

Mean Value Theorem for Functions Possessing First Order Convex Approximations. Applications in Optimization Theory

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In dieser Arbeit wird ein Mittelwertsatz für Funktionen abgeleitet, die konvexe Approximationen erster Stufe im Sinne von IOFFE [6] besitzen. Er umfaßt zwei bekannte Ergebnisse für konvexe und lokal Lipschitzsche Funktionen als Spezialfälle. Dieser Satz wird zur Ableitung einer hinreichenden Bedingung dafür verwendet, daß eine Funktion, die auf kartesischem Produkt zweier topologischer Vektorräume definiert ist, eine konvexe Approximation erster Stufe besitzt. Einige Anwendungen in der Optimierungstheorie werden auch dargestellt.

В работе доказана теорема о среднем для функций, обладающих выпуклыми аппроксимациями первого порядка в смысле Иоффе [6]. Она включает в себя два известных результата для выпуклых и локально липшицевых функций как частные случаи. Эта теорема применяется для вывода достаточного условия для того, чтобы функция, определенная на прямом произведении двух топологических векторных пространств, обладала выпуклой аппроксимацией первого порядка. Представлены тоже некоторые приложения этих результатов в теории оптимизации.

A mean value theorem for functions possessing first order convex approximations in the sense of IOFFE [6] is derived. It comprises two known results for convex and locally Lipschitzian functions as particular cases. This theorem is used in order to obtain a sufficient condition for a function defined on the Cartesian product of two topological vector spaces to possess a first order convex approximation. Some applications in optimization theory are also given.

1. Introduction

In the last few years there appeared many publications in which mean value theorems for various classes of nondifferentiable real- and vector-valued functions were derived (see [3, 4, 7, 9, 10, 12] for the most general results). These theorems were stated by means of various generalizations of the notion of a gradient (or derivative) in differential calculus and of a subdifferential in convex analysis. In this paper we present a mean value theorem for real-valued functions (on arbitrary real topological vector spaces) possessing first order convex approximations in the sense of IOFFE [6]. This kind of approximation plays an important role in the theory of first order necessary optimality conditions (it requires weaker assumptions than other approximations used in many earlier papers). A first order convex approximation of a function is not uniquely determined and, by taking its subdifferential, one can obtain different generalizations of the derivative of the function being approximated.

As corollaries from our mean value theorem (Theorem 1), we obtain the results of HIRIART-URRUTY [3] for convex lower semicontinuous and of LEBOURG [9] for locally Lipschitzian functions. From Theorem 1 as well, we derive a sufficient condition (Theorem 2) for the existence of a first order convex approximation for a function defined on the Cartesian product of two topological vector spaces. Then we apply Theorem 2 to obtain a variant of the extremum principle of IOFFE and ТИХО-

MIROV [8], and Theorem 1 to generalize the sufficient optimality condition of DYCKHOFF [2].

Throughout the paper, the letters X, Y will denote (unless otherwise stated) real topological vector spaces. Let $f: X \rightarrow \mathbf{R} \cup \{+\infty\}$ be convex and proper (i.e. $\text{dom } f = \{x \in X \mid f(x) < \infty\} \neq \emptyset$). We shall denote by $\partial f(x)$ the subdifferential of f at the point x , that is,

$$\partial f(x) = \{x^* \in X^* \mid \forall u \in X, f(u) \geq f(x) + \langle x^*, u - x \rangle\} \quad (1)$$

where X^* is the topological dual space of X . It can be shown (cf. [8: § 4.2, Prop. 1]) that, for each $x \in \text{dom } f$,

$$\partial f(x) = \{x^* \in X^* \mid \forall h \in X, f'(x; h) \geq \langle x^*, h \rangle\} \quad (2)$$

where

$$f'(x; h) = \lim_{\lambda \downarrow 0} \lambda^{-1} (f(x + \lambda h) - f(x)). \quad (3)$$

For two different points a and b in X , we shall denote, respectively, by $[a, b]$ and $]a, b[$ the subsets

$$\{a + t(b - a) \mid 0 \leq t \leq 1\} \quad \text{and} \quad \{a + t(b - a) \mid 0 < t < 1\}.$$

2. First order convex approximations and Dini derivatives

Let $f: U \rightarrow \mathbf{R}$ be a real-valued function defined on an open subset U of X , and let $x \in U$. We denote, for any $h \in X$,

$$f_+'(x; h) = \limsup_{\lambda \downarrow 0} \lambda^{-1} (f(x + \lambda h) - f(x)).$$

A function $\varphi: X \rightarrow \mathbf{R}$ is called a first order convex approximation for f at x if φ is sublinear (i.e. convex, and $\varphi(\lambda h) = \lambda \varphi(h)$ for all $\lambda \geq 0, h \in X$), continuous and satisfies the condition

$$f_+'(x; h) \leq \varphi(h) \quad \text{for all } h \in X. \quad (4)$$

Remarks: 1. The original definition of IOFFE [6] contains instead of (4) the equivalent condition

$$\limsup_{\lambda \downarrow 0} \lambda^{-1} (f(x + \lambda h) - f(x) - \lambda \varphi(h)) \leq 0.$$

The convexity and continuity assumptions are not included in this definition, but used in all subsequent theorems.

2. Instead of the continuity of φ , it suffices to assume that φ is bounded above on some open subset of X (then φ is continuous by [8: § 3.2, Theorem 1]). Since φ is convex and continuous, the subdifferential $\partial \varphi(0)$ is non-empty (the proof of this fact without the assumption of the local convexity of X is given in [5: § 14B]). By (1) we have

$$\partial \varphi(0) = \{x^* \in X^* \mid \forall h \in X, \varphi(h) \geq \langle x^*, h \rangle\}. \quad (5)$$

Moreover, by [6: Prop. 1,

$$\text{if } f \text{ has a local minimum at } x, \text{ then } 0 \in \partial \varphi(0). \quad (6)$$

Examples: 1. Let U be convex and f — convex and continuous. Then, for each $x \in U$ and $h \in X$, the directional derivative (3) exists and is finite, and the function $f'(x; \cdot): X \rightarrow \mathbf{R}$ is sublinear and continuous (cf. [8: § 4.1, Prop. 4]). Therefore $f'(x; \cdot)$ is a first order convex approximation for f at x .

2. Let f be locally Lipschitzian in the sense of [9], that is, the generalized directional derivative

$$f^\circ(x; h) = \limsup_{\substack{u \rightarrow x \\ \lambda \downarrow 0}} \lambda^{-1}(f(u + \lambda h) - f(u))$$

satisfies the following condition: for each $a \in U$, there exist a neighbourhood A of a in U and a circled neighbourhood W of 0 in X , such that the set $\{f^\circ(x; h) \mid x \in A, h \in W\}$ is bounded in \mathbf{R} . It follows from [9: Lemma (1.1) and Prop. (1.2)] that $f^\circ(x; \cdot)$ is a first order convex approximation for f at x . If f is as described in Example 1, then it is locally Lipschitzian and $f^\circ = f'$ by [9: Prop. (1.10)].

Let us now consider a function $f: V \rightarrow \mathbf{R}$ where V is an open subset of \mathbf{R} . We define the following Dini derivatives of f at $x \in V$

$$D^+f(x) = \limsup_{\lambda \downarrow 0} \lambda^{-1}(f(x + \lambda) - f(x)),$$

$$D_+f(x) = \liminf_{\lambda \downarrow 0} \lambda^{-1}(f(x + \lambda) - f(x))$$

and, analogously, $D^-f(x)$ and $D_-f(x)$ by taking the limits as $\lambda \uparrow 0$.

Proposition 1: A function $\varphi: \mathbf{R} \rightarrow \mathbf{R}$ is a first order convex approximation for f at x if and only if φ is sublinear and $-D_-f(x) \leq \varphi(-1)$, $D^+f(x) \leq \varphi(1)$.

Proof: It suffices to observe that $-D_-f(x) = f'_+(x; -1)$, $D^+f(x) = f'_+(x; 1)$ ■

Proposition 2: Let $f: [a, b] \rightarrow \mathbf{R}$ (where $a < b$) be continuous and satisfy the conditions:

- a) for each $x \in]a, b[$, there exists a first order convex approximation φ_x for f at x ;
 - b) the functions $x \mapsto \varphi_x(-1)$ and $x \mapsto \varphi_x(1)$ are upper semicontinuous on $]a, b[$.
- If f attains a local maximum at $c \in]a, b[$, then $0 \in \partial\varphi_c(0)$.

Proof: Suppose that f has a local maximum at c , and $0 \notin \partial\varphi_c(0)$. Hence (by (5)) either $\varphi_c(1) < 0$ or $\varphi_c(-1) < 0$. In the first case it follows from assumption b) and Proposition 1 that there exists $\varepsilon > 0$ such that

$$D^+f(x) \leq \varphi_x(1) < 0 \quad \text{for all } x \in [c - \varepsilon, c] \subset]a, b[. \tag{7}$$

For such x , we have $D^+(-f)(x) = -D_+f(x) \geq -D^+f(x) > 0$. Hence and from [1: Cor. XI.4.2] we obtain that $-f$ is non-decreasing on $[c - \varepsilon, c]$, thus $f(x) \geq f(c)$ for all $x \in [c - \varepsilon, c]$. Since f has a local maximum at c , there exists $\delta \in]0, \varepsilon[$ such that $f(x) \leq f(c)$ for all $x \in [c - \delta, c]$. Therefore f is constant on $[c - \delta, c]$ and $D^+f(c - \delta) = 0$, which contradicts (7). The case of $\varphi_c(-1) < 0$ can be considered analogously (instead of $-f$ one should take into account the function $g(x) = -f(-x)$ and observe that $D^+g(-x) \geq D_+g(-x) = D_-f(x) > 0$ for all x in some interval $[c, c + \varepsilon']$, $\varepsilon' > 0$) ■

Remark: Proposition 2 is not true without assumption b). As a counterexample it suffices to take $f(x) = -|x|$, $\varphi_x(u) = u$ for $x < 0$, $\varphi_x(u) = -u$ for $x \geq 0$, $c = 0$.

3. The mean value theorem

Let A be a subset of X with nonempty interior, and let $[a, b] \subset A$. We shall say that a function $f: A \rightarrow \mathbb{R}$ is *hemi-continuous* on $[a, b]$ (cf. [4]) if the function $t \mapsto f(a + t(b - a))$ is continuous on $[0, 1]$.

Theorem 1: *Let $f: A \rightarrow \mathbb{R}$ satisfy the conditions:*

- a) f is hemi-continuous on $[a, b]$;
- b) $]a, b[\subset \text{int } A$ and, for each $x \in]a, b[$, φ_x is a first order convex approximation, for f at x ;
- c) the functions $x \mapsto \varphi_x(a - b)$ and $x \mapsto \varphi_x(b - a)$, defined on $]a, b[$, are upper semicontinuous.

Then

there exist $c \in]a, b[$ and $x^* \in \partial\varphi_c(0)$ such that

$$f(b) - f(a) = \langle x^*, b - a \rangle. \quad (8)$$

Proof: Let us first consider the case when $X = \mathbb{R}$ (and $a < b$). If $f(a) = f(b)$, then there exists $c \in]a, b[$ which is a local minimum or maximum point for f . Hence $0 \in \partial\varphi_c(0)$ by (6) or Proposition 2, and (8) holds for $x^* = 0$. If $f(a) \neq f(b)$, then instead of f one should consider the function $\bar{f}(x) = f(x) - f(a) - \alpha(x - a)$ ($x \in A$) where $\alpha = (f(b) - f(a))/(b - a)$. It is easy to verify that $\bar{\varphi}_x(h) = \varphi_x(h) - \alpha h$ ($h \in \mathbb{R}$) is a first order convex approximation for \bar{f} at $x \in]a, b[$, and that $\partial\bar{\varphi}_c(0) = \partial\varphi_c(0) - \alpha$; hence (8) holds for $x^* = \alpha$.

In the general case we put $g(t) = f(a + t(b - a))$, $t \in [0, 1]$, and observe that, for each $t \in]0, 1[$, the function $\psi_t(s) = \varphi_{a+t(b-a)}(s(b - a))$ ($s \in \mathbb{R}$) is a first order convex approximation for g at t , and that the functions $t \mapsto \psi_t(-1)$ and $t \mapsto \psi_t(1)$ are upper semicontinuous on $]0, 1[$. Applying the result just proved to the function g , we obtain that there exist $r \in]0, 1[$ and $\beta \in \partial\psi_r(0)$ such that

$$\beta = g(1) - g(0) = f(b) - f(a). \quad (9)$$

Let $c = a + r(b - a)$. Since $\beta \in \partial\psi_r(0)$, we have $\beta s \leq \varphi_c(s(b - a))$ for all $s \in \mathbb{R}$. We define a continuous linear functional l on the subspace $\{x \in X \mid x = s(b - a), s \in \mathbb{R}\}$ by setting $l(s(b - a)) = \beta s$. It follows from the Hahn-Banach theorem [5: § 11G] that l has an extension $x^* \in X^*$ satisfying $\langle x^*, h \rangle \leq \varphi_c(h)$ for all $h \in X$. Since $\langle x^*, b - a \rangle = l(b - a) = \beta$, we obtain (8) by (5) and (9) ■

Corollary 1 [3: Theorem 7]: *Let $f: X \rightarrow \mathbb{R} \cup \{+\infty\}$ be convex and lower semicontinuous. Suppose that $[a, b] \subset \text{dom } f$, and that f is continuous at some point of $]a, b[$. Then*

there exist $c \in]a, b[$ and $x^* \in \partial f(c)$ such that

$$f(b) - f(a) = \langle x^*, b - a \rangle. \quad (10)$$

Proof: Since f is continuous at a point of $]a, b[$, we have $]a, b[\subset \text{int}(\text{dom } f)$, and f is continuous on $\text{int}(\text{dom } f)$ by [8: §3.2, Theorem 1]. It is easy to show (by making use of Example 1) that f restricted to $A = \text{dom } f$ satisfies the assumptions of Theorem 1 (the upper semicontinuity of $f'(\cdot; h)$ on $\text{int } A$ can be deduced from the continuity of f and the equality $f'(x; h) = \inf \{\lambda^{-1}(f(x + \lambda h) - f(x)) \mid \lambda > 0\}$, similarly as in the proof of Corollary 3 below). Thus (10) follows from (8) ■

The following result is a direct consequence of Theorem 1, Example 2 and the upper semicontinuity of $f'(\cdot; h)$.

Corollary 2 [9: Theorem (1.7)]: *If A is open and $f: A \rightarrow \mathbb{R}$ is locally Lipschitzian, then (10) is true, where $\partial f(c)$ denotes the generalized gradient of f at c (i.e. the subdifferential of $f^\circ(c; \cdot)$ at 0).*

4. Applications

Let us consider the following problem: given a function $f: X \times Y \rightarrow \mathbb{R}$ such that the functions $f(x, \cdot)$ and $f(\cdot, y)$ possess first order convex approximations, we want to formulate sufficient conditions (stated by means of these "partial" approximations) for the existence of an approximation for f at (x, y) in $X \times Y$.

Theorem 2: *Let U and V be open subsets of X and Y , respectively, and let $(x, y) \in U \times V$. Suppose that $f: U \times V \rightarrow \mathbb{R}$ satisfies the conditions:*

- a) *for any $u \in U$, the function $f(u, \cdot): V \rightarrow \mathbb{R}$ is hemi-continuous on each segment $[y, y'] \subset V$ and has at each point $v \in V$ a first order convex approximation $\psi_{u,v}: Y \rightarrow \mathbb{R}$;*
- b) *the function $f(\cdot, y): U \rightarrow \mathbb{R}$ has a first order convex approximation $\varphi: X \rightarrow \mathbb{R}$ at the point x ;*
- c) *for each $k \in Y$, the function $(u, v) \mapsto \psi_{u,v}(k)$ is upper semicontinuous on $U \times V$.*

Then the function $\omega: X \times Y \rightarrow \mathbb{R}$ defined by

$$\omega(h, k) = \varphi(h) + \psi_{x,y}(k) \quad (h \in X, k \in Y)$$

is a first order convex approximation for f at (x, y) .

Proof: The only difficulty is to check condition (4) of the definition, which is equivalent to the following one:

for each $\varepsilon > 0$ and $(h, k) \in X \times Y$, there exists $\mu > 0$ such that

$$\lambda^{-1}(f(x + \lambda h, y + \lambda k)) - f(x, y) \leq \omega(h, k) + \varepsilon \text{ for all } \lambda \in]0, \mu[. \tag{11}$$

Take any $\varepsilon > 0$, $h \in X$, $k \in Y$. By c), there exist neighbourhoods $U' \subset U$ and $V' \subset V$ of x and y , respectively, such that

$$\psi_{u,v}(k) \leq \psi_{x,y}(k) + \varepsilon/2 \text{ for all } u \in U', v \in V'. \tag{12}$$

By b), there exists $\mu > 0$ such that

$$x + \lambda h \in U', \quad y + \lambda k \in V' \quad \text{and} \\ \lambda^{-1}(f(x + \lambda h, y) - f(x, y)) \leq \varphi(h) + \varepsilon/2, \quad \text{for all } \lambda \in]0, \mu[. \tag{13}$$

It follows from a) and c) that, for each $\lambda \in]0, \mu[$, the function $f(x + \lambda h, \cdot)$ satisfies the assumptions of Theorem 1 on the segment $[y, y + \lambda k]$. Consequently, there exist $c_\lambda \in]y, y + \lambda k[$ and $x_\lambda^* \in \partial \psi_{x+\lambda h, c_\lambda}(0)$, such that $f(x + \lambda h, y + \lambda k) - f(x + \lambda h, y) = \langle x_\lambda^*, \lambda k \rangle$. Hence and from (12), (13) and (5) we obtain

$$\begin{aligned} & \lambda^{-1}(f(x + \lambda h, y + \lambda k) - f(x, y)) \\ &= \lambda^{-1}(f(x + \lambda h, y + \lambda k) - f(x + \lambda h, y)) + \lambda^{-1}(f(x + \lambda h, y) - f(x, y)) \\ &\leq \langle x_\lambda^*, k \rangle + \varphi(h) + \varepsilon/2 \leq \varphi(h) + \psi_{x+\lambda h, c_\lambda}(k) + \varepsilon/2 \leq \varphi(h) + \psi_{x,y}(k) + \varepsilon, \end{aligned}$$

which concludes the proof of (11) ■

Corollary 3: *Let $f: U \times V \rightarrow \mathbb{R}$ be a continuous function, where U and V are open subsets of X and Y , respectively, and V is convex. Let $(x, y) \in U \times V$. If, for each*

$u \in U$, $f(u, \cdot): V \rightarrow \mathbf{R}$ is convex and assumption b) of Theorem 2 is fulfilled, then $(h, k) \mapsto \varphi(h) + f'_v(x, y; k)$ is a first order convex approximation for f at (x, y) (here $f'_v(x, y; k)$ denotes the directional derivative of $f(x, \cdot)$ at y in the direction k).

Proof: It follows from Example 1 that assumption a) of Theorem 2 is satisfied for $\varphi_{u,v} = f'_v(u, v; \cdot)$. Thus it suffices to prove that, for each $k \in Y$, the function $(u, v) \mapsto f'_v(u, v; k)$ is upper semicontinuous on $U \times V$. Take any $\varepsilon > 0$, $\bar{u} \in U$, $\bar{v} \in V$. Since

$$f'_v(\bar{u}, \bar{v}; k) = \inf \{ \lambda^{-1} (f(\bar{u}, \bar{v} + \lambda k) - f(\bar{u}, \bar{v})) \mid \lambda > 0 \}$$

(cf. [8: § 4.1]), there exists $\mu > 0$ such that $\bar{v} + \mu k \in V$ and

$$\mu^{-1} (f(\bar{u}, \bar{v} + \mu k) - f(\bar{u}, \bar{v})) \leq f'_v(\bar{u}, \bar{v}; k) + \varepsilon/2. \quad (14)$$

By the continuity of f at the points (\bar{u}, \bar{v}) and $(\bar{u}, \bar{v} + \mu k)$, there exist neighbourhoods $U' \subset U$ and $V' \subset V$ of \bar{u} and \bar{v} , respectively, such that

$$\max (|f(u, v) - f(\bar{u}, \bar{v})|, |f(u, v + \mu k) - f(\bar{u}, \bar{v} + \mu k)|) \leq \varepsilon\mu/4$$

for all $u \in U'$, $v \in V'$. Hence and from (14) we obtain that, for all $u \in U'$ and $v \in V'$,

$$\begin{aligned} f'_v(u, v; k) &= \inf \{ \lambda^{-1} (f(u, v + \lambda k) - f(u, v)) \mid \lambda > 0 \} \\ &\leq \mu^{-1} (f(u, v + \mu k) - f(u, v)) \\ &= \mu^{-1} (f(u, v + \mu k) - f(\bar{u}, \bar{v} + \mu k)) + \mu^{-1} (f(\bar{u}, \bar{v} + \mu k) - f(\bar{u}, \bar{v})) \\ &\quad + \mu^{-1} (f(\bar{u}, \bar{v}) - f(u, v)) \leq f'_v(\bar{u}, \bar{v}; k) + \varepsilon, \end{aligned}$$

and so $(u, v) \mapsto f'_v(u, v; k)$ is upper semicontinuous at (\bar{u}, \bar{v}) ■

We shall now apply the above corollary to obtain a variant of the Ioffe-Tikhomirov extremum principle (cf. [8: §§ 1.1 and 5.1]). Let us consider the following extremal problem

minimize $f_0(x, y)$ subject to

$$f_i(x, y) \leq 0 \quad (i = 1, \dots, n), \quad F(x, y) = 0, \quad y \in U \quad (15)$$

where $U \subset Y$, $f_i: X \times Y \rightarrow \mathbf{R}$ ($i = 0, 1, \dots, n$), $F: X \times Y \rightarrow Z$ (X, Y, Z — normed spaces).

Theorem 3: Let $(\bar{x}, \bar{y}) \in X \times U$. Assume that

- f_i ($i = 0, 1, \dots, n$) and F satisfy the Lipschitz condition on a neighbourhood of (\bar{x}, \bar{y}) ;
- U is convex and closed;
- there are first order convex approximations φ_i ($i = 0, 1, \dots, n$) and ψ for $f_i(\cdot, \bar{y})$ and $\|F(\cdot, \bar{y})\|$, respectively, at \bar{x} ;
- for each $x \in X$, $f_i(x, \cdot)$ ($i = 0, 1, \dots, n$) and $\|F(x, \cdot)\|$ are convex on Y ;
- (\bar{x}, \bar{y}) is a regular point for F relative to $X \times U$ (i.e. there are $\alpha > 0$ and a neighbourhood V of (\bar{x}, \bar{y}) , such that, for all $(x, y) \in V \cap (X \times U)$, $d_Q(x, y) \leq \alpha \|F(x, y) - F(\bar{x}, \bar{y})\|$ where $Q = \{(x, y) \in X \times U \mid F(x, y) = F(\bar{x}, \bar{y})\}$ and d_Q denotes the distance function to Q).

If (\bar{x}, \bar{y}) is a local solution to (15), then there exist numbers

$$\lambda_i \geq 0 \quad (i = 0, 1, \dots, n), \quad r > 0, \quad (16)$$

such that

$$\lambda_0 + \dots + \lambda_n = 1, \quad \lambda_i f_i(\bar{x}, \bar{y}) = 0 \quad \text{for } i = 1, \dots, n, \tag{17}$$

$$0 \in \sum_{i=0}^n \lambda_i \partial \varphi_i(0) + r \partial \psi(0), \tag{18}$$

$$\begin{aligned} & \sum_{i=0}^n \lambda_i f_i(\bar{x}, \bar{y}) + r \|F(\bar{x}, \bar{y})\| \\ &= \min_{y \in U} \left(\sum_{i=0}^n \lambda_i f_i(\bar{x}, y) + r \|F(\bar{x}, y)\| \right). \end{aligned} \tag{19}$$

Proof: Put $g(x, y) = \|F(x, y)\|$. From Corollary 3 we get that the functions $\omega_i(h, k) = \varphi_i(h) + (f_i)_y'(\bar{x}, \bar{y}; k)$ ($i = 0, 1, \dots, n$), $\eta(h, k) = \psi(h) + g_y'(\bar{x}, \bar{y}; k)$ and $\xi(h, k) = d_{\sigma'}(\bar{y}; k)$ are first order convex approximations for f_i , $\|F\|$ and $d_{X \times U}$, respectively, at (\bar{x}, \bar{y}) . Hence and from [6: Theorem 2] we obtain that there exist numbers (16) satisfying conditions (17) and

$$0 \in \sum_{i=0}^n \lambda_i \partial \omega_i(0, 0) + r \partial \eta(0, 0) + r \partial \xi(0, 0). \tag{20}$$

It is easy to verify (cf. [11: Lemma 2]) that, for any continuous convex function $\omega: X \times Y \rightarrow \mathbb{R}$, if $z^* \in \partial \omega(x, y)$, then there exist $x^* \in \partial(\omega(\cdot, y))(x)$ and $y^* \in \partial(\omega(x, \cdot))(y)$ such that $\langle z^*, (u, v) \rangle = \langle x^*, u \rangle + \langle y^*, v \rangle$ for all $u \in X, v \in Y$. Thus, from (20) we obtain (18) and (by (2))

$$0 \in \sum_{i=0}^n \lambda_i \partial(f_i(\bar{x}, \cdot))(\bar{y}) + r \partial(g(\bar{x}, \cdot))(\bar{y}) + r \partial d_{\sigma'}(\bar{y}). \tag{21}$$

We readily deduce from the definition of the subdifferential (formula (1)) that

$$r \partial d_{\sigma'}(\bar{y}) \subset \partial(\delta(\cdot | U))(\bar{y}) \tag{22}$$

where $\delta(\cdot | U)$ is defined as follows:

$$\delta(v | U) = \begin{cases} 0 & \text{if } v \in U, \\ +\infty & \text{if } v \notin U. \end{cases}$$

Consequently, by the Moreau-Rockafellar theorem [8: § 0.3], (21) and (22) imply

$$0 \in \partial \left(\sum_{i=0}^n \lambda_i f_i(\bar{x}, \cdot) + r \|F(\bar{x}, \cdot)\| + \delta(\cdot | U) \right) (\bar{y}),$$

which is equivalent to (19) ■

We shall now give another application of Theorem 1: to extend the sufficient optimality condition of ДУСЬКHOFF [2] to the case of functions not necessarily directionally differentiable. Let U be a convex subset of X with nonempty interior, and let $\bar{x} \in U$. Suppose that a function $f: U \rightarrow \mathbb{R}$ has first order convex approximations at all points of the set $\tilde{U} = (\text{int } U) \setminus \{\bar{x}\}$, but may have no approximation at \bar{x} . We shall formulate a sufficient condition for \bar{x} to be the global minimum point of f on U .

Proposition 3: Assume that

- a) f is hemi-continuous on each segment $[a, b] \subset U$;
- b) f has a first order convex approximation φ_x at each $x \in \tilde{U}$;

c) for each $y \in \bar{U}$, the functions $x \mapsto \varphi_x(\bar{x} - y)$ and $x \mapsto \varphi_x(y - \bar{x})$, restricted to $]\bar{x}, y[$, are upper semicontinuous;

d) $\varphi_y(\bar{x} - y) \leq 0$ for all $y \in \bar{U}$.

Then $f(\bar{x}) \leq f(x)$ for all $x \in U$.

Proof: Fix $x \in \bar{U}$. By Theorem 1, there exist $c \in]\bar{x}, x[$ and $x^* \in \partial\varphi_c(0)$, such that $f(\bar{x}) - f(x) = \langle x^*, \bar{x} - x \rangle \leq \varphi_c(\bar{x} - x)$. Since $c \in \bar{U}$, we have (by d)) $\varphi_c(\bar{x} - c) \leq 0$. But $\bar{x} - c = \lambda(\bar{x} - x)$ for some $\lambda > 0$; hence $\varphi_c(\bar{x} - x) \leq 0$ and $f(\bar{x}) \leq f(x)$.

Assume now that $x \in U \setminus \bar{U}$. Take any $u \in \bar{U}$. It follows from a) and from the convexity of U that, for each $\varepsilon > 0$, there exists $w \in]x, u[\cap \bar{U}$ such that $f(w) \leq f(\bar{x}) + \varepsilon$. By the first part of the proof, $f(\bar{x}) \leq f(w)$. Thus $f(\bar{x}) \leq f(x)$ ■

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