

Existence and Approximation Results to the Cauchy Problem for a Class of Differential-Algebraic Equations

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For a class of differential-algebraic equations arising for example in modelling electrical circuits conditions are derived which ensure the existence of a unique solution of the Cauchy problem on any finite interval and its computation by means of a wave-form relaxation algorithm in case of a large system. The solution concept is understood in the sense of Carathéodory.

Key words: differential-algebraic equations, Carathéodory solution, wave-form relaxation
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1. Introduction

This paper is concerned with the initial value problem for differential-algebraic systems of the form

$$\frac{dx}{dt} = F(x, z, \frac{dx}{dt}, t), \quad z = G(x, z, \frac{dx}{dt}, t), \quad x(t_0) = x_0, \quad t \in J := [t_0, t_0 + T], \quad (1.1)$$

where x is an n -vector, z is an m -vector, and T is a given positive number. We are interested in conditions guaranteeing the existence of a unique solution (\bar{x}, \bar{z}) of (1.1) and in iterative procedures approaching (\bar{x}, \bar{z}) in case $n + m$ to be large. The problem formulated above arises for example in modelling non-linear electrical networks [6]. By using Kirchhoff's laws, the underlying constitutive relations (voltage-current relations) and the corresponding dynamic equations we arrive at a system of the kind

$$H(dy/dt, y, t) = 0, \quad (1.2)$$

where the vector y of network variables consists of two components x and z and the derivative of z does not occur in (1.2). Thus, without loss of generality we may represent the system (1.2) in the form (1.1).

By applying traditional integration procedures to solve the initial value problem (1.1) the computing time grows rapidly when $n + m$ becomes large. From this reason, new methods for numerical treatment of such problems has been developed basing on the decomposition either of the corresponding large system of linear equations in the process of discretization or of the corresponding differential-algebraic system (1.1) itself. In the latter case this method is called *wave-form relaxation method* [1, 3-5]. For a broad class of wave-form relaxation methods the canonical iteration scheme reads

$$\begin{aligned} dx^k/dt &= \tilde{F}(x^k, x^{k-1}, z^{k-1}, dx^{k-1}/dt, t) \\ z^k &= \tilde{G}(x^k, x^{k-1}, z^{k-1}, dx^{k-1}/dt, t) \end{aligned} \quad x^k(t_0) = x_0, \quad t \in J. \quad (1.3)$$

The convergence of this scheme in some Banach space was proved in [3] under a crucial assumption whose verification is not obvious. In this paper we derive an explicit condition on the Lipschitz constants of F and G which implies the convergence of (1.3). At the same time we give a new short proof of the convergence of (1.3) and introduce a solution concept, the so-called *Carathéodory solution* which is more appropriate for applications.

2. Notation and definitions

Let $|\cdot|$ be the Euclidean norm, $L^p(J, \mathbb{R}^k)$ the space of functions $z: J \rightarrow \mathbb{R}^k$ such that $|z|^k$ is integrable in the sense of Lebesgue, and $L^\infty(J, \mathbb{R}^k)$ the set of functions $z: J \rightarrow \mathbb{R}^k$ the essential supremum (ess sup) of which is bounded. Further, let $C(J, \mathbb{R}^k)$ be the space of continuous functions $z: J \rightarrow \mathbb{R}^k$, $AC(J, \mathbb{R}^k)$ the set of all functions $z \in C(J, \mathbb{R}^k)$ which are absolutely continuous

Definition 2.1: Let D be a set in \mathbb{R}^k . A function $f: D \times J \rightarrow \mathbb{R}^l$ is said to satisfy the *Carathéodory condition* if

- (i) f is defined for all $x \in D$ and for almost all (f.a.a.) $t \in J$,
- (ii) f is continuous in x f.a.a. $t \in J$ and (Lebesgue) measurable in t for all $x \in D$.

Definition 2.2: The couple (\bar{x}, \bar{z}) is said to be a *solution of (1.1) in the sense of Carathéodory (Ca-solution)* if

- (i) $(\bar{x}, \bar{z}) \in AC(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m)$,
- (ii) (\bar{x}, \bar{z}) satisfies (1.1) f.a.a. $t \in J$,
- (iii) $\bar{x}(t_0) = x_0$.

To make our representation self-consistent we include some results on explicite ordinary differential equations.

3. Global results for the Cauchy problem of ordinary differential equations

Consider the system of ordinary differential equations

$$dx/dt = f(x, t) \tag{3.1}$$

under the following hypotheses:

(3.1)_i The function $f: \mathbb{R}^n \times J \rightarrow \mathbb{R}^n$ satisfies the Carathéodory condition.

(3.1)_{ii} There are a constant c and a function $m \in L^1(J, \mathbb{R}^+)$ such that

$$|f(x, t)| \leq m(t) + c|x| \text{ for all } x \in \mathbb{R}^n \text{ and f.a.a. } t \in J.$$

The hypotheses (3.1)_i and (3.2)_{ii} imply the following important property for the *Nemyzki operator* F defined by $(Fx)(t) = f(x(t), t)$.

Lemma 3.1 [2]: Assume f satisfies the hypotheses (3.1)_i and (3.2)_{ii}. Then F is a continuous mapping from $L^1(J, \mathbb{R}^n)$ into itself.

Further we suppose on f the following hypothesis:

(3.1)_{iii} To any number $q, 0 < q < 1$, there is a norm $\|\cdot\|$ in $C(J, \mathbb{R}^n)$ with the properties

- (a) $C(J, \mathbb{R}^n)$ equipped with the norm $\|\cdot\|$ is a Banach space,
- (b) the operator $\bar{F}: C(J, \mathbb{R}^n) \rightarrow C(J, \mathbb{R}^n)$ defined by

$$(\bar{F}x)(t) = \int_{t_0}^t (Fx)(s) ds = \int_{t_0}^t f(x(s), s) ds$$

is strictly contractive with respect to the norm $\|\cdot\|$ with the contraction constant q .

The hypothesis (3.1)_{iii} can be fulfilled if f satisfies for instance a condition of the type

$$|f(x_1, t) - f(x_2, t)| \leq \omega(|x_1 - x_2|, t) \text{ for all } x_1, x_2 \in \mathbb{R}^n \text{ and } t \in J,$$

where $\omega: \mathbb{R}^+ \times J \rightarrow \mathbb{R}^+$ obeys the Carathéodory condition and the inequality

$$\left\| \int_{t_0}^t \omega(|x(s)|, s) ds \right\| \leq q \|x\| \text{ for all } x \in C(J, \mathbb{R}^n) \text{ and } t \in J.$$

In case $\omega(s, t) = s l(t)$ where $l \in L^1(J, \mathbb{R}^+)$ we can choose the norm

$$\|x\| = \max_{t \in J} \left\{ \exp \left[-\alpha \int_{t_0}^t l(s) ds \right] |x(t)| \right\},$$

where α is any positive number satisfying $\alpha > 1$. Obviously, for $x \in C(J, \mathbb{R}^n)$ we have

$$\begin{aligned} & \left\| \int_{t_0}^t \omega(|x(s)|, s) ds \right\| \\ &= \left\| \int_{t_0}^t |x(s)| l(s) ds \right\| = \max_{t \in J} \left\{ \exp \left[-\alpha \int_{t_0}^t l(s) ds \right] \left| \int_{t_0}^t l(s) |x(s)| ds \right| \right\} \\ &= \max_{t \in J} \left\{ \exp \left[-\alpha \int_{t_0}^t l(s) ds \right] \left| \int_{t_0}^t l(s) \exp \left[\alpha \int_{t_0}^s l(\sigma) d\sigma \right] \exp \left[-\alpha \int_{t_0}^s l(\sigma) d\sigma \right] |x(s)| ds \right| \right\} \\ &\leq \|x\| \max_{t \in J} \left\{ \exp \left[-\alpha \int_{t_0}^t l(s) ds \right] \left| \int_{t_0}^t l(s) \exp \left[\alpha \int_{t_0}^s l(\sigma) d\sigma \right] ds \right| \right\} \\ &= \|x\| \max_{t \in J} \left\{ \exp \left[-\alpha \int_{t_0}^t l(s) ds \right] \frac{1}{\alpha} \left[\exp \left[\alpha \int_{t_0}^t l(s) ds \right] - 1 \right] \right\} \leq \frac{1}{\alpha} \|x\|, \end{aligned}$$

that is, $q = 1/\alpha$ is arbitrary small provided α is sufficiently large.

Theorem 3.2: Assume the hypotheses (3.1)_i - (3.1)_{iii} hold. Then the Cauchy problem $dx/dt = f(x, t), x(t_0) = x_0, t \in J$ (3.2)

has a unique Ca-solution on J where T is any fixed positive number.

Proof: Let X be the space $C(J, \mathbb{R}^n)$ equipped with the norm $\|\cdot\|$. We define the operator F_0 by

$$(F_0 x)(t) = x_0 + (\bar{F}x)(t) = x_0 + \int_{t_0}^t f(x(s), s) ds.$$

By Lemma 3.1, the hypotheses (3.1)_i and (3.1)_{ii} imply $f(x(\cdot), \cdot) \in L^1(J, \mathbb{R}^n)$ for $x \in X$, thus we have $\bar{F}x \in AC(J, \mathbb{R}^n) \subset C(J, \mathbb{R}^n)$, that is $F_0 X \subset X$. Using the hypothesis (3.1)_{iii} we have

$$\|F_0(x_1) - F_0(x_2)\| \leq q \|x_1 - x_2\| \text{ for all } x_1, x_2 \in X,$$

where q can be assumed to be less than one. By Banach's fixed point theorem, F_0 has a unique fixed point x^* in X which is a Ca-solution of (3.2) ■

Next we study the case where f depends on some functional parameter z and investigate the dependence of x^* on z . The obtained result is used to establish an existence theorem for the Cauchy problem of some class of implicate differential equations.

Let us consider the initial value problem

$$dx/dt = f_1(x, z(t), t), \quad \dot{x}(t_0) = x_0, \quad t \in J \tag{3.3}$$

assuming the following hypotheses:

(3.3)_i The function $f_1: \mathbb{R}^n \times \mathbb{R}^m \times J \rightarrow \mathbb{R}^n$ satisfies the Carathéodory condition.

(3.3)_{ii} There are a constant $c_1 > 0$ and a function $m_1 \in L^1(J, \mathbb{R}^+)$ such that

$$|f_1(x, z, t)| \leq m_1(t) + c_1(|x| + |z|) \text{ for all } (x, z) \in \mathbb{R}^n \times \mathbb{R}^m \text{ and f.a.a. } t \in J.$$

(3.3)_{iii} The function z belongs to the space $L^1(J, \mathbb{R}^m)$.

(3.3)_{iv} There are positive numbers q_1 and k_1 where q_1 can be chosen arbitrarily small and a norm $\|\cdot\|$ in $C(J, \mathbb{R}^n)$ with the properties

- (a) $C(J, \mathbb{R}^n)$ equipped with the norm $\|\cdot\|$ is a Banach space,
- (b) the operator $F_1: C(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m) \rightarrow L^1(J, \mathbb{R}^n)$ defined by

$$(F_1(x, z))(t) = f_1(x(t), z(t), t) \tag{3.4}$$

satisfies the relation

$$\|F_1(x, z) - F_1(\bar{x}, \bar{z})\| \leq q_1 \|x - \bar{x}\| + k_1 \|z - \bar{z}\| \tag{3.5}$$

for $x, \bar{x} \in C(J, \mathbb{R}^n)$ and $z, \bar{z} \in L^1(J, \mathbb{R}^m)$, where $\|\cdot\|$ is defined by

$$\|z\| = \left\| \int_{t_0}^t |z(s)| ds \right\|. \tag{3.6}$$

In case that f_1 fulfills the generalized Lipschitz condition

$$|f_1(x_1, z_1, t) - f_1(x_2, z_2, t)| \leq \lambda_1(t)|x_1 - x_2| + \alpha_1(t)|z_1 - z_2|$$

for $x_1, x_2 \in \mathbb{R}^n, z_1, z_2 \in \mathbb{R}^m, t \in \mathbb{R}$, where $\lambda_1 \in L^1(J, \mathbb{R}^+)$ and $\alpha_1 \in L^\infty(\mathbb{R}^+)$ with $\text{ess sup } \alpha_1 \leq \bar{k}_1$, we can choose a norm in $C(J, \mathbb{R}^n)$ by

$$\|x\| = \max_{t \in J} \left\{ \exp \left[-\alpha \int_{t_0}^t \lambda_1(s) ds \right] |x(t)| \right\}, \quad \alpha > 1.$$

Then we have according to (3.6)

$$\|z\| = \max_{t \in J} \left\{ \exp \left[-\alpha \int_{t_0}^t \lambda_1(s) ds \right] \int_{t_0}^t |z(t)| dt \right\}.$$

Thus, (3.5) holds with $q_1 \leq 1/\alpha$ and $k_1 \leq \bar{k}_1$.

By Lemma 3.1, the hypotheses (3.3)_i - (3.3)_{iv} imply that $f(x, t) := f_1(x, z(t), t)$ satisfies the assumptions (3.1)_i - (3.1)_{iii}. Thus, to any $z \in L^1(J, \mathbb{R}^m)$ the Cauchy problem (3.3) has a unique Ca-solution denoted by x_z . Concerning the dependence of x_z on z we have the following result.

Theorem 3.3: Assume the hypotheses (3.3)_i - (3.3)_{iv} are valid. Let x_{z_1}, x_{z_2} be the Ca-solutions of (3.3) to $z_1, z_2 \in L^1(J, \mathbb{R}^m)$, respectively. Then we have

$$\|x_{z_1} - x_{z_2}\| \leq k_1 / (1 - q_1) \|z_1 - z_2\|, \tag{3.7}$$

where q_1 can be supposed to be less than one.

Proof: The solutions x_{z_1} and x_{z_2} satisfy the integral equation

$$y(t) = x_0 + \int_{t_0}^t f(y(s), z(s), s) ds, \quad t \in J. \tag{3.8}$$

From (3.8) and (3.4) - (3.6) we get

$$\|x_{z_1} - x_{z_2}\| = \|F_1(x_{z_1}, z_1) - F_1(x_{z_2}, z_2)\| \leq q_1 \|x_{z_1} - x_{z_2}\| + k_1 \|z_1 - z_2\|. \tag{3.9}$$

Since we may suppose $q_1 < 1$ we obtain from (3.9) the inequality (3.7) ■

Now we apply this result to prove a global existence theorem for the Cauchy problem of a class of implicit differential equations

$$dx/dt = f_1(x, dx/dt, t), \quad x(t_0) = x_0, \quad t \in J. \tag{3.10}$$

Theorem 3.4: Suppose f_1 satisfies the hypotheses (3.3)_i, (3.3)_{ii} and (3.3)_{iv}. Under the additional assumption

$$k_1 < 1 \tag{3.11}$$

the Cauchy problem (3.10) has a unique Ca-solution where T is any fixed positive number.

Proof: Consider the Cauchy problem (3.3) in case $m = n$. By Theorem 3.2, to any $z \in L^1(J, \mathbb{R}^n)$ the problem (3.3) has a unique solution x_z on J . We define the operator $\tilde{F}_1: L^1(J, \mathbb{R}^n) \rightarrow L^1(J, \mathbb{R}^n)$ by $(\tilde{F}_1 z)(t) = f_1(x_z(t), z(t), t)$. By (3.4) - (3.6) we have for $z_1, z_2 \in L^1(J, \mathbb{R}^n)$

$$\| \tilde{F}_1(z_1) - \tilde{F}_1(z_2) \| \leq q_1 \|x_{z_1} - x_{z_2}\| + k_1 \|z_1 - z_2\| \leq k_1/(1-q_1) \|z_1 - z_2\|.$$

Hence, \tilde{F}_1 is strictly contractive iff $k_1 + q_1 < 1$. As we can choose q_1 arbitrarily small, the validity of (3.11) implies \tilde{F}_1 to be strictly contractive on $L^1(J, \mathbb{R}^m)$. Therefore, \tilde{F}_1 has a unique fixed point z^* satisfying $dx_{z^*}/dt = f_1(x_{z^*}(t), z^*(t), t) = z^*$, that means (3.10) has a unique Ca-solution on J ■

4. Global results for the Cauchy problem to a class of differential-algebraic equations

Next we consider the Cauchy problem

$$\begin{aligned} dx/dt &= f_1(x, z(t), t) & x(t_0) &= x_0, \quad t \in J \\ z(t) &= g_1(x(t), z(t), t) \end{aligned} \tag{4.1}$$

under the following hypotheses:

(4.1)_i The functions $f_1: \mathbb{R}^n \times \mathbb{R}^m \times J \rightarrow \mathbb{R}^n$, $g_1: \mathbb{R}^n \times \mathbb{R}^m \times J \rightarrow \mathbb{R}^m$ obey the Carathéodory condition.

(4.1)_{ii} There are a constant $\bar{c}_1 > 0$ and a function $\bar{m}_1 \in L^1(J, \mathbb{R}^+)$ such that $|f_1(x, z, t) + g_1(x, z, t)| \leq \bar{m}_1(t) + \bar{c}_1(|x| + |z|) \quad \forall (x, z) \in \mathbb{R}^n \times \mathbb{R}^m$ and f.a.a. $t \in J$.

(4.1)_{iii} The function f_1 satisfies the hypothesis (3.3)_{iv}.

(4.1)_{iv} The function g_1 is such that the operator $G_1: C(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m) \rightarrow L^1(J, \mathbb{R}^m)$ defined by $G_1(x, z)(t) = g_1(x(t), z(t), t)$ fulfills for all elements $x_1, x_2 \in C(J, \mathbb{R}^n)$ and $z_1, z_2 \in L^1(J, \mathbb{R}^m)$ the relation

$$\| G_1(x_1, z_1) - G_1(x_2, z_2) \| \leq q_2 \|x_1 - x_2\| + k_2 \|z_1 - z_2\|. \tag{4.2}$$

Theorem 4.1: Assume the hypotheses (4.1)_i - (4.1)_{iv} hold. If we additionally suppose $k_2 < 1$,

then the Cauchy problem (4.1) has a unique Ca-solution on J with any $T > 0$.

Proof: By Theorem 3.3, the hypotheses (4.1)_i - (4.1)_{iii} imply that the differential equation in (4.1) has to any $z \in L^1(J, \mathbb{R}^m)$ a unique Ca-solution x_z satisfying $x_z(t_0) = x_0$. We define the operator \tilde{G}_1 on $L^1(J, \mathbb{R}^m)$ by

$$(\tilde{G}_1 z)(t) = g_1(x_z(t), z(t), t) \tag{4.4}$$

It is obvious that under our conditions \tilde{G}_1 maps from $L^1(J, \mathbb{R}^m)$ into $L^1(J, \mathbb{R}^m)$. From the relations (4.4) and (4.2) we get

$$\| \tilde{G}_1 z_1 - \tilde{G}_1 z_2 \| \leq q_2 \| x_{z_1} - x_{z_2} \| + k_2 \| |z_1 - z_2| \| \text{ for all } z_1, z_2 \in L^1(J, \mathbb{R}^m). \quad (4.5)$$

Taking into account (3.7) we obtain from (4.5)

$$\| \tilde{G}_1 z_1 - \tilde{G}_1 z_2 \| \leq (k_1 q_2 / (1 - q_1) + k_2) \| |z_1 - z_2| \|.$$

Thus, for sufficiently small q_2 the condition (4.3) implies that \tilde{G}_1 is strictly contractive on $L^1(J, \mathbb{R}^m)$ and has a unique fixed point z^* . Therefore, the couple (x_{z^*}, z^*) is a Ca-solution of (4.1) on J ■

In the next step we study the dependence of the solution (\bar{x}, \bar{z}) on some functional parameter. To this end we consider the problem

$$\begin{aligned} dx/dt &= F(x, z(t), y(t), t) & x(t_0) &= x_0, \quad t \in J \\ z(t) &= G(x(t), z(t), y(t), t) \end{aligned} \quad (4.6)$$

and assume the following hypotheses:

- (4.6)_i The function y belongs to the space $L^1(J, \mathbb{R}^k)$.
- (4.6)_{ii} The functions $F: \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^k \times J \rightarrow \mathbb{R}^n$ and $G: \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^k \times J \rightarrow \mathbb{R}^m$ satisfy the Carathéodory condition.
- (4.6)_{iii} There are a constant $\bar{c} > 0$ and a function $\bar{m} \in L^1(J, \mathbb{R}^+)$ such that

$$|F(x, z, y, t)| + |G(x, z, y, t)| \leq \bar{m}(t) + \bar{c}_1(|x| + |z| + |y|)$$

for all $(x, z, y) \in \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^n$ and f.a.a. $t \in J$.

- (4.6)_{iv} There are positive numbers q_i, k_i, l_i ($i = 1, 2$) where q_i can be chosen arbitrarily small and a norm $\| \cdot \|$ in $C(J, \mathbb{R}^n)$ such that the following conditions are satisfied:

- (a) $C(J, \mathbb{R}^n)$ equipped with the norm $\| \cdot \|$ is a Banach space.
- (b) The operator $F_2: C(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m) \times L^1(J, \mathbb{R}^k) \rightarrow L^1(J, \mathbb{R}^n)$ defined by

$$(F_2(x, z, y))(t) = F(x(t), z(t), y(t), t) \quad (4.7)$$

satisfies the relation

$$\| |F_2(x, z, y) - F_2(\bar{x}, \bar{y}, \bar{z})| \| \leq q_1 \| x - \bar{x} \| + k_1 \| |z - \bar{z}| \| + l_1 \| |y - \bar{y}| \|. \quad (4.8)$$

- (c) The operator $G_2: C(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m) \times L^1(J, \mathbb{R}^k) \rightarrow L^1(J, \mathbb{R}^m)$ defined by

$$(G_2(x, z, y))(t) = G(x(t), z(t), t) \quad (4.9)$$

satisfies the relation

$$\| |G_2(x, z, y) - G_2(\bar{x}, \bar{y}, \bar{z})| \| \leq q_2 \| x - \bar{x} \| + k_2 \| |z - \bar{z}| \| + l_2 \| |y - \bar{y}| \|. \quad (4.10)$$

- (d) The relation (4.3) holds.

According to Theorem 4.1 the problem (4.6) has to any $y \in L^1(J, \mathbb{R}^k)$ a unique Ca-solution (\bar{x}_y, \bar{z}_y) . With respect to the dependence on y we have the following result.

Theorem 4.2: Assume the hypotheses (4.6)_i - (4.6)_{iv} are valid. Then we have

$$\| \bar{x}_{y_1} - \bar{x}_{y_2} \| \leq \gamma \| |y_1 - y_2| \|, \quad (4.11)$$

$$\| \bar{z}_{y_1} - \bar{z}_{y_2} \| \leq \left\{ \frac{q_2 \gamma + l_2}{1 - k_2} \right\} \| |y_1 - y_2| \|, \text{ where } \gamma = \frac{k_1 l_2 + l_1 (1 - k_2)}{(1 - q_1)(1 - k_2) - k_1 q_2}. \quad (4.12)$$

Proof : Let $y_1, y_2 \in L^1(J, \mathbf{R}^k)$ be given. The corresponding solutions $(\bar{x}_{y_1}, \bar{z}_{y_1}), (\bar{x}_{y_2}, \bar{z}_{y_2})$ of (4.6) satisfy the problem

$$x(t) = x_0 + \int_{t_0}^t f(x(s), z(s), y(s), s) ds, \quad z(t) = g(x(t), z(t), y(t), t). \quad (4.13)$$

Using (4.7) and (4.8) we get from (4.13) the estimate

$$\begin{aligned} \|\bar{x}_{y_1} - \bar{x}_{y_2}\| &= \left\| F_2(\bar{x}_{y_1}, \bar{z}_{y_1}, y_1) - F_2(\bar{x}_{y_2}, \bar{z}_{y_2}, y_2) \right\| \\ &\leq q_1 \|\bar{x}_{y_1} - \bar{x}_{y_2}\| + k_1 \|\bar{z}_{y_1} - \bar{z}_{y_2}\| + l_1 \|y_1 - y_2\|. \end{aligned} \quad (4.14)$$

For $q_1 < 1$ we obtain from (4.14) the estimate

$$\|\bar{x}_{y_1} - \bar{x}_{y_2}\| \leq \frac{k_1}{1 - q_1} \|\bar{z}_{y_1} - \bar{z}_{y_2}\| + \frac{l_1}{1 - q_1} \|y_1 - y_2\|. \quad (4.15)$$

Taking into account (4.9), (4.10) and (4.3) we get from (4.13) the estimate

$$\|\bar{z}_{y_1} - \bar{z}_{y_2}\| \leq q_2 \|\bar{x}_{y_1} - \bar{x}_{y_2}\| + \frac{l_2}{1 - k_2} \|y_1 - y_2\|. \quad (4.16)$$

Substituting (4.16) into (4.15) we obtain the estimate

$$\|\bar{x}_{y_1} - \bar{x}_{y_2}\| \leq \frac{k_1}{1 - q_1} \left\{ \frac{q_2}{1 - k_2} \|\bar{x}_{y_1} - \bar{x}_{y_2}\| + \frac{l_2}{1 - k_2} \|y_1 - y_2\| \right\} + \frac{l_1}{1 - q_1} \|y_1 - y_2\|. \quad (4.17)$$

For sufficiently small q_2 the inequality (4.11) follows immediately from (4.17). Using (4.11) we get from (4.16) the inequality (4.12) ■

Finally we consider the Cauchy problem for the class of differential-algebraic equations

$$\begin{aligned} dx/dt &= F(x, z(t), dx/dt, t), & x(t_0) &= x_0, \quad t \in J, \\ z(t) &= G(x(t), z(t), dx/dt, t) \end{aligned} \quad (4.18)$$

Using Theorem 4.2 we can prove the existence and uniqueness of a solution to (4.18).

Theorem 4.3: Assume the hypotheses (4.6)_{ii} - (4.6)_{iv} with $n = k$ are valid. Additionally we assume

$$k_2 < 1, \quad l_1 + k_1 l_2 / (1 - k_2) < 1. \quad (4.19)$$

Then the Cauchy problem (4.18) has a unique Ca-solution on J , where T is any positive number.

Proof: To $y \in L^1(J, \mathbf{R}^n)$ given, by Theorem 4.1 the problem (4.6) has a unique solution (\bar{x}_y, \bar{z}_y) . We define the operator F_3 on $L^1(J, \mathbf{R}^n)$ by

$$(F_3 y)(t) = F(\bar{x}_y(t), \bar{z}_y(t), y(t), t). \quad (4.20)$$

Under the hypotheses above we have $F_3: L^1(J, \mathbf{R}^n) \rightarrow L^1(J, \mathbf{R}^n)$. We shall prove that F_3 is also strictly contractive under the same conditions. Let $y_1, y_2 \in L^1(J, \mathbf{R}^n)$. By (4.7), (4.8) we get from (4.20)

$$\|F_3(y_1) - F_3(y_2)\| \leq q_1 \|\bar{x}_{y_1} - \bar{x}_{y_2}\| + k_1 \|\bar{z}_{y_1} - \bar{z}_{y_2}\| + l_1 \|y_1 - y_2\|.$$

By using (4.11) and (4.12) it follows

$$\|F_3(y_1) - F_3(y_2)\| \leq \left\{ q_1 \gamma + \frac{k_1 q_2 \gamma}{1 - k_2} + \frac{k_1 l_2}{1 - k_2} + l_1 \right\} \|y_1 - y_2\|.$$

Since q_1 and q_2 may be chosen arbitrarily small and since γ is uniformly bounded for

decreasing q_1 and q_2 the condition (4.19) implies that F_3 is strictly contractive on $L^1(J, \mathbb{R}^n)$ and has a unique fixed point y^* in $L^1(J, \mathbb{R}^n)$. Then the couple $(\bar{x}_{y^*}, \bar{y}_{y^*})$ is the unique Ca-solution of (4.18) ■

5. Numerical approximation

As mentioned in the introduction, an important tool for the numerical integration of a broad class of differential-algebraic equations (1.1) in case $n + m$ to be large is the wave-form relaxation method. This approach represents an iteration method in some function space, the essential feature of which is to decompose the large system (1.1) into a set of subsystems each of which is integrated independently on J and taking into account inputs from other subsystems from their state on the previous iteration [3,5]. This process is equivalent to rewrite the problem (1.1) as

$$\begin{aligned} d\xi/dt &= \tilde{f}(\xi, \xi, \zeta, d\xi/dt, t) & \xi(t_0) &= x_0, t \in J, \\ \zeta &= \tilde{g}(\xi, \xi, \zeta, d\xi/dt, t) \end{aligned} \tag{5.1}$$

where $\xi \in \mathbb{R}^n, \zeta \in \mathbb{R}^m$, and to choose an iteration scheme providing a sequence of approximations converging to the solution of (5.1). Theorem 4.3 can be easily extended to the Cauchy problem (5.1).

Theorem 5.1: Assume the following hypotheses:

(5.1)_I The functions $\tilde{f}: \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^n \times J \rightarrow \mathbb{R}^n$ and $\tilde{g}: \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^n \times J \rightarrow \mathbb{R}^m$ obey the Carathéodory condition.

(5.1)_{II} There are a constant \tilde{c} and a function $\tilde{m} \in L^1(J, \mathbb{R}^+)$ such that

$$|\tilde{f}(w, x, z, y, t)| + |\tilde{g}(w, x, z, y, t)| \leq \tilde{m}(t) + \tilde{c}(|w| + |x| + |z| + |y|)$$

for all $(w, x, z, y) \in \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^n$ and f.a.a. $t \in J$.

(5.1)_{III} There are positive numbers $q_i, k_j, l_i (i = 1, 2)$, where q_1 and q_2 can be chosen arbitrarily small, and a norm $\|\cdot\|$ in $C(J, \mathbb{R}^n)$ such that the following conditions are satisfied:

(a) $C(J, \mathbb{R}^n)$ equipped with the norm $\|\cdot\|$ is a Banach space.

(b) The operator $\tilde{F}_2: C(J, \mathbb{R}^n) \times C(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m) \times L^1(J, \mathbb{R}^n) \rightarrow L^1(J, \mathbb{R}^n)$ defined by

$$(\tilde{F}_2(w, x, z, y, t))(t) = \tilde{f}(w(t), x(t), z(t), y(t), t) \tag{5.2}$$

satisfies the relation

$$\begin{aligned} &\| \tilde{F}_2(w, x, z, y) - \tilde{F}_2(\bar{w}, \bar{x}, \bar{z}, \bar{y}) \| \\ &\leq q_1(\|w - \bar{w}\| + \|x - \bar{x}\|) + k_1\|z - \bar{z}\| + l_1\|y - \bar{y}\|. \end{aligned} \tag{5.3}$$

(c) The operator $\tilde{G}_2: C(J, \mathbb{R}^n) \times C(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m) \times L^1(J, \mathbb{R}^n) \rightarrow L^1(J, \mathbb{R}^n)$ defined by

$$(\tilde{G}_2(w, x, z, y, t))(t) = \tilde{g}(w(t), x(t), z(t), y(t), t) \tag{5.4}$$

satisfies the relation

$$\begin{aligned} &\| \tilde{G}_2(w, x, z, y) - \tilde{G}_2(\bar{w}, \bar{x}, \bar{z}, \bar{y}) \| \\ &\leq q_2(\|w - \bar{w}\| + \|x - \bar{x}\|) + k_2\|z - \bar{z}\| + l_2\|y - \bar{y}\|. \end{aligned} \tag{5.5}$$

(5.1)_{iv} The relations (4.19) hold.

Then the Cauchy problem (5.1) has a unique Ca-solution on J where T is any positive number.

The **Proof** of this theorem proceeds in the same way as for Theorem 4.3 ■

In what follows we prove that the hypotheses of Theorem 5.1 guaranteeing the existence of a unique solution (ξ^*, ζ^*) of (5.1) also ensures that this solution can be iteratively approximated by a wave-form relaxation algorithm. To this end we consider the iteration scheme

$$\begin{aligned}\xi^k(t) &= \xi_0 + \int_{t_0}^t \tilde{F}(\xi^k(s), \xi^{k-1}(s), \zeta^{k-1}(s), \eta^{k-1}(s), s) ds, \\ \zeta^k(t) &= \tilde{G}(\xi^k(s), \xi^{k-1}(s), \zeta^{k-1}(s), \eta^{k-1}(s), s), \\ \eta^k(t) &= \tilde{F}(\xi^k(s), \xi^{k-1}(s), \zeta^{k-1}(s), \eta^{k-1}(s), s).\end{aligned}\quad (5.6)$$

Let us set $S = C(J, \mathbb{R}^n) \times L^1(J, \mathbb{R}^m) \times L^1(J, \mathbb{R}^n)$. Under the assumptions of Theorem 5.1, the scheme (5.6) defines an operator T mapping the space S into itself. We introduce a norm $\|\cdot\|_{a,b}$ in S by

$$\|(\xi, \zeta, \eta)\|_{a,b} = a\|\xi\| + b(\|\zeta\| + \|\eta\|), \quad (5.7)$$

where a and b are any positive numbers. The space S equipped with that norm is a Banach space. In the sequel we establish the existence of numbers a and b such that T is strictly contractive with respect to the norm $\|\cdot\|_{a,b}$.

Theorem 5.2: Assume the hypotheses of Theorem 5.1 are satisfied. Then there are positive numbers a and b such that the sequence $\{(\xi^k, \zeta^k, \eta^k)\}$ defined by (5.6) converges with respect to the norm $\|\cdot\|_{a,b}$ to the unique solution (ξ^*, ζ^*) of (5.1) for any initial guess in S .

Proof: Using the abbreviation $\Delta^{k+1}v = v^{k+1} - v^k$ we get from (5.6), (5.2), (5.3) and (4.2)

$$\begin{aligned}\|\Delta^{k+1}\xi\| &= \|\tilde{F}_2(\xi^{k+1}, \xi^k, \zeta^k, \eta^k) - \tilde{F}_2(\xi^k, \xi^{k-1}, \zeta^{k-1}, \eta^{k-1})\| \\ &\leq q_1(\|\Delta^{k+1}\xi\| + \|\Delta^k\xi\|) + k_1\|\Delta^k\zeta\| + l_1\|\Delta^k\eta\|.\end{aligned}\quad (5.8)$$

For $q_1 < 1$ it follows from (5.8)

$$\|\Delta^{k+1}\xi\| \leq \frac{q_1}{1-q_1}\|\Delta^k\xi\| + \frac{k_1}{1-q_1}\|\Delta^k\zeta\| + \frac{l_1}{1-q_1}\|\Delta^k\eta\|. \quad (5.9)$$

By a similar way we obtain

$$\|\Delta^{k+1}\eta\| \leq \frac{q_1}{1-q_1}\|\Delta^k\xi\| + \frac{k_1}{1-q_1}\|\Delta^k\zeta\| + \frac{l_1}{1-q_1}\|\Delta^k\eta\|.$$

From (5.6), (5.4), (5.5) and (5.9) it follows

$$\|\Delta^{k+1}\zeta\| \leq \frac{q_2}{1-q_1}\|\Delta^k\xi\| + \frac{k_2(1-q_1) + q_2k_1}{1-q_1}\|\Delta^k\zeta\| + l_2\frac{k_2(1-q_1) + q_2k_1}{1-q_1}\|\Delta^k\eta\|.$$

Let us set $\omega = (\xi, \zeta, \eta)$ and $a = 2(bq_1 + q_2)$ in (5.7). Then we get from (5.7) - (5.9)

$$\begin{aligned}
 (1 - q_1) \|\Delta^{k+1}\omega\|_{a,b} &= (2(bq_1 + q_2)q_1 + bq_2 + q_1) \|\Delta^k \xi\| \\
 &\quad + (2(bq_1 + q_2)k_1 + b(k_2 + q_2k_1 - k_2q_1) + k_1) \|\Delta^k \zeta\| \\
 &\quad + (2(bq_1 + q_2)l_1 + b(l_2 + q_2l_1 - l_2q_1) + l_1) \|\Delta^k \eta\|.
 \end{aligned} \tag{5.10}$$

From (5.10) it follows that if there exists a positive number b satisfying the inequalities

$$bk_2 + k_1 < b \text{ and } bl_2 + l_1 < 1 \tag{5.11}$$

then there are positive numbers q_0 and $x \in (0, 1)$ such that for $q_1, q_2 < q_0$ the relations

$$\begin{aligned}
 (2(bq_1 + q_2)k_1 + b(k_2(1 - q_1) + q_2k_1) + k_1) &\leq (1 - q_1)x b \\
 (2(bq_1 + q_2)l_1 + b(l_2(1 - q_1) + q_2l_1) + l_1) &\leq (1 - q_1)x
 \end{aligned} \tag{5.12}$$

hold. The inequalities (5.11) are equivalent to $k_1/(1 - k_2) < b < (1 - l_1)/l_2$. It is easy to show that the relations (4.19) holding accordingly to the hypothesis (5.1)_{iv} imply $k_1/(1 - k_2) < (1 - l_1)/l_2$. Thus, there is a positive number b satisfying (5.12). To such a number b there is a number $q^* < q_0$ such that, for $q_1, q_2 < q^*$, the inequality

$$(2(bq_1 + q_2)q_1 + bq_2 + q_1) \leq (1 - q_1)x 2(bq_1 + q_2)$$

holds. Therefore, we have

$$\|\Delta^{k+1}\omega\|_{a,b} \leq x \|\Delta^k\omega\|_{a,b} \text{ for } q_1, q_2 < q^*.$$

Hence, the sequence $\{\{\xi^k, \zeta^k, \eta^k\}\}$ converges with respect to the norm $\|\cdot\|_{a,b}$ to an element $(\xi^*, \zeta^*, \eta^*) \in S$ for any initial guess in S where (ξ^*, ζ^*) is the unique solution of (5.1) ■

Remark 5.3: Theorem 5.2 generalizes similar results obtained in [3,5].

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