A Note on the Poincaré Inequality for Convex Domains

M. Bebendorf

Abstract. In this article a proof for the Poincaré inequality with explicit constant for convex domains is given. This proof is a modification of the original proof [5], which is valid only for the two-dimensional case.

Keywords: Poincaré inequality, convex domains

AMS subject classification: 26D10

1. Introduction

The classical proof for the Poincaré inequality

 $\|u\|_{L^2(\Omega)} \le c_{\Omega} \|\nabla u\|_{L^2(\Omega)},$

where $\Omega \subset \mathbb{R}^n$ is a bounded domain and $u \in H^1(\Omega)$ with vanishing mean value over Ω , is based on the compact embedding of $H^1(\Omega)$ in $L^2(\Omega)$ which is valid under quite general assumptions on Ω (cf. [6]). However, the constant c_{Ω} depends on the domain Ω , and the proof based on compactness does not provide insight into this dependency.

For practical purposes it is important to know an explicit expression for this constant (see, for example, [2, 7]). Therefore, the special case of convex domains is interesting, since in [5] this constant is proved to be $\frac{d}{\pi}$, where dis the diameter of Ω . Though this proof is elegant, it contains a mistake in the case $n \geq 3$. The same mistake can also be found in [1], in which the L^1 -estimate is considered.

The goal of this article is to fix this gap (see Remark 3.3). Luckily, the constant $\frac{d}{\pi}$ in the Poincaré inequality remains valid.

ISSN 0232-2064 / \$ 2.50 © Heldermann Verlag Berlin

M. Bebendorf: Math. Inst. der Univ., Augustuspl. 10/11, D-04109 Leipzig; bebendorf@mathematik.uni-leipzig.de

2. The one-dimensional case

We first prove the Poincaré inequality for the one-dimensional case. In fact we will prove a generalization which the multi-dimensional case can be reduced to.

Lemma 2.1. Let $m \in \mathbb{N}$ and ρ be a non-negative concave function on the interval [0, L]. Then, for all $u \in H^1(0, L)$ satisfying

$$\int_{0}^{L} \rho^{m}(x)u(x) \, dx = 0, \qquad (2.1)$$

there holds

$$\int_{0}^{L} \rho^{m}(x) |u(x)|^{2} dx \leq \frac{L^{2}}{\pi^{2}} \int_{0}^{L} \rho^{m}(x) |u'(x)|^{2} dx.$$
(2.2)

Furthermore, the constant $\frac{L^2}{\pi^2}$ is optimal.

Proof.

(a) Let us first assume that ρ is strictly positive and twice differentiable. Then each non-zero function v minimizing the quotient

$$\frac{\int_{0}^{L} \rho^{m}(x) |u'(x)|^{2} dx}{\int_{0}^{L} \rho^{m}(x) |u(x)|^{2} dx}$$
(2.3)

and satisfying (2.1) must satisfy the Sturm-Liouville system (cf. [3])

$$\begin{cases} [\rho^m v']' + \lambda \rho^m v = 0 \\ v'(0) = v'(L) = 0 \end{cases}$$
 (2.4)

where λ is the minimum of quotient (2.3). After dividing (2.4) by ρ^m and differentiating, we introduce the new variable $w = \rho^{m/2} v'$ and obtain

$$w'' + \frac{m}{2} \left[\frac{\rho''}{\rho} - \left(1 + \frac{m}{2}\right) \frac{(\rho')^2}{\rho^2} \right] w + \lambda w = 0$$
$$w(0) = w(L) = 0$$

Since ρ is concave, $\rho'' \leq 0$. Hence, $w'' + (\lambda - a)w = 0$, where a is a non-negative function. Integration by parts leads to

$$\lambda \geq \frac{\int_0^L |w'(x)|^2 dx}{\int_0^L |w(x)|^2 dx}.$$

The last quotient is bounded by the first eigenvalue of the vibrating string with fixed ends, which gives $\lambda \geq \frac{\pi^2}{L^2}$.

(b) If ρ is a non-negative concave function, we may represent it as the L^{∞} -limit of strictly positive concave C^2 -functions ρ_k (cf. [4]). From Part (a) one has

$$\int_0^L \rho_k^m(x) |\hat{u}(x)|^2 dx \le \frac{L^2}{\pi^2} \int_0^L \rho_k^m(x) |u'(x)|^2 dx$$

where $\hat{u}(x) = u(x) - \overline{u}$ and

$$\overline{u} = \frac{\int_0^L \rho_k^m(x) u(x) dx}{\int_0^L \rho_k^m(x) \, dx}.$$

Hence,

$$\int_0^L \rho_k^m(x) |u(x)|^2 dx \le \frac{L^2}{\pi^2} \int_0^L \rho_k^m(x) |u'(x)|^2 dx + \overline{u} \int_0^L \rho_k^m(x) u(x) \, dx.$$

In the limit $k \to \infty$ we obtain (2.2).

(c) To see that the constant $\frac{L^2}{\pi^2}$ is optimal, choose $\rho^m \equiv 1$, L = 1 and $u(x) = \cos(\pi x)$. Then $\int_0^1 \rho^m(x)u(x) dx = 0$ and

$$\frac{\int_0^1 \rho^m(x) |u(x)|^2 dx}{\int_0^1 \rho^m(x) |u'(x)|^2 dx} = \frac{1}{\pi^2} \frac{\int_0^1 \cos^2(\pi x) dx}{\int_0^1 \sin^2(\pi x) dx} = \frac{1}{\pi^2}$$

Thus the lemma is proved \blacksquare

3. The *n*-dimensional case

In the rest of this article we will consider the case $n \ge 2$. By the following lemma we are able to reduce the *n*-dimensional problem to the one-dimensional case.

Lemma 3.1. Let $\Omega \subset \mathbb{R}^n$ be a convex domain with diameter d. Assume that $u \in L^1(\Omega)$ satisfies $\int_{\Omega} u(x) dx = 0$. Then for any $\delta > 0$ there are disjoint convex domains Ω_i (i = 1, ..., k) such that

$$\overline{\Omega} = \bigcup_{i=1}^{k} \overline{\Omega}_i, \qquad \int_{\Omega_i} u(x) \, dx = 0$$

and for each Ω_i there is rectangular coordinate system such that

$$\Omega_i \subset \Big\{ (x,y) \in \mathbb{R}^n : 0 \le x \le d \text{ and } |y_j| \le \delta, j = 1, \dots, n-1 \Big\}.$$

Proof. For each $\alpha \in [0, 2\pi]$ there is a unique hyperplane $H_{\alpha} \subset \mathbb{R}^n$ with normal $(0, \ldots, 0, \cos(\alpha), \sin(\alpha))$ that divides Ω into two convex sets Ω'_{α} and Ω''_{α} of equal volume. Since $I(\alpha) = -I(\alpha + \pi)$, where $I(\alpha) = \int_{\Omega'_{\alpha}} u(x) dx$, by continuity there is α_0 such that $I(\alpha_0) = 0$. Applying this procedure recursively to each of the parts Ω'_{α_0} and Ω''_{α_0} , we are able to subdivide Ω into convex sets Ω_i such that each of the sets is contained between two parallel hyperplanes with normal of the form $(0, \ldots, 0, \cos(\beta), \sin(\beta))$ at distance at most δ , and the average of u vanishes on each of them.

Consider one of these sets. By rotating the coordinate system we can assume that the normal of the enclosing hyperplanes is $(0, \ldots, 0, 1)$. In these coordinates we apply the above arguments using hyperplanes with normals of the form $(0, \ldots, 0, \cos(\alpha), \sin(\alpha), 0)$. Continuing this procedure we end up with the desired decomposition of Ω

Theorem 3.2. Let $\Omega \subset \mathbb{R}^n$ be a convex domain with diameter d. Then

$$\|u\|_{L^2(\Omega)} \le \frac{d}{\pi} \|\nabla u\|_{L^2(\Omega)}$$

for all $u \in H^1(\Omega)$ satisfying $\int_{\Omega} u(x) dx = 0$.

Proof. Let us first assume that u is twice continuously differentiable. According to the previous Lemma 3.1 we are able to decompose Ω into convex subsets Ω_i such that for each Ω_i there is a rectangular coordinate system in which Ω_i is contained in

$$\Big\{(x,y)\in\mathbb{R}^n: 0\leq x\leq d_i \text{ and } |y_j|\leq \delta, j=1,\ldots,n-1\Big\}.$$

We may assume that the interval $[0, d_i]$ on the x-axis is contained in Ω_i . Let R(t) be the (n-1)-volume of the intersection of Ω_i with the hyperplane x = t. In polar coordinates R(t) can be written in the form

$$R(t) = \int_{\mathbb{S}^{n-2}} \int_0^{\rho(t,\omega)} r^{n-2} dr d\omega = \frac{1}{n-1} \int_{\mathbb{S}^{n-2}} \rho^{n-1}(t,\omega) \, d\omega$$

where $\rho(t, \omega)$ is the distance of the boundary point of Ω_i at (t, ω) to the x-axis. Since Ω_i is convex, ρ is a concave function with respect to t. From the smoothness of u it can be seen that there are constants c_1,c_2 and c_3 such that

$$\left| \int_{\Omega_i} u(x,y) \, dx \, dy - \int_0^{d_i} u(x,0) R(x) \, dx \right| \le c_1 |\Omega_i| \delta \tag{3.2}$$

$$\left| \int_{\Omega_i} \left| \frac{\partial u}{\partial x}(x,y) \right|^2 - \int_0^{d_i} \left| \frac{\partial u}{\partial x}(x,0) \right|^2 R(x) \, dx \right| \le c_2 |\Omega_i| \delta \tag{3.3}$$

$$\int_{\Omega_i} |u(x,y)|^2 dx dy - \int_0^{d_i} |u(x,0)|^2 R(x) dx \le c_3 |\Omega_i| \delta.$$
(3.4)

Let $\omega \in \mathbb{S}^{n-2}$. Since $u(\cdot, 0) \in H^1(0, d_i)$, we can apply Lemma 2.1 to $\hat{u}_{\omega}(x) := u(x, 0) - \overline{u}_{\omega}$, where

$$\overline{u}_{\omega} := \frac{\int_0^{d_i} u(x,0)\rho^{n-1}(x,\omega) \, dx}{\int_0^{d_i} \rho^{n-1}(x,\omega) \, dx}$$

Hence,

$$\int_0^{d_i} |\hat{u}_{\omega}(x)|^2 \rho^{n-1}(x,\omega) \, dx \le \frac{d_i^2}{\pi^2} \int_0^{d_i} \left| \frac{\partial u}{\partial x}(x,0) \right|^2 \rho^{n-1}(x,\omega) \, dx.$$

Applying Fubini's theorem we obtain

$$\begin{split} \frac{d_i^2}{\pi^2} \int_0^{d_i} \left| \frac{\partial u}{\partial x}(x,0) \right|^2 R(x) \, dx \\ &= \frac{1}{n-1} \int_{\mathbb{S}^{n-2}} \frac{d_i^2}{\pi^2} \int_0^{d_i} \left| \frac{\partial u}{\partial x}(x,0) \right|^2 \rho^{n-1}(x,\omega) \, dx d\omega \\ &\ge \frac{1}{n-1} \int_{\mathbb{S}^{n-2}} \int_0^{d_i} |\hat{u}_{\omega}(x)|^2 \rho^{n-1}(x,\omega) \, dx d\omega \\ &= \frac{1}{n-1} \int_{\mathbb{S}^{n-2}} \int_0^{d_i} \hat{u}_{\omega}(x) u(x,0) \rho^{n-1}(x,\omega) \, dx d\omega \\ &\ge \int_0^{d_i} |u(x,0)|^2 R(x) \, dx - M \left| \int_0^{d_i} u(x,0) R(x) \, dx \right| \end{split}$$

where $M = \max_{\omega \in \mathbb{S}^{n-2}} |\overline{u}_{\omega}|$. By $\int_{\Omega_i} u(x, y) dx dy = 0$, (3.2) and (3.3) we are lead to

$$\begin{split} \int_0^{d_i} |u(x,0)|^2 R(x) \, dx &\leq \frac{d_i^2}{\pi^2} \int_0^{d_i} \left| \frac{\partial u}{\partial x}(x,0) \right|^2 R(x) \, dx + c_1 |\Omega_i| M\delta \\ &\leq \frac{d_i^2}{\pi^2} \int_{\Omega_i} |\nabla u(x,y)|^2 dx dy + \left(c_1 M + c_2 \frac{d_i^2}{\pi^2} \right) |\Omega_i| \delta \end{split}$$

From (3.4) and the summation over i we obtain

$$\int_{\Omega} |u(x,y)|^2 dx dy \le \frac{d^2}{\pi^2} \int_{\Omega} |\nabla u(x,y)|^2 dx dy + \left(c_1 M + c_2 \frac{d^2}{\pi^2} + c_3\right) |\Omega| \delta$$

and, since $\delta > 0$ is arbitrary, the desired estimate is proven. The assertion follows from the density of $C^{\infty}(\overline{\Omega})$ in $H^{1}(\Omega)$

Remark 3.3. In [5] it is claimed that R from (3.1) is a concave function, which is not true for $n \ge 3$ as can be seen from the following example. Let

$$\Omega = \left\{ (x_1, x_2, x_3) \in \mathbb{R}^3 : \sqrt{x_2^2 + x_3^2} \le \frac{1}{2}(x_1 + 1), \ 0 \le x_1 \le 1 \right\}$$

Then Ω is convex, vol $R(0) = \frac{\pi}{4}$ and vol $R(1) = \pi$. But

$$\operatorname{vol} R\left(\frac{1}{2}\right) = \frac{9}{16}\pi < \frac{5}{8}\pi = \frac{1}{2}\operatorname{vol} R(0) + \frac{1}{2}\operatorname{vol} R(1).$$

Hence, R is not concave.

Acknowledgement. Thanks go to C. Carstensen for pointing out the mistake in [5].

References

- [1] Acosta, G. and R. G. Durán: An optimal Poincaré inequality in L¹ for convex domains. Preprint. University of Buenos Aires 2003.
- [2] Bebendorf, M. and W. Hackbusch: Existence of *H*-matrix approximants to the inverse FE-matrix of elliptic operators with L[∞]-coefficients. Numer. Math. 2003 (to appear).
- [3] Courant, R. and D. Hilbert: Methoden der mathematischen Physik, Band I. Dritte Auflage. Berlin: Springer-Verlag 1968.
- [4] Eggleston, H. G.: Convexity. New York: Cambridge Univ. Press 1958.
- [5] Payne, L. E. and H. F. Weinberger: An optimal Poincaré inequality for convex domains. Arch. Rat. Mech. Anal. 5 (1960), 286 – 292.
- [6] Wloka, J.: Partial Differential Equations (translated from the German by C. B. Thomas and M. J. Thomas). Cambridge: Cambridge Univ. Press 1987.
- [7] Verfürth, R.: A note on polynomial approximation in Sobolev spaces. Math. Model. Numer. Anal. 33 (1999), 715 – 719.

Received 28.02.2003