

Fixed-Point Properties of Roughly Contractive Mappings

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Abstract. For given $k \in (0, 1)$ and $r > 0$, a self-mapping $T : M \rightarrow M$ is said to be r -roughly k -contractive provided

$$\|Tx - Ty\| \leq k \|x - y\| + r \quad (x, y \in M).$$

To state fixed-point properties of such a mapping, the self-Jung constant $J_s(X)$ is used, which is defined as the supremum of the ratio $2r_{\text{conv } S}(S)/\text{diam } S$ over all non-empty, non-singleton and bounded subsets S of some normed linear space X , where $r_{\text{conv } S}(S) = \inf_{x \in \text{conv } S} \sup_{y \in S} \|x - y\|$ is the self-radius of S and $\text{diam } S$ is its diameter. If M is a closed and convex subset of some finite-dimensional normed space X and if $T : M \rightarrow M$ is r -roughly k -contractive, then for all $\varepsilon > 0$ there exists $x^* \in M$ such that

$$\|x^* - Tx^*\| < \frac{1}{2} J_s(X) r + \varepsilon.$$

If $\dim X = 1$, or X is some two-dimensional strictly convex normed space, or X is some Euclidean space, then there is $x^* \in M$ satisfying $\|x^* - Tx^*\| \leq \frac{1}{2} J_s(X) r$.

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1. Introduction

Let X be a finite-dimensional normed linear space. For given $M \subset X$, $k \in (0, 1)$ and $r > 0$, a mapping $T : M \rightarrow M$ is said to be r -roughly k -contractive provided

$$\|Tx - Ty\| \leq k \|x - y\| + r \quad (x, y \in M). \quad (1.1)$$

We introduced this notion in [17, 18, 21] as a generalization of contractive mappings considered in the well-known Banach fixed-point theorem [2], where

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some roughness degree r is added to the right-hand side of the inequality. Such mappings may arise in quite natural ways. For example, if a given k -contractive mapping T_0 defined by $\|T_0x - T_0y\| \leq k \|x - y\|$ for all $x, y \in M$ cannot be determined exactly but it is only approximated by T , where $r = 2 \max_{x \in M} \|T_0x - Tx\|$ denotes the double maximal approximation error, then

$$\begin{aligned} \|Tx - Ty\| &\leq \|T_0x - Tx\| + \|Tx - Ty\| + \|Ty - T_0y\| \\ &\leq k \|x - y\| + r \end{aligned}$$

for all $x, y \in M$, i.e. T is r -roughly k -contractive.

Actually, such mappings were considered independently by Kirk [10], but his main attention was devoted to so-called h -non-expansive mappings defined by

$$\|Tx - Ty\| \leq \max\{\|x - y\|, h\} \quad (x, y \in M) \quad (1.2)$$

and to Hölder continuous mappings.

Since roughly contractive mappings cannot always possess fixed points, we have to consider so-called γ -fixed or γ -invariant points defined by $\|x^* - Tx^*\| \leq \gamma$ for some $\gamma > 0$, as already done for discontinuous mappings by Klee [12], Cromme and Diener [5 - 6], Bula [4], and Kirk [10]. In [16 - 18], we determined the best invariant degree γ of roughly contractive mappings in Minkowski and Euclidean spaces.

We now take advantage of the self-Jung constant $J_s(X)$ defined by (2.2) below to get a better result for non-Euclidean n -dimensional normed spaces. In Section 2, the self-Jung constant is used to estimate the distance between some set S and any point $z \in \text{conv } S \setminus S$. This is applied in Section 3 to state the following fixed point property of an r -roughly k -contractive mapping on a closed and convex subset M of some n -dimensional normed space X :

$$\forall \varepsilon > 0 \exists x^* \in M : \quad \|x^* - Tx^*\| < \frac{1}{2} J_s(X) r + \varepsilon.$$

Moreover, if

- dim $X = 1$,
- or X is some two-dimensional strictly convex normed space,
- or X is some Euclidean space,

then there exists $x^* \in M$ such that

$$\|x^* - Tx^*\| \leq \frac{1}{2} J_s(X) r$$

(Theorem 3.3).

2. Distance estimation by using self-Jung constant

For a bounded set $S \subset X$,

$$\text{diam } S = \sup_{x,y \in S} \|x - y\| \quad \text{and} \quad r_A(S) = \inf_{x \in A} \sup_{y \in S} \|x - y\| \quad (2.1)$$

are the *diameter* and the *relative radius* of S with respect to A . In particular, $r_X(S)$ and $r_{\text{conv } S} S$ are called its *absolute radius* and *self-radius*, respectively.

The ratio between absolute radius and diameter was studied by Jung [8] who investigated Euclidean spaces. Later on, Bohnenblust [3], Leichtweiß [13], and Grünbaum [7] considered this problem in Minkowski spaces. These works started a research direction of determining the supremum of this ratio which is called Jung’s constant (see, e.g., [1, 19, 20] and references therein).

In this paper, we are interested in a similar one, namely the *self-Jung constant* of X defined by

$$J_s(X) = \sup \left\{ \frac{2 r_{\text{conv } S}(S)}{\text{diam } S} \mid S \subset X \text{ is } \begin{bmatrix} \text{bounded} \\ \text{non-empty} \\ \text{non-singleton} \end{bmatrix} \right\}. \quad (2.2)$$

Obviously,

$$\begin{aligned} \frac{1}{2} \text{diam } S \leq r_X(S) \leq r_{\text{conv } S}(S) \leq \text{diam } S \\ 1 \leq J_s(X) \leq 2. \end{aligned} \quad (2.3)$$

For n -dimensional spaces, we have

$$J_s(\ell_2^n) = \left(\frac{2n}{n+1} \right)^{1/2} \quad (2.4)$$

which follows from the classical results of Jung [8] and Klee [11] (see [14]), and

$$J_s(X) \leq \frac{2n}{n+1} \quad \text{if } \dim X = n \quad (2.5)$$

(see [1]).

Let us now use the self-Jung constant to estimate the distance between a set S and any point $z \in \text{conv } S \setminus S$.

Proposition 2.1. *Let S be a bounded set of some finite-dimensional normed space X and $z \in \text{conv } S \setminus S$. Then there exists $s \in S$ such that*

$$\|z - s\| \leq \frac{1}{2} J_s(X) \text{diam } S.$$

Proof. Since $z \in \text{conv } S \setminus S$, there exists a set $S_k = \{x_1, \dots, x_k\} \subset S$ of $k \geq 2$ linearly independent points such that $z \in \text{ri}(\text{conv } S_k)$, where $\text{ri } A$ denotes the relative interior of A .

Let us prove by induction

$$\min_{1 \leq i \leq k} \|z - x_i\| \leq \frac{1}{2} J_s(X) \text{diam } S. \tag{2.6}$$

For $k = 2$, $\|x_1 - x_2\| \leq \text{diam } S$ and (2.3) yield

$$\min \{ \|z - x_1\|, \|z - x_2\| \} \leq \frac{1}{2} \|x_1 - x_2\| \leq \frac{1}{2} J_s(X) \text{diam } S.$$

Assuming now that (2.6) is true for $2 \leq k \leq l$, we have to show it for $k = l + 1$. Consider the relative center set of S_k with respect to the compact set $\text{conv } S_k$

$$\mathcal{C}_{\text{conv } S_k}(S_k) = \left\{ x \in \text{conv } S_k : \sup_{y \in S_k} \|x - y\| = r_{\text{conv } S_k}(S_k) \right\}$$

which is obviously non-empty. For any fixed $c \in \mathcal{C}_{\text{conv } S_k}(S_k)$, (2.1) and (2.2) imply

$$\begin{aligned} \max_{1 \leq i \leq k} \|c - x_i\| &\leq r_{\text{conv } S_k}(S_k) \\ &\leq \frac{1}{2} J_s(X) \text{diam } S_k \\ &\leq \frac{1}{2} J_s(X) \text{diam } S. \end{aligned} \tag{2.7}$$

If $z = c$, then (2.6) follows from (2.7). Otherwise, the ray from c through z cuts the boundary $\text{conv } S_k \setminus \text{ri}(\text{conv } S_k)$ at some point $z' \in \text{conv } S_{k'}$ where $S_{k'} = \{x_{i_1}, \dots, x_{i_{k'}}\} \subset S_k$ and $k' \leq k - 1 = l$. If $z' \in S_{k'}$, then $z \in [c, z']$ yields

$$\|z - z'\| \leq \|c - z'\| \leq r_{\text{conv } S_k}(S_k) \leq \frac{1}{2} J_s(X) \text{diam } S.$$

If $z' \notin S_{k'}$, then $z' \in \text{conv } S_{k'} \setminus S_{k'}$. By the inductive assumption, there is some $y \in S_{k'} \subset S$ such that $\|z' - y\| \leq \frac{1}{2} J_s(X) \text{diam } S$. Therefore, it follows from $z \in [c, z']$ and (2.7) that

$$\|z - y\| \leq \max \{ \|c - y\|, \|z' - y\| \} \leq \frac{1}{2} J_s(X) \text{diam } S$$

which completes our proof ■

Note that the assumption $z \in \text{conv } S \setminus S$ in the previous proposition and in the following one means at least $\text{diam } S > 0$.

Proposition 2.2. *Suppose X is some two-dimensional strictly convex normed space or some Euclidean space, $S = \{x_1, \dots, x_k\} \subset X$, and $z \in \text{conv } S \setminus S$. Then either*

$$\min_{1 \leq i \leq k} \|z - x_i\| < r_{\text{conv } S}(S) \leq \frac{1}{2} J_s(X) \text{diam } S$$

or

$$\|z - x_i\| = r_{\text{conv } S}(S) \leq \frac{1}{2} J_s(X) \text{diam } S \quad (i = 1, \dots, k).$$

Proof. By (2.2), we have to prove by induction that

$$\min_{1 \leq i \leq k} \|z - x_i\| \geq r_{\text{conv } S}(S) \tag{2.8}$$

implies

$$\|z - x_i\| = r_{\text{conv } S}(S) \quad (i = 1, \dots, k). \tag{2.9}$$

If $\dim S = 1$, then all points of S lie in some segment, say for instance, in the segment $[x_1, x_k]$ connecting x_1 and x_k . Then $r_{\text{conv } S}(S) = \frac{1}{2} \text{diam } S = \frac{1}{2} \|x_1 - x_k\|$ and

$$\min_{1 \leq i \leq k} \|z - x_i\| < r_{\text{conv } S}(S) \quad \text{if } z \neq \frac{1}{2}(x_1 + x_k).$$

Therefore, (2.8) implies $z = \frac{1}{2}(x_1 + x_k)$ and $\max_{1 \leq i \leq k} \|z - x_i\| \leq r_{\text{conv } S}(S)$. Hence, (2.9) follows from (2.8).

Assume now that the assertion is true for $\dim S \leq l$, and (2.8) holds for some set $S = \{x_1, \dots, x_k\}$ with $\dim S = l + 1 \geq 2$. We have to show (2.9) now. Due to [11: Corollary 3], $r_X(S) = r_{\text{conv } S}(S)$ and the absolute center set

$$\mathcal{C}_X(S) = \left\{ x \in X : \sup_{y \in S} \|x - y\| = r_X(S) \right\}$$

is a singleton contained in $\text{conv } S$, say $\mathcal{C}_X(S) = \{c\}$. If $c = z$, then similarly as above, (2.9) follows from (2.8). If $c \neq z \in \text{ri}(\text{conv } S)$, then the ray L from c through z cuts the boundary $\text{conv } S \setminus \text{ri}(\text{conv } S)$ at $z' \in \text{conv } S_l$ for some $S_l \subset S$ with $\dim S_l \leq l$. If $z' \in S_l$, then $z \in [c, z']$ and $c \neq z$ yield

$$\|z - z'\| < \|c - z'\| \leq r_X(S) = r_{\text{conv } S}(S),$$

a contradiction to (2.8). Hence, $z' \in \text{conv } S_l \setminus S_l$ and $S_l \cap L = \emptyset$. Consequently, for all $y \in S_l$, the function $g(x) = \|x - y\|$ is strictly convex on L , which implies by $\|c - y\| \leq r_X(S)$, $\|z - y\| \geq r_{\text{conv } S}(S) = r_X(S)$ and $z' \in L \setminus [c, z]$ that

$$\|z' - y\| > r_X(S) \geq r_X(S_l) = r_{\text{conv } S_l}(S_l) \quad (y \in S_l),$$

i.e. (2.8) is satisfied for z' and S_l instead of z and S while (2.9) fails, a contradiction to the inductive assumption.

If $c \neq z \notin \text{ri}(\text{conv } S)$, then $z \in \text{conv } S \setminus S$ implies $z \in \text{ri}(\text{conv } S_l)$ for some $S_l \subset S$ with $\dim S_l \leq l$. By the inductive assumption, it follows from

$$\min_{y \in S_l} \|z - y\| \geq \min_{y \in S} \|z - y\| \geq r_{\text{conv } S}(S) = r_X(S) \geq r_X(S_l)$$

and $\dim S_l \leq l$ that

$$\|z - y\| = r_X(S) = r_X(S_l) \quad (y \in S_l).$$

Therefore, by the strict convexity of the normed space X and $\|c - y\| \leq r_X(S) = r_X(S_l)$ we have

$$\left\| \frac{1}{2}(c + z) - y \right\| < r_X(S_l) \quad (y \in S_l),$$

a contradiction to the definition of $r_X(S_l)$ ■

3. Fixed-point theorems

Following the Banach fixed-point theorem [2], to investigate the invariant property of an r -roughly k -contractive mapping $T : M \rightarrow M$, we consider the iteration

$$\left. \begin{aligned} x_0 &\in M \\ x_{i+1} &= Tx_i \quad (i \geq 0) \end{aligned} \right\} \tag{3.1}$$

Without assuming M to be closed and convex, we proved in [18] the following γ -fixed-point theorem.

Theorem 3.1. *Let (M, d) be a metric space and let $T : M \rightarrow M$ be an r -roughly k -contractive mapping, i.e. $d(Tx, Ty) \leq kd(x, y) + r$ for all $x, y \in M$, where $r > 0$ and $k \in (0, 1)$ are given. Suppose $x_0 \in M$ and $a := d(x_0, Tx_0) - \frac{r}{1-k} > 0$.*

- (a) *If $\gamma > \frac{r}{1-k}$ and $i \geq \log_k \left((\gamma - \frac{r}{1-k})a^{-1} \right)$, then x_i determined by (3.1) is a γ -invariant point under T , i.e. $d(x_i, Tx_i) \leq \gamma$.*
- (b) *If $x^* \in M$ is a cluster point of the sequence (x_i) , then it is a γ -invariant point under T with $\gamma = \frac{r}{1-k}$.*
- (c) *For every $\gamma > 0$, the set I_γ of all γ -invariant points (of T) is bounded. If $\gamma \geq \frac{r}{1-k}$, then I_γ is invariant under T , i.e. $TI_\gamma \subset I_\gamma$.*

Consequently, if M is a compact metric space or if it is a closed subset of some finite-dimensional metric space, then each r -roughly k -contractive mapping $T : M \rightarrow M$ admits at least one γ -invariant point with $\gamma = \frac{r}{1-k}$.

In general there is no smaller invariant degree γ as given in Theorem 3.1 if M is not assumed to be convex. This fact was shown in [18] by considering the mapping $T : M_1 \cup M_2 \rightarrow M_1 \cup M_2$ defined by

$$Tx = \begin{cases} \frac{r}{2} - kx & \text{if } x \in M_1 = \left(-\infty, -\frac{r}{2(1-k)}\right) \\ -\frac{r}{2} - kx & \text{if } x \in M_2 = \left(\frac{r}{2(1-k)}, \infty\right). \end{cases}$$

This mapping is r -roughly k -contractive but has no γ -invariant points with $\gamma \leq \frac{r}{1-k}$. If T is extended continuously to the closure

$$\text{cl } M_1 \cup \text{cl } M_2 = \left(-\infty, -\frac{r}{2(1-k)}\right] \cup \left[\frac{r}{2(1-k)}, \infty\right),$$

i.e. $T\frac{-r}{2(1-k)} = \frac{r}{2(1-k)}$ and $T\frac{r}{2(1-k)} = \frac{-r}{2(1-k)}$, then $\frac{-r}{2(1-k)}$ and $\frac{r}{2(1-k)}$ are γ -invariant with $\gamma = \frac{r}{1-k}$ and there exists no γ -invariant point with $\gamma < \frac{r}{1-k}$.

Theorem 3.1 says that for all $\gamma > \frac{r}{1-k}$ there exists an $x \in M$ such that $d(x, Tx) \leq \gamma$. Consequently,

$$\inf\{d(x, Tx) : x \in M\} \leq \frac{r}{1-k}.$$

This inequality was shown by Kirk [10]. Note that the infimum $\frac{r}{1-k}$ is not necessarily attainable as shown by the above example.

For convex M , in [16, 18] we obtained the following result.

Theorem 3.2. *Let $T : M \rightarrow M$ be an r -roughly k -contractive mapping on a closed and convex subset M of some n -dimensional normed space X . If $\dim X = 1$, then there exists $x^* \in M$ such that*

$$\|x^* - Tx^*\| \leq \frac{1}{2} r. \tag{3.2}$$

If $\dim X \geq 2$, then for all $\varepsilon > 0$ there exists $x^ \in M$ such that*

$$\|x^* - Tx^*\| < \frac{n}{n+1} r + \varepsilon. \tag{3.3}$$

If, in addition, the normed space X is strictly convex, then there exists $x^ \in M$ such that*

$$\|x^* - Tx^*\| < \frac{n}{n+1} r. \tag{3.4}$$

If X is the n -dimensional Euclidean space, then there exists $x^ \in M$ such that*

$$\|x^* - Tx^*\| \leq \left(\frac{n}{2(n+1)}\right)^{1/2} r. \tag{3.5}$$

It is worth mentioning that iteration (3.1) is not suitable to approximate γ -invariant points with $\gamma < \frac{r}{1-k}$ even if they exist, as pointed out in [18] by considering

$$Tx = \begin{cases} \frac{r}{2} - kx & \text{if } x \leq 0 \\ -\frac{r}{2} - kx & \text{if } x > 0. \end{cases}$$

For any $\gamma \geq \frac{1}{2}r$, each x satisfying $-\frac{\gamma-\frac{r}{2}}{1+k} \leq x \leq \frac{\gamma-\frac{r}{2}}{1+k}$ is a γ -invariant point of this r -roughly k -contractive mapping $T : \mathbb{R} \rightarrow \mathbb{R}$. But, for any starting point $x_0 \in \mathbb{R}$, the sequence (x_i) determined by (3.1) has only two cluster points $x^- = -\frac{r}{2(1-k)}$ and $x^+ = \frac{r}{2(1-k)}$, which satisfy $Tx^- = x^+$, $Tx^+ = x^-$, and $|x^- - Tx^-| = |x^+ - Tx^+| = |x^- - x^+| = \frac{r}{1-k}$.

Let us now use the self-Jung constant $J_s(X)$ to improve Theorem 3.2.

Theorem 3.3. *Let $T : M \rightarrow M$ be an r -roughly k -contractive mapping on a closed and convex subset M of some n -dimensional normed space X . Then for all $\varepsilon > 0$ there exists $x^* \in M$ such that*

$$\|x^* - Tx^*\| < \frac{1}{2} J_s(X) r + \varepsilon. \tag{3.6}$$

If $\dim X = 1$, or X is some two-dimensional strictly convex normed space, or X is some Euclidean space, then there exists $x^ \in M$ such that*

$$\|x^* - Tx^*\| \leq \frac{1}{2} J_s(X) r. \tag{3.7}$$

Proof. (a) Take any $x_0 \in M$ and define

$$\widehat{B} = \{x \in X : \|x - x_0\| \leq \widehat{r}\}$$

where $\widehat{r} = \frac{r + \|x_0 - Tx_0\|}{1-k}$. Then $\widehat{M} = M \cap \widehat{B}$ is non-empty, compact, and convex, and T maps \widehat{M} into itself because, for all $x \in \widehat{M}$, (1.1) implies

$$\begin{aligned} \|Tx - x_0\| &\leq \|Tx - Tx_0\| + \|Tx_0 - x_0\| \\ &\leq k\|x - x_0\| + r + (1-k)\widehat{r} - r \\ &\leq \widehat{r}, \end{aligned}$$

i.e. $Tx \in \widehat{M}$.

(b) Consider $\overline{T} : \widehat{M} \rightarrow 2^{\widehat{M}}$ defined by $\overline{T}(x) = \text{conv } \overline{M}(x)$, where

$$\overline{M}(x) = \left\{ y \in \widehat{M} : \exists (x_i) \subset \widehat{M} \text{ such that } x_i \rightarrow x, Tx_i \rightarrow y \right\}. \tag{3.8}$$

For all $x \in \widehat{M}$, $\overline{M}(x)$ is closed and non-empty because \widehat{M} is compact. It is also bounded because $\text{diam } \overline{M}(x) \leq r$ follows from (1.1) and (3.8). Since X

is finite-dimensional, $\overline{M}(x)$ and $\text{conv } \overline{M}(x)$ are compact (see [22: p. 40]). It was shown in [6] that \overline{T} is upper semi-continuous. Therefore, by Kakutani's theorem (see [9, 23]), there exists $\bar{x} \in \widehat{M}$ such that $\bar{x} \in \overline{T}(\bar{x}) = \text{conv } \overline{M}(\bar{x})$.

(c) By Proposition 2.1 and $\text{diam } \overline{M}(\bar{x}) \leq r$, there is a $\bar{y} \in \overline{M}(\bar{x})$ such that

$$\|\bar{x} - \bar{y}\| \leq \frac{1}{2} J_s(X) \text{diam } \overline{M}(\bar{x}) \leq \frac{1}{2} J_s(X) r.$$

Due to (3.8), for any $\varepsilon > 0$ there exists a point $x^* \in \widehat{M} \subset M$ such that

$$\|x^* - \bar{x}\| < \frac{\varepsilon}{2} \quad \text{and} \quad \|Tx^* - \bar{y}\| < \frac{\varepsilon}{2} \tag{3.9}$$

which yields immediately

$$\|x^* - Tx^*\| \leq \|x^* - \bar{x}\| + \|\bar{x} - \bar{y}\| + \|\bar{y} - Tx^*\| < \frac{1}{2} J_s(X) r + \varepsilon,$$

i.e. (3.6) holds true.

(d) If $\dim X = 1$, then $J_s(X) = 1$, and therefore, (3.7) follows from (3.2). Assume now that X is a two-dimensional strictly convex normed space or it is the n -dimensional Euclidean space. If $\|\bar{x} - T\bar{x}\| \leq \frac{1}{2} J_s(X) r$, then (3.7) is fulfilled for $x^* = \bar{x}$. Otherwise, assume

$$\|\bar{x} - T\bar{x}\| > \frac{1}{2} J_s(X) r \geq r_{\text{conv } S}(S). \tag{3.10}$$

Since $\bar{x} \in \text{conv } \overline{M}(\bar{x})$, there exists a finite set $\widetilde{M} \subset \overline{M}(\bar{x})$ such that $\bar{x} \in \text{conv } \widetilde{M}$. For $S = \widetilde{M} \cup T\bar{x}$, we have $\bar{x} \in \text{conv } S$, and $\text{diam } S \leq r$ follows from (1.1) and (3.8). Consequently, Proposition 2.2 and (3.10) imply that there exists $\bar{y} \in \widetilde{M} \subset \overline{M}(\bar{x}) \subset \widehat{M} \subset M$ satisfying

$$\|\bar{x} - \bar{y}\| < r_{\text{conv } S}(S) \leq \frac{1}{2} J_s(X) r.$$

By choosing $\varepsilon = \frac{1}{2} J_s(X) r - \|\bar{x} - \bar{y}\| > 0$ and $x^* \in \widehat{M} \subset M$ satisfying (3.9), we obtain

$$\begin{aligned} \|x^* - Tx^*\| &\leq \|x^* - \bar{x}\| + \|\bar{x} - \bar{y}\| + \|\bar{y} - Tx^*\| \\ &\leq \|\bar{x} - \bar{y}\| + \varepsilon \\ &= \frac{1}{2} J_s(X) r, \end{aligned}$$

i.e. (3.7) holds true ■

Note that (3.3) and (3.5) in Theorem 3.2 can be derived from Theorem 3.3 by using the estimation of $J_s(X)$ for Euclidean and Minkowski spaces stated in (2.4) - (2.5).

In general, the invariant degrees given in Theorem 3.3 should be the best ones for r -roughly k -contractive mappings. This can be illustrated by the following

Example 3.1. Let $S = \{x_1, \dots, x_{n+1}\}$ be a subset of $n+1$ linearly independent points of the n -dimensional Euclidean space ℓ_2^n , where $\|x_i - x_j\| = r > 0$ for $i \neq j$. Then $M = \text{conv } S$ is an n -dimensional regular simplex in ℓ_2^n , $\bar{x} = \frac{1}{n+1} \sum_{i=1}^{n+1} x_i$ is its unique center, and

$$\|x_i - \bar{x}\| = r_M(M) = \frac{1}{2} J_s(\ell_2^n) r = \left(\frac{n}{2(n+1)}\right)^{1/2} r \quad (1 \leq i \leq n+1).$$

For any $x \in M$ we choose $Tx \in S$ such that $\|x - Tx\| = \max_{s \in S} \|x - s\|$. Then

$$\|Tx - Ty\| \leq \text{diam } M = r \leq k \|x - y\| + r \quad (x, y \in M, 0 < k < 1)$$

and

$$\|\bar{x} - T\bar{x}\| = r_M(M) = \frac{1}{2} J_s(\ell_2^n) r < \|x - Tx\| \quad (x \in M \setminus \{\bar{x}\}).$$

Hence, the mapping $T : M \rightarrow M$ is r -roughly k -contractive for arbitrary $k \in (0, 1)$ and $\frac{1}{2} J_s(\ell_2^n) r$ is the smallest invariant degree of T .

4. Concluding remarks

Due to Kirk [10], an r -roughly k -contractive mapping $T : M \rightarrow M$ is h -non-expansive for $h = \frac{r}{1-k}$, and if M is a non-empty bounded closed convex subset of a Banach space X , then an h -non-expansive mapping $T : M \rightarrow M$ satisfies $\inf\{\|x - Tx\| : x \in K\} \leq h$. This result allows to ensure the existence of γ -invariant points of r -roughly k -contractive mappings only for $\gamma \geq \frac{r}{1-k}$, which is just the same as in Theorem 3.1, where the convexity of M is not required.

By (2.5), if $\dim X = n$, then $J_s(X) \leq \frac{2n}{n+1}$, which implies $\frac{1}{2} J_s(X) r \leq \frac{nr}{n+1} < \frac{r}{1-k}$, i.e. the invariant degrees given in Theorem 3.3 are better than the ones given in Theorem 3.1, especially for k near 1.

In particular, if $M = [a, b] \subset \mathbb{R}^1$ and if $T : M \rightarrow M$ is h -non-expansive, then Kirk [10] showed that there exists $z \in M$ satisfying $|z - Tz| \leq \frac{h}{2}$. This is the best result available for such h -non-expansive mappings. But if this

result is applied to an r -roughly k -contractive mapping $T : M \rightarrow M$ as an h -non-expansive one for $h = \frac{r}{1-k}$, then we only obtain the invariant degree $\frac{h}{2} = \frac{r}{2(1-k)}$, which is also greater than the invariant degree $\gamma = \frac{r}{2}$ given in Theorems 3.2 - 3.3.

By using the result of Bula [4] for so-called uniformly w -continuous mappings, we can show that an r -roughly k -contractive mapping $T : M \rightarrow M$ possesses γ -invariant points with $\gamma = r + \varepsilon$ for arbitrary small ε , which is obviously greater than $\frac{nr}{n+1} \geq \frac{1}{2} J_s(X) r$.

In [15], we obtained similar results for discontinuous self-mappings on compact convex subsets of arbitrary normed spaces. By defining the self-Jung constant analogously, similar results are available for metric spaces.

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