JEMS

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Genus zero global surfaces of section for Reeb flows and a result of Birkhoff

Received December 16, 2019

Abstract. We exhibit sufficient conditions for a finite collection of periodic orbits of a Reeb flow on a closed 3-manifold to bound a positive global surface of section with genus zero. These conditions turn out to be C^{∞} -generically necessary. Moreover, they involve linking assumptions on periodic orbits with Conley–Zehnder index ranging in a finite set determined by the ambient contact geometry. As an application, we re-prove and generalize a classical result of Birkhoff on the existence of annulus-like global surfaces of section for geodesic flows on positively curved 2-spheres.

Keywords. Reeb flows, pseudo-holomorphic curves, periodic orbits, global surfaces of section

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Mathematics Subject Classification (2020): Primary 37J55; Secondary 53D10

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1. Introduction

Transverse foliations can be used as tools to study flows in dimension three. They allow for a decomposition into discrete two-dimensional systems. The best scenario is a transverse foliation whose leaves are global surfaces of section. The purpose of this paper is to provide conditions for a finite collection of periodic trajectories of a Reeb flow to bound a positive global surface of section with genus zero. Our main result (Theorem 1.11) explains why it suffices to make linking assumptions on periodic orbits with Conley– Zehnder index in a finite set of values determined by the ambient contact geometry. Tools come from pseudo-holomorphic curve theory in symplectic cobordisms developed by Hofer, Wysocki and Zehnder [18, 20–22, 24]. As an application, we explain why a classical theorem of Birkhoff on the existence of annulus-like global surfaces of section for positively curved geodesic flows on S^2 follows as a particular case.

1.1. Historical remarks

Let ϕ^t be a smooth flow on a smooth closed connected oriented 3-manifold M, generated by a vector field X.

Definition 1.1. A global surface of section for ϕ^t is an embedded compact surface $\Sigma \hookrightarrow M$ satisfying:

(i) $\partial \Sigma$ consists of periodic orbits (if non-empty) and *X* is transverse to $\Sigma \setminus \partial \Sigma$.

(ii) For every $p \in M$ there exist $t_+ > 0, t_- < 0$ such that $\phi^{t_{\pm}}(p) \in \Sigma$.

Remark 1.2. We always orient a global surface of section by the ambient orientation and the co-orientation induced by the flow. Flow lines intersect the interior of the section with sign + 1.

Definition 1.3. A global surface of section is *positive* if it orients its boundary along the flow.

The idea of a global surface of section goes back to Poincaré's work on Celestial Mechanics, in particular the *planar circular restricted three-body problem* (PCR3BP). Poincaré studies subcritical energy levels when almost all mass is concentrated in the primary around which the satellite moves, and finds annulus-like global surfaces of section bounded by the retrograde and the direct orbits. These situations arise as perturbations of an integrable system (rotating Kepler problem).

One of the first results for systems which are far from integrable is due to Birkhoff. A *Birkhoff annulus* over an embedded closed geodesic on a Riemannian 2-sphere consists of the unit vectors based at the geodesic pointing towards one of the hemispheres determined by it. **Theorem 1.4** (Birkhoff [5]). Let c be an embedded closed geodesic on a positively curved Riemannian 2-sphere. Then a Birkhoff annulus over c is a positive global surface of section for the geodesic flow on the unit sphere bundle.

There are no dynamical hypotheses to be checked in Birkhoff's theorem, but one gets strong dynamical conclusions. Positivity of the curvature and embeddedness of the closed geodesic can be checked by 'looking at' the geometric data.

The systems studied by Poincaré and Birkhoff are particular examples of Reeb flows of contact forms defining the standard contact structure on $\mathbb{R}P^3$ [3]. Motivated by their results, we want to understand the contact topological and dynamical properties that guarantee the existence of a global surface of section bounded by a prescribed collection of closed Reeb orbits. We seek for the counterpart of Theorem 1.4 in the realm of Reeb flows on planar contact manifolds. Pseudo-holomorphic curves can be used to implement this program. The case of disk-like global surfaces of section for a non-degenerate Reeb flow on the tight 3-sphere is handled by the statement below.

Theorem 1.5 ([27]). Consider a non-degenerate Reeb flow on the standard contact 3sphere. A periodic orbit γ bounds a disk-like global surface of section if and only if the following conditions are satisfied:

- (i) γ is unknotted and has self-linking number -1.
- (ii) The Conley–Zehnder index of γ is larger than or equal to 3.
- (iii) Every closed Reeb orbit with Conley–Zehnder index 2 is linked with γ .

Condition (i) in Theorem 1.5 is purely contact-topological; it means that γ binds an open book decomposition with disk-like pages supporting the contact structure. This is how one should rephrase (i) when looking for generalizations of the above statement. Condition (ii) is on the linearized dynamics along γ ; it implies that the flow twists fast enough near γ . The linking assumption in (iii) mixes dynamics and topology. It distinguishes the closed Reeb orbits which potentially obstruct the existence of a global surface of section bounded by γ .

In this paper we study Reeb flows on planar contact 3-manifolds, and prove a version of Theorem 1.5 for positive global surfaces of section with genus zero, and arbitrary number of boundary components. We provide conditions that are sufficient, and C^{∞} generically necessary, for a transverse link L formed by closed Reeb orbits to bound such a global section. It is necessary that L binds a planar open book decomposition supporting ξ and, C^{∞} -generically, that the Conley–Zehnder indices of the components of L relative to a page are positive. The counterpart of the linking assumption (iii) in Theorem 1.5 is made only on the closed trajectories in the complement of L that have Conley–Zehnder index in a finite interval of integers determined by the ambient contact geometry. This is clearly a necessary condition. Sufficiency of these conditions relies on the analysis of certain families of pseudo-holomorphic curves inspired by [1,22].

1.2. Main results

A *contact form* on an oriented closed 3-manifold M is a 1-form α such that $\alpha \wedge d\alpha$ is nowhere vanishing. In particular, ker $d\alpha$ is transverse to the *contact structure* $\xi = \ker \alpha$. Contact structures arising in this way are co-orientable since α orients TM/ξ . The orientation induced by $\alpha \wedge d\alpha$ depends only on ξ , and ξ is called *positive* if $\alpha \wedge d\alpha > 0$. The pair (M, ξ) is a *contact manifold*. The *Reeb vector field* X_{α} associated to α is implicitly defined by

$$d\alpha(X_{\alpha}, \cdot) = 0, \quad \alpha(X_{\alpha}) = 1.$$
⁽¹⁾

Its flow ϕ_{α}^{t} is called the *Reeb flow* of α .

An open book decomposition of M is a pair $\Theta = (\Pi, L)$ consisting of a link $L \subset M$ and a smooth fibration $\Pi : M \setminus L \to \mathbb{R}/\mathbb{Z}$ with a normal form near L. Namely, a neighborhood N of L is homeomorphic to $L \times \mathbb{D}$ in such a way that $L \simeq L \times \{0\}$ and Π is represented as $(p, re^{i2\pi x}) \mapsto x$ on $N \setminus L$. The closure of a fiber is called a *page*, L is called the *binding*, and Θ is said to be *planar* if the pages have genus zero. It is important to notice that Θ and the orientation of M naturally orient the pages, and hence also the binding L. One says that Θ supports ξ if there is a contact form α_0 such that $\xi = \ker \alpha_0$, $\alpha_0 > 0$ on L, and $d\alpha_0 > 0$ on the interior of each page. The contact structure ξ is *planar* if it is supported by a planar open book.

Remark 1.6. It is possible to show that L binds a supporting open book decomposition if, and only if, L bounds a positive global surface of section for the Reeb flow of some defining contact form.

When the binding L consists of periodic Reeb orbits we write μ_{CZ}^{Θ} for the Conley– Zehnder index of a binding orbit computed in a symplectic trivialization of ξ that does not wind with respect to the normal of a page. This means that if we push a connected component of L in the direction of such a trivialization we obtain a loop with algebraic intersection number zero with each page. We denote by ρ^{Θ} the transverse rotation number computed in the same trivialization. See Section 2.1 for precise definitions.

Definition 1.7. Consider a null-homologous link L consisting of periodic orbits of some flow on a 3-manifold. An oriented Seifert surface for L is said to be *positive* (with respect to the flow) if it orients every component of L along the flow.

Our first result, which is to be seen as preliminary work towards our main result (Theorem 1.11), reads as follows.

Theorem 1.8. Let the contact form α define a positive contact structure ξ on the closed, connected and oriented 3-manifold M. Let L be a null-homologous link consisting of periodic Reeb orbits, and let $b \in H_2(M, L)$. Consider the following assertions.

- (i) L bounds a positive global surface of section of genus zero for the Reeb flow of α representing the class b.
- (ii) L binds a planar open book supporting ξ with pages that are global surfaces of section for the Reeb flow of α and represent the class b.

- (iii) *L* binds a planar open book Θ supporting ξ with pages that represent the class *b*, and the following hold:
 - (a) $\mu_{CZ}^{\Theta}(\gamma) > 0$ for every component $\gamma \subset L$.
 - (b) All periodic orbits in $M \setminus L$ have non-zero intersection number with b.

Then (iii) \Rightarrow (ii) \Rightarrow (i). Moreover, (i) \Rightarrow (iii) holds C^{∞} -generically; in fact, it holds if every periodic orbit $\gamma \subset L$ satisfying $\rho^{\Theta}(\gamma) = 0$ is hyperbolic.

Remark 1.9. The C^{∞} -genericity condition used to prove (i) \Rightarrow (iii) holds if all components of *L* are non-degenerate periodic Reeb orbits.

Remark 1.10. In [29] the reader finds a version of Theorem 1.8 for general flows in dimension 3, which is based on a result of Fried [16]. The basic mechanism of proof comes from linking assumptions on the invariant measures of the flow, as in the theory of asymptotic cycles initiated by Schwartzman [40]. Proofs in [29] use techniques from Sullivan's work [44]. The paper [17] by Ghys provides a rich introduction to this topic, with many new ideas.

Now we work towards our main result, which concerns Reeb flows on contact manifolds (M, ξ) for which ξ is a trivial vector bundle over M. This provides the closed Reeb orbits with an absolute Conley–Zehnder index, allowing us to formulate a much weaker linking assumption than the one in Theorem 1.8.

Given a defining contact form α on (M, ξ) , we fix a global symplectic trivialization τ_{gl} of $(\xi = \ker \alpha, d\alpha)$ and denote Conley–Zehnder indices computed in this trivialization by $\mu_{CZ}^{\tau_{gl}}$. Let *L* be a null-homologous link consisting of periodic Reeb orbits. Let Σ be an oriented Seifert surface for *L* which is positive as in Definition 1.7. For each connected component $\gamma \subset L$ define

$$m(\gamma, \Sigma) \in \mathbb{Z}$$

to be the winding number, measured in τ_{gl} , of a non-vanishing vector field in $T_{\gamma}\Sigma \cap \xi$. In particular, we have

$$-\mathrm{sl}(L,\Sigma) = \sum_{\gamma} m(\gamma,\Sigma)$$

for the self-linking number of L with respect to Σ . Consider

$$C_{0} = \sum_{\{\gamma \mid m(\gamma, \Sigma) \ge 0\}} (m(\gamma, \Sigma) + 1),$$
(2)

and set

$$I(L, \Sigma, \tau_{\rm gl}) := [-2C_0 + 1, 2C_0 + 1] \cap \mathbb{Z}.$$
(3)

Our main result, formulated below only for disconnected links of periodic orbits since the connected case is handled by Theorem 1.14, reads as follows.

Theorem 1.11. Let the contact form α define a positive contact structure ξ on the closed, connected and oriented 3-manifold M. Suppose that there exists a symplectic trivialization τ_{g1} of $(\xi, d\alpha)$. Let L be a null-homologous disconnected link formed by periodic Reeb orbits, and let $b \in H_2(M, L)$. Consider the following assertions:

- (i) L bounds a positive global surface of section of genus zero for the Reeb flow of α representing the class b.
- (ii) *L* binds a planar open book supporting ξ with pages that are global surfaces of section for the Reeb flow of α and represent the class *b*.
- (iii) *L* binds a planar open book Θ supporting ξ with pages that represent the class *b*, and the following hold:
 - (a) $\mu_{CZ}^{\Theta}(\gamma) > 0$ for every component $\gamma \subset L$.
 - (b) All periodic Reeb orbits in $M \setminus L$ satisfying $\mu_{CZ}^{\tau_{gl}} \in I(L, page, \tau_{gl})$ have non-zero intersection number with b.

Then (iii) \Rightarrow (ii) \Rightarrow (i). Moreover, (i) \Rightarrow (iii) holds C^{∞} -generically; in fact, it holds if every periodic orbit $\gamma \subset L$ satisfying $\rho^{\Theta}(\gamma) = 0$ is hyperbolic.

Remark 1.12. In Theorem 1.11 the set of periodic orbits that have to 'link' with *L* for the implication (iii) \Rightarrow (ii) to hold is drastically smaller than the one in Theorem 1.8. Linking with all periodic orbits can not be directly obtained from the above hypotheses. In the proof of (iii) \Rightarrow (ii) one only needs to check linking with the periodic orbits with Conley–Zehnder index in $I(L, \text{page}, \tau_{gl})$ and period less than some positive constant depending on α and the open book. Generically this is a finite set of periodic orbits.

Remark 1.13. The class of closed contact 3-manifolds which are planar and whose contact structures admit a global trivialization contains the tight 3-sphere and the standard lens spaces L(p, p - 1), and is closed under contact connected sums. As a consequence, one can build a large family of examples that can carry contact forms satisfying the assumptions of Theorem 1.11, some of which are particularly relevant in Celestial Mechanics like, for instance, ($\mathbb{R}P^3 \# \mathbb{R}P^3$, $\xi_{std} \# \xi_{std}$). Persistence of planarity under contact connected sums can be proved using van Koert's book sums [33]; see [45, Section 2.2] for more details. Persistence of triviality of the contact structure as a symplectic vector bundle can be checked by hand.

We compute $I(L, \text{page}, \tau_{\text{gl}})$ in two examples. Consider \mathbb{R}^4 with coordinates (q_1, p_1, q_2, p_2) and its standard symplectic form $\omega_0 = \sum_j dq_j \wedge dp_j$. The primitive $\frac{1}{2} \sum_j (q_j dp_j - p_j dq_j)$ induces a contact form λ_0 on $S^3 = \{q_1^2 + p_1^2 + q_2^2 + p_2^2 = 1\}$, and $\xi_{\text{std}} = \ker \lambda_0$ is called the *standard* contact structure on S^3 . The Reeb flow of λ_0 is π -periodic, and its orbits are the fibers of the Hopf fibration $S^3 \rightarrow S^2$. Since λ_0 is antipodal symmetric, it descends to a contact form on $\mathbb{R}P^3 = S^3/\{\pm 1\}$ which we again denote by λ_0 . It defines a contact structure which we again denote by ξ_{std} and call standard. The Hopf fibration on S^3 is antipodal symmetric, hence it induces a fibration of $\mathbb{R}P^3$ by circles which we again call Hopf fibers. Any link transversely isotopic to a pair of Hopf fibers will be called a *Hopf link*, both in (S^3, ξ_{std}) or in $(\mathbb{R}P^3, \xi_{\text{std}})$.

Hopf links in (S^3, ξ_{std}) or in $(\mathbb{R}P^3, \xi_{std})$ bind supporting open book decompositions with annulus-like pages. We can use an ambient contact isotopy to put a Hopf link in a normal form, for instance it is interesting to see $\mathbb{R}P^3$ as the unit tangent bundle of the round metric on S^2 and realize a Hopf link *L* as velocity vectors $\gamma_1 = \dot{c}, \gamma_2 = -\dot{c}$ of a unit speed great circle *c* in S^2 traversed in both directions. In this form a Birkhoff annulus is a page of the aforementioned open book decomposition Θ . Let Σ be a page of Θ and let τ_{gl} be a trivialization of ξ_{std} . The winding number measured in τ_{gl} of a non-vanishing vector field in $T_{\gamma_i} \Sigma \cap \xi_{std}$ vanishes for i = 1, 2 and thus $m(\gamma_i, \Sigma) = 0$. Using (2) and (3) we compute $C_0 = 2$ and $I(L, \Sigma, \tau_{gl}) = \{-3, ..., 5\}$. This interval is not sharp, and we expect it to be further shortened to $\{0, 1, 2\}$ in the non-degenerate case. The same computation goes through for Hopf links in (S^3, ξ_{std}) .

A version of Theorem 1.11 was already available when *L* is connected, generalizing Theorem 1.5 to possibly degenerate contact forms. When ξ is supported by a planar open book decomposition with connected binding then $(M, \xi) = (S^3, \xi_{std})$ and the binding is unknotted with self-linking number -1. There exists a global trivialization τ_{gl} of ξ_{std} which is symplectic with respect to the standard symplectic structure of \mathbb{R}^4 , and is unique up to homotopy. One can then use τ_{gl} to define Conley–Zehnder indices $\mu_{CZ}^{\tau_{gl}}$ of periodic Reeb orbits. Note also that global surfaces of section for Reeb flows with connected boundary must be positive (Stokes' theorem), and if they have genus zero (disks) then their boundaries are unknotted with self-linking number -1. Finally, on the 3-sphere any Seifert surface for a periodic Reeb orbit singles out a homotopy class of symplectic trivializations of the contact structure along the orbit in an obvious manner. This homotopy class does not depend on the Seifert surface. We write $\mu_{CZ}^{Seifert}$ for the associated Conley– Zehnder index.

Theorem 1.14. Let γ be a periodic orbit of a Reeb flow on the tight 3-sphere. Consider the following assertions:

- (i) γ bounds a disk-like global surface of section for the Reeb flow.
- (ii) γ binds a planar supporting open book with pages that are disk-like global surfaces of section for the Reeb flow.
- (iii) γ is unknotted, has self-linking number -1, and the following hold:
 - (a) $\mu_{CZ}^{\text{Seifert}}(\gamma) = \mu_{CZ}^{\tau_{\text{gl}}}(\gamma) 2 > 0.$
 - (b) All periodic Reeb orbits γ' in the complement of γ satisfying either $\mu_{CZ}^{\tau_{gl}}(\gamma') = 2$, or $\mu_{CZ}^{\tau_{gl}}(\gamma') = 1$ and γ' is degenerate, are linked with γ .

Then (iii) \Rightarrow (i) \Rightarrow (i). Moreover, (i) \Rightarrow (iii) holds C^{∞} -generically; in fact, it holds if γ is hyperbolic whenever $\rho^{\tau_{gl}}(\gamma) = 1$.

Proof. When all periodic Reeb orbits are non-degenerate the equivalence of (i)–(iii) is given by Theorem 1.5. If non-degeneracy is dropped then the implications (iii) \Rightarrow (ii) \Rightarrow (i) are contained in [31, Theorem 1.7].

The proof that (i) \Rightarrow (iii) holds under the above stated C^{∞} -genericity condition goes as follows. Assume that γ bounds a disk-like global surface of section. Since its self-linking number is necessarily equal to -1, we compute $\mu_{CZ}^{\tau_{gl}}(\gamma) - 2 = \mu_{CZ}^{\text{Seifert}}(\gamma)$. Condition (iii)(b) is clearly satisfied, and we need to show that (iii)(a) also holds. Suppose, for contradiction, that $\mu_{CZ}^{\tau_{gl}}(\gamma) \leq 2$. Then the rotation number of the transverse linearized dynamics along γ is non-positive when computed in a Seifert framing. It must vanish

since otherwise nearby trajectories would intersect the global surface of section negatively. Hence $\mu_{CZ}^{\tau_{gl}}(\gamma) \in \{1, 2\}$ and γ is degenerate if $\mu_{CZ}^{\tau_{gl}}(\gamma) = 1$. By assumption γ is hyperbolic, hence non-degenerate, and we get $\mu_{CZ}^{\tau_{gl}}(\gamma) = 2$. Its stable manifold contains infinitely long trajectories that never touch the global surface of section, and this is a contradiction.

1.3. Applications

We derive two applications. The first is Birkhoff's theorem, thus showing that Theorem 1.8 is a generalization of Theorem 1.4.

Proof of Theorem 1.4. Suppose that the Birkhoff annulus A associated to an embedded closed geodesic γ on a positively curved 2-sphere is not a global surface of section. The contact structure on the unit sphere bundle induced by the Hilbert form associated to the metric is diffeomorphic to the standard contact structure on $\mathbb{R}P^3$, and A is one page of a supporting open book decomposition. By positivity of the curvature, the rotation numbers of the binding orbits $\dot{\gamma}$ and $-\dot{\gamma}$ with respect to the pages are strictly positive. In view of implications (iii) \Rightarrow (ii) \Rightarrow (i) in Theorem 1.8, there exists a closed geodesic β , say parametrized by unit speed, such that $\dot{\beta}$ has zero algebraic intersection number with A in the unit sphere bundle. Since the geodesic vector field is transverse to the interior of A, we conclude that β does not touch γ on the base, hence it is contained in the interior of one of the hemispheres determined by γ . The complement of $\gamma \cup \beta$ has a distinguished connected component Ω containing boundary points in both γ and β . Topologically, the closure of Ω is an annulus, its boundary has two components: γ is one of them, the other consists of finitely many geodesic arcs in β . The sum of the external angles (there may be none in case β is embedded) in the boundary of Ω is non-negative. Since the Euler characteristic of the annulus vanishes, we conclude from the Gauss-Bonnet theorem that the integral of the Gaussian curvature over Ω is non-positive, contradicting the assumption that the curvature is everywhere strictly positive.

Our second application reads as follows.

Proposition 1.15. Let α be a contact form on (S^3, ξ_{std}) . Consider a pair of periodic Reeb orbits γ_0, γ_1 forming a Hopf link, with Conley–Zehnder indices ≥ 1 in a global frame. Assume that γ_0 bounds a disk-like global surface of section, and that periodic orbits γ in the complement of γ_1 with Conley–Zehnder index in $\{-3, \ldots, 5\}$ satisfy link $(\gamma, \gamma_1) \geq 0$. Then $\gamma_0 \cup \gamma_1$ bounds an annulus-like global surface of section.

Proof. The link $\gamma_0 \cup \gamma_1$ binds a supporting open book decomposition Θ with annuluslike pages. Let *A* denote a page of Θ oriented in such a way that the boundary orientation on $\gamma_0 \cup \gamma_1$ coincides with the flow orientation. Let D_0 be a disk-like global surface of section bounded by γ_0 , and let D_1 be any embedded disk spanned by γ_1 . Both D_j are oriented so that the boundary orientation on γ_j coincides with the flow orientation. Then $S = A \# \overline{D_0} \# \overline{D_1}$ defines a 2-cycle. If γ is any closed Reeb orbit in $S^3 \setminus (\gamma_0 \cup \gamma_1)$ with Conley–Zehnder index in $\{-3, \ldots, 5\}$ then

$$0 = \operatorname{int}(\gamma, S) = \operatorname{int}(\gamma, A) - \sum_{j=0,1} \operatorname{int}(\gamma, D_j) \le \operatorname{int}(\gamma, A) - 1, \text{ so } \operatorname{int}(\gamma, A) \ge 1.$$

Another feature of Θ is that a section of $TA|_{\gamma_j} \cap \xi_{\text{std}}$ does not wind with respect to a global trivialization of ξ_{std} . Hence, since $\mu_{CZ}^{\Theta}(\gamma_j) \ge 1$ we have proved (iii) in Theorem 1.11. A direct application of this theorem completes the proof.

Proposition 1.15 can be applied to the PCR3BP. A satellite is subjected to the gravitational fields of two primaries which move on circular trajectories about their center of mass. The satellite moves on the same plane of the primaries, in a rotating system which fixes the primaries, and is determined by the Hamiltonian

$$H_{\mu}(q,p) = \frac{1}{2}|p|^{2} + \langle q - \mu, ip \rangle - \frac{\mu}{|q-1|} - \frac{1-\mu}{|q|}.$$
(4)

Here $q \in \mathbb{C} \setminus \{0, 1\}$ is the position of the satellite and $p \in \mathbb{C}$ is the momentum. The primaries have masses $\mu > 0$ and $1 - \mu > 0$ and rest at $1 \in \mathbb{C}$ and $0 \in \mathbb{C}$, respectively. For energies -c below the first Lagrange value $l_1(\mu)$ the energy surface $H_{\mu}^{-1}(-c)$ contains a component $\mathcal{B}_{\mu,c}$ which projects onto a punctured topological disk about the primary at $0 \in \mathbb{C}$. Levi-Civita coordinates regularize collisions with the primary:

$$q = 2v^2$$
 and $p = -\frac{u}{\bar{v}}$.

The regularized Hamiltonian reads

$$K_{\mu,c}(v,u) := |v|^2 (H_{\mu}(p,q) + c)$$

= $\frac{1}{2} |u|^2 + 2|v|^2 \langle u, iv \rangle - \mu \Im(uv) - \frac{1-\mu}{2} - \mu \frac{|v|^2}{|2v^2 - 1|} + c|v|^2.$ (5)

The Jacobi constant *c* becomes a parameter and the regularized dynamics on $\mathcal{B}_{\mu,c}$ is the dynamics on a \mathbb{Z}_2 -symmetric sphere-like component $\mathcal{S}_{\mu,c} \subset K_{\mu,c}^{-1}(0)$, where \mathbb{Z}_2 -symmetry refers to antipodal symmetry. The Hamiltonian flow on $\mathcal{S}_{\mu,c}/\mathbb{Z}_2$ is orbit equivalent to the Reeb flow of a contact form $\lambda_{\mu,c}$ on $(\mathbb{R}P^3, \xi_{std})$.

Definition 1.16. A *T*-periodic trajectory $(q(t), p(t)), t \in \mathbb{R}/T\mathbb{Z}$, in $\mathcal{B}_{\mu,c}$ is called *retro*grade if the curve $t \mapsto q(t) \in \mathbb{C} \setminus \{0\}$ is an embedded closed curve that winds around the origin precisely once in the clockwise direction.

Retrograde orbits are shown to exist by Birkhoff's shooting method for every $0 < \mu < 1$ and every -c below $l_1(\mu)$. A nice discussion about Birkhoff's shooting method can be found in [15, Section 8.3.2]. As a closed Reeb orbit $\gamma_{\mu,c}^r$ of $\lambda_{\mu,c}$, the retrograde orbit is a Hopf fiber, i.e., a 2-unknot with rational self-linking number -1/2. If $\lambda_{\mu,c}$ is dynamically convex then $\gamma_{\mu,c}^r$ is the boundary of a rational disk-like global surface of section and a fixed point of the first return map gives a closed Reeb orbit $\gamma_{\mu,c}^d$ which is called *direct*

and shares the same properties of $\gamma_{\mu,c}^r$ (see [31]). A result of Frauenfelder and Kang [14] applies to similar regimes of the PCR3BP and gives disk-like global surfaces of section on $S_{\mu,c}$ that respect additional symmetries of the problem. The link $L = \gamma_{\mu,c}^r \cup \gamma_{\mu,c}^d$ is a Hopf link, hence it binds an open book decomposition supporting ξ_{std} .

Theorem 1.17. If the Reeb flow of $\lambda_{\mu,c}$ on $(\mathbb{R}P^3, \xi_{std})$ is dynamically convex then the link $\gamma_{\mu,c}^r \cup \gamma_{\mu,c}^d$ formed by the retrograde and the direct orbits is the binding of an open book decomposition whose pages are annulus-like global surfaces of section.

Proof. The link $h = \gamma_{\mu,c}^r \cup \gamma_{\mu,c}^d$ lifts to a Hopf link $\tilde{h} \subset (S^3, \xi_{\text{std}})$. There exists a supporting open book decomposition $\tilde{\Theta}$ with annulus-like pages and binding \tilde{h} . We can arrange $\tilde{\Theta}$ so that it is \mathbb{Z}_2 -symmetric: the binding already consists of antipodal symmetric knots, and the pages can be arranged so that the image of a page by the antipodal map is the same page. By Theorem 1.14 and by the assumed dynamical convexity, both components of \tilde{h} bound disk-like global surfaces of section. It follows from Proposition 1.15 that \tilde{h} bounds an annulus-like global surface of section \tilde{A} representing the same class in $H_2(S^3, \tilde{h})$ as the pages of $\tilde{\Theta}$. Now denote by $\Theta = \tilde{\Theta}/\{\pm 1\}$ the induced open book decomposition in $\mathbb{R}P^3$. Up to taking a double cover, any periodic trajectory γ in $\mathbb{R}P^3 \setminus h$ lifts to a periodic trajectory in $S^3 \setminus \tilde{h}$, which must then have positive intersection number with each page of $\tilde{\Theta}$. A direct application of Theorem 1.11 concludes the argument.

We observe that annulus-like global surfaces of section bounded by the retrograde and the direct orbits are proven in the following situations:

- (i) For any fixed c > 3/2 and any μ sufficiently small. This goes back to celebrated work of Poincaré [37], and is proved by Birkhoff in [4, Sections 9 and 10]. Here the system is a perturbation of the rotating Kepler problem where annulus-like global surfaces of section are easily constructed.
- (ii) For every *c* sufficiently large and any $0 < \mu < 1$. This case is proved by Conley [8]. The flow of $\lambda_{\mu,c}$ is a perturbation of the degenerate flow associated with the standard contact form λ_0 on ($\mathbb{R}P^3$, ξ_{std}). A finer account of higher order terms is necessary in order to check that the link $\gamma_{\mu,c}^r \cup \gamma_{\mu,c}^d$ bounds an annulus-like global surface of section satisfying a boundary twist condition.

Theorem 1.17 gives annulus-like global surfaces of section bounded by $\gamma_{\mu,c}^r \cup \gamma_{\mu,c}^d$ in the following new case:

(iii) For any fixed c > 3/2 and any $1 - \mu$ sufficiently small.

Genus zero global surfaces of section for Reeb flows were used in [30] to characterize standard lens spaces from a dynamical viewpoint. We expect that every dynamically convex contact form on a lens space of order p > 1 carries a periodic orbit that spans a rational disk-like global surface of section, and whose *p*-th iterate has Conley–Zehnder index equal to 3 in a trivialization that extends to a capping disk; in particular such an orbit must be elliptic. In [31] this was confirmed when p = 2. Schneider [39] handles the standard contact structure on L(p, 1), for all p > 1.

Genus zero global surfaces of section were also used by Cristofaro-Gardiner, Hutchings and Pomerleano [9] to study non-degenerate contact forms such that the first Chern class of the contact structure is torsion. Under these assumptions, they show that if there are finitely many periodic orbits then the Reeb flow admits a (rational) genus zero global surface of section, thus forcing the number of periodic orbits to be 2. In particular, there are either two or infinitely many periodic orbits.

Transverse foliations that are more general than open book decompositions can be used to study Reeb flows in dimension 3. This line of research was initiated by Hofer, Wysocki and Zehnder in their seminal paper [25] where finite-energy foliations (FEF) in the symplectization of the standard contact 3-sphere were constructed. The leaves of a FEF are finite-energy curves, and the whole foliation is invariant under the natural \mathbb{R} action on the symplectization. Finitely many leaves are \mathbb{R} -invariant trivial cylinders and project onto periodic orbits, the so-called *binding orbits*. The remaining leaves project to form a smooth foliation of the complement of the binding orbits in S^3 , whose leaves are transverse to the Reeb flow. The construction of a FEF can be done for every nondegenerate contact form defining the standard contact structure on S^3 . Stability of FEFs under contact connected sums is proved in [13]. In [10, 11, 36] one finds existence results for FEFs which apply to explicit systems coming from Celestial Mechanics and to many other explicit, real analytic and possibly degenerate, contact forms.

In [38, Section 6] a definition of more general transverse foliations was given. Recently Colin, Dehornoy and Rechtman [7] introduced the so-called broken book decompositions, and showed that a non-degenerate Reeb flow on any closed 3-manifold is transverse to the leaves of some broken book. As an application, they show that nondegenerate Reeb flows on closed 3-manifolds carry two or infinitely many periodic orbits.

1.4. Outline of proofs

We end this introduction with a rough outline of the structure of the arguments. In both Theorem 1.8 and Theorem 1.11 the implications (ii) \Rightarrow (i), and (i) \Rightarrow (iii) under the stated C^{∞} -genericity condition, have rather simple proofs when compared to the proof of (iii) \Rightarrow (ii). Most of our work is concerned with the latter implication, which is done in Section 3 for Theorem 1.8, and with some additional arguments in Section 4 for Theorem 1.11.

Let α , L, Θ and b be as in the statements. In particular, L is the binding of Θ and consists of periodic Reeb orbits of α , the open book Θ is planar and supports $\xi = \ker \alpha$, and b is the class of the pages of Θ . Denote by n the number of connected components of L. It is no loss of generality to assume that $n \ge 2$ since the case n = 1 is contained in Theorem 1.14.

By a result of Wendl [47] there exists a non-degenerate contact form $\alpha_+ = f \alpha$, where $f \in C^{\infty}(M, (1, +\infty))$, such that *L* consists of periodic Reeb orbits of α_+ with $\mu_{CZ}^{\Theta} = 1$, and a $d\alpha_+$ -compatible complex structure $J_+ : \xi \to \xi$ such that there is a foliation of $M \setminus L$

by projections of finite-energy curves in $\mathbb{R} \times M$ with no negative punctures, asymptotic to *L* at its (positive) punctures. These curves are pseudo-holomorphic with respect to a suitably defined \mathbb{R} -invariant almost complex structure \tilde{J}_+ on $\mathbb{R} \times M$ induced by (α_+, J_+) . These projected curves form the pages of an open book decomposition, represent the class *b* and are global surfaces of section for the Reeb flow of the special contact form α_+ .

The next step is to consider an almost complex structure \overline{J} on $\mathbb{R} \times M$ interpolating from \widetilde{J}_+ near the positive end, to a suitable \mathbb{R} -invariant almost complex structure \widetilde{J} induced by (α, J) near the negative end, where $J : \xi \to \xi$ is some compatible complex structure. We can require that $\mathbb{R} \times L$ is a \overline{J} -complex surface since L is a common set of periodic orbits for both α_+ and α . See Sections 2.2.1 and 2.2.2 for detailed definitions. It should be mentioned that the components of L satisfy $\mu_{CZ}^{\Theta} = 1$ as periodic Reeb orbits of α_+ , and $\mu_{CZ}^{\Theta} \ge 1$ as periodic Reeb orbits of α . Hence the Fredholm index of the holomorphic cylinders given by the components of $\mathbb{R} \times L$ can be arbitrarily negative.

The curves in the symplectization of α_+ provided by [47] can be translated up and be seen as \overline{J} -curves. Since Θ is planar, their Fredholm index is 2. The bulk of the proof of Theorem 1.8 is to show we can deform these \overline{J} -curves indefinitely down in $\mathbb{R} \times M$, and obtain as SFT-limit a holomorphic building with two levels as in Figure 1. Here a non-degeneracy assumption on α is used. The upper level consists precisely of the (possibly non-regular) \overline{J} -holomorphic cylinders in $\mathbb{R} \times L$. The bottom level consists of a genus zero connected curve *C* with no negative punctures, and *n* positive punctures where it is asymptotic to *L*. Moreover, *C* does not intersect $\mathbb{R} \times L$, and has an embedded pro-



Fig. 1. Pushing curves down a cobordism, and controlling the SFT-limit using linking assumptions and intersection theory: the curve in the bottom level does not intersect $\mathbb{R} \times L$, has an embedded projection to M, approaches its asymptotic limits according to special eigenvectors of the asymptotic operators, and belongs to a moduli space with suitable exponential weights.

jection to $M \setminus L$ transverse to the Reeb vector field of α . Key to our arguments is the intersection theory from [42], the properties of α_+ , and the assumptions on α . Finally, it is absolutely crucial that the approach of *C* to its asymptotic limits in *L* is the 'right one', more precisely, it can be shown *C* is an element of a certain moduli space with exponential weights with respect to which the corresponding weighted Conley–Zehnder indices of the components of *L* are again 1. Hence, the weighted Fredholm index is 2, and automatic transversality holds for this weighted Fredholm problem. The linking assumptions provide compactness of the connected component of the moduli space containing *C*. The arguments so far are contained in Sections 3.1 and 3.2. Hence $M \setminus L$ can again be foliated by projections of finite-energy curves as an open book, this time by surfaces transverse to the Reeb flow of α . The assumption $\mu_{CZ}^{\Theta} \geq 1$ made on the components of *L* as Reeb orbits of α now plays a role to show that the pages are global surfaces of section; see Section 3.3.

The argument for (iii) \Rightarrow (ii) in Theorem 1.11 in the non-degenerate case is analogous. It depends on some estimates, based on the algebraic invariants from [20], to ensure that only linking assumptions with periodic orbits in $M \setminus L$ with Conley–Zehnder index in the interval $I(L, page, \tau_{gl})$ are needed; see Section 4.

The passage to the degenerate case is technical and delicate, but also somewhat standard in the literature. An important ingredient is [31, Proposition 4.15], stated here as Proposition 3.35. It summarizes some of the analysis which was originally done in [22, Section 8], and guarantees that if a sequence of curves with common asymptotic limits has exponential decay at the punctures uniformly bounded away from zero, then the limiting curves have the same bounds on the decay at the corresponding punctures. Details are found in Section 3.4.

2. Preliminaries

The purpose of this section is to review the basic facts about pseudo-holomorphic curves and periodic Reeb orbits needed in the proofs, and establish notation. Fix a smooth, closed, connected, oriented 3-manifold M with a co-orientable and positive contact structure ξ . Throughout this section α , α_+ , α_- etc. denote contact forms that define ξ and are all positive multiples of each other.

2.1. Periodic orbits and Conley–Zehnder indices

A periodic α -Reeb orbit is an equivalence class of pairs $\gamma = (x, T)$ where $x : \mathbb{R} \to M$ is a periodic trajectory of the flow of the Reeb vector field X_{α} , and T > 0 is a period of x. Here we declare two pairs $\gamma = (x, T)$ and $\gamma' = (x', T')$ to be equivalent if $x(\mathbb{R}) = x'(\mathbb{R})$ and T = T'. The set of equivalence classes is denoted $\mathcal{P}(\alpha)$.

Remark 2.1. A special point (marker) is chosen on $x(\mathbb{R})$ for every periodic trajectory $x : \mathbb{R} \to M$ of X_{α} . It will be implicit in the notation $\gamma = (x, T) \in \mathcal{P}(\alpha)$ that x(0) is the marker.

Given $n \in \mathbb{N}$ the *n*-th iterate of γ is $\gamma^n = (x, nT)$. We call $\gamma = (x, T)$ simply covered, or prime, if *T* is the minimal period of *x*. When γ is not prime then it is called *multiply* covered. In any case, $\gamma = \gamma_0^n$ for unique $n \in \mathbb{N}$ and prime orbit γ_0 , where *n* is called the covering multiplicity of γ , and γ_0 is called the prime orbit underlying γ .

Let $\gamma = (x, T) \in \mathcal{P}(\alpha)$. We denote the vector bundle $x(T \cdot)^* \xi \to \mathbb{R}/\mathbb{Z}$ by ξ_{γ} . It becomes a symplectic vector bundle with $d\alpha$. Since the symplectic group is connected, ξ_{γ} is trivial as a symplectic vector bundle. Given two $d\alpha$ -symplectic trivializations σ_1 and σ_2 , take a section which is represented as a non-zero constant with respect to σ_2 , represent it with σ_1 to obtain a non-vanishing loop $t \mapsto v(t)$ in \mathbb{C} , and set wind $(\sigma_1, \sigma_2) \in \mathbb{Z}$ to be equal to the winding number of v(t). It should be thought of as the winding of σ_2 with respect to σ_1 . Throughout this paper \mathbb{R}/\mathbb{Z} is given its canonical orientation.

A complex structure $J : \xi \to \xi$ is said to be $d\alpha$ -compatible if $d\alpha(\cdot, J \cdot)$ is an inner product on every fiber. The set of $d\alpha$ -compatible complex structures on ξ is contractible with the C^{∞} -topology. Choose a symmetric connection ∇ on TM and consider the first order differential operator

$$\eta \mapsto -J(\nabla_t \eta - T \nabla_\eta X_\alpha)$$

on sections of ξ_{γ} . It is called the *asymptotic operator*. Here ∇_t denotes covariant derivative along the loop $t \mapsto x(Tt)$. This operator does not depend on the choice of ∇ . A $(d\alpha, J)$ unitary frame identifies $\xi_{\gamma} \simeq \mathbb{R}/\mathbb{Z} \times \mathbb{C}$ where \mathbb{C} is endowed with its standard symplectic and complex structures. The asymptotic operator gets represented as $-i\partial_t - S(t)$ for some smooth loop $S : \mathbb{R}/\mathbb{Z} \to \mathcal{L}_{\mathbb{R}}(\mathbb{C})$ of symmetric matrices. Its spectrum consists of eigenvalues which are all real, form a discrete subset of \mathbb{R} and accumulate only at $\pm \infty$. Eigenvectors are smooth and non-vanishing. Thus, once a $d\alpha$ -symplectic frame σ is chosen, an eigenvector for the eigenvalue λ gets represented as a non-vanishing vector $\mathbb{R}/\mathbb{Z} \ni t \mapsto e(t) \in \mathbb{C}$ and, as such, has a winding number wind $(\lambda, \sigma) \in \mathbb{Z}$. As the notation suggests, the number does not depend on the choice of eigenvector. If $\lambda_1 \leq \lambda_2$ are eigenvalues then wind $(\lambda_1, \sigma) \leq wind(\lambda_2, \sigma)$. Moreover, every integer is equal to wind (λ, σ) for some eigenvalue λ , and for every $k \in \mathbb{Z}$ the algebraic count of eigenvalues satisfying wind $(\lambda, \sigma) = k$ is 2. See [20] for more details.

Fix $\delta \in \mathbb{R}$ arbitrarily. Let $\lambda_{-} < \delta$ be the largest eigenvalue of the asymptotic operator which is strictly less than δ , and let $\lambda_{+} \geq \delta$ be the smallest eigenvalue which is larger than or equal to δ . Choose a symplectic trivialization σ of ξ_{γ} . The δ -weighted Conley–Zehnder index of γ with respect to σ is defined as

$$\mu_{\rm CZ}^{\sigma,\delta}(\gamma) = 2\,{\rm wind}(\lambda_-,\sigma) + p$$

where p = 1 if wind $(\lambda_{-}, \sigma) < \text{wind}(\lambda_{+}, \sigma)$, p = 0 if wind $(\lambda_{-}, \sigma) = \text{wind}(\lambda_{+}, \sigma)$. It turns out to be independent of J. Moreover, we have

$$\mu_{\rm CZ}^{\sigma',\delta}(\gamma) = 2 \operatorname{wind}(\sigma',\sigma) + \mu_{\rm CZ}^{\sigma,\delta}(\gamma).$$

The 0-weighted Conley–Zehnder index will be referred to as the *Conley–Zehnder index* and denoted by $\mu_{CZ}^{\sigma}(\gamma) \in \mathbb{Z}$.

The linear map $d\phi^T|_{x(0)} : \xi|_{x(0)} \to \xi|_{x(0)}$ is $d\lambda$ -symplectic. The orbit $\gamma = (x, T)$ is called *non-degenerate* if 1 is not an eigenvalue of this map. It defines an orientation preserving diffeomorphism of the circle of rays $(\xi|_{x(0)} \setminus \{0\})/\mathbb{R}_+$. The frame σ singles out an isotopy from the identity to this diffeomorphism. Hence, its rotation number $\rho^{\sigma}(\gamma) \in \mathbb{R}$ is well-defined. It satisfies

$$\rho^{\sigma}(\gamma^n) = n\rho^{\sigma}(\gamma), \quad \rho^{\sigma'}(\gamma) = \operatorname{wind}(\sigma', \sigma) + \rho^{\sigma}(\gamma). \tag{6}$$

The rotation number can be read as $\rho^{\sigma}(\gamma) = \lim_{k\to\infty} \frac{1}{2k} \mu_{CZ}^{\sigma}(\gamma^k)$ in terms of Conley– Zehnder indices. Let $\nu_- < 0$ and $\nu_+ \ge 0$ be the largest negative and smallest non-negative eigenvalues of the asymptotic operator, respectively. If γ is non-degenerate then $\nu_+ > 0$. If γ is elliptic or negative hyperbolic then $\rho^{\sigma}(\gamma)$ belongs to the interval (wind(ν_-, σ), wind(ν_+, σ)). If γ is positive hyperbolic then $\rho^{\sigma}(\gamma)$ is equal to wind(ν_-, σ) = wind(ν_+, σ) $\in \mathbb{Z}$. In all cases $\mu_{CZ}^{\sigma}(\gamma) = 2 \lfloor \rho^{\sigma}(\gamma) \rfloor + p$ when γ is nondegenerate.

The contact form α is said to be *non-degenerate up to action* $E \in (0, +\infty]$ if every $\gamma = (x, T)$ in $\mathcal{P}(\alpha)$ satisfying $T \leq E$ is non-degenerate. If $E = +\infty$ we simply say that α is *non-degenerate*.

If L is a transverse link in (M, ξ) then we shall need to consider the set

$$\mathcal{F}_L = \{ f \in C^{\infty}(M, (0, +\infty)) \mid df(v) = 0 \; \forall v \in \xi |_L \}.$$

$$\tag{7}$$

Note that if the Reeb vector field of α is tangent to *L* then the contact forms of the form $f\alpha$ with $f \in \mathcal{F}_L$ are precisely those contact forms that co-orient ξ in the same way as α and whose Reeb vector field is tangent to *L*.

2.2. Pseudo-holomorphic curves

2.2.1. *Finite-energy maps in symplectizations*. Given a $d\alpha$ -compatible complex structure $J : \xi \to \xi$, denote by \tilde{J} the almost complex structure on $\mathbb{R} \times M$ defined by

$$\widetilde{J} \cdot \partial_a = X_{\alpha}, \quad \widetilde{J}|_{\xi} = J.$$
 (8)

Here *a* is the \mathbb{R} -component, and X_{α} , ξ are seen as \mathbb{R} -invariant objects. The dependence on α is not apparent in the notation \tilde{J} , but must not be forgotten. The set of almost complex structures defined as above will be denoted by $\mathcal{J}(\alpha)$.

Let (S, j) be a closed Riemann surface, and let $\Gamma \subset S$ be finite. A smooth map $\widetilde{u} : S \setminus \Gamma \to \mathbb{R} \times M$ is called a *finite-energy map* if it is \widetilde{J} -holomorphic, i.e. $\overline{\partial}_{\widetilde{J}}(\widetilde{u}) = \frac{1}{2}(d\widetilde{u} + \widetilde{J}(\widetilde{u}) \circ d\widetilde{u} \circ j) = 0$, and if its *Hofer energy*

$$E(\tilde{u}) = \sup_{\phi \in \Lambda} \int_{S \setminus \Gamma} \tilde{u}^* d(\phi \alpha)$$
(9)

satisfies $0 < E(\tilde{u}) < \infty$. Here Λ is the set of smooth functions $\phi : \mathbb{R} \to [0, 1]$ satisfying $\phi' \ge 0$. It follows that \tilde{u} is non-constant. Since \tilde{J} is invariant with respect to the $(\mathbb{R}, +)$ action on $\mathbb{R} \times M$ by translations of the first coordinate, the group $(\mathbb{R}, +)$ also acts on a finite-energy map $\tilde{u} = (a, u)$ as $c \cdot \tilde{u} = (a + c, u)$.

2.2.2. *Generalized finite-energy maps.* Assume that $\alpha_+ = g\alpha_-$ for some smooth $g : M \to (1, +\infty)$. In this case we write $\alpha_+ > \alpha_-$. Choose a smooth function $h : \mathbb{R} \times M \to \mathbb{R}$ satisfying

- $h(a, p) = e^{a+1}$ on $(-\infty, -1] \times M$,
- $h(a, p) = e^{a-1}g(p)$ if $(a, p) \in [1, +\infty) \times M$,
- $\partial_a h > 0$ everywhere.

The 2-form $\Omega = d(h\alpha_{-})$ is a symplectic form on $\mathbb{R} \times M$. Let $\tilde{J}_{\pm} \in \mathcal{J}(\alpha_{\pm})$. We will denote by $\mathcal{J}_{\Omega}(\tilde{J}_{-}, \tilde{J}_{+})$ the set of almost complex structures \bar{J} on $\mathbb{R} \times M$ satisfying

- \overline{J} coincides with \widetilde{J}_{-} on $(-\infty, -1] \times M$,
- \overline{J} coincides with \widetilde{J}_+ on $[1, +\infty) \times M$,
- \overline{J} is Ω -compatible on $[-1, 1] \times M$.

The set $\mathcal{J}_{\Omega}(\tilde{J}_{-}, \tilde{J}_{+})$ is non-empty and contractible with the C^{∞} -topology; weak or strong coincide here.

Let (S, j) be a closed Riemann surface and $\Gamma \subset S$ be finite. A smooth map \tilde{u} : $S \setminus \Gamma \to \mathbb{R} \times M$ is \bar{J} -holomorphic if $\bar{\partial}_{\bar{J}}(\tilde{u}) = \frac{1}{2}(d\tilde{u} + \bar{J}(\tilde{u}) \circ d\tilde{u} \circ j) = 0$, and its Hofer energy is defined as

$$E(\tilde{u}) = \sup_{\phi \in \Lambda} \int_{\tilde{u}^{-1}((-\infty, -1] \times M)} \tilde{u}^* d(\phi \alpha_-) + \int_{\tilde{u}^{-1}([-1, 1] \times M)} \tilde{u}^* \Omega$$
$$+ \sup_{\phi \in \Lambda} \int_{\tilde{u}^{-1}([1, +\infty) \times M)} \tilde{u}^* d(\phi \alpha_+).$$
(10)

The set Λ was introduced in Section 2.2.1. If $0 < E(\tilde{u}) < \infty$ then \tilde{u} is called a *generalized finite-energy map*.

2.2.3. *Punctures and asymptotic behavior*. Denote the projection onto ξ along the Reeb direction of α by

$$\pi_{\alpha}: TM \to \xi.$$

Choose $\widetilde{J} \in \mathcal{J}(\alpha)$ and let

$$\widetilde{u} = (a, u) : (S \setminus \Gamma, j) \to (\mathbb{R} \times M, J)$$
⁽¹¹⁾

be a finite-energy map as in 2.2.1. Points in Γ will be called *punctures*. If $z_* \in \Gamma$ then z_* is a *positive puncture* if $a(z) \to +\infty$ as $z \to z_*$, it is a *negative puncture* if $a(z) \to -\infty$ as $z \to z_*$, or it is a *removable puncture* if $\limsup_{z\to z_*} |a(z)| < \infty$. It turns out that every puncture is positive, negative or removable (see [18]), and \tilde{u} can be smoothly continued across removable punctures. Positive or negative punctures will be called *non-removable*.

Let ψ be a holomorphic diffeomorphism between $(\mathbb{D}, i, 0)$ and (V, j, z_*) , where $V \subset S$ is a neighborhood of $z_* \in \Gamma$. We assign positive holomorphic polar coordinates $(s, t) \in$ $[0, +\infty) \times \mathbb{R}/\mathbb{Z}$ to the point $\psi(e^{-2\pi(s+it)}) \in V \setminus \{z_*\}$. Analogously, we assign negative holomorphic polar coordinates $(s, t) \in (-\infty, 0] \times \mathbb{R}/\mathbb{Z}$ to the point $\psi(e^{2\pi(s+it)}) \in$ $V \setminus \{z_*\}$. In any case (s, t) are called *holomorphic polar coordinates* at z_* . Let $z_* \in \Gamma$ be non-removable. We associate a sign $\epsilon = +1$ or $\epsilon = -1$ to z_* when z_* is a positive or a negative puncture, respectively. Choose (s, t) holomorphic polar coordinates at z_* , which are positive when $\epsilon = +1$ or negative when $\epsilon = -1$. Write $\tilde{u}(s,t) = (a(s,t), u(s,t))$ with respect to these coordinates.

Theorem 2.2 (Hofer [18]). For every sequence s_n satisfying $\epsilon s_n \to +\infty$ one finds a subsequence s_{n_j} , $t_0 \in \mathbb{R}$, and $(x, T) \in \mathcal{P}(\alpha)$ such that $\lim_{j\to+\infty} u(s_{n_j}, t) = x(Tt + t_0)$ in $C^{\infty}(\mathbb{R}/\mathbb{Z}, M)$.

Definition 2.3. The following terminology is useful.

- (a) An asymptotic limit of \tilde{u} at z_* is some $\gamma = (x, T) \in \mathcal{P}(\alpha)$ for which there exists a sequence $s_n \to \epsilon \infty$ and some $t_0 \in \mathbb{R}$ such that $u(s_n, t) \to x(Tt + t_0)$ in $C^0(\mathbb{R}/\mathbb{Z}, M)$ as $n \to +\infty$.
- (b) The map ũ is weakly asymptotic to γ ∈ P(α) if γ is the only asymptotic limit of ũ at z_{*}.
- (c) The map \tilde{u} is asymptotic to $\gamma = (x, T) \in \mathcal{P}(\alpha)$ at z_* if there exists some $t_0 \in \mathbb{R}$ such that $u(s, t) \to x(Tt + t_0)$ in $C^0(\mathbb{R}/\mathbb{Z}, M)$ as $s \to \epsilon \infty$.

Remark 2.4. Theorem 2.2 implies that asymptotic limits always exist at non-removable punctures. In order to handle degenerate contact forms we need to consider the distinction between cases (b) and (c). The main result of [43] states that asymptotic limits might not be unique, but it does not address the question of whether (c) follows from (b). These definitions do not depend on the choice of holomorphic polar coordinates.

Theorem 2.5 (Hofer–Wysocki–Zehnder [21]). Assume that there is an asymptotic limit $\gamma = (x, T)$ of \tilde{u} at z_* which is non-degenerate. Then \tilde{u} is asymptotic to γ at z_* . Moreover, there exists $t_0 \in \mathbb{R}$ such that $u(s, t) \rightarrow x(Tt + t_0)$ in C^{∞} as $\epsilon s \rightarrow +\infty$.

A more precise description is available. Suppose that \tilde{u} is weakly asymptotic to some orbit $\gamma = (x, T = nT_0) = \gamma_0^n$ at z_* , where $\gamma_0 = (x, T_0)$ is simply covered. In particular, n is the covering multiplicity of γ . On $\mathbb{R}/\mathbb{Z} \times \mathbb{C}$ with coordinates $(\theta, z = x_1 + ix_2)$ we denote by λ_0 the contact form $d\theta + x_1 dx_2$.

Definition 2.6. A Martinet tube for (γ_0, α) is a pair (U, Ψ) where U is a neighborhood of $x(\mathbb{R})$ and Ψ is a diffeomorphism $U \to \mathbb{R}/\mathbb{Z} \times B$ $(B \subset \mathbb{C}$ is an open ball centered at the origin) such that $\Psi(x(T_0t)) = (t, 0)$ and $\Psi_*\alpha = f\lambda_0$ where $f|_{\mathbb{R}/\mathbb{Z}\times\{0\}} \equiv T_0$, $df|_{\mathbb{R}/\mathbb{Z}\times\{0\}} \equiv 0$.

Martinet tubes always exist [21]. Choose a Martinet tube $\Psi : U \to \mathbb{R}/\mathbb{Z} \times B$ for (γ_0, α) . We find $s_0 \ge 0$ such that $u(s, t) \in U$ for all $\epsilon s \ge s_0$. Thus $\Psi \circ u(s, t) = (\theta(s, t), z(s, t))$ is well-defined when $\epsilon s \ge s_0$, and $\theta(s, \cdot)$ has degree *n*.

Theorem 2.7 (Hofer–Wysocki–Zehnder [21], Siefring [41]). Suppose that γ is nondegenerate. If z(s, t) does not vanish identically then there exists b > 0 and an eigenvalue μ of the asymptotic operator at γ such that $\epsilon \mu < 0$ and the following holds: • For some $a_0, t_0 \in \mathbb{R}$ and some lift $\tilde{\theta} : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ of $\theta(s, t)$,

$$\lim_{\epsilon s \to +\infty} \sup_{t \in \mathbb{R}/\mathbb{Z}} e^{b\epsilon s} \left(|D^{\beta}[a(s,t) - Ts - a_0]| + |D^{\beta}[\tilde{\theta}(s,t+t_0) - nt]| \right) = 0$$

for every $\beta = (\beta_1, \beta_2)$.

There exists an eigenvector of μ, represented as a non-vanishing vector v(t) in the frame {∂_{x1}, ∂_{x2}}, such that

$$z(s, t + t_0) = e^{\mu s} (v(t) + R(s, t))$$

for some R(s,t) satisfying $\sup_{t \in \mathbb{R}/\mathbb{Z}} |D^{\beta}R(s,t)| \to 0$ as $\epsilon s \to +\infty$ for every $\beta = (\beta_1, \beta_2)$.

We will say that \tilde{u} has non-trivial asymptotic formula at the puncture z_* if z(s, t) does not vanish identically in the above statement. Otherwise we say that \tilde{u} has trivial asymptotic behavior at z_* . Under the assumptions of the above theorem, the similarity principle implies that \tilde{u} has non-trivial asymptotic formula at z_* when \tilde{u} does not map the corresponding component of $S \setminus \Gamma$ into $\mathbb{R} \times \gamma$.

The statements of Theorems 2.2, 2.5 and 2.7 hold for the generalized finite-energy maps explained in Section 2.2.2. The reason is that all proofs are based on the analysis of a given end of such a map, and generalized finite-energy maps are holomorphic with respect to \mathbb{R} -invariant almost complex structures near its ends. In all cases, both when the almost complex structure is \mathbb{R} -invariant as in Section 2.2.1 or when it is not \mathbb{R} -invariant as in Section 2.2.2, we will refer to the eigenvalue appearing in the formula for z(s, t) in Theorem 2.7 as the *asymptotic eigenvalue* at the puncture z_* , assuming the curve \tilde{u} has non-trivial asymptotic formula at z_* . In this case, if γ is the asymptotic limit of \tilde{u} at z_* then we denote by

wind_{$$\infty$$}(\tilde{u}, z_*, τ) $\in \mathbb{Z}$ (12)

the winding number with respect to a symplectic trivialization τ of ξ_{γ} of an eigenvector for the asymptotic eigenvalue at z_* . It will be referred to as *asymptotic winding number*.

Remark 2.8. It is convenient to agree on the following. If z(s,t) vanishes identically, and consequently there is no asymptotic eigenvalue, then we declare the asymptotic eigenvalue and asymptotic winding number to be $-\infty$ at a positive puncture, and $+\infty$ at a negative puncture.

In order to deal with degenerate situations we need to recall a definition from [26]. Using the notation above we consider a finite-energy curve $\tilde{u} = (a, u)$ as in (11). Let z_* be a non-removable puncture of \tilde{u} of sign ϵ , choose holomorphic polar coordinates (s, t) at z_* of sign ϵ , and choose any exponential map exp on M. Let $S(z_*)$ be the component of the domain around the puncture z_* .

Definition 2.9 ([26]). The puncture z_* is a *non-degenerate puncture* of \tilde{u} if:

• \tilde{u} is asymptotic to some $(x, T) \in \mathcal{P}(\alpha)$ at z_* .

- $|a(s,t) Ts a_0| \to 0$ as $s \to \epsilon \infty$ uniformly in t, for some $a_0 \in \mathbb{R}$.
- If $\int_{\mathcal{S}(z_*)} u^* d\alpha > 0$ then $\pi_{\alpha} \circ du(s, t) \neq 0$ if ϵs is large enough.
- Let $t_0 \in \mathbb{R}$ satisfy $u(s,t) \to x(Tt + t_0)$ in C^0 as $s \to \epsilon \infty$, and $\zeta(s,t)$ be defined by $\exp_{x(Tt+t_0)} \zeta(s,t) = u(s,t)$. There exists b > 0 such that $e^{\epsilon bs} |\zeta(s,t)| \to 0$ uniformly in t as $s \to \epsilon \infty$.

If \tilde{u} is a generalized finite-energy map then \tilde{u} is holomorphic with respect to an \mathbb{R} -invariant almost complex structure near the non-removable punctures. Hence Definition 2.9 readily extends to this case.

Theorem 2.10 ([26, Corollary 6.6]). Suppose that z_* is a non-degenerate puncture of \tilde{u} in the sense of Definition 2.9, and let \tilde{u} be asymptotic to $\gamma = (x, T)$ at z_* . Let γ_0 be the underlying prime orbit of γ . Then all the conclusions from Theorem 2.7 hold true in coordinates given by any Martinet tube for (γ_0, α) .

Remark 2.11. In the above statement γ might be degenerate. In view of Theorem 2.10 we can talk about asymptotic eigenvectors and define wind_{∞}(\tilde{u}, z_*, τ) exactly as before, provided the hypotheses of Theorem 2.10 are satisfied.

2.2.4. Energy in terms of asymptotic limits. As in Section 2.2.2, consider $\Omega = d(h\alpha_{-})$, $J_{\pm} \in \mathcal{J}(\alpha_{\pm}), \bar{J} \in \mathcal{J}_{\Omega}(\tilde{J}_{-}, \tilde{J}_{+})$ and a finite-energy map $\tilde{u} : (S \setminus \Gamma, j) \to (\mathbb{R} \times M, \bar{J})$. Here Γ consists of non-removable punctures. Assume that \tilde{u} is weakly asymptotic to some periodic Reeb orbit at every puncture. If the asymptotic limits of \tilde{u} at the positive punctures z_1, \ldots, z_n are $(x_1, T_1), \ldots, (x_n, T_n) \in \mathcal{P}(\alpha_+)$, respectively, then $E(\tilde{u}) = \sum_{k=1}^n T_k$. This follows from the Stokes theorem. The same conclusion holds in the \mathbb{R} -invariant case. In the literature the reader will find other definitions of the energy which yield the same finite-energy curves, all of which can be estimated by the energy used here up to a positive factor independent of the curves.

2.2.5. Classical algebraic invariants. Fix a $d\alpha$ -compatible complex structure J on ξ , and a finite-energy map $\tilde{u} = (a, u)$ as in Section 2.2.1. We make no non-degeneracy assumption on α , but we do assume that every puncture is non-removable and non-degenerate as in Definition 2.9. Then $\pi_{\alpha} \circ du(z) : (T_z S, j) \to (\xi|_{u(z)}, J)$ is a holomorphic linear map for all $z \in S \setminus \Gamma$. Seen as a section of the appropriate bundle, $\pi_{\alpha} \circ du$ satisfies a Cauchy–Riemann type equation. It follows from the similarity principle that either $\pi_{\alpha} \circ du$ vanishes identically, or all its zeros are isolated and contribute positively to the algebraic count of zeros. Moreover, $\pi_{\alpha} \circ du$ vanishes identically if, and only if, $u(S \setminus \Gamma)$ is contained on trivial cylinders over periodic Reeb orbits, and if $\pi_{\alpha} \circ du$ does not vanish identically on a given component of $S \setminus \Gamma$ then $\pi_{\alpha} \circ du$ has finitely many zeros there; see Definition 2.9.

Assume that $\pi_{\alpha} \circ du$ vanishes identically on no connected component of its domain. In [20] the integer-valued invariant

$$\operatorname{wind}_{\pi}(\widetilde{u}) \ge 0$$
 (13)

was defined as the algebraic count of zeros of $\pi_{\alpha} \circ du$. We can find a $d\alpha$ -symplectic trivialization of $u^*\xi$ that converges at the end of $S \setminus \Gamma$ corresponding to $z \in \Gamma$ to a $d\alpha$ -symplectization τ_z along the asymptotic limit, for each z. The invariant wind_{∞}(\tilde{u}) $\in \mathbb{Z}$ is defined as

wind_{$$\infty$$}(\widetilde{u}) = $\sum_{z \in \Gamma_+}$ wind(\widetilde{u}, z, τ_z) - $\sum_{z \in \Gamma_-}$ wind(\widetilde{u}, z, τ_z) (14)

where we split $\Gamma = \Gamma^+ \cup \Gamma^-$ into positive and negative punctures, assuming that $\pi_{\alpha} \circ du$ vanishes identically on no component of $S \setminus \Gamma$.

Remark 2.12. The identity wind_{∞}(\tilde{u}) = wind_{π}(\tilde{u}) + $\chi(S)$ – # Γ follows from basic degree theory; see details in [20].

2.2.6. Moduli spaces. Fix a symplectic form Ω as in Section 2.2.2. Suppose that the following data is given: an integer $g \ge 0$, $\tilde{J}_+ \in \mathcal{J}(\alpha_+)$, $\tilde{J}_- \in \mathcal{J}(\alpha_-)$ and $\bar{J} \in \mathcal{J}_{\Omega}(\tilde{J}_-, \tilde{J}_+)$, $\gamma_1^+, \ldots, \gamma_{m_+}^+ \in \mathcal{P}(\alpha_+)$ and $\gamma_1^-, \ldots, \gamma_{m_-}^- \in \mathcal{P}(\alpha_-)$, $\delta_1^+, \ldots, \delta_{m_+}^+ \le 0$ and $\delta_1^-, \ldots, \delta_{m_-}^- \ge 0$ such that δ_i^{\pm} is not in the spectrum of the asymptotic operator associated with $(J_{\pm}, \alpha_{\pm}, \gamma_i^{\pm})$. Denote by T_k^+ the action (period) of γ_k^+ . Denote $\delta = (\delta_1^+, \ldots, \delta_{m_+}^+; \delta_1^-, \ldots, \delta_{m_+}^-)$. The moduli space

$$\mathcal{M}_{\bar{J},g,\delta}(\gamma_1^+,\dots,\gamma_{m_+}^+;\gamma_1^-,\dots,\gamma_{m_-}^-)$$
 (15)

is defined as the set of equivalence classes of tuples $(\tilde{u}, S, j, \Gamma^+, \Gamma^-)$ consisting of a closed connected genus g Riemann surface (S, j), two disjoint finite and ordered subsets $\Gamma^{\pm} = \{z_1^{\pm}, \ldots, z_{m_{\pm}}^{\pm}\}$ of S, and a finite-energy \bar{J} -holomorphic map \tilde{u} : $(S \setminus (\Gamma^+ \cup \Gamma^-), j) \to (\mathbb{R} \times M, \bar{J})$ which has non-degenerate punctures as in Definition 2.9, a positive puncture at z_i^+ where it is asymptotic to γ_i^+ , and a negative puncture at z_i^- where it is asymptotic to γ_i^- . Moreover, the asymptotic eigenvalue (Remark 2.11) of \tilde{u} at z_i^+ is smaller than δ_i^+ , and the asymptotic eigenvalue of \tilde{u} at z_i^- is larger than δ_i^- . We declare $(\tilde{u}_0, S_0, j_0, \Gamma_0^+, \Gamma_0^-)$ and $(\tilde{u}_1, S_1, j_1, \Gamma_1^+, \Gamma_1^-)$ equivalent if there is a biholomorphism $\phi : (S_0, j_0) \to (S_1, j_1)$ that defines order preserving bijections $\phi : \Gamma_0^{\pm} \to \Gamma_1^{\pm}$ and satisfies $\tilde{u}_1 \circ \phi = \tilde{u}_0$. An element of (15) is called a *pseudo-holomorphic curve*. It will be called *embedded*, *immersed* or *somewhere injective* provided that it can be represented as a finite-energy map \tilde{u} that is an embedding, immersion or a somewhere injective map, respectively. The assumption that punctures are non-degenerate and Theorem 2.10 were used to guarantee that we can talk about asymptotic eigenvalues; see Remark 2.8.

Let $\tau = (\tau_1^+, \ldots, \tau_{m_+}^+; \tau_1^-, \ldots, \tau_{m_-}^-)$ be $d\alpha_{\pm}$ -symplectic trivializations of $\xi_{\gamma_i^{\pm}}$. The virtual dimension of $\mathcal{M}_{\overline{J}, g, \delta}(\gamma_1^+, \ldots, \gamma_{m_+}^+; \gamma_1^-, \ldots, \gamma_{m_-}^-)$ at $[\widetilde{u}, S, j, \Gamma^+, \Gamma^-]$ is

$$-(2-2g-m_{+}-m_{-})+c_{1}^{\tau}(\tilde{u}^{*}T(\mathbb{R}\times M)) +\sum_{i=1}^{m_{+}}\mu_{CZ}^{\tau_{i}^{+},\delta_{i}^{+}}(\gamma_{i}^{+})-\sum_{i=1}^{m_{-}}\mu_{CZ}^{\tau_{i}^{-},\delta_{i}^{-}}(\gamma_{i}^{-})$$
(16)

where $c_1^{\tau}(\tilde{u}^*T(\mathbb{R} \times M))$ is a relative first Chern number given as follows. First, Ω -symplectically trivialize $\tilde{u}^*T(\mathbb{R} \times M)$ in such a way that at the end $z_i^{\pm} \in \Gamma^{\pm}$ this trivialization splits as trivializations $\{\partial_a, X_{\alpha_{\pm}}\} \oplus \sigma_i^{\pm}$, with some $d\alpha_{\pm}$ -symplectic trivialization σ_i^{\pm} of $\xi_{\nu^{\pm}}$. Then set

$$c_{1}^{\tau}(\tilde{u}^{*}T(\mathbb{R}\times M)) = 2\Big(\sum_{i=1}^{m_{+}} \operatorname{wind}(\sigma_{i}^{+},\tau_{i}^{+}) - \sum_{i=1}^{m_{-}} \operatorname{wind}(\sigma_{i}^{-},\tau_{i}^{-})\Big).$$
(17)

Remark 2.13. This discussion applies to the case $\alpha_{-} = \alpha_{+} = \alpha$ and $\overline{J} = \widetilde{J} \in \mathcal{J}(\alpha)$ so that one can define moduli spaces $\mathcal{M}_{\widetilde{J},g,\delta}(\gamma_{1}^{+},\ldots,\gamma_{m_{+}}^{+};\gamma_{1}^{-},\ldots,\gamma_{m_{-}}^{-})$, where $\gamma_{i}^{\pm} \in \mathcal{P}(\alpha)$.

Let *C* be a curve in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1^+,\ldots,\gamma_{m_+}^+;\gamma_1^-,\ldots,\gamma_{m_-}^-)$ represented by the tuple ($\tilde{u} = (a, u), S, j, \Gamma^+, \Gamma^-$). Using the complex structure we can compactify $S \setminus (\Gamma^+ \cup \Gamma^-)$ by adding at its ends the circles made up of rays issuing from the origin of the tangent spaces of the corresponding punctures. We obtain a compact oriented surface with boundary, \overline{S} . Its fundamental class (with \mathbb{Z} coefficients) will be denoted by $[\overline{S}, \partial \overline{S}] \in H_2(\overline{S}, \partial \overline{S})$. Using Theorem 2.10 we can smoothly extend u to a map $\overline{u} : \overline{S} \to M$. We call $\overline{u}_*[\overline{S}, \partial \overline{S}] \in H_2(M, \gamma_1^+ \cup \cdots \cup \gamma_1^- \cup \cdots)$ the homology class *induced by C*. It does not depend on the choice of representative.

2.2.7. Intersection numbers. We here review basic facts of the intersection theory for punctured pseudo-holomorphic curves in dimension 4, as developed by Siefring [42]. Fix non-degenerate contact forms α_- , α_+ that define ξ and satisfy $\alpha_+ > \alpha_-$. Later we will describe situations where the non-degeneracy assumption can be relaxed; see Remark 2.16.

Let $\tilde{J}_{\pm} \in \mathcal{J}(\alpha_{\pm})$ and $\bar{J} \in \mathcal{J}_{\Omega}(\tilde{J}_{-}, \tilde{J}_{+})$ be as in Section 2.2.2. Choose a collection τ of symplectic trivializations of ξ_{γ_0} for every simply covered periodic orbit γ_0 of X_{α_+} and of X_{α_-} . Let $\tilde{u} = (a, u) : S \setminus \Gamma \to \mathbb{R} \times M$ be a finite-energy \bar{J} -holomorphic map, where (S, j) is a closed Riemann surface and $\Gamma \subset S$ is a finite set of non-removable punctures. Decompose $\Gamma = \Gamma^+ \sqcup \Gamma^-$ into positive and negative punctures. At each $w \in \Gamma_{\pm}$ the asymptotic limit of \tilde{u} is denoted by $\gamma_w^{n_w}$ where $\gamma_w = (x_w, T_w) \in \mathcal{P}(\alpha_{\pm})$ is prime and n_w is its covering multiplicity. Choose holomorphic polar coordinates (s, t) at w which are positive or negative according to whether w is a positive or a negative puncture. We can write the components $\tilde{u}(s, t) = (a(s, t), u(s, t))$ as functions of (s, t) near the punctures. Choose Martinet tubes (U_w, Ψ_w) around γ_w , with respect to α_+ or α_- accordingly, with coordinates $(\theta, z = (x_1 + ix_2))$ satisfying the requirements of Definition 2.6 and aligned with τ in the following sense: ∂_{x_1} gets represented by τ as a loop with winding number zero.

Let *w* be a positive puncture. By the asymptotic behavior described in Theorem 2.7, if $R \gg 1$ then $(s,t) \mapsto (a(s,t),t)$ defines a smooth proper orientation preserving embedding of $(R, +\infty) \times \mathbb{R}/\mathbb{Z}$ onto an end of $[0, +\infty) \times \mathbb{R}/\mathbb{Z}$. Hence we can use (a, t) as new polar coordinates near *w*, with respect to which the map \tilde{u} is written as

$$(a,t) \mapsto (a,u(a,t)).$$

The analogous conclusion holds near a negative puncture. If |a| is large enough we can again use Theorem 2.7 to conclude that the loop $t \mapsto u(a, t)$ lies in N_w . Hence

$$\Psi_w \circ u(a,t) = (\theta(a,t), z(a,t))$$

are well-defined functions of (a, t) with $|a| \gg 1$. Fix a smooth cut-off function $\beta : \mathbb{R} \rightarrow [0, 1]$ that vanishes near $(-\infty, 0]$ and is identically equal to 1 near $[1, +\infty)$. Taking $\varepsilon > 0$ small and r > 0 large, define $\tilde{u}^{\tau, w, \varepsilon, r}$ by

$$\widetilde{u}^{\tau,w,\varepsilon,r}(a,t) = \left(a,\theta(a,t), z(a,t) + \varepsilon\beta(a-r)\right), \quad a \ge r,$$
(18)

if w is a positive puncture, or by

$$\widetilde{u}^{\tau,w,\varepsilon,r}(a,t) = \left(a,\theta(a,t), z(a,t) + \varepsilon\beta(-a-r)\right), \quad a \le -r,$$
(19)

if w is a negative puncture. Repeating this construction at all $w \in \Gamma$ using common parameters $\varepsilon, r > 0$ such that min $\{\varepsilon^{-1}, r\}$ is large enough, we obtain a small neighborhood V of Γ and a smooth map defined on $V \setminus \Gamma$, which can be smoothly extended to a map

$$\widetilde{u}^{\tau,\varepsilon,r}:S\setminus\Gamma\to\mathbb{R}\times M$$

by setting it to be equal to \tilde{u} on $S \setminus V$. The dependence on τ is hidden in the choice of the Martinet tubes.

If \tilde{u}_0 and \tilde{u}_1 are finite-energy \bar{J} -holomorphic curves, then Siefring [42] defines

$$i^{\tau}(\widetilde{u}_0, \widetilde{u}_1) = \operatorname{int}(\widetilde{u}_0, \widetilde{u}_1^{\tau, \varepsilon, r})$$
(20)

where int stands for the oriented intersection number. This is well-defined since for $\min \{\varepsilon^{-1}, r\}$ large enough the maps \tilde{u}_0 and $\tilde{u}_1^{\tau,\varepsilon,r}$, do not intersect each other on the ends of their domains. Moreover, it depends only on the data $(\tau, \tilde{u}_0, \tilde{u}_1)$ as one easily checks. It is also symmetric: $i^{\tau}(\tilde{u}_0, \tilde{u}_1) = i^{\tau}(\tilde{u}_1, \tilde{u}_0)$.

It is interesting to compute the difference $i^{\tau'}(\tilde{u}_0, \tilde{u}_1) - i^{\tau}(\tilde{u}_0, \tilde{u}_1)$. This can be understood in terms of braided knots. Suppose that for $j \in \{0, 1\}$ we have positive punctures z_j of \tilde{u}_j with asymptotic limit γ^{n_j} , where γ is a simply covered Reeb orbit and $n_j \in \mathbb{N}$. Assume for simplicity that \tilde{u}_0, \tilde{u}_1 are somewhere injective. By Theorem 2.7, setting the \mathbb{R} -coordinate a in $\mathbb{R} \times M$ equal to a large constant near the punctures z_j , the maps $\tilde{u}_0, \tilde{u}_1^{\tau,\varepsilon,r}$ and $\tilde{u}_1^{\tau',\varepsilon,r}$ single out (up to small perturbation) braided knots $k_0(a), k_1^{\tau}(a)$ and $k_1^{\tau'}(a)$, respectively, on a tubular neighborhood of γ . Consider r so large that the corresponding ends of \tilde{u}_0 and $\tilde{u}_1^{\tau,\varepsilon,r}$, and of \tilde{u}_0 and $\tilde{u}_1^{\tau',\varepsilon,r}$, do not intersect for all $a \ge r$. If $a \ge r$ then all the n_1 strands $k_1^{\tau'}(a)$ wind around all the n_0 strands of $k_0(a)$. It follows that the contribution to the difference $i^{\tau'}(\tilde{u}_0, \tilde{u}_1) - i^{\tau}(\tilde{u}_0, \tilde{u}_1)$ coming from (z_0, z_1) is equal to n_0n_1 wind (τ, τ') . Negative punctures are treated similarly. The argument when curves are not somewhere injective is a straightforward modification. We arrive at [42, Proposition 4.1 (3)]

$$i^{\tau'}(\tilde{u}_0, \tilde{u}_1) - i^{\tau}(\tilde{u}_0, \tilde{u}_1) = \sum_{(z_0, z_1)}^{+} n_0 n_1 \operatorname{wind}(\tau, \tau') - \sum_{(z_0, z_1)}^{-} n_0 n_1 \operatorname{wind}(\tau, \tau') \quad (21)$$

where Σ^+ [Σ^-] indicates sum over all pairs of positive [negative] punctures (z_0 , z_1) where \tilde{u}_0 , \tilde{u}_1 are asymptotic to covers of a common simply covered Reeb orbit. As in [42] consider

$$\Omega^{\tau}(\tilde{u}_{0},\tilde{u}_{1}) = \sum_{(z_{0},z_{1})}^{+} n_{0}n_{1} \max\left\{\lfloor \rho^{\tau}(\gamma^{n_{0}}) \rfloor / n_{0}, \lfloor \rho^{\tau}(\gamma^{n_{1}}) \rfloor / n_{1}\right\} + \sum_{(z_{0},z_{1})}^{-} n_{0}n_{1} \max\left\{\lfloor -\rho^{\tau}(\gamma^{n_{0}}) \rfloor / n_{0}, \lfloor -\rho^{\tau}(\gamma^{n_{1}}) \rfloor / n_{1}\right\}.$$
(22)

Using (21) we get $\Omega^{\tau}(\tilde{u}_0, \tilde{u}_1) - \Omega^{\tau'}(\tilde{u}_0, \tilde{u}_1) = i^{\tau'}(\tilde{u}_0, \tilde{u}_1) - i^{\tau}(\tilde{u}_0, \tilde{u}_1)$. Siefring defines the generalized intersection number

$$\widetilde{u}_0 * \widetilde{u}_1 = i^{\tau} (\widetilde{u}_0, \widetilde{u}_1) + \Omega^{\tau} (\widetilde{u}_0, \widetilde{u}_1),$$
(23)

which is independent of the choice of τ in view of the above calculations. The generalized intersection number for curves is defined by the generalized intersection number of maps representing them.

Of course, the case $\alpha_{-} = \alpha_{+}$ and $\overline{J} = \widetilde{J} \in \mathcal{J}(\alpha)$ is a special case of the above discussion.

As explained in [42], one of the many motivations to consider this intersection number is that it is preserved under smooth homotopies of asymptotically cylindrical maps. We have not defined here this class of maps [42, Section 2.3], but we state a special case of [42, Proposition 4.3 (1)].

Proposition 2.14. The number $\tilde{u} * \tilde{v}$ does not change when \tilde{u} or \tilde{v} vary in smooth families of finite-energy curves with fixed asymptotic limits.

Crucial to our analysis is the adjunction inequality. Choose an Ω -symplectic trivialization of $\tilde{u}^*T(\mathbb{R} \times M)$ that splits as $\{\partial_a, X_{\alpha_{\pm}}\} \oplus \sigma_w$ at each puncture $w \in \Gamma_{\pm}$, where σ_w is a $d\alpha_{\pm}$ -symplectic trivialization of $\xi_{\gamma_w^{nw}}$. Denote

$$\mu_{\mathrm{CZ}}(\widetilde{u}) = \sum_{w \in \Gamma_{+}} \mu_{\mathrm{CZ}}^{\sigma_{w}}(\gamma_{w}^{n_{w}}) - \sum_{w \in \Gamma_{-}} \mu_{\mathrm{CZ}}^{\sigma_{w}}(\gamma_{w}^{n_{w}}),$$
$$\bar{\sigma}(\widetilde{u}) = \sum_{w \in \Gamma} \gcd(n_{w}, \lfloor \rho^{\Phi_{w}}(\gamma_{w}^{n_{w}}) \rfloor),$$

where, for each $w \in \Gamma$, Φ_w denotes any trivialization of ξ along the underlying primitive orbit γ_w . Let Γ_{odd} denote the set of punctures where the asymptotic limit has odd Conley–Zehnder index. The following is a special case of [42, Theorem 2.3].

Theorem 2.15 (Siefring). If \tilde{u} is somewhere injective then

$$\widetilde{u} * \widetilde{u} - \frac{1}{2}\mu_{\rm CZ}(\widetilde{u}) + \frac{1}{2}\#\Gamma_{\rm odd} + \chi(S) - \bar{\sigma}(\widetilde{u}) \ge 0$$

and equality implies that \tilde{u} is an embedding.

Remark 2.16. Assume that there exists a constant E > 0 such that every periodic Reeb orbit $(x, T) \in \mathcal{P}(\alpha_+) \cup \mathcal{P}(\alpha_-)$ with $T \leq E$ is non-degenerate. Then all definitions discussed here make sense and all results hold when applied to curves with energy at most equal to E.

2.2.8. Contact forms with common closed Reeb orbits. Let $L \subset (M, \xi)$ be a transverse oriented link with components $\gamma_1, \ldots, \gamma_n$. Assume that the Reeb vector fields of two defining contact forms $\alpha_+ > \alpha_-$ are positively tangent to L. Thus γ_i may be viewed as prime closed α_\pm -Reeb orbits. Let $\tilde{J}_\pm \in \mathcal{J}(\alpha_\pm)$ and let Ω be a symplectic form as considered in Section 2.2.2. We will denote by $\mathcal{J}_{\Omega,L}(\tilde{J}_-, \tilde{J}_+) \subset \mathcal{J}_{\Omega}(\tilde{J}_-, \tilde{J}_+)$ the subset consisting of those \tilde{J} which leave the tangent space of $\mathbb{R} \times L$ invariant. One can check that this set is non-empty and contractible when equipped with the C^{∞} -topology (strong equals weak here).

2.2.9. *SFT-compactness.* In preparation for the proofs we need to review the language necessary to use the SFT-compactness theorem [6]. Fix contact forms α_{\pm} that define ξ and satisfy $\alpha_{+} > \alpha_{-}$. Let $\tilde{J}_{\pm} \in \mathcal{J}(\alpha_{\pm})$, let Ω be a symplectic form as considered in Section 2.2.2, and let $\bar{J} \in \mathcal{J}_{\Omega}(\tilde{J}_{-}, \tilde{J}_{+})$.

Nodal curves. A nodal holomorphic curve in $(\mathbb{R} \times M, \overline{J})$ without marked points, also called a *holomorphic building of height* 1 without marked points, is the equivalence class of a tuple

$$(\tilde{u}, S, j, \Gamma^+, \Gamma^-, D)$$

consisting of a (possibly disconnected) closed Riemann surface (S, j), disjoint finite ordered sets $\Gamma^+, \Gamma^- \subset S$ of distinct points, a finite unordered set D of unordered pairs of points in S, called *nodal pairs*, such that all nodal points together with points in $\Gamma^+ \cup \Gamma^-$ make up a set of distinct points of S, and a finite-energy \overline{J} -holomorphic map

$$\widetilde{u}: S \setminus (\Gamma^+ \cup \Gamma^-) \to \mathbb{R} \times M$$

having positive punctures at Γ^+ , negative punctures at Γ^- , satisfying $\tilde{u}(z) = \tilde{u}(w)$ for all $\{z, w\} \in D$. Points of $\Gamma^+ \cup \Gamma^-$ will be called punctures. By *nodal points* we mean points belonging to nodal pairs; we may abuse notation and still write D to denote the set of nodal points. Two such tuples are declared equivalent,

$$(\widetilde{u}, S, j, \Gamma^+, \Gamma^-, D) \sim (\widetilde{u}', S', j', \Gamma'^+, \Gamma'^-, D'),$$

if there is a biholomorphism $\phi : (S, j) \to (S', j')$ that determines order preserving bijections $\Gamma^{\pm} \to \Gamma'^{\pm}$ and a bijection $D \to D'$ respecting pairs, and satisfies $\tilde{u}' \circ \phi = \tilde{u}$. We may refer to ϕ simply as an isomorphism.

The nodal curve is called *connected* if the space obtained from S by identifying points in each nodal pair is connected. It is called *stable* if for every connected component $S_* \subset S$ such that $\tilde{u}|_{S_* \setminus (\Gamma_+ \cup \Gamma_-)}$ is constant the inequality $2g_* + \mu_* \ge 3$ holds, where g_* is the genus of S_* and μ_* is the total number of punctures and nodal points in S_* . When there are no nodes the curve is said to be *smooth*.

Remark 2.17. If (S, j) is a Riemann surface and $z \in S$ then the conformal structure endows the circle $(T_z S \setminus 0)/\mathbb{R}_+$, called the *blown up circle* at z, with a metric which makes it isometric to $\mathbb{R}/2\pi\mathbb{Z}$ with its usual metric.

The *arithmetic genus* of a connected nodal curve $(\tilde{u}, S, j, \Gamma^+, \Gamma^-, D)$ is, by definition,

$$g = \frac{1}{2}d - b + \sum_{i=1}^{b} g_i + 1$$

where d is the number of nodal points, b is the number of connected components of S and $\sum_{i} g_{i}$ is the sum of their genera.

Remark 2.18. Assume that $(\tilde{u}, S, j, \Gamma^+, \Gamma^-, D)$ is a connected nodal curve. If we choose a collection *r* of orientation reversing isometries of blown up circles at nodal pairs, and use it to glue these circles obtaining a connected closed surface $S^{D,r}$ then the arithmetic genus is equal to the genus of $S^{D,r}$.

The above notion of nodal curve in $(\mathbb{R} \times M, \overline{J})$ can be adapted in a straightforward manner to that of a nodal curve in $(\mathbb{R} \times M, \widetilde{J}_{\pm})$. The only difference is in the concept of stability: one further requires the existence of at least one component $S_* \subset S$ such that $\widetilde{u}|_{S_*}$ is not an unbranched cover of a cylinder over some closed Reeb orbit (trivial cylinder).

Let $(\tilde{u}, S, j, \Gamma^+, \Gamma^-, D)$ represent a nodal curve, and write $\tilde{u} = (a, u)$ in components. If we denote by \bar{S} the smooth surface obtained from S by removing all punctures and nodal points and adding the corresponding blown up circles, and assume that α_+, α_- are non-degenerate up to action $E(\tilde{u})$, then we can use Theorem 2.5 to continuously extend the map u to a map

$$\bar{u}: \bar{S} \to M. \tag{24}$$

It maps blown up circles at punctures to the corresponding asymptotic closed Reeb orbits, and blown up circles at nodal points to the corresponding point in M. Blown up circles are oriented as the boundary of \bar{S} .

Holomorphic buildings. Nodal curves are, by definition, buildings of height 1. We pass now to the description of a general holomorphic building **u** of height $k_{-}|1|k_{+}$ in $(\mathbb{R} \times M, \overline{J})$ without marked points [6, Section 7], where $k_{\pm} \ge 0$. It is the equivalence class of the data consisting of an ordered collection of nodal holomorphic curves

$$\{\tilde{u}_m\} = \{(\tilde{u}_m = (a_m, u_m), S_m, j_m, \Gamma_m^+, \Gamma_m^-, D_m)\}, m \in \{-k_-, \dots, k_+\},\$$

as above, such that

- for each m < 0, \tilde{u}_m defines a stable nodal curve in $(\mathbb{R} \times M, \tilde{J}_-)$,
- \tilde{u}_0 defines a stable nodal curve in $(\mathbb{R} \times M, \bar{J})$,
- for each m > 0, \tilde{u}_m defines a stable nodal curve in $(\mathbb{R} \times M, \tilde{J}_+)$,

and a collection $\{\Phi_m\}, m \in \{-k_-, \dots, k_+ - 1\}$, of orientation reversing isometries

$$\Phi_m: \bigcup_{z \in \Gamma_m^+} (T_z S_m \setminus 0) / \mathbb{R}_+ \to \bigcup_{z \in \Gamma_{m+1}^-} (T_z S_{m+1} \setminus 0) / \mathbb{R}_+$$

covering order preserving bijections $\Gamma_m^+ \to \Gamma_{m+1}^-$, such that

 $\bar{u}_{m+1} \circ \Phi_m$ coincides with \bar{u}_m on $(T_z S_m \setminus 0)/\mathbb{R}_+$ for every $z \in \Gamma_m^+$. (25)

Here each \bar{u}_m is as in (24), which is well-defined under the assumption that α_+, α_- are non-degenerate up to action E for some constant satisfying $\max_m E(\tilde{u}_m) \leq E$. The \tilde{u}_m define nodal holomorphic curves called the levels, or stores, of the building. Two such collections $\{\{\tilde{u}_m\}, \{\Phi_m\}\}$ and $\{\{\tilde{u}'_m\}, \{\Phi'_m\}\}$ of data are equivalent if they have the same number of levels, and there are isomorphisms between the corresponding levels (in the sense explained before), whose linearizations intertwine the corresponding orientation reversing isometries $\{\Phi_m\}$ and $\{\Phi'_m\}$ at corresponding blown up circles. Moreover, synchronized reorderings of the intermediate punctures also define equivalent buildings.

Let *r* be an arbitrary collection of orientation reversing isometries between the blown up circles at points in the nodal pairs $\bigcup_m D_m$. Denote

$$S^{\mathbf{u},r} = \left(\bigsqcup_m \bar{S}_m\right) / \sim$$

where Φ_m identifies blown up circles at points in Γ_m^+ with blown up circles at corresponding points in Γ_{m+1}^- , and *r* identifies blown up circles at nodal pairs. The circles in the interior of $S^{\mathbf{u},r}$ obtained by these identifications of blown up circles will be called *special*.

Remark 2.19. One may see $S_m \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m)$ as an open subset of $S^{\mathbf{u},r}$.

Condition (25) and Theorem 2.5 allow us to define a continuous map

$$F_{\mathbf{u}}: S^{\mathbf{u},r} \to [-\infty, +\infty] \times M$$

as the unique continuous map that agrees with \tilde{u}_0 on $S_0 \setminus (\Gamma_0^+ \cup \Gamma_0^- \cup D_0)$, with $(+\infty, u_m)$ on $S_m \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m)$ for all m > 0, and with $(-\infty, u_m)$ on $S_m \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m)$ for all m < 0. Here we abuse notation and write D_m for sets of nodal points.

Similarly one defines holomorphic buildings in $(\mathbb{R} \times M, \tilde{J}_{\pm})$. The difference is that there is no distinction between upper and lower levels. All levels are nodal curves in the same symplectization. Here we simply consider $F_{\mathbf{u}}$ as a map $S^{\mathbf{u},r} \to M$ built from the *M*-components of the levels in a similar manner.

Lemma 2.20. Let **u** be a stable holomorphic building without marked points such that $S^{\mathbf{u},r}$ is a connected genus zero surface for some (and hence any) choice of r. Suppose that there exists a level $(\tilde{u}_m, S_m, j_m, \Gamma_m^+, \Gamma_m^-, D_m)$ of **u** and a connected component $Y \subset S_m$ such that \tilde{u}_m is constant on $Y \setminus (\Gamma_m^+ \cup \Gamma_m^-) = Y$. Then there exist connected components $Y' \neq Y''$ of S_m such that

- \tilde{u}_m is non-constant on $Y' \setminus (\Gamma_m^+ \cup \Gamma_m^-)$,
- \widetilde{u}_m is non-constant on $Y'' \setminus (\Gamma_m^+ \cup \Gamma_m^-)$,
- $\widetilde{u}_m(Y) \subset \widetilde{u}_m(Y' \setminus (\Gamma_m^+ \cup \Gamma_m^-)) \cap \widetilde{u}_m(Y'' \setminus (\Gamma_m^+ \cup \Gamma_m^-)).$

Proof. Note that there are no punctures in Y, otherwise \tilde{u}_m would not be constant on Y. Also, Y has genus zero. By stability there are at least three nodal points in Y, and Y contains no nodal pair; otherwise $S^{\mathbf{u},r}$ would not have genus zero. Hence we can find connected components Y_0, Y_1 of S_m , both different from Y, for which there exist nodal pairs $\{z_0, z'_0\}, \{z_1, z'_1\}$ satisfying $z_0, z_1 \in Y, z'_0 \in Y_0, z'_1 \in Y_1$. Consequently,

$$\widetilde{u}_m(z_1') = \widetilde{u}_m(Y) = \widetilde{u}_m(z_0').$$

Moreover, $Y_0 \neq Y_1$ again by the genus zero assumption. If \tilde{u}_m is not constant on $Y_0 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ and not constant on $Y_1 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ then we are done: define $Y' = Y_0$, $Y'' = Y_1$.

Suppose \tilde{u}_m is constant on $Y_1 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$; we must have $Y_1 = Y_1 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ in this case. The genus zero assumption implies that $Y_1 \cup Y \cup Y_0$ contains exactly two nodal pairs, namely $\{z_0, z'_0\}, \{z_1, z'_1\}$; it may contain many more nodal points though. Since Y_1 has genus zero, by stability we find at least three nodal points in Y_1 . Let $Y_2 \not\subset Y_1 \cup Y \cup Y_0$ be a connected component of S_m and $\{z_2, z'_2\}$ be a nodal pair such that $z_2 \in Y_1$ and $z'_2 \in Y_2$; these exist by the genus zero assumption on $S^{\mathbf{u}, \mathbf{r}}$. Note that

$$\widetilde{u}_m(z_2') = \widetilde{u}_m(Y) = \widetilde{u}_m(z_0').$$

If \tilde{u}_m is not constant on $Y_2 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ and not constant on $Y_0 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ then we are done: just set $Y' = Y_0$, $Y'' = Y_2$. This process must stop, otherwise we find infinitely many components of S_m . As a consequence, we find nodal pairs $\{z_1, z_1'\}, \ldots, \{z_k, z_k'\}$ and connected components Y_1, \ldots, Y_k of S_m such that $z_1 \in Y$, $\{z_1', z_2\} \subset Y_1, \{z_2', z_3\} \subset Y_2,$ $\ldots, \{z_{k-1}', z_k\} \subset Y_{k-1}, z_k' \in Y_k, \widetilde{u}_m$ is constant on $Y_i \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ for all $i = 1, \ldots, k-1$, and \widetilde{u}_m is not constant on Y_k . In particular, $\widetilde{u}_m(z_k') = \widetilde{u}_m(Y)$.

If \tilde{u}_m is not constant on $Y_0 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ then we are done since the genus zero assumption implies that $Y_0 \neq Y_k$. If \tilde{u}_m is constant on $Y_0 \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ then we can repeat the above process to find a connected component Y_{-j} of S_m , $j \ge 1$, connected through a chain of nodal points to Y, such that \tilde{u}_m is not constant on $Y_{-j} \setminus (\Gamma_m^+ \cup \Gamma_m^-)$, and a point $z'_{-j} \in Y_{-j} \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ such that $\tilde{u}_m(z'_{-j}) = \tilde{u}_m(Y)$. The genus zero assumption implies that $Y_{-j} \neq Y_k$.

SFT-convergence. Let $(\tilde{v}_l = (b_l, v_l), \Sigma_l, j_l, Z_l^+, Z_l^-)$ be a sequence of connected holomorphic curves in $(\mathbb{R} \times M, \bar{J})$ satisfying $E(\tilde{v}_l) \leq E$ for some E > 0 such that both α_+ and α_- are non-degenerate up to action E. By Theorem 2.7 we have unique associated continuous maps

$$F_{\tilde{v}_l}: \bar{\Sigma}_l \to [-\infty, +\infty] \times M$$

equal to \tilde{v}_l on $\bar{\Sigma}_l \setminus (\text{blown up circles at punctures}) = \Sigma_l \setminus (Z_l^+ \cup Z_l^-)$. It maps blown up circles onto corresponding asymptotic limits.

This sequence of curves SFT-converges to the building **u** if there is a collection *r* of orientation reversing isometries of blown up circles at nodal pairs in $\bigcup_m D_m$, there are ordered sets of distinct points $K_l \subset \Sigma_l$, $K \subset \bigsqcup_m S_m$ (additional marked points) of the same cardinality, and diffeomorphisms

$$\varphi_l: S^{\mathbf{u}, \mathbf{r}} \to \bar{\Sigma}_l \tag{26}$$

such that (a)-(g) below hold:

- (a) K_l and K are disjoint from punctures and nodal points, and φ_l induces an order preserving bijection $K \to K_l$.
- (b) $2g_l + v_l \ge 3$ where g_l is the genus of Σ_l and $v_l = \#Z_l^+ + \#Z_l^- + \#K_l$.
- (c) $2g + \nu \ge 3$ for every connected component $C \subset \bigsqcup_m S_m$, where g is the genus of C and ν is the total number of punctures, nodal points and points in K belonging to C.
- (d) φ_l defines a diffeomorphism between blown up circles at Z_l^+ and $\Gamma_{k_+}^+$ covering an order preserving bijection $\Gamma_{k_+}^+ \to Z_l^+$, and defines a diffeomorphism between blown up circles at Z_l^- and $\Gamma_{-k_-}^-$ covering an order preserving bijection $\Gamma_{-k_-}^- \to Z_l^-$.

In view of (b) we may consider the hyperbolic metric h_l in the conformal class induced by j_l in $\Sigma_l \setminus (Z_l^+ \cup Z_l^- \cup K_l)$ seen as an open subset of $\overline{\Sigma}_l$. In view of (c) we may consider *h* the hyperbolic metric in $V = \bigsqcup_m (S_m \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m \cup K))$ in the conformal class of the complex structure *j* induced by the j_m 's. Here we see *V* as an open subset of $S^{\mathbf{u},r}$. Note that $\varphi_l(V) \subset \Sigma_l \setminus (Z_l^+ \cup Z_l^- \cup K_l)$. One further requires

(e) $\varphi_l^* h_l \to h$ in $C_{loc}^{\infty}(V)$, and φ_l maps special circles to closed geodesics of h_l .

For the maps one further asks:

(f) $F_{\tilde{v}_l} \circ \varphi_l C^0$ -converges to $F_{\mathbf{u}}$.

(g) $\forall m \exists \{c_{m,l}\} \subset \mathbb{R}$ such that $b_l \circ \varphi_l|_{S_m \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m)} + c_{m,l} C_{loc}^0$ -converges to a_m .

Remark 2.21. The discussion above differs slightly from the discussion in [6] where one works with maps $\psi_l : S_0^{\mathbf{u},r} \to \Sigma_l$ defined on the closed surface $S_0^{\mathbf{u},r}$ obtained from blowing $\bigsqcup_m S_m$ up only at nodal points and punctures between the levels, and gluing back with r and $\{\Phi_m\}$. In other words, our $S^{\mathbf{u},r}$ is obtained from $S_0^{\mathbf{u},r}$ by blowing the punctures in $\Gamma_{k+}^+ \cup \Gamma_{-k-}^-$ up. The maps ψ_l are required to define order preserving bijections $\Gamma_{\pm k\pm}^{\pm} \to Z_l^{\pm}$, $K \to K_l$. Condition (e) above is replaced by asking that $\psi_l^* h_l \to h$ in $C_{\text{loc}}^{\infty}(V)$ and that each ψ_l maps special circles to closed geodesics. The maps $\varphi_l : S^{\mathbf{u},r} \to \overline{\Sigma}_l$ can be obtained from blowing the ψ_l up at $\Gamma_{k+}^+ \cup \Gamma_{-k-}^-$. Hence, the description of SFT-convergence from [6] implies the description here. It turns out that the converse also holds: one could modify the φ_l in (26) on neighborhoods U_l of $\partial S^{\mathbf{u},r}$ satisfying $U_{l+1} \subset U_l$, $\bigcap_l U_l = \partial S^{\mathbf{u},r}$, to new maps φ'_l which can be obtained by blowing up diffeomorphisms $\psi_l : S_0^{\mathbf{u},r} \to \Sigma_l$ with the properties required in [6].

Remark 2.22. Condition (e) above does not keep track of how the decoration at the punctures between levels induced by $\{\Phi_m\}$ arises in the limit; see condition **CRS3** in [6, Section 4.5].

Remark 2.23. Arguing as explained in [6, Section 4.5, Remark 4.1], one can see that (e) is equivalent to

(e') $\varphi_l^* j_l \to j$ in $C_{\text{loc}}^{\infty}(V')$ where $V' = \bigsqcup_m (S_m \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m))$ seen as open subset of $S^{\mathbf{u}, \mathbf{r}}$.

This might be more comfortable to work with because there is no reference to sets of additional marked points K_l , K.

The SFT-compactness theorem [6] implies, as a special case, that any sequence of stable curves with genus and energy bounds has an SFT-convergent subsequence to a stable holomorphic building. This holds under the assumption that α_+, α_- are non-degenerate up to some action *E* which is an upper bound for the energy of the curves in the sequence.

Remark 2.24. SFT-convergence in symplectizations is described in almost the same way, except that we may simply consider $F_{\tilde{v}_l}$ and F_u as maps into M built from M-components.

3. Proof of Theorem 1.8

The main work is to prove (iii) \Rightarrow (ii). The implication (ii) \Rightarrow (i) is obvious, and the proof of (i) \Rightarrow (iii) under the stated C^{∞} -genericity assumption is as in the proof of Theorem 1.14. For convenience of the reader we spell out this argument again here. Since *L* bounds a global surface of section in class *b*, obviously all periodic orbits in the complement of *L* must have positive intersection number with *b*. It only remains to prove that $\mu_{CZ}^{\Theta}(\gamma) > 0$ for all components $\gamma \subset L$, or equivalently $\rho^{\Theta}(\gamma) > 0$. If $\rho^{\Theta}(\gamma) < 0$ then nearby trajectories will intersect the section negatively, which is impossible. If $\rho^{\Theta}(\gamma) = 0$ then, by assumption, γ is hyperbolic and its stable/unstable manifolds contain trajectories that never hit the global surface of section, which is impossible. Hence $\rho^{\Theta}(\gamma) > 0$.

The remainder of this section contains the proof of (iii) \Rightarrow (ii). Let us make a brief summary of the structure of the argument.

In Section 3.1 we use intersection theory to derive various properties of the finiteenergy curves later used in the construction of the desired global surfaces of section. The crucial assumption is that these curves represent the same element in $H_2(M, L)$ as a Seifert surface with the same contact topological properties of a page of a supporting open book decomposition. These intersection-theoretic arguments do not use the genus zero assumption. We also obtain automatic transversality for these curves in a Fredholm theory with suitable exponential weights, and here the genus zero hypothesis plays a role.

In Section 3.2 we prove an implied existence result for the kinds of curves analyzed in Section 3.1. This argument is based on the assumption that corresponding curves exist for an auxiliary contact form with controlled Reeb dynamics. The genus zero hypothesis and (iii) in Theorem 1.8 play key roles in the study of SFT-limits of the curves involved.

Section 3.3 starts by explaining that the result of [47] can be used as input for the results from Section 3.2. The curves obtained are the pages of the desired open book

decomposition by global surfaces of section for the Reeb flow of a non-degenerate contact form satisfying (iii) in Theorem 1.8. Since in Section 3.4 degenerate contact forms will be studied, here we need to keep track of certain approximating sequences of non-degenerate contact forms.

The degenerate case is studied in Section 3.4 where sequences of holomorphic curves for approximating non-degenerate contact forms are shown to have well-behaved limits. One difficulty is that, strictly speaking, the SFT-compactness theorem does not apply. Still, we show that some more fundamental compactness arguments apply. Another technical point is that the curves for the approximating contact forms present an exponential decay that respects certain weights at the punctures, and these weights do not degenerate in the limiting process.

3.1. Seifert surfaces and holomorphic curves

Let $L \subset M$ be a link transverse to ξ , and suppose that there exists an oriented Seifert surface $\Sigma \subset M$ for *L* with genus *g*. Orient *L* as the boundary of Σ and denote its components by $\gamma_1, \ldots, \gamma_n$. Let α be a contact form defining ξ and assume that

- (A1) X_{α} is positively tangent to L,
- (A2) the Reeb vector field of $f\alpha$, for some $f \in C^{\infty}(M, (0, +\infty))$, is positively transverse to $\Sigma \setminus \partial \Sigma = \Sigma \setminus L$, and tangent to L.

We see each γ_i as a simply covered closed α -Reeb orbit with period T_i . The outward pointing normal vector of Σ along $L = \partial \Sigma$ induces a homotopy class of $d\alpha$ -symplectic trivializations of each ξ_{γ_i} . Denote by τ_{Σ} a collection of trivializations in these homotopy classes. Assume further that

(A3) $\mu_{CZ}^{\tau_{\Sigma}}(\gamma_i) \ge 1$ for every *i*, (A4) α is non-degenerate up to action $\sum_{k=1}^{n} T_k$.

For the remainder of this Section we fix a $d\alpha$ -compatible complex structure $J : \xi \to \xi$ arbitrarily. In view of (A3) there exists $\delta_i < 0$ in the spectral gap of the asymptotic operator along γ_i induced by (α, J) between eigenvalues with winding number 0 and 1 computed with respect to τ_{Σ} . In particular, $\mu_{CZ}^{\tau_{\Sigma},\delta_i}(\gamma_i) = 1$, $\forall i$. Denote $\delta = (\delta_1, \ldots, \delta_n; \emptyset)$. Let $\tilde{J} \in \mathcal{J}(\alpha)$ be defined as in (8) by α and J. From now on fix a closed connected oriented genus g surface S with distinct points z_1, \ldots, z_n in S, and set $\Gamma = \{z_1, \ldots, z_n\}$.

Lemma 3.1. Let $C = [\tilde{u} = (a, u), S, j, \Gamma, \emptyset] \in \mathcal{M}_{\tilde{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$, where *j* denotes some complex structure on *S*. If *C* and Σ induce the same class in $H_2(M, L)$ then *C* does not intersect $\mathbb{R} \times L$. Moreover,

$$\widetilde{u} * \widetilde{u} = \frac{1}{2}\mu_{\rm CZ}(\widetilde{u}) - \frac{1}{2}\#\Gamma_{\rm odd} - \chi(S) + \bar{\sigma}(\widetilde{u})$$
(27)

and

wind_{$$\pi$$}(\tilde{u}) = 0, wind _{∞} (\tilde{u} , z_i , τ_{Σ}) = 0 $\forall i$. (28)

By the definition of wind_{π} reviewed in Section 2.2.5, its vanishing means that the projection of the curve to *M* is transverse to the Reeb vector field. The vanishing of

wind_{∞} at the punctures with respect to τ_{Σ} means that the approach to the asymptotic limits is 'parallel' to Σ , up to continuous deformations. The conclusions of Lemma 3.1 serve as input for the results from [42] to say that the projection of the curve satisfies some of the properties that a global surface of section spanned by *L* in class *b* must satisfy; see Proposition 3.4 below.

Proof of Lemma 3.1. The first, and crucial, step is to show that wind_{π}(\tilde{u}) = 0. To prove this we start by noting that wind_{∞}($\tilde{u}, z_k, \tau_{\Sigma}$) ≤ 0 for every k since the asymptotic eigenvalue of \tilde{u} at z_k is less than δ_k . Here we use the definition of $\mathcal{M}_{\tilde{J},g,\delta}$ explained in Section 2.2.6, the monotonicity of winding numbers of eigenvalues explained in Section 2.1, and our special choice of δ_k . Let Ξ be a (homotopy class of) $d\alpha$ -symplectic trivialization of $u^*\xi$. Then Ξ induces (homotopy classes of) $d\alpha$ -symplectic trivializations τ_k^{Ξ} of ξ_{γ_k} , for each k. Since C and Σ give the same element in $H_2(M, L)$, the τ_k^{Ξ} together extend to a $d\alpha$ -symplectic trivialization of $\xi|_{\Sigma}$. By (A2) a section of $\xi|_{\Sigma}$ which is tangent to Σ along $L = \partial \Sigma$ and points outward must have the same algebraic count of zeros as a section of $T\Sigma$ which is outward pointing along $L = \partial \Sigma$. In the latter case the algebraic count is precisely 2 - 2g - n. Hence

$$\sum_{k=1}^{n} \operatorname{wind}(\tau_k^{\Xi}, \tau_{\Sigma}) = 2 - 2g - n.$$
(29)

Now we compute

wind_{$$\pi$$}(\widetilde{u}) + 2 - 2g - n = wind _{∞} (\widetilde{u}) = $\sum_{k=1}^{n}$ wind _{∞} (\widetilde{u} , z_k , τ_k^{Ξ})
= $\sum_{k=1}^{n}$ wind _{∞} (\widetilde{u} , z_k , τ_{Σ}) + wind(τ_k^{Ξ} , τ_{Σ})
 $\leq 0 + 2 - 2g - n$.

Thus wind_{π}(\tilde{u}) ≤ 0 , so wind_{π}(\tilde{u}) = 0. In particular, u is an immersion transverse to X_{α} . Plugging all this information back into the above identities we get

wind_{$$\infty$$}($\tilde{u}, z_k, \tau_{\Sigma}$) = 0 $\forall k$. (30)

We now follow [20, Theorem 4.10]. Let $int(\cdot, L) : H_2(M, M \setminus L; \mathbb{Z}) \to \mathbb{Z}$ be the algebraic count of intersections with *L*. Consider the long exact sequence of the pair $(M, M \setminus L)$,

$$\cdots \to H_2(M) \xrightarrow{\pi_*} H_2(M, M \setminus L) \xrightarrow{\hat{\delta}} H_1(M \setminus L) \to \cdots$$

where π_* is the map induced by the inclusion $(M, \emptyset) \hookrightarrow (M, M \setminus L)$ and $\hat{\delta}$ is the connecting homomorphism. Note that im $\pi_* \subset \ker \operatorname{int}(\cdot, L)$ since *L* is null-homologous in *M*. Consider conformal disks D_k centered at z_k , assumed to be very small. Denote $R = S \setminus \bigcup_k D_k$. By Theorem 2.7, $u(\partial R) \subset M \setminus L$, $u^{-1}(L) \subset R \setminus \partial R$, and the homotopy classes of the asymptotic eigenvectors govern how *u* approaches *L*. Moreover, combining Theorem 2.7 and (30) we see that if the D_k are small enough then $u|_{\partial R}$ is a link obtained by pushing *L* in the direction of τ_{Σ} . Thus $u|_R$ can be slightly C^0 -perturbed near

 ∂R , without creating new intersections with L, and be glued to $\overline{\Sigma}$ with a small annular neighborhood of its boundary deleted (here $\overline{\Sigma}$ denotes the surface Σ with reversed orientation) to obtain $Q \in H_2(M)$ satisfying $\operatorname{int}([u(R)], L) = \operatorname{int}(\pi_*(Q), L)$. It follows that $\operatorname{int}([u(R)], L) = 0$ because im $\pi_* \subset \ker \operatorname{int}(\cdot, L)$. But, since u is an immersion transverse to X_{α} , all intersections between u and L are isolated and count positively. Hence there are no intersections at all.

Finally, by (30) we must have $i^{\tau_{\Sigma}}(\tilde{u}, \tilde{u}) = 0$ since (by Theorem 2.7) at a puncture z_k the *M*-component *u* of \tilde{u} approaches the asymptotic limit γ_k by loops that do not wind around the center of a Martinet tube aligned with τ_{Σ} . Asymptotic limits of \tilde{u} at distinct punctures are distinct and prime closed Reeb orbits. Hence the pairs of punctures contributing to the sum Σ^+ in (22) are of the form $\{(z, z)\}_{z \in \Gamma}$. We get $\Omega^{\tau_{\Sigma}}(\tilde{u}, \tilde{u}) = \sum_{k=1}^{n} \lfloor \rho^{\tau_{\Sigma}}(\gamma_k) \rfloor$ since there are no negative punctures, and we arrive at

$$\widetilde{u} * \widetilde{u} = \sum_{k=1}^{n} \lfloor \rho^{\tau_{\Sigma}}(\gamma_k) \rfloor.$$
(31)

It follows from

$$\mu_{CZ}^{\tau_{\Sigma}}(\gamma_{k}) = \begin{cases} 2\lfloor \rho^{\tau_{\Sigma}}(\gamma_{k}) \rfloor & \text{if } \mu_{CZ}^{\tau_{\Sigma}}(\gamma_{k}) \text{ is even} \\ 2\lfloor \rho^{\tau_{\Sigma}}(\gamma_{k}) \rfloor + 1 & \text{if } \mu_{CZ}^{\tau_{\Sigma}}(\gamma_{k}) \text{ is odd,} \end{cases}$$

that

$$\sum_{k=1}^{n} \lfloor \rho^{\tau_{\Sigma}}(\gamma_k) \rfloor = \frac{1}{2} \sum_{k=1}^{n} \mu_{\text{CZ}}^{\tau_{\Sigma}}(\gamma_k) - \frac{1}{2} \# \Gamma_{\text{odd}}$$
(32)

where Γ_{odd} denotes the set of punctures where the asymptotic limit has odd Conley–Zehnder index (the parity of the Conley–Zehnder index does not depend on the choice of trivialization). In view of the formula $\sum_k \operatorname{wind}(\tau_k^{\Xi}, \tau_{\Sigma}) = \chi(S) - \#\Gamma$, which was already used, we conclude that

$$\begin{split} \widetilde{u} * \widetilde{u} &= \sum_{k=1}^{n} \lfloor \rho^{\tau_{\Sigma}}(\gamma_{k}) \rfloor = \frac{1}{2} \sum_{k=1}^{n} \mu_{CZ}^{\tau_{\Sigma}}(\gamma_{k}) - \frac{1}{2} \# \Gamma_{\text{odd}} \\ &= \frac{1}{2} \sum_{k=1}^{n} \mu_{CZ}^{\tau_{E}^{\Xi}}(\gamma_{k}) - \frac{1}{2} \# \Gamma_{\text{odd}} - \chi(S) + \# \Gamma = \frac{1}{2} \mu_{CZ}(\widetilde{u}) - \frac{1}{2} \# \Gamma_{\text{odd}} - \chi(S) + \# \Gamma. \end{split}$$

This finishes the proof of (27) since $\bar{\sigma}(\tilde{u}) = \#\Gamma$; note that all asymptotic limits are prime closed Reeb orbits.

Now let α' be another contact form defining ξ . Suppose that $\alpha > \alpha'$ and also that $X_{\alpha'}$ is positively tangent to *L*. Choose $\tilde{J}' \in \mathcal{J}(\alpha')$. Then we may choose *h* and construct Ω as in Section 2.2.2, and consider $\bar{J} \in \mathcal{J}_{\Omega,L}(\tilde{J}', \tilde{J})$ as in Section 2.2.8. In particular, $\mathbb{R} \times L$ is a \bar{J} -holomorphic embedded surface.

Remark 3.2. If $C \in \mathcal{M}_{\tilde{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ satisfies $C \subset [1, +\infty) \times M$ then we may view it as a curve in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$. Assumption (A4) ensures that we can apply Theorem 2.7 to all punctures of curves in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$; see Section 2.2.4.

Lemma 3.3. Curves in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ or in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ are somewhere injective.

Proof. Represent $C \in \mathcal{M}_{\bar{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ as $[\tilde{u}, S, j, \Gamma, \emptyset]$ for some complex structure j on S. By standard arguments one finds a closed Riemann surface (S_0, j_0) equipped with a finite set $\Gamma_0 \subset S_0$, a finite-energy somewhere injective \bar{J} -holomorphic map \tilde{u}_0 : $(S_0 \setminus \Gamma_0, j_0) \to (\mathbb{R} \times M, \bar{J})$ and a holomorphic map $\phi : (S, j) \to (S_0, j_0)$ of degree k such that $\phi^{-1}(\Gamma_0) = \Gamma$ and $\tilde{u} = \tilde{u}_0 \circ \phi$. See [35, Section 3.2] for a detailed account of this fact. To prove the lemma we need to show that k = 1. All points in Γ_0 are necessarily positive punctures of \tilde{u}_0 . Choose $\zeta \in \Gamma_0$. We have $k = \sum_{z \in \phi^{-1}(\zeta)} b_{\phi}(z) + 1$ where $b_{\phi}(z)$ is the branching index: in appropriate holomorphic charts centered at $z \in \phi^{-1}(\zeta)$ and at ζ the map ϕ is represented as $w \mapsto w^{b_{\phi}(z)+1}$. Since all asymptotic limits of \tilde{u} are simply covered we must have $b_{\phi}(z) = 0$ for all $z \in \phi^{-1}(\zeta)$. Since asymptotic limits of \tilde{u} are mutually geometrically distinct, we obtain $\#\phi^{-1}(\zeta) = 1$. Combining these facts and the formula for k we conclude that k = 1. The same argument handles the \mathbb{R} -invariant case.

Proposition 3.4. Let $C = [\tilde{u}, S, j, \Gamma, \emptyset] \in \mathcal{M}_{\tilde{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ induce the same class in $H_2(M, L)$ as Σ . If we denote by u the M-component of \tilde{u} , then u defines a proper embedding $S \setminus \Gamma \hookrightarrow M \setminus L$ transverse to X_{α} .

Proof. Consequence of Lemma 3.1, [42, Theorem 2.6] and Lemma 3.3; see Remark 3.2.

Proposition 3.5. The projections to M of two curves in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ are either equal or do not intersect.

Proof. Consequence of Proposition 3.4 and [42, Theorem 2.4].

The point of the above propositions is that later we will use projections of curves in $\mathcal{M}_{\tilde{J},0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ in class *b* as pages of an open book decomposition by global surfaces of section.

Proposition 3.6. Let $C \in \mathcal{M}_{\tilde{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ be contained in $[1, +\infty) \times M$. If C' can be connected to C by a smooth path of curves in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$, and C induces the same class in $H_2(M, L)$ as Σ , then C' is embedded.

Proof. Consequence of Proposition 2.14, Theorem 2.15 and formula (27), again noting that C' is somewhere injective by Lemma 3.3.

Lemma 3.7 (Automatic transversality). Let $\overline{J} \in \mathcal{J}_{\Omega,L}(\widetilde{J}', \widetilde{J})$ and let C be a curve in $\mathcal{M}_{\widetilde{J},0,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ contained in $[1, +\infty) \times M$ and inducing the same class in $H_2(M, L)$ as Σ . The subset of $\mathcal{M}_{\overline{J},0,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ consisting of curves that can be connected to C in $\mathcal{M}_{\overline{J},0,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ is a smooth two-dimensional manifold whose differentiable structure is compatible with the C_{loc}^{∞} -topology. Moreover, a neighborhood in $\mathbb{R} \times M$ of every curve in this space is smoothly foliated by curves in $\mathcal{M}_{\overline{J},0,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$.

Sketch of proof. Fix $C' \in \mathcal{M}_{\bar{J},0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ in the connected component of C. We can always represent it as $[\tilde{v}, S^2, j, \Gamma, \emptyset]$ using our fixed data S^2, Γ , where j is some complex structure on S^2 . It follows from Proposition 3.6 that \tilde{v} is an embedding. Consider a \bar{J} -invariant normal bundle $N_{\tilde{v}}$ and set up a Fredholm theory for sections of this normal bundle with exponential weights δ . One can use Hölder spaces with exponential weights as in [24]. The normal bundle can be chosen to extend as the contact plane field ξ along the ends of \tilde{v} . A crucial fact is that τ_{Σ} extends as an Ω -symplectic trivialization of $N_{\tilde{v}}$. The Cauchy–Riemann equation gives rise to a non-linear Fredholm map on the space of sections close to zero, whose linearization at zero is a Cauchy–Riemann type linear operator $D_{\tilde{v}}$. The associated asymptotic operators are precisely the asymptotic operators at the asymptotic limits. The weighted Fredholm index is

$$2 - n + \sum_{k=1}^{n} \mu_{CZ}^{\tau_{\Sigma}, \delta_{k}}(\gamma_{k}) = 2 - n + n = 2.$$

This formula has important consequences. By the similarity principle, every zero of a section in ker $D_{\tilde{v}}$ has strictly positive contribution to the algebraic count of zeros. Moreover, since τ_{Σ} extends as a trivialization of $N_{\tilde{v}}$, and a section in ker $D_{\tilde{v}}$ has an asymptotic behavior governed by eigenvalues of the asymptotic operators smaller than the δ_k , the total winding number of such a section at the ends is non-positive. Combining both these facts with basic degree theory, one concludes that non-trivial sections in the kernel are nowhere vanishing. But the Fredholm index is 2, so if $D_{\tilde{v}}$ has non-trivial cokernel then its kernel will have dimension ≥ 3 , and some non-trivial linear combination of sections in ker $D_{\tilde{v}}$ will vanish somewhere because $N_{\tilde{v}}$ has rank 2. This contradiction shows that there is no cokernel, in other words, we have automatically the transversality needed to apply the implicit function theorem and obtain a chart of the 2-manifold structure of the moduli space. Moreover, all curves near C' necessarily show up in this chart.

Finally, the difference of two sections near the zero section belonging to the zero locus of the non-linear Cauchy–Riemann equation again satisfies a Cauchy–Riemann type equation with the same asymptotic operators, and is subject to asymptotic analysis. Hence, the algebraic count of intersections between two such nearby sections is zero. By positivity of intersections, all intersection points contribute positively to this algebraic count. Hence, nearby curves do not intersect, and the claim made in the statement about local foliations follows.

Proposition 3.8. Let $C \in \mathcal{M}_{\tilde{J},g,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ be contained in $[1, +\infty) \times M$. If C' is in the same connected component of $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ as C, where we view C in $\mathcal{M}_{\tilde{J},g,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$, and if C induces the same class in $H_2(M, L)$ as Σ , then int $(C', \mathbb{R} \times L) = 0$. Moreover, if $C' = [\tilde{v}, S, j', \Gamma, \emptyset]$ then wind $_{\infty}(\tilde{v}, z_k, \tau_{\Sigma}) = 0$ for all k.

Proof. Represent $C = [\tilde{u} = (a, u), S, j, \Gamma, \emptyset]$. Following the beginning of the proof of Lemma 3.1 we arrive at (30). We will argue to show that (30) implies that

$$i^{\tau_{\Sigma}}(\widetilde{u}, \mathbb{R} \times L) = 0.$$

In fact, by (30) the *M*-component *u* approaches the asymptotic limits by loops that do not wind around the center of Martinet tubes aligned with τ_{Σ} . Thus, if we displace \tilde{u} near the punctures in the direction of τ_{Σ} to obtain a map $\tilde{u}^{\tau_{\Sigma},\varepsilon,r}$ as in Section 2.2.7, then there is no additional contribution to the intersection number with $\mathbb{R} \times L$ and we get

$$i^{\tau_{\Sigma}}(\widetilde{u}, \mathbb{R} \times L) = \operatorname{int}(\widetilde{u}^{\tau_{\Sigma}, \varepsilon, r}, \mathbb{R} \times L) = \operatorname{int}(\widetilde{u}, \mathbb{R} \times L).$$

Here *r* is large and ε is small. Proposition 3.4 gives $\operatorname{int}(\tilde{u}, \mathbb{R} \times L) = 0$, from which we conclude that $i^{\tau_{\Sigma}}(\tilde{u}, \mathbb{R} \times L) = 0$.

Now $i^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L) = i^{\tau_{\Sigma}}(\tilde{u}, \mathbb{R} \times L)$ for every finite-energy map \tilde{v} representing a curve C' in $\mathcal{M}_{\bar{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ in the same component as C. This follows from Proposition 2.14. Here we use the fact that min $a \ge 1$ allows us to view C as an element of $\mathcal{M}_{\bar{J},g,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$, and that $\mathbb{R} \times L$ is a \bar{J} -holomorphic surface since $\bar{J} \in \mathcal{J}_{\Omega,L}$. We get

$$i^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L) = 0.$$
(33)

We would like now to argue that $i^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L) = \operatorname{int}(\tilde{v}, \mathbb{R} \times L)$ and conclude the proof. Unfortunately, one cannot use an argument like the one used at the beginning of the proof of Lemma 3.1 to achieve (30) because here we deal with almost complex structures that are not \mathbb{R} -invariant. We argue differently.

The defining property of the weights δ_i implies that

wind_{$$\infty$$}($\tilde{v}, z_i, \tau_{\Sigma}$) $\leq 0 \quad \forall i.$ (34)

For each k consider a Martinet tube (U_k, Ψ_k) around γ_k aligned with τ_{Σ} . It provides coordinates (θ, z) near γ_k . Let (s, t) be positive holomorphic polar coordinates around z_k . For s large enough we can write $\tilde{v}(s, t) = (b(s, t), \theta(s, t), z(s, t))$. We know that $\tilde{v} = (b, v)$ must have non-trivial asymptotic formula at each z_k . Hence we find R such that $v([R, +\infty) \times \mathbb{R}/\mathbb{Z}) \subset U_k$ and z(s, t) does not vanish for $s \ge R$. By Theorem 2.7, perhaps after taking R larger, $(s, t) \mapsto (b(s, t), t)$ is a diffeomorphism between $[R, +\infty) \times \mathbb{R}/\mathbb{Z}$ and a positive end of $\mathbb{R} \times \mathbb{R}/\mathbb{Z}$. Thus we find $r \gg 1$ such that $(b, t) \in [r, +\infty) \times \mathbb{R}/\mathbb{Z}$ give new polar coordinates around z_k . This allows us to write $\tilde{v}(b, t) = (b, \theta(b, t), z(b, t))$. In addition z(b, t) does not vanish for $b \ge r$. Theorem 2.7 and the choice of r together imply that wind_{∞}($\tilde{v}, z_k, \tau_{\Sigma}$) equals the winding number of $t \mapsto z(r, t)$. With these choices, we take $\varepsilon > 0$ small enough, and define (as in Section 2.2.7)

$$\widetilde{v}^{k,\tau_{\Sigma},\varepsilon,r}(b,t) = (b,\theta(b,t), z(b,t) + \varepsilon\beta(b-r)), \quad (b,t) \in [r,+\infty) \times \mathbb{R}/\mathbb{Z},$$

where $\beta : \mathbb{R} \to [0, 1]$ is a smooth function equal to 0 near $(-\infty, 0]$ and to 1 near $[1, +\infty)$. In view of the choices of r and ε , the oriented intersection number $m_k \in \mathbb{Z}$ between $\tilde{v}^{k,\tau_{\Sigma},\varepsilon,r}$ and the \bar{J} -complex surface $\mathbb{R} \times \mathbb{R}/\mathbb{Z} \times \{0\}$ is well-defined. Repeating this construction for every k we arrive at what Siefring [42] defines as

$$i_{\infty}^{\tau_{\Sigma}}(\tilde{v},\mathbb{R}\times L):=\sum_{k=1}^{n}m_{k}.$$

Note that m_k is equal to the algebraic count of zeros of $z(b,t) + \varepsilon\beta(b-r)$ on $[r, +\infty) \times \mathbb{R}/\mathbb{Z}$ in the coordinates described above. Standard degree theory allows us to compute m_k as a difference of winding numbers. As explained before, by the choice of r the winding number of $t \mapsto z(r, t)$ is equal to wind $_{\infty}(\tilde{v}, z_k, \tau_{\Sigma})$ and, by construction, the winding number of $t \mapsto z(b, t) + \varepsilon\beta(b-r)$ vanishes when b is large enough. The crucial identity follows:

$$i_{\infty}^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L) = -\sum_{k=1}^{n} \operatorname{wind}_{\infty}(\tilde{v}, z_k, \tau_{\Sigma}).$$
(35)

Combining this with (34) we get

$$i_{\infty}^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L) \geq 0,$$

with equality if, and only if, wind_{∞}($\tilde{v}, z_k, \tau_{\Sigma}$) = 0 for every k. Now [42, Theorem 4.2], (33) and the above inequality together give

$$0 = i^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L) = \operatorname{int}(\tilde{v}, \mathbb{R} \times L) + i_{\infty}^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L).$$

Both terms on the right-hand side are non-negative: the first by positivity of intersections, the second by the previous inequality. Hence both terms vanish. The desired conclusion follows since $i_{\infty}^{\tau_{\Sigma}}(\tilde{v}, \mathbb{R} \times L) = 0$ if, and only if, wind_{∞} $(\tilde{v}, z_k, \tau_{\Sigma}) = 0$ for all k.

3.2. Existence and compactness of holomorphic curves

Let *L* be a link in *M* with components $\gamma_1, \ldots, \gamma_n$ and let α_+ and α_- be defining contact forms for ξ such that $\alpha_+ > \alpha_-$. Let Σ be an oriented genus zero Seifert surface for *L*, and orient *L* as the boundary of Σ . Consider the following list of hypotheses:

- (H1) Both $X_{\alpha_{+}}$ and $X_{\alpha_{-}}$ are positively tangent to *L*.
- (H2) X_{α_+} is positively transverse to $\Sigma \setminus L$.
- (H3) Every γ_k satisfies $\mu_{CZ}^{\tau_{\Sigma}} \ge 1$ with respect to both α_+ and α_- .
- (H4) The contact forms α_+, α_- are non-degenerate up to action

$$A = \sum_{k=1}^{n} \int_{\gamma_k} \alpha_+$$

and the following hold:

- (+) If $\gamma = (x, T)$ in $\mathcal{P}(\alpha_+)$ satisfies $T \leq A$ and $x(\mathbb{R}) \subset M \setminus L$ then $int(\gamma, \Sigma) \neq 0$.
- (-) If $\gamma = (x, T)$ in $\mathcal{P}(\alpha_{-})$ satisfies $T \leq A$ and $x(\mathbb{R}) \subset M \setminus L$ then $int(\gamma, \Sigma) \neq 0$.
- (H5) If *I* is any proper non-empty subset of $\{1, ..., n\}$ then the link in $M \setminus L$ obtained by pushing $\{\gamma_k \mid k \in I\}$ in the direction of Σ defines a non-zero homology class in $H_1(M \setminus L)$.

Remark 3.9. In (H4) we denote by int : $H_1(M \setminus L) \otimes H_2(M, L) \to \mathbb{Z}$ the algebraic intersection pairing. Hypothesis (H5) is automatically satisfied when Σ is a page of an open book decomposition with binding *L*. This is a consequence of Lemma B.1.
Under the assumption that (H1)–(H3) hold, choose almost complex structures $\tilde{J}_{\pm} \in \mathcal{J}(\alpha_{\pm})$ and $\bar{J} \in \mathcal{J}_{\Omega,L}(\tilde{J}_{-}, \tilde{J}_{+})$. Fix *h* and Ω as in Section 2.2.2, which allows us to define the energy (10) of a \bar{J} -holomorphic map. By (H3) we can choose numbers $\delta_{1}^{\pm}, \ldots, \delta_{n}^{\pm} < 0$ such that

- δ_k^+ is in the spectral gap between eigenvalues of winding number 0 and 1 relative to τ_{Σ} of the asymptotic operator at γ_k induced by (α_+, J_+) ,
- δ_k^- is in the spectral gap between eigenvalues of winding number 0 and 1 relative to τ_{Σ} of the asymptotic operator at γ_k induced by (α_-, J_-) .

Set $\delta^{\pm} = (\delta_1^{\pm}, \dots, \delta_n^{\pm}; \emptyset)$. The main goal of this section is to prove the statement below. It contains an 'implied existence statement' for the holomorphic curves relevant to our results: they are assumed to exist for the model contact form α_+ , and the proposition states that they need also exist for α_- .

Proposition 3.10. Assume all hypotheses (H1)–(H5) hold. If there exists some curve in $\mathcal{M}_{\tilde{J}_+,0,\delta^+}(\gamma_1,\ldots,\gamma_n;\emptyset)$ that induces the same class as Σ in $H_2(M, L)$, then there exists a curve $C_- \in \mathcal{M}_{\tilde{J}_-,0,\delta^-}(\gamma_1,\ldots,\gamma_n;\emptyset)$ whose projection to M is in the same class as Σ in $H_2(M, L)$. Moreover, if \mathcal{Y} denotes the connected component of C_- then \mathcal{Y}/\mathbb{R} is compact.

Throughout this subsection we always assume (H1)–(H3) and (H5). Different parts of (H4) will be used at different moments in the arguments below. We fix an ordered set $\Gamma \subset S^2$ of distinct points z_1, \ldots, z_n , and assume the existence of a curve

$$C_{+} = [\tilde{u}_{+} = (a_{+}, u_{+}), S^{2}, j, \Gamma, \emptyset] \in \mathcal{M}_{\tilde{J}_{+}, 0, \delta^{+}}(\gamma_{1}, \dots, \gamma_{n}; \emptyset)$$
(36)

inducing the same class as Σ in $H_2(M, L)$. As explained in Remark 3.2, we can translate C_+ up and assume that it also induces an element of $\mathcal{M}_{\overline{J},0,\delta^+}(\gamma_1,\ldots,\gamma_n;\emptyset)$.

Lemma 3.11. The following assertions hold:

(a) Let $C_l \in \mathcal{M}_{\overline{J},0,\delta^+}(\gamma_1,\ldots,\gamma_n;\emptyset)$ be a sequence in the same connected component as C_+ of (36). Assume that C_l SFT-converges to the building

$$\mathbf{u} = \{\{\widetilde{u}_m = (a_m, u_m), S_m, j_m, \Gamma_m^+, \Gamma_m^-, D_m)\}, \{\Phi_m\}\}.$$

Then for every m and every connected component $Y \subset S_m$, either

$$\widetilde{u}_m(Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)) \subset \mathbb{R} \times L \quad or \quad \widetilde{u}_m(Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)) \cap \mathbb{R} \times L = \emptyset.$$

(b) Let C₋ ∈ M_{J₋,0,δ}-(γ₁,..., γ_n; Ø) induce the same class as Σ in H₂(M, L), and let the sequence C_l in M_{J₋,0,δ}-(γ₁,..., γ_n; Ø), in the same connected component of C₋, SFT-converge to the building

$$\mathbf{u} = \{\{\widetilde{u}_m = (a_m, u_m), S_m, j_m, \Gamma_m^+, \Gamma_m^-, D_m)\}, \{\Phi_m\}\}.$$

Then for every m and every connected component $Y \subset S_m$, either

$$\widetilde{u}_m(Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)) \subset \mathbb{R} \times L \quad or \quad \widetilde{u}_m(Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)) \cap \mathbb{R} \times L = \emptyset.$$

Proof. We only prove (a) since (b) is proved in the same way. Represent the sequence C_l in (a) as $C_l = [\tilde{v}_l = (b_l, v_l), S^2, j_l, \Gamma, \emptyset]$. Fix *m* and a connected component $Y \subset S_m$ arbitrarily. If the restriction of \tilde{u}_m to $Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ is constant then there is nothing to prove. Assume that it is not constant and that $\tilde{u}_m(Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)) \not\subset \mathbb{R} \times L$. Our task is to show that $\tilde{u}_m(Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)) \cap (\mathbb{R} \times L) = \emptyset$, or equivalently that

$$X = \{ z \in Y \setminus (\Gamma_m^+ \cup \Gamma_m^-) \mid \widetilde{u}_m(z) \in \mathbb{R} \times L \}$$

is empty. The similarity principle implies that X is discrete since $\mathbb{R} \times L$ is an embedded \overline{J} -complex surface. By (e') in Remark 2.23,

$$\varphi_l^* j_l \to j \quad \text{in } C^{\infty}_{\text{loc}}(Y \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m))$$

for suitable diffeomorphisms φ_l as explained in (26). Combining this with (f)–(g) (just before Remark 2.21) and elliptic regularity, we find that there is a sequence $c_{m,l} \in \mathbb{R}$ such that

$$(c_{m,l}\cdot \widetilde{v}_l)\circ \varphi_l|_{Y\setminus (\Gamma_m^+\cup \Gamma_m^-\cup D_m)}\to \widetilde{u}_m|_{Y\setminus (\Gamma_m^+\cup \Gamma_m^-\cup D_m)} \quad \text{in } C^{\infty}_{\text{loc}}(Y\setminus (\Gamma_m^+\cup \Gamma_m^-\cup D_m)).$$

Here $c_{m,l} \cdot \tilde{v}_l$ denotes the map $(b_l + c_{m,l}, v_l)$. Denoting by τ_c the $(\mathbb{R}, +)$ action on $\mathbb{R} \times M$, we use the fact that the map $(c_{m,l} \cdot \tilde{v}_l) \circ \varphi_l = \tau_{c_{m,l}} \circ \tilde{v}_l \circ \varphi_l$ is pseudo-holomorphic with respect to $(\varphi_l^* j_l, (\tau_{c_{m,l}})_* \bar{J})$ on $Y \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m)$. Note that $\mathbb{R} \times L$ is an embedded $(\tau_c)_* \bar{J}$ -holomorphic curve for every $c \in \mathbb{R}$ since $\bar{J} \in \mathcal{J}_{\Omega,L}(\tilde{J}_-, \tilde{J}_+)$ (see Section 2.2.8). Up to choice of a subsequence, we can assume that $(\tau_{c_{m,l}})_* \bar{J}$ converges in C^{∞} as $l \to \infty$ to an almost complex structure which is equal to either $(\tau_c)^* \bar{J}$ for some $c \in \mathbb{R}$, or \tilde{J}_- or \tilde{J}_+ . Positivity and stability of intersections implies that if X intersects $Y \setminus (\Gamma_m^+ \cup \Gamma_m^- \cup D_m)$ then the image of $c_{m,l} \cdot \tilde{v}_l$ intersects $\mathbb{R} \times L$ when l is large enough, or equivalently the map \tilde{v}_l intersects $\mathbb{R} \times L$. This contradicts Proposition 3.8, and shows that $X \subset D_m$.

Let $z \in X \subset D_m$ and $K \subset Y \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ be a conformal disk with z in its interior. If K is small enough then $\{z\} = K \cap D_m$, and in particular $K \cap \tilde{u}_m^{-1}(\mathbb{R} \times L) = \{z\}$. The M-component u_m of \tilde{u}_m maps K into a small tubular neighborhood of L given a priori. Positivity of intersections implies that $\tilde{u}_m|_K$ has positive algebraic intersection count with $\mathbb{R} \times L$. An application of Lemma A.1 tells us that $\operatorname{int}(u_m(\partial K), \Sigma) > 0$. We see that if l is large enough then $\beta_l = \varphi_l(\partial K)$ is an embedded loop in $S^2 \setminus \Gamma$ such that $v_l(\beta_l)$ is uniformly close to $u_m(\partial K)$. We obtain $\operatorname{int}(v_l(\beta_l), \Sigma) > 0$ when l is large enough. We can use Proposition 3.8 to get $0 < \operatorname{int}(u_+(\beta_l), \Sigma) = \operatorname{int}(u_+(\beta_l), u_+(S^2 \setminus \Gamma))$, where u_+ is the M-component of the curve C_+ . This contradicts to Proposition 3.4. Thus $X = \emptyset$ as desired.

Lemma 3.12. The following assertions are true:

(a) Assume that (H4)(+) holds. Let C_l = [v
_l = (b_l, v_l), S², j_l, Γ, Ø] be a sequence in M_{j,0,δ+}(γ₁,..., γ_n; Ø) in the same connected component as the curve C₊ of (36), such that the sequence {inf b_l(S² \ Γ)}_l is bounded. Then a subsequence of {C_l} SFT-converges in M_{j,0,δ+}(γ₁,..., γ_n; Ø). (b) Assume that (H4)(−) holds. Let C_− ∈ M_{J−,0,δ−}(γ₁, ..., γ_n; Ø) be a curve that induces the same class as Σ in H₂(M, L). If 𝔅 denotes the connected component of M_{J−,0,δ−}(γ₁,..., γ_n; Ø) containing C_− then 𝔅/ℝ is compact.

Remark 3.13. The metrizable topology with respect to which we claim that \mathcal{Y}/\mathbb{R} is compact is the one induced by C_{loc}^{∞} -convergence. More precisely, for every sequence

$$\left\{C_l = [\widetilde{v}_l = (b_l, v_l), S_l, j_l, \{z_{1,l}^+, \dots, z_{n,l}^+\}, \emptyset]\right\}_{l \in \mathbb{N}} \subset \mathcal{Y}$$

one finds $C = [\tilde{v} = (b, v), S, j, \{\hat{z}_1, \dots, \hat{z}_n\}, \emptyset] \in \mathcal{Y}$, a subsequence C_{l_m} , and sequences $d_m \in \mathbb{R}, \varphi_m : S \to S_{l_m}$ such that φ_m is a diffeomorphism, $\varphi_m(\hat{z}_i) = z_{i,l_m}^+$ for all i, m and

$$\varphi_m^* j_{l_m} \to j, \quad b_{l_m} \circ \varphi_m + d_m \to b, \quad v_{l_m} \circ \varphi_m \to v$$

in $C^{\infty}_{\text{loc}}(S \setminus \{\hat{z}_1, \ldots, \hat{z}_n\}).$

Proof of Lemma 3.12. We first spell out the proof of (a) in full detail, and then sketch the proof of (b) since arguments are essentially the same.

Fix representatives $(\tilde{v}_l = (b_l, v_l), S^2, j_l, \Gamma, \emptyset)$ of C_l , where Γ is the ordered set fixed at the beginning of this subsection. By SFT-compactness we may assume, up to taking a subsequence, that \tilde{v}_l SFT-converges to a building $\mathbf{u} = (\{\tilde{u}_m = (a_m, u_m)\}, \{\Phi_m\})$ of height $k_-|1|k_+$. Borrowing notation from the above discussion, the domain of $F_{\tilde{v}_l}$ is an *n*-holed 2-sphere with interior equal to $S^2 \setminus \Gamma$, and we get diffeomorphisms φ_l together with finite ordered sets K_l , K such that (a)–(g) hold. Since $\sup_l |\inf_{S^2 \setminus \Gamma} b_l|$ is bounded we know that $k_- = 0$.

Our first task is to prove that $k_+ = 0$. Arguing indirectly, suppose that $k_+ \ge 1$. Consider an arbitrary level *m* different from the top level: $m < k_+$. We claim that the asymptotic limit γ at every positive puncture $z_* \in \Gamma_m^+$ of \tilde{u}_m is contained in *L*. The argument is indirect. Suppose that such an asymptotic limit $\gamma = (x, T)$ is a closed Reeb orbit in $M \setminus L$. We know that γ is a closed α_+ -Reeb orbit since $k_- = 0$, so $m \ge 0$. Hypothesis (H4)(+) implies that $int(\gamma, \Sigma) \ne 0$. Using (e)–(f) we obtain *l* large and an embedded loop $\beta_l \subset S^2 \setminus \Gamma$ such that $v_l(\beta_l)$ is C^0 -close to the loop $x(T \cdot) : \mathbb{R}/\mathbb{Z} \to M \setminus L$, in particular, $int(v_l(\beta_l), \Sigma) \ne 0$. By assumption, all C_l are in the same connected component of the curve C_+ of (36). It follows from Proposition 3.8 that $[u_+(\beta_l)] = [v_l(\beta_l)]$ in $H_1(M \setminus L)$ since the curves C_+ and C_l can be homotoped to one another through holomorphic curves that do not touch $\mathbb{R} \times L$. Hence $int(u_+(\beta_l), \Sigma) \ne 0$. But, by assumption, Σ and $u_+(S^2 \setminus \Gamma)$ induce the same element in $H_2(M, L)$. It follows that u_+ is not an embedding into $M \setminus L$ because $int(u_+(\beta_l), u_+(S^2 \setminus \Gamma)) \ne 0$. This contradiction to Proposition 3.4 shows that $\gamma \subset L$. Consider the top level which, by the contradiction assumption $k_+ \ge 1$, is a finite-energy \tilde{J}_+ -holomorphic nodal curve

$$\widetilde{u}_{k_+} = (a_{k_+}, u_{k_+}) : S_{k_+} \setminus (\Gamma_{k_+}^+ \cup \Gamma_{k_+}^-) \to \mathbb{R} \times M.$$

Let Y be a connected component of S_{k_+} such that $\tilde{u}_{k_+}|_Y$ is not a constant map and is not a trivial cylinder over some periodic orbit. Such a component Y exists, as one easily shows by combining Lemma 2.20 with the fact that asymptotic limits at positive punctures of \tilde{u}_{k_+} are prime and mutually geometrically distinct closed Reeb orbits. Let u_{k_+} denote the *M*-component of \tilde{u}_{k_+} . At each puncture in $\Gamma_{k_+}^+$ the curve \tilde{u}_{k_+} is asymptotic to a prime closed α_+ -Reeb orbit (one of the γ_k) and different punctures yield geometrically different asymptotic limits. It follows that

$$\int_{Y\setminus(\Gamma_{k_+}^+\cup\Gamma_{k_+}^-)}u_{k_+}^*d\alpha_+>0,$$

in other words, $\tilde{u}_{k+}|_{Y}$ is not a (possibly branched) cover of any trivial cylinder. In particular, \tilde{u}_{k+} has non-trivial asymptotic formula at all punctures in Y. Assume that there exists a negative puncture $z_* \in Y \cap \Gamma_{k+}^-$. Then, by what we have proved before, there exists $i \in \{1, \ldots, n\}$ such that the asymptotic limit γ_* of \tilde{u}_{k+} at z_* is of the form $\gamma_* = \gamma_i^{m_i}$, $m_i \in \mathbb{N}$. (H3) implies that $\mu_{CZ}^{\tau\Sigma}(\gamma_i^{m_i}) \ge \mu_{CZ}^{\tau\Sigma}(\gamma_i) \ge 1$. Now we use Theorem 2.7 to conclude that wind $_{\infty}(\tilde{u}_{k+}, z_*, \tau_{\Sigma}) \ge 1$ and that if $\beta \subset Y \setminus \Gamma_{k+}^+ \cup \Gamma_{k+}^-$ is a small loop winding once around z_* then $\operatorname{int}(u_{k+}(\beta), \Sigma) \ne 0$. The loop β corresponds to an embedded loop in the interior of $S^{\mathbf{u}, r}$. By (f) we obtain for l large, using diffeomorphisms φ_l as in (26), an embedded loop $\beta_l = \varphi_l(\beta)$ in $S^2 \setminus \Gamma$ such that $\operatorname{int}(v_l(\beta_l), \Sigma) \ne 0$. Arguing as before, combining Proposition 3.8 with Proposition 3.4, we arrive at a contradiction. This shows that \tilde{u}_{k+} has no negative punctures in Y. We have proved that $\tilde{u}_{k+}|_Y$ has positive $d\alpha_+$ area and no negative punctures. Obviously, it has at least one positive puncture.

We claim that

wind_{$$\infty$$}($\tilde{u}_{k_+}, \zeta, \tau_{\Sigma}$) = 0 $\forall \zeta \in Y \cap \Gamma_{k_+}^+$. (37)

If not then, by Theorem 2.7, u_{k_+} will map a small loop β_{ζ} winding once around ζ to a loop satisfying $\operatorname{int}(u_{k_+}(\beta_{\zeta}), \Sigma) \neq 0$. By the construction of $S^{\mathbf{u},r}$, β_{ζ} may be seen as a loop in $S^{\mathbf{u},r}$, and in view of (e)–(f) we find embedded loops $\beta_l \subset S^2 \setminus \Gamma$ such that $\operatorname{int}(v_l(\beta_l), \Sigma) \neq 0$. Arguing as at the beginning of this proof, Proposition 3.8 implies that $[u_+(\beta_l)] = [v_l(\beta_l)]$ in $H_1(M \setminus L)$, and by assumption $\Sigma = u_+(S^2 \setminus \Gamma)$ in $H_2(M, L)$. We get $\operatorname{int}(u_+(\beta_l), u_+(S^2 \setminus \Gamma)) \neq 0$, in contradiction to Proposition 3.4 and the important identities (37) are proved. We will now use (37) to show that $Y = S_{k_+}$. In fact, suppose not. Lemma 3.11 implies that $\widetilde{u}_{k_+}(Y \setminus \Gamma_{k_+}^+) \cap \mathbb{R} \times L = \emptyset$, or equivalently

$$u_{k_+}(Y \setminus \Gamma_{k_+}^+) \cap L = \emptyset.$$

But (37) and Theorem 2.7 tell us that u_{k_+} approaches the asymptotic limits at punctures in $Y \cap \Gamma_{k_+}^+$ along Σ . Hypothesis (H5) implies that $Y \cap \Gamma_{k_+}^+ = \Gamma_{k_+}^+$. No connected component $Y' \neq Y$ of S_{k_+} contains a positive puncture, and consequently $\tilde{u}_{k_+}|_{Y'}$ is constant due to exactness of symplectizations. If such a Y' exists then Lemma 2.20 provides two distinct components where \tilde{u}_{k_+} is non-constant, which is absurd. Hence $Y = S_{k_+}$, as desired. It follows that there are no negative punctures at the top level, contradicting $k_+ > 0$.

We have proved that $k_+ = 0$. Combining this with $k_- = 0$, we conclude that **u** has only one level \tilde{u}_0 , which must be a connected nodal curve. Let us argue that S_0 is connected. In fact, let Y be a connected component of S_0 such that $\tilde{u}_0|_Y$ is not constant. Arguing as above one first shows that (37) holds, and then uses (H5) to conclude that $Y \cap \Gamma_0^+ = \Gamma_0^+$. Here we heavily rely on the fact that the image of $\tilde{u}_0|_Y$ is not contained in $\mathbb{R} \times L$: by the similarity principle, if the image of $\tilde{u}_0|_Y$ would be contained in $\mathbb{R} \times L$ then there would be negative punctures, in contradiction to $k_- = 0$. Then \tilde{u}_0 is constant on all connected components of S_0 different from Y. If there is a connected component $Y' \subset S_0$ different from Y then Lemma 2.20 provides two distinct components where \tilde{u}_0 is non-constant, which is absurd. Hence $S_0 = Y$ is connected, and there are no nodes since the total genus is zero.

Summarizing, the limiting holomorphic building has one level \tilde{u}_0 , no nodal pairs, no negative punctures, and wind_{∞}($\tilde{u}_0, z, \tau_{\Sigma}$) = 0 for all $z \in \Gamma_0^+$. In other words, it is a curve in $\mathcal{M}_{\bar{J},0,\delta^+}(\gamma_1, \ldots, \gamma_n; \emptyset)$. The proof of (a) is complete.

The proof of (b) is essentially the same. In fact, consider a sequence $\mathbb{R} + C_l$ in \mathcal{Y}/\mathbb{R} . We may represent it by curves $C_l = [\tilde{v}_l = (b_l, v_l), S^2, j_l, \Gamma, \emptyset]$ satisfying $\min_{S^2 \setminus \Gamma} b_l = 0$ since we are allowed to translate in the \mathbb{R} -direction. As in the proof of (a), some subsequence converges to a limiting building **u** in the sense of SFT. This time assumption (H4)(-) plays the exact same role that (H4)(+) played in the proof of (a), and all arguments go through to conclude that **u** has one level which is the desired curve in $\mathcal{M}_{\tilde{J}-0.\delta} - (\gamma_1, \ldots, \gamma_n; \emptyset)$ representing the desired limit of the subsequence in \mathcal{Y}/\mathbb{R} .

Lemma 3.14. If (H4)(+) holds then there exists a sequence

$$C_l = [\tilde{v}_l = (b_l, v_l), S^2, j_l, \Gamma, \emptyset] \in \mathcal{M}_{\bar{J}, 0, \delta^+}(\gamma_1, \dots, \gamma_n; \emptyset)$$
(38)

in the same component as C_+ such that $\min b_l \to -\infty$ as $l \to \infty$.

Proof. Let \mathcal{Y} be the connected component of $\mathcal{M}_{\overline{J},0,\delta^+}(\gamma_1,\ldots,\gamma_n;\emptyset)$ containing the curve C_+ . Consider the set A of numbers $a \in \mathbb{R}$ such that all curves in \mathcal{Y} are contained in $[a, +\infty) \times M$. We wish to show that $A = \emptyset$. Assume that $A \neq \emptyset$ and consider $\underline{a} = \sup A$. Then $\underline{a} < +\infty$ since $\mathcal{Y} \neq \emptyset$, every curve in \mathcal{Y} is contained in $[\underline{a}, +\infty) \times M$ and there exists a sequence

$$C_l = [\widetilde{v}_l = (b_l, v_l), S^2, j_l, \Gamma, \emptyset]$$

such that $\inf b_l \to \underline{a}$ as $l \to \infty$. By Lemma 3.12 (a) we may assume that C_l SFT-converges to some $C_{\infty} \in \mathcal{M}_{\overline{J},0,\delta^+}(\gamma_1,\ldots,\gamma_n;\emptyset)$ represented by a finite-energy map $\tilde{v}_{\infty} = (b_{\infty},\tilde{v}_{\infty})$ satisfying $\inf b_{\infty} = \underline{a}$. Now Lemma 3.7 allows us to find curves in \mathcal{Y} whose \mathbb{R} -components reach below \underline{a} , which is absurd.

Lemma 3.15. Assume that (H4) holds. If there exists a sequence C_l as in (38) in the same component of C_+ satisfying min $b_l \to -\infty$ as $l \to \infty$, then there exists a curve $C_- \in \mathcal{M}_{\tilde{J}_-,0,\delta^-}(\gamma_1,\ldots,\gamma_n;\emptyset)$ inducing the same element in $H_2(M, L)$ as Σ . Moreover, if \mathcal{Y} denotes the connected component containing C_- then \mathcal{Y}/\mathbb{R} is compact.

Proof. This proof has many steps in common with the proof of Lemma 3.12. Fix representatives

$$(\tilde{v}_l = (b_l, v_l), S^2, j_l, \Gamma, \emptyset)$$

of a sequence of curves C_l as in the statement, where $\Gamma \subset S^2$ is independent of l. By SFTcompactness we may assume that, up to a subsequence, \tilde{v}_l SFT-converges to a building $\mathbf{u} = (\{\tilde{u}_m = (a_m, u_m)\}, \{\Phi_m\})$ of height $k_-|1|k_+$. We borrow all the notation used in the description of holomorphic buildings explained immediately before Lemma 3.12. The domain of $F_{\tilde{v}_l}$ is an *n*-holed 2-sphere with interior $S^2 \setminus \Gamma$. For each *l* large enough there is a diffeomorphism φ_l between the domain $S^{\mathbf{u},r}$ of $F_{\mathbf{u}}$ and the domain of $F_{\tilde{v}_l}$, and finite ordered sets K_l , K such that (a)–(g) hold. The first important remark is that $k_- \ge 1$ follows from the assumption min_l $b_l \to -\infty$.

Claim I. All asymptotic limits of all levels \tilde{u}_m are contained in L.

Proof of Claim I. We argue indirectly and suppose that the claim does not hold. Then some asymptotic limit of some level is a closed Reeb orbit $\gamma = (x, T)$ contained in $M \setminus L$, of α_+ or of α_- depending on the level. Using the diffeomorphisms φ_l and (f) we find for l large enough an embedded circle $\beta_l \subset S^2 \setminus \Gamma$ such that $v_l(\beta_l)$ is C^0 -close to the loop $\mathbb{R}/\mathbb{Z} \ni t \mapsto x(Tt)$. Fix l large. Hypothesis (H4) implies that $int(v_l(\beta_l), \Sigma) \neq 0$. Proposition 3.8 and positivity of intersections imply that C_l can be homotoped to C_+ through curves that do not touch $\mathbb{R} \times L$. Hence $int(u_+(\beta_l), \Sigma) = int(u_+(\beta_l), u_+(S^2 \setminus \Gamma)) \neq 0$. It follows that u_+ is not an embedding into $M \setminus L$, contradicting Proposition 3.4.

Claim II. If $-k_{-} \le m \le k_{+}$ and $Y \subset S_{m}$ is a connected component such that $\tilde{w} = \tilde{u}_{m}|_{Y}$ is non-constant and its image is not contained in $\mathbb{R} \times L$, then \tilde{w} does not intersect $\mathbb{R} \times L$ and has no negative punctures.

Proof of Claim II. To see this first note that, under these assumptions, \tilde{w} has a non-trivial asymptotic formula at every puncture. From claim I we already know that if \tilde{w} has a negative puncture z_* then its asymptotic limit at z_* is $\gamma_i^{m_i}$, for some $i \in \{1, \ldots, n\}$ and some $m_i \geq 1$. Hypothesis (H3) implies that $\mu_{CZ}^{\tau_{\Sigma}}(\gamma_i^{m_i}) \geq \mu_{CZ}^{\tau_{\Sigma}}(\gamma_i) \geq 1$. By Theorem 2.7, wind_{∞}($\tilde{w}, z_*, \tau_{\Sigma}$) ≥ 1 and a small embedded loop β_* winding once around z_* is mapped by the *M*-component *w* of \tilde{w} to a loop satisfying int($w(\beta_*), \Sigma$) $\neq 0$. Using the diffeomorphisms φ_l and (f) we find for *l* large an embedded loop β_l in $S^2 \setminus \Gamma$ such that int($v_l(\beta_l), \Sigma$) $\neq 0$. Now C_l is homotopic to C_+ of (36) through curves that do not touch $\mathbb{R} \times L$. This follows from Proposition 3.8 and positivity of intersections. For *l* large enough we find that $int(u_+(\beta_l), u_+(S^2 \setminus \Gamma)) = int(v_l(\beta_l), \Sigma) \neq 0$. This is in contradiction to Proposition 3.4. We have proved that \tilde{w} has no negative punctures, that is, $\Gamma_m^- \cap Y = \emptyset$. Lemma 3.11 implies that the image of \tilde{w} does not intersect $\mathbb{R} \times L$.

Claim III. $k_+ = 0$ and the top level $\tilde{u}_{k_+} = \tilde{u}_0$ is precisely $\mathbb{R} \times L$.

Proof of Claim III. Suppose first, for contradiction, that there exists a connected component Y of $S_{k+} \setminus (\Gamma_{k+}^+ \cup \Gamma_{k+}^-)$ such that $\tilde{u}_{k+}|_Y$ is not constant and $\tilde{u}_{k+}(Y)$ is not contained in $\mathbb{R} \times L$. We have $Y \cap \Gamma_{k+}^+ \neq \emptyset$ by the exact nature of symplectizations, and by exactness of the taming symplectic form Ω . The asymptotic limit of \tilde{u}_{k+} at $z_* \in Y \cap \Gamma_{k+}^+$ is a prime closed Reeb orbit given by one of the components of L and, by our contradiction assumption, \tilde{u}_{k+} has a non-trivial asymptotic formula at z_* . If wind_{∞}($\tilde{u}_{k_{\perp}}, z_*, \tau_{\Sigma}$) $\neq 0$ then, in view of Theorem 2.7, a small embedded loop $\beta_* \subset Y \setminus \Gamma_{k_+}^+$ winding once around z_* is mapped by the *M*-component u_{k_+} of \widetilde{u}_{k_+} to a loop satisfying $int(u_{k_+}(\beta_*), \Sigma) \neq 0$. Arguing as in Claim I, we find for l large an embedded loop $\beta_l \subset S^2 \setminus \Gamma$ such that $int(v_l(\beta_l), \Sigma) \neq 0$. Using Proposition 3.8, this leads to $int(u_+(\beta_l), u_+(S^2 \setminus \Gamma)) \neq 0$ in contradiction to Proposition 3.4. Thus wind_ $\infty(\widetilde{u}_{k_+}, z_*, \tau_{\Sigma}) = 0$ for every $z_* \in Y \cap \Gamma_{k_+}^+$. By Claim II, $Y \cap \Gamma_{k_+}^- = \emptyset$ and \widetilde{u}_{k_+} maps $Y \setminus \Gamma_{k+}^+$ to the complement of $\mathbb{R} \times L$. Hypothesis (H5) implies that $\Gamma_{k+}^+ \subset Y$. It follows that $\tilde{u}_{k_{\perp}}$ is constant on any other connected component of $S_{k_{\perp}}$, in particular, $\tilde{u}_{k_{\perp}}$ has no negative punctures in contradiction to $k_{-} > 0$. We have thus shown that for every connected component $Y \subset S_{k_{\perp}}$ the map $\widetilde{u}_{k_{\perp}}|_{Y}$ is either constant or its image is contained in $\mathbb{R} \times L$. In the latter case $\widetilde{u}_{k_{+}}|_{Y}$ must be a trivial cylinder over some γ_{k} ; it cannot be a (possibly branched) cover of a trivial cylinder since all asymptotic limits at the positive punctures of the top level are mutually geometrically distinct and simply covered. If there is a component of $S_{k_{\perp}}$ where $\tilde{u}_{k_{\perp}}$ is constant then Lemma 2.20 provides an intersection between two geometrically distinct closed Reeb orbits, which is absurd. Hence all components are trivial cylinders over some orbit in L. Then $k_{+} = 0$, for $k_{+} > 0$ would contradict the stability of the building since the top level would be a symplectization level. The desired conclusion follows.

Claim IV. $k_{-} = -1$ and \tilde{u}_{-1} provides an element of $\mathcal{M}_{\tilde{J}_{-},0,\delta^{-}}(\gamma_{1},\ldots,\gamma_{n};\emptyset)$.

Proof of Claim IV. Assume for contradiction that \tilde{u}_{-1} consists only of constant maps and of (possibly branched) covers of trivial cylinders. In the latter case the corresponding component would have to be a trivial cylinder over some component of L since, by Claim III, \tilde{u}_{-1} has n positive punctures and its asymptotic limits are exactly the n distinct components $\gamma_1, \ldots, \gamma_n$ of L, each simply covered and seen as a closed α_- -Reeb orbit. If on some component of S_{-1} minus the punctures the map \tilde{u}_{-1} is constant then Lemma 2.20 will provide an intersection between geometrically distinct closed Reeb orbits, and this is impossible. As a result, \tilde{u}_{-1} would consist precisely of n trivial cylinders, contradicting the stability of the building. We have shown that on some connected component $Y \subset S_{-1}$ the map \tilde{u}_{-1} is non-constant on $Y \setminus (\Gamma_{-1}^+ \cup \Gamma_{-1}^-)$ and $\tilde{u}_{-1}(Y \setminus (\Gamma_{-1}^+ \cup \Gamma_{-1}^-)) \not\subset$ $\mathbb{R} \times L$. We can apply Claim II to conclude that there are no negative punctures on Y and that $\widetilde{u}_{-1}(Y \setminus \Gamma_{-1}^+) \cap (\mathbb{R} \times L) = \emptyset$. Arguing as in the proof of Claim III we get wind_{∞}($\tilde{u}_{-1}, z_*, \tau_{\Sigma}$) = 0 for every $z_* \in Y \cap \Gamma_{-1}^+$. Hypothesis (H5) tells us that $\Gamma_{-1}^+ \subset Y$, in particular \tilde{u}_{-1} is constant on all other connected components of its domain. If there are nodes then, by Lemma 2.20, there are at least two distinct components where \tilde{u}_{-1} is non-constant, and this is absurd. Hence there are no nodes, $S_{-1} = Y$, and \tilde{u}_{-1} provides the desired curve in $\mathcal{M}_{\tilde{I}_{-0,\delta}}(\gamma_1,\ldots,\gamma_n;\emptyset)$.

Claims I–IV show the existence of C_- . Compactness of \mathcal{Y}/\mathbb{R} is a direct consequence of Lemma 3.12 (b).

Proposition 3.10 is a direct consequence of Lemmas 3.14 and 3.15.

3.3. Approximating sequences of contact forms

Proposition 3.16. Let α be a contact form on M, and let $L = \gamma_1 \cup \cdots \cup \gamma_n$ be a link consisting of periodic Reeb orbits of α . Assume that L binds a planar open book decomposition Θ that supports $\xi = \ker \alpha$, and assume with no loss of generality that α and Θ induce the same orientation on each γ_i . Suppose further that

(a) for every i, $\mu_{CZ}^{\Theta}(\gamma_i) \ge 1$ as a prime periodic Reeb orbit of α .

Then there exists a constant

$$A > \sum_{i=1}^n \int_{\gamma_i} \alpha$$

depending only on (α, L, Θ) , with the following significance. Fix any $d\alpha$ -compatible complex structure $J : \xi \to \xi$. For each *i*, choose any $\delta_i < 0$ in the spectral gap of the asymptotic operator induced by (α, J) on sections of ξ along γ_i , between eigenvalues of winding number 0 and 1 with respect to a Seifert framing induced by the pages of Θ . Denote $\delta = (\delta_1, \ldots, \delta_n; \emptyset)$. If

(b) every $\gamma' = (x', T') \in \mathcal{P}(\alpha)$ such that $x'(\mathbb{R}) \subset M \setminus L$ and $T' \leq A$ has non-zero algebraic intersection number with each page of Θ ,

then for any sequence $f_k \in \mathcal{F}_L$ satisfying

- $f_k \to 1$ in C^{∞} , $f_k|_L \equiv 1$ for all k,
- $f_k \alpha$ is non-degenerate for all k,

and \tilde{J}_k defined as in (8) using $f_k \alpha$ and J, there exists k_0 such that for every $k \ge k_0$ the link L binds a planar open book decomposition whose pages are global surfaces of section for the Reeb flow of $f_k \alpha$, all pages represent the same class in $H_2(M, L)$ as the pages of Θ and are projections of curves in $\mathcal{M}_{\tilde{J}_k, 0, \delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$.

Before embarking on the proof of Proposition 3.16 we state the following corollary.

Corollary 3.17. If (M, ξ) , L, α , Θ and b are as in Theorem 1.8 then the implication (iii) \Rightarrow (ii) from Theorem 1.8 holds whenever α is non-degenerate.

Proof. Apply Proposition 3.16 to the constant sequence $f_k \equiv 1$ for all k.

Let us start the proof of Proposition 3.16. Since Θ supports ξ , we know that the orientation of *L* induced by α either simultaneously agrees or simultaneously disagrees with the orientation induced by Θ on every component $\gamma \subset L$. It is no loss of generality to assume that these orientations agree on all γ . From now on, we give *L* this orientation and order its connected components $\gamma_1, \ldots, \gamma_n$ in an arbitrary manner.

By the results from [47], there exists at least one non-degenerate contact form α_+ such that $\alpha_+ > \alpha$, X_{α_+} is positively tangent to L, $\mu_{CZ}^{\Theta}(\gamma_i) = 1$ as closed Reeb orbits of α_+ , and every $\gamma \in \mathcal{P}(\alpha_+)$ contained in $M \setminus L$ has positive algebraic intersection number with each page of Θ . Moreover, setting

$$\delta^+ = (0, \dots, 0; \emptyset)$$

and choosing a suitable $d\alpha_+$ -compatible complex structure $J_+: \xi \to \xi$, we have

$$\mathcal{M}_{\tilde{J}_{+},0,\delta^{+}}(\gamma_{1},\ldots,\gamma_{n};\emptyset)\neq\emptyset.$$
(39)

Here \tilde{J}_+ is the \mathbb{R} -invariant almost complex structure on $\mathbb{R} \times M$ defined as in (8) using α_+ and J_+ . This moduli space is diffeomorphic to an open cylinder and its elements project to M as a circle family of embedded surfaces in $M \setminus L$ whose closures are C^1 -close to pages of Θ , all of which are global surfaces of section for the Reeb flow of α_+ . Finally, we can define

$$A = \sum_{i=1}^{n} \int_{\gamma_i} \alpha_+.$$

Let us fix any curve

$$C_{+} \in \mathcal{M}_{\tilde{J}_{+},0,\delta^{+}}(\gamma_{1},\ldots,\gamma_{n};\emptyset).$$

$$(40)$$

Let Σ be the Seifert surface for *L* obtained as the closure of the projection of C_+ onto *M*. Then Σ induces the same element in $H_2(M, L)$ as any page of Θ . We shall denote by τ_{Σ} a collection of symplectic (with respect to $d\alpha_+$ or equivalently $d\alpha$) trivializations of the bundles ξ_{γ_i} aligned with the normal of Σ . These trivializations are homotopic to trivializations aligned with the normal of any page of Θ .

Fix any $d\alpha$ -compatible complex structure $J : \xi \to \xi$. Recall that J is also compatible with $d(g\alpha)$ for every $g \in C^{\infty}(M, (0, +\infty))$. Consider the asymptotic operators at the γ_i induced by the data (α, J) . Choose numbers $\delta_i^- < 0$ in the spectral gap between eigenvalues of winding number 0 and 1 with respect to τ_{Σ} , and set $\delta^- = (\delta_1^-, \ldots, \delta_n^-; \emptyset)$. It follows from (a) in Proposition 3.16 that this choice can be made. From now on we denote by \tilde{J}_k the \mathbb{R} -invariant almost complex structure defined as in (8) using J and the contact form $f_k \alpha$.

Remark 3.18. Note that the numbers $\delta_i^- < 0$ lie in the spectral gap of the asymptotic operator along γ_i defined by the data $(f_k \alpha, J)$ between eigenvalues of winding number 0 and 1 with respect to τ_{Σ} , provided k is large enough.

Lemma B.1 shows that if we push a proper collection of components of L in the direction of Σ then we obtain a link which is non-zero in $H_1(M \setminus L)$. Summarizing, assumption (a) together with the results from [47] explained above allow us to check that hypotheses (H1), (H2), (H3) and (H5) from Section 3.2 are satisfied for α_+ and $f_k \alpha$ in place α_- , where Σ and L are as just described.

We claim that (H4) is also satisfied if k is large enough. We only need to find k_0 such that if $k \ge k_0$ then every periodic orbit $\gamma = (x, T)$ in $M \setminus L$ of the Reeb flow of $f_k \alpha$ satisfying $T \le \sum_{i=1}^n \int_{\gamma_i} \alpha_+$ must also satisfy $\operatorname{int}(\gamma, \Sigma) \ne 0$. Arguing indirectly we may assume that, up to the choice of a subsequence, for every k there exists a periodic Reeb orbit $\tilde{\gamma}_k = (\tilde{x}_k, \tilde{T}_k)$ of $f_k \alpha$ contained in $M \setminus L$ and satisfying $\tilde{T}_k \le \sum_{i=1}^n \int_{\gamma_i} \alpha_+$ and $\operatorname{int}(\tilde{\gamma}_k, \Sigma) = 0$. By these period bounds we can assume, up to taking a further subsequence, that $\tilde{\gamma}_k C^{\infty}$ -converges to a periodic orbit $\tilde{\gamma} = (\tilde{x}, \tilde{T})$ of the Reeb flow of α . The inequality

 $\tilde{T} \leq \sum_{i=1}^{n} \int_{\gamma_i} \alpha_+$ holds. It must be true that $\tilde{\gamma} \subset M \setminus L$. To see why we argue indirectly and assume that $\tilde{\gamma}$ is a multiple cover of some γ_i , say of covering multiplicity N. This forces the existence of a periodic solution of the linearization of the Reeb flow of α along the N-iterated orbit γ_i^N with zero winding number computed with a frame aligned to the normal of Σ . In particular, $N\rho^{\Theta}(\gamma_i) = \rho^{\Theta}(\gamma_i^N) = 0$, so $\rho^{\Theta}(\gamma_i) = 0$, which is absurd. Now that we have proved that $\tilde{\gamma} \subset M \setminus L$, we must have $\operatorname{int}(\tilde{\gamma}, \Sigma) \neq 0$ by assumption. Since $\tilde{\gamma}_k \to \tilde{\gamma}$ we find $\operatorname{int}(\tilde{\gamma}_k, \Sigma) \neq 0$ for large enough k. This contradiction finishes the proof that (H4) holds for α_+ and $f_k \alpha$ in place of α_- when k is large enough.

The numbers $\delta_i^- < 0$ lie in the spectral gap of the asymptotic operator along γ_i defined by the data $(f_k \alpha, J)$ between eigenvalues of winding number 0 and 1 with respect to τ_{Σ} , provided k is large enough. This is a simple consequence of $f_k \alpha \to \alpha$ in C^∞ . From Proposition 3.10 we get k_0 such that if $k \ge k_0$ then there is a curve $C_- \in \mathcal{M}_{\tilde{J}_k,0,\delta^-}(\gamma_1,\ldots,\gamma_n;\emptyset)$ whose projection to M induces the same element in $H_2(M, L)$ as Σ . Its Hofer energy is not larger than E. From now on we fix $k \ge k_0$ and such a curve C_- . Let \mathcal{Y} be the component of C_- in $\mathcal{M}_{\tilde{J}_k,0,\delta^-}(\gamma_1,\ldots,\gamma_n;\emptyset)$. Proposition 3.10 also tells us that \mathcal{Y}/\mathbb{R} is compact.

Every curve in \mathcal{Y} projects to M as a Seifert surface for L transverse to X_{α} in its interior. These Seifert surfaces induce the same element in $H_2(M, L)$ as Σ . All this follows from Proposition 3.4 and Lemma 3.1. Lemma 3.7 and Proposition 3.5 together tell us that the curves in \mathcal{Y} can be used to construct pieces of foliations of $M \setminus L$ transverse to the Reeb flow. Using the compactness of \mathcal{Y}/\mathbb{R} in combination with Proposition 3.5, these local foliations match to yield an open book decomposition of M with binding L whose pages are projections of curves in \mathcal{Y} . Moreover, \mathcal{Y}/\mathbb{R} is diffeomorphic to a circle.

To see why pages are global surfaces of section, consider a trajectory of the Reeb flow of $f_k \alpha$ on $M \setminus L$, where k is large enough. If its ω -limit does not intersect L then it will hit every page in the future infinitely often, by transversality of X_α to the pages. If its ω -limit intersects L then this trajectory spends arbitrarily long periods of time arbitrarily near L, in the far future, and consequently can be well-controlled by the linearized Reeb flow along L. The condition $\mu_{CZ}^{\Theta}(\gamma_i) \ge 1$ for all i is equivalent to $\rho^{\Theta}(\gamma_i) > 0$ for all i, and consequently forces the linearized flow near L to rotate very much with respect to τ_{Σ} in long periods of time. Hence the same will happen to nearby trajectories, forcing them to hit all pages. To analyze past times there is a similar reasoning, where one replaces ω -limit sets by ω^* -limit sets. This concludes the proof of Proposition 3.16.

3.4. Passing to the degenerate case

3.4.1. Geometric set-up. Let us fix a planar supporting open book decomposition $\Theta = (\Pi, L)$ on (M, ξ) . Order the components $\gamma_1, \ldots, \gamma_n$ of its binding L arbitrarily, and assume that

$$n \ge 2. \tag{41}$$

Write $b \in H_2(M, L)$ for the class of a page. As explained in the introduction, the pages get naturally oriented by Θ , and L gets oriented as the boundary of a page. Let α be a contact form such that $\xi = \ker \alpha$ and X_{α} is positively tangent to each γ_l . Note that α may

be very degenerate. We see the γ_l as prime closed Reeb orbits and denote their periods by T_l . Assume that

- (a) $\mu_{CZ}^{\Theta}(\gamma_l) \ge 1$ for all l,
- (b) all periodic orbits of the Reeb flow of α contained in $M \setminus L$ have non-zero algebraic intersection number with b.

Conley–Zehnder indices in (a) are computed with respect to trivializations of ξ aligned with the normal of a page. Let J be a $d\alpha$ -compatible complex structure on ξ . Consider a sequence f_k satisfying

$$f_k \in \mathcal{F}_L, \quad f_k \to 1 \text{ in } C^\infty, \quad f_k|_L \equiv 1 \ \forall k.$$
 (42)

Denote $\alpha_k = f_k \alpha$ and consider compatible complex structures $J_k : \xi \to \xi$ satisfying $J_k \to J$ in C^{∞} . Let $\tilde{J}_k \in \mathcal{J}(f_k \alpha)$ and $\tilde{J} \in \mathcal{J}(\alpha)$ be induced by (α_k, J_k) and (α, J) , respectively. Then $\tilde{J}_k \to \tilde{J}$ in C^{∞} (weak equals strong). Note that the tangent space of $\mathbb{R} \times L$ is invariant under \tilde{J} and \tilde{J}_k . The γ_l are periodic orbits of the Reeb flow of $f_k \alpha$ with prime period T_l , for all k. Choose $\delta_l < 0$ in the spectral gap of the asymptotic operator of γ_l induced by (α, J) between eigenvalues of winding number 0 and 1 with respect to frames aligned to the normal of a page. This can be done in view of (a). If k is large enough then the δ_l lie in the corresponding spectral gaps of asymptotic operators of γ_l induced by (α_k, J_k) . Denote $\delta = (\delta_1, \ldots, \delta_n; \emptyset)$.

3.4.2. Computing wind_{∞}. For each *l* choose a symplectic trivialization of ξ_{γ_l} aligned with the normal of some page of Θ . The collection of homotopy classes of these trivializations will be denoted by τ_{Σ} .

Lemma 3.19. If $\tilde{u} = (a, u)$ represents a curve in $\mathcal{M}_{\tilde{J},0,\delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$ inducing the class b, then wind_{π}(\tilde{u}) = 0 and u is an immersion transverse to X_{α} . Moreover, if the positive puncture where \tilde{u} is asymptotic to γ_l is denoted by z_l , then wind_{∞}($\tilde{u}, z_l, \tau_{\Sigma}$) = 0 for all l.

Proof. We may assume that \tilde{u} is defined on $\mathbb{C} \setminus \{z_2, \ldots, z_n\}$ with standard complex structure *i*, and that \tilde{u} is asymptotic to γ_1 at $z_1 = \infty$ and to γ_l at $z_l, 2 \le l \le n$. We use here the fact that all punctures are non-degenerate, by our definition of moduli spaces given in Section 2.2.6.

In view of Theorem 2.10 the numbers wind_{∞}($\tilde{u}, z_l, \tau_{\Sigma}$) are well-defined. Since each δ_i lies in the spectral gap between eigenvalues of winding number 0 and 1 with respect to τ , we get

wind_{$$\infty$$}($\tilde{u}, z_l, \tau_{\Sigma}$) $\leq 0 \quad \forall l.$ (43)

Now let τ' denote a collection of homotopy classes of symplectic trivializations of the ξ_{γ_l} which extend to a trivialization of $u^*\xi$. Since b is the class of a page of the supporting planar open book Θ , the self-linking number sl(L, page) of L with respect to a page of Θ

is equal to n - 2. Using this crucial information we can compute

$$0 \leq \operatorname{wind}_{\pi}(\widetilde{u}) = \operatorname{wind}_{\infty}(\widetilde{u}) - 2 + n = \left(\sum_{l=1}^{n} \operatorname{wind}_{\infty}(\widetilde{u}, z_{l}, \tau')\right) - 2 + n$$
$$= \left(\sum_{l=1}^{n} \operatorname{wind}_{\infty}(\widetilde{u}, z_{l}, \tau_{\Sigma})\right) - \operatorname{sl}(L, \operatorname{page}) - 2 + n$$
$$= \sum_{l=1}^{n} \operatorname{wind}_{\infty}(\widetilde{u}, z_{l}, \tau_{\Sigma}) \leq 0.$$
(44)

Hence wind_{π}(\tilde{u}) = 0. This forces *u* to be an immersion transverse to X_{α} , in view of the definition of wind_{π}, and also proves that wind_{∞}($\tilde{u}, z_l, \tau_{\Sigma}$) = 0 for all *l*.

3.4.3. A compactness statement. Standard SFT-compactness is not valid for degenerate contact forms unless the degeneracy is very mild (e.g., Morse–Bott). Nevertheless, we can get the compactness statement necessary to prove our results. It reads as follows.

Proposition 3.20. Consider a sequence $C_k \in \mathcal{M}_{\tilde{J}_k,0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ satisfying

(H) C_k is embedded, represents the class b, does not intersect $\mathbb{R} \times L$, and any loop in C_k projects to $M \setminus L$ as a loop with algebraic intersection number with b equal to zero.

There exist representatives

$$C_k = [\widetilde{u}_k = (a_k, u_k), \mathbb{C} \cup \{\infty\}, i, \{z_{k,1} = \infty, z_{k,2}, \dots, z_{k,n}\}, \emptyset]$$

distinct points $z_{\infty,2}, \ldots, z_{\infty,n} \in \mathbb{C}$, sequences $k_j \to +\infty$, $c_j \in \mathbb{R}$, and a finite-energy \tilde{J} -holomorphic embedding

$$\widetilde{u} = (a, u) : \mathbb{C} \setminus \{z_{\infty, 2}, \dots, z_{\infty, n}\} \to \mathbb{R} \times M$$

satisfying

$$z_{k_{j},l} \to z_{\infty,l} \quad as \ j \to +\infty, \ \forall l \in \{2, \dots, n\},$$

$$C = [\tilde{u}, \mathbb{C} \cup \{\infty\}, i, \{z_{\infty,1} = \infty, z_{\infty,2}, \dots, z_{\infty,n}\}, \emptyset] \in \mathcal{M}_{\tilde{J},0,\delta}(\gamma_{1}, \dots, \gamma_{n}; \emptyset),$$

$$(a_{k_{j}} + c_{j}, u_{k_{j}}) \to \tilde{u} \quad in \ C_{\text{loc}}^{\infty}(\mathbb{C} \setminus \{z_{\infty,2}, \dots, z_{\infty,n}\}) \ as \ k \to +\infty,$$

$$\tilde{u}(\mathbb{C} \setminus \{z_{\infty,2}, \dots, z_{\infty,n}\}) \cap \mathbb{R} \times L = \emptyset.$$

Remark 3.21. Using positivity of intersections one sees that the limiting curve $C \in \mathcal{M}_{\tilde{I},0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ obtained satisfies condition (H).

Now we prove Proposition 3.20. Parametrize the C_k by finite-energy \tilde{J}_k -holomorphic maps

$$\widetilde{u}_k = (a_k, u_k) : \mathbb{C} \setminus \Gamma_k \to \mathbb{R} \times M \tag{45}$$

where domains are equipped with the standard complex structure. Each

$$\Gamma_k = \{z_{k,2}, \ldots, z_{k,n}\} \subset \mathbb{C}$$

is a set of n-1 positive non-degenerate punctures, \tilde{u}_k is asymptotic to γ_i at $z_{k,i}$ for all $i \in \{2, ..., n\}$, and $z_{k,1} := \infty$ is a positive non-degenerate puncture where \tilde{u}_k is asymptotic to γ_1 .

For each *i* choose a small compact tubular neighborhood N_i of γ_i such that the N_i are pairwise disjoint, and no N_i contains periodic orbits of the Reeb flow of α that are contractible in N_i .

Lemma 3.22. After holomorphic reparametrizations we can achieve

$$u_k^{-1}(M \setminus N_1) \subset \mathbb{D}, \tag{46}$$

$$u_k^{-1}(\partial N_1) \cap \mathbb{D} \supset \{1, w_k\} \quad \text{where } \Re(w_k) \le 0, \tag{47}$$

$$\Gamma_k \subset \mathbb{D},$$
 (48)

$$a_k(2) = 0.$$
 (49)

Proof. For fixed k the closure F in \mathbb{C} of the set $u_k^{-1}(M \setminus N_1)$ is compact with nonempty interior. This is so since \tilde{u}_k is asymptotic to γ_1 at ∞ and is asymptotic to orbits in $N_2 \cup \cdots \cup N_n \subset M \setminus N_1$ at punctures in Γ_k . In particular, Γ_k is contained in the interior of F. Let r be the infimum of the radii of closed disks containing F. Then r > 0 and there exists a closed disk D of radius r containing F. Obviously $u_k^{-1}(\partial N_1) \supset \partial D \cap F \neq \emptyset$.

Let ℓ be a line such that $\ell \cap D$ is a diameter of D. We claim that $\partial D \cap F$ is contained in no connected component of $\mathbb{C} \setminus \ell$. Indeed, assume that some component of $\mathbb{C} \setminus \ell$ contains $\partial D \cap F$. If $u \neq 0$ is perpendicular to ℓ and points towards this connected component then we can find $\epsilon > 0$ small enough such that $D + \epsilon u$ contains F in its interior. Hence some disk of radius smaller than that of $D + \epsilon u$ would contain F, in contradiction with the definition of r.

Let $w_0 \in \partial D \cap F$ and let ℓ be the line through the center of D that is perpendicular to segment joining w_0 to the center of D. Let H_0 , H_1 be the closed half-spaces determined by ℓ , where H_0 contains w_0 . Above we proved that there exists $w_1 \in \partial D \cap F \cap H_1$. Choose $A \neq 0$, B such that $\psi(z) = Az + B$ satisfies: $\psi(0)$ is the center of D, $\psi(\mathbb{D}) = D$ and $\psi(1) = w_0$. Then ψ maps the imaginary axis onto ℓ , and $\Re(\psi^{-1}(w_1)) \leq 0$. Redefining \tilde{u}_k to be $\tilde{u}_k \circ \psi$ and translating it by -a(2) in the \mathbb{R} -direction of $\mathbb{R} \times M$ we achieve all the desired properties.

Let Σ be any fixed page of Θ , so that Σ is a Seifert surface for *L* representing *b*. Along each γ_l we choose a homotopy class of $d\alpha$ -symplectic trivialization of ξ_{γ_l} aligned with the normal of Σ . The collection of these homotopy classes is denoted by τ_{Σ} . Note that trivializations representing τ_{Σ} can be rescaled to give $d(f_k \alpha)$ -symplectic trivializations. We continue to write τ_{Σ} to denote their homotopy classes.

Before proceeding we recall the description of $H_1(M \setminus L)$ from Appendix B. Lemma B.1 provides an isomorphism

$$H_1(M \setminus L) = \frac{H_1(\text{page})}{\text{im}(\text{id} - h_*)} \oplus \mathbb{Z}e$$

where *h* is the monodromy of Θ and *e* is a 1-cycle with algebraic intersection number +1 with *b*. The first factor is seen geometrically in $M \setminus L$ as follows. Consider the loop γ'_i obtained by pushing γ_i into $M \setminus L$ in the direction of a page. We see γ'_i as a 1-cycle. Since Θ is planar, the first factor is the free abelian group generated by $\gamma'_1, \ldots, \gamma'_n$ modulo the single relation $\gamma'_1 + \cdots + \gamma'_n = 0$. This description of $H_1(M \setminus L)$ will be used many times in our analysis.

Lemma 3.23. Let c be a loop in $M \setminus L$ that is C^0 -close to an m-fold cover of γ_l and has algebraic intersection number with b equal to zero. Then c is homologous to $m\gamma'_l$ in $M \setminus L$.

Proof. Consider a small tubular neighborhood N of γ_l equipped with coordinates $(\theta, w) \in \mathbb{R}/\mathbb{Z} \times \mathbb{D}$ with respect to which $\gamma_l = (x_l, T_l)$ is represented as $x_l(T_l\theta) = (\theta, 0)$, and such that γ'_l is homologous to $\theta \mapsto (\theta, 1)$ in $M \setminus L$. Since γ'_l has zero algebraic intersection number with b we can conclude that any loop $t \mapsto (\theta(t), w(t))$ in $N \setminus L$ has algebraic intersection number with b equal to wind(w(t)). Let c be a loop inside N. Represent c as $\mathbb{R}/\mathbb{Z} \ni t \mapsto (\theta(t), w(t))$. If c is C^0 -close enough to the m-cover of γ_l then $t \mapsto \theta(t)$ has degree equal to m. Moreover, wind(w(t)) = 0 by the assumption on the intersection number with b. Hence c is homotopic in $N \setminus \gamma_l$ to $\theta \mapsto (m\theta, 1)$. The latter is homologous to $m\gamma'_l$ in $M \setminus L$.

Lemma 3.24. For every k one can find r > 0 small enough such that the loop $t \mapsto u_k(r^{-1}e^{i2\pi t})$ is homologous to γ'_1 in $M \setminus L$, and for every l = 2, ..., n the loop $t \mapsto u_k(z_{k,l} + re^{-i2\pi t})$ is homologous to γ'_1 in $M \setminus L$.

Proof. From the fact that $z_{k,l}$ is a non-degenerate positive puncture where \tilde{u}_k is asymptotic to γ_l it follows that for r > 0 small enough the loop $t \mapsto u_k(z_{k,l} + re^{-i2\pi t})$ is uniformly close to γ_l and, by hypothesis (H), it has algebraic intersection number with b equal to zero. Lemma 3.23 implies that $t \mapsto u_k(z_{k,l} + re^{-i2\pi t})$ is homologous to γ'_l in $M \setminus L$. The case l = 1 is handled analogously.

Up to selection of a subsequence we may assume that

$$\lim_{k \to \infty} z_{k,i} \quad \text{exists for every } i.$$
(50)

Let Γ be the set of such limits. Hence $\Gamma \subset \mathbb{D}$ by Lemma 3.22.

Choose some reference \mathbb{R} -invariant Riemannian metric on $\mathbb{R} \times M$. Domains in \mathbb{C} are equipped with the standard euclidean metric. With these choices we can consider norms of differentials $d\tilde{u}_k$.

Lemma 3.25. The sequence $d\tilde{u}_k$ is C^0_{loc} -bounded on $\mathbb{C} \setminus \Gamma$.

Proof. Consider the set

 $Z = \{ \zeta \in \mathbb{C} \setminus \Gamma \mid \exists k_l \to +\infty, \ \zeta_l \to \zeta \text{ satisfying } |d\widetilde{u}_{k_l}(\zeta_l)| \to +\infty \}.$

The goal of the lemma is to show that Z is empty. Assume that $Z \neq \emptyset$. We must have $Z \subset \mathbb{D}$. If not then we can use (46) and the analysis from [18] to conclude that a non-

constant finite-energy plane bubbles off inside N_1 . All asymptotic limits of this plane must be periodic orbits of the Reeb flow of α inside N_1 that are contractible in N_1 . This is in contradiction to the fact that N_1 contains no such periodic orbits.

The sequence $d\tilde{u}_k$ is C^0_{loc} -bounded in $\mathbb{C} \setminus (\Gamma \cup Z)$. Moreover, $2 \notin \Gamma \cup Z$ by (48) and the inclusion $Z \subset \mathbb{D}$ proved above. Thus we get C^1_{loc} -bounds for the sequence \tilde{u}_k on $\mathbb{C} \setminus (\Gamma \cup Z)$. By elliptic boot-strapping arguments, it is no loss of generality to assume, up to selection of a subsequence, that \tilde{u}_k is $C^\infty_{\text{loc}}(\mathbb{C} \setminus (\Gamma \cup Z))$ -convergent to a smooth \tilde{J} -holomorphic map

$$\widetilde{u} = (a, u) : \mathbb{C} \setminus (\Gamma \cup Z) \to \mathbb{R} \times M$$
(51)

with finite Hofer energy.

We can also assume that \tilde{u} is not constant. In fact, up to taking a subsequence, we can assume that a small conformal disk D around $\zeta \in Z$ satisfies $\int_D u_k^* d(f_k \alpha) \ge \sigma > 0$ for all k, where $\sigma > 0$ is any positive constant smaller than the least period of periodic orbits of contact forms in $\{\alpha, f_1\alpha, f_2\alpha, f_3\alpha, \ldots\}$ fixed *a priori*. This inequality is a consequence of the fact that a non-constant finite-energy \tilde{J} -holomorphic plane bubbles off from ζ in the limit, up to a subsequence. The Stokes theorem, and the fact that the loop $u_k|_{\partial D}$ C^{∞} -converges to the loop $u|_{\partial D}$, imply that $\int_{\partial D} u^*\alpha \ge \sigma$. Hence ζ is a non-removable puncture and \tilde{u} is not a constant map. In fact, ζ is a negative puncture.

Fix any $\zeta \in Z$ and let $\gamma_{\zeta} = (x_{\zeta}, T_{\zeta})$ be one of the (possibly many) asymptotic limits of \tilde{u} at ζ . We can find a sequence $r_l \to 0^+$ and $t_0 \in \mathbb{R}$ such that $u(\zeta + r_l e^{i2\pi t}) C^{\infty}$ converges to the loop $x_{\zeta}(T_{\zeta}t + t_0)$ as $l \to +\infty$. If $\gamma_{\zeta} \subset M \setminus L$ then $x_{\zeta}(T_{\zeta}t)$ has non-zero intersection number with the class b, by the standing assumption (b). The same must then be true for $u(\zeta + r_l e^{i2\pi t})$ if $l \gg 1$, hence also for $u_k(\zeta + r_l e^{i2\pi t})$ if $k \gg 1$. But no \tilde{u}_k intersects $\mathbb{R} \times L$; this is a consequence of hypothesis (H). Hence the loop $u_k(\zeta + r_l e^{i2\pi t})$ is contractible in $M \setminus L$ and its algebraic intersection number with b vanishes. We have used the fact that $\zeta + r_l e^{i2\pi t}$ is contractible in $\mathbb{C} \setminus \Gamma_k$. This contradiction proves that $\gamma_{\zeta} = \gamma_{j_*}^m = (x_{j_*}, mT_{j_*})$ for some $j_* \in \{1, \ldots, n\}$ and some $m \ge 1$. This argument shows independently that if k, l are large enough then the loop $u_k(\zeta + r_l e^{i2\pi t})$ has vanishing algebraic intersection number with b.

It follows from Lemma 3.23 that $t \mapsto u_k(\zeta + r_l e^{i2\pi t})$ is homologous to $m\gamma'_{j_*}$ in $M \setminus L$ when $k, l \gg 1$. Combining this with Lemma 3.24 and hypothesis (H) we obtain the identity

$$\gamma'_1 + \dots + \gamma'_n \equiv m\gamma'_{j_*}$$
 in $H_1(M \setminus L)$.

By our standing assumption (41) this identity contradicts Lemma B.1 since $m \ge 1$. We have shown that $Z = \emptyset$.

Lemma 3.25 and (49) together give C^1_{loc} bounds for \tilde{u}_k on $\mathbb{C} \setminus \Gamma$. By elliptic bootstrapping arguments it is no loss of generality, up to selection of a subsequence, to assume that \tilde{u}_k converges in $C^{\infty}_{\text{loc}}(\mathbb{C} \setminus \Gamma)$ to a smooth \tilde{J} -holomorphic map

$$\widetilde{u} = (a, u) : \mathbb{C} \setminus \Gamma \to \mathbb{R} \times M \tag{52}$$

with Hofer energy not larger than $\sum_{l} \int_{\gamma_l} \alpha$.

Lemma 3.26. The map \tilde{u} is not constant.

Proof. For every R > 1 and every k the loop $t \mapsto u_k(Re^{i2\pi t})$ lies inside N_1 and is homotopic in N_1 to γ_1 . This follows from (46). Since these loops converge in C^{∞} to the loop $t \mapsto u(Re^{i2\pi t})$ we conclude that the latter is a non-contractible loop in N_1 , hence non-constant.

Lemma 3.27. The following hold:

- $\#\Gamma = n 1$ and $\Gamma \cup \{\infty\}$ consists of positive punctures of \tilde{u} .
- Use (50) to write $\Gamma = \{z_{\infty,2}, \dots, z_{\infty,n}\}$ where $z_{\infty,i} = \lim_{k \to \infty} z_{k,i}$. Set $z_{\infty,1} = \infty$. Then \tilde{u} is weakly asymptotic to γ_i at $z_{\infty,i}$ for every $i = 1, \dots, n$.
- The image of \tilde{u} does not intersect $\mathbb{R} \times L$.

Proof. Let $z \in \Gamma$. By (50) and the definition of Γ , the set

$$I_z = \{l \in \{2, \dots, n\} \mid z_{k,l} \to z \text{ as } k \to +\infty\}$$

is non-empty.

We claim that z is not a removable puncture. In fact, assume that z is removable. Thus \tilde{u} smoothly extends at z. Consider first the case $u(z) \in L$. Choose a small open tubular neighborhood N with coordinates $(\theta, w) \in \mathbb{R}/\mathbb{Z} \times \mathbb{C}$ around the component $\gamma_i \subset L$ containing u(z), in such a way that $\gamma_i = \mathbb{R}/\mathbb{Z} \times 0$ and any loop $t \mapsto (\theta(t), w(t))$ in $N \setminus \gamma_i$ has algebraic intersection number with b equal to wind(w(t)). If ϵ is small enough and k is large enough then the loop $t \mapsto u_k(z + \epsilon e^{i2\pi t})$ is contained in N since it is C⁰close to $u(z) \in \gamma_i$. Thus it can be represented in coordinates as $t \mapsto (\theta_k(t), w_k(t))$, where $t \mapsto \theta_k(t)$ has degree zero. By hypothesis (H) we know that wind $(w_k(t)) = 0$. Consequently, $t \mapsto (\theta_k(t), w_k(t))$ is homotopic in $N \setminus \gamma_i$ to a constant loop. Putting this together with Lemma 3.24 and hypothesis (H) we conclude that $\sum_{l \in I_z} \gamma'_l \equiv 0$ in $H_1(M \setminus L)$. This is impossible because I_z is a proper subset of $\{1, \ldots, n\}$. We are left with the case $u(z) \notin L$, but this time we find that for ϵ small enough and k large enough the loop $t \mapsto u_k(z + \epsilon e^{i2\pi t})$ is contained in a contractible open subset of $M \setminus L$. The previous argument again shows that $\sum_{l \in I_z} \gamma'_l \equiv 0$ in $H_1(M \setminus L)$, which is absurd. In all cases we get a contradiction. Thus z must be non-removable. An analogous argument, using (48), shows that ∞ is non-removable.

We can now prove that every asymptotic limit of \tilde{u} at a given $z \in \Gamma$ is contained in *L*. In fact, it follows from our standing assumption (b) that if some asymptotic limit of \tilde{u} at some $z \in \Gamma$ is contained in $M \setminus L$ then we can find $\epsilon > 0$ small such that *u* maps $z + \epsilon S^1$ to a loop in $M \setminus L$ with non-zero algebraic intersection number with *b*. If *k* is large enough then the same is true for the loop $u_k(z + \epsilon S^1)$, in contradiction to hypothesis (H). Analogously one shows that every asymptotic limit at ∞ is contained in *L*.

Let $e = \pm 1$ be the sign of the non-removable puncture $z \in \Gamma$. By the reasoning above, any choice of asymptotic limit of \tilde{u} at z must be equal to $\gamma_{l_*}^N = (x_{l_*}, NT_{l_*})$ for some $l_* \in \{1, ..., n\}$ and some $N \ge 1$. Let us fix such a choice. We find $\epsilon_m \to 0^+$ and t_0 such that $t \mapsto u(z + \epsilon_m e^{i2\pi t}) C^{\infty}$ -converges to $t \mapsto x_{l_*}(-eNT_{l_*}t + t_0)$. By hypothesis (H) we find *m* large and k_m such that if $k \ge k_m$ then $t \mapsto u_k(z + \epsilon_m e^{i2\pi t})$ is a loop in $M \setminus L$ which is C^{∞} -close to $t \mapsto x_{l_*}(-eNT_{l_*}t + t_0)$ and has algebraic intersection number with *b* equal to zero. Hence $t \mapsto u_k(z + \epsilon_m e^{i2\pi t})$ is homologous to $-eN\gamma'_{l_*}$ in $M \setminus L$ whenever $k \ge k_m$; we have used Lemma 3.23.

We can now choose $k \gg k_m$ such that all $\{z_{k,l} \mid l \in I_z\}$ lie in the interior of the closed ϵ_m -disk $D_{\epsilon_m}(z)$ centered at z. Take $r_k > 0$ small enough such that the closed r_k -disks $D_{r_k}(z_{k,l})$ centered at the $\{z_{k,l} \mid l \in I_z\}$ lie in interior of $D_{\epsilon_m}(z)$, and such that u_k maps $-\partial D_{r_k}(z_{k,l})$ to a loop homologous to γ'_l . We have essentially used Lemma 3.24 here. Now consider the smooth domain S obtained by removing from $D_{\epsilon_m}(z)$ the interiors of the disks $D_{r_k}(z_{k,l})$, $l \in I_z$. Since $u_k(S) \subset M \setminus L$ we get a homology relation

$$-eN\gamma'_{l_*} + \sum_{l \in I_z} \gamma'_l \equiv 0 \quad \text{in } H_1(M \setminus L).$$
(53)

If e = -1 then (53) implies that $I_z = \{2, ..., n\}$, $l_* = 1$, N = 1 and $\Gamma = \{z\}$. It follows that \tilde{u} is a trivial cylinder over γ_1 , its positive puncture is ∞ and its negative puncture is z. It is now of course crucial to observe that $\{u_k(1), u_k(w_k)\} \subset \partial N_1$ where $w_k \in \partial \mathbb{D}$ has negative real part. Up to choice of subsequence we may assume $w_k \to w_* \in \partial \mathbb{D}$ and $\Re(w_*) \leq 0$. Since $w_* \neq 1$ and $\Gamma = \{z\}$, there is at least one point in $\partial \mathbb{D}$ mapped by u to ∂N_1 , contrary to \tilde{u} being a trivial cylinder over γ_1 . We have thus shown e = +1. Together with (53) this implies that $l_* \in \{2, ..., n\}$, $I_z = \{l_*\}$ and N = 1.

We have thus concluded the proof that $\#\Gamma = n - 1$, that we can order the points of $\Gamma = \{z_{\infty,2}, \ldots, z_{\infty,n}\}$ in such a way that $z_{k,l} \to z_{\infty,l}$ as $k \to +\infty$, and that \tilde{u} is weakly asymptotic to γ_l at $z_{\infty,l}$ for every $l \in \{2, \ldots, n\}$.

We prove now that ∞ is a positive puncture where \tilde{u} is weakly asymptotic to γ_1 . The argument is entirely analogous. Any asymptotic limit of \tilde{u} at ∞ is of the form $\gamma_{l_*}^N$ for some $l_* = 1, ..., n$ and some $N \ge 1$. By hypothesis (H) we can find R and k large such that the loop $t \mapsto u_k(Re^{i2\pi t})$ represents the class $eN\gamma'_{l_*}$ in $H_1(M \setminus L)$, where e is the sign of the puncture ∞ . Again using (H) and what was proved above we get the identity

$$eN\gamma'_{l_{*}} + \gamma'_{2} + \dots + \gamma'_{n} \equiv 0$$
 in $H_{1}(M \setminus L)$

This forces $l_* = 1$, e = +1 and N = 1.

Since $\Gamma \cup \{\infty\}$ consists precisely of *n* positive punctures $\infty, z_{\infty,2}, \ldots, z_{\infty,n}$ with geometrically distinct asymptotic limits, the image of \tilde{u} cannot be contained in any component of the embedded \tilde{J} -holomorphic surface $\mathbb{R} \times L$. Carleman's similarity principle implies that $E = \{w \in \mathbb{C} \setminus \Gamma \mid \tilde{u}(w) \in \mathbb{R} \times L\}$ is finite. Positivity of intersections guarantees that the (local) algebraic intersection number between \tilde{u} and $\mathbb{R} \times L$ at any point of E is positive. If E is non-empty we will find intersections of the image of \tilde{u}_k with $\mathbb{R} \times L$ provided k is large enough. This contradicts hypothesis (H).

Lemma 3.28. The curve $[\tilde{u}, \mathbb{C} \cup \{\infty\}, i, \Gamma, \emptyset]$ belongs to $\mathcal{M}_{\tilde{J}, 0, \delta}(\gamma_1, \dots, \gamma_n; \emptyset)$.

Most of the remainder of the proof of Proposition 3.20 consists in establishing Lemma 3.28. The main difficulty is to prove that the punctures are non-degenerate in the sense of Definition 2.9. We record an immediate consequence.

Lemma 3.29. The map \tilde{u} is an embedding.

Proof of Lemma 3.29 *assuming Lemma* 3.28. Lemma 3.19 implies that \tilde{u} is an immersion. Positivity and stability of isolated intersections of pseudo-holomorphic immersions shows that a self-intersection point of \tilde{u} would force self-intersection points of the \tilde{u}_k for k large enough. This contradicts hypothesis (H).

Lemmas 3.27–3.29 together complete the proof of Proposition 3.20. From now on, we are concerned with the proof of Lemma 3.28.

Fix $m \in \{1, ..., n\}$ and choose positive holomorphic polar coordinates $(s, t) \in [0, +\infty) \times \mathbb{R}/\mathbb{Z}$ centered at $z_{\infty,m}$. Choose a sequence ψ_k of Möbius transformations satisfying

$$\psi_k(\infty) = \infty, \quad \psi_k(z_{\infty,m}) = z_{k,m}, \quad \psi_k \to \text{id} \quad \text{in } C_{\text{loc}}^\infty.$$

Such a sequence exists since $z_{k,m} \to z_{\infty,m}$ as $k \to \infty$. Define

$$\widetilde{u}_k' = \widetilde{u}_k \circ \psi_k = (a_k', u_k'), \tag{54}$$

which is a finite-energy \tilde{J}_k -holomorphic map with positive punctures at

$$z'_{k,1} := \infty, \quad z'_{k,2} := \psi_k^{-1}(z_{k,2}), \dots, \ z'_{k,n} := \psi_k^{-1}(z_{k,n}).$$

Note that $z'_{k,m} = z_{\infty,m}$ for every k and, by Lemma 3.27, \tilde{u}'_k is weakly asymptotic to γ_l at $z'_{k,l}$ for every l. We write

$$\widetilde{u}'_k(s,t) = (a'_k(s,t), u'_k(s,t)), \quad \widetilde{u}(s,t) = (a(s,t), u(s,t)),$$

where (s, t) are the holomorphic polar coordinates at $z'_{k,m} = z_{\infty,m}$ fixed above.

Lemma 3.30. For all sequences $s_k \to +\infty$, $t_k \in \mathbb{R}/\mathbb{Z}$ there exists a subsequence of

$$(s,t) \mapsto (a'_k(s+s_k,t+t_k) - a'_k(s_k,t_k), u'_k(s+s_k,t+t_k))$$

that converges in C_{loc}^{∞} to a trivial cylinder over γ_m .

Proof. Denote $\tilde{v}_k(s,t) = (a'_k(s+s_k,t+t_k)) - a'_k(s_k,t_k), u'_k(s+s_k,t+t_k))$, which is defined on $[-s_k,+\infty) \times \mathbb{R}/\mathbb{Z}$. Write $\tilde{v}_k = (d_k,v_k)$ for the components of \tilde{v}_k . We claim that

$$\lim_{k \to \infty} \int_{[\hat{s}, +\infty) \times \mathbb{R}/\mathbb{Z}} v_k^* d\alpha_k = 0$$
(55)

and

$$\lim_{k \to \infty} \int_{\{\hat{s}\} \times \mathbb{R}/\mathbb{Z}} v_k^* \alpha_k = T_m$$
(56)

for every $\hat{s} \in \mathbb{R}$. In fact, fix $\epsilon > 0$. Recall that \tilde{u} is weakly asymptotic to γ_m at $z_{\infty,m}$ (Lemma 3.27). Hence, there exists $s_{\epsilon} > 0$ such that

$$\int_{\{s_{\epsilon}\}\times\mathbb{R}/\mathbb{Z}} (u')^* \alpha \in [T_m - \epsilon/2, T_m].$$

Here the upper bound T_m follows from the Stokes theorem since $(u')^* d\alpha_k$ is a nonnegative multiple of $ds \wedge dt$. Now use $u'_k \to u$ in C_{loc}^{∞} to find $k_{\epsilon} \ge 1$ satisfying

$$k \ge k_{\epsilon} \implies \int_{\{s_{\epsilon}\} \times \mathbb{R}/\mathbb{Z}} (u'_{k})^{*} \alpha_{k} \in [T_{m} - \epsilon, T_{m}].$$
(57)

The upper bound T_m is proven as before. Putting together the Stokes theorem, (57) and the fact that \tilde{u}'_k is asymptotic to γ_m at $z'_{k,m} = z_{\infty,m}$ we get

$$k \ge k_{\epsilon} \implies \int_{[s_{\epsilon}, +\infty) \times \mathbb{R}/\mathbb{Z}} (u'_k)^* d\alpha_k \le \epsilon$$

Since

$$\int_{[\hat{s},+\infty)\times\mathbb{R}/\mathbb{Z}} v_k^* d\alpha_k = \int_{[\hat{s}+s_k,+\infty)\times\mathbb{R}/\mathbb{Z}} (u_k')^* d\alpha_k$$

we get

$$\limsup_{k\to\infty}\int_{[\hat{s},+\infty)\times\mathbb{R}/\mathbb{Z}}v_k^*d\alpha_k\leq\epsilon$$

because $\hat{s} + s_k \ge s_{\epsilon}$ when k is large enough. This proves (55) since ϵ can be taken arbitrarily small. Again using (57) together with the Stokes theorem we can estimate, for $k \ge k_{\epsilon}$ and $\hat{s} + s_k \ge s_{\epsilon}$,

$$\begin{split} \int_{\{\hat{s}\}\times\mathbb{R}/\mathbb{Z}} v_k^* \alpha_k &= \int_{\{\hat{s}+s_k\}\times\mathbb{R}/\mathbb{Z}} (u_k')^* \alpha_k \\ &= \int_{\{s_\epsilon\}\times\mathbb{R}/\mathbb{Z}} (u_k')^* \alpha_k + \int_{[s_\epsilon,\hat{s}+s_k]\times\mathbb{R}/\mathbb{Z}} (u_k')^* d\alpha_k \\ &\geq \int_{\{s_\epsilon\}\times\mathbb{R}/\mathbb{Z}} (u_k')^* \alpha_k \geq T_m - \epsilon \end{split}$$

and

$$\int_{\{\hat{s}\}\times\mathbb{R}/\mathbb{Z}} v_k^* \alpha_k = \int_{\{\hat{s}+s_k\}\times\mathbb{R}/\mathbb{Z}} (u_k')^* \alpha_k = T_m - \int_{[\hat{s}+s_k,+\infty)\times\mathbb{R}/\mathbb{Z}} (u_k')^* d\alpha_k \le T_m.$$

Again the non-negativity of $(u'_k)^* d\alpha_k$ with respect to $ds \wedge dt$ was used. Now (56) follows since ϵ can be taken arbitrarily small.

The sequence $d\tilde{v}_k$ is C_{loc}^0 -bounded, for if not then we would find a bounded bubblingoff sequence of points, hence a compact set $F \subset \mathbb{R} \times \mathbb{R}/\mathbb{Z}$ satisfying $\liminf_k \int_F v_k^* d\alpha_k$ > 0, contradicting (55). Since $d_k(0, 0) = 0$ we obtain C_{loc}^1 -bounds for \tilde{v}_k . Elliptic estimates provide C_{loc}^∞ -bounds. Up to a further subsequence we get a smooth finite-energy \widetilde{J} -holomorphic map $\widetilde{v} : \mathbb{R} \times \mathbb{R}/\mathbb{Z} \to \mathbb{R} \times M$ as a C_{loc}^{∞} -limit of the \widetilde{v}_k . Write $\widetilde{v} = (d, v)$ for the components of \widetilde{v} . The map \widetilde{v} is not constant since (56) implies that

$$\int_{\{\hat{s}\}\times\mathbb{R}/\mathbb{Z}}v^*\alpha=T_m\quad\forall\hat{s}\in\mathbb{R}.$$

Moreover,

$$\int_{\mathbb{R}\times\mathbb{R}/\mathbb{Z}}v^*d\alpha=0$$

in view of (55). It follows that \tilde{v} is a cylinder over some periodic orbit $\hat{\gamma} = (\hat{x}, \hat{T} = T_m)$ with the same period as γ_m . In particular, there is t_0 such that $\tilde{v}(s,t) = (T_m s, \hat{x}(T_m t + t_0))$.

Suppose, for contradiction, that γ_m and $\hat{\gamma}$ are geometrically distinct. By the standing assumption (b) at the beginning of this subsection, we know that the loop $t \mapsto v(0, t) = \hat{x}(T_m t + t_0)$ has algebraic intersection number with *b* different from zero if it is contained in $M \setminus L$. Since the sequence of loops $u'_k(s_k, \cdot)$ converges in C^{∞} to the loop $v(0, \cdot)$, for $k \gg 1$ the loop $u'_k(s_k, \cdot)$ has non-zero algebraic intersection number with *b*. This contradicts hypothesis (H). We have established that \tilde{v} is a trivial cylinder over some cover of some component of *L*. Next we claim that this component must be γ_m . If not we find $s'_k \geq s_k$ and $t'_k \in \mathbb{R}/\mathbb{Z}$ such that $u'_k(s'_k, t'_k) \in \partial N_m$. Here we use the fact that each \tilde{u}'_k is asymptotic to γ_m at $z'_{k,m} = z_{\infty,m}$. Then, by the arguments showed above, a subsequence of the sequence of maps $\tilde{v}'_k(s, t) = (a'_k(s + s'_k, t + t'_k) - a(s'_k, t'_k), u'_k(s + s'_k, t + t'_k))$ converges to a trivial cylinder over some periodic orbit contained in *L* which also touches ∂N_m because $\tilde{v}'_k(0, 0) \in 0 \times \partial N_m$. This contradiction shows that $\hat{\gamma}$ is a cover of γ_m . Thus $\hat{\gamma} = \gamma_m$ since they have the same period.

Lemma 3.31. There exist $s_0 \ge 0$ and $k_0 \ge 1$ such that $u'_k(s, t) \in N_m$ for every $k \ge k_0$ and every $s \ge s_0$.

Proof. If the statement is not true then, up to selection of a subsequence, we may assume that there exist sequences $s_k \to +\infty$, $t_k \in \mathbb{R}/\mathbb{Z}$ such that $u'_k(s_k, t_k) \in \partial N_m$. By the previous lemma, the sequence of cylinders

$$\widetilde{v}_k(s,t) = \left(a'_k(s+s_k,t+t_k) - a'_k(s_k,t_k), u'_k(s+s_k,t+t_k)\right)$$

defined on $[-s_k, +\infty) \times \mathbb{R}/\mathbb{Z}$ converges in C_{loc}^{∞} to a trivial cylinder over γ_m . From $\tilde{v}_k(0,0) \in 0 \times \partial N_m$ we see that γ_m intersects ∂N_m , which is absurd.

Since the N_l are tubular neighborhoods of the γ_l which are allowed to be taken arbitrarily small, there is no loss of generality in assuming that N_m is contained in the domain of coordinates

$$(\theta, z = x + iy) \in \mathbb{R}/\mathbb{Z} \times \mathbb{C}$$

given by a Martinet tube for (γ_m, α) ; see Definition 2.6. The contact forms α_k, α are given on N_m as

$$\alpha_k = f_k h(d\theta + xdy), \quad \alpha = h(d\theta + xdy)$$

for some $h = h(\theta, z)$ satisfying $h(\theta, 0) = T_m$ and $dh(\theta, 0) = 0$ for all θ . In view of (42) the $f_k h$ satisfy the same properties. In coordinates we write

$$X_{\alpha} = (X_{\alpha}^1, Y), \quad X_{\alpha_k} = (X_{\alpha_k}^1, Y_k)$$

and define matrix-valued functions

$$D_k(\theta, z) = \int_0^1 D_2 Y_k(\theta, \tau z) \, d\tau, \quad D(\theta, z) = \int_0^1 D_2 Y(\theta, \tau z) \, d\tau.$$
(58)

By Lemma 3.31 the components

$$w_k(s,t) = \left(\theta_k(s,t), z_k(s,t) = x_k(s,t) + iy_k(s,t)\right)$$

of $u'_k(s,t)$ are well-defined functions of $(s,t) \in [s_0, +\infty) \times \mathbb{R}/\mathbb{Z}$. So are the components

$$w(s,t) = \left(\theta(s,t), z(s,t) = x(s,t) + iy(s,t)\right)$$

of u(s, t). We already know that

$$w_k(s,t) \to w(s,t)$$
 in C_{loc}^{∞}

In the frame $\{\partial_x, -x\partial_\theta + \partial_y\}$ of $\xi|_{N_m}$ we can represent J_k , J as matrix-valued functions of (θ, z) . The Cauchy–Riemann equations for $\tilde{u}'_k(s, t)$ and $\tilde{u}(s, t)$ read

$$\begin{cases} \partial_s a'_k - ((f_k h) \circ w_k)(\partial_t \theta_k + x_k \partial_t y_k) = 0, \\ \partial_s \theta_k + ((f_k h) \circ w_k)^{-1} \partial_t a'_k + x_k \partial_s y_k = 0, \\ (\delta_s a - (h \circ w)(\partial_t \theta + x \partial_t y) = 0, \\ \partial_s \theta + (h \circ w)^{-1} \partial_t a + x \partial_s y = 0, \end{cases}$$
(59)

and

$$\partial_s z_k + (J_k \circ w_k) \partial_t z_k + S_k z_k = 0,$$

$$\partial_s z + (J \circ w) \partial_t z + S z = 0,$$
(60)

where

$$S_k(s,t) = [\partial_t a'_k I - \partial_s a'_k (J_k \circ w_k)] D_k \circ w_k,$$

$$S(s,t) = [\partial_t a I - \partial_s a (J \circ w)] D \circ w.$$
(61)

The functions $\theta(s, t)$, $\theta_k(s, t)$ take values in \mathbb{R}/\mathbb{Z} . By Lemma 3.27 the degrees of the maps $\theta(s, \cdot)$, $\theta_k(s, \cdot)$ are equal to 1 since γ_m is simply covered. Since $z_{k,m}$ is a non-degenerate puncture of \tilde{u}_k , we know that $z'_{k,m} = z_{\infty,m}$ is a non-degenerate puncture of \tilde{u}'_k , and Theorem 2.10 guarantees that $\lim_{s \to +\infty} \theta_k(s, 0)$ exists in \mathbb{R}/\mathbb{Z} . Choose unique lifts of $\tilde{\theta}_k : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ determined by $\lim_{s \to +\infty} \tilde{\theta}_k(s, 0) \in [0, 1)$. Up to a subsequence we may assume without loss of generality that

$$\lim_{k \to \infty} \lim_{s \to +\infty} \tilde{\theta}_k(s, 0) \quad \text{exists in } [0, 1].$$

Choose a lift $\tilde{\theta} : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ of $\theta(s,t)$. We have $\tilde{\theta}_k(s,t+1) = \tilde{\theta}_k(s,t) + 1$ and $\tilde{\theta}(s,t+1) = \tilde{\theta}(s,t) + 1$.

Lemma 3.32. The following holds:

$$\lim_{s \to +\infty} \sup_{k,t} \left(|D^{\beta}[a'_{k} - T_{m}s]| + |D^{\beta}[\tilde{\theta}_{k} - t]| \right) = 0 \quad \forall \beta \text{ such that } |\beta| \ge 1,$$

$$\lim_{s \to +\infty} \sup_{k,t} |D^{\beta}z_{k}| = 0 \quad \forall \beta,$$
(62)

where $D^{\beta} = \partial_s^{\beta_1} \partial_t^{\beta_2}$ and $|\beta| = \beta_1 + \beta_2$.

Proof. Direct consequence of Lemma 3.30.

From now on we fix smooth maps $M_k(\theta, z), M(\theta, z) \in Sp(2)$ defined on a common neighborhood of $\mathbb{R}/\mathbb{Z} \times 0$ satisfying

$$M_k J_k = J_0 M_k, \quad MJ = J_0 M, \quad M_k \to M \text{ in } C^{\infty},$$

where $J_0 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$. Here we use $J_k \to J$ in C^{∞} . Define

$$J^{\infty}(t) = J(t, 0), \qquad M^{\infty}(t) = M(t, 0), D^{\infty}(t) = D_2 Y(t, 0), \qquad S^{\infty}(t) = -T_m J^{\infty}(t) D^{\infty}(t)$$

Lemma 3.33 ([31, Lemma 4.12]). For all pairs of sequences $k_j, s_j \to +\infty$ there exist $j_i \to +\infty$ and $c \in [0, 1]$ such that

$$\begin{split} &\lim_{i \to +\infty} \|D^{\beta}[J_{k_{j_i}} \circ w_{k_{j_i}} - J^{\infty}(t+c)](s_{j_i}, \cdot)\|_{L^{\infty}(\mathbb{R}/\mathbb{Z})} = 0, \\ &\lim_{i \to +\infty} \|D^{\beta}[D_{k_{j_i}} \circ w_{k_{j_i}} - D^{\infty}(t+c)](s_{j_i}, \cdot)\|_{L^{\infty}(\mathbb{R}/\mathbb{Z})} = 0, \\ &\lim_{i \to +\infty} \|D^{\beta}[M_{k_{j_i}} \circ w_{k_{j_i}} - M^{\infty}(t+c)](s_{j_i}, \cdot)\|_{L^{\infty}(\mathbb{R}/\mathbb{Z})} = 0, \\ &\lim_{i \to +\infty} \|D^{\beta}[S_{k_{j_i}} - S^{\infty}(t+c)](s_{j_i}, \cdot)\|_{L^{\infty}(\mathbb{R}/\mathbb{Z})} = 0, \end{split}$$

for every $D^{\beta} = \partial_s^{\beta_1} \partial_t^{\beta_2}$.

Proof. We only address the first limit. The second and third follow analogously, and the fourth is a consequence of the first three and of (61).

In this proof we may see functions defined on $\mathbb{R}/\mathbb{Z} \times \mathbb{C}$ as functions defined on $\mathbb{R} \times \mathbb{C}$ which are 1-periodic in the first coordinate. Set $c_j = \tilde{\theta}_{k_j}(s_j, 0) - m_j \in [0, 1)$ where $m_j \in \mathbb{Z}$. Choose j_i such that $c := \lim_{i \to +\infty} c_{j_i}$ exists in [0, 1]. Consider the function

$$\Delta_k(s,t) = (\tilde{\theta}_k(s,t) - t - \tilde{\theta}_k(s,0), z_k(s,t)).$$

By Lemma 3.32 we get

$$\lim_{s \to +\infty} \sup_{k,t} |D^{\beta} \Delta_k(s,t)| = 0 \quad \forall \beta.$$
(63)

Write

$$J_k \circ w_k(s,t) = J_k(t + \tilde{\theta}_k(s,0), 0) + \epsilon_k(s,t)$$
(64)

where

$$\epsilon_k(s,t) = \int_0^1 DJ_k\big((t + \tilde{\theta}_k(s,0), 0) + \tau \Delta_k(s,t)\big) \, d\tau \cdot \Delta_k(s,t).$$

Using (63) and the fact that any partial derivative of J_k is uniformly (also in k) bounded on a fixed compact neighborhood of $\mathbb{R}/\mathbb{Z} \times 0$, we get

$$\lim_{s \to +\infty} \sup_{k,t} |D^{\beta} \epsilon_k(s,t)| = 0.$$
(65)

Finally, we can write

$$J_{k_j} \circ w_{k_j}(s,t) - J^{\infty}(t+c) = \epsilon_{k_j}(s,t) + \epsilon'_j(s,t) + \epsilon''_j(t)$$

where

$$\begin{aligned} \epsilon'_j(s,t) &= J_{k_j}(t + \tilde{\theta}_{k_j}(s,0), 0) - J_{k_j}(t + c_j, 0), \\ \epsilon''_j(t) &= J_{k_j}(t + c_j, 0) - J(t + c, 0). \end{aligned}$$

Write

$$\epsilon'_{j}(s,t) = \int_{0}^{1} DJ_{k_{j}}(t + \tau(\tilde{\theta}_{k_{j}}(s,0) - c_{j} - m_{j}), 0) d\tau \cdot (\tilde{\theta}_{k_{j}}(s,0) - c_{j} - m_{j}, 0)$$

and use Lemma 3.32 to conclude that

$$\lim_{j \to +\infty} \sup_{t} |D^{\beta} \epsilon'_{j}(s_{j}, t)| = 0 \quad \forall \beta.$$

Obviously

$$\lim_{t \to +\infty} \sup_{t} |\partial_t^l \epsilon_{j_i}''(t)| = 0 \quad \forall l,$$

since $J_k \to J$ in C^{∞} and $c_{j_i} \to c$.

From now on we denote

$$\begin{split} M_k(s,t) &= M_k(w_k(s,t)), \quad M(s,t) = M(w(s,t)), \\ J_k(s,t) &= J_k(w_k(s,t)), \quad J(s,t) = J(w(s,t)), \\ D_k(s,t) &= D_k(w_k(s,t)), \quad D(s,t) = D(w(s,t)), \end{split}$$

without fear of ambiguity. Consider

$$\begin{aligned} \zeta_k(s,t) &= M_k(s,t) z_k(s,t), \\ \Lambda_k(s,t) &= (M_k S_k - \partial_s M_k - J_0 \partial_t M_k) M_k^{-1}. \end{aligned}$$
(66)

Then ζ_k satisfies

$$\partial_s \zeta_k + J_0 \partial_t \zeta_k + \Lambda_k \zeta_k = 0. \tag{67}$$

The following statement is a consequence of the previous lemma.

Corollary 3.34. If we set

$$\Lambda^{\infty}(t) = (M^{\infty}S^{\infty} - J_0\partial_t M^{\infty})(M^{\infty})^{-1}$$

then for all pairs of sequences $k_j, s_j \to +\infty$ there exist $j_i \to +\infty$ and $c \in [0, 1)$ such that

$$\lim_{i \to +\infty} \|D^{\beta}[\Lambda_{k_{j_i}} - \Lambda^{\infty}(t+c)](s_{j_i}, \cdot)\|_{L^{\infty}(\mathbb{R}/\mathbb{Z})} = 0 \quad \forall \beta.$$

We follow [24] closely. With $N \in \mathbb{N}$, $l \in \mathbb{N} \cup \{0\}$, $a \in (0, 1)$ and $d \in (-\infty, 0)$ fixed, a function $F : [s_0, +\infty) \times \mathbb{R}/\mathbb{Z} \to \mathbb{R}^N$ is said to be of class $C_0^{l,a,d}$ if F is of class $C_{loc}^{l,a}$ and

$$\lim_{R \to +\infty} \|e^{-ds} D^{\beta} F\|_{C^{0,a}([R,+\infty) \times \mathbb{R}/\mathbb{Z})} = 0 \quad \forall \beta \text{ with } |\beta| \le l.$$

The space of such functions becomes a Banach space with the norm

$$\|F\|_{C_0^{l,a,d}} = \|e^{-ds}F\|_{C^{l,a}([s_0,+\infty)\times\mathbb{R}/\mathbb{Z})}.$$

It follows from Theorem 2.10 and the definition of $\mathcal{M}_{\tilde{J}_k,0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ that for every k the function $z_k(s,t)$ is of class $C_0^{l,a,\delta}$ for every $l \ge 0$ and every $a \in (0,1)$. Lemma 3.33 implies that $\zeta_k(s,t)$ is also of class $C_0^{l,a,\delta}$. Moreover,

$$\zeta_k(s,t) \to \zeta(s,t) := M(s,t)z(s,t) \quad \text{in } C_{\text{loc}}^{\infty}.$$
(68)

The crucial step is now to apply the following result.

Proposition 3.35 ([31, Proposition 4.15]). Let

$$K_n: [0, +\infty) \times \mathbb{R}/\mathbb{Z} \to \mathbb{R}^{2N \times 2N} \ (n \ge 1), \quad K^\infty: \mathbb{R}/\mathbb{Z} \to \mathbb{R}^{2N \times 2N}$$

be smooth maps satisfying:

- (i) $K^{\infty}(t)$ is symmetric for all t.
- (ii) For any sequences $n_l, s_l \to +\infty$ there exist $l_k \to +\infty$ and $c \in [0, 1)$ such that

$$\lim_{k \to \infty} \|D^{\beta}[K_{n_{l_k}} - K^{\infty}(t+c)](s_{l_k}, \cdot)\|_{L^{\infty}(\mathbb{R}/\mathbb{Z})} = 0 \quad \forall \beta$$

Consider the unbounded self-adjoint operator L on $L^2(\mathbb{R}/\mathbb{Z},\mathbb{R}^{2N})$ defined by

$$Le = -J_0 \dot{e} - K^\infty e.$$

With $l \ge 1$, $a \in (0, 1)$ and $d \in (-\infty, 0)$, suppose that the \mathbb{R}^{2N} -valued smooth maps $X_n(s, t)$ are of class $C_0^{l,a,d}$ and satisfy

$$\partial_s X_n + J_0 \partial_t X_n + K_n X_n = 0 \quad \forall n.$$
⁽⁶⁹⁾

If d does not belong to the spectrum of L and the sequence $\{X_n\}$ is C_{loc}^{∞} -bounded then $\{X_n\}$ has a convergent subsequence in $C_0^{l,a,d}$.

Direct calculations show that $\Lambda^{\infty}(t)$ is symmetric for every t, and that the operator $-J_0\partial_t - \Lambda^{\infty}$ is nothing but a representation of the asymptotic operator at γ_m associated to (α, J) . It follows that δ_m is not in its spectrum. Corollary 3.34 allows us to apply the above proposition with $d = \delta_m$ and conclude that ζ_k has a convergent subsequence in C_0^{l,a,δ_m} . It follows that $\zeta(s,t)$ is of class C_0^{l,a,δ_m} . Hence, also z(s,t) is of class C^{l,a,δ_m} . Since $l \ge 1$ is arbitrary, we get

$$\lim_{s \to +\infty} \sup_{t \in \mathbb{R}/\mathbb{Z}} e^{-\delta_m s} |D^\beta z(s, t)| = 0 \quad \forall \beta.$$
(70)

The fact that $\zeta_k \to \zeta$ in C_0^{l,a,δ_m} implies that $z_k \to z(s,t)$ in C_0^{l,a,δ_m} by Lemma 3.33. As l is arbitrary we conclude from the definition of the spaces C_0^{l,a,δ_m} that

$$\lim_{s \to +\infty} \sup_{t,k} e^{-\delta_m s} |D^\beta z_k(s,t)| = 0 \quad \forall \beta.$$
(71)

From this point it is quite standard to use (70) and (71) together with (59)–(60) conclude that $z_{\infty,m}$ is a non-degenerate puncture of \tilde{u} . For completeness we provide the details [28, 31]. By Theorem 2.10, for every k we find d_k , $\tau_k \in \mathbb{R}$ such that

$$V_k(s,t) = \begin{pmatrix} a_k(s,t) - T_m s - d_k \\ \tilde{\theta}_k(s,t) - t - \tau_k \end{pmatrix}$$

satisfies

$$\lim_{s \to +\infty} \sup_{t} |V_k(s,t)| = 0 \quad \forall k.$$

Equations (59) tell us that

$$\partial_s V_k(s,t) + \begin{pmatrix} 0 & -T_m \\ T_m^{-1} & 0 \end{pmatrix} \partial_t V_k(s,t) + B_k(s,t) z_k(s,t) = 0$$
(72)

for some $B_k(s, t)$ satisfying

$$\limsup_{s\to+\infty}\sup_{t,k}|D^{\beta}B_k(s,t)|<\infty\quad\forall\beta.$$

Together with (71) we get

$$\lim_{s \to +\infty} \sup_{t,k} e^{-\delta_m s} |D^{\beta}[B_k z_k](s,t)| = 0 \quad \forall \beta.$$
(73)

Lemma 3.36. There exists r > 0 such that

$$\lim_{s \to +\infty} \sup_{t,k} e^{rs} |D^{\beta} V_k(s,t)| = 0 \quad \forall D^{\beta} = \partial_s^{\beta_1} \partial_t^{\beta_2} \text{ with } |\beta| \ge 1.$$

Proof. This is a version for sequences of [26, Lemma 6.3]. Fix any β_0 and denote $U_k = D^{\beta_0} \partial_t V_k$. Lemma 3.32 implies that

$$\lim_{s \to +\infty} \sup_{k,t} |D^{\beta} U_k(s,t)| = 0 \quad \forall \beta$$

It is no loss of generality to assume $T_m = 1$. Differentiating (72) we arrive at

 $\partial_s U_k + J_0 \partial_t U_k(s,t) = h_k(s,t).$

Moreover, (73) gives

$$\lim_{s \to +\infty} \sup_{t,k} e^{-\delta_m s} |D^{\beta'} h_k(s,t)| = 0 \quad \forall \beta'.$$
(74)

Let $g_k(s) = \frac{1}{2} \|U_k(s, \cdot)\|_{L^2(\mathbb{R}/\mathbb{Z})}^2$. Compute

$$g'_k(s) = \langle -J_0 \partial_t U_k(s, \cdot) + h_k(s, \cdot), U_k(s, \cdot) \rangle_{L^2}$$

and

$$g_k''(s) = \langle -J_0 \partial_s \partial_t U_k, U_k \rangle_{L^2} + \langle \partial_s h_k, U_k \rangle_{L^2} + \| -J_0 \partial_t U_k + h_k \|_{L^2}^2$$

= $\langle -J_0 \partial_t U_k + h_k, -J_0 \partial_t U_k \rangle_{L^2} + \langle \partial_s h_k, U_k \rangle_{L^2} + \| -J_0 \partial_t U_k + h_k \|_{L^2}^2$
= $2 \| \partial_t U_k \|_{L^2}^2 + 3 \langle -J_0 \partial_t U_k, h_k \rangle_{L^2} + \langle \partial_s h_k, U_k \rangle_{L^2} + \| h_k \|_{L^2}^2$
 $\ge 2 \| U_k \|_{L^2}^2 - 3 \| U_k \|_{L^2} \| h_k \|_{L^2} - \| U_k \|_{L^2} \| \partial_s h_k \|_{L^2} - \| h_k \|_{L^2}^2$

where in the last inequality we used the Poincaré inequality (U_k has average zero in t) and the Cauchy–Schwarz inequality. Fix $0 < d < \min\{1/2, -\delta_m\}$. By the 'Peter-Paul' inequality with $\epsilon > 0$, and (74), we get

$$g_k''(s) \ge (2-\epsilon) \|U_k\|_{L^2}^2 - C(\epsilon)(\|\partial_s h_k\|_{L^2}^2 + \|h_k\|_{L^2}^2) \ge 2(2-\epsilon)g_k(s) - ce^{-2ds}$$

for some c > 0 that depends on ϵ but does not depend on k. Choosing ϵ small we get

$$g_k''(s) \ge g_k(s) - ce^{-2ds}$$

uniformly in k. Choose 0 < v < 2d (< 1), set $L = c/(4d^2 - v^2)$ and consider $f_k := g_k + Le^{-2ds}$. Note that $f_k(s) > 0$ since $g_k(s) \ge 0$ for all s. The above differential inequality translates into

$$f_k'' \ge \nu^2 f_k$$

where ν is independent of k. Note that $f_k(s) \to 0$ as $s \to +\infty$, for all k.

We claim that $f'_k(s) \le 0$ for all k and $s \gg 1$. Indeed, if not then we could find $s_* \gg 1$ and k such that $f'_k(s_*) > 0$. Consider $G_k = f'_k + \nu f_k$, so that $G_k(s_*) > 0$. Let

$$\bar{s} = \sup \{s \ge s_* \mid G_k(y) > 0 \ \forall y \in [s_*, s]\} \in (s_*, +\infty].$$

The differential inequality $G'_k \ge \nu G_k$ implies that

$$G_k(s) \ge G_k(s_*)e^{\nu(s-s_*)} \ge G_k(s_*) > 0$$
 for every $s \in (s_*, \bar{s})$.

In particular, $\bar{s} = +\infty$ and $G_k(s) \to +\infty$ as $s \to +\infty$, forcing $f'_k(s) \to +\infty$ as $s \to +\infty$ since $f_k(s) \to 0$ as $s \to +\infty$. This is an obvious contradiction to $\lim_{s\to+\infty} f_k(s) = 0$. Consider now $H_k = f_k - \nu^{-1} f'_k$. Since $f'_k(s) \le 0$ and $f_k(s) > 0$, we conclude that $H_k(s) \ge f_k(s) > 0$ for all $s \ge s_0 \gg 1$. The differential inequality satisfied by f_k implies that $H'_k \le -\nu H_k$, which yields

$$g_k(s) \le f_k(s) \le H_k(s) \le H_k(s_0)e^{-\nu(s-s_0)}$$
 on $[s_0, +\infty)$.

Fix any $0 < r < \nu$. Since $H_k(s_0)$ has a limit as $k \to +\infty$, and β_0 was chosen arbitrarily, we get

$$\lim_{s \to +\infty} e^{rs} \sup_{k} \int_{\mathbb{R}/\mathbb{Z}} |D^{\beta} V_{k}(s,t)|^{2} dt = 0$$

for all $\beta = (\beta_1, \beta_2)$ satisfying $\beta_2 \ge 1$. The (trivial) Sobolev inqualities for functions on \mathbb{R}/\mathbb{Z} yield

$$\lim_{s \to +\infty} e^{rs} \sup_{k,t} |D^{\beta} V_k(s,t)| = 0 \quad \forall \beta = (\beta_1, \beta_2) \text{ with } \beta_2 \ge 1$$

as desired. The lemma now follows from this and (72).

Using (72) together with the previous lemma we get

$$\lim_{s \to +\infty} e^{rs} \sup_{k,t} |\partial_s V_k(s,t)| = 0.$$

Equivalently

$$\begin{cases} \lim_{s \to +\infty} e^{rs} \sup_{k,t} |\partial_s a'_k(s,t) - T_m| = 0, \\ \lim_{s \to +\infty} e^{rs} \sup_{k,t} |\partial_s \tilde{\theta}_k(s,t)| = 0. \end{cases}$$

Passing to the limit as $k \to +\infty$ we achieve

$$\begin{cases} \lim_{s \to +\infty} e^{rs} \sup_{t} |\partial_s a(s,t) - T_m| = 0, \\ \lim_{s \to +\infty} e^{rs} \sup_{t} |\partial_s \tilde{\theta}(s,t)| = 0. \end{cases}$$

In view of the exponential factor we conclude that the following integrals converge:

$$d = a(s_0, 0) - T_m s_0 + \int_{s_0}^{+\infty} (\partial_s a(s, 0) - T_m) \, ds,$$

$$\tau = \tilde{\theta}(s_0, 0) + \int_{s_0}^{+\infty} \partial_s \tilde{\theta}(s, 0) \, ds.$$

Now the constants d, τ satisfy

$$\lim_{s \to +\infty} \sup_{t} |a(s,t) - T_m s - d| = 0, \quad \lim_{s \to +\infty} \sup_{t} |\tilde{\theta}(s,t) - t - \tau| = 0.$$

We have finally shown that $z_{\infty,m}$ is a non-degenerate puncture of \tilde{u} . From (70) we see that the asymptotic eigenvalue at this puncture, which exists by Theorem 2.10, is $\leq \delta_m$. Since $m \in \{1, \ldots, n\}$ is arbitrary, the proof of Lemma 3.28 is complete.

As explained before, this completes the proof of Proposition 3.20.

3.4.4. Proof of (iii) \Rightarrow (ii) in Theorem 1.8. Consider smooth functions $g_k: M \rightarrow (0, +\infty)$ such that

- $g_k \to 1$ in C^{∞} ,
- $g_k(p) = 1$ and $dg_k(p) = 0$ for all $p \in L$,
- $g_k \alpha$ is non-degenerate for every k.

Fix a $d\alpha$ -compatible complex structure $J : \xi \to \xi$, and define \tilde{J}_k and \tilde{J} by (8) using $(g_k \alpha, J)$ and (α, J) , respectively.

Using Proposition 3.16 we get, for every k large enough, embedded curves in $\mathcal{M}_{\tilde{J}_k,0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ inside $\mathbb{R} \times (M \setminus L)$ representing the class $b \in H_2(M, L)$ of a page of Θ . By Proposition 3.20 we get an embedded curve $C_* \in \mathcal{M}_{\tilde{J},0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ contained in $\mathbb{R} \times (M \setminus L)$ that represents b.

Let X denote the connected component of $\mathcal{M}_{\tilde{J},0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)/\mathbb{R}$ that contains C_* . Since α is possibly degenerate, we do not have at our disposal the statements from [42] to study geometric properties of curves in X. We have to provide explicit arguments to conclude that curves in X are embedded, are contained in $\mathbb{R} \times (M \setminus L)$ and their projections to M do not intersect. We start by noting that curves in X are immersed and transverse to the Reeb vector field; this is the content of Lemma 3.19.

Lemma 3.37. Every curve in X is embedded.

Proof. The Fredholm theory described in Lemma 3.7 does not use non-degeneracy of the contact form; it only depends on the exponential weights and on the assumption that the reference curve is embedded. Note that in Section 2.2.6 we defined our moduli spaces to be spaces of curves with non-degenerate behavior at the punctures; see Definition 2.9. Thus, the neighboring curves in $\mathcal{M}_{\tilde{J},0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ of a fixed embedded curve $C_0 \in X$ foliate a neighborhood of C_0 in $\mathbb{R} \times M$, in particular they do not intersect each other. This was explained in the sketch of Lemma 3.7. Moreover, it follows that the set of curves in X that are embedded form an open subset of X.

Now we argue to show that this set is also closed in X. If not then we would have a sequence of embedded curves $C_k \in X$ converging to a curve $C_{\infty} \in X$ that is not embedded. Above we saw that C_{∞} is immersed. Hence C_{∞} must have self-intersections, and these must be isolated since curves in $\mathcal{M}_{\tilde{J},0,\delta}(\gamma_1,\ldots,\gamma_n;\emptyset)$ are somewhere injective; Lemma 3.3 does not use a non-degeneracy assumption on the contact form. Positivity and stability of intersections provide self-intersections of C_k for large k, and this is absurd. Since X is connected and contains the embedded curve C_* , we conclude that all curves in X are embedded.

Let $C \in X$ be represented by the map $\tilde{u} = (a, u) : \mathbb{C} \setminus \Gamma \to \mathbb{R} \times M$ defined on a punctured plane. The map \tilde{u} is pseudo-holomorphic and has finite energy. The set of punctures of \tilde{u} is $\Gamma \cup \{\infty\}$. We saw above that \tilde{u} is an embedding. Suppose that for some $c \neq 0$ we have

$$F_c := \{ (z, \zeta) \in (\mathbb{C} \setminus \Gamma) \times (\mathbb{C} \setminus \Gamma) \mid \widetilde{u}(z) = \widetilde{u}_c(\zeta) \} \neq \emptyset.$$

Here we denote by $\tilde{u}_c = (a + c, u)$ the \mathbb{R} -translation of \tilde{u} by c. Note that $(z, \zeta) \in F_c$ and $c \neq 0$ together imply that $z \neq \zeta$. Without loss of generality assume c > 0. We claim that for every $0 < \epsilon < c$ there exists a compact set $K \subset (\mathbb{C} \setminus \Gamma) \times (\mathbb{C} \setminus \Gamma)$ containing $\bigcup_{t \in [\epsilon, c]} F_t$. Indeed, if not then we find $t_n \in [\epsilon, c]$ and $(z_n, \zeta_n) \in F_{t_n}$ such that z_n or ζ_n converges to $\Gamma \cup \{\infty\}$. It follows that $a(z_n) \to +\infty$ or $a(w_n) \to +\infty$. Hence both $a(z_n)$ and $a(w_n)$ converge to $+\infty$ since $|a(z_n) - a(w_n)| = t_n$ is bounded. In other words, both sequences z_n and ζ_n converge to $\Gamma \cup \{\infty\}$. Since asymptotic limits are geometrically distinct, both z_n and ζ_n converge to the same puncture, say to $z_* \in \Gamma \cup \{\infty\}$. But, since asymptotic limits are simple orbits, we know that the M-component u is injective around z_* , in contradiction to $u(z_n) = u(\zeta_n)$ and $z_n \neq \zeta_n$. We have proved existence of the desired compact set K. By positivity of intersections, the image of \tilde{u} intersects the image of \tilde{u}_ϵ for every $\epsilon > 0$. But when ϵ is small enough the images of the maps \tilde{u}_ϵ show up in the local foliations around C given by Fredholm theory, hence they cannot intersect C, which is absurd. It follows that $F_c = \emptyset$ for every $c \neq 0$. There are two important consequences:

- $C \cap \mathbb{R} \times L = \emptyset$.
- *u* is injective.

In particular, since we already know that C projects to an immersed surface in M, the closure of the projection of C to M is a Seifert surface for L representing the class b.

We need to argue that if C, C' are distinct curves in X then their projections to M do not intersect. Represent C, C' as finite-energy maps

$$\widetilde{u} = (a, u) : (\mathbb{C}P^1 \setminus \Gamma, i) \to (\mathbb{R} \times M, \widetilde{J}),$$
$$\widetilde{u}' = (a', u') : (\mathbb{C}P^1 \setminus \Gamma', i) \to (\mathbb{R} \times M, \widetilde{J})$$

respectively, where Γ and Γ' are finite sets of positive punctures. Let

$$E_c = \{ z \in \mathbb{C} P^1 \setminus \Gamma \mid \widetilde{u}(z) = \widetilde{u}'_c(z') \text{ for some } z' \in \mathbb{C} P^1 \setminus \Gamma' \}$$

and consider the set

$$A := \{ c \in \mathbb{R} \mid E_c \neq \emptyset \}.$$
(75)

Lemma 3.38. $A = \emptyset$.

The proof will be presented below. Lemma 3.38 is equivalent to saying that the projections of *C* and *C'* to *M* do not intersect. We conclude that the projections of curves in *X* foliate $M \setminus L$ by surfaces which are transverse to the Reeb flow, forming a planar open book. It remains only to argue that pages are global surfaces of section; this argument was already explained at the end of Section 3.3. By transversality of the pages to X_{α} , if the ω -limit set of a point in $M \setminus L$ does not intersect *L* then the future trajectory of this point will hit every page infinitely often. If the ω -limit set of a point in $M \setminus L$ intersects *L* then the future trajectory of this point will spend arbitrarily long periods of time arbitrarily close to *L*, where it can be well controlled by the linearized dynamics along components of *L*. Assumption (iii)(a) in Theorem 1.8 guarantees that this trajectory hits every page infinitely often. The argument for past times is analogous. We have finally finished proving (iii) \Rightarrow (ii) of Theorem 1.8, up to presenting proof of Lemma 3.38. *Proof of Lemma* 3.38. The proof is accomplished by establishing two contradictory claims.

Step 1. If $A \neq \emptyset$ then $\inf A > -\infty$.

Step 2. If $A \neq \emptyset$ then $\inf A = -\infty$.

Consider a sequence $c_k \in A$ such that

$$c_k \to c = \inf A \in [-\infty, +\infty).$$

We can find sequences $z_k \in \mathbb{C}P^1 \setminus \Gamma$, $z'_k \in \mathbb{C}P^1 \setminus \Gamma'$ such that $\tilde{u}(z_k) = \tilde{u}'_{c_k}(z'_k)$. We claim that either (z_k, z'_k) is compactly contained in $(\mathbb{C}P^1 \setminus \Gamma) \times (\mathbb{C}P^1 \setminus \Gamma')$ or, up to a subsequence, we can assume that (z_k, z'_k) converges to a point in $\Gamma \times \Gamma'$. In fact, if z_k is compactly contained in $\mathbb{C}P^1 \setminus \Gamma$ and z'_k is not compactly contained in $\mathbb{C}P^1 \setminus \Gamma'$ then we may assume $u(z_k) = u'(z'_k) \to L$, forcing \tilde{u} to intersect $\mathbb{R} \times L$, which is absurd. A similar argument handles the case where the roles of z_k and z'_k are interchanged.

Up to choice of a subsequence we can assume $(z_k, z'_k) \to (z_*, z'_*) \in \mathbb{C}P^1 \times \mathbb{C}P^1$. By what was proved above either $(z_*, z'_*) \in (\mathbb{C}P^1 \setminus \Gamma) \times (\mathbb{C}P^1 \setminus \Gamma')$ or $(z_*, z'_*) \in \Gamma \times \Gamma'$.

Case 1: $(z_*, z'_*) \in (\mathbb{C}P^1 \setminus \Gamma) \times (\mathbb{C}P^1 \setminus \Gamma')$. We prove Step 1 in this case. If $c = -\infty$ then the identity $a'(z'_k) + c_k = a(z_k) \ge \inf a > -\infty$ shows that $a'(z'_k) \to +\infty$, contradicting $a'(z'_k) \to a'(z'_*) \in \mathbb{R}$.

Now we prove Step 2 in this case. If $c > -\infty$ then $\tilde{u}(z_*) = \tilde{u}'_c(z'_*)$. The point (z_*, z'_*) is isolated as an intersection point of \tilde{u} with \tilde{u}'_c ; otherwise we would use the similarity principle to conclude that C = C' (these curves are embedded). By stability and positivity of intersections we conclude that $E_y \neq \emptyset$ for some y < c, contrary to the definition of c.

Case 2: $(z_*, z'_*) \in \Gamma \times \Gamma'$. At the punctures z_*, z'_* the curves \tilde{u}, \tilde{u}' must be asymptotic to the same periodic orbit $\gamma_l = (x_l, T_l)$ since all asymptotic limits of both curves are geometrically distinct. For the *M*-components we get $u(z_k) = u'(z'_k)$ since the asymptotic limits are simply covered.

Choose asymptotic representatives (ϕ, U) and (ϕ', U') of \tilde{u} and \tilde{u}' at z_* and z'_* , respectively. The existence of asymptotic representatives makes use of Theorem 2.10. This means (see [41]), we can find $R, R' \gg 1$, compact neighborhoods D_*, D'_* of z_*, z'_* , smooth maps

$$U: [R, +\infty) \times \mathbb{R}/\mathbb{Z} \to \xi, \quad U(s,t) \in \xi|_{x_l(T_lt)}, \\ U': [R', +\infty) \times \mathbb{R}/\mathbb{Z} \to \xi, \quad U'(s,t) \in \xi|_{x_l(T_lt)},$$

and diffeomorphisms

 $\phi: [R, +\infty) \times \mathbb{R}/\mathbb{Z} \to D_* \setminus \{z_*\}, \quad \phi': [R', +\infty) \times \mathbb{R}/\mathbb{Z} \to D'_* \setminus \{z'_*\}$

satisfying

$$\widetilde{u}(\phi(s,t)) = (T_l s, \exp_{x_l(T_l t)} U(s,t)), \quad \widetilde{u}'(\phi'(s,t)) = (T_l s, \exp_{x_l(T_l t)} U'(s,t)).$$

Here exp is the exponential map given by an arbitrary auxiliary Riemannian metric on M. Then for every $\tau \in \mathbb{R}$, $(\phi'_{\tau}, U'_{\tau})$ is an asymptotic representative of \tilde{u}'_{τ} , where

$$\phi'_{\tau}(s,t) = \phi'(s-\tau/T_l,t), \quad U'_{\tau}(s,t) = U'(s-\tau/T_l,t).$$

The choice of parametrization $x_l(t)$ is fixed by the convention made in Remark 2.1. The sequences $z_k \to z_*, z'_k \to z'_*$ correspond to sequences $(s_k, t_k), (s'_k, t'_k)$ satisfying $\min \{s_k, s'_k\} \to +\infty$ and

$$(T_l s_k, \exp_{x_l(T_l t_k)} U(s_k, t_k)) = \tilde{u}(\phi(s_k, t_k)) = \tilde{u}_{c_k}(\phi'_{c_k}(s'_k, t'_k)) = (T_l s'_k, \exp_{x_l(T_l t'_k)} U'(s'_k - c_k/T_l, t'_k)).$$

For the \mathbb{R} -components we get $s_k = s'_k$. Now since exp yields a diffeomorphism of a neighborhood of the zero section of ξ_{γ_l} onto a neighborhood of $x_l(\mathbb{R})$, the identity

$$\exp_{x_l(T_lt_k)} U(s_k, t_k) = \exp_{x_l(T_lt_k')} U'(s_k' - c_k/T_l, t_k')$$

forces $t_k = t'_k$ and

$$U(s_k, t_k) = U'(s_k - c_k/T_l, t_k) = U'_{c_k}(s_k, t_k).$$
(76)

Let A denote the asymptotic operator on sections of $\xi_{\gamma_l} = x_l (T_l \cdot)^* \xi$ induced by (α, J) . Theorem 2.10 implies that

$$U(s,t) = e^{\lambda s} (v(t) + r(s,t)),$$

$$U'(s,t) = e^{\lambda' s} (v'(t) + r'(s,t)),$$

$$\lim_{s \to +\infty} \sup_{t} (|r(s,t)| + |r'(s,t)|) = 0,$$

(77)

where $\lambda, \lambda' < 0$ are eigenvalues of A and v, v' are corresponding eigensections. Moreover, both v and v' have winding number zero in a symplectic trivialization aligned to the normal of a page of Θ ; this follows from Lemma 3.19. There are two cases to consider.

Subcase 2.1: $\lambda = \lambda'$. From (76) and (77) we obtain

$$0 = e^{\lambda s_k} (v(t_k) + r(s_k, t_k)) - e^{\lambda (s_k - c_k/T_l)} (v'(t_k) + r'(s_k - c_k/T_l, t_k))$$

= $e^{\lambda s_k} (v(t_k) - e^{-\lambda c_k/T_l} v'(t_k) + r(s_k, t_k) - e^{-\lambda c_k/T_l} r'(s_k - c_k/T_l, t_k)).$

Dividing by $e^{\lambda s_k}$ and letting $k \to \infty$ we find that v(t) and $e^{-\lambda c/T_l}v'(t)$ coincide for some *t*, where the latter is zero if $c = -\infty$. Since they solve the same linear ODE we get

$$v(t) = \begin{cases} e^{-\lambda c/T_l} v'(t) \ \forall t & \text{if } c > -\infty, \\ 0 \ \forall t & \text{if } c = -\infty. \end{cases}$$
(78)

We can now prove Step 1 in Subcase 2.1. If $c = -\infty$ we get from (78) a contradiction to the fact that v(t) is nowhere vanishing.

We proceed assuming that $c > -\infty$ and work towards the proof of Step 2 in Subcase 2.1. Below we will show that $\hat{c}_k \in A$ for any sequence $\hat{c}_k \to c$, $\hat{c}_k < c$, in contradiction to the definition of c. Using (78) we obtain the following important fact:

$$\liminf_{s \to +\infty} e^{-\lambda s} |U(s,t) - U'_{\tau}(s,t)| > 0 \quad \forall \tau \neq c.$$
⁽⁷⁹⁾

To see this we plug in the identity $v'(t) = e^{\lambda c/T}v(t)$, which we get from (78) in the case $c > -\infty$, and compute for $\tau \neq c$:

$$U(s,t) - U'_{\tau}(s,t) = e^{\lambda s} (v(t) + r(s,t)) - e^{\lambda (s-\tau/T_l)} \left(e^{\lambda c/T_l} v(t) + r'(s-\tau/T_l,t) \right)$$

= $e^{\lambda s} \left((1 - e^{\lambda (c-\tau)/T_l}) v(t) + r(s,t) - e^{-\lambda \tau/T_l} r'(s-\tau/T_l,t) \right).$ (80)

The hypothesis $\tau \neq c$ implies that the coefficient $1 - e^{\lambda(c-\tau)/T_l}$ in front of v(t) does not vanish, and (79) follows.

However, for the special value $\tau = c$ we get

$$U(s,t) - U'_{c}(s,t) = e^{\lambda s} (v(t) + r(s,t)) - e^{\lambda (s-c/T_{l})} (e^{\lambda c/T_{l}} v(t) + r'(s-c/T_{l},t))$$

= $e^{\lambda s} (r(s,t) - e^{-\lambda c/T_{l}} r'(s-c/T_{l},t)),$

from which we conclude that

$$e^{-\lambda s}|U(s,t) - U'_c(s,t)| \to 0$$
 uniformly in t as $s \to +\infty$.

Theorem 2.10 implies that we can apply [41, Theorem 2.2] to write

$$U(s,t) - U'_{c}(s,t) = e^{\nu s}(w(t) + \hat{r}(s,t)), \quad \lim_{s \to +\infty} \sup_{t} |\hat{r}(s,t)| = 0, \tag{81}$$

where ν is an eigenvalue of A satisfying $\nu < \lambda$, and w(t) is a corresponding eigensection. We claim that wind(w) < wind(v) with respect to some (hence any) homotopy class of symplectic trivializations of ξ_{γ_l} . To see this, fix s_* large enough so that $U - U'_c$ does not vanish on $[s_*, +\infty) \times \mathbb{R}/\mathbb{Z}$ and

wind
$$(U(s_*, \cdot) - U'_c(s_*, \cdot)) = wind(w)$$

This is possible in view of (81). Since $U'_{c_k} \to U'_c$ in C^0_{loc} we can find k_* such that

$$k \ge k_* \implies \begin{cases} U(s_*, \cdot) - U'_{c_k}(s_*, \cdot) & \text{does not vanish, and} \\ \text{wind}(U(s_*, \cdot) - U'_{c_k}(s_*, \cdot)) = \text{wind}(w). \end{cases}$$
(82)

The algebraic count of zeros of $U(s,t) - U'_{c_k}(s,t)$ on $[s_*, +\infty) \times \mathbb{R}/\mathbb{Z}$, with respect to obvious orientations, is equal to the intersection number of the embedded holomorphic cylinders

$$\widetilde{u} \circ \phi([s_*, +\infty) \times \mathbb{R}/\mathbb{Z})$$
 and $\widetilde{u}'_{c_k} \circ \phi'_{c_k}([s_*, +\infty) \times \mathbb{R}/\mathbb{Z})$.

This is an immediate consequence of standard degree theory. From the existence of the sequence (s_k, t_k) we conclude that this intersection number is positive for k large.

But (80), (81), standard degree theory, and the assumption that $c_k \neq c$ together imply that this intersection number is equal to

$$0 < \operatorname{wind}(v) - \operatorname{wind}(U(s_*, \cdot) - U'_{c_k}(s_*, \cdot)) = \operatorname{wind}(v) - \operatorname{wind}(w)$$

as claimed.

We are now in a position to finish the proof of Step 2 in Subcase 2.1. Let $\hat{c}_k \to c$ with $\hat{c}_k < c$ for all k. Arguing as above we get

wind
$$(U(s_*, \cdot) - U'_{\hat{c}_k}(s_*, \cdot)) = wind(w)$$
 for k large enough

As before we use this fact together with the argument principle and (80) to conclude that the half-cylinder $\tilde{u} \circ \phi([s_*, +\infty) \times \mathbb{R}/\mathbb{Z})$ intersects the half-cylinder $\tilde{u}'_{\hat{c}_k} \circ \phi'_{\hat{c}_k}([s_*, +\infty) \times \mathbb{R}/\mathbb{Z})$ for *k* large enough. Hence $\hat{c}_k \in A$, in contradiction to $c = \inf A$.

Subcase 2.2: $\lambda \neq \lambda'$. In this case

$$v'(t) \notin \mathbb{R}v(t) \quad \forall t.$$
(83)

This is a consequence of the following two facts:

- The winding numbers of v and v' in any symplectic frame are equal: both vanish on a trivialization aligned to the normal of a page of Θ (Lemma 3.19).
- If eigensections associated to distinct eigenvalues have the same winding number (in any frame) then they are pointwise linearly independent.

From (76) and (77) we get

$$0 = e^{\lambda s_k} (v(t_k) + r(s_k, t_k)) - e^{\lambda'(s_k - c_k/T_l)} (v'(t_k) + r'(s_k - c_k/T_l, t_k)).$$
(84)

We claim that $(\lambda - \lambda')s_k + \lambda'c_k/T_l$ is a bounded sequence. If not then, up to choice of a subsequence, we may assume that it converges to $+\infty$ or to $-\infty$. In the former case we can divide (84) by $e^{\lambda s_k}$ and get

$$0 = v(t_k) + r(s_k, t_k) - e^{(\lambda' - \lambda)s_k - \lambda'c_k/T_l} (v'(t_k) + r'(s_k - c_k/T_l, t_k)).$$

Since in the present case the coefficient of $v'(t_k) + r'$ converges to zero, we conclude that v(t) vanishes somewhere, and this is impossible. The argument in the case $(\lambda - \lambda')s_k + \lambda'c_k/T_l \rightarrow -\infty$ is analogous: this time one divides (84) by $e^{\lambda'(s_k - c_k/T_l)}$ and arrives at a zero of v'(t). It follows from this claim that, up to a subsequence, we may assume that $e^{(\lambda - \lambda')s_k + \lambda'c_k/T_l} \rightarrow a$ for some $a \neq 0$. Hence, up to a further subsequence, we can use (84) to find t_* such that $av(t_*) = v'(t_*)$. This contradicts to (83).

4. Proof of Theorem 1.11

Theorem 1.8 contains (ii) \Rightarrow (i), and also (i) \Rightarrow (iii) under the stated C^{∞} -genericity assumption. Only (iii) \Rightarrow (ii) remains to be proved, and this will be accomplished by reducing to

Theorem 1.8 as follows. Let $\gamma \subset M \setminus L$ be a closed Reeb orbit of a contact form as in Theorem 1.11 satisfying (iii). We can consider non-degenerate C^{∞} -small perturbations of the contact form keeping $L \cup \gamma$ as periodic Reeb orbits. By Proposition 4.2 below, L bounds a GSS in class b for the perturbed Reeb flows, hence $int(\gamma, b) \neq 0$ and we are now again under the assumptions of Theorem 1.8.

Consider contact forms $\alpha_+ > \alpha_-$ on M defining the same positive contact structure ξ , a null-homologous link L transverse to ξ , and an oriented and positive Seifert surface Σ for L of genus zero. Orient L as the boundary of Σ . Denote the connected components of L by $\gamma_1, \ldots, \gamma_n$. Assume that $n \ge 2$. As in Section 3.2, we consider a conformal $d\alpha_{\pm}$ symplectic trivialization τ_{Σ} of $\xi|_L$ with respect to which a non-vanishing vector field in $T_{\gamma_i} \Sigma \cap \xi$ has winding number zero, for every i.

We assume the existence of a global conformal $d\alpha_{\pm}$ -symplectic trivialization τ_{gl} of ξ . Using τ_{gl} we can define $m_i = m(\gamma_i, \Sigma) \in \mathbb{Z}$ as the winding number of a non-vanishing vector field in $T_{\gamma_i} \Sigma \cap \xi$ computed with respect to τ_{gl} . Note that

$$-\mathrm{sl}(L,\Sigma) = \sum_{i} m_{i}.$$
(85)

With these numbers we define the interval $I(L, \Sigma, \tau_{gl}) \subset \mathbb{Z}$ as in (3). Consider also the interval

$$I_0(L, \Sigma, \tau_{\rm gl}) = [2c_0 - 2, 2(C_0 - \ell_0) + 1] \subset I(L, \Sigma, \tau_{\rm gl})$$

where C_0 is defined as in (2),

$$c_{0} = \sum_{\{\gamma \mid m(\gamma, \Sigma) + 1 < 0\}} (m(\gamma, \Sigma) + 1) \text{ and } \ell_{0} = \max\left\{0, \min_{\gamma} \{m(\gamma, \Sigma) + 1\}\right\}.$$

Below we will check that $c_0 = 2 - C_0$. Hence

$$I_0(L, \Sigma, \tau_{\rm gl}) \subset I(L, \Sigma, \tau_{\rm gl}), \quad I_0(L, \Sigma, \tau_{\rm gl}) \neq I(L, \Sigma, \tau_{\rm gl}).$$

We assume that hypotheses (H1)–(H3) and (H5) of Section 3.2 are valid. In particular, each γ_i is a closed Reeb orbit for both α_+ and α_- , both α_{\pm} orient each γ_i as the boundary of Σ , and X_{α_+} is positively transverse to Σ . We replace (H4) by the following weaker hypothesis.

(H4') The contact forms α_+, α_- are non-degenerate up to action

$$A = \sum_{k=1}^{n} \int_{\gamma_k} \alpha_+$$

and the following hold:

- (+) If $\gamma = (x, T) \in \mathcal{P}(\alpha_+)$ satisfies $T \leq A$ and $x(\mathbb{R}) \subset M \setminus L$ then also $int(\gamma, \Sigma) \neq 0$.
- (-) If $\gamma = (x, T) \in \mathcal{P}(\alpha_{-})$ satisfies $T \leq A$, $x(\mathbb{R}) \subset M \setminus L$ and its Conley– Zehnder index satisfies $\mu_{CZ}^{\tau_{gl}}(\gamma) \in I_0(L, \Sigma, \tau_{gl})$ then $int(\gamma, \Sigma) \neq 0$.

Fix $\tilde{J}_{\pm} \in \mathcal{J}(\alpha_{\pm})$. As before, by (H3) we can choose numbers $\delta_1^{\pm}, \ldots, \delta_n^{\pm} < 0$ such that

- δ_k^+ is in the spectral gap between eigenvalues with winding number 0 and 1 relative to τ_{Σ} of the asymptotic operator at γ_k given by (α_+, J_+) ,
- δ_k^- is in the spectral gap between eigenvalues with winding number 0 and 1 relative to τ_{Σ} of the asymptotic operator at γ_k given by (α_-, J_-) .

Set $\delta^{\pm} = (\delta_1^{\pm}, \dots, \delta_n^{\pm}; \emptyset)$. The main analytical fact we need to prove is the following statement analogous to Proposition 3.10.

Proposition 4.1. Assume (H1)–(H3), (H4') and (H5). If there exists a curve in the moduli space $\mathcal{M}_{\tilde{J}_+,0,\delta^+}(\gamma_1,\ldots,\gamma_n;\emptyset)$ with projection to M in the same class as Σ in $H_2(M, L)$, then there exists a curve C_- in $\mathcal{M}_{\tilde{J}_-,0,\delta^-}(\gamma_1,\ldots,\gamma_n;\emptyset)$ whose projection to M is in the same class as Σ in $H_2(M, L)$. Moreover, if \mathcal{Y} denotes the connected component of C_- in $\mathcal{M}_{\tilde{J}_-,0,\delta^-}(\gamma_1,\ldots,\gamma_n;\emptyset)$ then \mathcal{Y}/\mathbb{R} is compact.

The main consequence of Proposition 4.1 is a version of Proposition 3.16 in the present set-up.

Proposition 4.2. Let α be a contact form on M, and let $L = \gamma_1 \cup \cdots \cup \gamma_n$ be a link consisting of periodic Reeb orbits. Assume that L binds a planar open book decomposition Θ that supports $\xi = \ker \alpha$, and assume with no loss of generality that α and Θ induce the same orientation on each γ_i . Assume the existence of a global symplectic trivialization τ_{gl} of $(\xi, d\alpha)$ and use it to define $I(L, page, \tau_{gl}) \subset \mathbb{Z}$ as in (3). Suppose that

(a) for every *i*, $\mu_{CZ}^{\Theta}(\gamma_i) \geq 1$ as a prime periodic Reeb orbit of α .

Then there exists a constant

$$A > \sum_{i=1}^n \int_{\gamma_i} \alpha$$

that depends only on the triple (α, L, Θ) and has the following significance. Fix any $d\alpha$ compatible complex structure $J : \xi \to \xi$, and for each *i* choose $\delta_i < 0$ in the spectral gap of the asymptotic operator induced by (α, J) on sections of ξ along γ_i , between eigenvalues of winding number 0 and 1 with respect to a Seifert framing induced by pages of Θ . Denote $\delta = (\delta_1, \ldots, \delta_n; \emptyset)$. If

(b) every $\gamma' = (x', T') \in \mathcal{P}(\alpha)$ such that $x'(\mathbb{R}) \subset M \setminus L$, $T' \leq A$ and $\mu_{CZ}^{\tau_{gl}}(\gamma')$ is in $I(L, page, \tau_{gl})$ has non-zero algebraic intersection number with each page of Θ ,

then for any sequence $f_k \in \mathcal{F}_L$ satisfying

- $f_k \to 1$ in C^{∞} , $f_k|_L \equiv 1$ for all k,
- $f_k \alpha$ is non-degenerate for all k,

and \tilde{J}_k defined as in (8) using $f_k \alpha$ and J, there exists k_0 such that for every $k \ge k_0$ the link L binds a planar open book decomposition whose pages are global surfaces of section for the Reeb flow of $f_k \alpha$, all pages represent the same class in $H_2(M, L)$ as the pages of Θ , and are projections of curves in $\mathcal{M}_{\tilde{J}_k, 0, \delta}(\gamma_1, \ldots, \gamma_n; \emptyset)$. The proof of Proposition 4.2 is exactly the same as the proof of Proposition 3.16 given in Section 3.3, with Proposition 3.10 replaced by Proposition 4.1. We leave the details to the reader. The only novelty is to show that (b) in Proposition 4.2 implies the following: If f_k is as in the statement and k is large enough, then every periodic Reeb orbit of $f_k \alpha$ in $M \setminus L$ with action $\leq A$ and Conley–Zehnder index $\mu_{CZ}^{\tau_{gl}} \in I_0(L, \text{page}, \tau_{gl})$ has non-zero intersection number with b. This is a simple consequence of the way that Conley–Zehnder indices behave under limits.

In fact, suppose for contradiction that we can find $k_j \to \infty$ and closed Reeb orbits $\gamma'_j \subset M \setminus L$ of $f_{k_j} \alpha$ with period $\leq A$, $\mu_{CZ}^{\tau_{gl}}(\gamma'_j) \in I_0(L, \text{page}, \tau_{gl})$ and $\operatorname{int}(\gamma_j, b) = 0$. Up to choice of a subsequence we may assume that $\gamma'_j \to \gamma'$ for some closed Reeb γ' of α with period $\leq A$. If $\gamma' \subset L$ then $\mu_{CZ}^{\Theta} = 0$ holds for some component of L, which is forbidden by our assumptions. Hence $\gamma' \subset M \setminus L$ and $\operatorname{int}(\gamma', b) = 0$. Note that $I_0(L, \operatorname{page}, \tau_{gl}) = [x_0, y_0] \cap \mathbb{Z}$ where x_0, y_0 are even integers, and $I(L, \operatorname{page}, \tau_{gl}) = [x_0 - 1, y] \cap \mathbb{Z}$ where $y \in \{y_0, y_0 + 1\}$. By lower semicontinuity properties of Conley–Zehnder index, we know that $\mu_{CZ}^{\tau_{gl}}(\gamma') \in [x_0 - 2, y_0]$, but since x_0 is even we must have $\mu_{CZ}^{\tau_{gl}}(\gamma') \in [x_0 - 1, y_0] \cap \mathbb{Z} \subset I(L, \operatorname{page}, \tau_{gl})$. The existence of the orbit γ' contradicts assumption (b).

Proof of Theorem 1.11 *assuming Proposition* 4.2. By Theorem 1.8, it suffices to show that if all periodic Reeb orbits in $M \setminus L$ satisfying $\mu_{CZ}^{\tau_{gl}} \in I(L, \text{page}, \tau_{gl})$ have non-zero intersection number with b, then all periodic Reeb orbits in $M \setminus L$ have non-zero intersection number with b.

Let $\gamma = (x, T) \in \mathcal{P}(\alpha)$ satisfy $x(\mathbb{R}) \subset M \setminus L$ and assume for contradiction that $\operatorname{int}(\gamma, b) = 0$. Choose a sequence $f_k \in \mathcal{F}_L$ that satisfies (i) $f_k \to 1$ in C^{∞} and $f_k|_L \equiv 1$ for all k; (ii) $f_k \alpha$ is non-degenerate for all k; and (iii) $f_k|_{x(\mathbb{R})} \equiv 1$ and $df_k|_{x(\mathbb{R})} \equiv 0$ for all k. In particular, $\gamma \in \mathcal{P}(f_k \alpha)$ for all k. We can apply Proposition 4.2 to conclude that L bounds a global surface of section representing the class b when k is large enough. This forces $\operatorname{int}(\gamma, b) \neq 0$, which is a contradiction.

The remainder of this section consists of the proof of Proposition 4.1.

Lemma 4.3. The following identity holds:

$$\sum_{i=1}^{n} (m_i + 1) = 2.$$
(86)

Proof. Let Z be a section of $\xi|_{\Sigma}$ such that Z is non-vanishing and tangent to Σ on a neighborhood of $\partial \Sigma = L$ in Σ . After a C^{∞} -small perturbation we may assume that Z has only finitely many zeros, all of which are non-degenerate. By standard degree theory, the algebraic count of zeros of Z is equal to $\sum_{i=1}^{n} m_i$.

Now observe that $\operatorname{sl}(L, \Sigma)$ does not depend on the Seifert surface Σ since ξ is trivial. It does not depend either on the choice of global trivialization, while each individual term $m(\gamma, \Sigma)$ does. Moreover, by (H2) the Reeb vector field of α_+ is transverse to $\Sigma \setminus \partial \Sigma$. In particular, the projection of Z to Σ along X_{α_+} over points of $\Sigma \setminus \partial \Sigma$ is a vector field Z' on $\Sigma \setminus \partial \Sigma$ which coincides with Z near $L = \partial \Sigma$, and whose zeros (together with their
signs) coincide with those of Z. The Poincaré–Hopf theorem asserts that the algebraic count of zeros of Z' is the Euler characteristic of Σ , which is equal to 2 - n since Σ is an *n*-holed 2-sphere. We conclude that $\sum_{i=1}^{n} m_i = 2 - n$ as desired.

Corollary 4.4. We have $0 \le \ell_0 \le 1$ and $C_0 \ge 2$.

Proof. By definition $\ell_0 \ge 0$. Using the lemma and the definition of ℓ_0 we get

$$\ell_0 \ge 2 \implies m_i + 1 \ge 2, \forall i \implies 2 = \sum_{i=1}^n (m_i + 1) \ge 2n,$$

contradicting our standing hypothesis $n \ge 2$. The inequality $C_0 \ge \sum_{i=1}^{n} (m_i + 1) = 2$ follows directly from the definition of C_0 .

Our choice of δ_i^{\pm} implies that

$$\mu_{CZ}^{\tau_{\Sigma},\delta_{i}^{-}}(\gamma_{i}) = 1 \quad \text{where } \gamma_{i} \text{ is seen as a closed Reeb orbit of } \alpha_{+},$$
$$\mu_{CZ}^{\tau_{\Sigma},\delta_{i}^{-}}(\gamma_{i}) = 1 \quad \text{where } \gamma_{i} \text{ is seen as a closed Reeb orbit of } \alpha_{-},$$

and

 $\mu_{CZ}^{\tau_{gl},\delta_i^+}(\gamma_i) = 2m_i + 1 \quad \text{where } \gamma_i \text{ is seen as a closed Reeb orbit of } \alpha_+,$ $\mu_{CZ}^{\tau_{gl},\delta_i^-}(\gamma_i) = 2m_i + 1 \quad \text{where } \gamma_i \text{ is seen as a closed Reeb orbit of } \alpha_-,$

for all *i*. We get

$$\sum_{i=1}^{n} (\mu_{\text{CZ}}^{\tau_{\text{gl}}, \delta_i^{\pm}}(\gamma_i) + 1) = \sum_{i=1}^{n} (2m_i + 2) = 4,$$
(87)

in view of Lemma 4.3. Again by Lemma 4.3 and the assumption $n \ge 2$, we have

$$c_0 + C_0 = 2, \quad c_0 \le 0, \quad 0 \le \ell_0 \le 1 \quad \text{and} \quad C_0 \ge 2.$$
 (88)

Denote by

 $c = 2c_0 - 2 \le -2$ and $C = 2(C_0 - \ell_0) + 1 \ge 3$ (89)

the end points of the interval $I_0(L, \Sigma, \tau_{gl})$.

Choose *h* and Ω as in Section 2.2.2. Then we can consider the energy (10) of a \overline{J} -holomorphic map whenever $\overline{J} \in \mathcal{J}_{\Omega,L}(\widetilde{J}_-, \widetilde{J}_+)$. Let $\widetilde{u} = (a, u) : S^2 \setminus \Gamma \to \mathbb{R} \times M$ be a finite-energy \overline{J} -holomorphic map with $E(\widetilde{u}) \leq A$, where Γ is the set of non-removable punctures. In the following for any such map we split

$$\Gamma = \Gamma^b \cup \Gamma^+ \cup \Gamma^- \tag{90}$$

where Γ^{b} is the set of positive punctures of \tilde{u} whose asymptotic limits are simple and coincide with one of the components of *L*. The set Γ^{+} consists of the remaining positive punctures of \tilde{u} and Γ^{-} is the set of negative punctures of \tilde{u} .

Theorem 4.5 (Dragnev [12], Hofer–Wysocki–Zehnder [24], Wendl [46]). There is a dense subset $\mathcal{J}_{\text{reg}} \subset \mathcal{J}_{\Omega,L}(\tilde{J}_{-}, \tilde{J}_{+})$ such that if $\tilde{u} = (a, u) : S^2 \setminus \Gamma \to \mathbb{R} \times M$ is a somewhere injective \bar{J} -holomorphic curve for some $\bar{J} \in \mathcal{J}_{\text{reg}}$, satisfying

- (i) $E(\tilde{u}) \leq A$,
- (ii) $\Gamma^b \neq \emptyset$, $\Gamma^+ = \emptyset$, $\Gamma^- \neq \emptyset$,
- (iii) $u(S^2 \setminus \Gamma) \subset M \setminus L$,
- (iv) wind_{∞}($\tilde{u}, z, \tau_{\Sigma}$) = 0 for all $z \in \Gamma^b$,

then

$$0 \le -2 + \#\Gamma + \sum_{z \in \Gamma^b} (2m_z + 1) - \sum_{z \in \Gamma^-} \mu_{\text{CZ}}(P_z).$$
(91)

Here $m_z := m_i$ whenever \tilde{u} is asymptotic to $\gamma_i \subset L$ at $z \in \Gamma^b$, and the α_- -closed Reeb orbit P_z is the asymptotic limit of \tilde{u} at $z \in \Gamma^-$.

From now on we fix $\overline{J} \in \mathcal{J}_{\text{reg}}$ and an ordered set $\Gamma_0 \subset S^2$ with $\#\Gamma_0 = n$. We write $\mathcal{M}_{\tilde{J}_+,0,\delta^+}, \mathcal{M}_{\tilde{J}_-,0,\delta^-}$ and $\mathcal{M}_{\tilde{J},0,\delta^+}$ instead of $\mathcal{M}_{\tilde{J}_+,0,\delta^+}(\gamma_1,\ldots,\gamma_n;\emptyset)$ etc. for simplicity of notation. For the same reason we write I_0 instead of $I_0(L, \Sigma, \tau_{\text{gl}})$. Let $C_+ \in \mathcal{M}_{\tilde{J}_+,0,\delta^+}$ be the curve whose existence is assumed in the statement of Proposition 4.1. After translating up in the \mathbb{R} -direction, we can also view C_+ as an element of $\mathcal{M}_{\tilde{J},0,\delta^+}$; see Remark 3.2. Since (H4')(+) is the same as (H4)(+), we can invoke Lemma 3.14 to obtain a sequence

$$C_l = [\tilde{v}_l = (b_l, v_l), S^2, j_l, \Gamma_0, \emptyset]$$
(92)

in the same connected component of C_+ satisfying

$$\lim_{l \to \infty} \min b_l = -\infty. \tag{93}$$

By SFT-compactness (see Section 2.2.9), up to choice of a subsequence we may assume that C_l converges to a holomorphic building

$$\mathbf{u} = \{\{\widetilde{u}_m = (a_m, u_m), S_m, j_m, \Gamma_m^+, \Gamma_m^-, D_m)\}, \{\Phi_m\}\}, \quad m \in \{-k_-, \dots, k_+\},\$$

of height $k_{-}|1|k_{+}$, with $k_{-} > 0$. We shall prove that $k_{+} = 0$, $k_{-} = 1$, \tilde{u}_{0} coincides with $\mathbb{R} \times L$, and \tilde{u}_{-1} represents the desired C_{-} . This is accomplished by the sequence of claims listed below.

Claim I. Every asymptotic limit γ of **u** contained in $M \setminus L$ satisfies $\mu_{CZ}^{\tau_{gl}}(\gamma) \in \mathbb{Z} \setminus I_0$ and $int(\gamma, \Sigma) = 0$. In particular, every asymptotic limit which is a closed Reeb orbit of α_+ is contained in L.

Proof. We argue indirectly and assume that there exists a level of **u** containing an asymptotic limit $\gamma = (x, T)$ in $M \setminus L$ such that $\mu_{CZ}^{\tau_{gl}}(\gamma) \in I_0$ or $int(\gamma, \Sigma) \neq 0$. The action of every asymptotic limit of **u** is bounded from above by A. This follows from the energy bounds for the sequence \tilde{v}_l . Using hypothesis (H4') we conclude that $int(\gamma, \Sigma) \neq 0$. For every large l we find an embedded loop $\beta_l : \mathbb{R}/\mathbb{Z} \to S^2 \setminus \Gamma_0$ such that $v_l \circ \beta_l$ is C^0 -close

to the loop $t \mapsto x(Tt)$. But Proposition 3.8 and positivity of intersections imply that C_l can be homotoped to $C_+ = [\tilde{u}_+ = (a_+, u_+), S^2, j, \Gamma_0, \emptyset]$ in $M \setminus L$. By Proposition 3.4, u_+ is a proper embedding of $S^2 \setminus \Gamma_0$ into $M \setminus L$ inducing the same class in $H_2(M, L)$ as Σ and we obtain

$$0 = \operatorname{int}(u_{+} \circ \beta_{l}, u_{+}(S^{2} \setminus \Gamma)) = \operatorname{int}(u_{+} \circ \beta_{l}, \Sigma) = \operatorname{int}(v_{l} \circ \beta_{l}, \Sigma) = \operatorname{int}(\gamma, \Sigma) \neq 0,$$

which is a contradiction.

Define $I_0^- := (-\infty, c-1] \cap \mathbb{Z}$ and $I_0^+ := [C+1, +\infty) \cap \mathbb{Z}$, so that $I_0^- \cup I_0^+ = \mathbb{Z} \setminus I_0$.

Remark 4.6. In the statement of Claim I the number $\mu_{CZ}^{\tau_{gl}}(\gamma)$ should be understood as the Conley–Zehnder index taken with respect to the Reeb flow of α_+ or of α_- , depending on the level and on the sign of the puncture.

Claim II. If $-k_{-} \leq m \leq k_{+}$ and Y is a connected component of $S_{m} \setminus \Gamma_{m}^{+} \cup \Gamma_{m}^{-}$ such that $\tilde{w} := \tilde{u}_{m}|_{Y}$ is non-constant and its image is not contained in $\mathbb{R} \times L$, then \tilde{w} has no negative puncture whose asymptotic limit is contained in L, and the image of \tilde{w} does not intersect $\mathbb{R} \times L$.

Proof. We argue indirectly and assume that $\tilde{w} = (b, w)$ admits a negative puncture \bar{z} whose asymptotic limit is γ_i^k for some $i \in \{1, ..., n\}$ and some integer $k \ge 1$. By hypotheses, \tilde{w} has a non-trivial asymptotic formula near \bar{z} . Since $\mu_{CZ}^{\tau_{\Sigma}}(\gamma_i^k) \ge \mu_{CZ}^{\tau_{\Sigma}}(\gamma_i) \ge 1$ we find that wind $_{\infty}(\tilde{w}, \bar{z}, \tau_{\Sigma}) \ge 1$; see Theorem 2.7 for a more precise description of the behavior of \tilde{w} near \bar{z} . This implies that we can find an embedded loop $\beta : \mathbb{R}/\mathbb{Z} \to Y$ around \bar{z} such that $\operatorname{int}(w \circ \beta, \Sigma) \neq 0$. Hence for all large l we find an embedded loop $\beta_l : \mathbb{R}/\mathbb{Z} \to S^2 \setminus \Gamma$ such that $\operatorname{int}(v_l \circ \beta_l, \Sigma) \neq 0$. This leads to a contradiction as in the proof of Claim I.

Any intersection of \tilde{w} with $\mathbb{R} \times L$ must be isolated since $\mathbb{R} \times L$ is also holomorphic. By positivity and stability of intersections, such an intersection implies that C_l intersects $\mathbb{R} \times L$ for all large l. This is impossible since Proposition 3.8 and positivity of intersections together imply that C_l does not intersect $\mathbb{R} \times L$.

Claim III. $k_+ = 0$.

Proof. Assume that $k_+ > 0$. Suppose first that there exists a connected component Y of $S_{k_+} \setminus (\Gamma_{k_+}^+ \cup \Gamma_{k_+}^-)$ such that $\tilde{u}_{k_+}|_Y$ is non-constant and $\tilde{u}_{k_+}(Y) \not\subset \mathbb{R} \times L$. The asymptotic limit of \tilde{u}_{k_+} at a positive puncture z_* of $\tilde{u}_{k_+}|_Y$ is a prime closed Reeb orbit given by one of the components of L. Moreover, $\tilde{u}_{k_+}|_Y$ has a non-trivial asymptotic formula at z_* . If wind_{∞}($\tilde{u}_{k_+}, z_*, \tau_{\Sigma}$) $\neq 0$ then, by Theorem 2.7, a small embedded loop $\beta : \mathbb{R}/\mathbb{Z} \to Y \setminus (\Gamma_{k_+}^+ \cup \Gamma_{k_+}^-)$ winding once around z_* is mapped by u_{k_+} to a loop satisfying $int(u_{k_+} \circ \beta, \Sigma) \neq 0$. We find for large l an embedded loop $\beta_l : \mathbb{R}/\mathbb{Z} \to S^2 \setminus \Gamma_0$ such that $int(v_l \circ \beta_l, \Sigma) \neq 0$. As in the proof of Claim I, this fact and Proposition 3.8 lead to $int(u_+ \circ \beta_l, u_+(S^2 \setminus \Gamma)) \neq 0$, in contradiction to Proposition 3.4. Thus

$$\operatorname{wind}_{\infty}(\widetilde{u}_{k_{\pm}}, z_{\ast}, \tau_{\Sigma}) = 0 \tag{94}$$

for every positive puncture z_* of $\tilde{u}_{k_+}|_Y$. By hypothesis (H4') and Claims I and II, $\tilde{u}_{k_+}|_Y$ has no negative punctures and $u_{k_+}(Y) \subset M \setminus L$. Hypothesis (H5) and (94) together imply that the set of punctures of $\tilde{u}_{k_+}|_Y$ consists of $\Gamma_{k_+}^+$. It follows that \tilde{u}_{k_+} is constant on any other connected component of $S_{k_+} \setminus (\Gamma_{k_+}^+ \cup \Gamma_{k_+}^-)$. In particular, \tilde{u}_{k_+} has no negative punctures, in contradiction to $k_+ > 0$. We showed that for every connected component $Y \subset S_{k_+} \setminus (\Gamma_{k_+}^+ \cup \Gamma_{k_-}^-)$ the map $\tilde{u}_{k_+}|_Y$ is either constant or has image contained in $\mathbb{R} \times L$. In the latter case, $\tilde{u}_{k_+}|_Y$ is an unbranched cover of one of the cylinders $\mathbb{R} \times \gamma_i$ because asymptotic limits at distinct positive punctures of \tilde{u}_{k_+} are geometrically distinct. By the same token, if there is a component $Y' \subset S_{k_+} \setminus (\Gamma_{k_+}^+ \cup \Gamma_{k_-}^-)$ such that $\tilde{u}_{k_+}|_{Y'}$ is constant then Lemma 2.20 provides an intersection between two geometrically distinct closed Reeb orbits, and this is absurd. Hence all components of \tilde{u}_{k_+} are unbranched covers of only trivial cylinders, with no nodes or constant components, in contradiction to stability. This shows that $k_+ = 0$.

Definition 4.7. Fix a level *m* strictly below the top level and let $\Lambda \subset \Gamma_m^+$. For each $z \in \Lambda$ we consider the connected component B_z of S_m containing *z*.

- A connected component B' of S_k is said to be *directly above* Λ if k > m and if there exists z ∈ Λ such that points in B' \ (Γ_k⁺ ∪ Γ_k⁻ ∪ D_k) can be connected to points in B_z \ (Γ_m⁺ ∪ Γ_m⁻ ∪ D_m) through a path in S^{u,r} that only goes down negative punctures or passes through nodes, but never goes up a positive puncture.
- A connected component B" of S_k is said to be *above* Λ if k > m and if points in B" \ (Γ_k⁺ ∪ Γ_k⁻ ∪ D_k) can be connected to points in B' \ (Γ_j⁺ ∪ Γ_j⁻ ∪ D_j), for some B' directly above Λ, through a path in S^{u,r} that never reaches levels ≤ m.

Remark 4.8. In our particular geometric set-up, once a positive puncture z on a level below the top is fixed one can always reach a curve on the top level by only following components directly above z.

Remark 4.9. The curves given by the components above some Λ form a building, called the *(sub)building above* Λ .

Claim IV. The following assertions hold:

- Let $m \leq -1$, and let Y be a connected component of $S_m \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ such that $\tilde{u}_m|_Y$ is non-constant. If the asymptotic limit at some negative puncture of $\tilde{u}_m|_Y$ is contained in L, then there exists i such that $\tilde{u}_m|_Y$ is the trivial cylinder over γ_i , and the entire subbuilding above the (unique) positive puncture of $\tilde{u}_m|_Y$ has no nodes and consists of trivial cylinders over γ_i .
- If \tilde{u}_m has a positive puncture whose asymptotic limit is contained in L then this asymptotic limit is simply covered. Moreover, no two distinct positive punctures of \tilde{u}_m have the same asymptotic limit in L.

Proof. Let us prove the first assertion. We write $\tilde{w} = \tilde{u}_m |_Y$, and assume that there is a negative puncture of \tilde{w} whose asymptotic limit is contained in $\gamma_i \subset L$ for some $i \in \{1, ..., n\}$.

It follows directly from Claim II that the image of \tilde{w} is $\mathbb{R} \times \gamma_i$. Denote by Λ the set of positive punctures of \tilde{w} . Iterated applications of Claim II imply that the (non-constant) finite-energy maps defined on components directly above Λ (see Definition 4.7) have image $\mathbb{R} \times \gamma_i$. In particular, they are covers of $\mathbb{R} \times \gamma_i$, possibly branched. Some curve directly above Λ lying on the very top level is a trivial cylinder over γ_i since all asymptotic orbits at the top punctures of \mathbf{u} are simply covered and geometrically distinct (use Remark 4.8). This forces the subbuilding \mathbf{u}_{Λ} above Λ to have a very particular form: it has no nodes, and all its levels consist of precisely one curve which is a trivial cylinder over γ_i . Here the reader should not forget that \mathbf{u} is a limit of genus zero curves, and $\mathbb{R} \times L$ is a \overline{J} -holomorphic surface. Moreover, Lemma 2.20 is used. In particular, $\#\Lambda = 1$ and also \tilde{w} is a trivial cylinder over γ_i .

Now we address the second assertion. If m = 0 then this assertion is automatically satisfied, hence we can assume that $m \le -1$. Consider a positive puncture z^* of \tilde{u}_m whose asymptotic limit is γ_i^k for some $i \in \{1, ..., n\}$ and some $k \ge 1$. By Claim II and the first assertion of Claim IV, k = 1 and the subbuilding above z^* is formed by trivial cylinders over γ_i . If \tilde{u}_m is also asymptotic to γ_i at a positive puncture $z^{**} \ne z^*$ then, as before, the subbuilding above z^{**} is also formed by unbranched covers of $\mathbb{R} \times \gamma_i$. Since \tilde{u}_0 has only one positive puncture asymptotic to γ_i , we arrive at a contradiction to $z^* \ne z^{**}$. Hence such a puncture z^{**} cannot exist. This finishes the proof of Claim IV.

Claim V. Let Y be a connected component of $S_m \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ such that $\tilde{u} := \tilde{u}_m|_Y$ is non-constant. Assume that \tilde{u} has a positive puncture whose asymptotic limit is contained in $M \setminus L$ and satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^-$. Then $m \leq -1$ and at least one of the following alternatives holds:

- \tilde{u} contains a negative puncture whose asymptotic limit lies in $M \setminus L$ and has Conley– Zehnder index $\mu_{CZ}^{\tau_{gl}} \in I_0^-$;
- \tilde{u} contains a positive puncture whose asymptotic limit lies in $M \setminus L$ and has Conley– Zehnder index $\mu_{CZ}^{\tau_{gl}} \in I_0^+$.

Proof. We can identify $Y = S^2 \setminus \Gamma$ where Γ is the set of non-removable punctures of \tilde{u} . By Claim III we know that $m \leq 0$. If m = 0 then \tilde{u} is \bar{J} -holomorphic and asymptotic limits at its positive punctures are components of L, in conflict with the assumption on \tilde{u} . We conclude that $m \leq -1$ and \tilde{u} is \tilde{J} -holomorphic.

Consider the splitting $\Gamma = \Gamma^b \cup \Gamma^+ \cup \Gamma^-$ as in (90). By the first assertion of Claim IV and our hypotheses, every asymptotic limit of \tilde{u} at a negative puncture is contained in $M \setminus L$. By the second assertion in Claim IV, all asymptotic limits in Γ^+ are contained in $M \setminus L$, and all asymptotic limits in Γ^b are geometrically distinct. In particular, by Claim I, every asymptotic limit of \tilde{u} at a puncture in $\Gamma^+ \cup \Gamma^- = \Gamma \setminus \Gamma^b$ satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^- \cup I_0^+$ and its intersection number with Σ vanishes. By assumption, $\Gamma^+ \neq \emptyset$.

Assume, for contradiction, that no asymptotic limit at a negative puncture of \tilde{u} satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^-$ and no asymptotic limit at a puncture of \tilde{u} in Γ^+ satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^+$. It follows that the Conley–Zehnder indices of the asymptotic limits at negative punctures lie in I_0^+ and the Conley–Zehnder indices of the asymptotic limits at positive punctures in Γ^+ lie

in I_0^- . We claim that these assumptions force

$$\int_{\mathcal{S}^2 \setminus \Gamma} u^* d\alpha_- > 0. \tag{95}$$

If not then \tilde{u} is a (possibly branched) cover of $\mathbb{R} \times \beta$ for some simply covered periodic Reeb orbit β in $M \setminus L$. We claim that $int(\beta, \Sigma) = 0$. In fact, at any puncture the asymptotic limit is β^k for some $k \ge 1$. Hence

$$0 = int(\beta^k, \Sigma) = k int(\beta, \Sigma), \text{ so } 0 = int(\beta, \Sigma)$$

as claimed. By (H4') we must have $\mu_{CZ}^{\tau_{gl}}(\beta) \in I_0^- \cup I_0^+$. We can estimate

$$\mu_{CZ}^{\tau_{gl}}(\beta) \in I_0^- \Rightarrow \mu_{CZ}^{\tau_{gl}}(\beta) < 0 \Rightarrow \mu_{CZ}^{\tau_{gl}}(\beta^k) < 0 \ \forall k \ge 1 \Rightarrow \mu_{CZ}^{\tau_{gl}}(\beta^k) \in I_0^- \ \forall k \ge 1,$$

$$\mu_{CZ}^{\tau_{gl}}(\beta) \in I_0^+ \Rightarrow \mu_{CZ}^{\tau_{gl}}(\beta) > 0 \Rightarrow \mu_{CZ}^{\tau_{gl}}(\beta^k) > 0 \ \forall k \ge 1 \Rightarrow \mu_{CZ}^{\tau_{gl}}(\beta^k) \in I_0^+ \ \forall k \ge 1.$$

$$(96)$$

In particular, all asymptotic limits satisfy either $\mu_{CZ}^{\tau_{gl}} \in I_0^-$ or $\mu_{CZ}^{\tau_{gl}} \in I_0^+$, in conflict to the contradiction assumption made on \tilde{u} . This finishes the proof of (95).

As consequence of (95), \tilde{u} has a non-trivial asymptotic formula at every puncture since $Y = S^2 \setminus \Gamma$ is connected. We can then argue that wind_{∞}($\tilde{u}, z, \tau_{\Sigma}$) = 0 for every $z \in \Gamma^b$ since otherwise for *l* large we find loops in the image of the *M*-component v_l which intersect Σ non-trivially, contradicting a combination of Propositions 3.4 and 3.8 as in the proof of Claim II. We have

$$\sum_{z \in \Gamma^b} (\operatorname{wind}_{\infty}(\tilde{u}, z, \tau_{gl}) + 1) = \sum_{z \in \Gamma^b} (\operatorname{wind}_{\infty}(\tilde{u}, z, \tau_{\Sigma}) + m_z + 1)$$
$$= \sum_{z \in \Gamma^b} (m_z + 1) \le C_0 - \ell_0,$$

where $m_z = m_i$ if \tilde{u} is asymptotic to γ_i at $z \in \Gamma^b$. The last inequality above is explained as follows. Since **u** has arithmetic genus zero, \tilde{u} has at most *n* positive punctures; this relies on the fact that the domain of \tilde{u} is connected and that $S^{\mathbf{u},r}$ is also connected. Moreover, the assumptions on \tilde{u} imply that $\#\Gamma^b \leq n - 1$, i.e. Γ^b misses at least one binding orbit γ_i . By Corollary 4.4 we have $0 \leq \ell_0 \leq 1$, hence by the definition of C_0 in (2) the sum $\sum_{z \in \Gamma^b} (m_z + 1)$ is bounded from above by $C_0 - \ell_0$.

Let us denote by P_z the asymptotic limit of \tilde{u} at the puncture $z \in \Gamma$. Since $\mu_{CZ}^{\tau_{gl}}(P_z) \le c-1 = 2(c_0-2)+1$ for all $z \in \Gamma^+$, we have

wind_{$$\infty$$}(\tilde{u}, z, τ_{gl}) $\leq c_0 - 2 \quad \forall z \in \Gamma^+$,

hence

$$\sum_{z \in \Gamma^+} \operatorname{wind}_{\infty}(\widetilde{u}, z, \tau_{gl}) \le (c_0 - 2) \, \# \Gamma^+.$$

Since $\mu_{CZ}^{\tau_{\text{gl}}}(P_z) \ge C + 1 = 2(C_0 - \ell_0 + 1)$ for all $z \in \Gamma^-$, we have

wind_{$$\infty$$}(\tilde{u}, z, τ_{gl}) $\geq C_0 - \ell_0 + 1 \quad \forall z \in \Gamma^-$

hence

$$-\sum_{z\in\Gamma^{-}}\operatorname{wind}_{\infty}(\widetilde{u},z,\tau_{\mathrm{gl}}) \leq -(C_{0}-\ell_{0}+1)\,\#\Gamma^{-}$$

Plugging these inequalities into

$$0 \le \operatorname{wind}_{\pi}(\widetilde{u}) = -2 + \#\Gamma + \sum_{z \in \Gamma^{b} \cup \Gamma^{+}} \operatorname{wind}_{\infty}(\widetilde{u}, z, \tau_{gl}) - \sum_{z \in \Gamma^{-}} \operatorname{wind}_{\infty}(\widetilde{u}, z, \tau_{gl})$$
(97)

we obtain, in view of Lemma 4.3,

$$0 \le C_0 - \ell_0 + (c_0 - 1) \#\Gamma^+ - (C_0 - \ell_0) \#\Gamma^- - 2$$

= $(C_0 - \ell_0)(1 - \#\Gamma^-) + (c_0 - 1) \#\Gamma^+ - 2$
 $\le (C_0 - \ell_0) + (c_0 - 1) - 2$
 $\le C_0 + c_0 - 3 = -1$

where in the third line we used $c_0 - 1 < 0$ (see (88)). This contradiction concludes the proof of Claim V.

Claim VI. Let Y be a connected component of $S_m \setminus (\Gamma_m^+ \cup \Gamma_m^-)$ such that $\tilde{u} := \tilde{u}_m|_Y$ is non-constant. Assume that \tilde{u} has a negative puncture whose asymptotic limit is contained in $M \setminus L$ and has Conley–Zehnder index $\mu_{CZ}^{\tau_{gl}} \in I_0^+$. Then at least one of the following alternatives holds:

- \tilde{u} contains a negative puncture whose asymptotic limit lies in $M \setminus L$ and has $\mu_{CZ}^{\tau_{gl}} \in I_0^-$;
- \tilde{u} contains a positive puncture whose asymptotic limit lies in $M \setminus L$ and has $\mu_{CZ}^{\tau_{gl}} \in I_0^+$. Moreover, if m = 0 then the first alternative holds.

Proof. We can identify $Y = S^2 \setminus \Gamma$, where Γ consists of non-removable punctures of \tilde{u} . Write the components as $\tilde{u} = (a, u)$, and consider the splitting $\Gamma = \Gamma^b \cup \Gamma^+ \cup \Gamma^-$ as in (90). Claim III implies $m \leq 0$. The assumptions on \tilde{u} imply that its image is not contained in $\mathbb{R} \times L$. By Claim II all asymptotic limits at negative punctures are contained in $M \setminus L$. All asymptotic limits at punctures in Γ^+ are contained in $M \setminus L$, in fact if m = 0 this is true because Γ^+ is empty in this case, and if m < 0 then this follows from the second assertion of Claim IV.

Our argument is indirect and we proceed assuming that no asymptotic limit at a negative puncture of \tilde{u} has Conley–Zehnder index in I_0^- , and no asymptotic limit at a positive puncture in Γ^+ has Conley–Zehnder index in I_0^+ . Hence, by Claim I, asymptotic limits at negative punctures satisfy $\mu_{CZ}^{\tau_{gl}} \in I_0^+$ and have zero intersection number with Σ , and asymptotic limits at punctures in Γ^+ satisfy $\mu_{CZ}^{\tau_{gl}} \in I_0^-$ and have zero intersection number with Σ . We consider two cases: m = 0 and m < 0.

Assume m = 0, in which case \tilde{u} is \bar{J} -holomorphic. Every asymptotic limit at a positive puncture of \tilde{u} is a simply covered orbit in L, and such asymptotic limits are mutually distinct. In particular, $\Gamma^+ = \emptyset$ and \tilde{u} is somewhere injective. By assumption $\Gamma^- \neq \emptyset$. Moreover, \tilde{u} has a non-trivial asymptotic formula as in Theorem 2.7 at its punctures, and wind_{∞}($\tilde{u}, z, \tau_{\Sigma}$) = 0 for all $z \in \Gamma^b$ (by the same argument as in the proof of Claim II). Denote by P_z the asymptotic limit at $z \in \Gamma$. From wind_{∞}($\tilde{u}, z, \tau_{\Sigma}$) = 0 for all $z \in \Gamma^b$ we get wind_{∞}(\tilde{u}, z, τ_{gl}) = m_z for all $z \in \Gamma^b$ where $m_z = m_i$ if \tilde{u} is asymptotic to γ_i at $z \in \Gamma^b$. We get

$$\sum_{z \in \Gamma^b} (2m_z + 1) = 2 \sum_{z \in \Gamma^b} (m_z + 1) - \#\Gamma^b \le 2C_0 - \#\Gamma^b.$$

and

$$\sum_{z \in \Gamma^{-}} \mu_{\rm CZ}(P_z) \le -2(C_0 - \ell_0 + 1) \, \#\Gamma^{-}.$$

Using Theorem 4.5 we can estimate

$$0 \le 2C_0 - \#\Gamma^b - 2(C_0 - \ell_0 + 1) \#\Gamma^- - 2 + \#\Gamma^b + \#\Gamma^-$$

= $(2\ell_0 - 1 - 2C_0) \#\Gamma^- + 2C_0 - 2.$ (98)

By Corollary 4.4 we know that $2\ell_0 - 1 - 2C_0 \le -3$. Hence the expression on the righthand side of (98) strictly decreases when $\#\Gamma^-$ increases. When $\#\Gamma^- = 1$ this expression is strictly negative, no matter what the value of $\ell_0 \in \{0, 1\}$ is. This is in contradiction to (98).

Now we handle the case $m \leq -1$. In this case \tilde{u} is \tilde{J}_{-} -holomorphic. We split the argument into two subcases: $\Gamma^b \neq \emptyset$ and $\Gamma^b = \emptyset$.

Assume first that $\Gamma^b \neq \emptyset$. At all punctures \tilde{u} has a non-trivial asymptotic formula as in Theorem 2.7, $u^* d\alpha_-$ does not vanish identically, and wind_{∞}($\tilde{u}, z, \tau_{\Sigma}$) = 0 for all $z \in \Gamma^b$ just as before. Denote by P_z the asymptotic limit of \tilde{u} at $z \in \Gamma$. We have

$$\sum_{z\in\Gamma^b} (\operatorname{wind}_{\infty}(\tilde{u}, z, \tau_{\mathrm{gl}}) + 1) = \sum_{z\in\Gamma^b} (m_z + 1) \le C_0,$$

where $m_z = m_i$ if \tilde{u} is asymptotic to γ_i at $z \in \Gamma^b$. Furthermore, since

$$\mu_{\text{CZ}}^{\tau_{\text{gl}}}(P_z) \le c - 1 = 2(c_0 - 2) + 1 \quad \forall z \in \Gamma^+,$$

we have wind_{∞}(\tilde{u}, z, τ_{gl}) $\leq c_0 - 2$ for all $z \in \Gamma^+$. Hence

$$\sum_{z \in \Gamma^+} \operatorname{wind}_{\infty}(\widetilde{u}, z, \tau_{gl}) \le (c_0 - 2) \, \# \Gamma^+.$$

Now since $\mu_{CZ}(P_z) \ge C + 1 = 2(C_0 - \ell_0 + 1)$ for all $z \in \Gamma^-$, we must necessarily have wind_ $\infty(\tilde{u}, z, \tau_{gl}) \ge C_0 - \ell_0 + 1$ for all $z \in \Gamma^-$. Hence

$$-\sum_{z\in\Gamma^{-}}\operatorname{wind}_{\infty}(\widetilde{u},z,\tau_{\mathrm{gl}}) \leq -(C_{0}-\ell_{0}+1)\,\#\Gamma^{-}.$$

Combining these inequalities with Remark 2.12, with $c_0 \leq 0$ and with $\Gamma^- \geq 1$ we obtain

$$0 \le \operatorname{wind}_{\pi}(\widetilde{u}) = -2 + \#\Gamma + \operatorname{wind}_{\infty}(\widetilde{u})$$

$$\le C_0 + (c_0 - 1) \#\Gamma^+ - (C_0 - \ell_0) \#\Gamma^- - 2$$

$$\le \ell_0 - 2 - (C_0 - \ell_0)(\#\Gamma^- - 1) \le -1,$$

which is a contradiction.

Now assume $\Gamma^b = \emptyset$. Then all asymptotic limits of \tilde{u} are contained in $M \setminus L$. Note that $u^* d\alpha_-$ does not vanish identically. In fact, if it did then \tilde{u} would be a (possibly branched) cover of $\mathbb{R} \times \beta$ over some prime periodic Reeb orbit $\beta \subset M \setminus L$ satisfying $\operatorname{int}(\beta^k, \Sigma) = 0$ for all $k \ge 0$. Arguing as in Claim V using (H4') (see (96)), we would conclude that either $\mu_{CZ}^{\tau_{gl}}(\beta^k) \in I_0^+$ for all $k \ge 1$ or $\mu_{CZ}^{\tau_{gl}}(\beta^k) \in I_0^-$ for all $k \ge 1$, in conflict with the contradiction assumption made on \tilde{u} .

Denote by P_z the asymptotic limit of \tilde{u} at $z \in \Gamma$. Arguing as in the previous subcase we find

 $\operatorname{wind}_{\infty}(\widetilde{u}, z, \tau_{\mathrm{gl}}) \leq c_0 - 2 \; \forall z \in \Gamma^+, \quad \operatorname{wind}_{\infty}(\widetilde{u}, z, \tau_{\mathrm{gl}}) \geq C_0 - \ell_0 + 1 \; \forall z \in \Gamma^-.$

Hence

$$\sum_{z \in \Gamma^+} \operatorname{wind}_{\infty}(\tilde{u}, z, \tau_{\operatorname{gl}}) \le (c_0 - 2) \, \# \Gamma^+$$

and

$$-\sum_{z\in\Gamma^{-}}\operatorname{wind}_{\infty}(\widetilde{u},z,\tau_{\mathrm{gl}}) \leq -(C_{0}-\ell_{0}+1)\,\#\Gamma^{-}$$

Combining these inequalities with Remark 2.12 we obtain

$$0 \le \operatorname{wind}_{\pi}(\widetilde{u}) \le (c_0 - 1) \# \Gamma^+ - (C_0 - \ell_0) \# \Gamma^- - 2 < 0,$$

which is a contradiction. The proof of Claim VI is now complete.

Claim VII. We have $k_{-} = -1$, and moreover all asymptotic limits of \tilde{u}_{-1} at its positive punctures are contained in L, are simply covered, and mutually distinct.

Proof. Assume that $k_{-} \leq -2$. We shall prove that this forces $\bigsqcup_{m} S_{m}$ to have an infinite number of connected components.

Let Y_0 be a connected component of $S_{k-} \setminus (\Gamma_{k-}^+ \cup \Gamma_{k-}^-)$ such that $\tilde{w}_0 := \tilde{u}_{k-}|_{Y_0}$ is non-constant. We can identify $Y_0 = S^2 \setminus \Gamma$ where Γ is the set of non-removable punctures. All punctures in Γ are positive, and the image \tilde{w}_0 is not contained in $\mathbb{R} \times L$. We can pick Y_0 in such a way that one of the asymptotic limits of \tilde{w}_0 lies in $M \setminus L$. Indeed, if not then by Claim IV every level \tilde{u}_j , $k_- + 1 \leq j \leq -1$, is formed by trivial cylinders in $\mathbb{R} \times L$. Together with the assumption $k_- \leq -2$ and the stability condition, this implies that in every level $k_- < m < 0$ strictly between the bottom level and the top level there is a constant component, and possibly many nodes (at least three). Combining this with the genus zero assumption, it follows that at the top level there are at least two distinct positive punctures with geometrically equal asymptotic limits, and this contradicts the fact that all asymptotic limits at the positive punctures of the top level are geometrically distinct orbits in L. Moreover, \tilde{w}_0 does not intersect $\mathbb{R} \times L$ by Claim II. Claim I implies that asymptotic limits of \tilde{w}_0 in $M \setminus L$ must have Conley–Zehnder index $\mu_{CZ}^{\tau_{gl}}$ in $I_0^- \cup I_0^+$ and its intersection number with Σ vanishes.

Claim V provides at least one asymptotic limit at a positive puncture of \tilde{w}_0 which lies in $M \setminus L$ and satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^+$. Denote this asymptotic limit by γ . Now we find a connected component Y_1 of $S_{k-1} \setminus (\Gamma_{k-1}^+ \cup \Gamma_{k-1}^-)$ such that $\tilde{w}_1 := \tilde{u}_{k-1}|_{Y_1}$ has γ as asymptotic limit at a negative puncture. In particular, since $\mu_{CZ}^{\tau_{gl}}(\gamma) \in I_0^+$, Claim VI applies and at least one of the following holds:

- (i) \tilde{w}_1 has a negative puncture whose asymptotic limit lies in $M \setminus L$ and has Conley– Zehnder index in I_0^- ;
- (ii) \tilde{w}_1 has a positive puncture whose asymptotic limit lies in $M \setminus L$ and has Conley–Zehnder index in I_0^+ .

In case (i) we find a finite-energy map \tilde{w}_2 corresponding to a connected component Y_2 of $S_{k_{-}} \setminus (\Gamma_{k}^{+} \cup \Gamma_{k}^{-})$ which has a positive puncture whose asymptotic limit lies in $M \setminus L$ and its Conley–Zehnder index lies in I_0^- . In case (ii) we find a finite-energy map \tilde{w}_2 corresponding to a connected component Y_2 of $S_{k-2} \setminus (\Gamma_{k-2}^+ \cup \Gamma_{k-2}^-)$ which has a negative puncture whose asymptotic limit lies in $M \setminus L$ and has Conley–Zehnder index in I_0^+ . Back to case (i) we apply Claim V to obtain a positive puncture of \widetilde{w}_2 whose asymptotic limit lies in $M \setminus L$ and has Conley–Zehnder index in I_0^+ . This gives the next element \tilde{w}_3 of the sequence. Back to case (ii) we apply Claim VI to again obtain two possibly non-excluding possibilities: \tilde{w}_2 has a negative puncture whose asymptotic limit lies in $M \setminus L$ and has Conley–Zehnder index in I_0^- , or there is a positive puncture of \tilde{w}_2 whose asymptotic limit lies in $M \setminus L$ and has Conley–Zehnder index in I_0^+ . We choose one of the possibilities that apply; in the first case we go down a level and in the second case we go up a level, hence obtaining the next element \tilde{w}_3 of the sequence. Our procedure to find the next element of the sequence can be indefinitely continued: from \widetilde{w}_i one changes the level by +1 or -1 in order to find \tilde{w}_{i+1} for which Claim V or Claim VI applies. This allows us to construct a sequence \widetilde{w}_i . One always goes up a level through a positive puncture whose asymptotic limit is in $M \setminus L$ and satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^+$, or goes down a level through a negative puncture whose asymptotic limit is in $M \setminus L$ and satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^-$. Since the arithmetic genus of the building **u** is zero, whenever $i \neq j$ the domains of \tilde{w}_i and \widetilde{w}_j are distinct connected components of $\bigsqcup_m S_m \setminus (\Gamma_m^+ \cup \Gamma_m^-)$. Hence $\bigsqcup_m S_m$ has infinitely many connected components, which is absurd. We have proved that $k_{-} = -1$.

Now assume, for contradiction, that a \tilde{J}_{-} -holomorphic finite-energy map corresponding to the restriction of \tilde{u}_{-1} to a connected component of $S_{-1} \setminus (\Gamma_{-1}^+ \cup \Gamma_{-1}^-)$ has a positive puncture whose asymptotic limit lies in $M \setminus L$. By Claims I and V we can assume that such an asymptotic limit satisfies $\mu_{CZ}^{\tau_{gl}} \in I_0^+$. Using the same procedure as before, one finds that $S_0 \sqcup S_{-1}$ has infinitely many connected components, which is absurd. Now it is easy to argue, using Claim II, that asymptotic limits at Γ_{-1}^+ are geometrically distinct simply covered components of L.

Claim VIII. *The top level is precisely* $\mathbb{R} \times L$ *.*

Proof. Assume there exists a connected component Y of $S_0 \setminus (\Gamma_0^+ \cup \Gamma_0^-)$ such that $\tilde{u} = \tilde{u}_0|_Y$ is non-constant and its image is not contained in $\mathbb{R} \times L$. By Claim II the asymptotic limits at the negative punctures of \tilde{u} lie in $M \setminus L$, in contradiction to Claim VII. In particular, \tilde{u} has no negative punctures. Arguing as in the proof of Claim III, relying on hypothesis (H5), we conclude that all positive punctures of \tilde{u}_0 are punctures of \tilde{u} . Moreover, \tilde{u}_0 is constant on every other connected component of $S_0 \setminus (\Gamma_0^+ \cup \Gamma_0^-)$. In particular,

 \tilde{u}_0 has no negative punctures, and this is absurd. We conclude that every connected component of \tilde{u}_0 either corresponds to a constant curve or to a curve whose image is contained in $\mathbb{R} \times \gamma_i$ for some $i \in \{1, \ldots, n\}$. In the former case, Lemma 2.20 provides an intersection between two geometrically distinct closed Reeb orbits in *L*, which is again an absurd. Hence the latter case holds and each component of the level \tilde{u}_0 is a trivial cylinder over some γ_i . Claim VIII is proved.

Claim IX. The level \tilde{u}_{-1} provides an element of $\mathcal{M}_{\tilde{I}_{-0,\delta^{-}}}(\gamma_{1},\ldots,\gamma_{n};\emptyset)$.

Proof. Let $\tilde{u}: S^2 \setminus \Gamma \to \mathbb{R} \times M$ be a non-constant \tilde{J}_- -holomorphic map given by the restriction of \tilde{u}_{-1} to a connected component of $S_{-1} \setminus (\Gamma_{-1}^+ \cup \Gamma_{-1}^-)$; here Γ is the set of its (non-removable) punctures. By Claim VII, \tilde{u} has no negative punctures and it is asymptotic to distinct simply covered components of L at its positive punctures. Moreover, \tilde{u} does not intersect $\mathbb{R} \times L$ (Claim II). Hence \tilde{u} has a non-trivial asymptotic formula near each of its positive punctures. We claim that wind_{∞} $(\tilde{u}, z, \tau_{\Sigma}) = 0$ for every $z \in \Gamma$. This can be proved by recasting the argument for Claim III. In fact, if not then we can use Theorem 2.7 to find, for l large enough, a loop β_l in the domain of \tilde{v}_l such that $int(v_l \circ \beta_l, \Sigma) \neq i$ 0. By Proposition 3.8 we can homotope \tilde{v}_l to \tilde{u}_+ (the map representing C_+) in the complement of $\mathbb{R} \times L$. We conclude that the algebraic intersection number of the image under u_+ of a loop in the domain of \tilde{u}_+ with the image of u_+ is non-zero, in contradiction to Proposition 3.4 stating that u_+ is an embedding into $M \setminus L$. Hypothesis (H5) implies that $\Gamma = \Gamma_{-1}^+$, i.e. the asymptotic limits of \tilde{u} are mutually geometrically distinct and consist of all components of L. Hence any other component of \tilde{u}_0 is constant. The existence of such a constant component leads to a contradiction given by an application of Lemma 2.20. Hence \tilde{u}_0 has only one connected component represented by \tilde{u} . The curve \tilde{u} represents the desired element in $\mathcal{M}_{\tilde{J}_{-},0,\delta^{-}}(\gamma_1,\ldots,\gamma_n;\emptyset)$: the correct exponential decay to the γ_i at the positive punctures follows from wind_{∞}($\tilde{u}, z, \tau_{\Sigma}$) = 0 for all $z \in \Gamma = \Gamma_{-1}^+$.

This finishes the proof of Proposition 4.1, and hence also of Theorem 1.11.

Appendix A. Intersection and linking

Let *M* be an oriented 3-manifold and $\Sigma \subset M$ be an embedded compact oriented surface. Denote $L = \partial \Sigma$, and orient *L* by Σ . Let *N* be a small closed tubular neighborhood of *L* and choose a diffeomorphism $\Psi : N \to L \times \mathbb{C}$ satisfying

- (T1) Ψ is orientation preserving if N is oriented by M and $L \times \mathbb{C}$ is oriented as a product; here \mathbb{C} is given its canonical orientation;
- (T2) $\Psi(N \cap \Sigma) = L \times [0, +\infty).$

Consider a smooth map $\tilde{u} = (a, u) : \mathbb{D} \to \mathbb{R} \times N$ satisfying $\tilde{u}(\partial \mathbb{D}) \cap (\mathbb{R} \times L) = \emptyset$. We orient $\mathbb{D} \subset \mathbb{C}$ by \mathbb{C} , the real line \mathbb{R} by its canonical orientation and $\mathbb{R} \times M$, $\mathbb{R} \times L$ as products. The following simple statement is used in the compactness analysis from Section 3.2.

Lemma A.1. We have

$$\operatorname{int}'(\widetilde{u}_*[\mathbb{D}], \mathbb{R} \times L) = \operatorname{int}((u|_{\partial \mathbb{D}})_*[\partial \mathbb{D}], \Sigma)$$

where $[\mathbb{D}] \in H_2(\mathbb{D}, \partial\mathbb{D})$ and $[\partial\mathbb{D}] \in H_1(\partial\mathbb{D})$ denote the corresponding fundamental classes, the homomorphism $\operatorname{int}'(\cdot, \mathbb{R} \times L) : H_2(\mathbb{R} \times M, \mathbb{R} \times (M \setminus L)) \to \mathbb{Z}$ counts oriented intersections with $\mathbb{R} \times L$, and $\operatorname{int} : H_1(M \setminus L) \otimes H_2(M, L) \to \mathbb{Z}$ is the oriented intersection count pairing.

Proof. Let $z : \mathbb{D} \to \mathbb{C}$ denote the \mathbb{C} -component of $\Psi \circ u$. Note that $z(e^{i2\pi t}) \neq 0$ for all t. In view of our choices of orientations, $\operatorname{int}'(\tilde{u}_*[\mathbb{D}], \mathbb{R} \times L)$ is equal to the algebraic count of zeros of the map $z : \mathbb{D} \to \mathbb{C}$. By standard degree theory, this is equal to the winding number around the origin of the loop $\mathbb{R}/\mathbb{Z} \ni t \mapsto z(e^{i2\pi t})$. This winding number coincides with $\operatorname{int}((u|_{\partial \mathbb{D}})_*[\partial \mathbb{D}], \Sigma)$.

Appendix B. Homology of the complement of the binding

Let (Π, L) be an open book decomposition of the closed, connected and oriented 3manifold M. The standard orientation of \mathbb{R}/\mathbb{Z} and the map Π co-orient the pages. This co-orientation and the orientation of M together orient the pages. We orient L as the boundary of a page. Let $\gamma_1, \ldots, \gamma_n$ be the oriented components of L. Let γ'_i be the oriented loop obtained by pushing γ_i into $M \setminus L$ in the direction of a page.

Lemma B.1. We have

$$H_1(M \setminus L) \simeq \frac{H_1(\text{page})}{\text{im}(\text{id} - h_*)} \oplus \mathbb{Z}e$$

where h is a monodromy map of (Π, L) and e is any loop in $M \setminus L$ such that $\Pi_* e$ is the positive generator of $H_1(\mathbb{R}/\mathbb{Z})$. In particular, in the planar case we get $H_1(M \setminus L) \simeq A \oplus \mathbb{Z} \langle e \rangle$ where A is the abelian group generated by the γ'_i constrained by the single relation $\gamma'_1 + \cdots + \gamma'_n = 0$.

In the above statement, homology groups are taken with \mathbb{Z} coefficients.

Proof of Lemma B.1. By Wang's sequence [34, Lemma 8.4], we have an exact sequence

$$H_1(\text{page}) \xrightarrow{h_* - \text{id}} H_1(\text{page}) \to H_1(M \setminus L) \to H_0(\text{page}) \xrightarrow{h_* - \text{id}} H_0(\text{page}).$$

It turns out that h_* – id vanishes on H_0 (page). We get an exact sequence

$$0 \to \frac{H_1(\text{page})}{\text{im}(\text{id} - h_*)} \to H_1(M \setminus L) \to H_0(\text{page}) \to 0.$$

The first assertion of the lemma follows. In the special case where the page is a sphere with holes we have $h_* = id$ on $H_1(page)$ because this homology group is generated by boundary components as in the statement and h is supported away from the boundary.

Acknowledgments. Our friend and teacher Kris Wysocki passed away untimely in 2016. We started our collaboration in the fall of 2011, at the Institute for Advanced Study (IAS/Princeton) during the thematic year on Symplectic Dynamics. We thank the IAS for the opportunity to participate in such a wonderful and fruitful program. P. S. is grateful to Ruhr-Universität Bochum for the hospitality.

Funding. P. S. was partially supported by the FAPESP grant 2017/26620-6, the CNPq grant 306106/2016-7 and the Humboldt Foundation. P. S. acknowledges the support of NYU-ECNU Institute of Mathematical Sciences at NYU Shanghai. U. H. thanks the IAS/Princeton for its support during the academic year 2018-19 through a von Neumann Fellowship. U. H. was partially supported by the DFG SFB/TRR 191 'Symplectic Structures in Geometry, Algebra and Dynamics', Projectnummer 281071066-TRR 191.

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