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Zeitschrift für Analysis und ihre Anwendungen Journal for Analysis and its Applications Volume 26 (2007), 207–220

# Quasi-Periodic Solutions in Nonlinear Asymmetric Oscillations

Xiaojing Yang and Kueiming Lo

Abstract. The existence of Aubry–Mather sets and infinitely many subharmonic solutions to the following p-Laplacian like nonlinear equation

$$(p-1)^{-1}(\phi_p(x'))' + [\alpha\phi_p(x^+) - \beta\phi_p(x^-)] + g(x) = h(t)$$

is discussed, where  $\phi_p(u) = |u|^{p-2}u$ , p > 1,  $\alpha, \beta$  are positive constants satisfying  $\alpha^{-\frac{1}{p}} + \beta^{-\frac{1}{p}} = \frac{2}{n}$  with  $n \in \mathbb{N}$ , h is piece-wise two times differentiable and  $2\pi_p$ -periodic,  $g \in C^1(R)$  is bounded,  $x^{\pm} = \max\{\pm x, 0\}, \pi_p = \frac{2\pi}{p\sin(\pi/p)}$ .

Keywords. Aubry–Mather sets, *p*-Laplacian, resonance, quasi-periodic solutions Mathematics Subject Classification (2000). 34C25

## 1. Introduction

In this paper, we consider the existence of Aubry–Mather sets and quasi-periodic solutions to the following p-Laplacian like nonlinear differential equation

$$(p-1)^{-1}(\phi_p(x'))' + [\alpha\phi_p(x^+) - \beta\phi_p(x^-)] + g(x) = h(t) \quad ('=\frac{d}{dt}), \tag{1}$$

where  $\phi_p(u) = |u|^{p-2}u, p > 1$  is a constant,  $x^{\pm} = \max\{\pm x, 0\}, \alpha, \beta$  are positive constants satisfying

$$\alpha^{-\frac{1}{p}} + \beta^{-\frac{1}{p}} = \frac{2}{n}, \qquad (2)$$

*h* is piece-wise two times differentiable and  $2\pi_p$ -periodic,  $g \in C^1(R)$  is bounded and  $\pi_p = \frac{2\pi}{p\sin(\pi/p)}$ . If p = 2, then  $\pi_2 = \pi$  and (1) reduces to second order differential equation

$$x'' + \alpha x^{+} - \beta x^{-} + g(x) = h(t).$$
(3)

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This work is supported by the Funds 2004CB719400 and NSFC60474026.

The existence of Aubry–Mather sets and quasi-periodic solutions of (3) was discussed recently in [3] if  $g \in C^2$  and the limits

$$\lim_{x \to +\infty} g(x) = g(+\infty), \quad \lim_{x \to -\infty} g(x) = g(-\infty)$$

exist and g satisfies some further approximate properties at infinity. Capietto and Liu [3], by applying a version of Aubry–Mather theory due to Pei [11], proved the existence of quasi-periodic solutions in generalized sense and multiplicity of subharmonic solutions to equation (3) under the so-called "resonance" situation, i.e., (2) holds for p = 2 and some  $n \in \mathbb{N}$ .

Let C be the solution of the initial value problem

$$x'' + \alpha x^{+} - \beta x^{-} = 0, \qquad x(0) = 1, \quad x'(0) = 0$$

Assume  $\alpha \neq \beta$  and  $\frac{1}{\sqrt{\alpha}} + \frac{1}{\sqrt{\beta}} = \frac{2m}{n}$ ,  $m, n \in \mathbb{N}$ . Alonso and Ortega [2] proved that if the function

$$\phi_f(\theta) = \int_0^{2\pi} C\left(\frac{m\theta}{n} + t\right) h(t) dt$$

has only simple zeros, then any solution x of the linear equation

$$x'' + \alpha x^+ - \beta x^- = h \tag{4}$$

with large initial values, that is, if  $|x(t_0)| + |x'(t_0)| \gg 1$  for some  $t_0 \in \mathbb{R}$ , goes to infinity in the future or in the past. Moreover, they showed the existence of h such that unbounded solutions and  $2\pi$ -periodic solutions of (4) can coexist.

Fabry and Fonda [4] and Fabry and Mawhin [5] obtained, by degree methods, sufficient conditions for the existence of  $2\pi$ -periodic solutions and of unbounded solutions as well as subharmonic solutions for (5) below, respectively. More precisely, in [5] the following equation is considered:

$$x'' + \alpha x^{+} - \beta x^{-} = g(x) + f(x) + h(t), \qquad (5)$$

and it is proved that if the function

$$\Phi_h(\theta) = \frac{n}{\pi} \left[ \frac{g(+\infty)}{\alpha} - \frac{g(-\infty)}{\beta} \right] + \frac{1}{2\pi\sqrt{\alpha}} \int_0^{2\pi} C(t+\theta)h(t) dt$$

has zeros and all of them are simple, then all solutions of (5) with large initial values are unbounded if the following resonance condition is satisfied:

$$\frac{1}{\sqrt{\alpha}} + \frac{1}{\sqrt{\beta}} = \frac{2}{n}, \quad n \in \mathbb{N},$$

and f has a sublinear primitive, that is,  $\lim_{|x|\to\infty} \frac{1}{x} \int_0^x f(s) ds = 0$ . Later, the author of this paper [12] discussed the more general equation (1) and considered the following function:

$$\phi(\theta) = D_p - \frac{p}{\alpha^{\frac{1}{p}}} \int_0^{2\pi_p} h(mt) C_p(mt+\theta) \, dt,$$

where

$$D_p = \frac{2n}{m} B\left(\frac{2}{p}, 1 - \frac{1}{p}\right) \left[\frac{g(+\infty)}{\alpha^{\frac{2}{p}}} - \frac{g(-\infty)}{\beta^{\frac{2}{p}}}\right],$$

B(r,s) is the  $\beta$ -function  $B(r,s) = \int_0^1 (1-t)^{r-1} t^{s-1} dt$  for r > 0, s > 0, and  $C_p(t)$  is the  $\frac{2\pi_p m}{n}$  -periodic solution of the following initial value problem:

$$(p-1)^{-1}(\phi_p(u'))' + [\alpha \phi_p(u^+) - \beta \phi_p(u^-)] = 0, \quad u(0) = 1, \ u'(0) = 0,$$

if  $\alpha$  and  $\beta$  satisfy  $\alpha^{-\frac{1}{p}} + \beta^{-\frac{1}{p}} = \frac{2m}{n}, m, n \in \mathbb{N}.$ 

It was shown in [12] that if the function  $\phi(\theta)$  has no zero for all  $\theta \in \mathbb{R}$ , then all solutions of (1) are bounded. For more recent results on boundedness and existence  $2\pi$ -periodic solutions of (1) and (3), we refer [1], [6]–[9], [11]–[15] and the references therein.

In the rest of this paper, we denote by S the unique solution of the initial value problem

$$(p-1)^{-1}(\phi_p(x'))' + [\alpha\phi_p(x^+) - \beta\phi_p(x^-)] = 0, \quad x(0) = 0, \quad x'(0) = 1.$$
(6)

#### Definition 1.

(A) A solution of  $(x_{\omega}(t), x'_{\omega}(t))$  of (1) is called of *Mather type with rotation* number  $\omega$  if  $\omega = \frac{k}{m}$  is rational, the solutions  $(x_{\omega}(t + 2i\pi), x'_{\omega}(t + 2i\pi)),$  $1 \le i \le m - 1$ , are mutually unlinked periodic solutions of periodic  $2m\pi$ and, in this case,

$$\lim_{\omega \to n} \min_{t \in \mathbb{R}} (|x_{\omega}(t)| + |x'_{\omega}(t)|) = +\infty.$$

(B) If  $\omega$  is irrational, the solution  $(x_{\omega}(t), x'_{\omega}(t))$  is either a usual quasi-periodic solution or a generalized one, that is, the closed set

$$\overline{\{(x_{\omega}(2i\pi), x_{\omega}'(2i\pi)), i \in \mathbb{Z}\}}$$

is a Denjoy's minimal set.

The main results of this paper are formulated in the following theorems:

**Theorem 1.** Assume  $h \in L^{\infty}[0, 2\pi_p]$  is  $2\pi_p$ -periodic and  $g \in C^1(\mathbb{R})$  is bounded and satisfies the following conditions: the limits  $\lim_{x\to+\infty} g(x) = g(+\infty)$  and  $\lim_{x\to-\infty} g(x) = g(-\infty)$  exist and g satisfies

$$g(x) = g(\pm \infty) + c^{\pm} |x|^{-(p-1)\sigma} sgnx + O(|x|^{-(p-1)\sigma-1})$$

for  $|x| \gg 1$ , where  $\sigma \in (0, \frac{1}{p-1})$  is a constant and  $c^{\pm}$  are constants satisfying

$$D_0 =: \frac{c^+}{\alpha^{\frac{2-(p-1)\sigma}{p}}} + \frac{c^-}{\beta^{\frac{2-(p-1)\sigma}{p}}} \neq 0.$$

Define a  $2\pi_p$ -periodic function  $\lambda_1$  as

$$\lambda_1(t) = \int_0^{2\pi_p} S(\theta)h(t+\theta)d\theta - \frac{2}{p} \left(\frac{g(+\infty)}{\alpha^{\frac{2}{p}}} - \frac{g(-\infty)}{\beta^{2/p}}\right) B\left(\frac{2}{p}, \frac{1}{q}\right),$$

where  $q = \frac{p}{p-1}$  is the conjugate exponent of p. Let one of the following conditions be satisfied:

- (I)  $\lambda_1(t) \neq 0$  for all  $t \in \mathbb{R}$ ;
- (II) either (a)  $\lambda_1(t) \ge 0$  and  $D_0 < 0$  or (b)  $\lambda_1(t) \le 0$  and  $D_0 > 0$ .

Then there exists an  $\varepsilon_0 > 0$  such that for any  $\omega \in (n, n + \varepsilon_0)$ , equation (1) has a solution  $(x_{\omega}(t), x'_{\omega}(t))$  of Mather type with rotation number  $\omega$ .

**Theorem 2.** Assume  $g(x) \equiv 0$ , h is piece-wise two times differentiable and  $2\pi_p$ -periodic. Assume

$$\lambda_1(t) = \int_0^{2\pi_p} S(\theta) h(t+\theta) d\theta \equiv 0.$$

For  $p \neq 2$ , define a  $2\pi_p$ -periodic function  $\lambda_2(t)$  as

$$\lambda_2(t) = (p-2) \left[ \int_0^{2\pi_p} S(\theta) h(t+\theta) \int_0^\theta S(\tau) h'(t+\tau) d\tau d\theta - \int_0^{2\pi_p} S^2(\theta) h^2(t+\theta) d\theta \right].$$

For p = 2, define a  $2\pi$ -periodic function  $\lambda_3(t)$  as

$$\lambda_3(t) = -\frac{1}{2} \bigg[ \int_0^{2\pi} S^3(\theta) h^3(t+\theta) d\theta + \int_0^{2\pi} S(\theta) h''(t+\theta) \left( \int_0^{\theta} S(\tau) h(t+\tau) d\tau \right)^2 d\theta \bigg] \\ - \int_0^{2\pi} S^2(\theta) h(t+\theta) h'(t+\theta) \int_0^{\theta} S(\tau) h(t+\tau) d\tau d\theta.$$

Then the conclusions of Theorem 1 are true, if one of the following conditions holds:

(I)  $p \neq 2$ ,  $\lambda_2(t) \neq 0$  for all  $t \in \mathbb{R}$ ; (II) p = 2,  $\lambda_3(t) \neq 0$  for all  $t \in \mathbb{R}$ .

### 2. Generalized polar coordinates transformation

If we introduce a new variable  $y = \phi_p(x')$ , then (1) is equivalent to the planar system

$$x' = \phi_q(y), \quad y' = (p-1)[-\alpha\phi_p(x^+) + \beta\phi_p(x^-) + h(t) - g(x)], \tag{7}$$

where  $q = \frac{p}{p-1}$  is the conjugate exponent of p. Let  $u = \sin_p t$  be the solution of the initial value problem

$$(\phi_p(u'))' + (p-1)\phi_p(u) = 0, \qquad u(0) = 0, \ u'(0) = 1$$

which for  $t \in [0, \frac{\pi_p}{2}]$  can be expressed implicitly by

$$t = \int_0^{\sin_p t} \frac{ds}{(1 - s^p)^{\frac{1}{p}}}$$

Then it follows from [10] that  $u = \sin_p t$  can be extended to  $\mathbb{R}$  as a  $2\pi_p$ -periodic odd  $C^2$ -function which satisfies  $\sin_p t : [0, \frac{\pi_p}{2}] \to [0, 1]$  and  $\sin_p(\pi_p - t) = \sin_p t$  for  $t \in [\frac{\pi_p}{2}, \pi_p]$ ,  $\sin_p(2\pi_p - t) = -\sin_p t$  for  $t \in [\pi_p, 2\pi_p]$ .

Let the function S be the unique solution of problem (6), then it is not difficult to verify that  $S \in C^2(R)$  is  $\frac{2\pi_p}{n}$ -periodic and can be expressed as

$$S(t) = \begin{cases} \alpha^{-\frac{1}{p}} \sin_p \alpha^{\frac{1}{p}} t, & t \in \left[0, \, \alpha^{-\frac{1}{p}} \pi_p\right) \\ -\beta^{-\frac{1}{p}} \sin_p \beta^{\frac{1}{p}} (t - \alpha^{-\frac{1}{p}} \pi_p), & t \in \left[\alpha^{-\frac{1}{p}} \pi_p, \, \frac{2\pi_p}{n}\right], \end{cases}$$
(8)

from which it is easy to verify that the following equality holds:

$$|S'(t)|^{p} + \alpha (S^{+}(t))^{p} + \beta (S^{-}(t))^{p} \equiv 1, \quad t \in \mathbb{R}.$$
(9)

For  $\rho > 0$ ,  $\theta \pmod{2\pi_p}$ , we define the generalized polar coordinates transformation  $(\rho, \theta) \to (x, y)$  as

$$x = \rho^{\frac{1}{p}} S\left(\frac{\theta}{n}\right), \qquad y = \rho^{\frac{1}{q}} \phi_p\left(S'\left(\frac{\theta}{n}\right)\right).$$

Under this transformation and by using (9), (7) is changed into the planar system

$$\rho' = p\rho^{\frac{1}{p}}S'\left(\frac{\theta}{n}\right)(h(t) - g(x)), \qquad \theta' = n - n\rho^{-\frac{1}{q}}S\left(\frac{\theta}{n}\right)(h(t) - g(x)). \tag{10}$$

If we define  $r = \rho^{\frac{1}{q}}$ , then (10) can be further simplified as

$$r' = (p-1)S'(\frac{\theta}{n})(h(t) - g(x)), \quad \theta' = n\left[1 - r^{-1}S(\frac{\theta}{n})(h(t) - g(x))\right], \quad (11)$$

where  $x = r^{\frac{1}{p-1}} S(\frac{\theta}{n})$ .

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Let  $(r(t; r_0, \theta_0), \theta(t; r_0, \theta_0))$  be the solution of (11) with initial value  $(r_0, \theta_0)$ . Then for large initial value, i.e.,  $r_0 \gg 1$ , by the boundedness of h, g, S, S' and for t in any bounded interval  $I \subset [0, 2n\pi_p]$ , we get  $r(t) = r_0 + O(1)$  which yields  $r^{-1}(t) = r_0^{-1} + O(r_0^{-2})$ . Going back to (11), we get for  $t \in I, \theta'(t) \ge \frac{1}{2} > 0$ . As in [3], we can write (11) in the following equivalent form:

$$\frac{dt}{d\theta} = \frac{1}{n(1 - r^{-1}S\left(\frac{\theta}{n}\right)(h(t) - g(x)))}$$

$$\frac{dr}{d\theta} = \frac{(p - 1)S'\left(\frac{\theta}{n}\right)(h(t) - g(x))}{n(1 - r^{-1}S\left(\frac{\theta}{n}\right)(h(t) - g(x)))}.$$
(12)

Now let  $(r(\theta; r_0, t_0), t(\theta; r_0, t_0))$  be the solution of (12) with initial value  $(r_0, t_0)$ where  $t_0 \in I$  and  $\theta \in [0, 2n\pi_p]$ . Then for  $r_0 \gg 1$ , we obtain  $r(\theta) \ge r_0/2 \gg 1$ and (12) can be written as

$$\frac{dr}{d\theta} = \frac{p-1}{n} \left[ S'\left(\frac{\theta}{n}\right) (h(t) - g(x)) + r^{-1}(\theta) S'\left(\frac{\theta}{n}\right) S\left(\frac{\theta}{n}\right) (h(t) - g(x))^2 + \cdots \right] \\
\frac{dt}{d\theta} = \frac{1}{n} \left[ 1 + r^{-1}(\theta) S\left(\frac{\theta}{n}\right) (h(t) - g(x)) + r^{-2}(\theta) S^2\left(\frac{\theta}{n}\right) (h(t) - g(x))^2 + \cdots \right],$$
(13)

where  $x = x(\theta) = r_0^{\frac{1}{p-1}} S\left(\frac{\theta}{n}\right) + O(1).$ 

#### 3. Lemmas

For the proof of theorems, we need the following lemmas:

Lemma 1. Assume the conditions of Theorem 1 hold, then we have

$$r_{1} = r_{0} + \mu_{0}(t_{0}) + O(r_{0}^{-1})$$
  

$$t_{1} = t_{0} + 2\pi_{p} + \lambda_{1}(t_{0})r_{0}^{-1} + \lambda_{1+\sigma}r_{0}^{-(1+\sigma)} + O(r_{0}^{-2}),$$
(14)

where  $r_1 = r(2n\pi_p; r_0, t_0), t_1 = t(2n\pi_p; r_0, t_0)$  and

$$\begin{split} \mu_0(t) &= (p-1) \int_0^{2\pi_p} S'(\theta) f(t+\theta) d\theta \\ \lambda_1(t) &= \int_0^{2\pi_p} S(\theta) f(t+\theta) d\theta - \frac{2}{p} \left( \frac{g(+\infty)}{\alpha^{\frac{2}{p}}} - \frac{g(-\infty)}{\beta^{\frac{2}{p}}} \right) B\left(\frac{2}{p}, \frac{1}{q}\right) \\ \lambda_{1+\sigma} &= -\frac{2}{p} \left( \frac{c^+}{\alpha^{\frac{\tau+1}{p}}} + \frac{c^-}{\beta^{\frac{\tau+1}{p}}} \right) B\left(\frac{\tau+1}{p}, \frac{1}{q}\right) \\ &= -D_0 \frac{2}{p} B\left(\frac{\tau+1}{p}, \frac{1}{q}\right), \end{split}$$

where  $\tau = 1 - (p-1)\sigma \in (0, 1)$ . Moreover, we have  $\mu_0(t) = -(p-1)\lambda'_1(t)$ .

*Proof.* It follows from (13) and for  $t_0 \in \mathbb{R}$  and  $\theta \in [0, 2n\pi_p]$ , we have

$$r(\theta) = r_0 + O(1), \qquad t(\theta) = t_0 + \frac{\theta}{n} + O(r_0^{-1}).$$
 (15)

For  $r_0 \gg 1$ , substituting (15) into (13), then integrating over  $[0, 2n\pi_p]$  and letting  $r_1 = r(2n\pi_p)$ ,  $t_1 = t(2n\pi_p)$ , we obtain

$$r_{1} = r_{0} + \mu_{0}(t_{0}) + O(r_{0}^{-1})$$
  

$$t_{1} = t_{0} + 2\pi_{p} + \lambda_{1}(t_{0})r_{0}^{-1} + \lambda_{1+\sigma}r_{0}^{-(1+\sigma)} + O(r_{0}^{-2}),$$
(16)

where

$$\mu_0(t) = \frac{p-1}{n} \int_0^{2n\pi_p} S'\left(\frac{\theta}{n}\right) h\left(t + \frac{\theta}{n}\right) d\theta$$
$$-\frac{p-1}{n} g(+\infty) \int_I S'\left(\frac{\theta}{n}\right) d\theta - \frac{p-1}{n} g(-\infty) \int_J S'\left(\frac{\theta}{n}\right) d\theta$$
$$= (p-1) \int_0^{2\pi_p} S'(\theta) h(t+\theta) d\theta,$$

and

$$\lambda_{1}(t) = \frac{1}{n} \left[ \int_{0}^{2n\pi_{p}} S\left(\frac{\theta}{n}\right) h\left(t + \frac{\theta}{n}\right) d\theta - g(+\infty) \int_{I} S\left(\frac{\theta}{n}\right) d\theta \right] - \frac{1}{n} g(-\infty) \int_{J} S\left(\frac{\theta}{n}\right) d\theta$$
$$= \int_{0}^{2\pi_{p}} S(\theta) h(t + \theta) d\theta - g(+\infty) \int_{0}^{\frac{\pi_{p}}{\alpha^{1/p}}} S(\theta) d\theta + g(-\infty) \int_{\frac{\pi_{p}}{\alpha^{1/p}}}^{\frac{2\pi_{p}}{n}} |S(\theta)| d\theta ,$$

where  $I = \{\theta \in [0, 2n\pi_p] : S(\frac{\theta}{n}) > 0\}$  and  $J = \{\theta \in [0, 2n\pi_p] : S(\frac{\theta}{n}) < 0\}.$ 

By using the similar method used in [12], we can show that

$$\int_{0}^{\frac{\pi p}{\alpha^{1/p}}} S(\theta) d\theta = \frac{1}{\alpha^{\frac{2}{p}}} \frac{2}{p} B\left(\frac{2}{p}, \frac{1}{q}\right)$$
$$\int_{\alpha^{1/p}}^{\frac{2\pi p}{n}} S(\theta) d\theta = \frac{1}{\beta^{\frac{2}{p}}} \frac{2}{p} B\left(\frac{2}{p}, \frac{1}{q}\right).$$

From above equalities, we obtain the expressions of  $\mu_1(t)$  and  $\lambda_1(t)$ .

Next, we calculate the value  $\lambda_{1+\sigma}$ . From (16) and the expression of S in (8), we obtain

$$\lambda_{1+\sigma} = -c^{+} \int_{0}^{\frac{\pi_{p}}{\alpha^{1/p}}} \left(S(\theta)\right)^{\tau} d\theta - c^{-} \int_{\frac{\pi_{p}}{\alpha^{1/p}}}^{\frac{2\pi_{p}}{n}} |S(\tau)|^{\tau} d\theta$$
$$= -\left(\frac{c^{+}}{\alpha^{\frac{\tau+1}{p}}} + \frac{c^{-}}{\beta^{\frac{\tau+1}{p}}}\right) \int_{0}^{\pi_{p}} (\sin_{p}\theta)^{\tau} d\theta$$

and

$$\int_0^{\pi_p} (\sin_p \theta)^\tau d\theta = 2 \int_0^{\frac{\pi_p}{2}} (\sin_p \theta)^\tau d\theta = \frac{2}{p} B\left(\frac{\tau+1}{p}, \frac{1}{q}\right),$$

which yields the expression of  $\lambda_{1+\sigma}$ . Now the integration by parts yields  $\mu_0(t) = -(p-1)\lambda_1(t)$ .

Lemma 2. Assume the conditions of Theorem 2 hold, then we have

$$r_{1} = r_{0} + \mu_{1}(t_{0})r_{0}^{-1} + O(r_{0}^{-2})$$
  

$$t_{1} = t_{0} + 2\pi_{p} + \lambda_{2}(t_{0})r_{0}^{-2} + O(r_{0}^{-3}),$$
(17)

where

$$\mu_1(t) = -(p-1) \int_0^{2\pi_p} S(\theta) h''(t+\theta) \int_0^{\theta} S(\tau) h(t+\tau) d\tau d\theta$$
$$-2(p-1) \int_0^{2\pi_p} S^2(\theta) h(t+\theta) h(t+\theta) d\theta$$
$$\lambda_2(t) = (p-2) \int_0^{2\pi_p} S(\theta) h'(t+\theta) \int_0^{\theta} S(\tau) h(t+\tau) d\tau d\theta$$
$$-(p-2) \int_0^{2\pi_p} S^2(\theta) h^2(t+\theta) d\theta.$$

Moreover, we have  $(p-2)\mu_1(t) = (p-1)\lambda'_2(t)$ .

*Proof.* Substituting (15) into (13) and integrating over  $[0, \theta] \subset [0, 2\pi_p]$  we, obtain

$$r(\theta) = r_0 + \mu_0(t_0, \theta) + O(r_0^{-1})$$
  

$$t(\theta) = t_0 + \frac{\theta}{n} + \lambda_1(t_0, \theta)r_0^{-1} + O(r_0^{-2})$$
  

$$r^{-1}(\theta) = r_0^{-1} - \mu_0(t_0, \theta)r_0^{-2} + O(r_0^{-3}),$$
(18)

where

$$\mu_0(t,\theta) = \frac{p-1}{n} \int_0^\theta S'\left(\frac{\tau}{n}\right) h\left(t + \frac{\tau}{n}\right) d\tau$$

$$\lambda_1(t,\theta) = \frac{1}{n} \int_0^\theta S\left(\frac{\tau}{n}\right) h\left(t + \frac{\tau}{n}\right) d\tau.$$
(19)

Substituting (18)–(19) into (13) and integrating over  $[0, 2n\pi_p]$ , we get

$$r_{1} = r_{0} + \mu_{0}(t_{0}) + \mu_{1}(t_{0})r_{0}^{-1} + O(r_{0}^{-2})$$
  

$$t_{1} = t_{0} + 2\pi_{p} + \lambda_{1}(t_{0})r_{0}^{-1} + \lambda_{2}(t_{0})r_{0}^{-2} + O(r_{0}^{-3}),$$

where  $\lambda_1(t) = \lambda_1(t, 2n\pi_p), \ \mu_0(t) = \mu_0(t, 2n\pi_p),$ 

$$\mu_1(t) = \frac{p-1}{n} \int_0^{2n\pi_p} S'\left(\frac{\theta}{n}\right) h'\left(t+\frac{\theta}{n}\right) \lambda_1(t,\theta) d\theta$$
  
+  $\frac{p-1}{n} \int_0^{2n\pi_p} S\left(\frac{\theta}{n}\right) S'\left(\frac{\theta}{n}\right) h^2\left(t+\frac{\theta}{n}\right) d\theta$   
=  $-(p-1) \int_0^{2\pi_p} S(\theta) h''(t+\theta) \int_0^{\theta} S(\tau) h(t+\tau) d\tau d\theta$   
-  $2(p-1) \int_0^{2\pi_p} S^2(\theta) h(t+\theta) h'(t+\theta) d\theta - (p-1)\lambda_1(t) \lambda_1'(t)$ 

and

$$\lambda_{2}(t) = \frac{1}{n} \int_{0}^{2n\pi_{p}} S^{2}\left(\frac{\theta}{n}\right) h^{2}\left(t + \frac{\theta}{n}\right) d\theta - \frac{1}{n} \int_{0}^{2n\pi_{p}} S\left(\frac{\theta}{n}\right) h\left(t + \frac{\theta}{n}\right) \mu_{0}(t,\theta) d\theta$$
$$+ \frac{1}{n} \int_{0}^{2n\pi_{p}} S\left(\frac{\theta}{n}\right) h'\left(t + \frac{\theta}{n}\right) \lambda_{1}(t,\theta) d\theta$$
$$= (p-2) \int_{0}^{2\pi_{p}} S(\theta) h(t+\theta) \int_{0}^{\theta} S(\tau) h'(t+\tau) d\tau d\theta$$
$$- (p-2) \int_{0}^{2\pi_{p}} S^{2}(\theta) h^{2}(t+\theta) d\theta + \lambda_{1}(t) \lambda_{1}'(t).$$

From above equalities we obtain after some elementary calculation

$$(p-2)\mu_1(t) = (p-1) \Big[\lambda_2'(t) - \frac{p}{2} \big(\lambda_1'(t)\big)^2 - (p-1)\lambda_1(t)\lambda_1''(t)\Big],$$

which implies that, for  $\lambda_1(t) \equiv 0$ , we have  $(p-2)\mu_1(t) = (p-1)\lambda'_2(t)$ .

**Lemma 3.** Assume that the conditions of Theorem 2 hold, and p = 2. Then

$$r_{1} = r_{0} + \mu_{1}(t_{0})r_{0}^{-1} + O(r_{0}^{-2})$$
  

$$t_{1} = t_{0} + 2\pi + \lambda_{3}(t_{0})r_{0}^{-3} + O(r_{0}^{-4}),$$
(20)

where

$$\mu_1(t) = -\int_0^{2\pi} S(\theta) h''(t+\theta) \int_0^{\theta} S(\tau) h(t+\tau) d\tau d\theta - 2\int_0^{2\pi} S^2(\theta) h(t+\theta) h'(t+\theta) d\theta$$

and  $\lambda_3(t)$  is given as in Theorem 2.

*Proof.* Substituting (15) into (13) and integrating over  $[0, \theta] \subset [0, 2n\pi]$ , we obtain (18) with  $\mu_0$ ,  $\lambda_1$  given by (19) with p = 2. Substituting (18) into (13)

and integrating over  $[0, \theta] \subset [0, 2n\pi]$ , we obtain

$$r(\theta) = r_0 + \mu_0(t_0, \theta) + \mu_1(t_0, \theta)r_0^{-1} + O(r_0^{-2})$$
  

$$t(\theta) = t_0 + \frac{\theta}{n} + \lambda_1(t_0, \theta)r_0^{-1} + \lambda_2(t_0, \theta)r_0^{-2} + O(r_0^{-3})$$
  

$$r^{-1}(\theta) = r_0^{-1} - \mu_0(t_0, \theta)r_0^{-2} + (\mu_0^2(t_0, \theta) - \mu_1(t_0, \theta))r_0^{-3} + O(r_0^{-4}),$$
(21)

where

$$\mu_{1}(t,\theta) = \frac{1}{n} \int_{0}^{\theta} S'\left(\frac{\tau}{n}\right) h'\left(t + \frac{\tau}{n}\right) \lambda_{1}(t,\tau) d\tau$$

$$+ \frac{1}{n} \int_{0}^{\theta} S\left(\frac{\tau}{n}\right) S'\left(\frac{\tau}{n}\right) h^{2}\left(t + \frac{\tau}{n}\right) d\tau$$

$$= \frac{1}{n^{2}} \int_{0}^{\theta} S'\left(\frac{\tau}{n}\right) h'(t + \frac{\tau}{n}) \int_{0}^{\tau} S\left(u/n\right) h\left(t + u/n\right) du d\tau$$

$$+ \frac{1}{n} \int_{0}^{\theta} S\left(\frac{\tau}{n}\right) S'\left(\frac{\tau}{n}\right) h^{2}\left(t + \frac{\tau}{n}\right) d\tau$$
(22)

and

$$\lambda_{2}(t,\theta) = -\frac{1}{n} \int_{0}^{\theta} S\left(\frac{\tau}{n}\right) h\left(t + \frac{\tau}{n}\right) \mu_{0}(t,\tau) d\tau + \frac{1}{n} \int_{0}^{\theta} S^{2}\left(\frac{\tau}{n}\right) h^{2}\left(t + \frac{\tau}{n}\right) d\tau$$
$$+ \frac{1}{n} \int_{0}^{\theta} S(\tau) h(t + \tau) \lambda_{1}(t,\tau) d\tau$$
$$= \frac{1}{n^{2}} \int_{0}^{\theta} Sh \int_{0}^{\tau} Sh' du d\tau + \frac{1}{n^{2}} \int_{0}^{\theta} Sh' \int_{0}^{\tau} Sh du d\tau$$
$$= \frac{1}{n^{2}} \int_{0}^{\theta} S\left(\frac{\tau}{n}\right) h\left(t + \frac{\tau}{n}\right) d\tau \int_{0}^{\theta} S\left(\frac{\tau}{n}\right) h'\left(t + \frac{\tau}{n}\right) d\tau.$$
(23)

Substituting (21)–(23) into (13) again and integrating over  $[0, 2n\pi]$ , we obtain

$$r_{1} = r_{0} + \mu_{0}(t_{0}) + \mu_{1}(t_{0})r_{0}^{-1} + O(r_{0}^{-2})$$
  

$$t_{1} = t_{0} + 2\pi + \lambda_{1}(t_{0})r_{0}^{-1} + \lambda_{2}(t_{0})r_{0}^{-2} + \lambda_{3}(t_{0})r_{0}^{-3} + O(r_{0}^{-4}),$$

where  $\lambda_k(t) = \lambda_k(t, 2n\pi), \ k = 1, 2, \ \mu_i(t) = \mu_i(t, 2n\pi), \ i = 0, 1$ , and

$$\lambda_{3}(t) = \frac{1}{n} \int_{0}^{2n\pi} S^{3}h^{3}d\theta - \frac{2}{n} \int_{0}^{2n\pi} S^{2}h^{2}\mu_{0}d\theta + \frac{2}{n} \int_{0}^{2n\pi} S^{2}hh'\lambda_{1}d\theta + \frac{1}{n} \int_{0}^{2n\pi} Sh(\mu_{0}^{2} - \mu_{1})d\theta - \frac{1}{n} \int_{0}^{2n\pi} Sh'\lambda_{1}\mu_{0}d\theta + \frac{1}{n} \int_{0}^{2n\pi} Sh''\lambda_{1}^{2}d\theta + \frac{1}{n} \int_{0}^{2n\pi} Sh'\lambda_{2}d\theta.$$
(24)

Now, substituting the expressions of  $\mu_0$ ,  $\mu_1$ ,  $\lambda_1$  and  $\lambda_2$  into (24) and using  $\lambda_1(t) \equiv 0$ , we obtain from Lemma 2 that  $\lambda_2(t) \equiv 0$  and  $\mu_0(t) = -\lambda_1(t) \equiv 0$ . After some elementary calculation, we obtain the expression of  $\lambda_3(t)$  given in Theorem 2.

## 4. Proof of the theorems

Now, we are ready to prove the main results of this paper.

Proof of Theorem 1. Assume the conditions of Theorem 1 hold. If (I) is satisfied, then the Poincaré map  $P: (t_0, r_0) \to (t_1, r_1)$  of the solutions of (13) has the following form:

$$t_1 = t_0 + 2\pi_p + \lambda_1(t_0)r_0^{-1} + O(r_0^{-2})$$
  

$$r_1 = r_0 + \mu_0(t_0) + O(r_0^{-1}),$$
(25)

with  $\mu_0(t) = -(p-1)\lambda'_1(t)$ .

Now we introduce another action variable u and a positive parameter  $\varepsilon$  by  $r = \frac{1}{u\varepsilon}$  with  $u \in [1, 2]$ . Then  $r \gg 1 \Leftrightarrow \varepsilon \ll 1$ . Under this transformation, (25) is changed to the following form:

$$t_1 = t_0 + 2\pi_p + \lambda_1(t_0)u_0\varepsilon + O(\varepsilon^2)$$
$$u_1 = u_0 - \mu_0(t_0)u_0^2\varepsilon + O(\varepsilon^2).$$

Let  $t_1 = t_0 + \varepsilon R(t_0, u_0, \varepsilon)$ ,  $u_1 = u_0 + \varepsilon W(t_0, u_0, \varepsilon)$ , then  $R(t, u, \varepsilon) = \lambda_1(t)u + O(\varepsilon)$ ,  $W(t, u, \varepsilon) = -\mu_0(t)u_0^2 + O(\varepsilon)$ , and for  $t \in [0, 2n\pi_p]$ ,  $u \in [1, 2]$ , we have

$$|R(t, u, \varepsilon)| + \left|\frac{\partial R(t, u, \varepsilon)}{\partial t}\right| + \left|\frac{\partial R(t, u, \varepsilon)}{\partial u}\right| \le C_1$$
(26)

and

$$|W(t, u, \varepsilon)| + \left|\frac{\partial W(t, u, \varepsilon)}{\partial t}\right| + \left|\frac{\partial W(t, u, \varepsilon)}{\partial u}\right| \le C_2$$
(27)

for some constants  $C_1, C_2$ . Moreover, if  $\min_{t \in \mathbb{R}} \lambda_1(t) = d_0 > 0$ , we have for  $\varepsilon \ll 1, t \in \mathbb{R}, u \in [1, 2]$ ,

$$\frac{\partial R(t, u, \varepsilon)}{\partial u} \ge -\frac{d_0}{2} > 0$$

and if  $\max_{t \in S^1} \lambda_1(t) = -d_1 < 0$ , we have

$$\frac{\partial R(t, u, \varepsilon)}{\partial u} \le -\frac{d_1}{2} < 0.$$

In both cases, the Poincaré map of (25) is a monotone map. Going back to (13), we know that the Poincaré map  $Q : (\theta_0, r_0) \to (\theta_1, r_1)$  is also monotone if  $r_0 \gg 1$ . Using similar arguments as in [11, Section 4], we may construct a map  $\bar{Q}$  which is a global monotone twist homeomorphism of the cylinder  $S^1 \times \mathbb{R}$ and coincides with Q on  $S^1 \times [A_0, +\infty)$  with a fixed constant  $A_0 \gg 1$ , where  $S^1 = \mathbb{R}/2\pi_p\mathbb{Z}$ . Therefore, the existence of Mather sets  $M_{\omega}$  of  $\bar{Q}$  is guaranteed by Aubry–Mather theory (see [11]). Moreover, for some small  $\varepsilon_0 > 0$ , such invariant sets with rotation  $\omega \in (n, n + \varepsilon_0)$  lie in the domain  $S^1 \times [A_0, +\infty)$ . Hence they are just the Aubry–Mather sets of the Poincaré map of Q. The above discussion shows the existence of Mather sets, this implies that (1) has a solution  $(x_{\omega}(t), x'_{\omega}(t))$  of Mather type. Moreover, if  $\omega = \frac{m}{k}$  is a rational, the solutions  $(x_{\omega}(t + 2i\pi_p), x'_{\omega}(t + 2i\pi_p)), 1 \leq i \leq k - 1$ , are mutually unlinked periodic solutions of period  $2k\pi_p$  and  $\lim_{k\to+\infty} \min_{t\in\mathbb{R}} ||(x_{\omega}(t), x'_{\omega}(t))|| = +\infty$ . If  $\omega$  is irrational, the solution  $(x_{\omega}(t), x'_{\omega}(t))$  is either a usual quasi-periodic solution or a generalized one.

In case (II), by Lemma 1, the Poincaré map of (13) has the form of (14), under the same transformation  $r = \frac{1}{u\varepsilon}$ , (14) is of the following form:

$$t_1 = t_0 + 2\pi_p + \varepsilon R_1(t_0, u_0, \varepsilon)$$
$$u_1 = u_0 + \varepsilon W_1(t_0, u_0, \varepsilon),$$

where  $R_1(t, u, \varepsilon) = \lambda_1(t)u + \lambda_{1+\sigma}u^{1+\sigma}\varepsilon^{\sigma} + O(\varepsilon^1)$ , and  $W_1(t, u, \varepsilon) = -\mu_0(t)u^2 + O(\varepsilon)$ . It is easy to see that  $R_1$  and  $W_1$  satisfy the similar inequalities as (26) and (27). Moreover, for  $\lambda_1(t) \ge 0$  and  $D_0 < 0$ , we have for  $\varepsilon \ll 1, t \in \mathbb{R}, u \in [1, 2], \lambda_{1+\sigma} > 0$  and

$$\frac{\partial R_1(t, u, \varepsilon)}{\partial u} = \lambda_1(t) + (1 + \sigma)\lambda_{1+\sigma}\varepsilon^{\sigma} + O(\varepsilon^1) \ge \lambda_1(t) + \frac{1}{2}(1 + \sigma)\lambda_{1+\sigma}\varepsilon^{\sigma} > 0.$$

Similarly, for  $\lambda_1(t) \leq 0$  and  $D_0 > 0$ , we have  $\lambda_{1+\sigma} < 0$  and

$$\frac{\partial R_1(t, u, \varepsilon)}{\partial u} = \lambda_1(t) + (1 + \sigma)\lambda_{1+\sigma}\varepsilon^{\sigma} + O(\varepsilon^1) \le \lambda_1(t) + \frac{1}{2}(1 + \sigma)\lambda_{1+\sigma}\varepsilon^{\sigma} < 0.$$

The rest proof is similar to that of case (I), so we omit it for simplicity.

Proof of Theorem 2 (a sketch). By Lemma 2 and Lemma 3, the Poincaré map of (13) has the form of (17) or the form of (20). Under the transformation  $r = \frac{1}{w^{\epsilon}}$ , (17) and (20) have the forms

$$t_1 = t_0 + 2\pi_p + \lambda_2(t_0)u_0^2 \varepsilon^2 + O(\varepsilon^3)$$
  
$$u_1 = u_0 - \mu_1(t_0)u_0^3 \varepsilon^2 + O(\varepsilon^3),$$

and

$$t_1 = t_0 + 2\pi + \lambda_3(t_0)u_0^3\varepsilon^3 + O(\varepsilon^4)$$
  
$$u_1 = u_0 - \mu_1(t_0)u_0^3\varepsilon^3 + O(\varepsilon^4),$$

respectively. Let

$$t_1 = t_0 + 2\pi_p + \varepsilon^2 R_2(t, u, \varepsilon), \quad u_1 = u_0 + \varepsilon^2 W_2(t, u, \varepsilon) \quad \text{for } p \neq 2$$
  
$$t_1 = t_0 + 2\pi + \varepsilon^3 R_3(t, u, \varepsilon), \quad u_1 = u_0 + \varepsilon^3 W_3(t, u, \varepsilon) \quad \text{for } p = 2,$$

respectively, then it is not difficult to verify that for  $0 < \varepsilon \ll 1$ ,  $\frac{\partial R_k(t,u,\varepsilon)}{\partial u} \neq 0$  if  $\lambda_k(t) \neq 0, t \in \mathbb{R}$  for k = 2, 3. The rest proofs are similar to that of Theorem 1, so we omit them for simplicity.

**Example 1.** Consider equation (1) with  $\alpha = \beta = n = 1$ ,  $h(t) \equiv 1$ ,  $g(x) = \arctan x + |x|^{-\tau} \operatorname{sgn} x$ , where  $\tau \in (0, 1)$ . Then Theorem 1 implies that, for all  $t \in \mathbb{R}$ ,  $\lambda_1(t) = -\frac{2\pi}{p} B(\frac{1}{p}, \frac{1}{q}) < 0$ . Now (I) of Theorem 1 implies that the conclusion of Theorem 1 holds.

**Example 2.** Consider the following equation

$$(p-1)^{-1}(\phi_p(x'))' + \phi_p(x) + |x|^{-\tau} \operatorname{sgn} x - 2|x|^{-\tau} \operatorname{sgn} x = 1,$$
(28)

where p > 1,  $\tau \in (0, 1)$ . Then  $\alpha = \beta = n = 1$ ,  $c^+ = 1$ ,  $c^- = -2$ ,  $h(t) \equiv 1$ , and it is easy to see that  $S(t) = \sin_p t$ ,  $\lambda_1(t) \equiv 0$  and  $D_0 = c^+ + c^- < 0$ . Now (II) of Theorem 1 implies that there exists  $\varepsilon_0 > 0$  such that for any  $\omega \in (n, n + \varepsilon_0)$ , (28) has a solution  $(x_{\omega}(t), x'_{\omega}(t))$  of Mather type with rotation number  $\omega$ .

**Example 3.** Consider a special case of (1):

$$(p-1)^{-1}(\phi_p(x'))' + \phi_p(x) = 1.$$
(29)

In this example,  $p \neq 2$ ,  $\alpha = \beta = n = 1$ ,  $g(x) \equiv 0$ , h(t) = 1. Then it can be verified that  $\lambda_1(t) \equiv 0$ ,  $\lambda_2(t) = (2-p) \int_0^{2\pi_p} \sin_p^2 \theta d\theta \neq 0$ . Now Theorem 2 implies that there exists  $\varepsilon_0 > 0$  such that for any  $\omega \in (n, n + \varepsilon_0)$ , (29) has a solution  $(x_{\omega}(t), x'_{\omega}(t))$  of Mather type with rotation number  $\omega$ .

Example 4. Consider the following linear equation

$$x'' + \alpha x^{+} - \beta x^{-} = h(t), \qquad (30)$$

where  $\alpha \neq \beta$  satisfying (2) with p = 2, n = 1, and h is piecewise continuous and  $2\pi$ -periodic such that  $h(t) = 1, t \in [0, \frac{\pi}{\sqrt{\alpha}}]; h(t) = \frac{\beta}{\alpha}, t \in (\frac{\pi}{\sqrt{\alpha}}, 2\pi]$ . Then it follows from Theorem 2 that  $\lambda_1(t) = \lambda_2(t) \equiv 0$  and  $\lambda_3(t) \equiv \lambda_3(0) = -\frac{2}{3\alpha^3}(\alpha - \beta)$  $\neq 0$ . Hence Theorem 2 implies that the conclusion of Theorem 2 holds.

**Remark 1.** Let p = 2, Theorem 1 reduces to [3, Theorem 1], moreover, our assumption  $D_0 \neq 0$  is weaker than the assumption  $c^{\pm} \neq 0$  and  $c^+c^- > 0$ . In case  $g(x) \equiv 0$  and  $\lambda_1(t) \equiv 0$ , the result of [3] cannot be applied to equation (30), but Theorem 2 gives partial results. Therefore, our results are natural generalization and refinements of the result of [3].

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Received December 28, 2004; revised September 7, 2005