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On ramified covers of the projective plane II: Generalizing Segre's theory

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Abstract. The classical Segre theory gives a necessary and sufficient condition for a plane curve to be a branch curve of a (generic) projection of a smooth surface in \mathbb{P}^3 . We generalize this result for smooth surfaces in a projective space of any dimension in the following way: given two plane curves, B and E , we give a necessary and sufficient condition for B to be the branch curve of a surface X in \mathbb{P}^N and E to be the image of the double curve of a \mathbb{P}^3 -model of X.

In the classical Segre theory, a plane curve B is a branch curve of a smooth surface in \mathbb{P}^3 iff its 0-cycle of singularities is special with respect to a linear system of plane curves of particular degree. Here we prove that B is a branch curve of a surface in \mathbb{P}^N iff (part of) the cycle of singularities of the union of B and E is special with respect to the linear system of plane curves of a particular low degree. In particular, given just a curve B , we provide some necessary conditions for B to be a branch curve of a smooth surface in \mathbb{P}^N .

1. Introduction

Let X be a non-singular algebraic surface of degree ν in \mathbb{P}^N (we work over an algebraically closed field of characteristic 0). Choosing a generic linear subspace W of codimension 3 in \mathbb{P}^N and considering the projection of \mathbb{P}^N to a plane with center W, we get a ramified cover $\pi : X \to \mathbb{P}^2$. Let B be the branch curve of π ; it is known to be an irreducible nodal-cuspidal curve. Such branch curves are special among all nodal-cuspidal curves with the same type of singularities; for example, in the simplest and the most well-known case of a cubic surface in \mathbb{P}^3 , the branch curve B, which is a plane sextic with six cusps, is special since all of its six cusps lie on a conic (see Segre and Zariski [\[24\]](#page-25-1), [\[27\]](#page-25-2)). Segre studied the question of whether the singularities of B form a special configuration of points in the plane for a surface of any degree in \mathbb{P}^3 , as in the case of a surface of degree 3, and found a generalization of this statement. Moreover, he proved that this property uniquely characterizes branch curves and that one can reconstruct the surface from its branch curve.

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More specifically, let S be a smooth surface in \mathbb{P}^3 ; its branch curve is known to be of degree $v(v-1)$, have $c(v) = v(v-1)(v-2)$ cusps and $n(v) = \frac{1}{2}v(v-1)(v-2)(v-3)$ nodes. Let $a(v) = (v - 1)(v - 2)$. Segre proved that *a nodal-cuspidal plane curve B of degree* ν(ν − 1) *with* n(ν) *nodes and* c(ν) *cusps is a branch curve of a generic projection of a smooth surface of degree* $\nu \geq 3$ *in* \mathbb{P}^3 *if and only if there are two adjoint curves of degrees* $a(v)$ *and* $a(v) + 1$ *passing through the* 0-*cycle of singularities of B and having separated tangents and these singularities.* In particular, the 0-cycle of singularities of B is special. (See [\[24\]](#page-25-1) for Segre's original proof, but also [\[5\]](#page-24-0), [\[19\]](#page-25-3) and [\[8\]](#page-24-1) for recent surveys.)

In light of this necessary and sufficient condition for a curve to be a branch curve of a smooth surface in \mathbb{P}^3 , it was natural for Chisini [\[3\]](#page-24-2) to conjecture that a generic ramified cover of the plane \mathbb{P}^2 of degree at least 5 is uniquely determined by its branch curve. This conjecture was proved by Kulikov (in [\[17\]](#page-25-4) for ramified covers of degree at least 11, and then in [\[20\]](#page-25-5) for generic linear projections of surfaces other than Veronese), but his proof is not constructive.

Given a smooth surface X in \mathbb{P}^N , $N > 3$, one can decompose any projection π : $X \to \mathbb{P}^2$ as a composition of a generic projection $X \to \mathbb{P}^3$ and a projection $\mathbb{P}^3 \to \mathbb{P}^2$. Let S be the image of X in \mathbb{P}^3 . It is known that S is a surface with ordinary singularities, i.e., it has a double curve as its singular locus. (Note that the class of surfaces with ordinary singularities in \mathbb{P}^3 is broader than the class of images of generic linear projections of smooth surfaces in \mathbb{P}^N ; in particular, if E has multiple components then X is not a generic linear projection of a smooth surface.)

One can check that the branch curve of the projection of S to \mathbb{P}^2 is a union of the branch curve B of the projection $X \to \mathbb{P}^2$ and the image 2E of the double curve $2E^*$ with the corresponding double (scheme) structure. (We sometimes call B a *pure branch curve* for the projection of S to \mathbb{P}^2 .)

One possible direction toward generalizing Segre's theory for the smooth surface X in \mathbb{P}^N is to consider its image S in \mathbb{P}^3 and ask the same questions for the total branch curve, i.e., to study the configuration of the singularities of the branch curve $B \cup 2E$ on the plane. Slightly more generally, we can consider any surface S in \mathbb{P}^3 with ordinary singularities (not necessarily a projection of a surface from \mathbb{P}^N) projected further to \mathbb{P}^2 , and try to generalize Segre's theory to this class of surfaces.

We ask the following questions: What are the special properties of the pure branch curve B, or the total branch curve B \cup 2E? Can one construct a singular surface S in \mathbb{P}^3 , given two plane curves, a nodal-cuspidal curve B and a double curve 2E, where E possibly has triple points and nodes as singularities, and two adjoint curves (to $B \cup E$) such that the total branch curve of S is $B \cup 2E$?

In this paper we give answers to these questions. We prove that the branch curve \hat{B} has two adjoint curves, which also pass through some of the singularities of $B \cup E$, such that one can (re)construct a surface S with ordinary singularities given B , E , and these two adjoint curves. Thus, there is a 0-cycle of points on B consisting of cusps and the nodes of B and two other special sets of points (called the "vertical" points and the "new" intersection points of B and E), which is a special 0-cycle on the plane.

As a consequence, we have a constructive proof of the analogue of Chisini's conjecture for surfaces in \mathbb{P}^3 with ordinary singularities. That is, any such surface in \mathbb{P}^3 is determined uniquely and constructively by its *total* branch curve in \mathbb{P}^2 .

This paper is organized as follows. In Section [2](#page-2-0) we give the necessary background regarding surfaces in \mathbb{P}^3 \mathbb{P}^3 . Section 3 proves that if B is the pure branch curve of a singular surface $S \subseteq \mathbb{P}^3$, then B (respectively, $B \cup E$) has two adjoint curves, and in particular, there is a special 0-cycle on B that consists of the singularities of B (and the intersection of B and E). In Section [4](#page-15-0) we prove the converse, i.e., the sufficiency of these two adjoint curves to construct a surface S with a given (total) branch curve $B \cup 2E$. We conclude the paper with a few examples in Section [5.](#page-22-0)

2. Surfaces in \mathbb{P}^3

Let X be a smooth projective surface in \mathbb{P}^N . Projecting X to \mathbb{P}^2 by a generic linear projection, we know that the branch curve B is a nodal-cuspidal curve (see [\[4\]](#page-24-3) for a modern proof). However, X can be first projected onto \mathbb{P}^3 , where its image has a double curve. In this section we review the relations between the ramification curve, the double curve and their images in \mathbb{P}^2 .

It is classical that any smooth projective surface X can be embedded into \mathbb{P}^5 as a smooth surface. However, when projecting generically from \mathbb{P}^5 to \mathbb{P}^3 , the image $S \subset \mathbb{P}^3$ of X is a singular surface with so-called "ordinary singularities" (this is, of course, also true for smooth surfaces in \mathbb{P}^4). The singular locus of S is well known (see, e.g., [\[12\]](#page-25-6)): it consists of a double curve whose only singularities are some triple and pinch points. Explicitly, in terms of a local holomorphic coordinate system (x, y, z) , a local model of the surface S is as follows:

- in a neighborhood of a smooth point of the double curve, $S = \{xy = 0\}$;
- in a neighborhood of a triple point, $S = \{xyz = 0\}$;
- in a neighborhood of a pinch point, $S = \{x^2 yz^2 = 0\}.$

Notation 2.1. Scheme-theoretically, the double curve F^* of S is given as the annihilator of the pushforward of the sheaf $\Omega^1_{X/S}$ with respect to the map $f : X \to S$. The reduced closed subscheme structure of the double curve of S, which is denoted by E^* , is the support of F^* .

Remark 2.2. In $A_1(S)$, we have $[F^*] = 2[E^*]$, where $[F^*]$ is the Weil divisor associated with the Cartier divisor $2[E^*]$.

It is known that E^* is irreducible unless $X = V_2$, the Veronese embedding of \mathbb{P}^2 in \mathbb{P}^5 , where in this case the (reduced) double curve E^* of $f(X) = S$ is a union of three non-coplanar lines meeting in one point. See [\[21,](#page-25-7) Theorem 3] and [\[6\]](#page-24-4). Note, however, that there are surfaces in \mathbb{P}^3 with ordinary singularities such that their double curve is reducible, i.e., they are not generic projections of a smooth surface in \mathbb{P}^N , $N > 3$. For example, there is a degree 4 surface in \mathbb{P}^3 with two skew lines as a double curve (see e.g. [\[12,](#page-25-6) p. 630]).

Assume now that we are given a degree ν surface $S = \{f = 0\} \subset \mathbb{P}^3 = \mathbb{P}(V)$ with ordinary singularities and a point O not on S . We want to emphasize that S is not necessarily the projection of a smooth surface, and its double curve may be reducible. Consider the projection map $\pi : S \to \mathbb{P}(V/I_O) \simeq \mathbb{P}^2$ (where I_O is the line in V corresponding to the point O in $\mathbb{P}(V)$, and define the polar surface of S with respect to O as

$$
S'_{O} = \left\{ \sum O_i \frac{\partial f}{\partial x_i} = 0 \right\}.
$$

The ramification curve B_{Total}^* of the projection is defined as the scheme-theoretic intersection of S and the polar surface $S'_{\overline{O}}$. Note that $B_{\text{Total}}^* = S \cap S'_{\overline{O}}$ is the annihilator of the sheaf Ω_{S/\mathbb{P}^2} .

One can now see that B_{Total}^* can be decomposed (scheme-theoretically and in $Z_1(S)$) as

$$
[B^*_{\text{Total}}] = [B^*] + [F^*].
$$

Note that the set-theoretic intersection B^* of S'_0 with the smooth locus of S is the set of smooth points p on S such that the tangent plane $T_p(S)$ contains O. Scheme-theoretically, B^{*} is the support of the kernel sheaf of the canonical map $\Omega_{S/\mathbb{P}^2}^1 \to i_*i^*\Omega_{S/\mathbb{P}^2}^1 \to 0$, where *i* is the embedding of F^* into S (where this map is associated to the left adjointness of i_*). For a different scheme-theoretic description of E^* and B^* , see [\[22,](#page-25-8) Section 2].

Remark 2.3. For a smooth surface $X \subset \mathbb{P}^N$, $N \geq 3$, any generic projection $X \subset$ $\mathbb{P}^N \to \mathbb{P}^2$ can be factored as a composition of projections $X \subset \mathbb{P}^N \to \mathbb{P}^3 \to \mathbb{P}^2$ such that, letting $S = \text{Im}(X) \subset \mathbb{P}^3$, the projection $S \to \mathbb{P}^2$ is also generic. If we first project X to \mathbb{P}^3 , and then from \mathbb{P}^3 to \mathbb{P}^2 , we get an extra component of the branch curve: if $B^* \subset \mathbb{P}^2$ is the ramification curve of the direct projection $X \subset \mathbb{P}^N \to \mathbb{P}^2$ and $F^* \subset \mathbb{P}^3$ is the double curve, then, in $Z_1(\mathbb{P}^2)$,

$$
[B_{\text{Total}}] = [B] + [F],
$$

where B_{Total} , B and F are the scheme-theoretic images of B_{Total}^* , B^* and F^* , respectively. Of course, the direct projection of X from \mathbb{P}^N to \mathbb{P}^2 "does not know" about the double curve of S in \mathbb{P}^3 . As before, in terms of cycle classes, group $A_1(\mathbb{P}^2)$, we have $[F] = 2[E]$.

From now on, let S be a surface in \mathbb{P}^3 with ordinary singularities.

Notation 2.4. Let *u* be the number of components of E^* and let E_i^* be these components. Set

 $e = \deg E^*$, $e_i = \deg E_i^*$, $v = \deg S$, $d = \deg B^* = v(v-1) - 2e = \deg B^* - 2 \deg E^*$.

Remark 2.5. A generic hyperplane section $S \cap H$ of S is a plane curve of degree ν with e nodes at the points of $E^* \cap H$, so

$$
0\leq e\leq \frac{(\nu-1)(\nu-2)}{2},
$$

since the number of nodes of a plane curve cannot exceed its arithmetic genus. It follows that the pair (v, d) satisfies the relation

$$
2(\nu - 1) \le d \le \nu(\nu - 1).
$$

Note that for a given d there are only a finite number of possible values of ν such that a plane curve C of degree d can be a pure branch curve of a degree v surface in \mathbb{P}^3 with ordinary singularities. We discussed the geography of this domain in our previous paper [\[8\]](#page-24-1).

Definition 2.6. We define

$$
\mathcal{Q}^*_{\text{Total}} = \mathit{B}^*_{\text{Total}} \cap \mathit{S_O''}
$$

to be the scheme-theoretic intersection of B_{Total}^* and the second polar surface S_0'' , i.e., the intersection of S, S'_O and S'_O. For a smooth surface, the points Q_{Total}^* are the preimages of the cusps of the branch curve B (see e.g. [\[25\]](#page-25-9)). However, for a singular surface S , not all the points of Q_{Total}^* form cusps on the branch curve. (See Lemma [2.9.](#page-5-0))

We denote by Q^* the smooth points of B^* such that their images $\pi(Q^*)$ are the cusps of B.

Notation 2.7. Denote by $V_i^* \in E_i^*$ the points such that the tangent plane to S at V_i^* contains the center of projection \dot{O} . We call these points *vertical points*, as we think of O as being "high-above" (or *points of immersion*, in [\[25,](#page-25-9) Chapter VII, Section 3]). Let $V^* = \bigcup V_i^*.$

Denote by T^* the set of triple points of $E^* = \bigcup E_i^*$, and by t the number of these points. Let $\bigcup_{j=1}^{t} \tau_{ij}^{*}$ be the set of triple points of E_i^* (indexed by j) with their multiplici-ties on the component E_i (see [\[12,](#page-25-6) p. 622]). Note that $|\sum_i \tau_{ij}^*| = 3$ and $|\sum_{i,j} \tau_{ij}^*| = 3t$. We introduce this notation as we have to take into account the fact that there can be different types of spatial triple points, arising from the fact that a triple point can be composed from several components of the branch curve. In the figure below we picture the different arrangements, with the corresponding τ 's.

Let Pinch^{*} be the set of pinch points of E_i^* and let p_i be the number of these points. Denote Pinch^{*} = \bigcup_i Pinch^{*} and $p = \sum_i p_i$.

For any curve $\overline{C} \subset \mathbb{P}^N$ let h_C be the Cartier class of the hyperplane section of C.

Remark 2.8. Note that the number p of pinch points is always even (see [\[10\]](#page-25-10) or [\[21,](#page-25-7) Theorem 3(4)]) and it is 0 only when S is a smooth surface in \mathbb{P}^3 .

The following lemma is proved in [\[25,](#page-25-9) Chapter IX, Sections 3.1, 3.2].

Lemma 2.9. (1) $Q_{\text{Total}}^* = S_0'' \cap B_{\text{Total}}^*$ can be decomposed as

$$
[Q^*_{\text{Total}}] = [Q^*] + [S_O'' \cap F^*].
$$

Note that the images of points of $S''_O \cap E^*$ *under the projection are smooth points of* B*.*

(2) Points in $B^* \cap E^*$ do not project to nodes or cusps of the branch curve, i.e., their *images are smooth points on B. Moreover, scheme-theoretically (or in* $Z_0(B^*)$ *, the group of* 0*-cycles*)*,*

$$
B^* \cap E^* = \text{Pinch}^* \cup V^*, \quad B^* \cap E_i^* = \text{Pinch}_i^* \cup V_i^*.
$$

(3) In $Z_0(E^*)$, $S''_0 \cap E^*$ can be decomposed as

$$
[S_O'' \cap E^*] = [V^*] + 3[T^*],
$$

and in $Z_0(E_i^*)$ the equation is

$$
[S_O'' \cap E_i^*] = [V_i^*] + \sum_j [\tau_{ij}^*].
$$

In $Z_0(B^*)$, $S''_O \cap B^*$ *can be decomposed as*

$$
[S_O'' \cap B^*] = [V^*] + [Q^*].
$$

We cite here from [\[12,](#page-25-6) p. 628] the computation of the number of pinch points on E_i^* .

Lemma 2.10.

$$
p_i = 2(\nu - 4)e_i - 2\sum_j |\tau_{ij}| - 4(g_i - 1),
$$

\n
$$
p = 2(\nu - 4)e - 6t - 4(g - u),
$$
\n(2.1)

where $g = \sum g_i$ *is the sum of the arithmetic genera of* E_i^* *, and u is the number of components of* E ∗ *.*

Proof (see [\[12,](#page-25-6) p. 628]). By Riemann–Hurwitz and adjunction on the blow up of S with respect to the triple points and the double curve. \Box

Remark 2.11. In the case when S is a generic projection of a smooth surface, if S is not the image of the Veronese surface V_2 , then $u = 1$. When S is the image of V_2 , $u = 3$, $p = 6$ and on each double line there are two pinch points (|Pinch_i| = 2, 1 ≤ i ≤ 3; see e.g. [\[25\]](#page-25-9)).

Remark 2.12. In [\[12,](#page-25-6) p. 624] the Chern classes c_1^2 , c_2 of S are expressed in terms of v , e, t and $g - u$:

$$
c_1^2 = v(v - 4)^2 - 5ve + 24e + 4(g - u) + 9t,
$$

\n
$$
c_2 = v^2(v - 4) + 6v + 24e - 7ve + 8(g - u) + 15t.
$$

3. From ramification curves to adjoint curves

3.1. The pure branch curve

When projecting a surface $S \subset \mathbb{P}^3 = \mathbb{P}(V)$ to the plane $\Pi = \mathbb{P}(V/\ell_o)$ from a *generic* point $O \in \mathbb{P}^3$, $O \notin S$ (O is the projectivization of a 1-dimensional space $\ell_O \subset V$), the (pure) ramification curve B^* and the reduced double curve E^* project to two singular plane curves B and E, respectively. Denote the projection map by $\pi : S \to \Pi$.

The singular points of B are nodes, denoted by P , and cusps, denoted by Q , while the curve E has as singularities nodes (arising from the projection E^* to E), denoted by Node, and triple points, denoted by T .

We recall (from Lemma [2.9\)](#page-5-0) that B^* and E_i^* intersect at the pinch points Pinch^{*}_i and at the vertical points V_i^* .

Let Pinch_i (resp. V_i) be the image of Pinch^{*}_i (resp. V_i^*) under the projection $S \to \Pi$. Thus, set-theoretically, B and E_i intersect at the images of the pinch points Pinch_i and at the vertical points V_i , and also potentially at some new points N_i :

$$
B \cap E_i = \text{Pinch}_i \cup V_i \cup N_i.
$$

This N_i is the intersection points of Π with bisecants to B^* passing through O and intersecting both B^* and E_i^* (at two *distinct* points).

Let Node_i be the set of nodes of E_i that do not coincide with any of the triple points of E. Note that the sum of the lengths of 0-cycles $\#(\text{Node}_i)$ may be strictly less than $#(Node)$, as some nodes of E may arise from lines through O intersecting two different components of E^* , E_i^* and E_j^* .

Fig. 2. The ramification curve and the branch curve.

We now prove some relations in the Chow groups $A_0(B)$ and $A_0(E_i)$.

Lemma 3.1.

$$
[Pinch_i] + 2[V_i] + [N_i] = e_i h_B \qquad in \ A_0(B), \tag{3.1}
$$

$$
[\text{Pinch}_i] + 2[V_i] + [N_i] = (v(v-1) - 2e)h_{E_i} \quad \text{in } A_0(E_i). \tag{3.2}
$$

Proof. This is easily verified by a local computation for $B \cap E_i$. The curves B and E_i intersect transversely at Pinch_i and N_i , and are simply tangent at the vertical points. \square Note that the version of this equation on E (and all the other equations that follow) is induced by summing over i .

Definition 3.2. Let $C = \{f = 0\}$ be a reduced plane curve contained in the plane Π . Choose a generic point $O' \in \Pi$, $O' \notin C$. The *polar curve* C' is defined as

$$
C'_{O'} = \text{Pol}_{O'}(C) \doteq \left\{ \sum O'_i \frac{\partial f}{\partial x_i} = 0 \right\}.
$$

Note that $C \cap C' = R_C \cup \text{Sing}(C)$, where R_C is the scheme of non-singular points $p \in C$ such that the tangent line to C at p contains O' . The set R_C depends on O' , but the class $[R_C] \in A_0(C)$ is well defined. It follows that, scheme-theoretically,

$$
[R_C] = [C \cap C'] - [Sing(C)].
$$

Lemma 3.3. We have the following equalities in $A_0(B)$:

$$
[V] + [Q] = (\nu - 2)h_B,
$$
\n(3.3)

$$
2[P] + 3[Q] + [R_B] = (\nu(\nu - 1) - 2e - 1)h_B = (d - 1)h_B,
$$
\n(3.4)

$$
[R_B] = (\nu - 1)h_B - [V] - 2[\text{Pinch}]. \tag{3.5}
$$

Proof. [\(3.3\)](#page-7-0) follows from projecting the intersection $S'' \cap B^*$ to \mathbb{P}^2 (see Lemma [2.9\(](#page-5-0)3)), (3.4) follows by applying Definition [3.2](#page-7-1) to B, and (3.5) is a new computation, follows from studying $B^* \cap S'_{O'}$. The multiplicities are found by a local computation, e.g., in [\[25,](#page-25-9) Chapter IX] or $[22]$.

Subtract [\(3.5\)](#page-7-0) from [\(3.4\)](#page-7-0):

$$
2[P] + 3[Q] - [V] - 2[\text{Pinch}] = (\nu(\nu - 2) - 2e)h_B.
$$

From [\(3.3\)](#page-7-0) we get $[Q] = (\nu - 2)h_B - [V]$. Thus,

$$
2[P] + 2[Q] - 2[V] - 2[\text{Pinch}] = ((\nu - 1)(\nu - 2) - 2e)h_B.
$$

From the first equation in Lemma [3.1](#page-6-1) we see that (by multiplying by 2) $2e \cdot h_B$ = $2[Pinch] + 2[V] + 2[V] + 2[N]$ or $2[Pinch] + 2[V] = 2eh_B - 2[V] - 2[N]$. Substitute this in the equation above to get

$$
2[P] + 2[Q] + 2[V] + 2[N] = ((\nu - 1)(\nu - 2))h_B.
$$
\n(3.6)

3.2. Adjoint curves to the pure branch curve and to the double curve

We now ask whether the reduced total branch curve $B \cup E$ has naturally defined adjoint curves.

Definition 3.4. Given a point O' as above, let $[e_i^{\vee}] \in A_0(E_i)$ denote the class of *smooth* points $p \in E_i$ such that the line pO' is tangent to E_i . This is the class corresponding to R_{E_i} in Definition [3.2.](#page-7-1)

We recall that Node is the set of nodes of E . We have the following equalities in the corresponding Chow groups:

Lemma 3.5.

$$
[V] + 3[T] = (v - 2)h_E,
$$
\n(3.7)
\n
$$
V_1 + \sum_{r=1}^{r} [r - (v - 2)h_r]
$$
\n(3.8)

$$
[V_i] + \sum_j [\tau_{ij}] = (\nu - 2)h_{E_i}, \qquad (3.8)
$$

$$
[e^{\vee}] + 2[\text{Node}] + 6[T] = (e - 1)h_E,
$$
\n(3.9)

$$
[e_i^{\vee}] + \sum [\text{Node}]|_{E_i} + 2 \sum_j [\tau_{ij}] = (e - 1)h_{E_i},
$$
\n(3.10)

$$
[e_i^{\vee}] + 2[\text{Node}_i] + 2 \sum_{j, \tau_{ij} > 1}^{\cdot} [\tau_{ij}] = (e_i - 1)h_{E_i}.
$$
 (3.11)

Proof. The first pair of equations is the projection of $[S'' \cap E^*]$, $[S'' \cap E_i^*]$ (see Lemma [2.9\)](#page-5-0). The next three equations come from $E \cap E'$, $E_i \cap E'$ and $E_i \cap E'_i$. The contract \Box

Lemma 3.6.

$$
[\text{Pinch}_i] = 2[V_i] - 2[e_i^{\vee}], \quad [\text{Pinch}] = 2[V] - 2[e^{\vee}]. \tag{3.12}
$$

Proof. Consider the locus in $Gr(2, 3) \times Gr(2, 3) \times Gr(1, 3)$ consisting of triples (H, H', L) such that the line L is contained in both planes. Then V_i is the pullback to this locus of the class σ_1 in the first Grassmannian of planes, consisting of planes H containing a given specified point P, e_i^{\vee} is the pullback of the class σ_1 of lines L meeting a given line L', and Pinch_i is the pullback of the diagonal in Gr(2, 3) × Gr(2, 3) where the planes H and H' coincide. We can thus see that $2e_i^{\overline{V}} = \text{Pinch}_i + 2V_i$: the line L meets one of two lines L' and L'' if and only if L passes through one of the points where L' or L'' meets H'. That is, either $H = H'$ (and the class (H, H', L) is in Pinch_i), or H contains one of these two points (and the class (H, H', L) is in $2V_i$).

Remark 3.7. This lemma implies that every component of E contains vertical points. If E_i is a component of E with $e_i > 1$, then $[e_i^{\vee}] = [e^{\vee}]|_{E_i} > 0$, so $2[V_i] = 2[V]|_{E_i} =$ $[Pinch_i] + 2[e_i^{\vee}] > 0$. If E_i is a line with no vertical points, then this means that no lines from the projection point O to E_i are tangent to the surface S. But the class of $[V_i]$ is invariant under the choice of generic O, so no lines from almost any point to E_i are tangent to S. Hence S must contain a plane containing E_i , which contradicts the hypothesis that S is irreducible. Hence, if E_i is a line, then it must still contain some V_i. Therefore, $B^* \cup F^*$ is connected, since every component of F^* contains some points of V^* , but V^* are intersection points of F^* with B^* . Since B^* is irreducible and every component of F^* meets B^* , $B^* \cup F^*$ is connected.

Remark 3.8. Note that we now have equations for all the distinguished classes on $B \cup F$, i.e., for [T], [Node], [Pinch], [V], [N], [Q], [P], in terms of the classes h_E , h_B , e^{\vee} and K_E :

$$
6[T] = 2(\nu - 2)h_E - ([\text{Pinch}] + 2[e^{\vee}]), \tag{3.13}
$$

$$
[Node] = \frac{1}{2}(e - 1)h_E - [e^{\vee}] - 6[T],
$$
\n(3.14)

 $[V] = \frac{1}{2}([Pinch] + 2[e^{\sqrt{2}}]$ (3.15)

 $[N] = eh_B - 2[V] - [Pinch],$ (3.16)

$$
[Q] = (\nu - 2)h_B - [V], \tag{3.17}
$$

$$
[P] = \frac{1}{2}(\nu - 1)(\nu - 2)h_B - [Q] - [V] - [N].
$$
\n(3.18)

Local versions also exist, of course, but are more cumbersome to write down. Note that these numerics agree with those that appear in $[25]$.

3.2.1. Constructing some natural adjoint curves to B+E . We now construct some natural adjoint curves to the curve $B + E$ which later allow us to reconstruct the space curve $B^* + E^*$ from $B + E$.

In the classical Segre theory, in order to construct the natural adjoint curves, we start by computing the intersection of B with its polar in \mathbb{P}^2 (see [\[8\]](#page-24-1)).

In the singular case we compute the intersection of $B \cup F$ with the polar of $B \cup E$ in \mathbb{P}^2 .

Set-theoretically, the intersection is

$$
(B \cup F) \cap (B \cup E)' = P \cup Q \cup \text{Node} \cup R_B \cup R_E
$$

(see Definition [3.2](#page-7-1) for R_E , R_B).

Proposition 3.9. *Scheme-theoretically, the intersection* $(B \cup F) \cap (B \cup E)'$ *is*

2P ∪ 3Q ∪ 4Node ∪ 3N ∪ 3Pinch ∪ 6V ∪ 12T ∪ R_B ∪ 2 R_E .

Proof. We can see this from the following local computations:

- At P, the nodes of B, B ∪ F looks like $(x + y)(x y)$, up to a change of local coordinates, and $(B \cup E)'$ looks like 2x. The local intersection is the 2-dimensional vector space $\mathbb{C}\langle 1, y \rangle$.
- At Q, the cusps of B, $B \cup F$ looks like $x^2 y^3$, and $(B \cup E)'$ looks like 2x. The local intersection is the 3-dimensional vector space $\mathbb{C}\langle 1, y, y^2 \rangle$.
- At smooth points R_B of B where the tangent line passes through 0, B and B' meet transversely.
- At all other points of B , there is no intersection.
- At N and Pinch, B intersects E transversely, so $B \cup F$ looks like $(x + y)(x y)^2$, and $(B \cup E)'$ looks like 2x. Hence, the local intersection is of multiplicity 3.
- At V, B is tangent to E, so $B \cup F$ looks like $((x y) (x + y)^2)(x y)^2$, and $(B \cup E)'$ looks like

$$
(x - y)(-2x - 1) + (x - y) - (x + y)^2 = 2x(x - y) - (x + y)^2 = x^2 - 4xy + y^2.
$$

It vanishes to order 2 but is not tangent to either component of $B \cup F$, so the total multiplicity is 6.

• At the triple points T, $B \cup F$ looks locally like $(x - y)^2(x + y)^2(x + 2y)^2$, and $(B \cup E)'$ looks like $(x - y)(x + y) + (x - y)(x + 2y) + (x + y)(x + 2y)$, which vanishes to order 2 but has no common tangent directions with $B \cup F$, so the total multiplicity is 12.

- At the new nodes, Node, $B \cup F$ is locally $(x y)^2(x + y)^2$, and $(B \cup E)'$ is locally $2x$, so the total intersection multiplicity is 4.
- At the points $R_E = [e^{\vee}]$ where E has a tangent line through O', $B \cup F$ passes twice and $(B \cup E)'$ passes once, so the intersection multiplicity is 2.

Thus, the polar $(B \cup E)'$, which is of degree $v(v - 1) - e - 1$, intersects $B \cup F$ in

 $2P + 3Q + 4Node + 3N + 3Pinch + 6V + 12T + R_B + 2e^{\vee}.$

We recall the Residue Theorem (see e.g. Walker [\[26,](#page-25-11) Chap. VI, Theorem 6.2]):

Theorem 3.10 (Residue Theorem). Let C be a plane curve. If A, A', D are divisors *on* C *and* A *and* A⁰ *are linearly equivalent, and there is a curve* L *intersecting* C *in* $A + D$, then there is also a curve L' of the same degree intersecting C in $A' + D$.

Note that the theorem is stated for C a reduced curve and D containing its adjoint divisor (Walker denotes our D by $B + D$, where D is the adjoint divisor and B is some other positive divisor).

By the Residue Theorem, we can substitute $Q + 3V + 6T = (v - 2)h_{B \cup F}$ (see equations [\(3.3\)](#page-7-0) and [\(3.7\)](#page-8-0)) to show that there exists a curve W' of degree $v(v - 1) - e - 1$ that intersects $B \cup F$ in

$$
2P + 2Q + 3N + 3\text{Pinch} + 3V + 6T + 4\text{Node} + R_B + 2e^{\vee} + A_{\nu-2},
$$

where $A_{\nu-2}$ is the class of the intersection of a generic curve C' of degree $\nu - 2$ with B∪F (explicitly, in the notation of the Residue Theorem, $A = Q + 3V + 6T$, $A' = A_{\nu-2}$, $C = B \cup F$). Since deg W' \cdot deg C' < deg $A_{\nu-2}$, C' must be a component of W'; hence W' must be reducible.

Explicitly, dropping the component of degree $\nu - 2$, we are left with a curve of degree $v^2 - 2v + 1 - e$ that meets $B \cup F$ in

$$
2P + 2Q + 3N + 3\text{Pinch} + 3V + 6T + 4\text{Node} + R_B + 2e^{\vee}.
$$

We now apply the Residue Theorem again to replace equations (3.5) , (3.12) :

$$
(v-1)h_B = [V] + 2
$$
[Pinch] + [R_B], $2[e^{\vee}] +$ [Pinch] = 2[V],

to obtain a curve of degree $v^2 - 2v + 1 - e$ that meets $B \cup F$ in

$$
2P + 2Q + 3N + 4V + 6T + 4Node + A'_{v-1},
$$

where $A'_{\nu-1}$ is the class of the intersection of a generic curve of degree $\nu - 1$ with B.

By adding to this curve a new component of degree e , we obtain a curve of degree $v^2 - 2v + 1$ that meets $B \cup F$ in

$$
2P + 2Q + 3N + 4V + 6T + 4Node + A'_{\nu-1} + A_e,
$$

where A_{ρ} is the class of the intersection of a generic curve of degree e with $B \cup F$. Note that $[A_e]$ is $eh_{B\cup F}$ and thus is linearly equivalent to $v(v-1)h_E$, because both are linearly

equivalent to the excess intersection class of $E \cap (B \cup F)$ in $A_0(E) \subset A_0(B \cup F)$. Using the fact that $(v - 1)h_{B\cup F} = (v - 1)h_B + 2(v - 1)h_E$, we can write

$$
[A'_{\nu-1}] + [A_e] = (\nu - 1)h_B + eh_{B \cup F} = (\nu - 1)h_{B \cup F} + \nu(\nu - 1)h_E - 2(\nu - 1)h_E
$$

= (\nu - 1)h_{B \cup F} + (\nu - 2)(\nu - 1)h_E.

Let $A_{\nu-1}$, $A_{(\nu-2)(\nu-1)}''$ be the classes of the intersection of a generic curve of degree $\nu-1$ (resp. $(\nu-2)(\nu-1)$) with $B \cup F$ (resp. E). Hence, there exists a curve of degree $\nu^2 - 2\nu - 1$ that meets $B \cup F$ in

$$
2P + 2Q + 3N + 4V + 6T + 4Node + A_{\nu-1} + A_{(\nu-2)(\nu-1)}''.
$$

By degree considerations (as before), this curve must split into a component of degree $v - 1$ and a component of degree $(v - 1)(v - 2)$ passing through

 $2P + 2Q + 3N + 4V + 6T + 4Node + A_{(\nu-2)(\nu-1)}''$

Explicitly, in $A_0(B \cup F)$ we can write

 $2P + 2Q + 3N + 4V + 6T + 4Node + (v - 2)(v - 1)h_E = (v - 2)(v - 1)h_{B\cup F}$. (3.19)

Subtracting (3.6) from the above equation we get

$$
2[V] + [N] + 6[T] + 4[\text{Node}] = (\nu - 1)(\nu - 2)h_E.
$$

Hence, applying the Residue Theorem one more time, there is a curve L of degree $(\nu - 1)(\nu - 2)$ that intersects $B \cup F$ in

$$
2[P] + 2[Q] + 4[N] + 6[V] + 12[T] + 8[Node].
$$

Thus

$$
(\nu - 1)(\nu - 2)h_{B \cup F} = 2[P] + 2[Q] + 4[N] + 6[V] + 8[\text{Node}] + 12[T]. \tag{3.20}
$$

We recall the definition of an *adjoint* curve (see e.g. [\[11\]](#page-25-12) for a classical treatment, or the modern definition in [\[1,](#page-24-5) Appendix A]):

Definition 3.11. Let $f(x, y) = 0$ be the affine equation of a reduced plane curve $C \subset \mathbb{P}^2$ of degree d with normalization $\phi : C^* \to C$. Let $p \in C$ be a singular point of C and let p_1, \ldots, p_s be the points of C^* which lie over p. The *adjoint divisor* Δ_p of p is the divisor on C^* defined by $\Delta_p = \sum_i (a_i p_i)$ where $a_i = -\text{mult}_{p_i}(\phi^* \frac{dx}{\partial f/\partial y})$. For a plane curve with affine equation $g(x, y) = 0$, define the zero divisor $\phi^*(g)$ to be the divisor of the meromorphic function $\phi^*(g)$ on C.

We say that a plane curve of affine equation $g(x, y) = 0$ is *adjoint* to $f(x, y) = 0$ at p if $\phi^*(g) \ge \Delta_p$. Denoting $\Delta = \sum_{p \in \text{Sing}(C)} \Delta_p$, a curve A is adjoint to C if $A \cdot C \ge \Delta$.

Note that the classical definition is the following: Given a plane curve C , another curve A is said to be *adjoint* to C if it contains each singular point of C of multiplicity r with multiplicity at least $r - 1$. In particular, A is adjoint to a nodal-cuspidal curve C if it contains all nodes and all cusps of C.

Definition 3.12. Denote for each singular point $p \in C_{\text{red}}$, $\Delta'_p = 0$ or $\sum_i (a_i p_i)$, and $\Delta' = \sum_{p \in \text{Sing}(C_{\text{red}})} \Delta'_p$. A curve A is *pseudo-adjoint* to C if $A \cdot C \geq \Delta'$.

Proposition 3.13. *There are two pseudo-adjoint curves* L, L_1 *to* $B \cup F$ *of degrees* $(v - 1)(v - 2)$, $(v - 1)(v - 2) + 1$, passing through the points P, Q, N, V, Node *and* T *with intersection multiplicities* 2, 2, 4, 6, 8, *and* 12, *respectively.*

Proof. Though not necessary for the proof, note that we have the following exact sequence:

$$
0 \to H^0(\Pi, \mathcal{O}((\nu - 1)(\nu - 2))) \xrightarrow{\text{res}} H^0(B \cup F, \mathcal{O}((\nu - 1)(\nu - 2))) \to 0, \quad (3.21)
$$

as deg($B \cup F$) = $\nu(\nu - 1) > (\nu - 1)(\nu - 2)$. Note that we could not have used this sequence to prove the existence of L, as we should have proved first that $2[P] + 2[Q] +$ $4[N] + 6[V] + 8[Node] + 12[T]$ is a positive Cartier divisor.

Indeed, the existence of the adjoint curve L of degree $(\nu - 1)(\nu - 2)$ was deduced above (see the discussion before (3.20)). The existence of a pseudo-adjoint curve L_1 of degree $(\nu - 1)(\nu - 2) + 1$ follows from the fact that $B \cup F$ is a projection of a complete intersection curve in \mathbb{P}^3 , by using [\[8,](#page-24-1) Corollary 4.24].

Remark 3.14. L and L_1 are indeed pseudo-adjoint curves but not adjoint curves, as they do not pass through all the singular points of $B \cup F$ (e.g., the images Pinch of the pinch points).

Remark 3.15. Note that the curves L and L_1 are also adjoint curves to B of degrees $(\nu - 1)(\nu - 2), (\nu - 1)(\nu - 2) + 1.$

3.3. Possible tangent directions

We need to determine the possible tangent directions of the pseudo-adjoint curves at the singular points of $B \cup F$ in order to see how these pseudo-adjoint curves reconstruct the space curve $B^* \cup F^*$. Explicitly, denote $L = \{f = 0\}$, $L_1 = \{f_1 = 0\}$. We want to identify the necessary restrictions on L, L₁ such that the z-coordinate of $B^* \cup F^*$ is given by f_1/f , i.e., the "new" singularities of $B \cup F$ are resolved by this definition of the z-coordinate.

Remark 3.16. By [\(3.19\)](#page-11-1),

$$
2[V] + [N] + 6[T] + 4[\text{Node}] = (\nu - 1)(\nu - 2)h_E,
$$

we see that the curve L passes transversely to E through the points N , and intersects it at V (which are smooth points of E) with intersection multiplicity 2. Therefore, L must be tangent to B at N (so as to have intersection multiplicity 1 with E and 2 with B at N), must either have a node or be tangent to both curves at V , and must have nodes at T and Node.

To determine the possible tangent directions of L and L_1 , as in [\[8\]](#page-24-1), we consider the set of Cartier divisors on $C = B \cup F$ passing through ξ , where $\xi = 2[P] + 2[Q] +$ $4[N] + 6[V] + 8[Node] + 12[T]$ is the 0-cycle of the singularities to be resolved. We are interested in positive Cartier divisors ζ_0 and ζ_1 , where ζ_1 is of the form $\zeta_1 = \zeta_1^{\xi} + \zeta_1^{\text{res}}$, ζ_0 and ζ_1^{ξ} $\frac{1}{1}$ are supported on ξ , and ζ_1^{res} is supported on the smooth points of C. Note that the sections of the sheaf $\mathcal{O}_C(\zeta_0 - \zeta_1)$ can locally be given by $r = h_1/h_0$, where ord_p(r) = ord_p(h₁) – ord_p(h₀) ≥ 0 at each singular point $p \in \xi$. As in [\[8\]](#page-24-1), we have the adjunction sequence, for $a = (v - 1)(v - 2)$,

$$
ac_{i,\zeta_1}: J_{\zeta_1, \mathbb{P}}(a+i) \xrightarrow{\text{res}_C} \mathcal{O}_C(-\zeta_1)(a+i) \xrightarrow{\frac{f_1^a/f_L}{\sim}} \mathcal{O}_C(\zeta_0 - \zeta_1)(i)
$$

= $\mathcal{O}_C(\zeta_0 - \zeta_1^{\xi})(i)(-\zeta_1^{\text{res}}) \subset \mathcal{O}_C(\zeta_0 - \zeta_1^{\xi})(i) \subset R_C(i)$ (3.22)

where the first map is restriction to C , the second map is induced from (3.20) (where f_l , f_l are the equations of a line and the curve L, respectively), and R_c is the sheaf of rational functions given locally by fractions $r = h_1/h_0$ such that ord $Z(r) = \text{ord}_Z(h_1) \text{ord}_Z(h_0) \geq 0$ for each codimension one subvariety Z of C.

Remark 3.17 (Graded algebras for a space curve C^*). Assume we are given a space curve $C^* = B^* \cup F^*$ not contained in any plane in \mathbb{P}^3 and a projection $p : C^* \to$ C to a plane curve C. Let $S = \bigoplus S_i$, $S_i = H^0(C, \mathcal{O}(i))$, be the graded algebra of homogeneous functions on C , and T be the graded algebra of homogeneous functions on C^* . The inclusion $S \to T$ gives an isomorphism of fraction fields $\mathbb{Q}(S) \to \mathbb{Q}(T)$, since C and C^{*} are birational. Now $T_1 = S_1 \oplus kz$ for some element (the "vertical coordinate") $z \in T_1$; since $T_1 \subset \mathbb{Q}(T) \simeq \mathbb{Q}(S)$, we should have

$$
z = f_{n+1}/f_n
$$

for some integer *n* and plane curves f_n and f_{n+1} of degrees *n* and $n + 1$.

Corollary 3.18. Apply the previous remark to the space curve $C^* = B^* \cup F^*$, the generic *projection* $p : \mathbb{P}^3 \to \mathbb{P}^2$ with center O not on C^* and the pseudo-adjoint curve L. Let $a = (\nu - 1)(\nu - 2)$.

Then the "vertical coordinate" z *on* C^* , $z \in H^0(C^*, \mathcal{O}_{C^*}(1))$, is the image of a *uniquely defined plane curve* L_1 *of degree* $a + 1$ *under the adjunction map* $a_{C,1}$ *defined by* [\(3.22\)](#page-13-0)*.*

In other words, we can choose $n = a$ *in the remark above, and*

$$
z = f_{L_1}/f_L,
$$

where f_L and f_{L_1} are the equations of the plane curves L and L₁, deg $L_1 = a + 1$, and *the curve* L¹ *is not a union of* L *and a line, i.e., it is a "new" pseudo-adjoint curve. The curve* L¹ *must satisfy the following conditions:*

(1) L *and* L¹ *meet* P *and* Q *transversely and have different tangent directions.*

(2) L *and* L¹ *are both tangent to* B *at* N , *and have intersection multiplicity* 2 *with each other.*

- (3) L and L_1 have nodes at V such that one branch of L is tangent to one branch of L_1 , *or either* L *or* L_1 *is tangent to* $B \cup E$ *at* V .
- (4) L and L_1 have nodes at T with the same tangent cone, and their intersection multi*plicity with each other is exactly* 6*.*
- (5) L *and* L¹ *have nodes at* Node *with distinct tangent cones.*

Proof. Let S be the graded homogeneous algebra of C, and T be the graded homogeneous algebra of C^{*}; consider the element $t = z \cdot f_L$ of T_{a+1} . It is enough to prove that t actually belongs to S_{a+1} , since then we can let $f_{a+1} = t$ and $z = f_{a+1}/f_L$. Now this is an easy local computation for each singular point of C , since the exact sequence

$$
0 \to S_{a+1} \to T_{a+1} \to T_{a+1}/S_{a+1} \to 0
$$

is obtained from the exact sequence of sheaves

$$
0 \to \mathcal{O}_C(a+1) \to p_*\mathcal{O}_{C^*}(a+1) \to \text{Fac}(a+1) \to 0,
$$

where Fac is by definition the factor sheaf $p_*\mathcal{O}_{C^*}/\mathcal{O}_C$, by passing to global sections,

$$
0 \to H^0(C, \mathcal{O}_C(a+1)) \xrightarrow{p^*} H^0(C^*, \mathcal{O}_{C^*}(a+1)) \to \text{coker } p^* \to 0.
$$

Since the factor sheaf Fac is a product of sheaves supported at singular points of C , this makes computing the image of t in $H^0(C, \text{Fac}(a+1))$ an easy local computation at the singular points.

(1) The nodes P and cusps Q are resolved by a single blowup.

(2) A local model for $B \cup E$ at N is $xy = 0$, and since by intersection theory considerations L is tangent to B, we can take $f_L = y - x^2$. Since L vanishes to order 4 on $B \cup F$, so must L_1 . Hence L_1 is tangent to B, say $f_{L_1} = y - 2x^2$. It is easy to check that the node is resolved and t is in S_{a+1} .

(3) At V, L and L_1 must either have nodes or be tangent to B. If they both have nodes at V, then suppose the tangent directions of L are v, w and the tangent directions of L_1 are α , β . We want to blow up V partially, to a transverse intersection. If $v = \alpha$ and $w = \beta$ then V is not blown up at all. If $v \neq \alpha$ and $w \neq \beta$ then it blows up completely, unless one of the tangent directions is that of $B \cup E$. If v is the tangent direction of $B \cup E$, or if $v = \alpha$ and $w \neq \beta$, then we have the following condition:

$$
\left(\frac{f_{L_1}}{f_L}\right)'_{B^*}(t) = \left(\frac{f_{L_1}}{f_L}\right)'_{F^*}(t),
$$

i.e., the intersection of B^* and F^* at V^* is transverse.

For example a local model in the first case is

$$
V: y \cdot (y - x^2) = 0, \quad L = \{(y + x^2)(y - 2x) = 0\}, \quad L_1 = \{(y - x)(y - 3x) = 0\},
$$

and a local model in the second case is

$$
V: y \cdot (y - x^2) = 0, \quad L = \{x(y - 2x) = 0\}, \quad L_1 = \{(y - x)(y - 2x) = 0\}.
$$

Another possibility is that L is tangent at V and L_1 has a node (or vice versa). Again,

$$
\left(\frac{f_{L_1}}{f_L}\right)'_{B^*}(t) = \left(\frac{f_{L_1}}{f_L}\right)'_{F^*}(t)
$$

as long as the tangent directions of L_1 are different from those of L and B ∪ E. A local model is

$$
V: y \cdot (y - x^2) = 0
$$
, $L = \{y - 2x^2 = 0\}$, $L_1 = \{(y - x)(y - 2x) = 0\}$.

(4) At T , L and L_1 have nodes. If they have different tangent directions, then they will blow up T. To avoid blowing up, L and L_1 must have the same tangent cone. A local model at T is

$$
T: x \cdot y \cdot (y - x) = 0, \quad L = \{(x - 2y)(x - 3y) = 0\}, \quad L_1 = \{(x - 2y)(x - 3y + x^2) = 0\}.
$$

This model does not resolve the triple point but lifts one of the tangent directions out of the plane of the other two.

(5) L and L_1 have nodes at [Node] by intersection theory considerations, and they resolve [Node] when the tangent cones of the two adjoint curves are different, e.g., $L =$ ${(y-x)(y+x) = 0}, L_1 = L = {(y-2x)(y+2x) = 0}.$

Since f_L vanishes at the singularities of $B \cup F$ that are resolved in $B^* \cup F^*$, $t = z f_L$ is a regular (holomorphic) object on $B \cup F$, and thus belongs to S_{a+1} . □

4. From adjoint curves to ramification curves

Assume we are given a plane curve C that consists of a reduced component B and a double curve component F (where $F_{\text{red}} = E$) such that B has nodes P and cusps Q, E has nodes denoted by Node and triple points T , and that B and E intersect transversely (in points which we divide into two sets, called Pinch and N) and have simple tangencies at V. Suppose that these points satisfy all the numerical conditions of the previous section, and that the curve C has pseudo-adjoint curves L and L_1 satisfying the conditions of the previous section. In this section we prove that these conditions are sufficient for C to be the (total) branch curve of a surface with ordinary singularities in \mathbb{P}^3 .

Theorem 4.1. Let $C = B \cup F$ be a plane curve of degree $v(v - 1)$ such that B has *nodes* P and cusps Q, and F is a double curve such that $F_{\text{red}} = E$ *is of degree e and has nodes* Node *and triple points* T *, and* B *and* E *intersect transversely in two distinguished sets of points, which are called the "pinch points"* Pinch *of the double curve* F *and a set of "new nodes"* N*, and are simply tangent at a set of points* V *. The following conditions are necessary and sufficient for* C *to be a* (*total*) *branch of a surface* S *of degree* ν *with ordinary singularities:*

- (1) *The distinguished points on* B, E *satisfy the numerical conditions induced from* [\(3.13\)](#page-8-2)–[\(3.18\)](#page-8-2) (*see Remark* [3.8](#page-8-3))*.*
- (2) *On each component of* E *there is at least one point from the set* V *.*

(3) *There are two pseudo-adjoint curves,* L *of degree* a = (ν−1)(ν−2) *and* L¹ *of degree* a + 1*, satisfying the constraints* (1)–(5) *of Corollary* [3.18](#page-13-1) *on their intersections and tangent directions.*

The necessity of these conditions was proved in Section 3. The following subsections provide the proof of the sufficiency.

4.1. The model of the curve in \mathbb{P}^3

We use the pseudo-adjoint curves to $B \cup F$ to construct a model of the curve C in \mathbb{P}^3 . Let f_L be the equation of the curve L and let f_{L_1} be the equation of L_1 . The equation $z = f_{L_1}/f_L$ defines a space curve $C^* = B^* \cup F^*$, whose projection to \mathbb{P}^2 is C. Note that F^* really is a double space curve; its double structure is determined by using the differential of the function z to lift the tangent vectors from the double structure of F .

Since f_L is defined uniquely and f_{L_1} is defined up to adding multiples of f_L , and since z is defined by f_L and f_{L_1} , the model $B^* \cup F^*$ is well defined up to coordinate changes generated by those of the form $(x : y : z : w) \mapsto (x : y : z + c : w)$; in particular, it is determined up to rational automorphisms of \mathbb{P}^3 that commute with projection to \mathbb{P}^2 .

This model has the geometric properties of a ramification curve: by assumption it has all the correct numbers of distinguished points. It resolves each of the singularities correctly, by the calculations in Corollary 3.20.

4.2. The model as a complete intersection

We now prove the following theorem.

Theorem 4.2. *The curve* $B^* \cup F^*$ *is a complete intersection.*

First, we introduce the following definition:

Definition 4.3. Given a curve C, we define the *index of speciality*

$$
s(C) = \max\{n : h^1(C, \mathcal{O}_C(n)) \neq 0\}.
$$

(Note that many works denote the index by e (see, e.g., Schlesinger [\[23\]](#page-25-13)) but we call it s to avoid confusion with the degree of E .)

To motivate our use of this definition we briefly recall some history. One of the first methods used to prove that an irreducible reduced space curve is a complete intersection of two surfaces of degrees a and b was Halphen's Speciality Theorem, introduced in 1882:

Theorem (see [\[14\]](#page-25-14)). Let C be a space curve of order $a \cdot b$ in \mathbb{P}^3 such that $a < b$ which *has* ¹ 2 a(a −1)b(b−1) *bisecants all lying on a cone of degree* (a −1)(b−1)*. Assume also that* C *is not on a surface of degree smaller than* a*. Then* C *is a complete intersection of two surfaces of degree* a *and* b*.*

In the case of a smooth surface in \mathbb{P}^3 , Segre used this method to show that a model built from a nodal-cuspidal plane curve is indeed a complete intersection (and later he showed that this space curve is an intersection of a surface and its polar). Indeed, every node and cusp are induced from a bisecant, so a space curve of degree $v(v - 1)$, not on a surface of degree $v - 2$, with *nodes* + *cusps* = $\frac{1}{2}v(v - 1)^2(v - 2)$ bisecants, lying on a cone of degree $(\nu - 1)(\nu - 2)$ (induced from the adjoint curve of this degree) is a complete intersection of two surfaces of degree ν and $\nu - 1$.

However, as noted by Gruson and Peskine [\[13\]](#page-25-15), the proof of Halphen involves "des considérations qui en rendent l'interprétation hasardeuse", and it is not at all clear whether it extends to the case of reducible or non-reduced curves. Gruson and Peskine rephrased this theorem in modern terms in 1978 as the Speciality Theorem:

Let C *be an integral curve in* P ³ *of degree* d*, not contained in a surface of degree less than* t*.* Let $s = s(C)$ *. Then* $s \le t + d/t - 4$ *, with equality holding if and only if* C *is a complete intersection of type* $(t, d/t)$ (*and thus* $\mathcal{O}_C(s)$ *is special, i.e.,* $h^1(\mathcal{O}_C(s)) \neq 0$ *).*

Substituting $t = v - 1$, $d = v(v - 1)$, we obtain Halphen's theorem.

However, in our case, the model of our curve in \mathbb{P}^3 is non-reduced and reducible—two phenomena that the Speciality Theorem does not address. However, in 1999, Schlesinger generalized the above theorem:

Theorem 4.4 ([\[23\]](#page-25-13)). Let C be a curve (possibly non-reduced and reducible) in \mathbb{P}^3 with *index of speciality* $s = s(C)$ *. Suppose that no subcurve* D *of* C *with* $s(D) = s$ *lies on a surface of degree* $t - 1$ *, and let m be the minimum of t and the integral part of* $(s + 4)/2$ *. Then* deg $C > m(s + 4 - m)$ *with equality holding if and only if* C *is a deformation with constant cohomology of a complete intersection of two surfaces of degree m and* $s + 4 - m$.

Thus, in order to prove that $B^* \cup F^*$ is (a degeneration of) a complete intersection of surfaces of degrees v and $v - 1$ we have to prove that no subcurve of $B^* \cup F^*$ with the same index of speciality of $s(B^* \cup F^*)$ lies on a surface of degree less than $v - 1$. We prove this in four steps.

Lemma 4.5. *The index of speciality* $s(B^* \cup F^*)$ *is* $2v - 5$ *, while all the subcurves of* $B^* \cup F^*$, with the possible exception of $B^* \cup E^*$, have strictly lower speciality index.

Proof. In the case of $B^* \cup F^*$, the proof is the same as that of D'Almeida ([\[5\]](#page-24-0) for the case of a smooth surface in \mathbb{P}^3): by intersection theory considerations, we know that the curve L does not meet $B \cup F$ outside the singular points. Hence there can be no curve of smaller degree containing the same set of singular points (counted with their multiplicities).

Let now $p : B^* \cup F^* \to B \cup F$ be the projection from the point O. The conductor of the structure sheaf $\mathcal{O}_{B^*\cup F^*}$ in $\mathcal{O}_{B\cup F}$ is Ann $(p_*\mathcal{O}_{B^*\cup F^*}/\mathcal{O}_{B\cup F})$, which by duality is isomorphic to Ann $(\omega_{B \cup F}/p_*(\omega_{B^* \cup F^*}))$ (see e.g. [\[2,](#page-24-6) Chapter 8]). By the definition of the conductor, we see that $\text{Ann}(\omega_{B\cup F}/p_*(\omega_{B^*\cup F^*})) = \text{Hom}(\omega_{B\cup F}, p_*(\omega_{B^*\cup F^*})) =$ $p_*(\omega_{B^*\cup F^*})\otimes\omega_B^\vee$ B_{U} . It is well known that H is a global section of the conductor sheaf iff H passes through the singular points of the curve $B \cup F$ that get resolved.

By Serre duality, for all *i*, $H^1(\mathcal{O}_{B^*\cup F^*}(i)) = H^0(\omega_{B^*\cup F^*}(-i))$. Hence the minimal degree of a curve containing the points that get resolved when $B \cup F$ is lifted to $B^* \cup F^*$ is $v(v-1) - 3 - s(B^* \cup F^*)$. Setting this equal to $(v-1)(v-2)$, the degree of L, we see that $s(B^* \cup F^*) = 2v - 5$.

We now examine the subcurves of $B^* \cup F^*$. Note that by our construction, the curve $B^* \cup F^*$ is connected, and $B^* \cap F^*$ consists only of $|\text{Pinch}^*| + |V^*|$ (double) points.

• $s(B^*)$: We use the fact that for any integral space curve C,

$$
2p_a(C) - 2 \ge \deg(C)s(C)
$$

(see, e.g., [\[16,](#page-25-16) Section 2]), as $2p_a(C) - 2 - \deg(C)s(C)$ is the third Chern class of a rank two reflexive sheaf; this inequality is an equality in the case of subcanonical curves $([12])$ $([12])$ $([12])$. (In the case of a smooth surface, the ramification curve is itself a complete intersection, hence subcanonical.) Suppose that $s(B^*) = 2v - 5$, i.e. $2p_a(B^*) - 2 \ge$ $deg(B^*)(2\nu – 5)$. Since

$$
p_a(B^*) = \frac{(\nu(\nu-1) - 2e - 1)(\nu(\nu-1) - 2e - 2)}{2} - n - c,
$$

we have

$$
(\nu(\nu-1)-2e-1)(\nu(\nu-1)-2e-2)-2n-2c-2 \geq (\nu(\nu-1)-2e)(2\nu-5).
$$

Substituting for n and c , we get

$$
(v(v-1) - 2e - 1)(v(v-1) - 2e - 2)
$$

- v(v - 1)(v - 2)(v - 3) + 4e(v - 2)(v - 3) + 4(e^v)* + 24t
- 4e(e - 1) - 2v(v - 1)(v - 2) + 6e(v - 2) - 6t
\ge (v(v - 1) - 2e)(2v - 5),

which simplifies to $2 + 4(e^{\vee})^* + 18T + 12e - 6\nu e \ge 0$. Since [Pinch] = 2[V] - 2[e^{\vee}], we have $4[e^{\vee}] = 4[V] - 2[Pinch]$. Hence this reduces to $2 + 4|V| - 2|Pinch| + 18|T| + 1$ $6e(2 - v) \ge 0$. Since $e(v - 2) = |V| + 3|T|$, we get $2 - 2|\text{Pinch}| - 2|V| \ge 0$, which is clearly impossible since $\text{[Pinch + } V \text{]}$ is always greater than 1.

• $s(F^*)$: Consider two Cohen–Macaulay curves $Y_1, Y_2 \subseteq \mathbb{P}^3$ meeting in a zero-dimensional subscheme Z^* , let $Y = Y_1 \cup Y_2$, $Z^* = Y_1 \cap Y_2$. Then we have the following exact sequence (see [\[15,](#page-25-17) p. 82]):

$$
0 \to \omega_Y \to \omega_{Y_1}(Z^*) \oplus \omega_{Y_2}(Z^*) \to \mathbb{C}^{\oplus Z^*} \to 0.
$$

Twisting by $-k$ and taking cohomology, we see that

$$
h^{0}(\omega_{Y}(-k)) = h^{0}(\omega_{Y_{1}}(-kh_{Y_{1}} + Z^{*})) + h^{0}(\omega_{Y_{2}}(-kh_{Y_{2}} + Z^{*})).
$$

Hence, if Z^* is at least equal to h_{Y_1} (in the partial order of the Chow group $A_0(Y)$), then $s(Y_1) < s(Y)$, a strict inequality. In our case, since B^* is irreducible, we can divide

 $B^* \cup F^*$ into two components as B^* and F^* . The intersection $[Z]^*$ is $[Pinch]^* + [V]^*$. We need to prove that $[Z^*] > h_{F^*} = 2h_{E^*}$. Denote by Z the image of Z^* in \mathbb{P}^2 ; it is enough to show that $[Z] = [Pinch] + [V] > 2h_E$.

We know that $[V] + 3[T] = (v - 2)h_E$, and that $0 < [Pinch] = 2(v - 4)h_E - 2C_E$ 6[T], so 3[T] < $(\nu - 4)h_E$. Hence [V] must be at least $2h_E$, or [Z] = [Pinch] + [V] > 2*h*_E. Hence *s*(F^*) < *s*($B^* \cup F^*$). Let F_1^* be a component of F^* .

• $s(B^* \cup F_1^*)$: For $T = 0$, assume $s(B^* \cup F_1^*) = 2\nu - 5$. The minimal degree of a curve passing through all the singularities of $B \cup F_1$ that should be resolved must be

$$
(\nu(\nu-1) - 2e + 2e_1) - 3 - (2\nu - 5) = (\nu - 1)(\nu - 2) - 2e + 2e_1 \doteq b
$$

(by the same reasoning as in the case of $B^* \cup F^*$). Assume such a curve C_0 of degree b exists. Then

$$
C_0 \cap (B \cup F_1) = 2P + 2Q + 4N_1 + 6V_1 + 8Node_1 + {Residual points},
$$

by intersection theory considerations. But

$$
b \cdot \deg(B \cup F_1) = ((\nu - 1)(\nu - 2) - 2e + 2e_1) \deg(B \cup F_1)
$$

= 2P + 2Q + 4N₁ + 6V₁ + 8Node₁ - 2(e - e₁) deg(B \cup F₁)

(by [\(3.20\)](#page-11-0) restricted to $B \cup F_1$). So we should get

$$
b \cdot \deg(B \cup F_1) = |C_0 \cap (B \cup F_1)|,
$$

or

$$
-2(e - e_1) \deg(B \cup F_1) = \{Residual points\},\
$$

which is a contradiction.

However, if such a curve does not exist, then the degree of the minimal-degree curve is not $b = (v - 1)(v - 2) - 2e + 2e_1$, i.e., $s(B^* \cup F^*) < 2v - 5$. Likewise, for $T > 0$, the minimal degree of a curve passing through the singularities is still $(v(v-1)-2e+2e_1)$ $-3 - (2\nu - 5) = (\nu - 1)(\nu - 2) - 2e + 2e_1 = b$. Assume that such a curve C_0 exists. Then

 $C_0 \cap (B \cup F_1) = 2P + 2Q + 4N_1 + 6V_1 + 8N_2$ + $3T_1 + {Residual points}$,

where T_1 denotes the triple points that are triple points of F_1 . (The other triple points appear as nodes or smooth points of F_1 and hence do not have to be resolved.) However,

$$
b \cdot \deg(B \cup F_1) = ((\nu - 1)(\nu - 2) - 2e + 2e_1) \deg(B \cup F_1)
$$

= 2|P| + 2|Q| + 4|N_1| + 6|V_1| + 8|Node_1| + $\sum_j |\tau_{1j}| - 2(e - e_1) \deg(B \cup F_1)$,

so

$$
b \cdot \deg(B \cup F_1) = |C \cap (B \cup F_1)| + \sum_{j, |\tau_{1j}| \neq 3} |\tau_{1j}|.
$$

Hence

$$
-2(e-e_1)\deg(B\cup F_1)=\{\text{Residual points}\}-\sum_{j,\,|\tau_{1j}|\neq 3}|\tau_{1j}|.
$$

By (3.8),
$$
V_2 + \sum_j \tau_{2j} = (\nu - 2)e_2
$$
, so $\sum_j \tau_{2j} < (\nu - 2)e_2$. Also

$$
\sum_{j, |\tau_{1j}| \neq 3} \tau_{1j} \leq 2 \sum_{j, \tau_{2j} \neq 3} \tau_{2j} \leq 2(\nu - 2)e_2.
$$

Hence

$$
\begin{aligned} \text{[Residual points]} &< -2(e - e_1) \deg(B \cup F_1) + (e - e_1)(2v - 4) \\ &= (e - e_1)(2v - 4 - 2(v(v - 1) - 2e + 2e_1)) \\ &= (e - e_1)(-2v^2 + 4v - 4 + 4e - 4e_1) \\ &< (e - e_1)(-2v^2 + 4v - 4 + 2(v - 1)(v - 2)) \\ &= (e - e_1)(-2v) < 0. \end{aligned}
$$

This is a contradiction, as above, so the degree of the minimal curve cannot be b , and hence $s(B^* \cup F_1^*) \neq 2\nu - 5$.

- As max($s(B^*), s(F_i^*)) \le s(B^* \cup F_i^*)$, it follows that $s(F_i^*) < 2\nu 5$.
- As for the subcurves E_i^* of F_i^* (and likewise $B^* \cup E_i^*$), consider the exact sequence

$$
0 \to \mathcal{I}_E(k) \to \mathcal{O}_F(k) \to \mathcal{O}_E(k) \to 0.
$$

The last terms of the long exact sequence of cohomology are

$$
H^1(\mathcal{O}_F(k)) \to H^1(\mathcal{O}_E(k)) \to 0.
$$

Thus $s(F) \geq s(E)$.

We next verify that the curve $B^* \cup F^*$ does not lie on a surface of degree lower than the degree of the polar of the surface we wish to construct.

Lemma 4.6. *The curve* $B^* \cup E^*$ *does not lie on a surface of degree less than* $v - 1$ *.*

Proof. Let S be a surface containing $B^* \cup E^*$. Since B^* is smooth at Q while B has a cusp at Q, B^* and E^* are transverse at V^* while B and E are tangent, and E^* has a non-planar triple point at T^* while E has a planar triple point at T, the projection to \mathbb{P}^2 kills an element of the tangent space to $B^* \cup E^*$, and hence of the tangent space to S, at each of these points. Therefore, the polar to S contains Q^* , V^* and T^* . Thus $(B^* \cup E^*) \cap S' \ge Q^* + 2V^* + 3T^* = (\nu - 2)h_{B^* \cup E^*}$. Hence deg $S' \ge \nu - 2$, so $\deg S \geq \nu - 1.$

These two lemmas satisfy the premises of Schlesinger's generalized Speciality Theorem (Theorem [4.4\)](#page-17-0), which we can apply to conclude that $B^* \cup F^*$ is a degeneration of a complete intersection.

Lemma 4.7. *The curve* $B^* \cup F^*$ *is a degeneration of complete intersections of surfaces of degrees* ν *and* ν−1, *preserving the dimensions of the cohomologies of the twisted ideal sheaves.*

Proof. By Theorem [4.4,](#page-17-0) it is enough to check that no subcurve C of $B^* \cup F^*$ with the same index of speciality $s(B^* \cup F^*)$ lies on a surface of lower degree.

The speciality of $B^* \cup F^*$ is $2\nu - 5$, by Lemma [4.6.](#page-20-0) $B^* \cup E^*$ cannot lie on a surface of degree less than $v - 1$, and $B^* \cup F^*$ clearly cannot lie on any surface that does not contain its subcurve $B^* \cup E^*$. Finally, all the other subcurves of $B^* \cup F^*$ have speciality index strictly lower than $2v - 5$, as was shown in Lemma [4.5.](#page-17-1)

In fact, our curve is not only a degeneration of complete intersections, but is itself a complete intersection.

Theorem 4.8. *The curve* $B^* \cup F^*$ *is itself a complete intersection of two surfaces of degrees* ν *and* ν − 1*.*

Proof. A complete intersection of surfaces of degrees v and $\nu - 1$ lies on one surface of degree $\nu - 1$ and a 4-dimensional family of surfaces of degree ν , generated by the products of three linear forms with the form of degree $\nu - 1$ and one independent degree ν form. Since the degeneration is required to be cohomology-preserving, it follows that the limit $B^* \cup 2E^*$ also lies on a surface of degree $\nu - 1$ and a 4-dimensional family of surfaces of degree ν . Hence it lies on the intersection of a surface Σ of degree $\nu-1$ and an independent surface S of degree ν . Since the degrees match, the intersection is complete.

 \Box

4.3. The complete intersection of a surface and its polar

We can now prove our main theorem.

Proof of Theorem [4.1.](#page-15-1) Consider the 5-dimensional vector space W of v-forms S_t of the form $t_0S + t_1xF + t_2yF + t_3zF + t_4wF$. The generic S_t is a smooth surface, whose intersection with its polar is the ramification curve of S_t . The intersection of B^* with $S_t \cap S'_t$ includes Q^* and V^* , since a tangent direction of the curve $B^* \cup 2E^*$ gets collapsed at these points, so any surface containing $B^* \cup 2E^*$ must have a vertical tangent direction at these points. But by degree considerations, $[B^* \cap S_t \cap S'_t] = (\nu - 1)h_{B^*}$, whereas $[Q^*] + [V^*] = (v - 2)h_{B^*}$. Hence $B^* \cap S_t \cap S'_t = Q^* + V^* + r_{B^*}(t)$, where $r_{B^*}(t) \in$ $|h_{B^*}|$. This $r_{B^*}(t)$ thus determines (at least generically) a linear map from W to the 4dimensional vector space $H^0(\mathcal{O}_{B^*}(1)) = H^0(\mathcal{O}_{\mathbb{P}^3}(1))$, by sending S_t to $|t| \phi(r_{B^*}(t))$, where |t| is the magnitude of the vector (t_0, \ldots, t_4) and $\phi(r_{B^*}(t))$ is the normalized 1form that vanishes on $r_{B*}(t)$.

Likewise, the intersection of F^* with $S_t \cap S'_t$ includes $2V^* + 6T^*$, since vertical tangent directions get collapsed and the local intersection of F^* with any other curve is at least 2 at V^* and at least 6 at T^* . Since $[2V^*]+[6T^*] \in (\nu-2)h_{F^*}$, and $[F^* \cap S_t \cap S_t'] \in$ $(v-1)h_{F^*}$, we find that $F^* \cap S_t \cap S'_t = 2V^* + 6T^* + r_{F^*}(t)$, where $r_{F^*}(t) \in |h_{F^*}|$. Thus we get another generic map from W to $H^0(\mathcal{O}_{\mathbb{P}^3}(1))$. Finally, if we play the same game with $B^* \cup F^*$, then $r_{B^*}(t) + r_{F^*}(t) \in |h_{B^* \cup F^*}|$ determines yet another map to $H^0(\mathcal{O}_{\mathbb{P}^3}(1)).$

Any map from a 5-dimensional vector space to a 4-dimensional one has at least a one-dimensional kernel. The only way such a kernel can arise is when the class $r(t)$ is not well defined, i.e., if the intersection of the curves is an excess intersection rather than a set of points including Q^* , V^* and T^* , i.e., if B^* or F^* is a component of the ramification curve. Hence the kernel of $r_{B*}(t)$ is the linear space of *v*-forms that define surfaces whose ramification curve contains B^* , and the kernel of $r_{F^*}(t)$ consists of v-forms defining surfaces whose ramification curve contains the double curve F^* . The kernel of the third map $r_{B^*\cup F^*}$ is the set of v-forms for which either B^* or F^* is in the ramification curve. Since the kernel of a linear map is a linear subspace, not a union of linear subspaces, we conclude that the above two kernels coincide; that is, there exists a surface S_t such that $S_t \cap S'_t$ contains $B^* \cup F^*$. By degree considerations, $S_t \cap S'_t = B^* \cup F^*$.

Hence $B^* \cup F^*$ is the intersection of a surface and its polar; in other words, it is a ramification curve. \Box

Remark 4.9. Note that the surface S_t whose ramification curve is $B + F$ is uniquely defined by the model $B^* + F^*$, since $B^* + F^*$ can only lie on a single surface S'_t , and S_t is determined by its polar up to translation along the *z*-axis. Thus the surface, like its ramification curve, is uniquely determined by $B + F$ up to automorphisms of \mathbb{P}^3 that commute with projection.

The construction in this paper thus provides a constructive proof of an analogue of Chisini's theorem for surfaces with ordinary singularities in \mathbb{P}^3 . In particular, given the total branch curve of such a surface, one can construct its model in \mathbb{P}^3 from the pseudoadjoint curves, which are determined by the special divisor class of $B \cup F$. This model is then a complete intersection of a surface S and its polar. This S is the original surface, up to changes of coordinates that commute with projection.

5. Examples

We first introduce some notation.

Notation 5.1. Let $V(c, d, n)$ (resp. $B(c, d, n)$) be the variety of degree d plane curves (resp. branch curves of generic linear projections) with c cusps and n nodes.

By Remark [3.15,](#page-12-0) equation [\(3.6\)](#page-7-2) and the exact sequence [\(3.21\)](#page-12-1), there exists a curve L of degree $(\nu - 1)(\nu - 2)$ that passes (smoothly) through the cusps Q and the nodes P of the (pure) branch curve B , is tangent to B at the points N and has nodes at the points V . The curve L is unique if the exact sequence [\(3.21\)](#page-12-1) is exact for B as well as for $B \cup F$, in particular if $d > (v - 1)(v - 2)$. Therefore, in this case

$$
\{L\} \simeq H^0(\mathbb{P}^2, J_{\zeta}(a))
$$

where $\zeta = P + Q + 2V + 2N$ is a Cartier divisor on B. Note that 2N is a summand of ζ , as L has a specified tangent direction at this point, and to pass through a point with a given tangent direction is equivalent to passing through two points (the actual point and one infinitely near point).

Let ξ be a 0-cycle in \mathbb{P}^2 . Define the *superabundance* of ξ (relative to degree *n* curves) as

$$
\delta(\xi, n) = h^1 J_{\xi}(n).
$$

We first examine the case of a surface with a double line.

5.1. Surfaces with a double line

A surface $S \subset \mathbb{P}^3$ of degree ν with a double line as its only double curve has the following invariants:

$$
d = \deg(B) = v(v - 1) - 2, \quad e = \deg(E) = 1, \quad c = v(v - 1)(v - 2) - 3(v - 2),
$$

\n
$$
n = \frac{1}{2}v(v - 1)(v - 2)(v - 3) - 2(v - 2)(v - 3), \quad p = |\text{Pinch}| = 2(v - 2), \quad |V| = v - 2,
$$

\n
$$
|N| = (v - 2)(v - 3), \quad |\text{Node}| = 0, \quad t = 0, \quad e_1 = 0.
$$

These numerics are classical; the history is explained in some detail by Ragni Piene [\[22\]](#page-25-8). Set $\zeta = P + Q + 2V + 2N$ and $a = (\nu - 1)(\nu - 2)$. Note that in this case $d > a$.

Proposition 5.2 (Speciality index of ζ). *The speciality index of* ζ *satisfies*

$$
\delta(\zeta, a) = \frac{1}{2}(\nu - 2)(\nu - 3)(2\nu - 1).
$$

Proof. For the expected dimension vdim $|J_{\zeta}(a)|$, we have

$$
vdim |J_{\zeta}(a)| = dim |ah| - deg \zeta = \frac{1}{2}a(a+3) - \frac{1}{2}(\nu - 2)^{2}(\nu^{2} + 1).
$$

Since $a = (v - 1)(v - 2)$, we get

$$
vdim |J_{\zeta}(a)| = \frac{1}{2}(\nu - 2)(-2\nu^{2} + 7\nu - 3).
$$

Since, by the definition of the speciality index,

$$
\dim |J_{\zeta}(d)| = \text{vdim} |J_{\zeta}(d)| + \delta(\zeta, d),
$$

and since $|J_{\zeta}(a)| = \{L\}$, we get the equality. Likewise, $\delta(\zeta, a + 1)$ can be computed analogously. \Box

Thus, $\delta(\zeta, a) > 0$ only when $\nu > 3$. For example, for $\nu = 4$, $\delta(\zeta, 6) = 7$. Indeed, the curve L (which is adjoint to $B \in B(10, 18, 8)$) passes through 34 points, counted with multiplicity. However, it is not known if there is a curve $C \in V(10, 18, 8)$ such that $\delta(\zeta, 6) < 7.$

5.2. Degree 4 surfaces

As was noted at the end of the last subsection, for a degree 4 surface in \mathbb{P}^3 with a double line, the 0-cycle $\zeta = P + Q + 2V + 2N$ is special, and $\delta(\zeta, 6) = 7$. We will now look at other degree 4 surfaces in \mathbb{P}^3 such that this 0-cycle is special with respect to degree 6 curves passing through it (as L is a degree 6 curve passing through ζ).

- (1) *Double curve is a smooth conic*: In this case, $e = \deg(E) = 2$, $d = \deg(B) = 8$, $|Q| = 12$, $|P| = 4$, $|N| = 4$, $|V| = 4$. Thus deg $\zeta = 32$ and $\delta(\zeta, 6) = 5$. The variety $V(8, 12, 4)$ is in fact reducible; there is a Zariski pair for this curve (see [\[7\]](#page-24-7)).
- (2) *Double curve is a union of two skew lines*: In this case, $e = 2$, $d = 8$, $|Q| = 12$, $|P| = 8$, $|N| = 0$, $|V| = 4$. Thus deg $\zeta = 28$ and $\delta(\zeta, 6) = 1$. The variety $V(8, 12, 8)$ is irreducible, i.e., for every curve $C \in V(8, 12, 8)$ the 0-cycle ζ is special with respect to degree 6 curves.
- (3) *Double curve is a rational space cubic or a union of three lines meeting in a point*: In these two cases, $d = a$ and it is not known whether ζ is a special 0-cycle.

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