respectively. Suppose that $C(H_0, v_0)$ is bilipschitz equivalent to $C(H_1, v_1)$ for some scaling factors v_0 , v_1 . Then $C(G_0, v_0)$ is bilipschitz equivalent to $C(G_1, v_1)$.

D. Osin an M. Sapir proved this independently in [18].

Note that the theorem implies, in particular, that if G is hyperbolic relative to H and the asymptotic cones of H are all bilipschitz equivalent, then so are the asymptotic cones of G. This is the case when H is, for example, virtually nilpotent. Therefore this consideration applies to the case of the fundamental groups of finite volume (complete, non-compact) manifolds of pinched negative curvature.

We also obtain the following result, in the minimal structure case.

Theorem 0.2. Suppose that $C(G_0)$, $C(G_1)$ are asymptotic cones of the (non-virtually cyclic) groups G_0 , G_1 and that they contain cut-points. Let \mathcal{P}_i be the minimal treegraded structure on $C(G_i)$, i = 1, 2, and suppose that for each $P \in \mathcal{P}_j$ there exists $P' \in \mathcal{P}_{j+1}$ such that P and P' are bilipschitz equivalent (with the same bilipschitz constant). Then $C(G_0)$ and $C(G_1)$ are bilipschitz equivalent.

D. Osin an M. Sapir proved this in [18] under the Continuum Hypothesis.

The theorems above can be applied to study asymptotic cones of 3-manifold groups [21].

An important intermediate step in the proof of the theorems above is the following result of independent interest (see Propositions 3.9 and 3.11).

Theorem 0.3. In each asymptotic cone of a relatively hyperbolic group (resp. asymptotic cone a group containing a cut-point) endowed with the standard (resp. minimal) tree-graded structure, the valency of each transversal tree is 2^{\aleph_0} .

This result has been proven independently in [18] in the relatively hyperbolic case and under the Continuum Hypothesis, which we do not assume, also in the minimal case.

For convenience and simplicity, we will fix an ultrafilter and state our results for asymptotic cones constructed using it. However, the proofs give analogue results when we allow the ultrafilter to change as well. This is made more precise in Remark 3.42.

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1. Nonstandard extensions

For the following sections we will need basic results about the theory of nonstandard extensions. The treatment will be rather informal, for a more formal one and the proofs of the results in this section see for example [10].

Roughly speaking, nonstandard extensions are given by a "* map" such that

- (1) for each set X, *X is a set naturally containing X,
- (2) for each function $f: X \to Y$, $*f: *X \to *Y$ is a function which extends f (this makes sense in view of the inclusion $X \subseteq *X$,
- (3) if R is a *n*-ary relation on X, *R is an *n*-ary relation on *X extending R.

We will start by stating the basic properties of nonstandard extensions, and we will provide a construction only in the end. This is to emphasize that the properties are more important than the actual construction, and most of the times they are all that is needed to know.

Let us first state a result about the properties that the "standard world" and the "nonstandard world" have in common, then we will study the extra properties of the nonstandard extensions.

Definition 1.1. A formula ϕ is *bounded* if all quantifiers appear in expressions like $\forall x \in X, \exists x \in X$ (bounded quantifiers).

The *nonstandard interpretation of* ϕ , denoted $*\phi$, is obtained by adding * before any set, relation or function (not before quantified variables).

An example will make these concepts clear: consider

$$\forall X \subseteq \mathbb{N}, X \neq \emptyset \ \exists x \in X \ \forall y \in X \ x \leq y,$$

which expresses the fact that any non-empty subset of \mathbb{N} has a minimum. This formula is not bounded, because it contains " $\forall X \subseteq \mathbb{N}$ ". However, it can be turned into a bounded formula by substituting " $\forall X \subseteq \mathbb{N}$ " with " $\forall X \in \mathcal{P}(\mathbb{N})$ ". The nonstandard interpretation of the modified formula reads

$$\forall X \in {}^*\mathcal{P}(\mathbb{N}), X \neq {}^*\emptyset \ \exists x \in X \ \forall y \in X \ x^* \le y.$$
(1)

The following theorem will also be referred to as the *transfer principle*.

Theorem 1.2 (Łoš Theorem). Let ϕ be a bounded formula. Then $\phi \iff {}^*\phi$.

Easy consequences of this theorem are, for example, that the nonstandard extension (*G, * ·) of a group (G, ·) is a group, or that the nonstandard extension (*X, *d) of a metric space (X, d) is a * \mathbb{R} -metric space (that is *d : * $X \times *X \to *\mathbb{R}$ satisfies the axioms of distance, which make sense as * \mathbb{R} is in particular an ordered abelian group). To avoid too many *'s, we will often drop them before functions or relations, for example we will denote the "distance" on *X as above simply by "d", the order on $*\mathbb{R}$ by " \leq " and the group operation on *G by " \cdot ". In view of the transfer principle, the following definition will be very useful:

Definition 1.3. $A \subseteq {}^*X$ will be called *internal* subset of X if $A \in {}^*\mathcal{P}(X)$. An internal set is an internal subset of some *X .

 $f: *X \to *Y$ will be called *internal* function if $f \in *(Y^X) = *\{f: X \to Y\}$.

One may think that "living inside the nonstandard world" one only sees internal sets and functions, and therefore, by the transfer principle, one cannot distinguish the standard world from the nonstandard world.

The following inclusions can be proven using the transfer principle:

$$\{^*A : A \in \mathcal{P}(X)\} \subseteq ^*\mathcal{P}(X) \subseteq \mathcal{P}(^*X),$$
$$\{^*f : f \in Y^X\} \subseteq ^*(Y^X) \subseteq (^*Y)^{^*X}.$$

The equalities are in general very far from being true, as we will see.

Another example: the transfer principle applied to (1), which tells that each nonempty subset of \mathbb{N} has a minimum, gives that each *internal* non-empty subset of **X* has a minimum (* $\emptyset = \emptyset$ as, for each set *A*, $\exists a \in A \iff \exists a \in *A$).

Let us now introduce a convention we will often use. For each definition in the "standard world" there exists a nonstandard counterpart. For example, the definition of geodesic (in the metric space X), yields the definition of *geodesics, in the following way. The definition of geodesic (with domain the interval [0, 1], for simplicity) can be given as

$$\gamma \in X^{[0,1]}$$
 is a geodesic $\iff \forall x, y \in [0,1] d(\gamma(x), \gamma(y)) = |x - y|.$

Therefore the definition of *geodesic can be given as

. . . .

 $\gamma \in {}^*(X^{[0,1]})$ is a *geodesic $\iff \forall x, y \in {}^*[0,1] d(\gamma(x), \gamma(y)) = |x - y|.$

Nonstandard extensions enjoy another property, which will be referred to as *sat-uration*. First, a definition, and then the statement.

Definition 1.4. A collection of sets $\{A_j\}_{j \in J}$ has the *finite intersection property* (FIP) if for each $n \in \mathbb{N}$ and $j_0, \ldots, j_n \in J$, we have $A_{j_0} \cap \cdots \cap A_{j_n} \neq \emptyset$.

Theorem 1.5. Suppose that the collection of internal sets $\{A_n\}_{n \in \mathbb{N}}$ has the FIP. Then $\bigcap_{n \in \mathbb{N}} A_n \neq \emptyset$.

Let us use this theorem to prove that $*\mathbb{R}$ contains infinitesimals. It is enough to consider the collection of sets $\{*(0, 1/n)\}_{n \in \mathbb{N}^+}$ and apply the theorem to it. Note that for $n \in \mathbb{N}^+$, $*(0, 1/n) \in *\mathcal{P}(\mathbb{R})$ as it is of the form *A for $A \in \mathcal{P}(\mathbb{R})$. More

generally, however, for each $x, y \in {}^{*}\mathbb{R}$, $(x, y) \in {}^{*}\mathbb{R}$ (we should use a different notation for intervals in \mathbb{R} and intervals in ${}^{*}\mathbb{R}$, but hopefully it will be clear from the context which kind of interval is under consideration). This can be proven using the transfer principle.

Using this one can show the following.

Lemma 1.6. Let $\{\xi_n\}_{n \in \mathbb{N}}$ be a sequence of infinitesimals. There exists an infinitesimal ξ greater than any ξ_n .

Now some lemmas which are frequently used when working with nonstandard extensions. The first one is usually referred to as *overspill*:

Lemma 1.7. Suppose that the internal subset $A \subseteq *\mathbb{R}^+$ (or $A \subseteq *\mathbb{N}$) contains, for each $n \in \mathbb{N}$, an element greater than n. Then A contains an infinite number.

Lemma 1.8. Suppose that the internal subset $A \subseteq *\mathbb{R}^+$ is such that, for each $n \in \mathbb{N}^+$, $A \cap \{x \in *\mathbb{R} : x < 1/n\} \neq \emptyset$. Then A contains an infinitesimal.

Let us introduce some (quite intuitive) notation, which we are going to use from now on.

Definition 1.9. Consider $\xi, \eta \in {}^*\mathbb{R}$, with $\eta \neq 0$. We will write:

 $\xi \in o(\eta)$ (or $\xi \ll \eta$ if ξ , η are nonnegative) if ξ/η is infinitesimal. $\xi \in O(\eta)$ if ξ/η is finite. $\xi \gg \eta$ if ξ , η are nonnegative and ξ/η is infinite. $\xi \equiv \eta$ if $\xi \in O(\eta) \setminus o(\eta)$.

The map we give by the following lemma plays a fundamental role in nonstandard analysis and will be used in the definition of asymptotic cone.

Proposition 1.10. There exists a map st: $O(1) \to \mathbb{R}$ such that $\xi - \operatorname{st}(\xi)$ is infinitesimal for each $\xi \in {}^*\mathbb{R}$.

We will call $st(\xi)$ the standard part of ξ . Note that $st(\xi) = 0 \iff \xi$ is infinitesimal.

1.1. Construction of nonstandard extensions. In this section we will briefly describe the construction of nonstandard extensions which is (implicitly) used to define the asymptotic cones in virtually every article in which they are used.

Fix a (non-principal) ultrafilter \mathcal{U} on \mathbb{N} . If X is any set, consider the equivalence relation \sim on $X^{\mathbb{N}}$ defined by

$$(x_n)_{n\in\mathbb{N}} \sim (y_n)_{n\in\mathbb{N}} \iff \{n\in N : x_n = y_n\} \in \mathcal{U}.$$

We can define, for each set X,

$$^*X = X^{\mathbb{N}} / \sim$$
.

The inclusion of X into *X is given by constant sequences, that is, $x \in X$ is mapped to the sequence with constant value x.

Nonstandard extensions of functions and relations can be defined componentwise, for example if $f: X \to Y$ is any function we set ${}^*f([(x_n)_{n \in \mathbb{N}}]) = [(f(x_n))_{n \in \mathbb{N}}]$.

Convention 1.11. The definition of the nonstandard extensions depends on the ultrafilter \mathcal{U} . From now on we fix an ultrafilter \mathcal{U} on \mathbb{N} , and we will consider the nonstandard extensions constructed using \mathcal{U} .

The following remark gives the only property which we will need that depends on the particular construction of the nonstandard extensions we chose.

Remark 1.12. The nonstandard extension of a set of cardinality at most 2^{\aleph_0} has cardinality at most 2^{\aleph_0} .

Finally, a remark on how to translate the nonstandard language in the ultrafilter language, and vice versa.

Remark 1.13. Internal subsets (resp. functions) are ultralimits of subsets (resp. functions).

1.2. Asymptotic cones. Let (X, d) be a metric space. The asymptotic cones of X are "ways to look at X from infinitely far away". Let us make this idea precise.

Definition 1.14. Consider $v \in {}^*\mathbb{R}$, $v \gg 1$. Define on *X the equivalence relation $x \sim y \iff d(x, y) \in o(v)$. The asymptotic cone C(X, p, v) of X with basepoint $p \in {}^*X$ and scaling factor v is defined by

$$\{[x] \in {}^{*}X/{\sim} : d(x, p) \in O(v)\}.$$

The distance on C(X, p, v) is defined by d([x], [y]) = st(*d(x, y)/v).

This definition of asymptotic cone is basically due to van den Dries and Wilkie, see [22]. However, the original concept is due to Gromov, see [11]. The aim of [22] was to simplify the proofs in [11].

Before proceeding, a few definitions. If $q \in {}^{*}X$ and $d(p,q) \in O(v)$, so that $[q] \in C(X, p, v)$, then [q] will be called the *projection of q on* C(X, p, v). Similarly, if $A \subseteq \{x \in {}^{*}X : d(x, p) \in O(v)\}$, the projection of A on C(X, p, v) is $\{[a] : a \in A\}$. If $A \subseteq {}^{*}X$ is not necessarily contained in $\{x \in {}^{*}X : d(x, p) \in O(v)\}$, we will call $\{[a] \in C(X, p, v) : a \in A\}$ the *set induced by* A.

Let us now introduce the asymptotic cones we are mostly interested in.

Definition 1.15. Let *G* be a finitely generated group and *S* a finite generating set for *G*. The *asymptotic cone* $C_S(G, g, v)$ of *G* with basepoint $g \in {}^*G$ and scaling factor $v \gg 1$ is $C(\mathcal{CG}_S(G), g, v)$, where $\mathcal{CG}_S(G)$ denotes the Cayley graph of *G* with respect to *S*.

Here are the basic properties of asymptotic cones of groups (see [4]).

Lemma 1.16. For any finitely generated group G, finite generating sets S, S', g, $g' \in {}^{*}\mathbb{G}, v \gg 1$:

 $C_S(G, g, v)$ is complete, geodesic and homogeneous. $C_S(G, g, v)$ is isometric to $C_S(G, g', v)$. $C_S(G, g, v)$ is k-bilipschitz homeomorphic to $C_{S'}(G, g, v)$.

When a finite generating set S is fixed, we will often write $C(G, g, \nu)$ instead of $C_S(G, g, \nu)$.

We will often identify G with the set of vertices of $\mathcal{CG}_S(G)$.

2. Tree-graded spaces

The asymptotic cones we will be interested in have the structure which we will describe in this section. All results and definitions before Lemma 2.9 are taken from [6].

Definition 2.1. A geodesic complete metric space \mathbb{F} is *tree-graded* with respect to a collection \mathcal{P} of closed geodesic subsets of \mathbb{F} (called *pieces*) that cover \mathbb{F} if the following properties are satisfied:

 (T_1) Two different pieces intersect in at most one point.

 (T_2) Each geodesic simple triangle is contained in one piece.

Convention 2.2. Throughout the section, let \mathbb{F} denote a tree-graded space with respect to \mathcal{P} .

Lemma 2.3. *Each simple* loop *in* \mathbb{F} *is contained in one piece.*

In particular, for example, simple quadrangles are contained in one piece.

The most powerful technical tool for studying tree-graded spaces are the projections defined in the following lemma.

Lemma 2.4. For each $P \in \mathcal{P}$ there exists a map $\pi_P \colon \mathbb{F} \to P$, called the projection on P, such that for each $x \in \mathbb{F}$:

 $d(x, P) = d(x, \pi_P(x)),$

each curve (in particular each geodesic) from x to a point in P contains $\pi_P(x)$, π_P is locally constant outside \mathbb{F} . In particular, if $A \subseteq \mathbb{F}$ $(A \neq \emptyset)$ is connected and $|A \cap P| \leq 1$, $\pi_P(A)$ consists of one point.

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Note that if $x \in P$, then $\pi_P(x) = x$. The following results can be easily proven using projections.

Corollary 2.5. Each arc (i.e., injective path) connecting two points of a piece *P* is contained in *P*. In particular the intersection between a geodesic and a piece is either empty, a point or a subgeodesic.

Corollary 2.6. If x, y are such that $\pi_P(x) \neq \pi_P(y)$ for some piece P, then any geodesic δ from x to y intersects P.

Another useful concept is that of transversal tree, defined below.

Definition 2.7. For each $x \in \mathbb{F}$ denote by T_x the set of points $y \in \mathbb{F}$ such that there exists a path joining x to y which intersects each piece in at most one point. Such sets will be called *transversal trees*.

Basic properties of *transversal trees* are given below.

Lemma 2.8. For each $x \in \mathbb{F}$, T_x is a real tree, T_x is closed in \mathbb{F} , if $y \in T_x$, then $T_x = T_y$, every arc joining $y, x \in T_x$ is contained in T_x .

The next lemma will be used a lot of times.

If β and γ are geodesics such that the final point of β is the initial point of γ , we will denote their concatenation by $\beta\gamma$.

Lemma 2.9. Suppose that γ_1 and γ_2 are geodesics or geodesic rays in a tree-graded space such that

- (1) the final point p of γ_1 is the starting point of γ_2 ,
- (2) $\gamma_1 \cap \gamma_2 = \{p\},\$
- (3) there is no piece containing a final subpath of γ_1 and an initial subpath of γ_2 .

Then $\gamma_1\gamma_2$ is a geodesic (or a geodesic ray or a geodesic line). Also, each geodesic from a point in γ_1 to a point in γ_2 contains p.

Proof. If the conclusion were false, we would have points $q \in \gamma_1$, $r \in \gamma_2$ such that d(q, r) < d(q, p) + d(p, r). Consider a geodesic triangle with vertices p, q, r and $[q, p] \subseteq \gamma_1, [p, r] \subseteq \gamma_2$. Condition (2) and d(q, r) < d(q, p) + d(p, r) imply that it cannot be a tripod, for otherwise $[q, p] \cap [p, q]$ should contain a non-trivial geodesic. Therefore there exists a piece P intersecting both [q, p] and [p, r]. Condition (3) implies that P does not contain p. But then both [q, p] and [p, r] should pass through $\pi_P(p) \neq p$, which contradicts (2).

The last part of the statement has a similar proof.

Definition 2.10. We will say that γ_1 and γ_2 *concatenate well* if they satisfy the hypothesis of Lemma 2.9.

2.1. Alternative definition of tree-graded spaces. In this section we give a characterization of tree-graded spaces that will turn out to be more effective in the proof that certain spaces are tree-graded.

Throughout the section, let us denote by X a complete geodesic metric space and by \mathcal{P} a collection of subsets of X. We want to capture the fundamental properties of projections on a piece in a tree-graded space.

Definition 2.11. A family of maps $\Pi = {\pi_P : X \to P}_{P \in \mathcal{P}}$ will be called *projection* system for \mathcal{P} if, for each $P \in \mathcal{P}$,

(P1) for each $r \in P, z \in X, d(r, z) = d(r, \pi_P(z)) + d(\pi_P(z), z),$

(P2) π_P is locally constant outside P,

(P3) for each $Q \in \mathcal{P}$ with $P \neq Q$, we have that $\pi_P(Q)$ is a point.

Remark 2.12. Note that $\pi_P(x)$ is a point which minimizes the distance from x to *P*. In particular, *P* is closed. Also, if $x \in P$, then $\pi_P(x) = x$.

Lemma 2.13. Suppose that $\{\pi_P\}_{P \in \mathcal{P}}$ is a projection system.

(1) Consider $x \in X$ and $P \in \mathcal{P}$. Each arc (in particular, each geodesic) from x to some $p \in P$ passes through $\pi_P(x)$.

(2) For each $P \in \mathcal{P}$, each arc (in particular, each geodesic) connecting two points in P is entirely contained in P. As a consequence, the intersection between an arc γ and $P \in \mathcal{P}$ is either empty, a point or a subarc of γ .

(3) Each simple loop which intersects some $P \in \mathcal{P}$ in more than one point is contained in P.

Proof. (1) Consider an arc $\gamma: [0, t] \to \mathbb{F}$ from x to p. Let $q = \gamma(u)$ be the first point of $\gamma \cap P$ (P is closed in X by assumption). By (P2), $\pi_P \circ \gamma|_{[0,u)}$ is constant, so $\pi_P(x) = \pi_P(\gamma(u'))$ for each $u' \in [0, u)$. Using this fact and (P1) with r = q and $z = \gamma(u')$, for $u' \in [0, u)$, we get

$$d(q, \gamma(u')) = d(q, \pi_P(x)) + d(\pi_P(x), \gamma(u'))$$

As u' tends to u, the left-hand side tends to d(q, q) = 0, while the right-hand side tends to $2d(q, \pi_P(x))$. Therefore $d(q, \pi_P(x)) = 0$ and $q = \pi_P(x)$.

(2) Consider an arc γ between two points in some $P \in \mathcal{P}$ and suppose by contradiction that there exists $x \in (\gamma \setminus P)$. We can consider a subarc γ' of γ containing x and with endpoints $x_1 \neq x_2$ with the property that $\gamma' \cap P = \{x_1, x_2\}$. We have that $[x, x_1]$ intersects P only in its endpoint. By what we proved so far, we must have $\pi_P(x) = x_1$. But, for the very same reason, we should also have $\pi_P(x) = x_2$, a contradiction.

(3) The loop as in the statement can be considered as the union of two arcs connecting points on P. The conclusion follows from point (2).

The characterization of projection systems given below will be helpful for future arguments.

Lemma 2.14. Properties (P1) and (P2) can be substituted by:

(P1') for each $P \in \mathcal{P}$ and $x \in P$, $\pi_P(x) = x$, (P2') for each $P \in \mathcal{P}$ and for each $z_1, z_2 \in X$ such that $\pi_P(z_1) \neq \pi_P(z_2)$,

$$d(z_1, z_2) = d(z_1, \pi_P(z_1)) + d(\pi_P(z_1), \pi_P(z_2)) + d(\pi_P(z_2), z_2).$$

Proof. Assume that $\{\pi_P\}$ satisfies (P1') and (P2'). Property (P1) is not trivial only if $r \neq \pi_P(z)$, and in this case follows from (P2') setting $z_1 = z$, $z_2 = r$ and taking into account that, by (P1'), $\pi_P(r) = r \neq \pi_P(z)$. As we have property (P1), we also have that $d(z, P) = d(z, \pi_P(z))$ for each $z \in X$. Hence, property (P2) follows from the fact that if $\pi_P(z_1) \neq \pi_P(z_2)$ then $d(z_1, z_2) > d(z_1, P)$.

Assume that $\{\pi_P\}$ satisfies (P1) and (P2). We already remarked that (P1) holds. Consider z_1, z_2, P as in property (P2'), and a geodesic δ between z_1 and z_2 . If we had $\delta \cap P = \emptyset$, then π_P would be constant along δ and so $\pi_P(z_1) = \pi_P(z_2)$. Therefore δ intersects *P*. So, by point (1) of the previous lemma, δ contains $\pi_P(z_1)$ and $\pi_P(z_2)$, hence the thesis.

Definition 2.15. A geodesic is \mathcal{P} -transverse if it intersects each $P \in \mathcal{P}$ in at most one point. A geodesic triangle in X is \mathcal{P} -transverse if each side is \mathcal{P} -transverse.

 \mathcal{P} is *transverse-free* if each \mathcal{P} -transverse geodesic triangle is a tripod.

Theorem 2.16. Let X be a complete geodesic metric space and let \mathcal{P} a collection of subsets of X that covers X. Then X is tree-graded with respect to \mathcal{P} if and only if \mathcal{P} is transverse-free and there exists a projection system for \mathcal{P} .

Proof. \Rightarrow : This implication follows from the properties of tree-graded spaces we stated before.

 \Leftarrow : Let Π = { π_P } be a projection system for *P*. Let us prove property (T₁). Consider *P*, *Q* ∈ *P* with *P* ≠ *Q*. If *x*, *y* ∈ *P* ∩ *Q*, we have $\pi_P(Q) \supseteq \{x, y\}$. By (P3), this implies that *x* = *y*.

Let us show how to obtain property (T_2) . Consider a simple geodesic triangle Δ with vertices a, b, c. If it consists of one point (recall that we consider these triangles to be simple), then it is contained in some $P \in \mathcal{P}$, as we assume that elements of \mathcal{P} cover X. So we can suppose that Δ is not trivial. Then it cannot be \mathcal{P} -transverse, for otherwise it would be a non-trivial tripod, and therefore not a simple triangle.

So we can assume that $P \cap [a, b]$ contains a non-trivial subgeodesic $[a', b'] \subseteq [a, b]$, for some $P \in \mathcal{P}$. The conclusion follows from Lemma 2.13 (3), as Δ is in particular a simple loop.

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Remark 2.17. Property (P3) was used only to prove (T₂). Therefore, another way to prove that X is tree-graded is to prove property (T₁), properties (P1) and (P2) (or (P1') and (P2')) for some family of maps $\{\pi_P\}$, and that \mathcal{P} is transverse-free.

Lemma 2.18. Suppose that there exists a projection system for \mathcal{P} . Consider points $p, q \in X$ such that there exists one \mathcal{P} -transverse geodesic γ from p to q. Then γ is the only geodesic from p to q.

Proof. Consider a geodesic γ' from p to q. If γ' is different from γ , then a simple loop obtained as the union of non-trivial subgeodesics of γ , γ' is easily found. This loop is contained in some $P \in \mathcal{P}$, so γ cannot be \mathcal{P} -transverse.

2.2. Relative hyperbolicity

Definition 2.19. *X* is asymptotically tree-graded with respect to \mathcal{P} if each asymptotic cone *Y* of *X* is tree-graded with respect to the collection of the non-empty subsets of *Y* induced by elements of * \mathcal{P} . Also, we require that if two distinct elements of * \mathcal{P} induce pieces of *Y*, these pieces intersect in at most one point.

Asymptotically tree-graded spaces were first defined in [6], see Definition 4.19. Note that the above definition is more easily stated, thanks to the nonstandard formalism. The following result is contained in [6]

Lemma 2.20. Let X be asymptotically tree-graded with respect to \mathcal{P} . Then there exists M with the following property. If γ is a geodesic connecting x to y, and $d(x, P), d(y, P) \leq d(x, y)/3$ for some $P \in \mathcal{P}$, then $\gamma \cap N_M(P) \neq \emptyset$.

We are finally ready to define relatively hyperbolic groups. Let G be a finitely generated group and let H_1, \ldots, H_n be finitely generated subgroups of G.

Definition 2.21 ([6]). *G* is hyperbolic relative to H_1, \ldots, H_n if for some (hence every) finite generating system *S* for *G*, $C_S(G)$ is asymptotically tree-graded with respect to $\{gH_i : g \in G, i = 1, \ldots, n\}$.

Convention 2.22. To avoid trivial cases, we will always assume that each H_i as above is infinite and has infinite index in G.

3. Homeomorphism type of tree-graded spaces

To simplify the notation, when G is a group we will denote by $C(G, \nu)$ the asymptotic cone $C(G, e, \nu)$, where ν is a scaling factor. The main results in this section are Theorem 0.2 and the theorem we are about to state. First, a definition.

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Definition 3.1. Consider groups G_i , for i = 0, 1, which are hyperbolic relative to the collections of proper subgroups $\mathcal{H}_i = \{H_i^1, \ldots, H_i^{n(i)}\}$, and $v_0, v_1 \gg 1$. We will say that G_0 at scale v_0 is comparable with G_1 at scale v_1 if for each $H \in \mathcal{H}_i$ such that $C(H, v_i)$ is not a real tree there exists $H' \in \mathcal{H}_{i+1}$ such that $C(H', v_{i+1})$ is bilipschitz equivalent to $C(H, v_i)$.

Remark 3.2. If each $C(H_i^j, v_i)$ does not have cut-points and $C(G_0, v_0)$ is bilipschitz equivalent to $C(G_1, v_1)$, then G_0 at scale v_0 is comparable to G_1 at scale v_1 , because a homeomorphism between tree-graded spaces whose pieces do not have cut-points preserves the pieces (see [6]).

For example, suppose that *G* is hyperbolic relative to subgroups whose (bilipschitz type of the) asymptotic cones do not depend on the scaling factor (this is the case if the subgroups are virtually nilpotent, for example). Then for each $v_0, v_1 \gg 1$ we have that *G* at scale v_0 is comparable with itself at scale v_1 .

The theorem is the following.

Theorem 3.3. Suppose that G_0 and G_1 are relatively hyperbolic groups and that G_0 at scale v_0 is comparable with G_1 at scale v_1 . Then $C(G_0, v_0)$ is bilipschitz homeomorphic to $C(G_1, v_1)$.

Corollary 3.4. Suppose that G is hyperbolic relative to subgroups whose (bilipschitz type of the) asymptotic cones do not depend on the scaling factor. Then the asymptotic cones of G are all bilipschitz equivalent.

3.1. Hyperbolic elements and transversal trees. Throughout the subsection G will denote a group which is hyperbolic relative to its subgroups H_1, \ldots, H_n . Recall that we always assume that each H_i has infinite index in G and is infinite. We also fix a finite system of generators S.

In this subsection recall some algebraic properties of relatively hyperbolic groups discovered by Osin, and we apply them to determine the structure of transversal trees in their asymptotic cones.

Definition 3.5. A hyperbolic element of *G* is an infinite order element which is not conjugated to any element of H_i , i = 1, ..., n.

Lemma 3.6 ([17], Corollary 4.5). *There exists a hyperbolic element* $g \in G$.

Fix such g.

Lemma 3.7 ([17], Corollary 1.7). g is contained in a virtually cyclic subgroup E(g) of g such that G is hyperbolic relative to $H_1, \ldots, H_n, E(g)$.

We are ready to study transversal trees.

Let X be the asymptotic cone of a group G' hyperbolic relative to H'_1, \ldots, H'_k with basepoint $e \in {}^*G$ and scaling factor ν . We have that X is asymptotically treegraded with respect to the set of pieces $\mathcal{P} = \mathcal{P}_1 \cup \cdots \cup \mathcal{P}_k$, where elements of \mathcal{P}_i are induced by left *cosets of * H'_i .

Let us start with counting how many pieces contain a fixed point.

Lemma 3.8. For each $i \in \{1, ..., k\}$ and $x \in X$, $P(i, x) = \{P \in \mathcal{P}_i : x \in P\}$ has cardinality 2^{\aleph_0} .

Proof. As X is homogeneous through isometries which preserve the pieces (those induced by left translations by suitable elements of *G), it is enough to determine the cardinality of P(i, e). Consider the function $f : \mathbb{N} \to \mathbb{N}$ such that f(n) is the number of left cosets of H'_i which have a representative closer than n to e. We have that f is of course increasing an unbounded. In particular, for each infinite $\xi \in *\mathbb{N}$, $f(\xi)$ is an infinite number. Let us fix an infinite $\xi \in o(v)$. The left *cosets counted by $f(\xi)$ give distinct elements of P(i, e), so $|P(i, e)| \ge 2^{\aleph_0}$. Also $|X \setminus \{e\}| \le 2^{\aleph_0}$ and, as different pieces can intersect in at most one point and each piece contains infinite points, $|P(i, e)| \le |X \setminus \{e\}|$ (for each $P \in P(i, e)$ consider a point in P different from e). So we obtained the inequality $|P(i, e)| \le 2^{\aleph_0}$, and hence the assertion.

Now let us focus on transversal trees in an asymptotic cone Y of G (recall that we denote the transversal tree at e by T_e , see Definition 2.7). Note that they are isomorphic homogeneous trees, so we only need to study the valency of T_e in e.

Proposition 3.9. The valency of T_e in e is 2^{\aleph_0} .

Proof. We have that ${}^{*}E(g)$ induces a line in Y, as it is quasi-isometrically embedded in G. This line intersects each piece induced by a left * coset of some H_i in at most one point, because this line belongs to a set of pieces including the sets induced by left * cosets of the H_i 's, so property (T₁) applies. Using the previous lemma, we get that T_e contains 2^{\aleph_0} geodesic lines. As the valency of T_e cannot be more than $|T_e| \leq |X| \leq 2^{\aleph_0}$, it must be exactly 2^{\aleph_0} .

3.2. Transversal trees in minimal tree-graded structures. Let *G* be a group and set X = C(G, e, v). Also, to avoid trivialities, assume that *G* is non-virtually cyclic. Suppose that *X* contains a cut-point. Then, by the proof of [6], Lemma 2.31, we have that *X* is tree-graded with respect to \mathcal{P} , the collection of maximal subsets of *X* which (consist of a single point or) do not contain cut-points. We will refer to \mathcal{P} as the *minimal* tree-graded structure of *X*. Notice that for each $g \in {}^*G$ and $P \in \mathcal{P}$ such that gP is defined, we have $gP \in \mathcal{P}$ (as the characterization of the elements of \mathcal{P} is invariant under isometries).

Lemma 3.10. For each $P \in \mathcal{P}$ which contains e and does not consist of a single point there exists $g \in {}^*G$ such that $gP \neq P$ and gP contains e.

Proof. Consider an element $g \in {}^*G$ such that gP is defined and $[g] \notin P$. We claim that for each $p \in P$ we have $d(gp, p) \ge 2d(e, p) - d(e, [g])$. To show this, notice that $gP \neq P$ so that, for $x = \pi_P(gP)$, $y = \pi_{gP}(P)$, we have d(p, gp) = d(p, x) + d(x, y) + d(y, gp). This holds in particular for p = e, so

$$d(p,gp) + d(e,[g]) \ge (d(p,x) + d(x,e)) + (d(y,gp) + d(ge,y))$$

$$\ge d(e,p) + d(ge,gp) = 2d(e,p),$$

as claimed.

Notice that for each $n \in \mathbb{N}^+$ we can find g as above such that d(e, [g]) < 1/n. Also, we have the following property, for each $n \in \mathbb{N}^+$ and some fixed $p \in P \setminus \{e\}$ and $q \in {}^*G$ with [q] = p: "each path in *G obtained concatenating at most n internal geodesics connecting q to gq contains a point whose distance from e is a most v/n."

Saturation (see also Lemma 1.8) gives that there exists g satisfying d(e, [g]) < 1/n and the property above for each $n \in \mathbb{N}^+$. In particular, $d(e, g) \in o(v)$, d(gp, p) = 2d(e, p) and all paths from p to gp contain e (as paths can be approximated arbitrarily well by concatenations of geodesics induced by internal geodesics). Clearly, g is as required.

Proposition 3.11. T_e is an homogeneous tree with valency 2^{\aleph_0} .

Proof. Notice that in the case that each $P \in \mathcal{P}$ is a point, then X is a real tree. By [20], X is a point, a line or a homogeneous tree of valency 2^{\aleph_0} . In the first two cases, G is virtually cyclic (see [6], Proposition 6.1). So the case when each $P \in \mathcal{P}$ consists of a single point is set. Notice that (by homogeneity of X and the definition of \mathcal{P}) if there exists $P \in \mathcal{P}$ containing at least two points, then the same is true for each element of \mathcal{P} .

Finding a ray contained in T_e . If γ is a geodesic in X (resp. an internal geodesic in *G), any map $\pi : X \to \gamma$ (resp. $\pi : *G \to \gamma$) satisfying $d(x, \gamma) = d(x, \pi(x))$ for each $x \in X$ (resp. for each $x \in *G$) will be called a *closest point projection* on γ .

The idea is to use the fact that a transversal ray γ has the property that the closest point projection on γ satisfies property (P2) (i.e., it is locally constant outside γ). This is easily seen as, for example, $\mathcal{P} \cup \{\gamma\}$ gives a tree-graded structure for X when γ is a ray contained in T_e , and the closest point projection on a piece satisfies (P2). Also we claim that if a ray δ is not contained in a transversal tree then there is no closest point projection on δ satisfying (P2). In fact, by definition, δ intersects some $P \in \mathcal{P}$ in a non-trivial subpath δ' . As P does not have cut-points, there exists a path α connecting the endpoints x, y of δ' and not containing the midpoint p of δ' . However, if a closest point projection π existed, it would be continuous at x and y and we would have $\pi(x) = x$, $\pi(y) = y$. This is easily seen to contradict (P2). Now we wish to show that a transversal ray γ exists by showing that, informally, there are geodesics such that any closest point projection on them is arbitrarily close to satisfying (P2), and then a saturation argument will quickly lead to the conclusion.

Fix any $n \in \mathbb{N}^+$. If γ is an internal geodesic, denote by $\phi(\gamma, n)$ the following property: "for each closest point projection π on γ and for each $x, y \in {}^*G$ such that $d(x, e), d(y, e) \le nv$ and $d(x, y) \le d(x, \gamma)/2$ we have $d(\pi(x), \pi(y)) \le v/n$."

We will construct an internal geodesic γ_n in *G satisfying the following properties:

- *e* is the starting point of γ_n ,
- $l(\gamma_n) \ge n\nu$,
- γ_n satisfies $\phi(\gamma_n, n)$.

Once we can construct such geodesics, we are done as saturation implies that there exists a geodesic γ satisfying the above properties for each $n \in \mathbb{N}^+$. It is clear that γ induces a transversal ray in X, by the previous discussion on properties of the closest point projection on (non-)transversal rays.

Constructing the "approximate transversal rays". The idea to construct such geodesics is just to concatenate short geodesics in different pieces. Let us show how to construct $\gamma = \gamma_n$. We will first construct a geodesic δ in X. Choose a geodesic δ_0 in X starting at e contained in a piece $P_0 \in \mathcal{P}$ and such that $0 < l(\delta_0) \le 1/(10n)$. Lemma 3.10 readily implies that there exists $g_0 \in {}^*G$ such that $g_0P_0 \neq P_0$ and $[g_0] = p_0$. We can define inductively δ_i as the concatenation of δ_{j-1} and $g_0^j \delta_0$. Set $P_i = g_0^i P_0$. Notice that for each *i* we have that $Q_i = \bigcup_{j \le i} P_j$ is a piece in some tree-graded structure of X.

Let $\gamma \subseteq {}^*G$ be an internal geodesic connecting e to a representative of the endpoint p_i of δ_i , for i big enough, and let δ be the induced geodesic in X. As $g_0^j \delta_0$ and $g_0^{j+1} \delta_0$ concatenate well, it is easily seen for i big enough γ has length at least $n\nu$. Let π be a closest point projection on γ . Notice that, for each $p \in X$, if $\pi_{Q_i}(p) \in P_j$, then $[\pi(q)] \in P_j$ as well, for any q such that [q] = p. Suppose that $d(\pi(x), \pi(y)) \ge 10l(\delta_0)$, for some x, y with $d(x, e), d(y, e) \in O(\nu)$. It is easily seen that for each j, k such that $\pi_{Q_i}([x]) \in P_j, \pi_{Q_i}([y]) \in P_k$ we have $|j-k| \ge 5$. Fix such j, k and suppose j < k. It is easy to show inductively that $\pi_{P_j}(P_k) = \{g_0^{j+1}\}$. So, we have that each geodesic from [x] to [y] contains g_0^k and g_0^{j+1} , as it contains $\pi_{Q_i}([x])$ and $\pi_{Q_i}([y])$ and any geodesic connecting them contains the claimed points.

This easily implies $d([x], [y]) > d([x], [\pi(x)])$. In particular, given x, y such that $d(x, y) \le d(x, \gamma)/2$ we must have $d(\pi(x), \pi(y)) < 10l(\delta_0)v \le v/n$, and this shows $\phi(\gamma, n)$. To sum up, we showed that there exists γ satisfying the second and third condition required for γ_n , and by definition of γ the third condition is satisfied as well.

Finding many rays contained in T_e . Up to now we proved that T_e contains a ray γ . Next let us use this ray to construct several other rays in T_e (containing e). Consider a piece P containing e. Consider an element $g \in {}^*G$ such that $[g] \neq e$ and $[g] \in P$. We have that d(gp, p) = 2d(e, p) + d(e, [g]) for each $p \in \gamma$. Also, if $[g_1] \neq [g_2]$ and $[g_1], [g_2] \in P$, we have $d(g_1p, g_2p) = 2d(e, p) + d([g_1], [g_2])$. Fix q such that $[q] \in \gamma$ and $[q] \neq e$. In view of the considerations above, for each $n \in \mathbb{N}^+$ we can find g_1, \ldots, g_n such that

- (1) $d(g_iq, g_jq) \ge 2d(e,q)$ for $i \neq j$,
- (2) $d(g_i, e) \leq 1/n$ for each *i*.

By overspill, we can find an infinite $\mu \in {}^*\mathbb{N}$ and g_1, \ldots, g_μ with the same properties for some infinite μ . In particular, it is easily seen that the valency of T_e at e is at least 2^{\aleph_0} as $g_i[q]$ is not in the same connected component of $T_e \setminus \{e\}$ as $g_j[q]$ when $i \neq j$.

The homogeneity of T_e follows from the homogeneity of X together with the fact that the set of pieces is invariant under isometries (and therefore the set of transversal trees is also invariant).

3.3. Geodesics in tree-graded spaces. We are going to need some results about the structure of geodesics in tree-graded spaces. Throughout the subsection \mathbb{F} will denote a tree-graded space with respect to the collection of proper subsets \mathcal{P} . Unfortunately, it is not true that all geodesics in \mathbb{F} are obtained by concatenation of geodesics in transversal trees or pieces, as shown by the "fractal" geodesics used in the proof of Lemma 6.11 in [6]. We want to analyze how far this is from being true.

Remark 3.12. If \mathbb{F} is tree-graded with respect to \mathcal{P} , then it is tree-graded also with respect to the collection of subsets \mathcal{P}' obtained from \mathcal{P} by adding a collection of disjoint transversal trees which cover \mathbb{F} . When \mathbb{F} is considered as a tree-graded space with respect to \mathcal{P}' , all its transversal trees are trivial.

The above remark tells us how we can reduce to studying tree-graded spaces with trivial transversal trees. Henceforth, let \mathbb{F} be such a tree-graded space.

Definition 3.13. Let $\gamma : [0, l] \to \mathbb{F}$ be a geodesic. A *piece interval* is an interval $[a, b) \subseteq [0, l]$ (with a < b) such that $\gamma([a, b))$ is contained in a piece and [a, b] is a maximal interval with this property. The *piece subset* P_{γ} is the union of all piece intervals.

Remark 3.14. A maximal interval *I* such that $\gamma(I)$ is contained in a certain piece is closed because pieces are closed in \mathbb{F} .

Remark 3.15. By the fact that different pieces intersect in at most one point, different piece intervals are disjoint.

It is not true that for each geodesic $\gamma : [0, l] \to \mathbb{F}, P_{\gamma}$ is the entire [0, l), however:

Lemma 3.16. $\overline{P_{\gamma}} = [0, l].$

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Proof. We have that if $x \in [0, l] \setminus \overline{P_{\gamma}}$ then x is contained in some open interval I such that no non-trivial interval $I' \subseteq I$ has the property that $\gamma(I')$ is contained in just one piece. We have that $\gamma(I)$ is contained in a transversal tree (by Corollary 2.5), a contradiction since transversal trees are trivial.

The following two definitions are given in order to capture the properties of a geodesic in a tree-graded space with trivial transversal trees. For short, we will call closed-open interval an interval closed on the left and open on the right.

Definition 3.17. An almost filling of an interval [l, m] is a collection $\{I_a\}_{a \in A}$ of non trivial closed-open intervals in [l, m] (in particular A is at most countable) such that

- (1) if $a \neq a'$, I_a and $I_{a'}$ are disjoint,
- (2) $\bigcup_{a \in A} I_a$ is dense in [l, m].

Before giving the next definition, let us describe the idea behind it. A P-geodesic is something which wants to keep track of the following data:

- the kind of pieces a certain geodesic γ intersects non-trivially,
- the maximal intervals of the domain of γ mapped in a piece (the $\overline{I_a}$'s, for I_a as above),
- the last point on γ ∩ P for some P which γ intersects non-trivially (Γ(t) for every t varying in the appropriate interval I_a).

More precisely, it is the associated almost filling that keeps track of the first and second kind of information.

Definition 3.18. Suppose we are given a family of pointed metric spaces $\{(P_i, r_i)\}_{i \in I}$. A P-geodesic Γ with associated almost filling $\{I_a\}_{a \in A}$ of an interval [l, m] and range $\{(P_i, r_i)\}_{i \in I}$ is a function $\Gamma : \bigcup I_a \to \bigsqcup P_i$ such that

- (1) $\Gamma|_{I_a}$ is constant for each $a \in A$,
- (2) denoting by $h_{\Gamma}: \bigcup I_a \to I$ the function such that $\Gamma(t) \in P_i \iff h_{\Gamma}(t) = i$, we have $d(r_{h_{\Gamma}(t)}, \Gamma(t)) = l(I_a)$.

The function h_{Γ} will be called the *index selector* for Γ .

We could equivalently define Γ as a function with domain A. The reason we chose this definition is merely technical.

Suppose now that \mathbb{F} is a homogeneous tree-graded space such that each piece is homogeneous (we still assume that transversal trees are trivial). Let $\{P_i\}$ be a choice of representatives of isometry classes of the pieces. For each *i*, fix a basepoint $r_i \in P_i$ and set $\mathcal{P} = \{(P_i, r_i)\}$.

Definition 3.19. A choice of charts is the choice, for each piece *P* and $p \in P$, of an isometry between *P* and *P_i* sending *p* to r_i , for some $(P_i, r_i) \in \mathcal{P}$.

Suppose that for each pair (x, P), where P is a piece and x is a point contained in P, we have a fixed an isometry between P and some P_i sending x to the corresponding r_i . Finally, fix a basepoint $p \in \mathbb{F}$. Given this data, we can associate to each geodesic γ in \mathbb{F} parametrized by arc length a P-geodesic.

Lemma 3.20. If $\gamma : [0, l] \to \mathbb{F}$ is a geodesic in \mathbb{F} parametrized by arc length, then:

- (1) The collection $I_{\gamma} = \{I_a = [q_a, q'_a)\}_{a \in A_{\gamma}}$ of all maximal closed-open subintervals J of [0, l] such that $\gamma|_J$ is contained in one piece is an almost filling of [0, l].
- (2) Consider the function h_Γ: ∪ I_a → I which associates to each t the only i ∈ I such that γ|_{Ia} is contained in a piece isometric to P_{h(t)}, where t ∈ I_a. Also, let Γ: ∪ I_a → ⊔ P_i be such that Γ(t) is the point identified with γ(q'_a) under the identification of (γ(q_a), P) with (p_{hΓ(a)}, P_{hΓ(a)}), where P is the piece which contains γ|_{Ia}. Then Γ is a P-geodesic and h_Γ is its index selector.
- (3) $\{I_a\}$ and Γ depend only on the endpoints of γ .

Definition 3.21. Γ as above will be called the P-geodesic induced by γ .

Proof. Lemma 3.16 implies (1), and (2) is clear.

In order to prove (3), we will prove that if γ , γ' are geodesics from p to q and γ intersect the piece P in a non trivial arc, entering it in x and leaving from y, then γ' enters P in x and leave it from y as well.

First of all, we have to prove that γ' intersects *P*. If this is not the case, then $(\gamma \cup \gamma') \setminus P$ is connected. But the projection of $\gamma \setminus P$ on *P* consists of two points, and the projection of γ' on *P* consists of one point, as $\gamma' \cap P = \emptyset$. Therefore the projection of $(\gamma \cup \gamma') \setminus P$ on *P* is not connected, a contradiction.

Suppose now that γ' enters P in $x' \neq x$. Let $\bar{\gamma}$ (resp. γ') be the initial subgeodesic of γ (resp. γ') whose final point is x (resp. x'). The projection of $\bar{\gamma}$ on P is x and the projection of γ' on P is x'. But $\bar{\gamma} \cap \bar{\gamma'}$ contains p, and therefore their projections on P cannot be disjoint, a contradiction. One can proceed similarly for y, y', considering final subgeodesics instead of initial subgeodesics.

From now until the end of the subsection, fix a family $\{(P_i, r_i)\}_{i \in I}$ of homogeneous geodesic complete pointed metric spaces. Throughout the subsection all P-geodesics are implied to have range $\{(P_i, r_i)\}$.

If \mathcal{I} is a family of subintervals of [0, l] we set $\mathcal{I}[x] = \{J \in \mathcal{I} : J \subseteq [0, x]\}$ for x > 0.

Definition 3.22. We will say that the P-geodesics Γ and Γ' with associated almost fillings, respectively, \mathcal{I}_{Γ} and \mathcal{I}'_{Γ} have the same P-pattern until x > 0 if

- (1) $\mathcal{I}_{\Gamma}[x] = \mathcal{I}_{\Gamma'}[x],$
- (2) $\Gamma(I) = \Gamma'(I)$ for all $I \in \mathcal{I}_{\Gamma}[x]$,

(3) if there exists $J \in \mathcal{I}_{\Gamma}$ such that $x \in J$ and x is not the first point of J, then there exists $J' \in \mathcal{I}_{\Gamma'}$ with the same property and $h_{\Gamma}(J) = h_{\Gamma'}(J')$.

We will say that Γ and Γ' have the same initial P-pattern if there exists some x > 0 such that Γ and Γ' have the same pattern until x.

Clearly, having the same initial P-pattern is an equivalence relation on the set of P-geodesics. Denote by W the quotient set.

The property of having the same initial P-pattern is modeled on the following property for geodesics.

Definition 3.23. Let γ , γ' be geodesics in \mathbb{F} parametrized by arc length both starting from the same point *p*. We will say that γ and γ' have the same initial pattern if there exists x > 0 and a piece *P* such that $\gamma(x)$ and $\gamma'(x)$ both belong to *P*.

Lemma 3.24. (1) Consider geodesics γ and γ' parametrized by arc length starting from p. If there exists a piece P such that, for some x > 0, $\gamma(x)$ and $\gamma'(x)$ both belong to P, then for each $0 \le y \le x$ there exists a piece P_y such that $\gamma(y), \gamma'(y) \in P_y$. (2) Having the same initial pattern is an equivalence relation.

Proof. (1) If $p \in P$, the claim follows from the fact that each piece is convex. If this is not the case there exists x' such that $\gamma(x') = \gamma'(x') = \pi_P(p)$, and, for $x' \leq y \leq x$, $\gamma(y), \gamma'(y) \in P$. For $0 \leq y \leq x'$, and y contained in a non-trivial interval I such that $\gamma(I) \subseteq P'$ for some piece P', the claim follows from the proof of Lemma 3.20, point (3), which shows that $\gamma'(I) \subseteq P'$ as well. Also, if $I = [t_1, t_2]$ is maximal with that property, $\gamma(t_i) = \gamma'(t_i)$. If y is not contained in such an interval, then $\gamma(y) = \gamma'(y)$ because the union of maximal intervals as above is dense in [0, x'], and so y is the limit of a sequence of endpoints of such intervals.

(2) Consider geodesics parametrized by arc length γ , γ' , γ'' and x, y > 0 such that $\gamma(x)$ and $\gamma'(x)$ (resp. $\gamma'(y)$ and $\gamma''(y)$) both belong to some piece P_1 (resp. P_2). By point (1), we can assume that y = x. If $\gamma(x) = \gamma'(x)$ or $\gamma'(x) = \gamma''(x)$, we are done. Assuming that this is not the case, we will prove that $P_1 = P_2$. In fact, in this case it is easily seen that $\gamma'(x) \neq \pi_{P_1}(p), \pi_{P_2}(p)$, and therefore $\gamma'|_{[0,x]}$ contains non-trivial final subsegments contained in P_1 and P_2 . So $P_1 \cap P_2$ contains more than one point and $P_1 = P_2$, as required.

The importance of this notion is due to the following lemma:

Lemma 3.25. If γ and γ' are geodesic starting from p which have different initial patterns, then $\gamma^{-1}\gamma'$ is a geodesic.

Proof. It is clear that γ^{-1} and γ' concatenate well.

Lemma 3.26. If γ , γ' have the same initial pattern, then the induced P-geodesics Γ and Γ' have the same initial P-pattern.

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Proof. Let *x* and *P* be as in the definition of having the same initial pattern. If *p* is contained in *P*, then *P* contains the starting and ending point of the geodesics $\gamma|_{[0,x]}$, $\gamma'|_{[0,x]}$ and therefore they are contained in *P*. In this case $\mathcal{I}_{\Gamma}[x/2] = \mathcal{I}_{\Gamma}[x/2] = \emptyset$ and $h_{\Gamma}(J) = h_{\Gamma'}(J') = i$, where *J*, *J'* are maximal closed-open intervals such that $\gamma(J), \gamma'(J')$ are contained in *P* and *i* is chosen in such a way that *P* is isometric to P_i .

If $p \notin P$, then both γ and γ' must pass through the projection $\gamma(y)$ of p on P (and y > 0). It is easy to prove (see the proof of point (3) of Lemma 3.20) that Γ and Γ' have the same pattern until y.

Denote by $\mathcal{Y}(\mathbb{F}, p)$ the quotient of the set of geodesics starting from p by the equivalence relation of having the same initial pattern. The above lemma tells us that there is a well defined map $F_{\mathbb{F},p} \colon \mathcal{Y}(\mathbb{F}, p) \to \mathcal{W}$ (recall that \mathcal{W} is the set of equivalence classes of P-geodesics with the same initial P-pattern).

Convention 3.27. Suppose that \mathbb{G} is a tree-graded space satisfying the same requirements as \mathbb{F} , with a fixed choice of charts, and $p \in \mathbb{G}$. We will set, for each $w \in \mathcal{W}$, $H_{\mathbb{G},p}(w) = |F^{-1}(w)|$.

3.4. Counting geodesics. Now we will analyze asymptotic cones of relatively hyperbolic groups and minimal tree-graded structures. In each asymptotic cone X of a group G relatively hyperbolic with respect to its subgroups H_1, \ldots, H_n (infinite and with infinite index in G), the *normalized* tree-graded structure is the set of pieces containing the following:

- the subsets of X induced by a left *coset of some ${}^{*}H_{i}$ which are not real trees (notice that if it is not empty it covers X, and if it is empty X is a real tree),
- the transversal trees with respect to \mathcal{H} if the collection \mathcal{H} described above is a set of pieces, and X otherwise.

The pieces as in the second point will be referred to, with an abuse, as transversal trees. If \mathcal{H} is a set of pieces, by Proposition 3.9 they are homogeneous real trees of valency 2^{\aleph_0} . On the other hand, if \mathcal{H} is not a set of pieces, the valency of X is once again 2^{\aleph_0} . In fact, the set P induced by any H_i is not a point, as each H_i is infinite, and P belongs to a set of pieces for X. Hence, being a homogeneous real tree, it contains a geodesic line. So, applying Lemma 3.8, we easily obtain that X has valency at least 2^{\aleph_0} , and hence exactly 2^{\aleph_0} .

Let G be a group hyperbolic relative to H_1, \ldots, H_n . Let $\mathcal{P} = \{(P_i, r_i)\}_{i=0,\ldots,k}$ be representatives for the isometry classes of the pieces, where P_0 is a homogeneous real tree with valency 2^{\aleph_0} . We will denote by w_t the class in \mathcal{W} of a P-geodesic Γ with associated almost filling of [0, 1] simply $\{[0, 1)\}$ and such that $\Gamma(0) \in P_0$.

As we will see, the P-geodesics defined below are the ones represented by actual geodesics.

Definition 3.28. A P-geodesic Γ is admissible if for each $I_1 = [p_1, q_1), I_2 = [p_2, q_2)$ in its associated almost filling and such that $q_1 = p_2, \Gamma(p_1) \notin P_0$ or $\Gamma(p_2) \notin P_0$.

Given a non-virtually cyclic group G with cut-points in an asymptotic cone X, we can still consider a family $\mathcal{P} = \{(P_i, r_i)\}$ of representatives for the isometry classes of the pieces in the minimal tree-graded structure, where P_0 is a homogeneous real tree with valency 2^{\aleph_0} . The class w_t and the definition of admissible P-geodesic make sense in this case as well.

Proposition 3.29. If \mathbb{G} is either an asymptotic cone of a group G hyperbolic relative to H_1, \ldots, H_n equipped with the normalized tree-graded structure, or an asymptotic cone of a non-virtually cyclic group G containing cut-points equipped with the minimal tree-graded structure, then for each $p \in \mathbb{G}$ there exists a choice of charts such that

- $H_{\mathbb{G},p}(w_t) = 1$,
- $H_{\mathbb{G},p}(w) = 2^{\aleph_0}$ if $w_t \neq w \in W$ and w has an admissible representative,
- $H_{\mathbb{G},p}(w) = 0$ otherwise,

where $H_{\mathbb{G},p}$ is defined in Convention 3.27.

Proof. Suppose (without loss of generality) that $\mathbb{G} = C(G, e, v)$ and that p = e. In the case that G is relatively hyperbolic, let $J \subseteq \{1, ..., n\}$ be the set of the indices j such that $C(H_j, e, v)$ is not a real tree.

Let us consider an admissible P-geodesic Γ , with associated almost filling of [0, l] $\{I_a = [p_a, q_a)\}_{a \in A}$.

Step 1: "Finite approximants" for Γ . Consider some finite subset $A' \subseteq A$. We want to find an internal non-empty set $\mathscr{G} = \mathscr{G}(A')$ of internal geodesics $\hat{\gamma}$ such that their projections γ satisfy the properties required by Γ for $\{I_a\}_{a \in A'}$. Let us make this more precise. Choose for each *i* an identification of P_i with a piece Q_i containing *e*. For each $a \in A$ choose $u_a \in \mathbb{G}$ such that *e* and u_a lie on $Q_{h_{\Gamma}(I_a)}$, where h_{Γ} is as usual the index selector.

We require for the internal geodesics $\hat{\gamma} \in \mathcal{G}$ to satisfy the following, for each $a \in A'$:

- (1) $\hat{\gamma}(0) = e$,
- (2) for each $a \in A'$ such that $h_{\Gamma}(I_a) \ge 1$ there exists $g = g_a \in {}^*G$ such that $\gamma(p_a) = [g_a], \gamma(q_a) = g_a u_a$,
- (3) for each $a \in A'$ such that $h_{\Gamma}(I_a) = 0$ we have that $\gamma|_{I_a}$ is contained in a transversal tree.

Suppose that we are able to prove that there actually exist internal geodesics with these properties for each finite $A' \subseteq A$, as we will do later. The idea is to use saturation to find an internal geodesic $\hat{\gamma}$ which satisfies (1)–(3) for each $a \in A$. But first, we

have "express those properties internally": we need to find non-empty *internal* sets $\mathscr{G}(A')$, to apply saturation and find that the intersection is non-empty. We will do this separately for relatively hyperbolic groups and minimal tree-graded structures, starting with the relatively hyperbolic case.

Normalized structure case. Property (1) requires no comments. Property (2) holds if and only if there exists an infinitesimal ρ such that

$$d(\hat{\gamma}(p_a\nu), g_a), d(\hat{\gamma}(p_a\nu), g_a\hat{u}_a) \le \rho\nu,$$

where $[\hat{u}_a] = u_a$. So, fixing ρ , we have an internal set of internal geodesics satisfying (2): the one described by the property above (we can consider a fixed \hat{u}_a).

The task is slightly more difficult for condition (3). Let M be as in Lemma 2.20. If the projection of γ is contained in a transversal tree, using the property of M and an argument based on Lemma 1.8, we get that there exists an infinitesimal η such that for each left *coset H of some H_j ($j \in J$), the diameter of $\gamma \cap N_M(H)$ is bounded by $\eta \nu$. We claim that the converse holds as well.

In fact, consider γ such that there are two points $\gamma(x)$ and $\gamma(y)$, with x < y, such that $d(\gamma(x), \gamma(y)) \equiv v$, but there exists a left *coset *H* of some H_j such that $d(x, H), d(y, H) \leq \eta' v$, for some infinitesimal η' . By the property of *M*, there are points $\gamma(x'), \gamma(y')$ whose distance from *H* is at most *M*. What is more, we can assume that $d(\gamma(x'), \gamma(y')) \equiv v$ by taking the x' as close as possible to x and y' as close as possible to y. This is a contradiction since any arc between [x'] and [y'] is contained in *P*. In particular this applies to a non-trivial subgeodesic of the geodesic δ induced by γ , and therefore δ is not contained in a transversal tree. This completes the proof of the claim.

Minimal structure case. Let us move on to minimal tree-graded structures. For what regards property (2), we can proceed as above. The idea for property (3) is the characterization of transversal lines as those admitting a projection satisfying (*P*2) as in the proof of Proposition 3.11. Namely, $\gamma|_{I_a}$ is contained in a transversal tree if and only if there exists an infinitesimal ρ such that $\phi(\gamma|_{[p_av,q_av]}, 1/\rho)$, as defined in the proof of Proposition 3.11, holds.

Step 2: Applying saturation. In both cases we have that, for each A' and fixing a sufficiently large infinitesimal $\rho(A')$, we can find a non-empty (as we will show later) internal set of internal geodesics $\mathcal{G}(A')$ satisfying (1)–(3). Therefore, after choosing an infinitesimal greater than any $\rho(A')$ (see Lemma 1.6), we can use saturation to find an internal geodesic $\hat{\gamma}$ which satisfies (1)–(3) for each $a \in A$. Let γ be the induced geodesic in \mathbb{G} . It is quite clear that we can choose identifications of each pair (P, p) with some (P_i, r_i) , where P is a piece intersecting γ in a non-trivial subgeodesic and p is the entrance point of γ in P, in such a way that the P-geodesic associated to γ is Γ . In fact, in the case when (P, p) has to be identified with (P_i, r_i) for $i \ge 1$, we can use g_a as in property (2) to "translate" the fixed identification of (P_i, r_i) with Q_i . In the case when (P, p) has to be identified with (P_0, r_0) , we can use the isotropy of P_0 , that is the fact that for each $x, y \in P_0$ with $d(x, r_0) = d(y, r_0)$ there exists an

isometry of P_0 fixing r_0 and taking x to y. Notice that we implicitly used the fact that $\bigcup I_a$ is dense in [0, l] to guarantee that the I_a 's are exactly the maximal intervals such that $\gamma |_{I_a}$ is contained in a piece.

Step 3: Constructing many geodesics starting from a given one. So far we proved that $H_{\mathbb{G},e}([\Gamma]) \ge 1$ (for an admissible Γ). We want to use $\hat{\gamma}$, γ as in step 2 to construct many other geodesics with the same properties. Again, we will start with the relatively hyperbolic case and then move on to the minimal tree-graded structure case.

Normalized structure case. Consider a hyperbolic element $g \in G$. Note that the isometry induced in \mathbb{G} by left multiplication by g stabilizes no piece which is not a transversal tree. This immediately implies that, unless an initial subgeodesic of γ is contained in the transversal tree at e, γ and $g\gamma$ do not have the same initial pattern. Similarly, if $n_1 \neq n_2 \in \mathbb{N}$ (and $d(e, g^{n_i}) \in o(v)$), $g^{n_1}\gamma$ and $g^{n_2}\gamma$ do not have the same initial pattern. Note that the cardinality of $\{n \in \mathbb{N} : d(e, g^n) \in o(v)\}$ is at least 2^{\aleph_0} . Therefore, if $[\Gamma] \neq w_t$ and Γ is admissible, we have $H_{\mathbb{G},e}(w) \geq 2^{\aleph_0}$. The other inequality clearly holds, so we are done in this case. On the other hand, it is clear from the definitions that $H_{\mathbb{G},e}(w_t) = 1$, and that no geodesic in \mathbb{G} has non-admissible associated P-geodesic, that is $H_{\mathbb{G},e}(w) = 0$ if w has no admissible representatives.

Minimal structure case. In the minimal tree-graded structure case, we proceed approximating the argument above. Namely, consider an element $g \in {}^*G$ such that $[g] \neq e$ but $[g] \in T_e$. Notice that if $[\Gamma] \neq w_t$ then $d(gp, p) = 2l(\gamma) + d(e, [g])$, where p is the second endpoint of γ . Similarly, if $[g_1] \neq [g_2]$ and $[g_1], [g_2] \in T_e$, we have an analogous property for g_1p, g_2p . Using this, it is easily seen that for each $n \in \mathbb{N}^+$ we can find g_1, \ldots, g_n such that

- (1) $d(g_i q, g_j q) \ge 2l(\gamma)\nu$ for $i \ne j$, where q is such that [q] = p,
- (2) $d(g_i, e) \leq 1/n$ for each *i*.

Therefore, we can also find g_1, \ldots, g_{μ} with the same properties for some infinite μ . Unfortunately, this is not enough to conclude that $g_i \gamma$ concatenates well with γ_j for each $i \neq j$, which would lead to the end of the proof (up to the final considerations as in the relatively hyperbolic case). However, this still holds because we can add the following requirement:

(3) each path in *G obtained concatenating at most n internal geodesics connecting a point on g_i ŷ to a point in g_j ŷ contains a point whose distance from g_i is a most ν/n, if i ≠ j.

If g_1, \ldots, g_{μ} also satisfies this property, it is easily seen that all paths connecting $g_i \gamma$ to $g_j \gamma$ for $i \neq j$ contain *e*. In particular, no piece (except transversal trees) can contain initial subpaths of both $g_i \gamma$ and $g_j \gamma$, as it does not contain cut-points. So, $g_i \gamma$ and $g_j \gamma$ concatenate well for $i \neq j$, and we are done.

Step 4: Actually constructing the "finite approximants". We are only left with finding internal geodesics as above. For each $a \in A'$ we can find a geodesic parametrized by (a translate of the) arc length $\gamma_a: [p_a, q_a] \to \mathbb{G}$ which is contained in a piece isometric to $P_{h_{\Gamma}(a)}$, $\gamma_a(p_a) = e$ and $\gamma_a(q_a) = u_a$. Order A' in such a way that $a \leq b$ if $p_a \leq p_b$. We want to show that if a < b, up to translating γ_b by an element of **G*, we can find a geodesic parametrized by a translate of the arc length $\gamma: [p_a, q_b] \to \mathbb{G}$ such that $\gamma|_{[p_a, q_a]} = \gamma_a$ and $\gamma_{[p_b, q_b]} = \gamma_b$. In fact, suppose first that $q_a < p_b$. It is easy to find a geodesic δ of length $q_b - q_a$ starting from $\gamma_a(q_a)$ such that γ_a and δ concatenate well. Also, there exists an element $g \in *G$ such that $g\gamma_b$ has starting point the final point of δ . Up to changing *g* we can also arrange that δ and γ_b concatenate well (by Lemma 3.10). The concatenation of γ_a , δ and $g\gamma_b$ is the required geodesic. If $q_a = p_b$, we can still find *g* such that γ_a and γ_b concatenate well by Lemma 3.10, unless they are both contained in a transversal tree, but this is not the case as Γ is admissible.

Using inductively the argument above (and, possibly, the first part of it for the minimum and maximum of A'), we obtain a geodesic γ such that $\gamma|_{I_a}$ is contained in a piece isometric to $P_{h_{\Gamma}(a)}$ for each $a \in A'$. An internal geodesic connecting e to an element of **G* which projects on the last point of γ satisfies all our requirements.

The aim of the next subsections is to prove that the kind of information provided by the proposition above is enough to determine the bilipschitz type of \mathbb{G} .

3.5. A criterion for being bilipschitz. Fix, throughout the subsection, a family $\{(P_i, r_i)\}_{i \in I}$ of complete homogeneous geodesic pointed metric spaces. We also assume that P_i is not isometric to P_j if $i \neq j$ and that no P_i consists of a single point.

Convention 3.30. All tree-graded spaces from now on are assumed to be homogeneous and to have homogeneous pieces.

Recall that by \mathcal{W} we denote the set of equivalence classes of P-geodesics (with range $\{(P_i, r_i)\}$) with the same initial P-pattern, and consider a map α assigning to each $w \in \mathcal{W}$ a cardinality $\alpha(w)$. Denote by \mathbb{F}_{α} a tree-graded space such that for each $p \in \mathbb{F}$ there exists a choice of charts such that $H_{\mathbb{F}_{\alpha},p}(w) = \alpha(w)$ for each $w \in \mathcal{W}$, if such \mathbb{F}_{α} exists (the question whether or not such \mathbb{F}_{α} exists will be addressed later).

We will be interested in tree-graded spaces with pieces not necessarily isometric (but bilipschitz equivalent) to the P_i 's. Suppose that we are given a family of homogeneous, geodesic complete metric space $\{Q_j\}_{j \in J}$ and bilipschitz equivalences $f_j: Q_j \to P_{i(j)}$. Suppose that $\{i(j)\}_{j \in J} = I$. Denote by \mathcal{X} the set of equivalence classes of P-geodesics with range $\{(Q_j, s_j)\}$ (for $s_j \in Q_j$ such that $f_j(s_j) = r_{i(j)}$) with the same initial P-pattern. Set $\mathcal{F} = \{f_j\}_{j \in J}$.

Starting from the data above we are going to construct a map $\psi_{\mathcal{F}} \colon \mathcal{X} \to \mathcal{W}$, which describes how P-geodesics change when "substituting the Q_j 's with the P_i 's".

Indeed, we are going to construct first a map $\psi'_{\mathcal{F}}$ from the set of P-geodesics with range $\{(Q_j, s_j)\}$ to the set of P-geodesics with range $\{(P_i, r_i)\}$, which induce the required map $\psi_{\mathcal{F}}$.

Consider a P-geodesic Γ with range $\{(Q_j, s_j)\}$ with associated almost filling of [0, l] $\{I_a = [p_a, q_a)\}_{a \in A}$.

First of all, let us define the almost filling $\{J_a\}_{a \in A}$ associated to $\Theta = \psi'_{\mathcal{F}}(\Gamma)$. We will need a function $s_{\Gamma} : [0, l] \to \mathbb{R}$, defined in such a way that it keeps track of the "stretching factor" given by the f_i 's.

For $a \in A$ set $A_a = \{b \in A | q_b \le p_a\}$. If $t \in [0, l] \setminus \bigcup_{a \in A} \mathring{I}_a$, set

$$s_{\Gamma}(t) = \sum_{b \in A_a} d(r_{i(h_{\Gamma}(b))}, f_{h_{\Gamma}(b)}(\Gamma(I_b))) + \lambda([0, p_a] \setminus \bigcup_{b \in A_a} I_b),$$

where λ is the Lebesgue measure and h_{Γ} is, as usual, the index selector. If $t \in I_a$ set

$$s_{\Gamma}(t) = s_{\Gamma}(p_a) + \frac{t - p_a}{q_a - p_a} d(r_{i(h_{\Gamma}(a))}, f_{h_{\Gamma}(a)}(\Gamma(I_a))).$$

Remark 3.31. It is not difficult to prove that s_{Γ} is k-bilipschitz.

We are ready to define

$$J_a = s_{\Gamma}(I_a).$$

Now, simply set $\Theta(J_a) = f_{h_{\Gamma}(a)}(\Gamma(I_a))$. It is easily shown that $\{J_a\}$ is an almost filling and that Θ is a P-geodesic whose initial pattern does not depend on the choice of the representative of $[\Gamma] \in \mathcal{X}$. In particular, $\psi'_{\mathcal{F}}$ induce a well defined map $\psi_{\mathcal{F}} : \mathcal{X} \to \mathcal{W}$.

Remark 3.32. $\psi_{\mathcal{F}}$ is surjective (because $\{i(j)\}_{j \in J} = I$).

Convention 3.33. With an abuse of notation, if γ is a geodesic (and a choice of charts has been fixed) we will denote $\psi'_{\mathcal{F}}(\Gamma)$ and s_{Γ} , where Γ is the P-geodesic associated to γ , simply by $\psi'_{\mathcal{F}}(\gamma)$ and s_{γ} , respectively.

Theorem 3.34. Suppose that $\alpha(w)$ is infinite for each $w \in W$. Also suppose that \mathbb{F} is tree-graded with trivial transversal trees and that each of its pieces is isometric to one of the Q_j 's as above, and that each f_j is k-bilipschitz. Also, suppose that for each $p \in \mathbb{F}$ there exists a choice of charts such that:

- (1) $\sum_{\{x' \in \mathfrak{X}: \psi_{\mathcal{F}}(x') = \psi_{\mathcal{F}}(x)\}} H_{\mathbb{F},p}(x') \leq \alpha(\psi_{\mathcal{F}}(x)) \text{ for each } x \in \mathfrak{X}.$ Then \mathbb{F} admits a k-bilipschitz embedding into \mathbb{F}_{α} .
- (2) $\sum_{\{x' \in \mathfrak{X}: \psi_{\mathcal{F}}(x') = \psi_{\mathcal{F}}(x)\}} H_{\mathbb{F},p}(x') = \alpha(\psi_{\mathcal{F}}(x)) \text{ for each } x \in \mathfrak{X} \text{ and } p \in \mathbb{F}.$ Then \mathbb{F} is k-bilipschitz equivalent to \mathbb{F}_{α} .

Remark 3.35. Unfortunately, in the case we are interested in not all the cardinalities are infinite. However, modifying slightly the proof one can obtain Theorem 3.3. This would be a shorter way to prove that theorem than the one we will follow, that is reducing to the case when all cardinalities are infinite. We will do that to obtain an "explicit" description of the asymptotic cones of relatively hyperbolic group (as the universal tree-graded space described in the proof of Theorem 3.36).

Proof of Theorem 3.34. We prove (2), the proof of (1) being very similar. Set $\mathbb{G} = \mathbb{F}_{\alpha}$. During the proof bilipschitz maps are implied to be *k*-bilipschitz.

If $X \subseteq \mathbb{F}$ and $x \in X$ denote by $\mathcal{Y}(X, x)$ the set of elements of $\mathcal{Y}(\mathbb{F}, x)$ which can be represented by a geodesic contained in *X*. We will call a subspace *X* of \mathbb{F} *good* if it has the following properties:

- (1) X is geodesic.
- (2) For each x ∈ X, the set 𝔅(X, x) either has at most two elements or it coincides with 𝔅(𝔅, x). In the first case x will be called empty for X, while in the second case it will be called full for X.
- (3) If *X* contains a non-trivial geodesic contained in one piece (or, equivalently, if it contains two points on the same piece), then it contains the entire piece.

Analogous definitions can be given for \mathbb{G} . Note that an increasing union of good subspaces is a good subspace. Also, remark that if X is a good subspace of \mathbb{F} or \mathbb{G} and $x, y \in X$, then *any* geodesic between x and y is contained in X (i.e., X is convex). In fact, if γ , γ' are geodesics connecting x and y and $p \in \gamma \setminus \gamma'$, there exists a piece containing p and intersecting both γ and γ' in a non-trivial arc (as p is contained in a simple loop which is a union of two subgeodesics of γ and γ'). Therefore, conditions (1) and (3) imply the claim.

We wish to construct the required bilipschitz equivalence using Zorn's Lemma on the set of *good pairs*, that is pairs (X, f) such that

- X is a good subspace of \mathbb{F} ,
- f is a bilipschitz embedding of X into \mathbb{G} which preserves fullness, that is, f(x) is full for f(X) whenever x is full for X,
- if, for some piece P ⊆ G, f(X) ∩ P contains at least two points, there exists a piece P' of F such that f(P') = P.

Note that if (X, f) is a good pair, f(X) is a good subspace of \mathbb{G} (we require the third property in order to have this). A point is a good subspace, therefore the set such pairs is not empty. If we set $(X, f) \leq (Y, g)$ when $X \subseteq Y$ and $g|_X = f$, then clearly any chain has an upper bound. Therefore there exists a maximal element (M, h). We want to show that $M = \mathbb{F}$. Note that M is closed, because h can be extended to \overline{M} as \mathbb{G} is complete, and, as we are going to show, \overline{M} is a good subspace.

Let us prove that \overline{M} satisfies (3) first, as it is the simplest condition to check. If [x, y] is a non-trivial geodesic contained in a piece P and x', y' are sufficiently close to x and y respectively, then any geodesic from x' to y' contains a non-trivial subgeodesic contained in P. This readily implies (3).

Let us prove (1). Consider any $x, y \in M$. We want to show that there is a geodesic contained in \overline{M} which connects them. Consider any geodesic γ in \mathbb{F} from x to y. Consider any piece Q which intersects γ in a non-trivial arc between $\pi_Q(x) = x'$ and $\pi_Q(y) = y'$. Each geodesic between points close enough to x and y intersects Q in a non-trivial arc, and this readily implies, by conditions (1) and (3) for M, that $Q \subseteq M$. This argument shows that there exists a dense subset of γ contained in M (see Lemma 3.16). By the remark that each geodesic connecting two points in M is contained in M, we have that $\gamma \setminus \{x, y\} \subseteq M$, and therefore $\gamma \subseteq \overline{M}$.

We are left to show (2). First, we have that $\mathcal{Y}(M, x) = \mathcal{Y}(M, x)$ if $x \in M$. In fact, if γ represents an element of $\mathcal{Y}(\overline{M}, x)$, by the previous argument $\gamma \setminus \{y\}$ is contained in M, where y is the last point of γ . An initial subgeodesic γ' of γ is contained in M and so $[\gamma] = [\gamma'] \in \mathcal{Y}(M, x)$. Also, $\mathcal{Y}(\overline{M}, x)$ cannot contain more than one element if $x \in \overline{M} \setminus M$. Suppose in fact that this is not the case and consider geodesics $\gamma_1, \gamma_2 \subseteq \overline{M}$ such that $[\gamma_1] \neq [\gamma_2] \in \mathcal{Y}(\overline{M}, x)$. By Lemma 3.25, the concatenation γ of γ_2^{-1} and γ_1 is a geodesic. By the proof of point (1), we would have $x \in M$, as it is not an endpoint of γ .

We have thus proved that \overline{M} is good, so $M = \overline{M}$ by maximality and M is closed.

Assume that there exists $x \notin M$. Consider some $p' \in M$ and let p be the last point on a geodesic [p', x] which lies on M. We want to show that p is empty for M, by showing that [p, x] is not a representative of an element in $\mathcal{Y}(M, p)$. In fact, suppose that this is not the case. Then there exists a point $q \neq p$ on [p, x], a piece P and a point $r \in P$, $r \neq p$, such that a geodesic [p, r] is contained in M and $q, r \in P$. If $p \in P$, by property (3) we have $P \subseteq M$ and in particular $q \in M$, which contradicts our choice of p. If $p \notin P$, we can assume $r = \pi_P(p)$. So [p,q]must contain $r \in M$. This is a contradiction as $[p,q] \cap M = \{p\}$.

Fix a set of representatives R_1 (resp. R_2) for the elements of $\mathcal{Y}(\mathbb{F}, p) \setminus \mathcal{Y}(M, p)$ (resp. $\mathcal{Y}(\mathbb{G}, p) \setminus \mathcal{Y}(h(M), h(p))$). At first, we want to extend *h* to the union *M'* of *M* and all the elements of R_1 .

We wish to prove that up to changing representatives of R_i , there is a bijection $b: R_1 \rightarrow R_2$ such that, for each $\gamma \in R_1$,

• the P-geodesic associated to $b(\gamma)$ is $\psi'_{\mathcal{F}}(\gamma)$ (for some choices of charts).

Consider choices of charts for \mathbb{F} and \mathbb{G} as in the statement. We clearly have

$$|F_{\mathbb{F},p}^{-1}(\{x' \in \mathcal{X} : \psi_{\mathcal{F}}(x') = \psi_{\mathcal{F}}(x)\}) \setminus \mathcal{Y}(M, p)|$$

=
$$\sum_{\substack{\{x' \in \mathcal{X}:\\\psi_{\mathcal{F}}(x') = \psi_{\mathcal{F}}(x)\}}} H_{\mathbb{F},p}(x') = H_{\mathbb{G},f(p)}(\psi_{\mathcal{F}}(x)) = |F_{\mathbb{G},f(p)}^{-1}(\psi_{\mathcal{F}}(x)) \setminus \mathcal{Y}(f(M), f(p))|$$

for each $x \in \mathcal{X}$ (the first and last equality hold because each $\alpha(w)$ is infinite and $|\mathcal{Y}(M, p)|, |\mathcal{Y}(f(M), f(p))| \le 2$ by emptiness).

These considerations imply that we can choose a bijection $b: R_1 \to R_2$ such that for each $\gamma \in R_1$ the P-geodesic associated to $b(\gamma)$ represents the same class in W as $\psi'_{\mathcal{F}}(\gamma)$. To obtain what we need is now sufficient to substitute geodesics in R_1 and R_2 with appropriate subgeodesics.

We are now ready define an extension of *h*, denoted by $\bar{h}: M' \to \mathbb{F}_{\alpha}$, as follows:

$$\bar{h}(x) = \begin{cases} h(x) & \text{if } x \in M, \\ b(\gamma)(s_{\gamma}(t)) & \text{if } x = \gamma(t) \text{ for some } \gamma \in R_1. \end{cases}$$

Note that *h* is indeed a bilipschitz embedding (see Lemma 3.25 and Remark 3.31). The last step is to extend it further so that the domain satisfies property (3). Consider a piece *P* which intersects some $\gamma \in R_1$ in a non-trivial subgeodesic γ' . As the P-geodesic associated to $b(\gamma)$ is $\psi'_{\mathcal{F}}(\gamma)$, $\bar{h}(\gamma')$ is contained in a piece *P'* bilipschitz equivalent to *P*. Not only that: using the fixed choices of charts and the maps f_i 's, we have that there exists a $g_P : P \to P'$ which maps γ' to $\bar{h}(\gamma')$. Let Δ be the family of pieces *P* as above. Consider the bilipschitz equivalences $\{g_P\}_{P \in \Delta}$. We can use them to further extend \bar{h} to $\tilde{h} : M'' \to \mathbb{G}$, where $M'' = M' \cup \bigcup_{P \in \Delta} P$, as follows:

$$\tilde{h}(x) = \begin{cases} \bar{h}(x) & \text{if } x \in M', \\ g_P(x) & \text{if } x \in P. \end{cases}$$

Once again, this is a bilipschitz embedding. It is quite clear that M'' satisfies (1) and (3). It is also not difficult to see that it satisfies (2) as well, and more precisely that

- p is full for M'',
- each point in *M*\{*p*} is empty (resp. full) for *M*["] if and only if it is empty (resp. full) for *M*,
- each point in $M'' \setminus M$ is empty for M''.

Also, h is readily checked to satisfy all the requirements needed to establish that (M'', h) is a good pair. By maximality of M, this is a contradiction.

We finally proved that if (M, h) is a maximal good pair, then $M = \mathbb{F}$. Therefore, there exists a bilipschitz embedding $h: \mathbb{F} \to \mathbb{G}$, with the further property that h preserves fullness. Let us show that this implies that h is surjective. Consider, by contradiction, some $x \in \mathbb{G} \setminus h(\mathbb{F})$. Fix some $p \in \mathbb{F}$ and consider a geodesic [h(p), x]. As $h(\mathbb{F})$ is closed, being a complete metric space, we can assume that $[h(p), x] \cap h(\mathbb{F}) = \{h(p)\}$. Repeating an argument we already used for M (recall that $h(\mathbb{F})$ is a good subspace), we have that [h(p), x] represents an element of $\mathcal{Y}(\mathbb{G}, h(p)) \setminus \mathcal{Y}(h(\mathbb{F}), h(p))$. But p is full for \mathbb{F} , so this contradicts the hypothesis that h preserves fullness.

3.6. Universal tree graded spaces. As in the previous subsection, consider a family $\{(P_i, r_i)\}_{i \in I}$ of complete homogeneous geodesic pointed metric spaces.

At this point it is a natural problem to find those maps $(w \in W) \mapsto \alpha(w)$, where each $\alpha(w)$ is a cardinality, which are realized by a homogeneous tree-graded space.

Our aim is now to construct a "universal" tree-graded space, given an infinite cardinality $\alpha(w)$ for each $w \in W$.

Theorem 3.36. Consider any map $(w \in W) \mapsto \alpha(w)$, where each $\alpha(w)$ is infinite. There exists a tree-graded space $\mathbb{F} = \mathbb{F}_{\alpha}$ with trivial transversal trees such that each of its pieces is isometric to one of the P_i 's and, for an appropriate choice of charts, for each $w \in W$ and $p \in \mathbb{F}$ we have $H_{\mathbb{F},p}(w) = \alpha(w)$.

We will say that \mathbb{F} as above is a universal tree-graded space.

Remark 3.37. If we did not require the $\alpha(w)$'s to be infinite the theorem would be false, for if the cardinality of some $F_{\mathbb{F},p}^{-1}(w)$ is a most one, many other cardinalities are forced to be 0 (for the same reason why only admissible P-geodesics are represented by geodesics in the asymptotic cone of a relatively hyperbolic group). It seems reasonable that the theorem can be extended (in the same generality) to the case when the $\alpha(w)$'s are at least 2.

Proof. Denote by W the set of all P-geodesics. For $\Gamma \in W$, we will denote by $[\Gamma]$ the corresponding class in W.

Let us define \mathbb{F} , at first as a set. Some of the definitions which follow are inspired by the definitions of A_{μ} and of its distance in [7]. Set $\alpha = \sup_{w \in W} \alpha(w)$. We will need to fix for each *i* and $x \in P_i$ different from r_i an isometry ϕ_x of P_i which maps *x* to r_i . If Γ is a P-geodesic with associated almost filling of [0, l] $\mathcal{I} = \{[p_a, q_a)\}$, and $x < y \in [0, l]$ do not lie in the interior of any $I \in \mathcal{I}$, denote by

- $-\Gamma$ the P-geodesic with associated almost filling (once again of [0, l]) { $[l q_a, l p_a)$ } and such that $-\Gamma(l q_a) = \phi_{\Gamma(p_a)}(r_{h_{\Gamma}(p_a)})$ (where h_{Γ} denotes as usual the index selector of Γ),
- $\Gamma^{x,y}$ the P-geodesic with associated almost filling (of [0, y x]) { $[p_a x, q_a x) : p_a \ge x, q_a \le y$ } and such that $\Gamma^{x,y}(t) = \Gamma(t + x)$.

The idea is that $-\Gamma$ moves backwards along Γ , and $\Gamma^{x,y}$ is a restriction of Γ . The elements of \mathbb{F} will be quadruples $f = (\rho_f, \Gamma_f, \mathcal{I}_f, \beta_f)$ such that

- (1) $\rho_f \in \mathbb{R}_{\geq 0}$,
- (2) \mathcal{I}_f is an almost filling of $[0, \rho_f]$,
- (3) Γ_f is a P-geodesic with associated almost filling \mathcal{I}_f ,
- (4) $\beta_f : [0, \rho_f) \to \alpha$ is piecewise constant from the right, that is, for each *t* there exists $\varepsilon > 0$ such that $f|_{[t,t+\varepsilon]}$ is constant,
- (5) if x lies in the interior of some $I \in \mathcal{I}_f$, β_f is constant in a neighborhood of x,
- (6) $\beta_f(t) < \alpha([\Gamma_f^{t,\rho_f}])$ for each $t \in [0, \rho_f)$ such that t = 0 or β_f is not constant in a neighborhood of t.

Let us construct some examples of elements of \mathbb{F} . If $x \in P_i$ and $\mu < \alpha$, denote by $f^{x,\mu}$, if it exists, the element of \mathbb{F} such that

- $\rho_{f^{x,\mu}} = d_{P_i}(r_i, x),$
- $\mathcal{I}_{f^{x,\mu}} = \{[0, \rho_{f^{x,\mu}})\},\$
- $\Gamma_{f^{x,\mu}}(0) = x$,
- $\beta_{f^{x,\mu}}$ is constantly μ .

Condition (6) restricts the possible values of μ .

We are now going to define a concatenation of elements of \mathbb{F} . Consider $f, g \in \mathbb{F}$. The concatenation f * g is the element of \mathbb{F} such that

- $\rho_{f*g} = \rho_f + \rho_g$,
- $\mathcal{I}_{f*g} = \mathcal{I}_f \cup \{\rho_f + I : I \in \mathcal{I}_g\},$
- $\Gamma_{f*g}^{0,\rho_f} = \Gamma_f$ and $\Gamma_{f*g}^{\rho_f,\rho_f+\rho_g} = \Gamma_g$,
- $\beta_{f*g}(t) = \beta_f(t)$, where $\beta_f(t)$ is defined and $\beta_{f*g}(t) = \beta_g(t \rho_f)$ where $\beta_g(t \rho_f)$ is defined.

We want now to define a distance on \mathbb{F} . Consider $f, g \in \mathbb{F}$. Let s = s(f, g) be their separation moment, i.e.,

$$s = \sup\{t : \Gamma_f(t') = \Gamma_g(t'), \, \beta_f(t') = \beta_g(t') \text{ for all } t' \in [0, t]\}.$$

Note that this supremum is never a maximum. We will consider two cases.

(a) If $\beta_f(s) = \beta_g(s)$ and $h_{\Gamma_f}(s) = h_{\Gamma_g}(s) = i$ (in particular they are defined in *s*), denoting by $J_f \in \mathcal{I}_f$ and $J_g \in \mathcal{I}_g$ the intervals containing *s*, we set

$$d(f,g) = (\rho_f - s) + (\rho_g - s) + d_{P_i}(\Gamma_f(s), \Gamma_g(s)) - l(J_f) - l(J_g);$$

(b) in any other case,

$$d(f,g) = (\rho_f - s) + (\rho_g - s)$$

For later purposes, define u = u(f, g) and v = v(f, g) in the following way: if d(f, g) is as in case (a), let u and v be such that $J_f = [s, u), J_g = [s, v)$; if d(f, g) is as in case (b), set u = v = s. The following remark will be used many times in the proof that d is a distance.

Remark 3.38. *s* does not lie in the interior of any element of \mathcal{I}_f or \mathcal{I}_g . If u > s or v > s, then both inequalities hold and $[s, u) \in \mathcal{I}_f, [s, v) \in \mathcal{I}_g$. $s \le u \le \rho_f, s \le v \le \rho_g$. The formula in case (a) can be rewritten as $d(f,g) = (\rho_f - u) + (\rho_g - v) + d_{P_i}(\Gamma_f(s), \Gamma_g(s))$. $(\rho_f - u) + (\rho_g - v) \le d(f,g) \le (\rho_f - s) + (\rho_g - s)$. If s(f,g) < s(g,h), then s(f,h) = s(f,g).

Lemma 3.39. *d* is a distance.

Proof. The only non trivial property to check is the triangular inequality. Consider $f, g, h \in \mathbb{F}$. We have to show that $d(f, h) \leq d(f, g) + d(g, h)$. Set $s_1 = s(f, g)$, $s_2 = s(g, h)$ and $s_3 = s(f, h)$. Define analogously u_i and v_i , i = 1, 2, 3. We will consider several cases, which cover all possible situations up to exchanging the roles of f and h (and therefore, for example, u_1 and v_2).

1) $u_1 \leq s_3, v_2 \leq s_3$. In this case we get

$$d(f,h) \leq (\rho_f - s_3) + (\rho_h - s_3)$$

$$\leq (\rho_f - u_1) + (\rho_h - v_2)$$

$$\leq (\rho_f - u_1) + (\rho_g - v_1) + (\rho_g - u_2) + (\rho_h - v_2)$$

$$\leq d(f,g) + d(g,h).$$

2) $s_3 < u_1 \le u_3$, $s_1 < u_1$ and $v_2 \le v_3$. We have that $[s_3, u_3)$ and $[s_1, u_1)$ both belong to \mathcal{I}_f and their intersection is not empty. Therefore $[s_3, u_3) = [s_1, u_1)$, that is, $s_3 = s_1$ and $u_3 = u_1$. Also, clearly $s_2 \ge s_3$, by the definition of separation moment. We will consider two subcases.

2') $s_2 < v_2$. In this case, by the same argument we just used, $s_2 = s_3 = s_1$ and $v_2 = v_3$. For $i = h_{\Gamma_f}(s_3)$ (we will not repeat this), using the relations we found so far and the triangular inequality in P_i , we have

$$d(f,h) = (\rho_f - u_3) + d_{P_i}(\Gamma_f(s_3), \Gamma_h(s_3)) + (\rho_h - v_3)$$

$$\leq (\rho_f - u_1) + d_{P_i}(\Gamma_f(s_1), \Gamma_g(s_1)) + (\rho_g - v_1)$$

$$+ (\rho_g - v_2) + d(\Gamma_g(s_2), \Gamma_h(s_2)) + (\rho_h - v_2)$$

$$= d(f,g) + d(g,h).$$

If $s_2 = v_2$, we have $s_2 \in [s_3, v_3]$. But s_2 cannot belong to the interior of $[s_3, v_3) \in \mathcal{I}_h$. Therefore either $s_2 = s_3$ or $s_2 = v_3$. But $s_2 = s_3$ is contradictory as it implies $\beta_g(s_2) = \beta_g(s_1) = \beta_f(s_1) = \beta_f(s_3) = \beta_h(s_3) = \beta_h(s_2)$ and similarly $h_{\Gamma_g}(s_2) = h_{\Gamma_h}(s_2)$, therefore we should have $s_2 < v_2$.

2") $v_2 = s_2 = v_3$. As $[s_1, v_1) \in \mathcal{I}_g$, $[s_1, v_2) = [s_3, v_3) \in \mathcal{I}_h$ and v_3 is the separation moment of g and h, we get $v_1 = v_2$. We have, using $s_1 = s_3 < s_2$ (and the definition of separation moment),

$$d(f,h) = (\rho_f - u_3) + d_{P_i}(\Gamma_f(s_3), \Gamma_h(s_3)) + (\rho_h - v_3)$$

= $(\rho_f - u_1) + d_{P_i}(\Gamma_f(s_1), \Gamma_g(s_1)) + (\rho_h - v_2)$
 $\leq (\rho_f - u_1) + d_{P_i}(\Gamma_f(s_1), \Gamma_g(s_1)) + (\rho_g - v_1) + (\rho_h - u_2) + (\rho_h - v_2)$
 $\leq d(f,g) + d(g,h).$

3) $s_3 < u_1 \le u_3$, $s_1 = u_1$ and $v_2 \le v_3$. As s_1 cannot lie in the interior of $[s_3, u_3) \in \mathcal{I}_f$, $s_1 = u_1 = u_3$. Up to exchanging the roles of f and h we already treated the case when $s_2 < v_2$ (case 2"). So we can assume $s_2 = v_2$. As $s_1 = u_3 > s_3$, we have $s_2 = s_3$, in particular $s_1 > s_2$. But $\beta_g(s_2) = \beta_f(s_2) =$ $\beta_f(s_3) = \beta_h(s_3) = \beta_h(s_2)$ and analogously $h_{\Gamma_g}(s_2) = h_{\Gamma_h}(s_2)$, so we should have $s_2 < v_2$, a contradiction. This (sub)case is therefore impossible.

4) $u_1 = u_3 = s_3$, $v_2 \le v_3$. Note that $v_3 = s_3$, and so $v_2 \le s_3$. Thus,

$$d(f,h) = (\rho_f - s_3) + (\rho_h - s_3)$$

$$\leq (\rho_f - u_1) + (\rho_g - v_1) + (\rho_g - u_2) + (\rho_h - v_2)$$

$$\leq d(f,g) + d(g,h).$$

5) $u_1 > u_3 > s_3$. In this case we have $s_1 \ge u_3$ (if $s_1 = u_1$ it is obvious, if $s_1 < u_1$ it follows from the fact that u_3 cannot lie in the interior of $[s_1, u_1)$). Also, $s_2 = \min\{s_3, s_1\} = s_3$. Observe that $s_2 < u_2$, as $\beta_g(s_2) = \beta_f(s_2) = \beta_f(s_3) = \beta_h(s_3) = \beta_h(s_2)$ and similarly $h_{\Gamma_g}(s_2) = h_{\Gamma_h}(s_2)$ (we used $s_1 \ge u_3 > s_3 = s_2$, $s_3 = s_2$ and $u_3 > s_3$). Note that $v_2 = v_3$ and $u_2 = u_3$. In fact, $[s_2, v_3) = [s_3, v_3) \in I_h$ and $[s_2, u_3) = [s_3, u_3) \in I_f$, but also $[s_3, u_3) \in I_g$ as $u_3 < u_1$. If $s_1 = u_1$, we have

$$d(f,h) = (\rho_f - u_3) + d_{P_i}(\Gamma_f(s_3), \Gamma_h(s_3)) + (\rho_h - v_3)$$

$$\leq (\rho_f - s_1) + (s_1 - u_3) + 2(\rho_g - s_1) + d_{P_i}(\Gamma_g(s_2), \Gamma_h(s_2)) + (\rho_h - v_2)$$

$$= (\rho_f - s_1) + (\rho_g - s_1) + (\rho_g - u_2) + d_{P_i}(\Gamma_g(s_2), \Gamma_h(s_2)) + (\rho_h - v_2)$$

$$= d(f,g) + d(g,h).$$

If $s_1 < u_1$ and $j = h_{\Gamma_f}(s_1)$, the chain of inequalities can be modified as follows:

$$\begin{aligned} d(f,h) &= (\rho_f - u_3) + d_{P_i}(\Gamma_f(s_3), \Gamma_h(s_3)) + (\rho_h - v_3) \\ &\leq (\rho_f - u_1) + (u_1 - s_1) + (s_1 - u_3) + 2(\rho_g - v_1) \\ &+ [(v_1 - s_1) - (v_1 - s_1)] + d_{P_i}(\Gamma_g(s_2), \Gamma_h(s_2)) + (\rho_h - v_2) \\ &= (\rho_f - u_1) + d_{P_j}(\Gamma_f(s_1), r_j) + (\rho_g - v_1) + (\rho_g - u_2) - (v_1 - s_1) \\ &+ d_{P_i}(\Gamma_g(s_2), \Gamma_h(s_2)) + (\rho_h - v_2) \\ &\leq (\rho_f - u_1) + d_{P_j}(\Gamma_f(s_1), \Gamma_g(s_1)) + (v_1 - s_1) \\ &- (v_1 - s_1) + (\rho_g - v_1) + d(g,h) \\ &= d(f,g) + d(g,h). \end{aligned}$$

6) $u_1 > u_3 = s_3$. As in case 5), $s_1 \ge u_3$, so $s_1 \ge s_3$. Note that $s_2 \ge s_3$. If $s_1 = u_1$, we also have $s_1 > s_3$ and hence $s_2 = s_3$. Also, $\beta_g(s_2) = \beta_f(s_2) = \beta_f(s_3) \ne \beta_h(s_3) = \beta_h(s_2)$, hence $u_2 = v_2 = s_2$ (we used $s_1 > s_3 = s_2$, $s_3 = u_3$ and $s_3 = s_2$). Thus,

$$d(f,h) = (\rho_f - s_3) + (\rho_h - s_3)$$

$$\leq (\rho_f - s_1) + (s_1 - s_3) + 2(\rho_g - s_1) + (\rho_h - s_2)$$

$$= (\rho_f - s_1) + (\rho_g - s_1) + (\rho_g - s_2) + (\rho_h - s_2)$$

$$= d(f,g) + d(g,h).$$

We are left to deal with the case $s_1 < u_1$, which has two subcases.

6') $s_1 = s_3$. In this case $s_2 = s_3$, for otherwise (i.e., for $s_2 > s_3 = s_1$) we would have $\beta_f(s_3) = \beta_f(s_1) = \beta_g(s_1) = \beta_h(s_1) = \beta_h(s_3)$ and similarly $h_{\Gamma_f}(s_3) = h_{\Gamma_h}(s_3)$, so $s_3 < u_3$ (we used $s_3 = s_1$, $s_1 < u_1$, $s_1 < s_2$ and $s_1 = s_3$). Also, $s_2 = u_2$ as $\beta_g(s_2) = \beta_g(s_1) = \beta_f(s_1) = \beta_f(s_3) \neq \beta_h(s_3) = \beta_h(s_2)$ (we used $s_2 = s_1$, $s_1 < u_1$, $s_1 = s_3$, $s_3 = u_3$ and $s_3 = s_2$).

6" $s_1 > s_3$. Also in this case $s_2 = s_3$, and $s_2 = u_2$ because $\beta_g(s_2) = \beta_g(s_3) = \beta_f(s_3) \neq \beta_h(s_3) = \beta_h(s_2)$.

In both cases 6') and 6'') the following estimate holds:

$$d(f,h) = (\rho_f - s_3) + (\rho_h - s_3)$$

$$\leq (\rho_f - u_1) + d_{P_i}(\Gamma_f(s_1), r_i) + (s_1 - s_3) + 2(\rho_g - v_1) + (\rho_h - s_2)$$

$$\leq (\rho_f - u_1) + d_{P_i}(\Gamma_f(s_1), \Gamma_g(s_1)) + (\rho_g - v_1) + (v_1 - s_1)$$

$$+ (s_1 - s_3) + (\rho_g - v_1) + (\rho_h - s_2)(\rho_f - u_1) + d_{P_i}(\Gamma_f(s_1), \Gamma_g(s_1))$$

$$+ (\rho_g - v_1) + (\rho_g - s_2) + (\rho_h - v_2)$$

$$= d(f,g) + d(g,h).$$

Lemma 3.40. \mathbb{F} *is complete.*

Proof. Note that $d(f,g) \ge |\rho_f - \rho_g|$. Therefore, given a Cauchy sequence f_n we have that $\rho_{f_n} \to \rho$, for some $\rho \ge 0$. If for some $t \in [0, \rho)$ the sequences $\{\Gamma_{f_n}(t)\}$, $\{\beta_{f_n}(t)\}$ (which are defined at least for *n* large enough) is definitively constant, then define $\Gamma_f(t) = \Gamma_{f_n}(t), \beta_f(t) = \beta_{f_n}(t)$ for *n* large. This may not happen for each *t*. However, in this case, it is easily seen that there exists $t_0 < \rho$ such that

- $\{\Gamma_{f_n}(t)\}, \{\beta_{f_n}(t)\}\$ are definitively constant for $t < t_0$,
- $\beta_{f_n}(t)$ is definitively constant for $t \in [t_0, t)$,
- Γ_{f_n} , for *n* large enough, is constant on $[t_0, \rho_{f_n})$, $h_{\Gamma_{f_n}}(t_0)$ is definitively constant (say equal to *i*) and the sequence $\{\Gamma_{f_n}(t_0)\}_{n \ge n_0}$ for n_0 large enough is a Cauchy sequence in P_i .

Using the completeness of the P_i 's a limit for $\{f_n\}$ is easily constructed.

Let us show that \mathbb{F} is geodesic. We will need a notion of restriction of a Pgeodesic Γ to a closed subinterval. For each *i* and any pair of points $q, q' \in P_i$ choose a geodesic $\gamma_{q,q'}$ which connects them. Suppose that Γ has domain $\mathcal{I} = \{I_a\}$, where \mathcal{I} is an almost filling of [0, l]. Consider some $0 \leq x \leq l$. First, we define the domain of $\Gamma|_{[0,x]}$ to be

$$\mathcal{J} = \{J \cap [0, x) : J \in \mathcal{I} \text{ and } J \cap [0, x) \neq \emptyset\}.$$

If $J \in \mathcal{J}$ denote by \hat{J} the only interval in \mathcal{I} such that $J = \hat{J} \cap [0, x)$. Define $\Gamma|_{[0,x]}(J) = \gamma_{r_h, \Gamma(\hat{J})}(l(J))$, where $h = h_{\Gamma}(\hat{J})$.

We can now define, for $f \in \mathbb{F}$, its \mathbb{F} -restriction $f ||_{[0,x)}$ to [0,x), for $0 \le x \le \rho_f$. We set, for $t \in [0,x)$ and in the domain of Γ_f , $\Gamma_f ||_{[0,x)}(t) = \Gamma |_{[0,x]}(t)$ and $\beta_f ||_{[0,x]}(t) = \beta_f(t) \ (\rho_f ||_{[0,x)} = x)$.

We are finally ready to describe a geodesic between $f, g \in \mathbb{F}$. If d(f, g) is given by the formula in case (b), then γ can be easily checked to be a geodesic parametrized by arc length between f and g, where

$$\gamma(t) = \begin{cases} f \|_{[0,\rho_f - t)} & \text{if } 0 \le t \le \rho_f - s, \\ g \|_{[0,2s - \rho_f + t)} & \text{if } \rho_f - s \le t \le (\rho_f - s) + (\rho_g - s). \end{cases}$$

If d(f,g) is given by the formula in case (a), set $\delta = \gamma_{\Gamma_f(s),\Gamma_g(s)}$.

Set $i = h_{\Gamma_f}(s)$, u = u(f, g), v = v(f, g) and $d = d_{P_i}(\Gamma_f(s), \Gamma_g(s))$. The geodesic γ between f and g is given by

$$\gamma(t) = \begin{cases} f \parallel_{[0,\rho_f - t)} & \text{if } 0 \le t \le \rho_f - s - u, \\ f \parallel_{[0,s+t_1)} * f^{\delta(t)} & \text{if } \rho_f - s - u \le t \le \rho_f - s - u + d, \\ g \parallel_{[0,2s+t_2+t_1 - d - \rho_f + t)} & \text{if } \rho_f - s - u + d \le t \le (\rho_f - s) \\ + (\rho_g - s) + d - u - v. \end{cases}$$

We will call the geodesics we just described explicit geodesics.

In order to prove that \mathbb{F} is tree-graded, we have to find a candidate set of pieces. For $i \in I$ denote by $w_i \in W$ the class in W of a P-geodesic Γ with associated almostfilling (of [0, 1]) simply {[0, 1]} with $\Gamma(0) = x$ for some $x \in P_i$, $d(x, r_1) = 1$. If $f, g \in \mathbb{F}$ set $f \leq g$ if their separation moment is ρ_f (it actually is a partial order). Given $f \in \mathbb{F}$, $i \in I$ and $\beta < \alpha(w_i)$, set

$$P(f,i,\beta) = \{g \in \mathbb{F} : f \leq g, \beta_g(\rho_f) = \beta, \text{ and if } f < g, \\ [\Gamma_g^{\rho_f,\rho_g}] = w_i, [\rho_f,\rho_g) \in \mathcal{I}_g\}.$$

Each $P(f, i, \beta)$ is easily seen to be isometric to P_i (the isometry $P_i \rightarrow P(f, i, \beta)$ is given by $x \mapsto f * f^{x,\beta}$). Let \mathcal{P} be the set of all $P(f, i, \beta)$'s. We want to show that \mathbb{F} is tree-graded with respect to \mathcal{P} . We will use the characterization of tree-graded spaces given by Theorem 2.16. More precisely, we will use the version stated in Remark 2.17.

First, notice that each $P \in \mathcal{P}$ is geodesic and complete, being isometric to some P_i . In particular, they are closed in \mathbb{F} .

Also, it is readily checked that each non-trivial explicit geodesic intersects a piece in a non-trivial subgeodesic. So, each geodesic triangle whose sides are explicit geodesics which intersect each $P \in \mathcal{P}$ in at most one point is trivial. Therefore, if we find a projection system for \mathcal{P} , by Lemma 2.18 we are done.

Consider $P = P(f, i, \beta) \in \mathcal{P}$. For each $r \in \mathbb{F}$ define $\pi_P(r)$ to be the first point on the explicit geodesic between r and f. It is obvious that (P1') holds.

The following claim can be checked directly.

Claim. Suppose that $\pi_P(r_1) \neq \pi_P(r_2)$. Then the explicit geodesic from r_1 to r_2 is obtained concatenating the explicit geodesics from r_1 to $\pi_P(r_1)$, from $\pi_P(r_1)$ to $\pi_P(r_2)$ and from $\pi_P(r_2)$ to r_2 .

In particular, $d(r_1, r_2) = d(r_1, \pi_P(r_1)) + d(\pi_P(r_1), \pi_P(r_2)) + d(\pi_P(r_2), r_2)$, that is, (P2').

To conclude the proof that \mathbb{F} is tree-graded, we are left to show (T_1) . Consider $P(f, i, \beta)$ and $P(g, j, \delta)$. First of all $P(f, i, \beta)$ can have a point in common with $P(g, j, \delta)$ only if $f \leq g$ or vice versa. Let us consider the case f < g (the case g < f is of course analogous, so we will be left to deal only with the case f = g). If $h \in P(f, i, \beta) \cap P(g, j, \delta)$ (in particular $h \geq g > f$), then \mathcal{I}_h contains $[\rho_f, \rho_h)$. If we also had h > g, \mathcal{I}_h would contain $[\rho_g, \rho_h)$, which is different from $[\rho_f, \rho_h)$, but their intersection is not empty, a contradiction. This readily implies that if $f \in P(f, i, \beta) \cap P(g, j, \delta)$, then $\rho_h = \rho_g$, and so we must have h = g.

In the case f = g, it is clear that if $i \neq j$ or $\beta \neq \delta$ then f = g is the only point in $P(f, i, \beta) \cap P(g, j, \delta)$.

In order to prove the theorem, we are left to show that for each $w \in W$, $F_{\mathbb{F},p}^{-1}(w)$ has cardinality $\alpha(w)$, for some choice of charts. Choose the identification $(P_i, r_i) \rightarrow (P(f, i, \beta), f)$ to be $x \mapsto f * f^{x,\beta}$. Recall that we fixed for each *i* and $x \in P_i$ different from r_i an isometry ϕ_x of P_i which maps *x* to r_i . These isometries, together with the already fixed identifications, yield a choice of charts, which is the one we will use.

Note that each equivalence class in $\mathcal{Y}(\mathbb{F}, p)$ has a representative which is an explicit geodesic, by the fact that there is an explicit geodesic connecting each pair of points in \mathbb{F} (clearly, geodesics with the same endpoints have the same initial pattern). Therefore, in what follows we are allowed to restrict to considering explicit geodesics only.

Consider any $f \in \mathbb{F}$. There can be 4 kinds of explicit geodesics starting from f, which are listed below.

- (1) Explicit geodesics γ such that, for each $\varepsilon > 0$ in the domain of γ , $f < \gamma(\varepsilon)$ and $\beta_{\gamma(\varepsilon)}$ is not constant in a neighborhood of ρ_f . In this case $F_{\mathbb{F},f}([\gamma]) = [\Gamma_{\gamma(\varepsilon)}^{\rho_f,\rho_f+\varepsilon}]$ for ε as above.
- (2) Explicit geodesics as in point (1) except that $\beta_{\gamma(\varepsilon)}$ is constant in a neighborhood of ρ_f . There is one element in each $F_{\mathbb{F},f}^{-1}(w)$ which can be represented by this kind of explicit geodesics.
- (3) Explicit geodesics γ such that $F_{\mathbb{F},f}([\gamma]) = [-\Gamma_f]$.
- (4) Other explicit geodesics: in this case there exists an interval in \mathcal{I}_f of the kind $[t, \rho_f)$ such that $F_{\mathbb{F},f}([\gamma]) = [-\Gamma_f]$, for any $x \in P_i, x \neq r_i$, where $i = h_{\Gamma_f}(t)$.

Let G be the set of equivalence classes in $\mathcal{Y}(\mathbb{F}, f)$ of explicit geodesics of type (1). We claim that for each $w \in \mathcal{W}$, the map $H_w : (F_{\mathbb{F},f}^{-1}(w) \cap G) \mapsto \alpha(w)$ given by $[\gamma] \mapsto \beta_{\gamma(\varepsilon)}(\rho_f)$ (for any $\varepsilon > 0$ in the domain of γ) is injective and the image differs from $\alpha(w)$ for at most one element.

If this holds, as geodesics of type (2)–(4) accounts for finitely many elements in each $F_{\mathbb{F},f}^{-1}(w)$ and each $\alpha(w)$ is infinite, we are done.

We are left to prove the claim. Let us prove "almost-surjectivity" first. Suppose that $w = [\Gamma]$ for some P-geodesic Γ with domain the almost filling of [0, l] \mathcal{I} . For each $\kappa < \alpha(w)$, there exists an element $g(\kappa)$ of \mathbb{F} such that

- $\rho_{g(\kappa)} = l$,
- $\mathcal{I}_{g(\kappa)} = \mathcal{I},$
- $\Gamma_{g(\kappa)} = \Gamma$,
- $\beta_{g(\kappa)}$ is constantly k.

We have that the explicit geodesic γ from f to $f * g(\kappa)$ is of type (1) for each but at most one value of k. As clearly γ is contained in $F_{\mathbb{F},f}^{-1}(w)$ and $H_w(\gamma) = \kappa$, "almost-surjectivity" is proved.

For what regards injectivity, if $H_w(\gamma_1) = H_w(\gamma_2)$, by the fact that the function β_* 's are piecewise constant from the right there exists $\varepsilon > 0$ such that $\beta_{\gamma_1(\varepsilon)} = \beta_{\gamma_2(\varepsilon)}$. It is easily seen that γ_1 and γ_2 have the same pattern until ε .

3.7. A tree-graded structure on the homogeneous real tree of valency 2^{\aleph_0} . Consider a homogeneous real tree T of valency 2^{\aleph_0} , and fix a base point $p \in T$. Let W be the set of the equivalence classes of the P-geodesics with range $\{(T, p)\}$ and set $\alpha(w) = 2^{\aleph_0}$ for each $w \in W$. A direct application of Theorem 3.36 shows that a universal tree-graded space $\mathbb{F} = \mathbb{F}_{\alpha}$ exists.

Proposition 3.41. \mathbb{F} *is isometric to T*.

Proof. Being tree-graded with respect to real trees, \mathbb{F} is a real tree. We only need to determine the valency at each $q \in \mathbb{F}$.

It is not difficult to show that $|\mathcal{W}| = 2^{\aleph_0}$ (this is also the cardinality of the set of the P-geodesics with range $\{(T, p)\}$). So, considering the partition of $\mathcal{Y}(\mathbb{F}, q)$ given by $\{F_{\mathbb{F},q}^{-1}(w)\}_{w \in \mathcal{W}}$, we get $|\mathcal{Y}(\mathbb{F}, q)| = 2^{\aleph_0} \times 2^{\aleph_0}$. Consider two geodesics γ_1, γ_2 starting at q, and suppose that $\gamma_1 \cap \gamma_2 = \{q\}$. It is clear that either γ_1 and γ_2 represent different elements of $\mathcal{Y}(\mathbb{F}, q)$ or they belong to the same piece. In particular we have that the valency of \mathbb{F} at q is at most $2^{\aleph_0} \times 2^{\aleph_0} = 2^{\aleph_0}$, and so that it is exactly 2^{\aleph_0} .

Therefore the valency of \mathbb{F} at each $q \in \mathbb{F}$ is 2^{\aleph_0} . In particular, \mathbb{F} is isometric to T.

We are finally ready to prove Theorem 3.3 and Theorem 0.2. The proof is the same for both results.

Proof of Theorem 3.3 *and Theorem* 0.2. The proposition above together with Proposition 3.29 implies that $C(G_0, v_0)$ and $C(G_1, v_1)$ can be given a tree-graded structure such that for each $p \in C(G_0, v_0), q \in C(G_1, v_1)$ (there exists a choice of charts such that) $H_{C(G_0, v_0), p}$ and $H_{C(G_1, v_1), q}$ are constant functions with value 2^{\aleph_0} .

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Consider now a family of homogeneous geodesic representatives $\{P_i\}$ for the classes of bilipschitz equivalence of the pieces of $C(G_0, \nu_0)$ and $C(G_1, \nu_1)$. Let \mathcal{X} be the set of the equivalence classes of the P-geodesics with range $\{(P_i, r_i)\}$, for some choice of $r_i \in P_i$, and set $\beta(x) = 2^{\aleph_0}$ for each $x \in \mathcal{X}$. Applying Theorem 3.36 we have that a universal tree-graded space $\mathbb{G} = \mathbb{F}_{\beta}$ exists.

An easy application of Theorem 3.34 gives that both $C(G_0, \nu_0)$ and $C(G_1, \nu_1)$ are bilipschitz equivalent to \mathbb{G} , and therefore they are bilipschitz equivalent.

Remark 3.42. Notice that in the proof above we only used two facts about $C(G_0, v_0)$ and $C(G_1, v_1)$, that is, that we can apply Proposition 3.29 to them and that the sets of the bilipschitz equivalence classes of their pieces coincide. In particular, the proof works also if, in the definition of being comparable, we allow the asymptotic cones of G_0 and those of G_1 to be constructed using different ultrafilters.

Remark 3.43. In view of the tree-graded structure constructed in the previous proof, an asymptotic cone of a relatively hyperbolic group is (isometric to a) universal tree-graded space. In particular, the proof of Theorem 3.36 provides an "explicit" description of such asymptotic cones when the pieces are known.

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