Embeddings of Sobolev Spaces with Weights of Power Type

D. E. EDMUNDS, A. KUFNER and J. RÁKOSNÍK-

Die Arbeit befaßt sich mit einigen Eigenschaften gewichteter Sobolevscher Räume $W_0^{k,p}$, $W_M^{k,p}$ und $H^{k,p}$, in denen als Gewichte Potenzen der Entfernung von einem Teil M des Randes des Definitionsgebietes auftreten. Es werden Bedingungen angegeben, unter denen diese Räume gegenseitig eingebettet und gewisse Normen äquivalent sind. Dabei werden einige Ergebnisse aus [1] verallgemeinert und eine in [2] formulierte Vermutung wird bewiesen.

В работе исследованы некоторые свойства весовых пространств С. Л. Соболева $W_0^{k,p}$, $W_M^{k,p}$ и $H^{k,p}$, весовые функции которых являются степенями расстояния от части M границы области определения. Указаны условия, при которых эти пространства вкладываются друг'в друга и при которых некоторые нормы эквивалентны. Обобщаются некоторые результаты из [1] и доказана гипотеза, сформулированная в [2].

The paper deals with some properties of the weighted Sobolev spaces $W_0^{k,p}$, $W_M^{k,p}$ and $H^{k,p}$, with weights which are powers of the distance from a part M of the boundary of the domain of definition. Conditions are given which guarantee the mutual embeddings of these spaces and the equivalence of certain norms. The paper generalizes some results of [1] and verifies a conjecture formulated in [2].

0. Introduction

1/2

Let Ω be a domain in the Euclidean space \mathbb{R}^N and let M be a non-empty subset of the boundary $\partial\Omega$ of Ω ; given any $x \in \mathbb{R}^N$ write

$$d_M(x) = \operatorname{dist}(x, M).$$

(0.1)

Let ε , $p \in \mathbf{R}$, with $p \ge 1$, $k \in \mathbf{N}$, and let $W^{k,p}(\Omega; d_M, \varepsilon)$ be the weighted Sobolev space of (equivalence classes of) functions $u: \Omega \to \mathbf{R}$ such that for all $\alpha := (\alpha_i) \in \mathbf{N}_0^N$ with $|\alpha| := \alpha_1 + \alpha_2 + \cdots + \alpha_N \le k$, the distributional derivative $D^2 u$ satisfies

$$|D^{a}u(x)|^{p} d_{M}^{\epsilon}(x) dx < \infty.$$

The space $W^{k,p}(\Omega; d_M, \varepsilon)$ is a Banach space when equipped with the norm defined by

$$\iota\|_{W} := \left(\sum_{|\alpha| \le k} \int_{\Omega} |D^{\alpha}u(x)|^{p} d_{M}^{\epsilon}(x) dx\right)^{1/p}.$$

$$(0.2)$$

We also introduce the spaces $W_M^{k,p}(\Omega; d_M, \varepsilon)$ and $W_0^{k,p}(\Omega; d_M, \varepsilon)$, which are the closures in the Banach space $W^{k,p}(\Omega; d_M, \varepsilon)$ of the sets

$$C_{\mathcal{M}}^{\infty}(\Omega) := \{ w \in C^{\infty}(\overline{\Omega}) : \operatorname{supp} w \cap \overline{M} = \emptyset \}$$

$$(0.3)$$

and $C_0^{\infty}(\Omega)$ respectively; and the space $H^{k,p}(\Omega; d_M, \varepsilon)$, which is the set of all functions $u: \Omega \to \mathbf{R}$ such that for all $\alpha \in \mathbf{N}_0^N$ with $|\alpha| \leq k$,

$$\int_{\Omega} |D^{\mathfrak{a}}_{\mathfrak{c}} u(x)|^p d_M^{\mathfrak{c}-(k-|\mathfrak{a}|)p}(x) dx < \infty.$$

D. E. EDMUNDS, A. KUFNER and J. RÁKOSNÍK

This last space is also a Banach space when provided with the norm given by

$$\|u\|_{H} := \left(\sum_{|\alpha| \le k} \int_{\Omega} |D^{\alpha}u(x)|^{p} d_{M}^{\epsilon - (k - |\alpha|)p}(x) dx\right)^{1/p}.$$
 (0.4)

If $\varepsilon = 0$, $W^{k,p}(\Omega; d_M, \varepsilon)$ and $W_0^{k,p}(\Omega; d_M, \varepsilon)$ are simply the classical unweighted Sobolev spaces $W^{k,p}(\Omega)$ and $W_0^{k,p}(\Omega)$ respectively; if k = 0, then $W^{k,p}(\Omega; d_M, \varepsilon)$ is nothing more than the weighted Lebesgue space $L^p(\Omega; d_M, \varepsilon)$.

In [1] the case $M = \partial \Omega$ was considered, and it was shown that if for i = 1, 2, ..., k the inequality $\varepsilon \neq ip - 1$ holds, then

$$W_0^{k,p}(\Omega; d_M, \varepsilon) \hookrightarrow H^{k,p}(\Omega; d_M, \varepsilon). \tag{0.5}$$

the symbol \hookrightarrow denoting continuous embedding; it was also shown that for all $\varepsilon \in \mathbf{R}$,

$$H^{k,p}(\Omega; d_M, \varepsilon) \hookrightarrow W_0^{k,p}(\Omega; d_M, \varepsilon). \tag{0.6}$$

In particular, if $\varepsilon = 0$, then for any $u \in W^{k,p}(\Omega)$ such that $D^{\ast}u \in L^p(\Omega; d_M, (k - |\alpha|)p)$ for all $\alpha \in \mathbb{N}_0^N$ with $|\alpha| \leq k - 1$, we have $u \in W_0^{k,p}(\Omega)$. The assumption that Ω had a Lipschitz boundary was important in [1], although insofar as the embedding (0.6) is concerned this condition can be weakened.

When $\varepsilon = 0$ it is possible, by following unpublished suggestions of D. J. HARRIS, to establish (0.6) under the sole assumption on Ω that it should be bounded (see Theorem 1.1). The method used relies on the properties of the maximal function, and can be extended to the case of an arbitrary set $M \subset \partial \Omega$ and an arbitrary $\varepsilon \in \mathbf{R}$: in Theorem 1.2 it is shown that

$$H^{k,p}(\Omega; d_M, \varepsilon) \hookrightarrow W_M^{k,p}(\Omega; d_M, \varepsilon).$$

The embedding (0.5) follows from embedding theorems in weighted spaces; in the case $M = \partial \Omega$, such theorems hold if $\partial \Omega$ is Lipschitzian. It was conjectured in [2] that

$$W_{\mathcal{M}}^{k,p}(\Omega; d_{\mathcal{M}}, \varepsilon) \hookrightarrow H^{k,p}(\Omega; d_{\mathcal{M}}, \varepsilon)$$

for certain special sets M, provided that for i = 1, 2, ..., k the inequality $\varepsilon \pm ip - 1$ holds. This conjecture is verified in Corollary 3.1, (ii); the main tool is due to the third author (J. R.) and is a fuller version of the short communication [4].

1. The embedding $H \hookrightarrow W$

First, we shall prove a theorem, which implies (0.6) for the case $\varepsilon = 0$ and $M = \partial \Omega$. This result is contained in [1], but here, the condition on Ω is weakened and the method is completely new.

Theorem 1.1: Let Ω be a non-empty open subset of \mathbb{R}^N , $\Omega \neq \mathbb{R}^N$, and for each $x \in \Omega$ put $d(x) = \text{dist}(x, \partial \Omega)$; let $p \in (1, \infty)$ and $k \in \mathbb{N}$. Suppose that $u \in W^{k,p}(\Omega)$ is such that $ud^{-k} \in L^p(\Omega)$. Then $u \in W_0^{k,p}(\Omega)$.

Proof: First suppose Ω is bounded. Let $0 < h' < \delta$; define $u^{(\delta)}$ by $u^{(\delta)}(x) = u(x)$ if $d(x) \ge \delta$ and $x \in \Omega$, $u^{(\delta)}(x) = 0$ otherwise; let $\phi \in C_0^{\infty}(\mathbb{R}^N)$ be such that $\phi(x) = 0$ if $|x| \ge 1$, $\phi(x) > 0$ if |x| < 1, $\int \phi(x) dx = 1$; and put $\phi_h(x) = h^{-N}\phi(x/h)$. Let us

agree that any function g defined on Ω will be supposed extended to the whole \mathbb{R}^N , if necessary, by setting g(x) = 0 for all $x \in \mathbb{R}^N \setminus \Omega$. Note that $\phi_h * u^{(\delta)} \in C_0^{\infty}(\Omega)$.

 $\mathbf{26}$

 $\mathbf{27}$

(1.1)

First suppose that $d(x) > \delta + h$, $x \in \Omega$ and $\alpha \in \mathbb{N}_0^N$, $|\alpha| \leq k$. Then since B(x, h):= $\{y \in \mathbb{R}^N : |x - y| < h\} \subset B(x, \delta + h) \subset \Omega$, and $d(y) > \delta$ if $y \in B(x, h)$,

$$D^{\mathbf{x}}(\phi_h \ast u^{(\delta)})(x) = D^{\mathbf{x}} \int_{B(x,h)} \phi_h(x-y) u^{(\delta)}(y) dy$$

$$= D^{\mathfrak{a}} \int_{\mathbb{R}^N} \phi_h(x-y) \, u(y) \, dy = \int_{\mathbb{R}^N} \phi_h(x-y) \, D^{\mathfrak{a}}(y) \, dy;$$

, that is,

$$D^{\mathfrak{a}}(\phi_h \ast u^{(\delta)}) \ (x) = (\phi_h \ast D^{\mathfrak{a}} u) \ (x) \quad ext{if} \quad d(x) > \delta + h \ , \ \ x \in \Omega \ .$$

It follows that, with $\mathcal{M}(g)$ as the maximal function defined by

$$\mathcal{M}(g) (x) = \sup_{r>0} |B(0, r)|^{-1} \int_{B(x, r)} |g(y)| \, dy$$

 $(|B(0,r)| = \omega_N r^N$ being the volume of the ball B(0,r), we have

$$\begin{split} |D^{\mathfrak{s}}(\phi_{h} \ast u^{(\delta)})(x)| &\leq \mathcal{M}(D^{\mathfrak{s}}u)(x) \cdot \omega_{N} \sup_{y \in B(x,h)} \phi\left(\frac{x-y}{h}\right) \\ &= \mathcal{M}(D^{\mathfrak{s}}u)(x) \cdot \omega_{N} \sup_{z \in B(0,1)} \phi(z) = \mathcal{M}(D^{\mathfrak{s}}u)(x) b(\phi), \quad \text{say} \end{split}$$

Next, suppose that $d(x) \leq lh$ for some $l \in \mathbb{N}$, and let $\alpha \in \mathbb{N}_0^N$, $|\alpha| \leq k$. Then

$$\begin{split} |D^{\mathfrak{a}}(\phi_{h}\ast u^{(\delta)})(x)| &= \left| \int\limits_{\mathbf{R}^{N}} h^{-N-|\mathfrak{a}|}(D^{\mathfrak{a}}\phi)\left(\frac{x-y}{h}\right) u^{(\delta)}(y) \, dy \right| \\ &\leq h^{-N-|\mathfrak{a}|} \int\limits_{\mathbf{R}^{N}} \left| (D^{\mathfrak{a}}\phi)\left(\frac{x-y}{h}\right) u^{(\delta)}(y) \, d^{-k}(y) \right| h^{k}(l+1)^{k} \, dy \\ &\leq \omega_{N} h^{k-|\mathfrak{a}|}(l+1)^{k} \, \mathcal{M}(ud^{-k})(x) \sup_{z \in B(0,1)} |(D^{\mathfrak{a}}\phi)(z)| \, . \end{split}$$

Thus if we take $\delta = 2h = 2/j$ $(j \in \mathbb{N})$ and l = 3, we see that for all $x \in \Omega$, for all $\alpha \in \mathbb{N}_0^N$ with $|\alpha| \leq k$, and for all $j \in \mathbb{N}$,

$$|D^{a}(\phi_{1/j} * u^{(2/j)}(x))| \leq \max \{b(\phi) \mathcal{M}(D^{a}u)(x), 4^{k}c(\alpha, \phi) \mathcal{M}(ud^{-k})(x)\} := G_{a,a}(x), \quad (1.2)$$

where $c(\alpha, \phi) = \omega_N \sup_{z \in B(0,1)} |(D^*\phi)(z)|$. Since, by [5: Chap. I, Th. 1], \mathcal{M} is a bounded mapping from $L^p(\mathbb{R}^N)$ into $L^p(\mathbb{R}^N)$, it follows that $G_{\alpha,\varphi} \in L^p(\mathbb{R}^N)$. Moreover, for each $\alpha \in \mathbb{N}_0^N$ with $|\alpha| \leq k$, $\phi_{1/j} * D^*u \to D^*u$ in $L^p(\Omega)$ as $j \to \infty$, and hence there is a subsequence (j(l)) of the sequence of positive integers such that for all $\alpha \in \mathbb{N}_0^N$ with $|\alpha| \leq k$, $(\phi_{1/j(l)} * D^*u)(\alpha) \to D^*u(\alpha)$ almost everywhere in Ω . Thus by (1.1),

$$D^{a}(\phi_{1/j(l)} * u^{(2/j(l))})(x) \to D^{a}u(x)$$
(1.3)

a.e. in Ω . Together with Lebesgue's dominated convergence theorem, (1.2) and (1.3) show that $(\phi_{1/j(l)} * u^{(2/j(l))}) \to u$ in $W^{k,p}(\Omega)$; that is, $u \in W_0^{k,p}(\Omega)$.

If Ω is unbounded we simply apply the arguments above to $u\psi_m := u_m$, where $\psi_m \in C_0^{\infty}(\mathbb{R}^N)$, $\psi_m(x) = 1$ (|x| < m), $\psi_m(x) = 0$ (|x| > 2m), and note that $u_m d^{-4} \in L^p(\Omega)$ and $u_m \to u$ in $W^{k,p}(\Omega)$ as $m \to \infty$

Note that if Ω is bounded, the validity of (0.6), when $\varepsilon = 0$ and $M = \partial \Omega$, follows immediately from Theorem 1.1. We now set about the proof of (0.6) for general ε and M.

Theorem 1.2: Let Ω be a bounded domain in \mathbb{R}^N , let $M \subset \partial\Omega$, $M \neq \emptyset$, and let $p \in (1, \infty)$, $k \in \mathbb{N}$ and $\varepsilon \in \mathbb{R}$. Then

$$H^{k,p}(\Omega; d_M, \varepsilon) \hookrightarrow W_M^{k,p}(\Omega; d_M, \varepsilon).$$

Proof: Let $u \in H^{k,p}(\Omega; d_M, \varepsilon)$, and for any $\delta > 0$ write $u^{(\delta)}(x) = u(x)$ if $d_M(x) > \delta$ and $x \in \Omega$, $u^{(\delta)}(x) = 0$ otherwise. Let ϕ be as in the proof of Theorem 1.1 and write $\phi_h(x) = h^{-N}\phi(x/h)$ $(h > 0, x \in \mathbb{R}^N)$. Let h > 0 and set $v_h = \phi_h * u^{(3h)}$. We distinguish various cases.

. (i) Let $x \in \Omega$ be such that

$$d_M(x) \ge 2h. \tag{1.4}$$

Then $v_h(x) = h^{-N} \int_{B(x,h)} \phi\left(\frac{x-y}{h}\right) u^{(3h)}(y) \, dy = 0$ since by (1.4) if $y \in B(x,h)$ then

 $d_M(y) < 3h$ and consequently $u^{(3h)}(y) = 0$. It follows that

$$\operatorname{supp} v_h \subset \Omega_h := \left\{ x \in \Omega : d_M(x) > h \right\}.$$

$$(1.5)$$

Note that $\Omega_h \cap \overline{M} = \emptyset$.

(ii) Suppose that $x \in \Omega$ is such that

$$2h < d_M(x) \le 4h. \tag{1.6}$$

Then if $y \in B(x, h)$ we see that

$$h < d_M(y) < 5h; \tag{1.7}$$

and (1.6) and (1.7) imply the equivalence of h, $d_M(x)$ and $d_M(y)$:

$$d_M(x) \approx h$$
, $d_M(y) \approx h$, (1.8)

with the obvious meaning of the symbol \approx . For all $\alpha \in N_0^N$, $|\alpha| \leq k$, we have

$$\begin{split} |D^{a}v_{h}(x)| &= \left| D^{a} \int_{\mathbb{R}^{N}} \phi_{h}(x-y) u^{(3h)}(y) \, dy \right| = h^{-N} \left| \int_{\mathbb{R}^{N}} D^{a} \phi \left(\frac{x-y}{h} \right) u^{(3h)}(y) \, dy \right| \\ &\leq h^{-N-|a|} \int_{B(x,h)} \left| (D^{a} \phi) \left(\frac{x-y}{h} \right) \right| |u(y)| \, dy \\ &\leq \left(\sup_{z \in \mathbb{R}^{N}} |D^{a} \phi(z)| \right) |B(0,1)| |B(x,h)|^{-1} h^{-|a|} \int_{B(x,h)} |u(y)| \, dy \\ &\leq c_{0} h^{-|a|} |B(x,h)|^{-1} \int_{B(x,h)} |u(y)| \, d_{M}^{(\epsilon/p)-k}(y) \, dy \cdot h^{k-(\epsilon/p)} \\ &\leq c_{1} h^{k-|a|} |B(x,h)|^{-1} \int_{B(x,h)} |u(y)| \, d_{M}^{(\epsilon/p)-k}(y) \, dy \cdot [d_{M}(x)]^{-\epsilon/p}, \end{split}$$

the last two inequalities following from the equivalence of $d_M(y)$ and h, and that of $d_M(x)$ and h. Thus we have

$$|D^{\mathfrak{a}}v_{h}(x)| d_{M}^{\epsilon/p}(x) \leq c_{1}h^{k-|\mathfrak{a}|} \mathcal{M}(ud_{M}^{(\epsilon/p)-k})(x), \qquad (1.9)$$

(1.10)

where, as before, \mathcal{M} stands for the maximal function and any function on Ω is extended by zero in $\mathbb{R}^N \setminus \Omega$.

(iii) Let $x \in \Omega$ be such that for some $l \ge 4$,

$$lh < d_M(x) < (l+1) h$$
.

Embeddings of Sobolev Spaces

Let $y \in B(x, h)$. Then

$$(l-1) h < d_M(y) < (l+2) h,$$
 (1.11)

and (1.10) together with (1.11) imply

$$d_M(x) \approx lh, \qquad d_M(y) \approx lh.$$
 (1.12)

From (1.11) it follows that $u^{(3h)}(y) = u(y)$, since $d_M(y) > (l-1)$ $h \ge 3h$. For $\alpha \in \mathbb{N}_0^N$, $|\alpha| \le k$, we find, as in (ii), that

$$\begin{split} |D^{a}v_{h}(x)| &= \left| D^{a}\int_{\mathbb{R}^{N}} \phi_{h}(x-y) u^{(3h)}(y) dy \right| = \left| D^{a}\int_{\mathbb{R}^{N}} \phi_{h}(x-y) u(y) dy \right| \\ &= \left| \int_{\mathbb{R}^{N}} \phi_{h}(x-y) D^{a}u(y) dy \right| = h^{-N} \left| \int_{B(x,h)} \phi' \left(\frac{x-y}{h} \right) D^{a}u(y) dy \right| \\ &\leq c_{2} \Big(\sup_{z \in \mathbb{R}^{N}} \phi(z) \Big) |B(0,1)| |B(x,h)|^{-1} \\ &\times \int_{B(x,h)} |D^{a}u(y)| d_{M}^{(\epsilon/p) - (k-|a|)}(y) dy \cdot (lh)^{-(\epsilon/p) + k - |a|} \\ &\leq c_{3} \mathcal{M}(D^{a}u \cdot d_{M}^{(\epsilon/p) - (k-|a|)}) (x) \cdot [d_{M}(x)]^{-(\epsilon/p) + k - |a|}. \end{split}$$

Hence

$$D^{\alpha}v_{k}(x)|d_{M}^{(\epsilon/p)}(x) \leq c_{3}\mathcal{M}(D^{\alpha}u \cdot d_{M}^{(\epsilon/p)-(k-|\alpha|)})(x) \cdot d_{M}^{k-|\alpha|}(x).$$

$$(1.13)$$

However, since Ω is bounded and $|\alpha| \leq k$, $d_M^{k-|\alpha|}(x)$ is bounded. Thus there is a constant c_4 such that

$$|D^{\mathbf{x}}v_{h}(x)| d_{M}^{(\epsilon/p)}(x) \leq c_{4} \mathcal{M}(D^{\mathbf{x}}u \cdot d_{M}^{(\epsilon/p)-(k-|\mathbf{a}|)})(x).$$

It follows from (i), (ii) and (iii) that if $0 < h \leq 1$, there is a constant c_5 , independent of h, such that for all $x \in \Omega$ and all $\alpha \in N_0^N$ with $|\alpha| \leq k$,

$$|D^{\circ}v_{h}(x)| d_{M}^{\epsilon/p}(x) \leq c_{5}G(x), \qquad (1.14)$$

where $G(x) := \max \{ \mathcal{M}(ud_M^{(\epsilon/p)-k})(x), \mathcal{M}(D^a u \cdot d^{(\epsilon/p)-k+|a|})(x) \}$. Since $u \in H^{k,p}(\Omega; d_M, \epsilon)$, $D^a u \cdot d_M^{(\epsilon/p)-k+|a|} \in L^p(\Omega)$ and hence $D^a u \cdot d_M^{(\epsilon/p)-k+|a|} \in L^p(\mathbb{R}^N)$; in particular, $ud_M^{(\epsilon/p)-k} \in L^p(\mathbb{R}^N)$. The properties of the maximal function now imply that

 $G \in L^p(\mathbf{R}^N). \tag{1.15}$

By the Lebesgue dominated convergence theorem, the assumption that as $h \rightarrow 0$,

$$|D^{\mathfrak{s}} v_{\mathfrak{h}}(x)| \ d_{\mathfrak{M}}{}^{\mathfrak{e}/p}(x) \to |D^{\mathfrak{s}} u(x)| \ d_{\mathfrak{M}}{}^{\prime/p}(x) \tag{1.16}$$

for almost all $x \in \Omega$, implies (in view of (1.14) and (1.15)) that as $h \to 0$, $d_M^{\epsilon/p} D^a v_h \to d_M^{\epsilon/p} D^a u$ in L^p ; that is,

$$v_h \to u \quad \text{in} \quad W^{k,p}(\Omega; d_M, \varepsilon),$$

$$(1.17)$$

which is what we need.

All that remains to complete the proof of the Theorem is to establish (1.16). To do this, let $\delta > 0$, $\Omega_{\delta} = \{x \in \Omega : d_M(x) > \delta\}$, and note that since $u \in H^{k,p}(\Omega; d_M, \varepsilon)$, $u \in W^{k,p}(\Omega_{\delta})$. For $h \in (0, \delta/4)$ and $x \in \Omega_{\delta}$, we have $u^{(3h)}(x) = u(x)$ and, for $|\alpha| \leq k$, α fixed,

$$D^{a}v_{h}(x) = D^{a}(\phi_{h} * u^{(3h)})(x) = D^{a}(\phi_{h} * u)(x) = (\phi_{h} * D^{a}u)(x),$$

and as $h \to 0$,

$$D^{\alpha}v_{h} \rightarrow D^{\alpha}u \quad \text{in} \quad L^{p}(\Omega_{\delta})$$

(1.18)

D. E. EDMUNDS, A. KUFNER and J. RÁKOSNÍK

since $\phi_h * D^a u \to D^a u$ in $L^p(\Omega_\delta)$. From (1.18) it follows that there is a sequence (h_n) of positive real numbers, converging to 0, such that $D^a v_{h_n} \to D^a u$ almost everywhere in Ω_δ . Now take $\delta = 1/k_0$, $k_0 \in \mathbb{N}$, and let $(v_n^{(1)})$ be the sequence (v_{h_n}) for this particular δ . Let $(v_n^{(2)})$ be a subsequence of $(v_n^{(1)})$ such that

$$D^{\alpha}v_{n}^{(2)} \rightarrow D^{\alpha}u$$
 a.e. in $\Omega_{1/(k_{\alpha}+1)}$;

more generally let $(v_n^{(l)})$ be a subsequence of $(v_n^{(l-1)})$ such that

$$D^{\alpha}v_{n}^{(l)} \rightarrow D^{\alpha}u$$
 a.e. in $\Omega_{1/(k_{0}+l)}$.

It follows that the diagonal sequence (w_n) , $w_n = v_n^{(n)}$, has the property that

$$D^{\alpha}w_{n} \rightarrow D^{\alpha}u$$
 a.e. in Ω . (1.19)

Of course; $\{w_n : n \in \mathbb{N}\} \subset \{v_h : h > 0\}$. Moreover, while the multi-index α was fixed, it is easy to see that matters can be arranged so that (1.19) holds for every $\alpha \in \mathbb{N}_0^N$ with $|\alpha| \leq k$. Thus

$$d_M^{\epsilon/p} D^{\alpha} w_n \to d_M^{\epsilon/p} D^{\alpha} u$$
 a.e. in Ω ,

and the arguments used to pass from (1.16) to (1.17) show that $w_n \to u$ in $W^{k,p}(\Omega; d_M, \varepsilon)$. Our discussion in (i) shows that $\sup w_n \cap \overline{M} = \emptyset$ (see (1.5)); moreover, $w_n \in C^{\infty}(\mathbb{R}^N)$. Hence $u \in W_M^{k,p}(\Omega; d_M, \varepsilon)$, and the proof is complete, since the continuity of the embedding of H in W is clear

2. The embedding $W \hookrightarrow H$

Now we shall deal with embeddings inverse to those of 1. For this case, we need more special domains.

Definition 2.1: Put $Q = (0, 1)^N$ and $Q(m) = \{x \in \overline{Q} : x_{m+1} = \cdots = x_N = 0\}, m = 0, 1, \ldots, N - 1$. A closed subset M of $\partial \Omega$ is said to be a manifold of dimension m on $\partial \Omega$ if there is an open covering $\{U_i\}_{i=0}^{\omega}$ (ω finite or $\omega = \infty$) of Ω with the following properties:

(i) $M \subset \bigcup_{i=1}^{\infty} U_i$, and there exists $s \in \mathbb{N}$ such that every system of (s+1) sets U_i is disjoint;

(ii) there exists $\delta > 0$ such that

$$d_{\mathcal{M}}(x) \geq \delta$$
, for all $x \in U_0$;

(iii) there are numbers c_1, c_2 , with $c_2 \ge c_1 > 0$, and a system of one-to-one mappings $T_i: \overline{Q} \to \overline{Q \cap U_i}$ $(i = 1, 2, ..., \omega)$ such that $T_i(Q(m)) = M \cap \overline{U}_i$ and

(2.1)

(2:2)

$$|x - y| \leq |T_i(x) - T_i(y)| \leq c_2 |x - y|$$

for all $x, y \in \overline{Q}$ and $i = 1, ..., \omega$.

Remark 2.2: In what follows we shall see that this notion of an *m*-dimensional manifold on $\partial\Omega$ is suitable for dealing with embeddings of Sobolev spaces with weights which are powers of d_M . We use simple idea to avoid technical complications, but theorems of the type of the following Theorem 2.3 hold for more general sets M, and

Embeddings of Sobolev Spaces

in particular for the set

$$M^* := \bigcup_{i=1}^{N} \{ x \in \overline{Q} : x_j \neq 0 \text{ for } j \neq i \} \subset \partial \Omega,$$

which is not a one-dimensional manifold on $\partial \Omega$ in the sense of Definition 2.1.

Theorem 2.3: Let $\Omega \subset \mathbb{R}^N$ be a domain, let $M \in \partial \Omega$ be an *m*-dimensional manifold on $\partial \Omega$, let $m \in \{0, 1, ..., N - 1\}$ and suppose that $p \in (1, \infty)$. Then:

$$V \hookrightarrow L^p(\Omega; d_M, \varepsilon - p) \tag{2.3}$$

where

(i) $V = W^{1,p}(\Omega; d_M, \varepsilon)$ if $\varepsilon > p + m - N$ (2.4) $\varepsilon \le m - N;$ (2.5)

(ii)
$$V = W_M^{1,p}(\Omega; d_M, \varepsilon)$$
 if
 $\varepsilon \neq p + m - N;$
(2.6)

(iii)
$$V = W_0^{1,p}(\Omega; d_M, \varepsilon)$$
 if $m < N - 1$ and ε is an arbitrary real number.

Proof: Let $(\phi_i)_{i=0}^{\omega}$ be a partition of unity subordinate to the covering $\{U_i\}_{i=0}^{\omega}$ mentioned in Definition 2.1. Let $u \in W^{1,p}(\Omega; d_M, \varepsilon)$ and put $u_i = u\phi_i, i = 0, 1, ..., \omega$. It is enough to prove that there is a constant c, independent of u, such that for $i = 0, 1, ..., \omega$,

$$\int_{U_i\cap\Omega} |u_i(x)|^p d_M^{\epsilon-p}(x) dx \leq c ||u_i||_{\overline{W}}.$$
(2.7)

For i = 0, (2.7) holds trivially in view of (2.1). Now suppose that i > 0, and for the sake of simplicity omit the subscript i on u_i and U_i . By (2.2)

$$c_1 d_{\mathcal{Q}(m)}(y) \le d_{\mathcal{M}}(T(y)) \le c_2 d_{\mathcal{Q}(m)}(y) \tag{2.8}$$

for all $y \in \overline{Q}$; and from [3: Chap. 2, Lemma 3.1] it follows that there are positive constants c_3, c_4 , depending only on c_1, c_2, p and N, such that

$$c_3 \int_{\Omega \cap U} |w(x)|^p dx \leq \int_{Q} |w(T(y))|^p dy \leq c_4 \int_{\Omega \cap U} |w(x)|^p dx$$
(2.9)

or all $w \in L^p(\Omega \cap U)$.

For all $y \in Q$ put v(y) = u(T(y)), and introduce the "cylindrical" coordinates $y = (y', y'') \mapsto (y', \theta, r), \quad y' = (y_1, \dots, y_m), \quad \theta \in \Xi := \left(0, \frac{\pi}{2}\right)^{N-m-1}, \quad r \in (0, R(\theta)),$ $r = d_{Q(m)}(y) = \left(\sum_{i=m+1}^{N} y_i^2\right)^{1/2}$. The corresponding Jacobian is $\left|\frac{D(y)}{D(y', \theta, r)_i}\right| = r^{N-m-1}$ $\times \Phi(y', \theta),$ and

$$\int_{Q} |v(y)|^p d_{Q(m)}^{\epsilon-p}(y) dy$$

$$= \int_{Q(m)} \int_{\Xi} \Phi(y',\theta) \int_{0}^{h(0)} |v(y',\theta,r)|^{p} r^{\epsilon-p+N-m-1} dr d\theta dy'.$$
(2.10)

Since $v(y', \theta, r) = 0$ for almost all $y' \in Q(m)$, $\theta \in \Xi$ and for all r in a neighbourhood of $R(\theta)$, we can extend the function v by zero for $r \ge R(\theta)$ with preservation of all

D. E. EDMUNDS, A. KUFNER and J. Rákosník

differentiability properties. Application of the Hardy inequality (see, for example, [2: Chap. 5]) to the inner integral on the right-hand side of (2.10) now shows that for almost all $y' \in Q(m)$, $\theta \in \Xi$,

$$\int_{0}^{\infty} |v(y',\theta,r)|^{p} r^{\varepsilon-p+N-m-1} dr \leq c_{H} \int_{0}^{\infty} \left| \frac{\partial y}{\partial r} (y',\theta,r) \right|^{p} r^{\varepsilon+N-m-1} dr \qquad (2.11)$$

if

$$\varepsilon + N - m - 1 > p - 1 \tag{2.12}$$

and $\lim_{r\to\infty} v(y', \theta, r) = 0$ (this condition is satisfied trivially), or if

$$+ N - m - 1$$

and

$$\lim v(y', \theta, r) := v_0(y', \theta) = 0.$$
(2.14)

The constant c_H in (2.11) is given by $c_H = p/|\varepsilon - p + N - m|$. Integrating the inequality (2.11) over $Q(m) \times \Xi$ and passing back to Cartesian coordinates we obtain

$$\int_{\Omega} |v(y)|^p d_{Q(m)}^{\epsilon-p}(y) dy \leq c_H \int_{Q} \left| \frac{\partial v}{\partial r}(y) \right|^p d_{Q(m)}^{\epsilon}(y) dy$$
$$\leq c_5 \sum_{j=m+1}^{N} \int_{Q} \left| \frac{\partial v}{\partial y_j}(y) \right|^p d_{Q(m)}^{\epsilon}(y) dy.$$

Use of (2.9) with $w = ud_M^{(\epsilon/p)-1}$ and with $w = \frac{\partial u}{\partial x_j} d_M^{\epsilon/p}$, the estimates (2.8) and the inequality $\left| \frac{\partial v}{\partial y_j}(y) \right| \leq c_2 \sum_{l=1}^{N} \left| \frac{\partial u}{\partial y_l}(T(y)) \right|$ which follows from (2.2) now gives (2.7) with a constant c which depends only on p, ϵ , N, c_1 and c_2 .

All that remains is to discuss the validity of the assumptions (2.12)-(2.14). The inequalities (2.4) and (2.12) are equivalent. If (2.5) holds, then (2.13) is satisfied. Further, for almost all $y' \in Q(m)$, $\theta \in \Xi$ and for r, h > 0 we have, by Hölder's inequality,

$$|v(y', \theta, r+h) - v(y', \theta, r)| = \left| \int_{r}^{r+h} \frac{\partial v}{\partial r} (y', \theta, \varrho) \, d\varrho \right|$$
$$\leq \left(\int_{r}^{r+h} \left| \frac{\partial v}{\partial r} (y', \theta, \varrho) \right|^{p} \varrho^{\varepsilon + N - m - 1} \, d\varrho \right)^{1/p}$$
$$\times \left(\int_{r}^{r+h} \varrho^{(\varepsilon + N - m - 1)/(1 - p)} \, d\varrho \right)^{(p-1)/p} = o(1)$$

as $h \to 0$, since the former of the last two integrals is finite and the exponent in the latter one is positive. Hence the function $v(y', \theta, \cdot)$ is uniformly continuous in a neighbourhood of the origin and the limit $v_0(y', \theta)$ in (2.14) exists. Since

$$\int_{0}^{R(\theta)} |v(y', \theta, r)| r^{\epsilon+N-m-1} dr < \infty,$$

the assumption (2.5) yields (2.14). Thus assertion (i) holds.

If $V = W_M^{1,p}(\Omega; d_M, \varepsilon)$, it is enough to deal with functions u in $C_M^{\infty}(\Omega)$, so that $\sup v \subset Q$; and condition (2.14) is then trivially satisfied. The condition (2.6) means that (2.12) or (2.13) holds.

Finally, suppose that m < N - 1. If $\varepsilon \neq p + m - N$, assertion (iii) follows from (ii), since $W_0^{1,p}(\Omega; d_M, \varepsilon) \subset W_M^{1,p}(\Omega; d_M, \varepsilon)$. Thus suppose that $\varepsilon = p + m - N$. and let $u \in C_0^{\infty}(\Omega)$. Since m < N - 1, we can write

$$2^{-1/2}(y_{l} + \varrho_{l}) \leq d_{Q(m)}(y) \leq y_{l} + \varrho_{l}, \quad \varrho_{l}^{2} = \sum_{j=m+1, j\neq l}^{N} y_{j}^{2}$$
$$(l = m + 1, \dots, N; y \in Q)$$

and

$$\int_{0} |v(y)|^{p} d\xi_{Q(m)}^{\epsilon-p}(y) dy \leq c_{6} \int_{(0,1)^{N-1}}^{1} \int_{0}^{1} |v(y)|^{p} (y_{l} + \varrho_{l})^{\epsilon-p} dy_{l} dy^{(l)},$$

where $y^{(l)} = (y_1, \ldots, y_{l-1}, y_{l+1}, \ldots, y_N)$. Taking into account the fact that $\sup v \subset Q$ and $\varepsilon = p + m - N , we apply the generalized Hardy inequality (see, [5:$ Lemma 5.3]) to the inner integral on the right-hand side and obtain

$$\int\limits_{Q} |v(y)|^p d_{Q(m)}^{s-p}(y) dy \leq c_7 \int\limits_{Q} \left| \frac{\partial v}{\partial y_t}(y) \right|^p d_{Q(m)}^s(y) dy.$$

It is now sufficient to use (2.9) with $w = u d_M^{(\epsilon/p)-1}$ and with $w = \frac{\partial u}{\partial x_l} d_M^{\epsilon/p}$; the assertion (iii) and consequently Theorem 2.3 are proved

3. Concluding remarks

We present two natural consequences of the work in § 1 and § 2.

Corollary 3.1: Let Ω be a bounded domain in \mathbb{R}^N , let M be an m-dimensional manifold on $\partial\Omega$ where $m \in \{0, 1, ..., N - 1\}$, and let $p \in (1, \infty)$, $k \in \mathbb{N}$. Then

$$V \hookrightarrow H^{k,p}(\Omega; d_M, \varepsilon),$$

where

(i) $V = W^{k,p}(\Omega; d_M, \varepsilon)$ if $\varepsilon > kp + m - N$

or :

$$\varepsilon \leq m - N;$$
(ii) $V = W_M^{k,p}(\Omega; d_M, \varepsilon)$ if (3.2)

$$\varepsilon = jp + m - N, \quad j = 1, 2, ..., k;$$
 (3.3)

(iii)
$$V = W_0^{k,p}(\Omega; d_M, \varepsilon)$$
 if
 $m < N - 1$ and $c \in \mathbf{R}$

Proof: Use Theorem 2.3 successively for $D^{\beta}u$ with $|\beta| = k$, $|\beta| = k - 1, ...$

Corollary 3.2: Let the assumptions of Corollary 3.1 be satisfied. If ε satisfies (3.1) or (3.2), then

$$W_M^{k,p}(\Omega; d_M, \varepsilon) = H^{k,p}(\Omega; d_M, \varepsilon) = W^{k,p}(\Omega; d_M, \varepsilon).$$

3 Analysis Bd. 4, Heft 1 (1985)

(3.1)

(3.4)

If ε satisfies (3.3), then

$$W_M^{k,p}(\Omega; d_M, \varepsilon) = H^{k,p}(\Omega; d_M, \varepsilon).$$
(3.5)

If m < N - 1, then (3.5) holds for all $\varepsilon \in \mathbb{R}$ with $W_0^{k,p}(\Omega; d_M, \varepsilon)$ instead of $W_M^{k,p}(\Omega; d_M, \varepsilon)$.

Proof: The assertions follow immediately from Corollary 3.1 and Theorem 1.2

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VERFASSER:

Prof. Dr. DAVID EDMUNDS

School of Mathematical and Physical Sciences University of Sussex 7 (Falmer, Brighton BN1 9QH Great Britain

Prof. Dr. ALOIS KUFNER and Dr. JIŘÍ RÁKOSNÍK Matematický Ústav ČSAV 11567 Praha 1, Žitná 25 Czechoslovakia