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Optimal regularity for the porous medium equation

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Abstract We prove optimal regularity for solutions to porous media equations in Sobolev spaces, based on velocity averaging techniques. In particular, the regularity obtained is consistent with the optimal regularity in the linear limit.

Keywords. Porous medium equation, entropy solutions, kinetic formulation, velocity averaging, regularity results

1. Introduction

We establish the optimal spatial regularity of solutions of the porous medium equation

$$\begin{aligned} \partial_t u &= \Delta(|u|^{m-1}u) \quad \text{on } (0, T) \times \mathbb{R}_x^d, \\ u(0) &= u_0 \quad \text{on } \mathbb{R}_x^d, \end{aligned} \quad (1.1)$$

with $u_0 \in L^1(\mathbb{R}_x^d)$, $T \geq 0$, $m > 1$.

All known regularity estimates in terms of Hölder or Sobolev spaces are restricted to differentiability order less than one. The best known regularity estimate in Sobolev spaces, obtained by Tadmor and Tao [33] and Ebmeyer [16], is that, if $u_0 \in (L^1 \cap L^\infty)(\mathbb{R}_x^d)$, then

$$u \in L^{m+1}([0, T]; W_{\text{loc}}^{\frac{2}{m+1}-, m+1}(\mathbb{R}_x^d)). \quad (1.2)$$

Since $\frac{2}{m+1} < 1$, this estimate is inconsistent with the optimal order of differentiability in the linear case of the heat equation ($m = 1$), which is $u \in L^1([0, T]; W^{2,1}(\mathbb{R}_x^d))$.

A scaling argument (cf. Appendix D below) shows that it may be possible to improve the regularity to $u \in L^m([0, T]; \dot{W}^{2/m, m}(\mathbb{R}_x^d))$, which is consistent with the linear case $m = 1$. The Barenblatt solution shows that this regularity is optimal. This is the main result of this paper.

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Theorem. *Let $u_0 \in (L^1 \cap L^{1+\varepsilon})(\mathbb{R}_x^d)$ for some $\varepsilon > 0$. Then, for all $p \in [1, m)$ and $s < 2/m$,*

$$u \in L^p([0, T]; \dot{W}_{\text{loc}}^{s,p}(\mathbb{R}_x^d)). \tag{1.3}$$

Moreover, there is a constant $C \geq 0$ such that

$$\|u\|_{L_t^p \dot{W}_{x,\text{loc}}^{s,p}} \leq C(\|u_0\|_{L_x^1 \cap L_x^{1+\varepsilon}}^2 + 1).$$

The precise statement is given in Theorem 3.4 below.

In addition, we treat more general classes of equations, in particular including anisotropic porous media equations of the form

$$\partial_t u = \sum_{j=1}^d \partial_{x_j x_j} u^{[m_j]} + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}_x^d, \tag{1.4}$$

with $u_0 \in L^1(\mathbb{R}_x^d)$, $S \in L^1([0, T] \times \mathbb{R}_x^d)$ and $u^{[m]} := |u|^{m-1}u$. Setting $1 < \underline{m} := \min m_j$, $\bar{m} := \max m_j$ we will show that, for all $s < \frac{2}{\underline{m}} \frac{\underline{m}-1}{\bar{m}-1}$ and $p < \frac{2\bar{m}}{\bar{m}+1}$,

$$\int_v f(t, x, v) \phi(v) dv \in L^p([0, T]; W_{\text{loc}}^{s,p}(\mathbb{R}_x^d))$$

where $f(t, x, v) := 1_{v < u(t,x)} - 1_{v < 0}$ and ϕ is an arbitrary cut-off function (see Theorem 2.7 below for details).

In a third main result, we consider the degenerate parabolic Anderson model

$$\begin{aligned} \partial_t u &= \partial_{xx} u^{[m]} + uS && \text{on } (0, T) \times I, \\ u &= 0 && \text{on } (0, T) \times \partial I, \\ u(0) &= u_0 \in L^{m+1}(I), \end{aligned} \tag{1.5}$$

on an open, bounded interval $I \subseteq \mathbb{R}$, with $m \in (1, 2)$ and S being spatial white noise. The additional difficulty in this case is the irregularity of the source S , since spatial white noise is a distribution only. We again obtain regularity consistent with the optimal regularity in the linear case ($m = 1$).

Theorem. *Let $u_0 \in L^{m+1}(I)$. Then there exists a weak solution u to (1.5) satisfying, for all $p \in [1, m)$ and $s < \frac{3}{2} \frac{1}{m}$,*

$$u \in L^p([0, T]; W_{\text{loc}}^{s,p}(I)). \tag{1.6}$$

Moreover, there is a constant $C \geq 0$ such that

$$\|u\|_{L_t^p W_{x,\text{loc}}^{s,p}} \leq C(\|u_0\|_{L_x^{m+1}}^{m+1} + \|S\|_{B_{\infty,\infty}^{-\eta}}^\tau + 1)$$

for some $\tau \geq 2$ and $\eta \in (1/2, 1]$ small enough.

The precise statement is given in Corollary 4.4 below.

The proof presented in this paper is based on Fourier analytic techniques and averaging lemmata. The first step is to pass to a kinetic formulation of (1.1). Introducing the kinetic function $f(t, x, v) := 1_{v < u(t, x)} - 1_{v < 0}$ leads to the kinetic form of (1.1),

$$\partial_t f = m|v|^{m-1} \Delta f + \partial_v q \quad (1.7)$$

for some non-negative measure q . Since this constitutes a linear equation in f , the regularity of the velocity averages $\int f \phi(v) dv$ for smooth cut-off functions ϕ can be analyzed by means of suitable microlocal decompositions in Fourier space. Up to this point our setup is in line with [33]. However, in the available literature, one of the drawbacks of analyzing regularity by means of averaging techniques is that it was unknown how to make use of the sign of the measure q . Indeed, these arguments were only able to use the fact that the total variation norm of q is finite (cf. e.g. [12, 13]). In contrast, in this work, we make use of the additional fact that the entropy dissipation measure q has finite singular moments, meaning that $|v|^{-\gamma} q$ has finite mass for all $\gamma \in [0, 1)$. In this way we are able to (indirectly) exploit the sign property of q for the first time.

In addition, classical averaging techniques are restricted to working in L^p spaces with $p \in [1, 2]$ (cf. [33, Averaging Lemma 2.1]), which leads to non-optimal integrability exponents. Indeed, because of this in [33, (4.10)] only $W^{\frac{2}{m+1}-1}$ regularity for solutions to (1.1) could be shown. In order to obtain the optimal integrability exponent $p < m$ we introduce a new concept of isotropic truncation properties for Fourier multipliers.

A further obstacle in classical averaging arguments is that they rely on a bootstrap technique. However, even if u is smooth, the kinetic function f will only have up to one spatial derivative. Therefore, the standard bootstrap argument is not suited to prove regularity of a higher (than one) order. In the anisotropic case, this difficulty is avoided in the current paper by directly exploiting the v -regularity of f . In the isotropic case these issues are overcome by introducing the isotropic truncation property mentioned above. In both cases this allows us to fully avoid bootstrapping arguments. In order to underline the differences and improvements with regard to [33] we follow the notation and structure of [33] as far as possible. While, as usual in the theory of averaging techniques, our proof also relies on a microlocal decomposition in Fourier space, the order of decomposition and real interpolation, the key Lemma A.3, the bootstrapping argument and the estimation of the entropy dissipation measure proceed differently, as outlined above.

1.1. Short overview of the literature

The study of regularity of solutions to porous media equations has a long history and we make no attempt to reproduce a complete account here. In the absence of external forces, the continuity of weak solutions to the porous medium equation has been first shown in general dimension by Caffarelli–Friedman [8]. This result has been subsequently generalized to the case of forced porous media equations by Sacks [31, 32], based on arguments developed by Caffarelli–Evans [7]. Further generalizations to more general classes of equations have been given by DiBenedetto [14] and Ziemer [36]. A detailed account of these developments may be found in Vázquez [34]. Hölder continuity of solutions to

the porous medium equation without force was first obtained by Caffarelli–Friedman [9] (see also [34, 35]), where it is shown that bounded solutions to porous media equations are spatially α -Hölder continuous with $\alpha = 1/m \in (0, 1)$. We note that in the linear limit $m \downarrow 1$ this does not recover the optimal Hölder regularity of the linear case. A generalization to a more general class of degenerate PDEs has been obtained by DiBenedetto–Friedman [15]. In the recent work [27], the assumptions on the forcing have been relaxed and quantitative estimates are obtained. In particular, it is shown that the Hölder exponent α is uniformly bounded away from 0 for $m \downarrow 1$. In the nice recent works [5, 6] continuity estimates for the porous medium equation and inhomogeneous generalizations thereof with measure-valued forcing have been derived.

A particular feature of the porous medium equation ($m > 1$) is the effect of finite speed of propagation and thus the occurrence of open interfaces. The regularity of the open interfaces has attracted a lot of attention in the literature: see e.g. Caffarelli–Friedman [9], Caffarelli–Vázquez–Wolansky [10], Koch [25] and the references therein.

In non-forced porous media equations also higher order regularity estimates have been obtained. In one spatial dimension Aronson–Vázquez [2] proved eventual C^∞ regularity of solutions. For recent progress in the general dimension case see Kienzler–Koch–Vázquez [24].

In terms of fractional Sobolev regularity of solutions to porous media equations, less is known. As mentioned above, Ebmeyer [16] and Tadmor–Tao [33] proved for non-forced porous media equations that

$$u \in L^{m+1}([0, T]; W_{\text{loc}}^{s, m+1}), \quad \forall s < \frac{2}{m+1}. \quad (1.8)$$

See also Appendix C for a slight improvement of these results. In the recent work [21], Gianazza–Schwarzacher proved higher integrability for non-negative, local weak solutions to forced porous media equations in terms of a bound on

$$\|u^{(m+1)/2}\|_{L_{\text{loc}}^{2+\varepsilon}((0, T); W_{\text{loc}}^{1, 2+\varepsilon})}$$

for all $\varepsilon > 0$ small enough. In the case of non-forced porous media equations, Aronson–Benilan type estimates can be used to derive further regularity properties. For example, in [34, Theorem 8.7] it has been shown that $\Delta u^m \in L_{\text{loc}}^1((0, \infty); L^1)$.

Extensions of [33] to stochastic parabolic-hyperbolic equations have been considered in [19].

1.2. Structure of the paper

In Section 2 we will consider the case of anisotropic, parabolic-hyperbolic second order PDEs. The proof of certain multiplier estimates will be postponed to Appendix A. In Section 3 we then treat the isotropic case in more detail, in particular introducing the concept of the isotropic truncation property for Fourier multipliers. We then deduce our main regularity estimates for forced porous media equations. In Section 4 we treat the case of the one-dimensional degenerate parabolic Anderson model. A slight improvement of the results obtained by Ebmeyer [16] is presented in Appendix C.

1.3. Notation

For $p \in [1, \infty)$ we let L^p be the usual Lebesgue space. The space of all locally finite Radon measures is denoted \mathcal{M} , and \mathcal{M}_{TV} is the subspace of all measures with finite total variation. We let $\mathcal{M}^+ \subseteq \mathcal{M}$ be the set of all non-negative, locally finite Radon measures, and $\mathcal{M}_{TV}^+ = \mathcal{M}_{TV} \cap \mathcal{M}^+$. When convenient, we will use the shorthand notation $L_x^1 = L^1(\mathbb{R}_x^d)$ and $L_{t,x}^1 = L^1([0, T] \times \mathbb{R}_x^d)$. For $p \geq 1$ let p' be its conjugate, that is, $1/p + 1/p' = 1$. We further let $H^{s,p}$ be the fractional Sobolev space defined via the Fourier transform, that is, as in [23, Definition 6.2.2], and $W^{s,p}$ be the fractional Sobolev–Slobodetskiĭ spaces (cf. [1, Section 7.35]). For $1 \leq p < \infty$, $s \in (0, \infty) \setminus \mathbb{N}$ and $f \in W_{loc}^{[s],1}(\mathbb{R}^d)$ let $\theta = s - [s] \in (0, 1)$, define the (homogeneous) Slobodetskiĭ semi-norm by

$$\|f\|_{\dot{W}^{s,p}} := \sup_{|\alpha|=[s]} \left(\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \frac{|D^\alpha f(x) - D^\alpha f(y)|^p}{|x - y|^{\theta p + d}} dx dy \right)^{1/p}$$

and set $\dot{W}^{s,p} := \{f \in W_{loc}^{[s],1}(\mathbb{R}^d) : \|f\|_{\dot{W}^{s,p}} < \infty\}$. For $f \in L_{loc}^1(\mathbb{R}^d)$ the total variation is given by

$$\|f\|_{\mathring{B}\dot{V}} := \sup \left\{ \int_{\mathbb{R}^d} f(x) \operatorname{div} \phi(x) dx : \phi \in C_c^1(\mathbb{R}^d; \mathbb{R}^d), \|\phi\|_{L^\infty(\mathbb{R}^d)} \leq 1 \right\}$$

and we set $\mathring{B}\dot{V} := \{f \in L_{loc}^1(\mathbb{R}^d) : \|f\|_{\mathring{B}\dot{V}} < \infty\}$. We follow the notation of [22, 23] and [3]: Let $\mathcal{N}^{s,p}(\mathbb{R}^d)$ be the Nikol’skiĭ space (see [29]) and $B_{p,q}^s$ the Besov space (see [22]). We further let $\tilde{L}_t^p B_{p,q}^s = \tilde{L}^p([0, T]; B_{p,q}^s(\mathbb{R}^d))$ denote the time-space non-homogeneous Besov space as in [3, Definition 2.67]. We define the discrete increment operator by $\Delta_e^h u := u(x + he) - u(x)$. For results and standard notations in interpolation theory we refer to [4]. We let $\mathcal{S}_+^{d \times d}$ denote the space of symmetric, non-negative definite matrices. For $b = (b_{i,j})_{i,j=1}^d \in \mathcal{S}_+^{d \times d}$ we set $\sigma = b^{1/2}$, that is, $b_{i,j} = \sum_{k=1}^d \sigma_{i,k} \sigma_{k,j}$. For a locally bounded function $b : \mathbb{R} \rightarrow \mathcal{S}_+^{d \times d}$ we let $\beta_{i,k}$ be such that $\beta_{i,k}'(v) = \sigma_{i,k}(v)$. Similarly, for $\psi \in C_c^\infty(\mathbb{R}_v)$ we let $\beta_{i,j}^\psi$ be such that $(\beta_{i,k}^\psi)'(v) = \psi(v) \sigma_{i,k}(v)$. We further introduce the kinetic function

$$\chi(u, v) := 1_{v < u} - 1_{v < 0}.$$

Analogously, for a function $u : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}$ we set $f(t, x, v) := \chi(u(t, x), v) := 1_{v < u(t,x)} - 1_{v < 0}$. We use the short-hand notation $|\xi| \sim 2^j$ for the set $\{\xi \in \mathbb{R} : 2^{j-1} \leq |\xi| \leq 2^{j+1}\}$. For $u \in \mathbb{R}$ we set $u^{[m]} := |u|^{m-1}u$. For $a, b \in \mathbb{R}_+ = [0, \infty)$ we write $a \lesssim b$ if there exists a constant $C > 0$ such that $a \leq Cb$.

2. Anisotropic case

We consider equations of the form

$$\begin{aligned} \partial_t f(t, x, v) + a(v) \cdot \nabla_x f(t, x, v) - \operatorname{div}(b(v) \nabla_x f(t, x, v)) \\ =: \mathcal{L}(\partial_t, \nabla_x, v) f(t, x, v) = g_0(t, x, v) + \partial_v g_1(t, x, v), \end{aligned} \tag{2.1}$$

where $a : \mathbb{R} \rightarrow \mathbb{R}^d$ and $b : \mathbb{R} \rightarrow \mathcal{S}_+^{d \times d}$ are C^1 . The operator \mathcal{L} is given by its symbol

$$\mathcal{L}(i\tau, i\xi, v) = i\tau + ia(v) \cdot \xi - (\xi, b(v)\xi). \tag{2.2}$$

In this section we will derive regularity estimates for the velocity average, for $\phi \in C_b^\infty(\mathbb{R}_v)$,

$$\bar{f}(t, x) := \int f(t, x, v)\phi(v) dv.$$

These regularity properties are obtained by using a suitable microlocal decomposition of f in Fourier space, which in turn relies on the so-called truncation property satisfied by the multiplier \mathcal{L} (see Appendix A). In contrast to previous results, we will make use of singular moments of g_1 , that is, for $\gamma \in (0, 1)$,

$$g_1(t, x, v)|v|^{-\gamma} \in \begin{cases} L^q(\mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v), & 1 < q \leq 2, \\ \mathcal{M}_{\text{TV}}(\mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v), & q = 1. \end{cases}$$

An additional difficulty arises in the use of bootstrapping arguments. In the theory of averaging lemmata, optimal regularity estimates are typically obtained by bootstrapping a first non-optimal regularity estimate. This argument, however, can only be applied if the aspired final order of regularity is less than 1. Therefore, we have to devise a proof which avoids the use of a bootstrapping argument. This is achieved in Appendix A by improving a fundamental L^p estimate on a class of Fourier multipliers by directly exploiting regularity of f in the velocity direction.

2.1. Anisotropic averaging lemma

Lemma 2.1. *Let $f \in L_{t,x}^p(H_v^{\sigma,p})$ for $1 < p \leq 2$ and $\sigma \in (0, 1)$ solve, in the sense of distributions,*

$$\mathcal{L}(\partial_t, \nabla_x, v)f(t, x, v) = \Delta_x^{\eta/2}g_0(t, x, v) + \partial_v \Delta_x^{\eta/2}g_1(t, x, v) \quad \text{on } \mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v \tag{2.3}$$

with g_i being locally bounded measures satisfying

$$|g_0|(t, x, v) + |g_1|(t, x, v)|v|^{-\gamma} \in \begin{cases} L^q(\mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v), & 1 < q \leq 2, \\ \mathcal{M}_{\text{TV}}(\mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v), & q = 1, \end{cases} \tag{2.4}$$

for some $\gamma \geq 0, \eta \geq 0, 1 \leq q \leq p$ and $\mathcal{L}(\partial_t, \nabla_x, v)$ as in (2.1) with symbol $\mathcal{L}(i\tau, i\xi, v)$ as in (2.2). Let $I \subseteq \mathbb{R}$ be a not necessarily finite interval, set

$$\omega_{\mathcal{L}}(J; \delta) := \sup_{\tau \in \mathbb{R}, \xi \in \mathbb{R}^d, |\xi| \sim J} |\Omega_{\mathcal{L}}(\tau, \xi; \delta)|, \quad \Omega_{\mathcal{L}}(\tau, \xi; \delta) = \{v \in I : |\mathcal{L}(i\tau, i\xi, v)| \leq \delta\},$$

and suppose that the following non-degeneracy condition holds: There exist $\alpha \in (0, q')$ and $\beta > 0$ such that

$$\omega_{\mathcal{L}}(J; \delta) \lesssim (\delta/J^\beta)^\alpha, \quad \forall \delta, J \geq 1. \tag{2.5}$$

Moreover, assume that there exist $\lambda \geq 0$ and $\mu \in [0, 1]$ such that, for all $\delta, J \geq 1$,

$$\sup_{\tau, |\xi| \sim J} \sup_{v \in \Omega_{\mathcal{L}}(\tau, \xi; \delta)} |\partial_v \mathcal{L}(i\tau, i\xi, v)| |v|^\gamma \lesssim J^\lambda \delta^\mu \tag{2.6}$$

and $\alpha\beta/q' \leq \lambda + \eta$. Then, for all $s \in [0, s^*)$, $\tilde{p} \in [1, p^*)$, $\phi \in C_b^\infty(I)$, $T \geq 0$ and $\mathcal{O} \subset\subset \mathbb{R}^d$, there is a $C \geq 0$ such that

$$\begin{aligned} \left\| \int f(t, x, v) \phi(v) dv \right\|_{L^{\tilde{p}}([0, T]; \dot{W}^{s, \tilde{p}}(\mathcal{O}))} &\leq C (\|g_0 \phi\|_{L_{t,x,v}^q} + \| |v|^{-\gamma} g_1 \phi \|_{L_{t,x,v}^q} + \|g_1 \phi'\|_{L_{t,x,v}^q} \\ &\quad + \|f \phi\|_{L_{t,x}^p(H_v^{\sigma,p})} + \|f \phi\|_{L_{t,x}^q L_v^1} + \|f \phi\|_{L_t^{\tilde{p}} L_{x,v}^1}) \end{aligned}$$

with $s^* := (1 - \theta)\alpha\beta/r + \theta(\alpha\beta/q' - \lambda - \eta)$, where $\theta = \theta_\alpha$ and p^* are given by

$$\theta := \frac{\alpha/r}{\alpha(1/r - 1/q') + 1} \in (0, 1), \quad \frac{1}{p^*} := \frac{1 - \theta}{p} + \frac{\theta}{q}, \quad r \in \left(\frac{p'}{1 + \sigma p'}, p' \right] \cap (1, \infty).$$

Proof. Let φ_0, φ_1 be smooth functions with φ_0 supported in $B_1(0)$ and φ_1 supported in the annulus $\{\xi \in \mathbb{R}^d : 1/2 \leq |\xi| \leq 2\}$ and

$$\varphi_0(\xi) + \sum_{j \in \mathbb{N}} \varphi_1(2^{-j}\xi) = 1, \quad \forall \xi \in \mathbb{R}^d.$$

By considering the decomposition $f = f_0 + f_1$ with

$$f_0 := \mathcal{F}_x^{-1}[\varphi_0(\xi) \mathcal{F}_x f], \quad f_1 := \sum_{j \in \mathbb{N}} \mathcal{F}_x^{-1}[\varphi_1(\xi/2^j) \mathcal{F}_x f],$$

we may assume without loss of generality that f has Fourier transform supported on $B_1(0)^c$, since for all $\eta \in [1, \infty)$,

$$\left\| \int f_0 \phi dv \right\|_{L_t^\eta \dot{W}_x^{s,\eta}} \leq \|f \phi\|_{L_t^\eta L_{x,v}^1}. \tag{2.7}$$

Partially inspired by [33, Averaging Lemma 2.3] we consider a microlocal decomposition of f with regard to the degeneracy of the operator $\mathcal{L}(\partial_t, \nabla_x, v)$. Let ψ_0, ψ_1 be smooth functions with ψ_0 supported in $B_1(0)$ and ψ_1 supported in the annulus $\{\xi \in \mathbb{C} : 1/2 \leq |\xi| \leq 2\}$ and

$$\psi_0(\xi) + \sum_{k \in \mathbb{N}} \psi_1(2^{-k}\xi) = 1, \quad \forall \xi \in \mathbb{C}.$$

For $\delta > 0$ to be specified later we write

$$f = \psi_0 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta} \right) f + \sum_{k \in \mathbb{N}} \psi_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) f =: f^0 + f^1,$$

where, for $k \in \mathbb{N} \cup \{0\}$,

$$\psi_i \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) := \mathcal{F}_{t,x}^{-1} \psi_i \left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k} \right) \mathcal{F}_{t,x}.$$

Since f solves (2.3), we have

$$\mathcal{L}(\partial_t, \nabla_x, v) f^1(t, x, v) = \sum_{k \in \mathbb{N}} \psi_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) (\Delta_x^{\eta/2} g_0(t, x, v) + \Delta_x^{\eta/2} \partial_v g_1(t, x, v)) \tag{2.8}$$

and thus

$$\begin{aligned} f^1(t, x, v) &= \sum_{k \in \mathbb{N}} \frac{1}{\delta 2^k} \tilde{\psi}_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) \Delta_x^{\eta/2} g_0(t, x, v) \\ &\quad + \sum_{k \in \mathbb{N}} \frac{1}{\delta 2^k} \tilde{\psi}_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) \Delta_x^{\eta/2} \partial_v g_1(t, x, v) \\ &=: f^2(t, x, v) + f^3(t, x, v), \end{aligned} \tag{2.9}$$

where

$$\tilde{\psi}(z) = \psi(z)/z.$$

In conclusion, we have arrived at the decomposition

$$\bar{f} := \int f \phi \, dv = \int f^0 \phi \, dv + \int f^2 \phi \, dv + \int f^3 \phi \, dv =: \bar{f}^0 + \bar{f}^2 + \bar{f}^3.$$

We aim to estimate the regularity of $\bar{f}^0, \bar{f}^2, \bar{f}^3$ in Besov spaces. Hence, we decompose each f^i into Littlewood–Paley pieces with respect to the x -variable. Let φ_0, φ_1 be as above. We set, for $i = 0, 2, 3$,

$$f_j^i := \mathcal{F}_x^{-1}[\varphi_1(\xi/2^j) \mathcal{F}_x f^i] \quad \text{for } j \in \mathbb{N}.$$

Then, since f^i has Fourier transform supported on $B_1(0)^c$,

$$f^i = \sum_{j \geq 1} f_j^i,$$

where $\hat{f}_j^i(\tau, \xi, v)$ is supported on frequencies $|\xi| \sim 2^j$.

Step 1: f^0

Fix $j \in \mathbb{N}$. Then by Lemma A.3, for every $r \in (\frac{p'}{1+\sigma p'}, p'] \cap (1, \infty)$,

$$\begin{aligned} \left\| \int f_j^0 \phi \, dv \right\|_{L_{t,x}^p} &\lesssim \|f_j^0 \phi\|_{L_{t,x}^p(H_v^{\sigma,p})} \sup_{\tau, |\xi| \sim 2^j} |\Omega \mathcal{L}(\tau, \xi, \delta)|^{1/r} \\ &\lesssim \|f \phi\|_{L_{t,x}^p(H_v^{\sigma,p})} (\delta/(2^j)^\beta)^{\alpha/r}. \end{aligned}$$

Hence, $\bar{f}^0 = \int f^0 \phi \, dv \in \tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r}$ (see [3, Definition 2.67]) with

$$\left\| \int f^0 \phi \, dv \right\|_{\tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r}} \lesssim \delta^{\alpha/r} \|f \phi\|_{L_x^p(H_v^{\sigma,p})}.$$

Step 2: f^2

Fix $j \in \mathbb{N}$. We set

$$\begin{aligned} f_j^{2,k} &= \frac{1}{\delta 2^k} \mathcal{F}_{t,x}^{-1} \varphi_1(\xi/2^j) \tilde{\psi}_1\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k}\right) |\xi|^\eta \mathcal{F}_{t,x} g_0(x, v) \\ &= \frac{1}{\delta 2^k} \mathcal{F}_{t,x}^{-1} \tilde{\psi}_1\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k}\right) |\xi|^\eta \mathcal{F}_{t,x} g_{0,j}(x, v). \end{aligned}$$

Hence,

$$\int f_j^{2,k} \phi \, dv = \frac{1}{\delta 2^k} \int \tilde{\psi}_1\left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k}\right) \Delta_x^{\eta/2} g_{0,j} \phi \, dv$$

and, by Lemma A.3 and since $|\xi|^\eta$ acts as a constant multiplier of order $(2^j)^\eta$ on $g_{0,j}$,

$$\begin{aligned} \left\| \int f_j^{2,k} \phi \, dv \right\|_{L_{t,x}^q} &\lesssim \frac{1}{\delta 2^k} \left\| \int \mathcal{F}_{t,x}^{-1} \tilde{\psi}_1\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k}\right) |\xi|^\eta \mathcal{F}_{t,x} g_{0,j} \phi \, dv \right\|_{L_{t,x}^q} \\ &\lesssim \frac{\sup_{\tau, |\xi| \sim 2^j} |\Omega(\tau, \xi, \delta 2^k)|^{1/q'}}{\delta 2^k} (2^j)^\eta \|g_{0,j} \phi\|_{L_{t,x,v}^q} \\ &\lesssim \frac{1}{\delta 2^k} \left(\frac{\delta 2^k}{(2^j)^\beta}\right)^{\alpha/q'} (2^j)^\eta \|g_{0,j} \phi\|_{L_{t,x,v}^q}. \end{aligned}$$

Hence,

$$\begin{aligned} \left\| \int f_j^2 \phi \, dv \right\|_{L_{t,x}^q} &\lesssim \sum_{k \in \mathbb{N}} \frac{1}{\delta 2^k} \left(\frac{\delta 2^k}{(2^j)^\beta}\right)^{\alpha/q'} (2^j)^\eta \|g_{0,j} \phi\|_{L_{t,x,v}^q} \\ &\lesssim \delta^{\alpha/q'-1} (2^j)^{\eta-\alpha\beta/q'} \|g_{0,j} \phi\|_{L_{t,x,v}^q}. \end{aligned}$$

In conclusion, $\int f^2 \phi \, dv \in \tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\eta}$ with

$$\left\| \int f^2 \phi \, dv \right\|_{\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\eta}} \lesssim \delta^{\alpha/q'-1} \|g_0 \phi\|_{L_{t,x,v}^q}.$$

Step 3: f^3

Fix $j \in \mathbb{N}$. We set

$$\begin{aligned} f_j^{3,k} &= \frac{1}{\delta 2^k} \mathcal{F}_{t,x}^{-1} \varphi_1(\xi/2^j) \tilde{\psi}_1\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k}\right) |\xi|^\eta \mathcal{F}_{t,x} \partial_v g_1(t, x, v) \\ &= \frac{1}{\delta 2^k} \mathcal{F}_{t,x}^{-1} \tilde{\psi}_1\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k}\right) |\xi|^\eta \mathcal{F}_{t,x} \partial_v g_{1,j}(t, x, v). \end{aligned}$$

Hence,

$$\int f_j^{3,k} \phi \, dv = \frac{1}{\delta 2^k} \int \tilde{\psi}_1\left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k}\right) \Delta_x^{\eta/2} \phi \partial_v g_{1,j} \, dv.$$

We observe

$$\begin{aligned}
 \int f_j^{3,k} \phi \, dv &= -\frac{1}{\delta 2^k} \int \partial_v \tilde{\psi}_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) \Delta_x^{\eta/2} g_{1,j} \phi \, dv \\
 &\quad - \frac{1}{\delta 2^k} \int \tilde{\psi}_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) \Delta_x^{\eta/2} g_{1,j} \phi' \, dv \\
 &= -\frac{1}{\delta 2^k} \int \mathcal{F}_{t,x}^{-1} \left(\tilde{\psi}'_1 \left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k} \right) \frac{\partial_v \mathcal{L}(i\tau, i\xi, v)}{\delta 2^k} |\xi|^\eta \mathcal{F}_{t,x} g_{1,j} \phi \right) dv \\
 &\quad - \frac{1}{\delta 2^k} \int \tilde{\psi}_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) \Delta_x^{\eta/2} g_{1,j} \phi' \, dv \\
 &= \frac{1}{(\delta 2^k)^2} \int \mathcal{F}_{t,x}^{-1} \left(\tilde{\psi}'_1 \left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k} \right) \partial_v \mathcal{L}(i\tau, i\xi, v) |v|^\gamma |\xi|^\eta \mathcal{F}_{t,x} |v|^{-\gamma} g_{1,j} \phi \right) dv \\
 &\quad - \frac{1}{\delta 2^k} \int \tilde{\psi}_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) \Delta_x^{\eta/2} g_{1,j} \phi' \, dv.
 \end{aligned}$$

By the Marcinkiewicz Multiplier Theorem (see [22, Theorem 5.2.4]) and (2.6) we find that $\partial_v \mathcal{L}(i\tau, i\xi, v) |v|^\gamma$ acts as a constant multiplier on L^q of order $O((2^j)^\lambda (\delta 2^k)^\mu)$ on $g_{1,j}$. Hence, using Lemma A.3 yields

$$\begin{aligned}
 &\left\| \int f_j^{3,k} \phi \, dv \right\|_{L_{t,x}^q} \\
 &\leq \frac{1}{(\delta 2^k)^2} \left\| \int \mathcal{F}_{t,x}^{-1} \tilde{\psi}'_1 \left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta 2^k} \right) (\partial_v \mathcal{L})(i\tau, i\xi, v) |v|^\gamma |\xi|^\eta \mathcal{F}_{t,x} |v|^{-\gamma} g_{1,j} \phi \, dv \right\|_{L_{t,x}^q} \\
 &\quad + \frac{1}{\delta 2^k} \left\| \int \tilde{\psi}_1 \left(\frac{\mathcal{L}(\partial_t, \nabla_x, v)}{\delta 2^k} \right) \Delta_x^{\eta/2} g_{1,j} \phi' \, dv \right\|_{L_{t,x}^q} \\
 &\lesssim \frac{\sup_{\tau, |\xi| \sim J} |\Omega(\tau, \xi, \delta 2^k)|^{1/q'}}{(\delta 2^k)^2} (2^j)^{\eta+\lambda} (\delta 2^k)^\mu \| |v|^{-\gamma} g_{1,j} \phi \, dv \|_{L_{t,x,v}^q} \\
 &\quad + \frac{\sup_{\tau, |\xi| \sim J} |\Omega(\tau, \xi, \delta 2^k)|^{1/q'}}{\delta 2^k} (2^j)^\eta \| g_{1,j} \phi' \|_{L_{t,x,v}^q} \\
 &\lesssim \frac{1}{(\delta 2^k)^2} \left(\frac{\delta 2^k}{(2^j)^\beta} \right)^{\alpha/q'} (2^j)^{\eta+\lambda} (\delta 2^k)^\mu \| |v|^{-\gamma} g_{1,j} \phi \|_{L_{t,x,v}^q} \\
 &\quad + \frac{1}{\delta 2^k} \left(\frac{\delta 2^k}{(2^j)^\beta} \right)^{\alpha/q'} (2^j)^\eta \| g_{1,j} \phi' \|_{L_{t,x,v}^q} \\
 &= (\delta 2^k)^{-2+\alpha/q'+\mu} (2^j)^{\eta+\lambda-\alpha\beta/q'} \| |v|^{-\gamma} g_{1,j} \phi \|_{L_{t,x,v}^q} \\
 &\quad + (\delta 2^k)^{-1+\alpha/q'} (2^j)^{\alpha\beta/q'+\eta} \| g_{1,j} \phi' \|_{L_{t,x,v}^q}.
 \end{aligned}$$

Hence, for $\delta \geq 1$ and using $\mu \in [0, 1]$, $\alpha < q'$,

$$\begin{aligned} \left\| \int f_j^3 \phi \, dv \right\|_{L_{t,x}^q} &\lesssim \sum_{k \in \mathbb{N}} (\delta 2^k)^{-2+\alpha/q'+\mu} (2^j)^{\eta+\lambda-\alpha\beta/q'} \| |v|^{-\gamma} g_{1,j} \phi \|_{L_{t,x,v}^q} \\ &\quad + (\delta 2^k)^{-1+\alpha/q'} (2^j)^{\alpha\beta/q'+\eta} \| g_{1,j} \phi' \|_{L_{t,x,v}^q} \\ &\lesssim \delta^{-2+\alpha/q'+\mu} (2^j)^{\eta+\lambda-\alpha\beta/q'} \| |v|^{-\gamma} g_{1,j} \phi \|_{L_{t,x,v}^q} + \delta^{-1+\alpha/q'} (2^j)^{\alpha\beta/q'+\eta} \| g_{1,j} \phi' \|_{L_{t,x,v}^q} \\ &\lesssim \delta^{-1+\alpha/q'} (2^j)^{\eta+\lambda-\alpha\beta/q'} (\| |v|^{-\gamma} g_{1,j} \phi \|_{L_{t,x,v}^q} + \| g_{1,j} \phi' \|_{L_{t,x,v}^q}). \end{aligned}$$

In conclusion, $\int f^3 \phi \, dv \in \tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}$ with

$$\left\| \int f^3 \phi \, dv \right\|_{\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}} \lesssim \delta^{-1+\alpha/q'} (\| |v|^{-\gamma} g_1 \phi \|_{L_{t,x,v}^q} + \| g_1 \phi' \|_{L_{t,x,v}^q}).$$

Step 4: Conclusion

Since $B_{q,\infty}^{\alpha\beta/q'-\eta} \hookrightarrow B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}$, we have

$$\bar{f} = \bar{f}^0 + \bar{f}^1$$

with $\bar{f}^0 \in \tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r}$, $\bar{f}^1 = \bar{f}^2 + \bar{f}^3 \in \tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}$ and, for $\delta \geq 1$,

$$\begin{aligned} \|\bar{f}^0\|_{\tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r}} &\lesssim \delta^{\alpha/r} \|f\phi\|_{L_{t,x}^p(H_v^{\sigma,p})}, \\ \|\bar{f}^1\|_{\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}} &\lesssim \delta^{\alpha/q'-1} (\|g_0\phi\|_{L_{t,x,v}^q} + \| |v|^{-\gamma} g_1 \phi \|_{L_{t,x,v}^q} + \|g_1\phi'\|_{L_{t,x,v}^q}). \end{aligned}$$

We aim to conclude by real interpolation. We set, for $z > 0$,

$$\begin{aligned} K(z, \bar{f}) &:= \inf \{ \|\bar{f}^1\|_{\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}} + z \|\bar{f}^0\|_{\tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r}} : \bar{f}^0 \in \tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r}, \\ &\quad \bar{f}^1 \in \tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}, \bar{f} = \bar{f}^0 + \bar{f}^1 \}. \end{aligned}$$

We first note the trivial estimate, since $\alpha\beta/q' - \lambda - \eta \leq 0$,

$$K(z, \bar{f}) \leq \|\bar{f}\|_{\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q'-\lambda-\eta}} \leq \|\bar{f}\|_{\tilde{L}_t^q L_x^q} \leq \|f\phi\|_{L_{t,x}^q L_v^1}, \quad \forall z > 0.$$

Hence, it is enough to consider $z \leq 1$ in the estimates below. By the above estimates we deduce that, for $\delta \geq 1$,

$$K(z, \bar{f}) \leq \delta^{\alpha/q'-1} (\|g_0\phi\|_{L_{t,x,v}^q} + \| |v|^{-\gamma} g_1 \phi \|_{L_{t,x,v}^q} + \|g_1\phi'\|_{L_{t,x,v}^q}) + z \delta^{\alpha/r} \|f\phi\|_{L_{t,x}^p(H_v^{\sigma,p})}.$$

We now equilibrate the first and the second term on the right hand side, that is, we set

$$\delta^{\alpha/q'-1} = z \delta^{\alpha/r}, \quad \text{which yields} \quad \delta = z^{-\frac{1}{\alpha(1/r-1/q')+1}} \geq 1.$$

Hence, with

$$\theta = \frac{1 - \alpha/q'}{\alpha(1/r - 1/q') + 1} = 1 - \frac{\alpha/r}{\alpha(1/r - 1/q') + 1}$$

we obtain, for $|z| \leq 1$,

$$K(z, \bar{f}) \leq z^\theta (\|g_0\phi\|_{L^q_{t,x,v}} + \||v|^{-\gamma} g_1\phi\|_{L^q_{t,x,v}} + \|g_1\phi'\|_{L^q_{t,x,v}} + \|f\phi\|_{L^p_{t,x}(H_v^{\sigma,p})}).$$

Note that $\theta \in (0, 1)$ since $\alpha < q'$. Consequently, for $\tau \in (0, \theta)$ and $\frac{1}{p^*} = \frac{1-\tau}{q} + \frac{\tau}{p}$,

$$\begin{aligned} \|\bar{f}\|^{p^*} &= \|(\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q' - \lambda - \eta}, \tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r})_{\tau, p\tau} \|^{p^*} = \|z^{-\tau} K(z, \bar{f})\|_{L^{p^*}_{t,x,v}(0,\infty)}^{p^*} \\ &= \|z^{-\tau} K(z, \bar{f})\|_{L^{p^*}_{t,x,v}(0,1)}^{p^*} + \|z^{-\tau} K(z, \bar{f})\|_{L^{p^*}_{t,x,v}(1,\infty)}^{p^*} \\ &\leq \|z^{\theta-\tau}\|_{L^{p^*}_{t,x,v}(0,1)}^{p^*} (\|g_0\phi\|_{L^q_{t,x,v}} + \||v|^{-\gamma} g_1\phi\|_{L^q_{t,x,v}} + \|g_1\phi'\|_{L^q_{t,x,v}} + \|f\phi\|_{L^p_{t,x}(H_v^{\sigma,p})})^{p^*} \\ &\quad + \|z^{-\tau}\|_{L^{p^*}_{t,x,v}(1,\infty)}^{p^*} \|f\phi\|_{L^q_{t,x} L^1_v}^{p^*} \\ &\lesssim \|g_0\phi\|_{L^q_{t,x,v}}^{p^*} + \||v|^{-\gamma} g_1\phi\|_{L^q_{t,x,v}}^{p^*} + \|g_1\phi'\|_{L^q_{t,x,v}}^{p^*} \\ &\quad + \|f\phi\|_{L^p_{t,x}(H_v^{\sigma,p})}^{p^*} + \|f\phi\|_{L^q_{t,x} L^1_v}^{p^*}. \end{aligned}$$

Let

$$s < s^* := (1 - \theta)(\alpha\beta/q' - \lambda - \eta) + \theta\alpha\beta/r.$$

From [3, p. 98] we recall that, for $\varepsilon > 0$,

$$\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q' - \lambda - \eta} \hookrightarrow \tilde{L}_t^q B_{q,1}^{\alpha\beta/q' - \lambda - \eta - \varepsilon} \hookrightarrow L_t^q B_{q,1}^{\alpha\beta/q' - \lambda - \eta - \varepsilon}$$

and analogously for $\tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r}$. Thus, using [4, Section 5.6 and Theorem 6.4.5] and choosing $\varepsilon > 0$ small enough yields

$$\begin{aligned} (\tilde{L}_t^q B_{q,\infty}^{\alpha\beta/q' - \lambda - \eta}, \tilde{L}_t^p B_{p,\infty}^{\alpha\beta/r})_{\tau, p\tau} &\hookrightarrow L^{p\tau}(B_{q,1}^{\alpha\beta/q' - \lambda - \eta - \varepsilon}, B_{p,1}^{\alpha\beta/r - \varepsilon})_{\tau, p\tau} \\ &\hookrightarrow L_t^{p\tau} B_{p\tau, p\tau}^s \hookrightarrow L_t^{p\tau} W_x^{s, p\tau}. \end{aligned}$$

Hence, choosing $\tau \in (0, \theta)$ large enough and recalling (2.7), for all $p < p^*$ with $\frac{1}{p^*} = \frac{1-\theta}{q} + \frac{\theta}{p}$ and all $\mathcal{O} \subset \mathbb{R}^d$ compact, we have

$$\begin{aligned} \|\bar{f}\|_{L^p([0,T]; \dot{W}^{s,p}(\mathcal{O}))} &\lesssim \|g_0\phi\|_{L^q_{t,x,v}} + \||v|^{-\gamma} g_1\phi\|_{L^q_{t,x,v}} + \|g_1\phi'\|_{L^q_{t,x,v}} \\ &\quad + \|f\phi\|_{L^p_{t,x}(H_v^{\sigma,p})} + \|f\phi\|_{L^q_{t,x} L^1_v} + \|f\phi\|_{L^p_{t,x} L^1_v}. \quad \square \end{aligned}$$

Remark 2.2. In the above averaging lemma we do not require ϕ to have compact support, nor I to be a bounded interval. We note that if I and $\text{supp } \phi$ are unbounded, then the non-degeneracy condition (2.5) entails a growth condition on $\mathcal{L}(i\tau, i\xi, v)$.

This becomes clear when looking at specific examples, such as porous media equations with non-linearity $B(u)$, which in kinetic form corresponds to (2.1) with $a \equiv 0$, $b(v) = B'(v) \text{Id}$. In this case, $|\mathcal{L}(i\tau, i\xi, v)| \geq |\xi|^2 b(v)$ and thus

$$\begin{aligned} \omega_{\mathcal{L}}(J; \delta) &= \sup_{\tau, |\xi| \sim J} |\{v \in \text{supp } \phi : |\mathcal{L}(i\tau, i\xi, v)| \leq \delta\}| \\ &\leq \sup_{|\xi| \sim J} |\{v \in \text{supp } \phi : |b(v)| \leq \delta|\xi|^{-2}\}| \leq |b^{-1}(B_{\delta|J|^{-2}}(0)) \cap \text{supp } \phi|. \end{aligned}$$

Hence, if $\text{supp } \phi = \mathbb{R}$ condition (2.5) becomes, roughly speaking, $|b^{-1}(B_r(0))| \lesssim r^\alpha$ for all $r > 0$.

2.2. Anisotropic parabolic-hyperbolic equations

In this section we consider parabolic-hyperbolic equations of the type

$$\begin{aligned} \partial_t u + \text{div } A(u) &= \text{div}(b(u)\nabla u) + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}_x^d, \\ u(0) &= u_0 \quad \text{on } \mathbb{R}_x^d, \end{aligned} \tag{2.10}$$

where

$$\begin{aligned} u_0 &\in L^1(\mathbb{R}_x^d), \quad S \in L^1([0, T] \times \mathbb{R}_x^d), \quad T \geq 0, \\ a &:= A' \in C(\mathbb{R}; \mathbb{R}^d) \cap C^1(\mathbb{R} \setminus \{0\}; \mathbb{R}^d), \\ b &= (b_{jk})_{j,k=1}^d \in C(\mathbb{R}; \mathcal{S}_+^{d \times d}) \cap C^1(\mathbb{R} \setminus \{0\}; \mathcal{S}_+^{d \times d}). \end{aligned} \tag{2.11}$$

The corresponding kinetic form for

$$f(t, x, v) = \chi(u(t, x), v) \tag{2.12}$$

reads (see [11])

$$\begin{aligned} \mathcal{L}(\partial_t, \nabla_x, v)f(t, x, v) &= \partial_t f + a(v) \cdot \nabla_x f - \text{div}(b(v)\nabla_x f) \\ &= \partial_v q + S(t, x)\delta_{u(t,x)=v}(v), \end{aligned} \tag{2.13}$$

where $q \in \mathcal{M}^+$ and \mathcal{L} is identified with the symbol

$$\mathcal{L}(i\tau, i\xi, v) := i\tau + a(v) \cdot i\xi - (b(v)\xi, \xi). \tag{2.14}$$

We will use the terms kinetic solution and entropy solution synonymously. From [11] we recall the definition of entropy/kinetic solutions to (2.10).

Definition 2.3. We say that $u \in C([0, T]; L^1(\mathbb{R}^d))$ is an *entropy solution* to (2.10) if $f = \chi(u)$ satisfies:

- (i) For any non-negative $\psi \in \mathcal{D}(\mathbb{R})$ and $k = 1, \dots, d$,

$$\sum_{i=1}^d \partial_{x_i} \beta_{i_k}^\psi(u) \in L^2([0, T] \times \mathbb{R}^d).$$

(ii) For any non-negative functions $\psi_1, \psi_2 \in \mathcal{D}(\mathbb{R})$ and $k = 1, \dots, d$,

$$\sqrt{\psi_1(u(t, x))} \sum_{i=1}^d \partial_{x_i} \beta_{ik}^{\psi_2}(u(t, x)) = \sum_{i=1}^d \partial_{x_i} \beta_{ik}^{\psi_1 \psi_2}(u(t, x)) \quad \text{a.e.}$$

(iii) There are non-negative measures $m, n \in \mathcal{M}^+$ such that, in the sense of distributions,

$$\partial_t f + a(v) \cdot \nabla_x f - \operatorname{div}(b(v) \nabla_x f) = \partial_v(m + n) + \delta_{v=u(t, x)} S \quad \text{on } (0, T) \times \mathbb{R}_x^d \times \mathbb{R}_v$$

where n is defined by

$$\int \psi(v) n(t, x, v) dv = \sum_{k=1}^d \left(\sum_{i=1}^d \partial_{x_i} \beta_{ik}^{\psi}(u(t, x)) \right)^2$$

for any $\psi \in \mathcal{D}(\mathbb{R})$ with $\psi \geq 0$.

(iv) We have

$$\int (m + n) dx dt \leq \mu(v) \in L_0^\infty(\mathbb{R}),$$

where L_0^∞ is the space of L^∞ -functions vanishing for $|v| \rightarrow \infty$.

A sketch of the proof of well-posedness of entropy solutions is given in Appendix B. For notational convenience we set $q = m + n$ in the following. We first establish the following a priori bound .

Lemma 2.4. *Let u be the unique entropy solution to (2.10) with $u_0 \in (L^1 \cap L^{2-\gamma})(\mathbb{R}_x^d)$ and $S \in (L^1 \cap L^{2-\gamma})([0, T] \times \mathbb{R}_x^d)$ for some $\gamma \in (-\infty, 1)$. Then there is a constant $C = C(T, \gamma) \geq 0$ such that*

$$\sup_{t \in [0, T]} \|u(t)\|_{L_x^{2-\gamma}}^{2-\gamma} + (1 - \gamma) \int_0^T \int_{\mathbb{R}^{d+1}} |v|^{-\gamma} q dv dx dr \leq C(\|u_0\|_{L_x^{2-\gamma}}^{2-\gamma} + \|S\|_{L_{t,x}^{2-\gamma}}^{2-\gamma}). \quad (2.15)$$

Moreover, for $\eta \in C_c^\infty(\mathbb{R}_v)$ and $t \in [0, T]$ we have

$$\int_{\mathbb{R}_x^d} \eta(u(t)) dx + \int_0^t \int_{\mathbb{R}^{d+1}} \eta''(v) q dv dx dr \leq \int_{\mathbb{R}_x^d} \eta(u_0) dx + \|\eta'\|_{L_v^\infty} \|S\|_{L_{t,x}^1}. \quad (2.16)$$

Proof. By (B.4) below we have $u \in L^\infty([0, T]; L^{2-\gamma}(\mathbb{R}_x^d))$. Let $\eta \in C_c^\infty(\mathbb{R}_v)$ with $\eta(0) = 0$, $t \in [0, T]$, and let $\varphi^n \in C_c^\infty((0, T) \times \mathbb{R}_x^d)$ be a sequence of cut-off functions satisfying $\varphi^n = 1$ on $(1/n, t - 1/n) \times B_n(0)$. Testing (2.13) with $\eta'(v)\varphi^n(r, x)$ yields

$$\begin{aligned} & - \int_0^t \int \eta(u) \partial_r \varphi^n dx dr \\ & = \int_0^t \int \left(\eta'(v) a(v) f \cdot \nabla_x \varphi^n + \sum_{i,j=1}^d \eta'(v) b_{ij}(v) f \partial_{x_i x_j} \varphi^n \right) dv dx dr \\ & \quad + \int_0^t \int \eta'(u) \varphi^n S dx dr - \int_0^t \int \eta''(v) \varphi^n q dv dx dr. \end{aligned}$$

Taking the limit $n \rightarrow \infty$ yields

$$\int \eta(u(t)) \, dx = \int \eta(u_0) \, dx + \int_0^t \int \eta'(u) S \, dx \, dr - \int_0^t \int \eta''(v) q \, dv \, dx \, dr$$

and thus (2.16). Hölder’s inequality implies

$$\begin{aligned} \int \eta(u(t)) \, dx &\lesssim \int \eta(u_0) \, dx + \int_0^t \int |\eta'(u)|^{\frac{2-\gamma}{1-\gamma}} \, dx \, dr + \int_0^t \int |S|^{2-\gamma} \, dx \, dr \\ &\quad - \int_0^t \int \eta''(v) q \, dv \, dx \, dr. \end{aligned}$$

Using a standard cut-off argument we may choose $\eta = \eta^\delta \in C^\infty$ with

$$(\eta^\delta)''(v) := (|v|^2 + \delta)^{-\gamma/2}.$$

Then η^δ is convex and $(\eta^\delta)'(v) \leq |v|^{1-\gamma}$. Hence,

$$\begin{aligned} \int \eta^\delta(u(t)) \, dx + \int_0^t \int (\eta^\delta)''(v) q \, dv \, dx \, dr &\lesssim \int \eta^\delta(u_0) \, dx + \int_0^t \int |u|^{2-\gamma} \, dx \, dr \\ &\quad + \int_0^t \int |S|^{2-\gamma} \, dx \, dr. \end{aligned}$$

Letting $\delta \rightarrow 0$ yields, by Fatou’s Lemma,

$$\begin{aligned} \int |u(t)|^{2-\gamma} \, dx + \int_0^t \int |v|^{-\gamma} q \, dv \, dx \, dr &\lesssim \int |u_0|^{2-\gamma} \, dx + \int_0^t \int |u|^{2-\gamma} \, dx \, dr \\ &\quad + \int_0^t \int |S|^{2-\gamma} \, dx \, dr. \end{aligned}$$

Gronwall’s inequality concludes the proof. □

Lemma 2.5. *Let u be the unique entropy solution to (2.10) and $\psi \in C^2(\mathbb{R}) \cap \text{Lip}(\mathbb{R})$ be a convex function with $|\psi(r)| \leq c|r|$ for some $c > 0$. Then*

$$\int q(t, x, v) \psi''(v) \, dv \, dx \, dt \leq C(\|u_0\|_{L^1_x} + \|S\|_{L^1_{t,x}}),$$

for some constant C depending only on c and $\sup_v |\psi'(v)|$.

Proof. We first note that multiplying (2.13) by a smooth approximation of $\text{sgn}(v)$, integrating and taking the limit yields, for all $t \geq 0$,

$$\int |u(t, x)| \, dx \leq \int |u(0, x)| + \|S\|_{L^1([0, T] \times \mathbb{R}^d)}.$$

From (2.13) and a standard cut-off argument we further obtain

$$\begin{aligned} \partial_t \int \psi(u(t, x)) \, dx &= \partial_t \int f(t, x, v) \psi'(v) \, dv \, dx \\ &\leq - \int \psi''(v) q(t, x, v) \, dv \, dx + \int S(t, x) \psi'(u(t, x)) \, dx. \end{aligned}$$

Hence,

$$\begin{aligned} & \int_0^T \int \psi''(v)q(t, x, v) dv dx dt \\ & \leq - \int \psi(u(\cdot, x)) dx \Big|_0^T + \int_0^T \int S(r, x)\psi'(u(r, x)) dx dr \\ & \leq c \int |u(0, x)| dx + c \int |u(T, x)| dx + C \|S\|_{L^1_{t,x}} \leq C(\|u_0\|_{L^1_x} + \|S\|_{L^1_{t,x}}). \quad \square \end{aligned}$$

We may now apply Lemma 2.1 to obtain

Corollary 2.6. *Let $u_0 \in L^1(\mathbb{R}_x^d)$, $S \in L^1([0, T] \times \mathbb{R}_x^d)$, a, b satisfy (2.11) and let u be the entropy solution to (2.10). Further assume that the symbol \mathcal{L} defined in (2.14) satisfies (2.5) and (2.6) for all $\gamma \in [0, 1)$ large enough. Then, for all*

$$s \in \left[0, \frac{\alpha}{\alpha + 1}(\beta - \lambda)\right), \quad p \in \left[1, \frac{2\alpha + 2}{2\alpha + 1}\right),$$

all $\phi \in C_c^\infty(\mathbb{R}_v)$, $\gamma \in [0, 1)$ large enough and $\mathcal{O} \subset\subset \mathbb{R}^d$, there is a constant $C \geq 0$ such that

$$\left\| \int f\phi dv \right\|_{L^p([0, T]; W^{s,p}(\mathcal{O}))} \leq C(\|u_0\|_{L^1_x} + \|u_0\|_{L^{2-\gamma}_x}^{2-\gamma} + \|S\|_{L^1_{t,x}} + \|S\|_{L^{2-\gamma}_{t,x}}^{2-\gamma} + 1). \tag{2.17}$$

Proof. We will derive (2.17) at the level of the approximating equation (B.5). By convergence of the approximating solutions u^ε and lower semicontinuity of the norm, this is sufficient. For notational simplicity we suppress the ε -dependency in the following, but note that all estimates are uniform with respect to these parameters. As in [11, Section 7] we get the bound (uniformly in ε), for each $\psi \in C_c^\infty(\mathbb{R}_v)$, $k = 1, \dots, d$,

$$\left\| \sum_{i=1}^d \partial_{x_i} \beta_{ik}^\psi(u) \right\|_{L^2_{t,x}} \lesssim \|u_0\|_{L^1_x} + \|S\|_{L^1_{t,x}} + 1.$$

We hence estimate, for any $\varphi \in C_c^\infty(\mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v)$ and $\psi \in C_c^\infty(\mathbb{R}_v)$ such that $\varphi\psi = \varphi$,

$$\begin{aligned} \int_{t,x,v} |\nabla f \cdot b(v)\nabla\varphi| & \leq \sum_{k=1}^d \int_{t,x,v} \left| \left(\sum_{i=1}^d \partial_{x_i} f \sigma_{ik}(v) \right) \left(\sum_{j=1}^d \sigma_{kj}(v) \partial_{x_j} \varphi \right) \right| \\ & = \sum_{k=1}^d \int_{t,x,v} \left| \left(\sum_{i=1}^d \delta_{u(t,x)=v} \partial_{x_i} u \sigma_{ik}(v) \psi(v) \right) \left(\sum_{j=1}^d \sigma_{kj}(v) \partial_{x_j} \varphi \right) \right| \\ & = \sum_{k=1}^d \int_{t,x} \left| \left(\sum_{i=1}^d \partial_{x_i} \beta_{ik}^\psi(u) \right) \left(\sum_{j=1}^d \sigma_{kj}(u) (\partial_{x_j} \varphi)(t, x, u(t, x)) \right) \right| \\ & \leq \sum_{k=1}^d \left\| \sum_{i=1}^d \partial_{x_i} \beta_{ik}^\psi(u) \right\|_{L^2_{t,x}} \left\| \sum_{j=1}^d \sigma_{kj}(u) (\partial_{x_j} \varphi)(t, x, u(t, x)) \right\|_{L^2_{t,x}} \\ & \lesssim \|u_0\|_{L^1_x} + \|S\|_{L^1_{t,x}} + 1. \end{aligned} \tag{2.18}$$

We next note that due to (2.12) we have $\partial_v f(t, x, v) = \delta_{v=0} - \delta_{u(t,x)=v}$ and thus $f \in L_{t,x}^\infty(\mathbf{B}\dot{\mathbf{V}}_v) \subseteq L_{t,x;\text{loc}}^1(\mathbf{B}\dot{\mathbf{V}}_v)$ with $\|f\|_{L_{t,x}^\infty(\mathbf{B}\dot{\mathbf{V}}_v)} \leq 2$. Moreover, by (B.4),

$$\|f\|_{L_{t,x,v}^1} \lesssim \|u_0\|_{L_x^1} + \|S\|_{L_{t,x}^1} \tag{2.19}$$

and $|f| \leq 1$. Hence, $f \in L_{t,x,v}^1 \cap L_{t,x,v}^\infty$ and, for all $\sigma \in [0, 1/2)$,

$$\begin{aligned} \|f\|_{L_{t,x;\text{loc}}^2(B_{2,\infty}^\sigma(\mathbb{R}_v))}^2 &= \|f\|_{L_{t,x;\text{loc}}^2(L_v^2)}^2 + \left\| \sup_{\delta>0} \sup_{0<|h|<\delta} \int_{\mathbb{R}} \frac{|f(t, x, v+h) - f(t, x, v)|^2}{|h|^{2\sigma}} dv \right\|_{L_{t,x;\text{loc}}^2}^2 \\ &\lesssim \|f\|_{L_{t,x;\text{loc}}^1(L_v^1)} + \left\| \sup_{\delta>0} \sup_{0<|h|<\delta} \int_{\mathbb{R}} \frac{|f(t, x, v+h) - f(t, x, v)|}{|h|^{2\sigma}} dv \right\|_{L_{t,x;\text{loc}}^2}^2 \\ &\lesssim \|u_0\|_{L_x^1} + \|S\|_{L_{t,x}^1} + \|f(t, x, \cdot)\|_{\mathbf{B}\dot{\mathbf{V}}_v} \|L_{t,x;\text{loc}}^2\| \\ &\lesssim \|u_0\|_{L_x^1} + \|S\|_{L_{t,x}^1} + 1, \end{aligned}$$

which implies, for all $\sigma \in [0, 1/2)$,

$$\|f\|_{L_{t,x;\text{loc}}^2(H_v^{\sigma,2})} \lesssim 1 + \|u_0\|_{L_x^1} + \|S\|_{L_{t,x}^1}. \tag{2.20}$$

In order to apply Lemma 2.1 we have to localize f . Let $\varphi \in C_c^\infty((0, T) \times \mathbb{R}_x^d \times \mathbb{R}_v)$, let $\eta^\delta \in C^\infty(\mathbb{R})$ satisfy $\eta^\delta(v) \in [0, 1]$ for all $v \in \mathbb{R}$, $|(\eta^\delta)'| \lesssim 1/\delta$,

$$\eta^\delta(v) = \begin{cases} 1 & \text{for } |v| \geq \delta, \\ 0 & \text{for } |v| \leq \delta/2, \end{cases} \tag{2.21}$$

and set $\varphi^\delta = \varphi \eta^\delta$. For simplicity we suppress the δ -index in the following. Set $\tilde{f} := \varphi f \in L_{t,x}^2(W_v^{\sigma,2})$ and $\tilde{q} := \varphi q$. Then

$$\begin{aligned} \partial_t \tilde{f} &= \varphi(-a(v) \cdot \nabla f + \text{div}(b(v)\nabla f) + \partial_v q + S\delta_{u(t,x)=v}(v)) + f \partial_t \varphi \\ &= -a(v) \cdot \nabla \tilde{f} + \text{div}(b(v)\nabla \tilde{f}) + \partial_v \tilde{q} + \varphi S\delta_{u(t,x)=v}(v) \\ &\quad + a(v) \cdot f \nabla \varphi - 2\nabla f \cdot b(v)\nabla \varphi - f \text{div}(b(v)\nabla \varphi) - (\partial_v \varphi)q + f \partial_t \varphi. \end{aligned} \tag{2.22}$$

Since φ is compactly supported and $q \in \mathcal{M}$, we have $\tilde{q} \in \mathcal{M}_{\text{TV}}$. Moreover, due to (2.18) and $S \in L_{t,x}^1$ we have

$$\begin{aligned} g_0 &:= \varphi S\delta_{u(t,x)=v}(v) + a(v) \cdot f \nabla \varphi - 2\nabla f \cdot b(v)\nabla \varphi - f \text{div}(b(v)\nabla \varphi) \\ &\quad - (\partial_v \varphi)q + f \partial_t \varphi \in \mathcal{M}_{\text{TV}} \end{aligned}$$

with

$$\|g_0\|_{\mathcal{M}_{\text{TV}}} \leq \|u_0\|_{L_x^1} + \|S\|_{L_{t,x}^1} + \|\partial_v \varphi q\|_{\mathcal{M}_{\text{TV}}} + \|f \phi \partial_t \varphi\|_{L_{t,x,v}^1}. \tag{2.23}$$

Let $s \in [0, \frac{\alpha}{\alpha+1}(\beta - \lambda))$ and $p \in [1, \frac{2\alpha+2}{2\alpha+1})$. Choose $\gamma \in [0, 1)$ large enough and $r > 1$ small enough, such that $s < (1 - \theta)\alpha\beta/r - \lambda\theta$ and $p < \frac{2}{1+\theta}$ where $\theta = \frac{\alpha/r}{\alpha/r+1}$. We may assume $u_0 \in L_x^1 \cap L_x^{2-\gamma}$ and $S \in L_{t,x}^1 \cap L_{t,x}^{2-\gamma}$, otherwise there is nothing to show. By Lemma 2.4 we have

$$\|u(t)\|_{L_x^{2-\gamma}}^{2-\gamma} + (1 - \gamma) \int_0^t \int_{\mathbb{R}^{d+1}} |v|^{-\gamma} q \, dv \, dx \, dr \lesssim \|u_0\|_{L_x^{2-\gamma}}^{2-\gamma} + \|S\|_{L_{t,x}^{2-\gamma}}^{2-\gamma}.$$

We note that due to (2.21) and (2.11) we may assume $a, b \in C^1$ without changing (2.22). We now apply Lemma 2.1 with $\eta = 0, g_1 = \tilde{q}, f = \tilde{f}, q = 1, p = 2, \sigma \in (0, 1/2)$ large enough, $T \geq 0, \mathcal{O} \subseteq \mathbb{R}^d$ compact to deduce that there is a constant $C \geq 0$ such that

$$\begin{aligned} \left\| \int f \varphi^\delta \phi \, dv \right\|_{L^p([0,T]; \dot{W}^{s,p}(\mathcal{O}))} &\lesssim \|g_0^\delta \phi\|_{\mathcal{M}_{TV}} + \||v|^{-\gamma} g_1^\delta \phi\|_{\mathcal{M}_{TV}} + \|g_1^\delta \phi'\|_{\mathcal{M}_{TV}} \\ &\quad + \|f \phi\|_{L_{t,x}^p(H_v^{\sigma,p})} + \|f \phi\|_{L_{t,x,v}^1} + \|f \phi\|_{L_t^p L_{x,v}^1}. \end{aligned}$$

Noting that

$$\|f \phi\|_{L_t^p L_{x,v}^1} \lesssim \|u\|_{L_t^p L_x^1} \lesssim \|u_0\|_{L_x^1},$$

by Lemma 2.4, (2.20), (2.19) and (2.23) we obtain

$$\begin{aligned} \left\| \int f \varphi^\delta \phi \, dv \right\|_{L^p([0,T]; \dot{W}^{s,p}(\mathcal{O}))} &\lesssim \|u_0\|_{L_x^1} + \|S\|_{L_{t,x}^1} + \|\partial_v \varphi q\|_{\mathcal{M}_{TV}} + \|f \phi \partial_t \varphi\|_{L_{t,x,v}^1} \\ &\quad + \|u_0\|_{L_x^{2-\gamma}}^{2-\gamma} + \|S\|_{L_{t,x}^{2-\gamma}}^{2-\gamma} + 1. \end{aligned}$$

We next consider the limit $\delta \rightarrow 0$. Since $|\eta^\delta| \leq 1$, the only non-trivial term appearing on the right hand side is $\|(\partial_v \eta^\delta) \varphi q\|_{\mathcal{M}_{TV}}$. Let ψ^δ be such that $(\psi^\delta)'' = |\partial_v \eta^\delta|$ and $|\psi^\delta(r)| \leq c|r|$. Then ψ^δ satisfies the assumptions of Lemma 2.5 uniformly in δ , which yields the required bound. Since φ is arbitrary, we conclude

$$\left\| \int f \phi \, dv \right\|_{L^p([0,T]; \dot{W}^{s,p}(\mathcal{O}))} \lesssim \|u_0\|_{L_x^1} + \|u_0\|_{L_x^{2-\gamma}}^{2-\gamma} + \|S\|_{L_{t,x}^1} + \|S\|_{L_{t,x}^{2-\gamma}}^{2-\gamma} + 1.$$

Since ϕ is compactly supported, we have $\|\int f \phi \, dv\|_{L_{t,x}^\infty} \lesssim 1$, concluding the proof. \square

Theorem 2.7. *Let $u_0 \in L^1(\mathbb{R}_x^d), S \in L^1([0, T] \times \mathbb{R}_x^d), m_j, n_j \geq 1, j = 1, \dots, d$, and let u be the entropy solution to*

$$\begin{aligned} \partial_t u + \sum_{j=1}^d \partial_{x_j} u^{n_j} &= \sum_{j=1}^d \partial_{x_j x_j}^2 u^{[m_j]} + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}^d, \\ u(0) &= u_0 \quad \text{on } \mathbb{R}^d. \end{aligned} \tag{2.24}$$

Set $\underline{m} = \min(\{m_j : j = 1, \dots, d\})$, $\bar{m} = \max(\{m_j : j = 1, \dots, d\})$ and analogously for \underline{n} , \bar{n} . Then, for all

$$s \in \left[1, \frac{2}{\underline{m}} \frac{\underline{m} \wedge \underline{n} - 1}{\bar{m} - 1}\right), \quad p \in \left[1, \frac{2\bar{m}}{1 + \bar{m}}\right),$$

all $\phi \in C_c^\infty(\mathbb{R}_v)$, $\gamma \in [0, 1)$ large enough and $\mathcal{O} \subset\subset \mathbb{R}^d$, there is a constant $C \geq 0$ such that

$$\left\| \int f \phi \, dv \right\|_{L^p([0, T]; W^{s, p}(\mathcal{O}))} \leq C(\|u_0\|_{L_x^1} + \|u_0\|_{L_x^{2-\gamma}}^{2-\gamma} + \|S\|_{L_{t,x}^1} + \|S\|_{L_{t,x}^{2-\gamma}}^{2-\gamma} + 1). \quad (2.25)$$

As a special case, for $m_j = n_j = m$, $j = 1, \dots, d$, we obtain (2.25) for all

$$s \in [0, 2/m), \quad p \in \left[1, 2\frac{m}{m+1}\right).$$

Proof. We have

$$\begin{aligned} \mathcal{L}(i\tau, i\xi, v) &= i\tau + i \sum_{j=1}^d n_j v^{n_j-1} \xi_j - \sum_{j=1}^d m_j |v|^{m_j-1} |\xi_j|^2 \\ &=: \mathcal{L}_{\text{hyp}}(i\tau, i\xi, v) + \mathcal{L}_{\text{par}}(\xi, v). \end{aligned}$$

Let $I \subseteq \mathbb{R}$ be a bounded set. Then, for $|\xi| \sim J$,

$$\begin{aligned} \Omega_{\mathcal{L}}(\tau, \xi; \delta) &= \{v \in I : |\mathcal{L}(i\tau, i\xi, v)| \leq \delta\} \\ &\subseteq \Omega_{\mathcal{L}_{\text{par}}}(\xi; \delta) = \left\{v \in I : \sum_{j=1}^d m_j |v|^{m_j-1} |\xi_j|^2 \leq \delta\right\} \\ &\subseteq \{v \in I : |v|^{\bar{m}-1} J^2 \lesssim \delta\}. \end{aligned} \quad (2.26)$$

Thus,

$$|\Omega_{\mathcal{L}}(\tau, \xi; \delta)| \lesssim (\delta/J^2)^{\frac{1}{\bar{m}-1}},$$

i.e. (2.5) is satisfied with $\beta = 2$, $\alpha = \frac{1}{\bar{m}-1}$. Moreover, due to (2.26), for $|\xi| \sim J$ and $v \in \Omega_{\mathcal{L}}(\tau, \xi; \delta) \setminus \{0\}$,

$$\begin{aligned} |\partial_v \mathcal{L}(i\tau, i\xi, v)| |v|^\gamma &= \left| i \sum_{j=1}^d n_j (n_j - 1) v^{n_j-2} \xi_j - \sum_{j=1}^d m_j (m_j - 1) v^{[m_j-2]} |\xi_j|^2 \right| |v|^\gamma \\ &\lesssim |v|^{\underline{n}-2+\gamma} J + |v|^{\underline{m}-2+\gamma} J^2 \\ &\lesssim \delta^{\frac{n-2+\gamma}{\bar{m}-1}} J^{-\frac{2(n-2+\gamma)}{\bar{m}-1}+1} + \delta^{\frac{m-2+\gamma}{\bar{m}-1}} J^{-\frac{2(m-2+\gamma)}{\bar{m}-1}+2}. \end{aligned}$$

Using $\delta, J \geq 1$ we get

$$|\partial_v \mathcal{L}(i\tau, i\xi, v)| |v|^\gamma \lesssim \delta^{\frac{m \vee n - 2 + \gamma}{\bar{m} - 1}} J^{2 - 2\frac{m \wedge n - 2 + \gamma}{\bar{m} - 1}}, \quad (2.27)$$

i.e. (2.6) is satisfied with $\lambda = 2 - 2\frac{m \wedge n - 2 + \gamma}{m-1}$, $\mu = \frac{m \vee n - 2 + \gamma}{m-1}$. An application of Corollary 2.6 with γ close to 1 implies that for all

$$s < s^* = \frac{2}{m} \frac{m \wedge n - 1}{m - 1},$$

all $p < p^* = \frac{2m}{1+m}$, all $\phi \in C_c^\infty(\mathbb{R}_v)$, $\gamma \in [0, 1)$ large enough, and $\mathcal{O} \subset\subset \mathbb{R}^d$ there is a constant $C \geq 0$ such that

$$\left\| \int f \phi \, dv \right\|_{L^p([0, T]; W^{s, p}(\mathcal{O}))} \leq C(\|u_0\|_{L_x^1} + \|u_0\|_{L_x^{2-\gamma}}^{2-\gamma} + \|S\|_{L_{t,x}^1} + \|S\|_{L_{t,x}^{2-\gamma}}^{2-\gamma} + 1). \quad \square$$

Remark 2.8. In Theorem 2.7 only the regularizing effect of the parabolic part is used. It may be that for $n_j \ll m_j$ the hyperbolic regularizing effect would dominate. Since we are mostly interested in the parabolic regularization, we do not consider this point here. For related work on hyperbolic averaging we refer to [20].

3. Isotropic case

In this section we consider parabolic-hyperbolic PDEs with isotropic parabolic part, that is,

$$\begin{aligned} \partial_t f(t, x, v) + a(v) \cdot \nabla_x f(t, x, v) - b(v) \Delta_x f(t, x, v) \\ =: \mathcal{L}(\partial_t, \nabla_x, v) f(t, x, v) = g_0(t, x, v) + \partial_v g_1(t, x, v), \end{aligned} \quad (3.1)$$

where $a : \mathbb{R} \rightarrow \mathbb{R}^d$ and $b : \mathbb{R} \rightarrow \mathbb{R}_+ \cup \{0\}$ are twice continuously differentiable. The operator \mathcal{L} is given by its symbol

$$\mathcal{L}(i\tau, i\xi, v) := \mathcal{L}_{\text{hyp}}(i\tau, i\xi, v) + \mathcal{L}_{\text{par}}(\xi, v) := i\tau + ia(v) \cdot \xi - b(v)|\xi|^2,$$

which by Appendix A satisfies the truncation property uniformly in $v \in \mathbb{R}$.

In this isotropic case we may work with a more restrictive non-degeneracy condition, which will allow us to improve the order of integrability obtained in Theorem 2.7.

Definition 3.1 (Isotropic truncation property).

- (i) We say that a function $m : \mathbb{R}_\xi^d \rightarrow \mathbb{C}$ is *isotropic* if m is radial, that is, it depends only on $|\xi|^2$.
- (ii) Let $m : \mathbb{R}_\xi^d \times \mathbb{R}_v \rightarrow \mathbb{C}$ be a Carathéodory function such that $m(\cdot, v)$ is isotropic for all $v \in \mathbb{R}$. Then m is said to satisfy the *isotropic truncation property* if for every bump function ψ supported on a ball in \mathbb{C} , every bump function φ supported in $\{\xi \in \mathbb{C} : 1 \leq |\xi| \leq 4\}$ and every $1 < p < \infty$,

$$M_{\psi, J} f(x, v) := \mathcal{F}_x^{-1} \varphi \left(\frac{|\xi|^2}{J^2} \right) \psi \left(\frac{m(\xi, v)}{\delta} \right) \mathcal{F}_x f(x)$$

is an L_x^p -multiplier for all $v \in \mathbb{R}$, $J = 2^j$, $j \in \mathbb{N}$ and, for all $r \geq 1$,

$$\| \|M_{\psi, J}\|_{\mathcal{M}^p} \|_{L_v} \lesssim |\Omega_m(J, \delta)|^{1/r},$$

where

$$\Omega_m(J, \delta) := \{v \in \mathbb{R} : |m(J, v)/\delta| \in \text{supp } \psi\}.$$

Example 3.2. Consider $\mathcal{L}(\xi, v) = -|\xi|^2 b(v)$ with $b : \mathbb{R} \rightarrow \mathbb{R}_+ \cup \{0\}$ measurable. Then \mathcal{L} satisfies the isotropic truncation property.

Proof. Let φ, ψ be as in the definition of the isotropic truncation property. In order to prove that $M_{\psi, J}$ is an L^p -multiplier we will invoke the Hörmander–Mikhlin Multiplier Theorem [22, Theorem 5.2.7]. We note that

$$\sup_{\xi \in \mathbb{R}^d} \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) < \infty$$

and

$$\begin{aligned} \partial_{\xi_i} \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) &= \varphi'\left(\frac{|\xi|^2}{J^2}\right) \frac{|\xi|^2}{J^2} \frac{2\xi_i}{|\xi|^2} \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) + \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi'\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \frac{\mathcal{L}(\xi, v)}{\delta} \frac{2\xi_i}{|\xi|^2} \\ &= \left[\varphi'\left(\frac{|\xi|^2}{J^2}\right) \frac{|\xi|^2}{J^2} \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) + \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi'\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \frac{\mathcal{L}(\xi, v)}{\delta} \right] \frac{2\xi_i}{|\xi|^2} \\ &= \tilde{\varphi}\left(\frac{|\xi|^2}{J^2}\right) \tilde{\psi}\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \frac{2\xi_i}{|\xi|^2}, \end{aligned}$$

where $\tilde{\varphi}, \tilde{\psi}$ are bump functions with the same support properties as φ, ψ . Hence, induction yields

$$\left| \partial_{\xi}^{\alpha} \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \right| \leq \tilde{\varphi}^{\alpha}\left(\frac{|\xi|^2}{J^2}\right) \tilde{\psi}^{\alpha}\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \frac{C_{\alpha}}{|\xi|^{|\alpha|}}$$

for all multi-indices α with $|\alpha| \leq [d/2] + 1$, where $\tilde{\varphi}^{\alpha}, \tilde{\psi}^{\alpha}$ are bump functions with the same support properties as φ, ψ . The Hörmander–Mikhlin Multiplier Theorem thus implies that

$$\varphi\left(\frac{|\xi|^2}{J^2}\right) \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \in \mathcal{M}^p$$

for all $1 < p < \infty$ with

$$\left\| \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \right\|_{\mathcal{M}^p} \leq C_{d,p} \sup_{\xi \in \mathbb{R}^d} \tilde{\varphi}\left(\frac{|\xi|^2}{J^2}\right) \tilde{\psi}\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right),$$

where $\tilde{\varphi}, \tilde{\psi}$ are bump functions as above. Hence,

$$\left\| \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \right\|_{\mathcal{M}^p} \leq C_{d,p} \sup_{J \leq |\xi| \leq 2J} \tilde{\psi}\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right).$$

Consequently,

$$\begin{aligned} \left\| \left\| \varphi\left(\frac{|\xi|^2}{J^2}\right) \psi\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) \right\|_{\mathcal{M}^p} \right\|_{L^r_v} &\lesssim \left(\int \sup_{J \leq |\xi| \leq 2J} \tilde{\psi}\left(\frac{\mathcal{L}(\xi, v)}{\delta}\right) dv \right)^{1/r} \\ &\lesssim \left(\int \sup_{J \leq |\xi| \leq 2J} 1_{|\xi|^2 b(v)/\delta \in \text{supp } \tilde{\psi}} dv \right)^{1/r} \lesssim \left(\int 1_{|J|^2 b(v)/\delta \in \text{supp } \tilde{\psi}} dv \right)^{1/r} \\ &\lesssim (\{|v \in \mathbb{R} : |J|^2 b(v)/\delta \in \text{supp } \tilde{\psi}\})^{1/r} = |\Omega_{\mathcal{L}}(J, \delta)|^{1/r}. \quad \square \end{aligned}$$

3.1. Averaging lemma

Working with the isotropic truncation property allows us to prove a statement similar to Lemma 2.1, but without the restriction to $p \leq 2$. This leads to an improved estimate on the integrability of the solution.

Lemma 3.3. *Let $f \in L_v^{r'}(L_{t,x}^p)$ for $1 < p < \infty$ and $r' \in (1, \infty]$ solve, in the sense of distributions,*

$$\mathcal{L}(\partial_t, \nabla_x, v)f(t, x, v) = \Delta_x^{\eta/2}g_0(t, x, v) + \partial_v \Delta_x^{\eta/2}g_1(t, x, v) \quad \text{on } \mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v \quad (3.2)$$

with g_i being Radon measures satisfying

$$|g_0|(t, x, v) + |g_1|(t, x, v)|v|^{-\gamma} \in \begin{cases} L^q(\mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v), & 1 < q \leq 2, \\ \mathcal{M}_{\text{TV}}(\mathbb{R}_t \times \mathbb{R}_x^d \times \mathbb{R}_v), & q = 1, \end{cases} \quad (3.3)$$

for some $\gamma \geq 0, \eta \geq 0, 1 \leq q \leq \min(p, 2)$ and $\mathcal{L}(\partial_t, \nabla_x, v)$ as in (3.1) with symbol $\mathcal{L}(i\tau, i\xi, v) = \mathcal{L}_{\text{hyp}}(i\tau, i\xi, v) + \mathcal{L}_{\text{par}}(\xi, v)$. Let $I \subseteq \mathbb{R}$ be a not necessarily bounded interval, set

$$\omega_{\mathcal{L}}(J; \delta) := \sup_{\tau \in \mathbb{R}, \xi \in \mathbb{R}^d, |\xi| \sim J} |\Omega_{\mathcal{L}}(\tau, \xi; \delta)|, \quad \Omega_{\mathcal{L}}(\tau, \xi; \delta) = \{v \in I : |\mathcal{L}(i\tau, i\xi, v)| \leq \delta\},$$

and suppose that the following non-degeneracy condition holds: There exist $\alpha, \beta > 0$ such that

$$\omega_{\mathcal{L}}(J; \delta) \lesssim (\delta/J^\beta)^\alpha, \quad \forall \delta, J \geq 1. \quad (3.4)$$

Moreover, assume that there exist $\lambda \geq 0$ and $\mu \in [0, 1]$ such that, for all $\delta, J \geq 1$,

$$\sup_{\tau, |\xi| \sim J} \sup_{v \in \Omega_{\mathcal{L}}(\tau, \xi; \delta)} |\partial_v \mathcal{L}(i\tau, i\xi, v)| |v|^\gamma \lesssim J^\lambda \delta^\mu \quad (3.5)$$

and $\alpha\beta/q' \leq \lambda + \eta$. Assume that \mathcal{L}_{par} satisfies the isotropic truncation property with

$$|\Omega_{\mathcal{L}_{\text{par}}}(J, \delta)| \lesssim (\delta/J^\beta)^\alpha, \quad \forall \delta, J \geq 1. \quad (3.6)$$

Then, for all $\phi \in C_b^\infty(I), s \in [0, s^*), \tilde{p} \in [1, p^*), T \geq 0, \mathcal{O} \subset\subset \mathbb{R}^d$, there is a constant $C \geq 0$ such that

$$\begin{aligned} \left\| \int f(t, x, v)\phi(v) dv \right\|_{L^{\tilde{p}}([0, T]; \dot{W}^{s, \tilde{p}}(\mathcal{O}))} &\leq C(\|g_0\phi\|_{L_{t,x,v}^q} + \| |v|^{-\gamma} g_1\phi \|_{L_{t,x,v}^q} \\ &+ \|g_1\phi'\|_{L_{t,x,v}^q} + \|f\phi\|_{L_v^{r'}(L_{t,x}^p)} + \|f\phi\|_{L_{t,x}^q L_v^1} + \|f\phi\|_{L_t^{\tilde{p}} L_{x,v}^1}) \end{aligned} \quad (3.7)$$

with $s^* := (1 - \theta)\alpha\beta/r + \theta(\alpha\beta/q' - \lambda - \eta)$, where $\theta = \theta_\alpha$ and p^* are given by

$$\theta := \frac{\alpha/r}{\alpha(1/r - 1/q') + 1} \in (0, 1), \quad \frac{1}{p^*} := \frac{1 - \theta}{p} + \frac{\theta}{q}, \quad \frac{1}{r} + \frac{1}{r'} = 1.$$

An analogous estimate can be given for inhomogeneous Sobolev spaces.

Proof. The proof proceeds analogously to the one of Lemma 2.1. The only change appears in the estimation of f^0 . We may assume that ψ_0 is of the form $\psi_0(ia + b) = \psi_0^1(a)\psi_0^2(b)$ with ψ_0^i being locally supported bump functions. Hence,

$$\psi_0\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta}\right) = \psi_0^1\left(\frac{\mathcal{L}_{\text{hyp}}(i\tau, i\xi, v)}{\delta}\right)\psi_0^2\left(\frac{\mathcal{L}_{\text{par}}(\xi, v)}{\delta}\right)$$

and

$$\left\| \varphi_1\left(\frac{\xi}{2^j}\right)\psi_0\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta}\right) \right\|_{\mathcal{M}^p} \lesssim \left\| \varphi_1\left(\frac{\xi}{2^j}\right)\psi_0^2\left(\frac{\mathcal{L}_{\text{par}}(\xi, v)}{\delta}\right) \right\|_{\mathcal{M}^p}.$$

The isotropic truncation property and (3.6) then imply

$$\left\| \left\| \varphi_1\left(\frac{\xi}{2^j}\right)\psi_0\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta}\right) \right\|_{\mathcal{M}^p} \right\|_{L_v^r} \lesssim |\Omega_{\mathcal{L}_{\text{par}}}(2^j, \delta)|^{1/r} \lesssim (\delta/2^{j\beta})^{\alpha/r}.$$

Hence,

$$\begin{aligned} \left\| \int f_j^0 \phi \, dv \right\|_{L_{t,x}^p} &= \left\| \int \mathcal{F}_{t,x}^{-1} \varphi_1\left(\frac{\xi}{2^j}\right)\psi_0\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta}\right) \mathcal{F}_{t,x} f^0 \phi \, dv \right\|_{L_{t,x}^p} \\ &\leq \int \left\| \mathcal{F}_{t,x}^{-1} \varphi_1\left(\frac{\xi}{2^j}\right)\psi_0\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta}\right) \mathcal{F}_{t,x} f^0 \phi \right\|_{L_{t,x}^p} \, dv \\ &\lesssim \int \left\| \mathcal{F}_{t,x}^{-1} \varphi_1\left(\frac{\xi}{2^j}\right)\psi_0\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta}\right) \mathcal{F}_{t,x} \right\|_{\mathcal{M}^p} \|f^0 \phi\|_{L_{t,x}^p} \, dv \\ &\leq \left\| \varphi_1\left(\frac{\xi}{2^j}\right)\psi_0\left(\frac{\mathcal{L}(i\tau, i\xi, v)}{\delta}\right) \right\|_{\mathcal{M}^p} \left\| f^0 \phi \right\|_{L_v^r L_{t,x}^p} \\ &\lesssim (\delta/2^{j\beta})^{\alpha/r} \|f^0 \phi\|_{L_v^r L_{t,x}^p}. \end{aligned}$$

The proof then proceeds as before, the only difference being that we do not have to restrict to $1 < p \leq 2$ and that we use the modified definition of r, r' . \square

3.2. Porous media equations

In this section we consider porous media equations with a source of the type

$$\begin{aligned} \partial_t u &= \Delta u^{[m]} + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}_x^d, \\ u(0) &= u_0, \end{aligned} \tag{3.8}$$

where $u_0 \in L^1(\mathbb{R}_x^d)$, $S \in L^1([0, T] \times \mathbb{R}_x^d)$, $T \geq 0$ and $m > 1$.

As in [11], the kinetic form to (3.8) reads, with $f = \chi(u(t, x), v)$, $q \in \mathcal{M}^+$,

$$\partial_t f = m|v|^{m-1} \Delta f + \partial_v q + S(t, x) \delta_{u(t,x)}(v) \quad \text{on } (0, T) \times \mathbb{R}_x^d \times \mathbb{R}_v. \tag{3.9}$$

For the notion and well-posedness of entropy solutions to (3.8) see Appendix B. As before, let $\mathcal{L}(\partial_t, \nabla_x, v) f = \partial_t f - m|v|^{m-1} \Delta f$ with symbol

$$\mathcal{L}(i\tau, \xi, v) := \mathcal{L}_{\text{hyp}}(i\tau) + \mathcal{L}_{\text{par}}(\xi, v) := i\tau - m|v|^{m-1} |\xi|^2.$$

Theorem 3.4. *Let $u_0 \in (L^1 \cap L^{1+\varepsilon})(\mathbb{R}_x^d)$ and $S \in (L^1 \cap L^{1+\varepsilon})([0, T] \times \mathbb{R}_x^d)$ for some $\varepsilon > 0$. Let u be the unique entropy solution to (3.8). Then, for all $s \in [0, 2/m)$ and $p \in [1, m)$, we have*

$$u \in L^p([0, T]; \dot{W}_{\text{loc}}^{s,p}(\mathbb{R}_x^d)).$$

In addition, for all $\mathcal{O} \subset\subset \mathbb{R}^d$ there is a constant $C = C(m, p, s, \varepsilon, T, \mathcal{O})$ such that

$$\|u\|_{L^p([0,T]; \dot{W}^{s,p}(\mathcal{O}))} \leq C(\|u_0\|_{L_x^1 \cap L_x^{1+\varepsilon}}^2 + \|S\|_{L_{t,x}^1 \cap L_{t,x}^{1+\varepsilon}}^2 + 1).$$

Proof. Let $s \in [0, 2/m)$ and $p \in [1, m)$. We have $f \in L_{t,x,v}^1 \cap L_{t,x,v}^\infty$ and thus $f \in L_v^{\tilde{p}}(L_{t,x}^{\tilde{p}})$ for all $\tilde{p} \geq 1$ with

$$\|f\|_{L_v^{\tilde{p}}(L_{t,x}^{\tilde{p}})} \leq \|f\|_{L_v^1(L_{t,x}^1)}. \tag{3.10}$$

This bound will replace the property $f \in L_{t,x;\text{loc}}^2(H_v^{\sigma,2})$ used in the proof of Corollary 2.6, which is possible due to Lemma 3.3. As a consequence, the localization of f performed in Corollary 2.6 is not required here. In order to apply (3.3) we need to extend (3.9) to all time $t \in \mathbb{R}$, which can be done by multiplication by a smooth cut-off function $\varphi \in C_c^\infty(0, T)$. Let $\eta = 0$, $\alpha = \frac{1}{m-1}$, $\beta = 2$ and choose $\gamma \in [0, 1)$ large enough and $r \geq 1$ small enough such that $\lambda = 2 - 2\frac{m-2+\gamma}{m-1} = 2\frac{1-\gamma}{m-1}$ is such that

$$(1 - \theta)\beta\alpha/r - \theta(\lambda + \eta) = \theta(\beta/r - \lambda) = \frac{2}{m} \left(\frac{1}{r} - \frac{1 - \gamma}{m - 1} \right) > s,$$

where $\theta = 1/m$. Next, choose \tilde{p} large enough that $p^* = m\frac{\tilde{p}}{m-1+\tilde{p}} > p$ and note $\frac{1-\theta}{\tilde{p}} + \theta = \frac{1}{p^*}$. We can choose \tilde{p}, r such that $\tilde{p} = r'$. Let $g_0 = \delta_{v=u(t,x)}S + f\partial_t\varphi$, $g_1 = q$. In order to treat the possible singularity of $\partial_v\mathcal{L}$ at $v = 0$ we proceed as in Corollary 2.6, i.e. first cutting out the singularity, then controlling the respective error uniformly by Lemma 2.5. Note that \mathcal{L} satisfies (3.4), (3.5) on $\mathbb{R} \setminus \{0\}$ for all $\gamma \in [0, 1)$ and \mathcal{L}_{par} satisfies the isotropic truncation property with (3.6). With these choices, Lemma 3.3 with $p = \tilde{p}$, $q = 1$ and $\phi \equiv 1$ yields

$$\begin{aligned} \|u\|_{L^p([0,T]; \dot{W}^{s,p}(\mathcal{O}))} &\lesssim \|\delta_{v=u(t,x)}S\|_{\mathcal{M}_{\text{TV}}} + \|f_0\|_{L_x^1 L_v^1} + \||v|^{-\gamma}q\|_{\mathcal{M}_{\text{TV}}} \\ &\quad + \|f\|_{L_v^{\tilde{p}}(L_{t,x}^{\tilde{p}})} + \|f\|_{L_{t,x}^1 L_v^1} + \|f\|_{L_{t,x}^p L_v^1} \\ &\lesssim \|S\|_{L_{t,x}^1} + \|u_0\|_{L_x^1} + \||v|^{-\gamma}q\|_{\mathcal{M}_{\text{TV}}} + \|f\|_{L_{t,x}^1 L_v^1} + \|f\|_{L_{t,x}^p L_{x,v}^1} + 1. \end{aligned}$$

The fact that, for all $\eta \in [1, \infty)$,

$$\begin{aligned} \|f\|_{L_{t,x}^\eta L_v^1} &= \|u\|_{L_{t,x}^\eta} \lesssim \|u_0\|_{L_x^\eta} + \|S\|_{L_{t,x}^\eta}, \\ \|f\|_{L_{t,x,v}^\eta L_x^1} &= \|u\|_{L_{t,x}^\eta L_x^1} \lesssim \|u_0\|_{L_x^1} + \|S\|_{L_{t,x}^1} \end{aligned}$$

and Lemma 2.4 thus imply

$$\|u\|_{L^p([0,T]; \dot{W}^{s,p}(\mathcal{O}))} \lesssim \|u_0\|_{L_x^1 \cap L_x^{2-\gamma}}^2 + \|S\|_{L_{t,x}^1 \cap L_{t,x}^{2-\gamma}}^2 + 1.$$

Since $p^* > p$, choosing $\gamma \in (0, 1)$ large enough so that $2 - \gamma \leq 1 + \varepsilon$ yields the claim. □

Remark 3.5. We note that for $u_0 \in L^1_x$ or $S \in L^1_{t,x}$ the kinetic measure q does not necessarily have finite mass (see e.g. [28]). Therefore, in the literature the cut-off $\phi \in C^\infty_c(\mathbb{R})$ in (3.7) is required to be compactly supported, which makes it impossible to deduce regularity estimates for u itself, unless u is bounded. Our arguments allow avoiding this restriction since we work with the singular moments $|v|^{-\gamma} q$ only, which are shown to be finite in Lemma 2.4 provided $u \in L^{2-\gamma}_x, S \in L^{2-\gamma}_{t,x}$.

Remark 3.6. As pointed out in the introduction, the results obtained in [16] are restricted to fractional differentiability of order less than 1. This restriction is inherent to the method used in [16]. More precisely, the estimates obtained in [16] are (informally) based on testing (3.8) with $\int_0^t \Delta u^{[m]} dr$, integrating in space and time and using Hölder’s inequality, which leads to the energy inequality (neglecting constants)

$$\int_0^T \int (\nabla u^{[\frac{m+1}{2}]})^2 dx dr \leq \int u^2(0) dx. \tag{3.11}$$

The regularity estimates are then deduced from (3.11) alone. In [16] these formal computations are made rigorous, a careful treatment of boundary conditions is given and the bound on $\int_0^T \int (\nabla u^{[\frac{m+1}{2}]})^2 dx dr$ is used to prove (1.8). Since (3.11) only involves derivatives of first order, it does not seem possible to deduce higher than first order differentiability from this.

4. Degenerate parabolic Anderson model

We consider the degenerate parabolic Anderson model

$$\begin{aligned} \partial_t u &= \partial_{xx} u^{[m]} + uS && \text{on } (0, T) \times I, \\ u^\varepsilon &= 0 && \text{on } \partial I, \end{aligned} \tag{4.1}$$

with $m \in (1, 2)$, $I \subseteq \mathbb{R}$ a bounded, open interval and S being a distribution only. As for the parabolic Anderson model (see [17, 18]), the particular example we have in mind is $S = \xi$ being spatial white noise. Accordingly, we assume that, locally on \mathbb{R} ,

$$S \in B_{\infty, \infty}^{-1/2-\varepsilon} \quad \text{for all } \varepsilon > 0. \tag{4.2}$$

The choice of zero Dirichlet boundary data in (4.1) is for simplicity only and the arguments of this section can easily be adapted to the Cauchy problem.

We define weak solutions to (4.1) to be functions $u \in L^2([0, T]; H_0^1(I))$ such that $u^{[m]} \in L^2([0, T]; H_0^1(I))$ and (4.1) is satisfied in the sense of distributions. We will prove the following regularity estimate for a weak solution to (4.1).

Corollary 4.1. *Let $u_0 \in L^{m+1}(I)$. Then there exists a weak solution u to (4.1) satisfying, for all $p \in [1, m)$, $s \in [0, \frac{3}{2} \frac{1}{m})$,*

$$u \in L^p([0, T]; W_{\text{loc}}^{s,p}(I)),$$

with, for all $T \geq 0$ and $\mathcal{O} \subset\subset I$,

$$\|u\|_{L^p([0,T]; W^{s,p}(\mathcal{O}))} \lesssim \|u_0\|_{L^{m+1}(I)}^{m+1} + \|S\|_{B_{\infty,\infty}^{-\eta}}^\tau + 1$$

for some $\tau \geq 2$ and $\eta \in (1/2, 1]$ small enough.

The above proposition is a consequence of uniform regularity estimates (see Theorem 4.5 below) for the approximating problem

$$\begin{aligned} \partial_t u^\varepsilon &= \partial_{xx}(u^\varepsilon)^{[m]} + u^\varepsilon S^\varepsilon(x) && \text{on } (0, T) \times I, \\ u^\varepsilon &= 0 && \text{on } \partial I, \end{aligned} \tag{4.3}$$

where $S^\varepsilon \in C^\infty(\mathbb{R})$ with $\|S^\varepsilon\|_{B_{\infty,\infty}^{-1/2-\varepsilon}} \leq \|S\|_{B_{\infty,\infty}^{-1/2-\varepsilon}}$ and $S^\varepsilon \rightarrow S$ locally in $B_{\infty,\infty}^{-1/2-\varepsilon}$ for all $\varepsilon > 0$. These estimates will be derived from the kinetic formulation of (4.3). Informally, with $\chi^\varepsilon := \chi(u^\varepsilon)$ the kinetic form reads, in the sense of distributions,

$$\begin{aligned} \partial_t \chi^\varepsilon &= m|v|^{m-1} \partial_{xx} \chi^\varepsilon + \delta_{u^\varepsilon(t,x)=v} u^\varepsilon S^\varepsilon + \partial_v q^\varepsilon \\ &= m|v|^{m-1} \partial_{xx} \chi^\varepsilon + \chi^\varepsilon S^\varepsilon + \partial_v q^\varepsilon - \partial_v(\chi^\varepsilon v S^\varepsilon) && \text{on } (0, T) \times I \times \mathbb{R}. \end{aligned} \tag{4.4}$$

Definition 4.2. We say that $u^\varepsilon \in L^1([0, T] \times I)$ is an *entropy solution* to (4.3) if

- (i) for every $\alpha \in (0, m]$ there is a constant $K_1 \geq 0$ such that

$$\|\partial_x(u^\varepsilon)^{[\frac{m+\alpha}{2}]}\|_{L^2([0,T] \times I)} \leq K_1. \tag{4.5}$$

- (ii) $\chi^\varepsilon = \chi(u^\varepsilon)$ satisfies (4.4), in the sense of distributions on $(0, T) \times I \times \mathbb{R}$, for some non-negative, finite measure q^ε such that,

$$q^\varepsilon = m^\varepsilon + n^\varepsilon$$

with m^ε being a non-negative measure and n^ε given by

$$n^\varepsilon = \delta_{v=u^\varepsilon} (\partial_x(u^\varepsilon)^{[\frac{m+1}{2}]})^2$$

and satisfying, for every $\alpha \in (0, m]$ with K_1 as in (i),

$$\int_{[0,T] \times \mathbb{R}^d \times \mathbb{R}} |v|^{\alpha-1} q^\varepsilon dt dx dv \leq K_1. \tag{4.6}$$

The well-posedness of entropy solutions to (4.3) follows along the lines of Theorem B.1 in Appendix B. It only remains to show that the constant K_1 in (4.5) and (4.6) can be chosen uniformly in ε .

Lemma 4.3. Let $\alpha > 0$, $\tau = \frac{2\alpha+2}{2\alpha+3-m} \in (1, 2]$ and $u_0 \in (L^{m+1} \cap L^{\alpha+1})(\mathbb{R}_x^d)$. Then, for some constant $C = C(\alpha, m, T)$,

$$\sup_{t \in [0, T]} \int_I |u^\varepsilon(t)|^{\alpha+1} dx + \int_0^T \int_I (\partial_x(u^\varepsilon)^{[\frac{m+\alpha}{2}]})^2 dx dr \leq C \int_I |u_0|^{\alpha+1} dx + C \|S\|_{W^{-1,\tau}}^{\tau'}$$

and

$$\int_{[0,T] \times \bar{I} \times \mathbb{R}} |v|^{\alpha-1} q^\varepsilon dr dx dv \leq C \int_I |u_0|^{\alpha+1} dx + C \|S\|_{W^{-1,\tau}}^{\tau'}. \tag{4.7}$$

Proof. First, let $u_0 \in C_c^\infty(\mathbb{R}_x^d)$, let $b^\delta \in C^\infty(\mathbb{R})$ be increasing with $b^\delta(u) \geq \delta u$ for all $u \in \mathbb{R}$ and $b^\delta(u) \rightarrow u^{[m]}$ locally uniformly, and let $u^{\varepsilon, \delta}$ be the classical solution to the approximating equation

$$\partial_t u^{\varepsilon, \delta} = \partial_{xx} b^\delta(u^{\varepsilon, \delta}) + u^{\varepsilon, \delta} S^\varepsilon(x) \quad \text{on } (0, T) \times I.$$

For simplicity we drop the ε in the notation. Then, for $\eta \in C^2(\mathbb{R})$ convex and Lipschitz continuous, we obtain

$$\begin{aligned} \int_I \eta(u^\delta(t)) dx &= \int_I \eta(u_0) dx + \int_0^t \int_I \eta'(u^\delta) (\partial_{xx} b^\delta(u^\delta) + u^\delta S) dx dr \\ &\leq \int_I \eta(u_0) dx - c \int_0^t \int_I (\partial_x F^\eta(u^\delta))^2 dx dr + \int_0^t \int_I \eta'(u^\delta) u^\delta S dx dr \end{aligned}$$

with $F^\eta(u) := \int_0^u \sqrt{\eta''(r)(b^\delta)'(r)} dr$. Hence (for a non-re-labeled subsequence) we have $\partial_x F^\eta(u^\delta) \rightharpoonup Z$ for some $Z \in L^2([0, T]; L^2(\mathbb{R}_x^d))$. Since $u^\delta \rightarrow u$ in $C([0, T]; L^1(\mathbb{R}_x^d))$, we have $Z = \partial_x F^\eta(u)$, which implies

$$\int_I \eta(u(t)) dx \leq \int_I \eta(u_0) dx - c \int_0^t \int_I (\partial_x F^\eta(u))^2 dx dr + \int_0^t \int_I \eta'(u) u S dx dr,$$

where $F^\eta(u) := m \int_0^u \sqrt{\eta''(r)|r|^{m-1}} dr$.

Using a suitable approximation of $\eta(u) = |u|^{\alpha+1}$ this yields, for some $c = c(\alpha, m)$,

$$\int_I |u(t)|^{\alpha+1} dx \lesssim \int_I |u_0|^{\alpha+1} dx - c \int_0^t \int_I (\partial_x u^{[\frac{m+\alpha}{2}]})^2 dx dr + \int_0^t \int_I |u|^{\alpha+1} S dx dr.$$

We further have, for $\tau \in [1, 2)$ to be chosen later,

$$\int_I |u|^{\alpha+1} S dx \lesssim \| |u|^{\alpha+1} \|_{W^{1, \tau}}^\tau + \| S \|_{W^{-1, \tau'}}^{\tau'} \tag{4.8}$$

and, for every $\eta > 0$ and some $C_\eta \geq 0$,

$$\begin{aligned} \| |u|^{\alpha+1} \|_{W^{1, \tau}}^\tau &\lesssim \int_I |\partial_x |u|^{\alpha+1}|^\tau dx = (\alpha + 1)^\tau \int_I |u^{[\alpha]} \partial_x u|^\tau dx \\ &= (\alpha + 1)^\tau \int_I |u^{[\alpha - \frac{m+\alpha-2}{2}]} |u|^{\frac{m+\alpha-2}{2}} \partial_x u|^\tau dx \\ &= \frac{4(\alpha + 1)^\tau}{(m + \alpha)^2} \int_I |u^{\frac{\alpha-m+2}{2}}|^\tau |\partial_x u^{[\frac{m+\alpha}{2}]}|^\tau dx \\ &\leq C \int_I (C_\eta |u^{\frac{\alpha-m+2}{2}}|^{\frac{2\tau}{2-\tau}} + \eta |\partial_x u^{\frac{m+\alpha}{2}}|^2) dx. \end{aligned} \tag{4.9}$$

Thus, since $\tau < 2$ and choosing η small enough,

$$\begin{aligned} \int_I |u(t)|^{\alpha+1} dx &\lesssim \int_I |u_0|^{\alpha+1} dx - c \int_0^t \int_I (\partial_x u^{[\frac{m+\alpha}{2}]})^2 dx dr \\ &\quad + \int_0^t \int_I |u|^{\frac{\alpha-m+2}{2}}|^{\frac{2\tau}{2-\tau}} dx dr + \| S \|_{W_x^{-1, \tau'}}^{\tau'}. \end{aligned}$$

Now we choose τ such that $\frac{\alpha-m+2}{2} \frac{2\tau}{2-\tau} = \alpha + 1$, i.e. since $m - 2 < \alpha$,

$$\tau = \frac{2\alpha + 2}{2\alpha + 3 - m} \in (1, 2].$$

In conclusion,

$$\begin{aligned} \int_I |u(t)|^{\alpha+1} dx &\lesssim \int_I |u_0|^{\alpha+1} dx - c \int_0^t \int_I (\partial_x u^{[\frac{m+\alpha}{2}]})^2 dx dr \\ &\quad + \int_0^t \int_I |u|^{\alpha+1} dx dr + \|S\|_{W_x^{-1,\tau'}}^{\tau'}. \end{aligned}$$

Gronwall’s inequality implies

$$\int_I |u^\varepsilon(t)|^{\alpha+1} dx + \int_0^t \int_I (\partial_x (u^\varepsilon)^{[\frac{m+\alpha}{2}]})^2 dx dr \lesssim \int_I |u_0|^{\alpha+1} dx + \|S^\varepsilon\|_{W_x^{-1,\tau'}}^{\tau'}. \tag{4.10}$$

For general initial data $u_0 \in (L^{m+1} \cap L^{\alpha+1})(\mathbb{R}_x^d)$ we choose a sequence of smooth approximations $u_0^\delta \in C_c^\infty(\mathbb{R}_x^d)$ such that $u_0^\delta \rightarrow u_0$ in $(L^{m+1} \cap L^{\alpha+1})(\mathbb{R}_x^d)$. The respective solutions $u^{\varepsilon,\delta}$ satisfy (4.10) and, due to (B.3), we may take the limit $\delta \rightarrow 0$ to conclude.

In order to establish (4.7) we note that on the approximate level $u^{\varepsilon,\delta}$ the kinetic form is satisfied with $q^{\varepsilon,\delta} = \delta_{v=u^{\varepsilon,\delta}} (\partial_x (u^{\varepsilon,\delta})^{[\frac{m+1}{2}]})^2$. Thus,

$$\begin{aligned} \int_{[0,T] \times \bar{I} \times \mathbb{R}} |v|^{\alpha-1} q^{\varepsilon,\delta} dr dx dv &= \int_I (\partial_x (u^{\varepsilon,\delta})^{[\frac{m+\alpha}{2}]})^2 dt dx \\ &\lesssim \int_I |u_0|^{\alpha+1} dx + \|S^\varepsilon\|_{W_x^{-1,\tau'}}^{\tau'}. \end{aligned}$$

Passing to the limit $\delta \rightarrow 0$ yields (4.7). □

Corollary 4.4. *Let $u_0 \in L^{m+1}(I)$. Then there is a unique entropy solution u^ε to (4.3), and u^ε satisfies the conditions in Definition 4.2 with*

$$K_1 \lesssim \|u_0\|_{L^{m+1}}^{m+1} + \|S\|_{B_{\infty,\infty}^{-\eta}}^\tau + 1$$

for some $\tau \geq 2$ and some $\eta \in (1/2, 1)$. In particular, the constants K_1 in Definition 4.2 can be chosen uniformly in ε and

$$\|u^\varepsilon\|_{L^2([0,T]; H_0^1(I))}^2 \leq K_1.$$

Proof. We apply Lemma 4.3 with $\alpha \in (0, m]$. □

Theorem 4.5. *Assume (4.2) and let u^ε be the entropy solution to (4.3). Then for all $p \in [1, m)$ $s \in [0, \frac{3}{2} \frac{1}{m})$ we have*

$$u^\varepsilon \in L^p([0, T]; W_{\text{loc}}^{s,p}(I))$$

with, for all $T \geq 0$ and $\mathcal{O} \subset\subset I$,

$$\|u^\varepsilon\|_{L^p([0,T]; W^{s,p}(\mathcal{O}))} \leq C(\|u_0\|_{L^{m+1}(I)}^{m+1} + \|S\|_{B_{\infty,\infty}^{-\eta}}^\tau + 1)$$

for some $\tau \geq 2$, C independent of $\varepsilon > 0$ and $\eta \in (1/2, 1)$ small enough.

Proof. Let $p \in [1, m)$ and $s \in [0, \frac{3}{2} \frac{1}{m})$. For simplicity we drop the ε in the notation. Rewriting (4.4) we obtain, for $\eta \in (1/2, 1)$,

$$\begin{aligned} \partial_t \chi &= m|v|^{m-1} \partial_{xx} \chi \\ &+ \Delta_x^{\eta/2} \underbrace{\Delta_x^{-\eta/2} \chi S}_{:=g_0} + \Delta_x^{\eta/2} \partial_v \underbrace{\Delta_x^{-\eta/2} q}_{:=g_1} - \Delta_x^{\eta/2} \partial_v \underbrace{\Delta_x^{-\eta/2} \chi v S}_{:=g_2} \quad \text{on } (0, T) \times I \times \mathbb{R}. \end{aligned} \tag{4.11}$$

An elementary computation shows $\|\chi\|_{L^1_{t,v} W_x^{\eta,1}} \lesssim \|u\|_{L^1_{t,v} W_x^{\eta,1}}$. We next use embedding results for Besov spaces [3, Proposition 2.78], estimates for the paraproduct of functions and distributions [30, Section 4.4.3, Theorem 1] and Corollary 4.4 to obtain, for $\delta > 0$ small enough,

$$\begin{aligned} \|g_0\|_{L^1_{t,x,v}} &= \|\Delta_x^{-\eta/2} \chi S\|_{L^1_{t,x,v}} \lesssim \|\chi S\|_{L^1_{t,v} B_{1,1}^{-\eta}} \lesssim \|\chi\|_{L^1_{t,v} B_{1,1}^{\eta+\delta}} \|S\|_{B_{\infty,\infty}^{-\eta}} \\ &\lesssim \|u\|_{L^1_t(W_x^{\eta+2\delta,1})} \|S\|_{B_{\infty,\infty}^{-\eta}} \lesssim \|u\|_{L^2_t(H_0^1)}^2 + \|S\|_{B_{\infty,\infty}^{-\eta}}^2 \leq K_1 + \|S\|_{B_{\infty,\infty}^{-\eta}}^2. \end{aligned} \tag{4.12}$$

Moreover, using the same reasoning we obtain

$$\begin{aligned} \||v|^{-1} g_2\|_{L^1_{t,x,v}} &= \||v|^{-1} \Delta_x^{-\eta/2} \chi v S\|_{L^1_{t,x,v}} \\ &= \|\Delta_x^{-\eta/2} |\chi| S\|_{L^1_{t,x,v}} \lesssim K_1 + \|S\|_{B_{\infty,\infty}^{-\eta}}^2. \end{aligned} \tag{4.13}$$

We choose a cut-off function and localize (4.11) as in the proof of Corollary 2.6. Hence, using (3.10), we may apply Lemma 3.3, with η sufficiently close to $1/2$, $\alpha = \frac{1}{m-1}$, $\beta = 2$, $\lambda = 2 - 2\frac{m-2+\gamma}{m-1}$ small enough by choosing γ close to 1, $r > 1$ small enough, $p = r'$, $q = 1$, $\theta = 1/m$, such that

$$\begin{aligned} (1 - \theta)\beta\alpha/r - \theta(\lambda + \eta) &= \theta(\beta/r - \lambda - \eta) \\ &= \frac{1}{m} \left(\frac{3}{2} + \left(\frac{2}{r} - 2 \right) + \left(2\frac{\gamma - 1}{m - 1} \right) + \left(\frac{1}{2} - \eta \right) \right) > s. \end{aligned}$$

This yields, for all $\mathcal{O} \subset\subset I$,

$$\begin{aligned} \|u\|_{L^p([0,T]; W^{s,p}(\mathcal{O}))} &\lesssim \|\Delta_x^{-\eta/2} \chi S\|_{\mathcal{M}_{t,x,v}} + \|\Delta_x^{-\eta/2} |v|^{-\gamma} q\|_{\mathcal{M}_{t,x,v}} \\ &+ \||v|^{-1} \Delta_x^{-\eta/2} \chi v S\|_{\mathcal{M}_{t,x,v}} + \|f\|_{L^{r'}_{t,x,v}} + \|f\|_{L^1_{t,x,v}} + \|f\|_{L^p_{t,x} L^1_v} + 1. \end{aligned}$$

Hence, since

$$\|f\|_{L^{r'}_{t,x,v}} \lesssim \|f\|_{L^1_{t,x,v}} + 1, \quad \|f\|_{L^1_{t,x,v}} = \|u\|_{L^1_{t,x}}, \quad \|f\|_{L^p_{t,x} L^1_v} = \|u\|_{L^p_{t,x}},$$

we have, using (4.12), (4.13),

$$\|u\|_{L^p([0,T]; W^{s,p}(\mathcal{O}))} \lesssim K_1 + \|S\|_{B_{\infty,\infty}^{-\eta}}^2 + \|u\|_{L^1_{t,x}} + \|u\|_{L^p_{t,x}} + 1.$$

In fact, (4.11) is not exactly of the form (3.1), since g_1, g_2 allow singular moments of different order, i.e. $\gamma \in (0, 1)$ for g_1 , $\gamma = 1$ for g_2 . However, in the proof of Lemma 3.3, the

terms involving g_2 only lead to terms better behaved than g_1 and thus may be absorbed. We next note that by the arguments of Lemma 4.3,

$$\|u\|_{L^1_{t,x}} \lesssim \|u_0\|_{L^1_x} + \|S\|_{W^{-1,\tau}}^\tau + 1, \quad \|u\|_{L^p_{t,x}} \lesssim \|u_0\|_{L^{m+1}_x} + \|S\|_{W^{-1,\tau}}^\tau + 1$$

for some $\tau \geq 2$. Hence, by Corollary 4.4 we obtain

$$\begin{aligned} \|u\|_{L^p([0,T];W^{s,p}(\mathcal{O}))} &\lesssim \|u_0\|_{L^{m+1}}^{m+1} + \|S\|_{B_{\infty,\infty}^{-\eta}}^\tau + \|u_0\|_{L^1_x} + \|u_0\|_{L^{m+1}_x} + \|S\|_{W^{-1,\tau}}^\tau + 1 \\ &\lesssim \|u_0\|_{L^{m+1}}^{m+1} + \|S\|_{B_{\infty,\infty}^{-\eta}}^\tau + 1 \end{aligned}$$

for some $\tau \geq 2$. □

Proof of Corollary 4.1. By Lemma 4.3 we have

$$\|u^\varepsilon\|_{L^2([0,T];H^1_0)}^2 + \|\partial_x(u^\varepsilon)^{[m]}\|_{L^2([0,T];L^2)}^2 \leq C.$$

Hence also $\|u^\varepsilon S^\varepsilon\|_{W^{-1,2}}^2 \lesssim \|u^\varepsilon\|_{W^{1,2}}^2 \|S^\varepsilon\|_{W^{-1,2}}^2 \leq C$. By (4.3) we obtain

$$\|\partial_t u^\varepsilon\|_{L^2([0,T];W^{-1,2})}^2 \leq C.$$

The Aubin–Lions compactness lemma yields (for a subsequence)

$$u^\varepsilon \rightharpoonup u \quad \text{in } L^2([0, T]; L^2(I)).$$

This allows us to pass to the limit in the weak form of (4.3). Hence, Theorem 4.5 finishes the proof. □

Appendix A. Truncation property and basic estimates

From [33, Definition 2.1] we recall the following definition.

Definition A.1. Let m be a complex-valued Fourier multiplier. We say that m has the *truncation property* if, for any locally supported bump function ψ on \mathbb{C} and any $1 \leq p < \infty$, the multiplier with symbol $\psi(m(\xi)/\delta)$ is an L^p -multiplier as well as an \mathcal{M}_{TV} -multiplier uniformly in $\delta > 0$, that is, its L^p -multiplier norm (\mathcal{M}_{TV} -multiplier norm resp.) depends only on the support and C^l size of ψ (for some large l that may depend on m) but otherwise is independent of δ .

We slightly deviate from the definition of the truncation property given in [33, Definition 2.1] since we require it to hold also for $p = 1$ and on \mathcal{M}_{TV} . In [33, Section 2.4] it was shown that multipliers corresponding to parabolic-hyperbolic PDEs satisfy the truncation property for $p > 1$. We extend this property under our definition in the following example.

Example A.2. Let

$$m(\tau, \xi, v) = i\tau + ia(v) \cdot \xi - (\xi, b(v)\xi)$$

for some measurable $a : \mathbb{R} \rightarrow \mathbb{R}^d$ and $b : \mathbb{R} \rightarrow \mathcal{S}_+^{d \times d}$. Then m satisfies the truncation property uniformly in v .

Proof. Following [33, Section 2.4] it remains to consider the cases $p = 1$ and \mathcal{M}_{TV} . Arguing as in [33, Section 2.4] we can consider the cases $m(\tau, \xi, v) = i\tau + ia(v) \cdot \xi$ and $m(\tau, \xi, v) = -(\xi, b(v)\xi)$ separately. By invariance under linear transformations, arguing again as in [33, Section 2.4] it is enough to consider $\psi(i\xi_1)$, $\psi(|\xi|^2)$. Due to [22, Theorem 2.5.8] in order to prove that these are L^1 -multipliers, we need to show that their inverse Fourier transforms have finite L^1 -norm, which is true since ψ is a bump function. Again by [22, Theorem 2.5.8] an operator is an L^1 -multiplier if and only if it is given by convolution with a finite Borel measure. As such, it can be extended to a multiplier on \mathcal{M}_{TV} with the same norm. \square

We next provide a basic L^p -estimate for symbols satisfying the truncation property uniformly. The following estimate is an extension of [33, Lemma 2.2] by making use of regularity in the v -component of f . As pointed out in the introduction, this allows one to avoid bootstrapping arguments in applications, which is crucial, since such arguments do not allow one to deduce regularity of order more than 1.

Lemma A.3. *Assume that $m(\xi, v)$ satisfies the truncation property uniformly in v . Let φ, ϕ be bounded, smooth functions, ψ be a smooth cut-off function and M_ψ be the Fourier multiplier with symbol $\varphi(\xi)\psi(m(\xi, v)/\delta)$. Then, for all $1 < p \leq 2$, $\sigma \geq 0$ and $r \in (\frac{p'}{1+\sigma p'}, p'] \cap (1, \infty)$,*

$$\left\| \int M_\psi f \phi \, dv \right\|_{L_x^p} \lesssim \|f\phi\|_{L_x^p(H_v^{\sigma,p})} \sup_{\xi \in \text{supp } \varphi} |\Omega_m(\xi, \delta)|^{1/r},$$

where $\Omega_m(\xi, \delta) = \{v \in \text{supp } \phi : |m(\xi, v)| \leq \delta\}$. Moreover,

$$\left\| \int M_\psi f \phi \, dv \right\|_{\mathcal{M}_{TV,x}} \lesssim \|f\phi\|_{\mathcal{M}_{TV,x}}.$$

Proof. We first consider the case $p = 2$. Then

$$\begin{aligned} \left\| \int M_\psi f \phi \, dv \right\|_{L_x^2} &\lesssim \left\| \int \mathcal{F}_x^{-1} \varphi(\xi) \psi(m(\xi, v)/\delta) \hat{f} \phi \, dv \right\|_{L_x^2} \\ &= \left\| \int \varphi(\xi) \psi(m(\xi, v)/\delta) \hat{f} \phi \, dv \right\|_{L_\xi^2} \lesssim \|\varphi(\xi)\|_{H_v^{-\sigma,2}} \|\psi(m(\xi, v)/\delta)\|_{H_v^{\sigma,2}} \|\hat{f}\phi\|_{L_\xi^2} \\ &\lesssim \sup_{\xi \in \text{supp } \varphi} \|\psi(m(\xi, v)/\delta)\|_{H_v^{-\sigma,2}} \|\hat{f}\phi\|_{L_\xi^2(H_v^{\sigma,2})}. \end{aligned}$$

Note that

$$\begin{aligned} \|\hat{f}\phi\|_{L_\xi^2(H_v^{\sigma,2})}^2 &= \int \|\hat{f}\phi\|_{H_v^{\sigma,2}}^2 \, d\xi = \int |(1 + \Delta_v)^{\sigma/2} \hat{f}\phi|^2 \, dv \, d\xi \\ &= \int |\mathcal{F}_x(1 + \Delta_v)^{\sigma/2} f\phi|^2 \, d\xi \, dv = \int |(1 + \Delta_v)^{\sigma/2} f\phi|^2 \, dx \, dv \\ &= \int \|f\phi\|_{H_v^{\sigma,2}}^2 \, dx = \|f\phi\|_{L_x^2 H_v^{\sigma,2}}^2. \end{aligned}$$

By Sobolev embeddings (see e.g. [3, Theorem 1.66]) we have $H_v^{\sigma,2} \hookrightarrow L_v^{r'}$ for all r' in $[2, \frac{2}{1-2\sigma}] \cap \mathbb{R}$. Hence, for $r \in [\frac{2}{1+2\sigma}, 2] \cap (1, \infty)$ we have $L_v^r \hookrightarrow H_v^{-\sigma,2}$. Fix r in $[\frac{2}{1+2\sigma}, 2] \cap (1, \infty)$. Then

$$\begin{aligned} \left\| \int M_\psi f \phi \, dv \right\|_{L_x^2} &\lesssim \sup_{\xi \in \text{supp } \varphi} \|\psi(m(\xi, v)/\delta)\|_{L_v^r} \|f\phi\|_{L_x^2(H_v^{\sigma,2})} \\ &\lesssim \sup_{\xi \in \text{supp } \varphi} |\Omega_m(\xi, \delta)|^{1/r} \|f\phi\|_{L_x^2(H_v^{\sigma,2})}. \end{aligned}$$

This finishes the proof for $p = 2$.

Due to the truncation property (on L^1 and \mathcal{M}_{TV}) uniform in v , we have, for all $\eta \geq 1$,

$$\left\| \int M_\psi f \phi \, dv \right\|_{L_x^\eta} \lesssim \|f\phi\|_{L_{x,v}^\eta}, \quad \left\| \int M_\psi f \phi \, dv \right\|_{\mathcal{M}_{\text{TV}}} \lesssim \|f\phi\|_{\mathcal{M}_{\text{TV}}}.$$

We now conclude by interpolation: From the above we see that $\overline{M}_\psi f := \int M_\psi f \phi \, dv$ is a bounded linear operator in $L(L_x^2(H_v^{\sigma,2}); L_x^2) \cap L(L_{x,v}^\eta; L_x^\eta)$. By complex interpolation, for $\theta \in (0, 1)$, \overline{M}_ψ is in $L([L_x^2(H_v^{\sigma,2}), L_{x,v}^\eta]_\theta; [L_x^2, L_x^\eta]_\theta)$. Interpolation of Banach-space-valued L^p -spaces yields

$$[L_x^2(H_v^{\sigma,2}), L_{x,v}^\eta]_\theta = L_x^{\frac{2}{1+\theta(2/\eta-1)}}([H_v^{\sigma,2}, L_v^\eta]_\theta).$$

Next we note that, for $\eta > 1$,

$$[H_v^{\sigma,2}, L_v^\eta]_\theta = H_v^{(1-\theta)\sigma, \frac{2}{1+\theta(2/\eta-1)}}.$$

Hence,

$$[L_x^2(H_v^{\sigma,2}), L_{x,v}^\eta]_\theta \supseteq L_x^{\frac{2}{1+\theta(2/\eta-1)}}(H_v^{(1-\theta)\sigma, \frac{2}{1+\theta(2/\eta-1)}}), \quad [L_x^2, L_x^\eta]_\theta = L^{\frac{2}{1+\theta(2/\eta-1)}}.$$

Let now $p \in (1, 2)$. Let $\eta > 1$ be such that $\theta = \frac{2-p}{p} \frac{\eta}{2-\eta} \in (0, 1)$, i.e. $p = \frac{2}{1+\theta(2/\eta-1)}$. Then, in conclusion, for all $\sigma > 0$ and all $r \in [\frac{2}{1+2\sigma}, 2] \cap (1, \infty)$,

$$\begin{aligned} \left\| \int M_\psi f \phi \, dv \right\|_{L^p} &= \left\| \int M_\psi f \phi \, dv \right\|_{L^{\frac{2}{1+\theta(2/\eta-1)}}} \\ &\lesssim \|\overline{M}_\psi\|_{L(L_x^2(H_v^{\sigma,2}); L_x^2)}^{1-\theta} \|\overline{M}_\psi\|_{L(L_{x,v}^\eta; L_x^\eta)}^\theta \|f\phi\|_{L_x^{\frac{2}{1+\theta(2/\eta-1)}}(H_v^{(1-\theta)\sigma, \frac{2}{1+\theta(2/\eta-1)}})} \\ &\lesssim \sup_\xi |\Omega_m(\xi, \delta)|^{\frac{2}{r p'}} \|f\phi\|_{L_x^p(H_v^{2\sigma \frac{p-\eta}{p(2-\eta)}, p})}. \end{aligned}$$

Now given $\sigma > 0$ we apply the above with σ replaced by $\sigma' := \frac{p(2-\eta)}{2(p-\eta)}\sigma > 0$ and $\eta > 1$ small enough. Again choosing $\eta > 1$ small enough, this yields the claim for all $r \in (\frac{p'}{1+\sigma p'}, p'] \cap (1, \infty)$. □

Appendix B. Entropy solutions for parabolic-hyperbolic PDEs with a source

In this section we present a sketch of the proof of well-posedness of entropy/kinetic solutions for PDEs of the type

$$\partial_t u + \operatorname{div} A(u) = \operatorname{div}(b(u)\nabla u) + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}^d \tag{B.1}$$

with

$$\begin{aligned} u_0 &\in L^1(\mathbb{R}^d), \quad S \in L^1([0, T] \times \mathbb{R}^d), \\ a &= A' \in L^\infty_{\text{loc}}(\mathbb{R}; \mathbb{R}^d), \\ b_{ij}(\cdot) &= \sum_{k=1}^d \sigma_{ik}(\cdot)\sigma_{kj}(\cdot), \quad \sigma_{ik} \in L^\infty_{\text{loc}}(\mathbb{R}; \mathbb{R}^d). \end{aligned} \tag{B.2}$$

Theorem B.1. *Let $u_0 \in L^1(\mathbb{R}^d)$ and $S \in L^1([0, T] \times \mathbb{R}^d)$. Then there is a unique entropy solution u to (B.1) satisfying $u \in C([0, T]; L^1(\mathbb{R}^d))$. For two entropy solutions u^1, u^2 with initial conditions u_0^1, u_0^2 and forcing S^1, S^2 we have*

$$\sup_{t \in [0, T]} \|u^1(t) - u^2(t)\|_{L^1(\mathbb{R}^d)} \leq \|u_0^1 - u_0^2\|_{L^1(\mathbb{R}^d)} + \|S^1 - S^2\|_{L^1([0, T] \times \mathbb{R}^d)}. \tag{B.3}$$

Moreover, if $u_0 \in L^p(\mathbb{R}^d)$ and $S \in L^p([0, T] \times \mathbb{R}^d)$ for some $p \in [1, \infty)$, then

$$\sup_{t \in [0, T]} \|u(t)\|_{L^p_x} \leq C(\|u_0\|_{L^p_x} + \|S\|_{L^p_{t,x}}) \tag{B.4}$$

for some constant $C = C(T, p)$.

Proof. Uniqueness: We present a sketch of the proof. The argument is a combination of [11, 20] and is rigorously justified by the convolution error estimates from [11, 20]. Owing to [20, proof of Theorem 11] we note that $g(t, x, v) = 1_{v < u(t,x)}$ satisfies the same kinetic equation as f . We further note that, informally, due to Definition 2.3(ii),(iii),

$$n(t, x, v) = \delta_{v=u(t,x)} \sum_{k=1}^d \left(\sum_{i=1}^d \partial_{x_i} \beta_{ik}(u(t, x)) \right)^2.$$

We next note that

$$\begin{aligned} \partial_t \int_{\mathbb{R}} g^1(1 - g^2) dv &= \int_{\mathbb{R}} (\partial_t g^1(1 - g^2) - g^1 \partial_t g^2) dv \\ &= \int_{\mathbb{R}} [(-a(v) \cdot \nabla_x g^1 + \operatorname{div}(b(v)\nabla_x g^1) + \partial_v q^1 + \delta_{v=u^1} S^1)(1 - g^2) \\ &\quad - g^1(-a(v) \cdot \nabla_x g^2 + \operatorname{div}(b(v)\nabla_x g^2) + \partial_v q^2 + \delta_{v=u^2} S^2)] dv \\ &= -\operatorname{div}_x \int_{\mathbb{R}} a(v) g^1(1 - g^2) dv + 2 \int_{\mathbb{R}} \nabla_x g^1 \cdot b(v)\nabla_x g^2 dv \\ &\quad + \int_{\mathbb{R}} (q^1 \partial_v g^2 + \partial_v g^1 q^2) dv + \int_{\mathbb{R}} [(\delta_{v=u^1} S^1)(1 - g^2) - g^1(\delta_{v=u^2} S^2)] dv. \end{aligned}$$

Concerning the forcing, as in [20], we observe that

$$\int_{\mathbb{R}} [(\delta_{v=u^1} S^1)(1 - g^2) - g^1(\delta_{v=u^2} S^2)] dv = 1_{u^1 \geq u^2} (S^1 - S^2).$$

Next, as in [11],

$$\begin{aligned} \int_{\mathbb{R}} (q^1 \partial_v g^2 + \partial_v g^1 q^2) dv &= - \int_{\mathbb{R}} (q^1 \delta_{v=u^2} + \delta_{v=u^1} q^2) dv \\ &\leq - \int_{\mathbb{R}} \left(\sum_{k=1}^d \left(\sum_{i=1}^d \partial_{x_i} \beta_{ik}(u^1) \right)^2 \delta_{v=u^1} \delta_{v=u^2} + \delta_{v=u^1} \delta_{v=u^2} \sum_{k=1}^d \left(\sum_{i=1}^d \partial_{x_i} \beta_{ik}(u^2) \right)^2 \right) dv \\ &\leq -2 \int_{\mathbb{R}} \delta_{v=u^1} \delta_{v=u^2} \sum_{k=1}^d \left(\sum_{i=1}^d \partial_{x_i} \beta_{ik}(u^1) \sum_{j=1}^d \partial_{x_j} \beta_{jk}(u^2) \right) dv \\ &= -2 \int_{\mathbb{R}} \delta_{v=u^1} \delta_{v=u^2} \sum_{i,j,k=1}^d \sigma_{ik}(u^1) \partial_{x_i} u^1 \sigma_{jk}(u^2) \partial_{x_j} u^2 dv \\ &= -2 \int_{\mathbb{R}} \delta_{v=u^1} \delta_{v=u^2} \sum_{i,j=1}^d b_{ij}(v) \partial_{x_i} u^1 \partial_{x_j} u^2 dv. \end{aligned}$$

Note that, informally (justified as in [11] based on the chain-rule Definition 2.3(ii)),

$$2 \int_{\mathbb{R}} \nabla_x g^1 \cdot b(v) \nabla_x g^2 dv = 2 \sum_{i,j=1}^d \int_{\mathbb{R}} b_{ij}(v) \delta_{v=u^1} \partial_{x_i} u^1 \delta_{v=u^2} \partial_{x_j} u^2 dv.$$

We thus obtain

$$\partial_t \int_{\mathbb{R}^{d+1}} g^1(1 - g^2) dv dx \leq \int_{\mathbb{R}^d} 1_{u^1 \geq u^2} (S^1 - S^2) dx.$$

Since $\int g^1(1 - g^2) dv dx = \int (u^1 - u^2)_+ dx$, this implies

$$\int_{\mathbb{R}^d} (u^1(t) - u^2(t))_+ dx \leq \int_{\mathbb{R}^d} (u_0^1 - u_0^2)_+ dx + \int_0^t \int_{\mathbb{R}^d} 1_{u^1 \geq u^2} (S^1 - S^2) dx dr,$$

which by reversing the roles of u^1 and u^2 implies (B.3).

Existence: Step 1: Assume that $u_0 \in C_c^\infty(\mathbb{R}^d_x)$ and $S \in C_c^\infty((0, T) \times \mathbb{R}^d_x)$.

The construction of solutions relies on a smooth, non-degenerate approximation of A, b . Let $A^\varepsilon : \mathbb{R} \rightarrow \mathbb{R}^d$ and $b^\varepsilon : \mathbb{R} \rightarrow \mathcal{S}_+^{d \times d}$ be smooth, Lipschitz continuous, satisfying $b^\varepsilon(u) \geq \varepsilon \text{Id}$ for all $u \in \mathbb{R}$, $\varepsilon > 0$ and $A^\varepsilon, b^\varepsilon \rightarrow A, b$ locally uniformly. Then by [26] there is a classical solution to

$$\partial_t u^\varepsilon + \text{div} A^\varepsilon(u^\varepsilon) = \text{div}(b^\varepsilon(u^\varepsilon) \nabla u^\varepsilon) + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}^d_x. \quad (\text{B.5})$$

For $\eta \in C^2(\mathbb{R}_v)$ convex we have

$$\begin{aligned} \partial_t \int_{\mathbb{R}^d} \eta(u^\varepsilon(t)) dx &= \int_{\mathbb{R}^d} \eta'(u^\varepsilon(t))(-\operatorname{div} A^\varepsilon(u^\varepsilon) + \operatorname{div}(b^\varepsilon(u^\varepsilon)\nabla u^\varepsilon) + S(t, x)) dx \\ &= \int_{\mathbb{R}^d} [-\eta'(u^\varepsilon(t))(A^\varepsilon)'(u^\varepsilon) \cdot \nabla u^\varepsilon - \eta''(u^\varepsilon(t))(\nabla u^\varepsilon \cdot b^\varepsilon(u^\varepsilon)\nabla u^\varepsilon) + \eta'(u^\varepsilon(t))S(t, x)] dx \\ &\leq \int_{\mathbb{R}^d} \eta'(u^\varepsilon(t))S(t, x) dx. \end{aligned} \tag{B.6}$$

Hence, by a standard approximation argument, for all $p \in [1, \infty)$,

$$\frac{1}{p} \partial_t \int_{\mathbb{R}^d} |u^\varepsilon(t)|^p dx \leq \int_{\mathbb{R}^d} u^\varepsilon(t)^{[p-1]} S(t, x) dx \lesssim \int_{\mathbb{R}^d} (|u^\varepsilon(t)|^p + |S(t, x)|^p) dx$$

and thus

$$\sup_{t \in [0, T]} \|u^\varepsilon(t)\|_{L_x^p} \leq C(\|u_0\|_{L_x^p} + \|S\|_{L_{t,x}^p}). \tag{B.7}$$

By the L^1 -contraction (B.3) we further have, uniformly in $\varepsilon > 0$,

$$\begin{aligned} \sup_{t \in [0, T]} \|u^\varepsilon\|_{\mathbb{B}\dot{V}_x} &\leq \|u_0\|_{\mathbb{B}\dot{V}_x} + \sup_{t \in [0, T]} \|S\|_{\mathbb{B}\dot{V}_x} \\ \|\partial_t u^\varepsilon(t, \cdot)\|_{L_x^1} &\leq \|\partial_t u^\varepsilon(0)\|_{L_x^1} + \|\partial_t S\|_{L_{t,x}^1} \\ &\leq \|\operatorname{div} A(u_0) + \operatorname{div}(b(u_0)\nabla u_0) + S(0, \cdot)\|_{L_x^1} + \|\partial_t S\|_{L_{t,x}^1}. \end{aligned}$$

Since u^ε is a classical solution, it is easy to verify that u^ε is an entropy solution following the lines of [11, Section 7]. The above estimates imply the convergence (of a non-re-labeled subsequence) $u^\varepsilon \rightarrow u$ in $C([0, T]; L^1(\mathbb{R}^d))$. The verification that u is an entropy solution again follows from the same arguments as [11, Section 7]. The L^p -bound (B.4) follows from (B.7).

Step 2: Let now $u_0 \in L^1(\mathbb{R}^d)$ and $S \in L^1((0, T) \times \mathbb{R}^d)$.

We choose $u_0^\varepsilon \in C_c^\infty(\mathbb{R}^d)$ and $S^\varepsilon \in C_c^\infty((0, T) \times \mathbb{R}^d)$ such that $u_0^\varepsilon \rightarrow u_0$ in $L^1(\mathbb{R}^d)$ and $S^\varepsilon \rightarrow S$ in $L^1((0, T) \times \mathbb{R}^d)$. By the L^1 -contraction (B.3) this implies that $u^\varepsilon \rightarrow u$ in $C([0, T]; L^1(\mathbb{R}^d))$. The verification that u is an entropy solution again follows along the lines of [11, Section 7, Step 2]. \square

Appendix C. The case $m \geq 2$

In this section we present an improvement of the results obtained in [16]. We consider

$$\partial_t u + \operatorname{div} A(u) = \Delta u^{[m]} + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}_x^d, \tag{C.1}$$

where

$$\begin{aligned} u_0 &\in L^1(\mathbb{R}_x^d), \quad S \in L^1([0, T] \times \mathbb{R}_x^d), \\ a &= A' \in L_{\text{loc}}^\infty(\mathbb{R}; \mathbb{R}^d), \\ u^{[m]} &= |u|^{m-1}u \quad \text{with } m \geq 2. \end{aligned} \tag{C.2}$$

By [11] and Appendix B there is a unique entropy solution to (C.1).

Lemma C.1. *Let $\gamma > 0$, $u_0 \in (L^1 \cap L^{1+\gamma})(\mathbb{R}_x^d)$ and $S \in (L^1 \cap L^{1+\gamma})([0, T] \times \mathbb{R}_x^d)$. Then there are $c_{\gamma,m}, C_\gamma > 0$ such that*

$$\sup_{t \in [0, T]} \|u(t)\|_{L_x^{1+\gamma}}^{1+\gamma} + c_{\gamma,m} \int_0^T \int_{\mathbb{R}_x^d} (\nabla u^{[\frac{\gamma+m}{2}]})^2 dx \leq C_\gamma (\|u_0\|_{L_x^{1+\gamma}}^{1+\gamma} + \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma}).$$

Proof. First let $u_0 \in C_c^\infty(\mathbb{R}_x^d)$ and $S \in C_c^\infty((0, T) \times \mathbb{R}_x^d)$, and let A^ε be smooth and Lipschitz continuous with $A^\varepsilon \rightarrow A$ locally uniformly. Then, for $\varepsilon > 0$, there is a unique classical solution to

$$\partial_t u^\varepsilon + \operatorname{div} A^\varepsilon(u^\varepsilon) = \varepsilon \Delta u^\varepsilon + \Delta(u^\varepsilon)^{[m]} + S(t, x) \quad \text{on } (0, T) \times \mathbb{R}_x^d.$$

From (B) we have, for $\eta \in C^2(\mathbb{R})$ convex, Lipschitz continuous,

$$\begin{aligned} \partial_t \int_{\mathbb{R}_x^d} \eta(u^\varepsilon(t)) dx &\leq \int_{\mathbb{R}_x^d} (-\eta''(u^\varepsilon(t)) |\nabla u^\varepsilon(t)|^2 |u^\varepsilon(t)|^{m-1} + \eta'(u^\varepsilon(t)) S(t, x)) dx \\ &\leq \int_{\mathbb{R}_x^d} \left(-|\nabla F^\eta(u^\varepsilon(t))|^2 + \frac{\gamma}{1+\gamma} |\eta'(u^\varepsilon(t))|^{\frac{1+\gamma}{\gamma}} + \frac{1}{1+\gamma} |S(t, x)|^{1+\gamma} \right) dx, \end{aligned}$$

where $F^\eta(u) := m \int_0^u \sqrt{\eta''(r)} |r|^{m-1} dr$. By integrating in time and choosing a suitable approximation of η this inequality may be applied to $\eta(u) = |u|^{1+\gamma}$, which yields

$$\begin{aligned} \int_{\mathbb{R}_x^d} |u^\varepsilon(t)|^{1+\gamma} dx &\lesssim \int_{\mathbb{R}_x^d} |u_0|^{1+\gamma} dx - \frac{4\gamma m(1+\gamma)}{(\gamma+m)^2} \int_0^t \int_{\mathbb{R}_x^d} (\nabla(u^\varepsilon)^{[\frac{\gamma+m}{2}]})^2 dx \\ &\quad + \int_{\mathbb{R}_x^d} (|u^\varepsilon|^{1+\gamma} + |S(t, x)|^{1+\gamma}) dx. \end{aligned}$$

Gronwall’s inequality yields

$$\sup_{t \in [0, T]} \|u^\varepsilon(t)\|_{L_x^{1+\gamma}}^{1+\gamma} + c_{\gamma,m} \int_0^T \int_{\mathbb{R}_x^d} (\nabla(u^\varepsilon)^{[\frac{\gamma+m}{2}]})^2 dx ds \leq C_\gamma (\|u_0\|_{L_x^{1+\gamma}}^{1+\gamma} + \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma}). \tag{C.3}$$

From the construction of entropy solutions (Theorem B.1) we see that $u^\varepsilon \rightarrow u$ in $C([0, T]; L^1(\mathbb{R}_x^d))$. Moreover, by (C.3) for a non-relabeled subsequence $\nabla(u^\varepsilon)^{[\frac{\gamma+m}{2}]} \rightharpoonup Z$ in $L^2([0, T] \times \mathbb{R}_x^d)$. Since $u^\varepsilon \rightarrow u$ a.e., we have $Z = \nabla(u)^{[\frac{\gamma+m}{2}]}$, which allows us to pass to the limit in (C.3).

For general $u_0 \in (L^1 \cap L^{1+\gamma})(\mathbb{R}_x^d)$ and $S \in (L^1 \cap L^{1+\gamma})([0, T] \times \mathbb{R}_x^d)$ we choose smooth, compactly supported approximations $u_0^\varepsilon, S^\varepsilon$ with $\|u_0^\varepsilon\|_{L_x^{1+\gamma}}^{1+\gamma} \leq \|u_0\|_{L_x^{1+\gamma}}^{1+\gamma}$ and $\|S^\varepsilon\|_{L_{t,x}^{1+\gamma}}^{1+\gamma} \leq \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma}$ and $u_0^\varepsilon \rightarrow u_0, S^\varepsilon \rightarrow S$ in L^1 . The corresponding entropy solution u^ε then satisfies (C.3). Due to Theorem B.1 we have $u^\varepsilon \rightarrow u$ in $C([0, T]; L^1(\mathbb{R}_x^d))$, which allows us to pass to the limit in (C.3) as above. \square

For $p \in [1, \infty)$ and $s \in (0, 1)$ we recall

$$\begin{aligned} \|f\|_{\mathcal{N}^{s,p}}^p &:= \sup_{\delta>0} \sup_{0<|z|<\delta} \int_{\mathbb{R}^d} \left| \frac{|f(x+z) - f(x)|}{|z|^s} \right|^p dx, \\ \|f\|_{\mathcal{N}^{s,p}}^p &:= \|f\|_{L^p}^p + \|f\|_{\mathcal{N}^{s,p}}^p. \end{aligned}$$

Theorem C.2. *Let $\gamma > 0, m \geq 2, u_0 \in (L^1 \cap L^{1+\gamma})(\mathbb{R}_x^d), S \in (L^1 \cap L^{1+\gamma})([0, T] \times \mathbb{R}_x^d)$. Then*

$$\|u\|_{L^{m+\gamma}([0,T]; \mathcal{N}^{\frac{2}{m+\gamma}, m+\gamma}(\mathbb{R}_x^d))}^{m+\gamma} \leq C_{\gamma,m} (\|u_0\|_{L_x^{1+\gamma}}^{1+\gamma} + \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma}).$$

If, in addition, $u_0 \in L^{m+\gamma}(\mathbb{R}_x^d)$ and $S \in L^{m+\gamma}([0, T] \times \mathbb{R}_x^d)$ then

$$u \in L^{m+\gamma}([0, T]; \mathcal{N}^{\frac{2}{m+\gamma}, m+\gamma}(\mathbb{R}_x^d))$$

with

$$\|u\|_{L^{m+\gamma}([0,T]; \mathcal{N}^{\frac{2}{m+\gamma}, m+\gamma}(\mathbb{R}_x^d))}^{m+\gamma} \leq C_{\gamma,m} (\|u_0\|_{L_x^{1+\gamma}}^{1+\gamma} + \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma} + \|u_0\|_{L_x^{m+\gamma}}^{m+\gamma} + \|S\|_{L_{t,x}^{m+\gamma}}^{m+\gamma}). \tag{C.4}$$

Proof. We again restrict ourselves to an informal derivation; the rigorous justification is standard by considering a vanishing viscosity approximation first, and then using lower semicontinuity. From [16, Lemma 4.1] we recall the elementary inequality, for $m \geq 2$,

$$|r - s|^m \leq c|r^{[m/2]} - s^{[m/2]}|^2, \quad \forall r, s \in \mathbb{R},$$

for some $c > 0$. Hence,

$$\begin{aligned} |\Delta_e^h u(x)|^m &= |u(x + he) - u(x)|^m \leq c|u(x + he)^{[m/2]} - u(x)^{[m/2]}|^2 \\ &= c|\Delta_e^h u^{[m/2]}(x)|^2 \end{aligned}$$

and thus, by Lemma C.1,

$$\begin{aligned} &\int_0^T \sup_{h>0} \sup_{e \in \mathbb{R}^d, |e|=1} \int_{\mathbb{R}^d} \left| \frac{\Delta_e^h u(t, x)}{h^{\frac{2}{m+\gamma}}} \right|^{m+\gamma} dx dt \\ &= \int_0^T \sup_{h>0} \sup_{e \in \mathbb{R}^d, |e|=1} \int_{\mathbb{R}^d} h^{-2} |\Delta_e^h u(t, x)|^{m+\gamma} dx dt \\ &\leq c \int_0^T \sup_{h>0} \sup_{e \in \mathbb{R}^d, |e|=1} \int_{\mathbb{R}^d} h^{-2} |\Delta_e^h u^{[\frac{m+\gamma}{2}]}(t, x)|^2 dx dt \\ &\leq c \int_0^T \int_{\mathbb{R}^d} |\nabla u^{[\frac{m+\gamma}{2}]}(t, x)|^2 dx dt \leq C_{\gamma,m} (\|u_0\|_{L_x^{1+\gamma}}^{1+\gamma} + \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma}). \end{aligned}$$

This implies

$$\int_0^T \|u(t, \cdot)\|_{\mathcal{N}^{\frac{2}{m+\gamma}, m+\gamma}(\mathbb{R}_x^d)}^{m+\gamma} dt \leq C_{\gamma,m} (\|u_0\|_{L_x^{1+\gamma}}^{1+\gamma} + \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma}).$$

Using Lemma C.1 with γ replaced by $m - 1 + \gamma$ yields

$$\|u\|_{L^\infty([0, T]; L^{m+\gamma}(\mathbb{R}_x^d))}^{m+\gamma} \leq C_{m, \gamma} (\|u_0\|_{L_x^{m+\gamma}}^{m+\gamma} + \|S\|_{L_{t,x}^{m+\gamma}}^{m+\gamma}).$$

This implies that

$$\|u\|_{L^{m+\gamma}([0, T]; \mathcal{N}^{\frac{2}{m+\gamma}, m+\gamma}(\mathbb{R}^d))}^{m+\gamma} \leq C_\gamma (\|u_0\|_{L_x^{1+\gamma}}^{1+\gamma} + \|S\|_{L_{t,x}^{1+\gamma}}^{1+\gamma}) + C_{m, \gamma} (\|u_0\|_{L_x^{m+\gamma}}^{m+\gamma} + \|S\|_{L_{t,x}^{m+\gamma}}^{m+\gamma}).$$

□

Appendix D. Optimality and scaling

In this section we present scaling arguments that indicate the optimal regularity of solutions of porous media equations. We then show that these estimates are indeed sharp since they are attained by the Barenblatt solution. Consider

$$\begin{aligned} \partial_t u &= \Delta(|u|^{m-1}u) \quad \text{on } (0, T) \times \mathbb{R}_x^d, \\ u(0) &= u_0 \quad \text{on } \mathbb{R}_x^d, \end{aligned} \tag{D.1}$$

with $u_0 \in L^1(\mathbb{R}_x^d)$, $m > 1$.

Lemma D.1. *Assume that for some $s \geq 0$, $p \geq 1$, and $C \geq 0$ we have*

$$\|u\|_{L^p([0, T]; \dot{W}^{s,p}(\mathbb{R}_x^d))}^p \leq C \|u_0\|_{L^1(\mathbb{R}_x^d)} \tag{D.2}$$

for all solutions u to (D.1). Then necessarily $p \leq m$ and $s \leq \frac{p-1}{p} \frac{2}{m-1} \leq \frac{2}{m}$.

Proof. Given a solution u to (D.1), for every $\eta > 0$, also $\tilde{u}(t, x) := u(\eta t, x)\eta^{\frac{1}{m-1}}$ is a solution to (D.1). Since $\|\tilde{u}\|_{L^p([0, T]; \dot{W}^{s,p}(\mathbb{R}_x^d))}^p = \eta^{\frac{p}{m-1}-1} \|u\|_{L^p([0, \eta T]; \dot{W}^{s,p}(\mathbb{R}_x^d))}^p$ and $\|\tilde{u}(0)\|_{L^1(\mathbb{R}_x^d)} = \eta^{\frac{1}{m-1}} \|u_0\|_{L^1(\mathbb{R}_x^d)}$, from (D.2) we obtain

$$\|u\|_{L^p([0, T]; \dot{W}^{s,p}(\mathbb{R}_x^d))}^p \leq C \eta^{1-\frac{p-1}{m-1}} \|u_0\|_{L^1(\mathbb{R}_x^d)}.$$

This leads to a contradiction (letting $\eta \uparrow \infty$), unless

$$p \leq m. \tag{D.3}$$

Similarly, we may rescale in space: Given a solution u to (D.1), for every $\eta > 0$, also $\tilde{u}(t, x) := u(t, \eta x)\eta^{-\frac{2}{m-1}}$ is a solution to (D.1). Note $\|\tilde{u}(0)\|_{L^1(\mathbb{R}_x^d)} = \eta^{-\frac{2}{m-1}-d} \|u_0\|_{L^1(\mathbb{R}_x^d)}$ and $\|\tilde{u}\|_{L^p([0, T]; \dot{W}^{s,p}(\mathbb{R}_x^d))}^p = \eta^{-\frac{2}{m-1}p+ps-d} \|u\|_{L^p([0, T]; \dot{W}^{s,p}(\mathbb{R}_x^d))}^p$. Hence, by (D.2),

$$\|u\|_{L^p([0, T]; \dot{W}^{s,p}(\mathbb{R}_x^d))}^p \leq C \eta^{\frac{2}{m-1}(p-1)-ps} \|u_0\|_{L^1(\mathbb{R}_x^d)},$$

which leads to a contradiction unless $s \leq \frac{p-1}{p} \frac{2}{m-1}$. Maximizing the right hand side under (D.3) yields $p = m$ and $s \leq 2/m$. □

Example D.2. Consider the Barenblatt solution

$$u(t, x) = t^{-\alpha} (C - k|x t^{-\beta}|_+^2)^{\frac{1}{m-1}},$$

where $m > 1$, $\alpha = \frac{d}{d(m-1)+2}$, $k = \frac{\alpha(m-1)}{2md}$, $\beta = \frac{\alpha}{d}$ and $C > 0$ is a free constant. Then

$$u \in L^m([0, T]; \dot{W}^{s,m}(\mathbb{R}_x^d)) \implies s < 2/m.$$

Proof. With $F(x) = (C - k|x|^2)_+^{\frac{1}{m-1}}$ we have $u(t, x) = t^{-\alpha} F(x t^{-\beta})$. We next observe that, for $s \in (0, 1)$,

$$\begin{aligned} \|u(t, \cdot)\|_{\dot{W}^{s,m}(\mathbb{R}_x^d)}^m &= \int_{\mathbb{R}_x^d} \int_{\mathbb{R}_y^d} \frac{|u(t, x) - u(t, y)|^m}{|x - y|^{sm+d}} dx dy \\ &= t^{-\alpha m - \beta(sm+d) + 2d\beta} \|F\|_{\dot{W}^{s,m}(\mathbb{R}_x^d)}^m. \end{aligned}$$

Hence,

$$\|u\|_{L^m([0, T]; \dot{W}^{s,m}(\mathbb{R}_x^d))}^m = \|t^{-\alpha m - \beta(sm+d) + 2d\beta}\|_{L^1([0, T])} \|F\|_{\dot{W}^{s,m}(\mathbb{R}_x^d)}^m,$$

which is finite if and only if

$$-\alpha m - \beta(sm + d) + 2d\beta > -1 \quad \text{and} \quad F \in \dot{W}^{s,m}(\mathbb{R}_x^d).$$

Hence, necessarily

$$-m - \frac{1}{d}(sm + d) + 2 > -\frac{1}{\alpha} = -\left(\frac{d(m-1) + 2}{d}\right),$$

which is equivalent to $2 > ms$. In the case $s \in (1, 2)$ we observe that $\partial_{x_i} u(t, x) = t^{-(\alpha+\beta)} F_{x_i}(x t^{-\beta})$, so that analogous arguments may be applied. \square

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