

Attractor Bifurcation of Three-Dimensional Double-Diffusive Convection

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Abstract. In this article, we present a bifurcation analysis on the double-diffusive convection. Two pattern selections, rectangles and squares, are investigated. It is proved that there are two different types of attractor bifurcations depending on the thermal and salinity Rayleigh numbers for each pattern. The analysis is based on a newly developed attractor bifurcation theory, together with eigen-analysis and the center manifold reductions.

Keywords. Attractor bifurcation

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1. Introduction

The main objective of this article is to develop a bifurcation and stability theory for the double-diffusive convection, using a newly developed bifurcation theory for dynamical systems, both finite and infinite dimensional [11]. Convective motions occur in a fluid when there are density variations present. Double-diffusive convection is the name given to such convective motions when the density variations are caused by two different components which have different rates of diffusion. Double-diffusion was first originally discovered in the 1857 by Jevons [9], forgotten, and then rediscovered as an “oceanographic curiosity” a century later; see among others Stommel, Arons and Blanchard [17], Veronis [19], and Baines and Gill [1].

We have conducted a bifurcation and stability analysis in [8] for the *two dimensional* (2D) double-diffusive convection model. In this article, we continue our analysis to study the *three dimensional* (3D) double-diffusive convection problem. As in the two-dimensional case, the governing equations are

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the Boussinesq equations with two diffusion equations of the temperature and salinity functions.

The double-diffusive system involves four important nondimensional parameters: the thermal Rayleigh number λ , the solute Rayleigh number η , the Prandtl number σ and the Lewis number τ . We examine in this article different transition/instability regimes defined by these parameters. We study the onset of double diffusive instabilities in these regimes. In the ocean circulation case, the Prandtl and Lewis numbers satisfy $\sigma > 1$ and $\tau < 1$, as the heat diffuses about 100 times more rapidly than salt [16]. In this case, different regimes of stabilities and instabilities/transitions of the basic state can be described by regions in the λ - η plane (the thermal and salt Rayleigh numbers) as shown in Figure 3.1. In this article, we focus on the regimes where $\eta < \eta_c$; see Figure 3.1. In the case where $\eta > \eta_c$, transitions to periodic or aperiodic solutions are expected, and will be addressed elsewhere.

In both 2D and 3D cases, the central gravity of the analysis is the reduction of the problem to the center manifold in the first unstable eigendirections, based on an approximation formula for the center manifold function. The key idea is to find the approximation of the reduction to certain order, leading to a “nondegenerate” system with higher order perturbations. The analysis for the 3D case studied here has all the difficulties appeared in the analysis for the 2D case such as the nonsymmetric linearized eigenvalue problem. Additional difficulties occur in the 3D case. One difficulty is the lack of the existence of global strong solutions of the 3D Boussinesq equations, and another is the higher dimensionality of the generalized eigenspace, leading to the center manifold reduction to higher dimensional center manifolds, and consequently to more complicated dynamics.

With this reduction in our disposal, a general bifurcation theorem follows from the general strategy of attractor bifurcations. We prove in particular that there are two different types of transition/bifurcation from the basic state: one is subcritical and the other is supercritical. In the rectangle case (i.e., the horizontal domain is a rectangle), the types of transition/bifurcation are dictated explicitly by a nondimensional parameter η_{c_1} ; see Figure 3.1. In the square case (i.e., the horizontal domain is a square), types are determined by the quadratic form (3.9). From the physical point of view, the supercritical bifurcation corresponds to a continuous transition. The subcritical bifurcation corresponds, however, to a jump transition, a very different transition. As demonstrated in the 2D case [8], this subcritical bifurcation leads to the existence of a saddle-node bifurcation and the hysteresis phenomena, thanks to the existence of strong solutions and the existence of global attractors. In the 3D case studied here in this article, we are not able to make such conclusions. However, we can still prove that there is an absorbing region resembling the main properties of the saddle-node bifurcation and hysteresis.

There have been extensive studies on bifurcation and stability analysis for convection models; see among others [2, 3, 6, 14] and the references therein. We mention in particular that in [3], Buzano and Golubitsky used the singularity-theory method to study the problem of pattern formation as it relates to bifurcation with respect to the hexagonal lattice. They treated bifurcation problems that are symmetric with respect to group preserving doubly periodic functions on a hexagonal lattice. Their method provides a delicate alternative to study the convection problem in this paper.

Another remark is that as mentioned by Sattinger on page 96 in [15], a stable bifurcating solution with respect to a subclass of disturbances of full symmetry might turn out to be unstable with respect to the disturbances of full symmetry. In our analysis, although we use the symmetry properties implicitly to reduce the calculations, we don't use the equivariant theory to reduce the problem to a lower dimensional space. Since we want to keep as much stability information as possible.

This article is organized as follows. The basic governing equations are given in Section 2. The main theorems are stated in Section 3. The remaining sections are devoted to the proof of the main theorems, with Section 4 on eigenvalue problems, Section 5 on center manifold reductions and the proofs of the theorems.

2. The double-diffusive equations

The nondimensional double-diffusive convection problem in a three-dimensional (3D) domain $\Omega = \mathbb{R}^2 \times (0, 1) \subset \mathbb{R}^3$ with coordinates denoted by (x, y, z) are given as follows; see Veronis [19]:

$$\begin{cases} \frac{\partial U}{\partial t} = \sigma(\Delta U - \nabla p) + \sigma(\lambda T - \eta S)e - (U \cdot \nabla)U \\ \frac{\partial T}{\partial t} = \Delta T + w - (U \cdot \nabla)T \\ \frac{\partial S}{\partial t} = \tau \Delta S + w - (U \cdot \nabla)S \\ \operatorname{div}U = 0, \end{cases} \tag{2.1}$$

where $U = (u, v, w)$, λ the thermal Rayleigh number, η the salinity Rayleigh number, σ the Prandtl number, and τ the Lewis number. We consider the periodic boundary condition in the x and y directions

$$\begin{aligned} (U, T, S)(x, y, z, t) &= (U, T, S)\left(x + \frac{2j\pi}{\alpha_1}, y, z, t\right) \\ &= (U, T, S)\left(x, y + \frac{2k\pi}{\alpha_2}, z, t\right), \end{aligned} \tag{2.2}$$

for any $j, k \in \mathbb{Z}$. At the top and bottom boundaries, we impose the free-free boundary conditions; namely,

$$(T, S, w) = 0, \quad \frac{\partial u}{\partial z} = 0, \quad \frac{\partial v}{\partial z} = 0, \quad \text{at } z = 0, 1. \quad (2.3)$$

It's natural to put the constraint

$$\int_{\Omega} u \, dx \, dy \, dz = \int_{\Omega} v \, dx \, dy \, dz = 0 \quad (2.4)$$

for the problem (2.1)–(2.3). It is easy to see that (2.1) is invariant under this constraint. The initial value conditions are given by

$$(U, T, S) = (\tilde{U}, \tilde{T}, \tilde{S}) \quad \text{at } t = 0. \quad (2.5)$$

Let

$$H = \{(U, T, S) \in L^2(\Omega)^5 \mid \operatorname{div} U = 0, w|_{z=0,1} = 0, (u, v) \text{ satisfies (2.2), (2.4)}\}$$

$$H_1 = \{(U, T, S) \in H^2(\Omega)^5 \cap H \mid (U, T, S) \text{ satisfies (2.2), (2.3)}\}.$$

Let $G : H_1 \rightarrow H$, and $L_{\lambda\eta} = -A - B_{\lambda\eta} : H_1 \rightarrow H$ be defined by

$$G(\psi) = (-P[(U \cdot \nabla)U], -(U \cdot \nabla)T, -(U \cdot \nabla)S)$$

$$A\psi = (-P[\sigma(\Delta U)], -\Delta T, -\tau\Delta S)$$

$$B_{\lambda\eta}\psi = (-P[\sigma(\lambda T - \eta S)e], -w, -w),$$

for any $\psi = (U, T, S) \in H_1$. Here P is the Leray projection to L^2 fields, and for a detailed account of the function spaces, see among many others [18]. Then the Boussinesq equations (2.1)–(2.4) can be written in the following operator form:

$$\frac{d\psi}{dt} = L_{\lambda\eta}\psi + G(\psi), \quad \psi = (U, T, S).$$

It is classical that there is a global weak solution for the system, and there is a global strong solution for small data; see among others [5, 10]. Of course, the global existence of strong solutions is not known for large data.

3. Main results

3.1. Attractor bifurcation theory. In this subsection, we recapitulate the attractor bifurcation theory introduced by two of the authors in [11, 12].

Let H and H_1 be two Hilbert spaces, and $H_1 \hookrightarrow H$ be a dense and compact inclusion. We consider the following nonlinear evolution equations:

$$\begin{cases} \frac{du}{dt} = L_{\lambda}u + G(u, \lambda) \\ u(0) = u_0, \end{cases} \quad (3.1)$$

where $u : [0, \infty) \rightarrow H$ is the unknown function, $\lambda \in \mathbb{R}$ is the system parameter, and $L_\lambda : H_1 \rightarrow H$ are parameterized linear completely continuous fields depending continuously on $\lambda \in \mathbb{R}^1$, which satisfy

$$\begin{cases} -L_\lambda = A + B_\lambda & \text{a sectorial operator} \\ A : H_1 \rightarrow H & \text{a linear homeomorphism} \\ B_\lambda : H_1 \rightarrow H & \text{parameterized linear compact operators.} \end{cases} \tag{3.2}$$

It is easy to see [7] that L_λ generates an analytic semi-group $\{e^{tL_\lambda}\}_{t \geq 0}$. Then we can define fractional power operators $(-L_\lambda)^\mu$ for any $0 \leq \mu \leq 1$ with domain $H_\mu = D((-L_\lambda)^\mu)$ such that $H_{\mu_1} \subset H_{\mu_2}$ if $\mu_1 > \mu_2$, and $H_0 = H$.

Furthermore, we assume that the nonlinear terms $G(\cdot, \lambda) : H_\mu \rightarrow H$ for some $1 > \mu \geq 0$ are a family of parameterized C^r bounded operators ($r \geq 1$) continuously depending on the parameter $\lambda \in \mathbb{R}^1$, such that

$$G(u, \lambda) = o(\|u\|_{H_\mu}), \quad \forall \lambda \in \mathbb{R}^1. \tag{3.3}$$

In this paper, we are interested in the sectorial operator $-L_\lambda = A + B_\lambda$ such that there exist an eigenvalue sequence $\{\rho_k\} \subset \mathbb{C}^1$ and an eigenvector sequence $\{e_k, h_k\} \subset H_1$ of A :

$$\begin{cases} Az_k = \rho_k z_k, & z_k = e_k + ih_k \\ \text{Re } \rho_k \rightarrow \infty & (k \rightarrow \infty) \\ \left| \frac{\text{Im } \rho_k}{(a + \text{Re } \rho_k)} \right| \leq c, \end{cases} \tag{3.4}$$

for some $a, c > 0$, such that $\{e_k, h_k\}$ is a basis of H . Also we assume that there is a constant $0 < \theta < 1$ such that

$$B_\lambda : H_\theta \longrightarrow H \text{ bounded} \quad \forall \lambda \in \mathbb{R}^1. \tag{3.5}$$

Under conditions (3.4) and (3.5), the operator $-L_\lambda = A + B_\lambda$ is a sectorial operator.

Let $\{S_\lambda(t)\}_{t \geq 0}$ be an operator semi-group generated by the equation (3.1). Then the solution of (3.1) can be expressed as $\psi(t, \psi_0) = S_\lambda(t)\psi_0, t \geq 0$.

Consider (3.1) satisfying (3.2) and (3.3). We start with the Principle of Exchange of Stabilities (PES). Let the eigenvalues (counting the multiplicity) of L_λ be given by $\beta_1(\lambda), \beta_2(\lambda), \dots$. Suppose that

$$\text{Re } \beta_i(\lambda) \begin{cases} < 0, & \text{if } \lambda < \lambda_0 \\ = 0, & \text{if } \lambda = \lambda_0 \\ > 0, & \text{if } \lambda > \lambda_0 \end{cases} \quad (1 \leq i \leq m) \tag{3.6}$$

$$\text{Re } \beta_j(\lambda_0) < 0 \quad (m + 1 \leq j). \tag{3.7}$$

Let the eigenspace of L_λ at λ_0 be

$$E_0 = \bigcup_{1 \leq j \leq m} \bigcup_{k=1}^{\infty} \{u, v \in H_1 \mid (L_{\lambda_0} - \beta_j(\lambda_0))^k w = 0, w = u + iv\}.$$

It is known that $\dim E_0 = m$.

Theorem 3.1 (T. Ma and S. Wang [11,12]). *Assume that the conditions (3.2)–(3.5) and (3.6)–(3.7) hold true, and $u = 0$ is locally asymptotically stable for (3.1) at $\lambda = \lambda_0$. Then the following assertions hold true.*

1. (3.1) bifurcates from $(u, \lambda) = (0, \lambda_0)$ to attractors Σ_λ , having the same homology as S^{m-1} , for $\lambda > \lambda_0$, with $m - 1 \leq \dim \Sigma_\lambda \leq m$, which is connected if $m > 1$;
2. for any $u_\lambda \in \Sigma_\lambda$, u_λ can be expressed as $u_\lambda = v_\lambda + o(\|v_\lambda\|_{H_1})$, $v_\lambda \in E_0$;
3. there is an open set $U \subset H$ with $0 \in U$ such that the attractor Σ_λ bifurcated from $(0, \lambda_0)$ attracts $U \setminus \Gamma$ in H , where Γ is the stable manifold of $u = 0$ with co-dimension m .

3.2. Main theorems. We now consider the double diffusive convection equations (2.1). In this article, we always consider the case where the parameters λ and η satisfy

$$\begin{aligned} \eta < \eta_c &= \frac{27}{4} \pi^4 \tau^2 (1 + \sigma^{-1})(1 - \tau)^{-1} \\ \lambda \approx \lambda_c &= \frac{\eta}{\tau} + \frac{27}{4} \pi^4. \end{aligned} \tag{3.8}$$

Two pattern selections, rectangles and squares, are studied.

3.2.1. Rectangle Case. For the rectangle case, we assume that $\alpha_1 = \frac{\pi}{\sqrt{2}}$ and $\alpha_2 \neq \alpha_1$. Here the condition on α_1 and α_2 defines the aspect ratios of the domain. The first eigenspace of the eigenvalue problem (4.1) is of dimension two.

First we consider a more physically relevant diffusive regime where the thermal Prandtl number σ is bigger than 1, and the Lewis number τ is less than 1: $\sigma > 1 > \tau$. In this case, we consider two straight lines in the $\lambda - \eta$ parameter plane as shown in Figure 3.1:

$$\begin{cases} L_1 : & \lambda = \lambda_c(\eta) = \frac{\eta}{\tau} + \frac{27}{4} \pi^4 \\ L_2 : & \lambda = \lambda_{c_1}(\eta) = \frac{(\sigma + \tau)}{(\sigma + 1)} \eta + \frac{27}{4} \pi^4 (1 + \sigma^{-1} \tau)(1 + \tau). \end{cases}$$

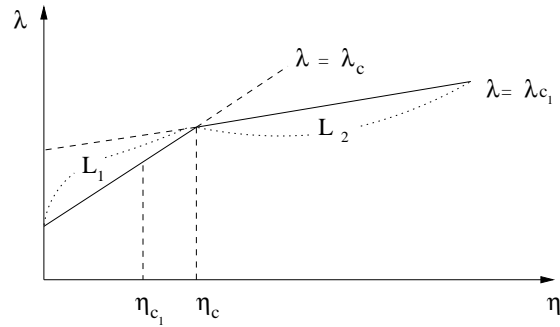


Figure 3.1: Regimes of stabilities and instabilities/transitions of the basic state.

Also shown in Figure 3.1 are two critical values for η given by

$$\eta_c = \frac{27}{4}\pi^4\tau^2(1 + \sigma^{-1})(1 - \tau)^{-1}, \quad \eta_{c_1} = \frac{27}{4}\pi^4\tau^3(1 - \tau^2)^{-1}.$$

The following two theorems study the transitions/bifurcation of the double-diffusive model near the line L_1 for $\eta < \eta_c$.

Theorem 3.2. *Assume that the condition (3.8) holds true, $\sigma > 1 > \tau$, and $\eta < \eta_{c_1} = \frac{27}{4}\pi^4\tau^3(1 - \tau^2)^{-1}$. Then the following assertions for the problem (2.1)–(2.5) hold true:*

1. *If $\lambda \leq \lambda_c$, the steady state $(U, T, S) = 0$ is locally asymptotically stable for the problem.*
2. *For $\lambda > \lambda_c$, the solutions bifurcate from $((U, T, S), \lambda) = (0, \lambda_c)$ to an attractor $\Sigma_\lambda = S^1$, consisting of steady state solutions of the problem.*

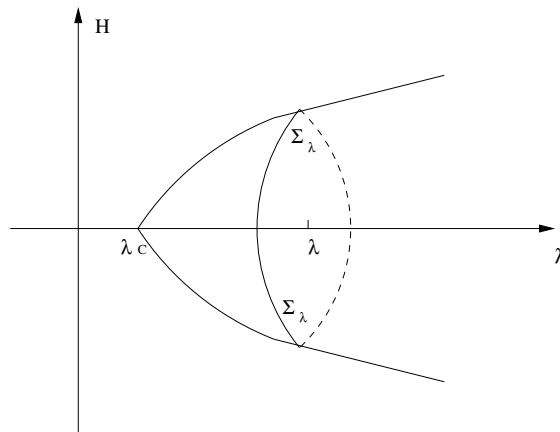


Figure 3.2: If $\tau > 1$ or $\eta < \eta_{c_1}$, the solutions bifurcate from $(0, \lambda_c)$ to an attractor Σ_λ for $\lambda > \lambda_c$.

Theorem 3.3. Assume that the condition (3.8) holds true, $\sigma > 1 > \tau$ and $\eta_c > \eta > \eta_{c_1} = \frac{27}{4}\pi^4\tau^3(1 - \tau^2)^{-1}$. Then on $\lambda < \lambda_c$, the problem (2.1)–(2.5) bifurcates from $((U, T, S), \lambda) = (0, \lambda_c)$ to a repeller $\Sigma_\lambda = S^1$, consisting of steady state solutions of the problem.

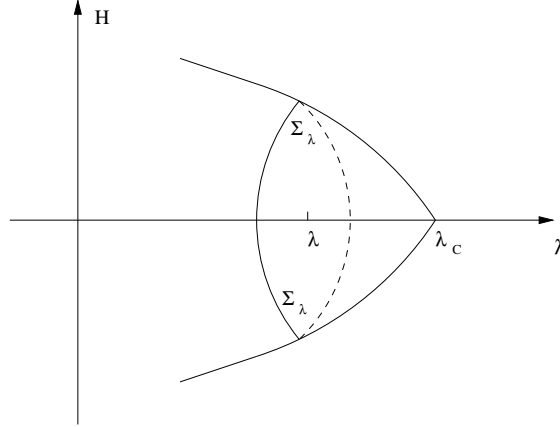


Figure 3.3: If $\tau < 1$ and $\eta_{c_1} < \eta < \eta_c$, the problem has a subcritical type bifurcation for $\lambda < \lambda_c$.

We now consider the diffusive parameter regime where $\sigma > 1$, $\tau > 1$, and $\sigma \neq \tau$. In this case, two lines are shown in Figure 3.4. The following theorem provides bifurcation when λ crosses the line L_1 .

Theorem 3.4. Assume that $\sigma > 1$, $\tau > 1$, $\sigma \neq \tau$ and (3.8) hold true, then for any $\eta > 0$, the following assertions for the problem (2.1)–(2.5) hold true:

1. If $\lambda \leq \lambda_c$, the steady state $(U, T, S) = 0$ is locally asymptotically stable for the problem.
2. For $\lambda > \lambda_c$, the solutions bifurcate from $((U, T, S), \lambda) = (0, \lambda_c)$ to an attractor Σ_λ , homeomorphic to S^1 , which consists of steady state solutions of the problem.

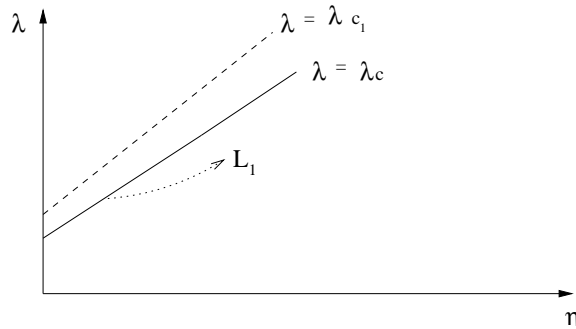


Figure 3.4: The diffusive parameter regime.

3.2.2. Square Case. For the square case, we assume $\alpha_1 = \alpha_2 = \frac{\pi}{2}$. Then, the first eigenspace of the eigenvalue problem (4.1) is of dimension 4. In this case, the bifurcation type is determined by the following quadratic form:

$$\delta_1(x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)^2 + 2\delta_2(x_{1111}^2 + y_{1111}^2)(x_{1-111}^2 + y_{1-111}^2), \quad (3.9)$$

where δ_1 and δ_2 are as defined in (5.4) and (5.5), which can be evaluated precisely when the parameters τ , σ , η and λ are given. More precisely, we have the following two theorems.

Theorem 3.5. *Assume that (3.8) holds true and the quadratic form (3.9) is negative definite, then the following assertions for the problems (2.1)–(2.5) hold true:*

1. *If $\lambda \leq \lambda_c$, the steady state $(U, T, S) = 0$ is locally asymptotically stable for the problem.*
2. *For $\lambda > \lambda_c$, the solutions bifurcate from $((U, T, S), \lambda) = (0, \lambda_c)$ to an attractor Σ_λ , having the same homology as S^3 .*

Theorem 3.6. *Assume that (3.8) holds true and the quadratic form (3.9) is positive definite. Then on $\lambda < \lambda_c$, the problem (2.1)–(2.5) bifurcates from $((U, T, S), \lambda) = (0, \lambda_c)$ to a repeller Σ_λ , having the same homology as S^3 .*

4. Eigenvalue problem

In order to apply the center manifold theory to reduce the bifurcation problems, we consider the following eigenvalue problem for the linearized equations of (2.1)–(2.4):

$$\begin{cases} \sigma(\Delta U - \nabla p) + \sigma(\lambda T - \eta S)e = \beta U \\ \Delta T + w = \beta T \\ \tau \Delta S + w = \beta S \\ \operatorname{div} U = 0, \end{cases} \quad (4.1)$$

supplemented with (2.3) and (2.4).

4.1. Eigenvalues. We shall use the method of separation of variables to deal with the problem (4.1). Since $\psi = (U, T, S)$ satisfies the periodic condition (2.2), we expand the fields in Fourier series as

$$\psi(x, y, z) = \sum_{j,k=-\infty}^{\infty} \psi_{jk}(z) e^{i(j\alpha_1 x + k\alpha_2 y)}. \quad (4.2)$$

Plugging (4.2) into (4.1), we obtain the following ODE system:

$$\left\{ \begin{array}{l} D_{jk}u_{jk} - ij\alpha_1 p_{jk} = \sigma^{-1}\beta u_{jk} \\ D_{jk}v_{jk} - ik\alpha_2 p_{jk} = \sigma^{-1}\beta v_{jk} \\ D_{jk}w_{jk} - p'_{jk} + \lambda T_{jk} - \eta S_{jk} = \sigma^{-1}\beta w_{jk} \\ D_{jk}T_{jk} + w_{jk} = \beta T_{jk} \\ \tau D_{jk}S_{jk} + w_{jk} = \beta S_{jk} \\ ij\alpha_1 u_{jk} + ik\alpha_2 v_{jk} + w'_{jk} = 0 \\ u'_{jk} |_{z=0,1} = v'_{jk} |_{z=0,1} = w_{jk} |_{z=0,1} = T_{jk} |_{z=0,1} = S_{jk} |_{z=0,1} = 0, \end{array} \right. \quad (4.3)$$

for $j, k \in \mathbb{Z}$, where $' = \frac{d}{dz}$, $D_{jk} = \frac{d^2}{dz^2} - \alpha_{jk}^2$ and $\alpha_{jk}^2 = j^2\alpha_1^2 + k^2\alpha_2^2$. If $w_{jk} \neq 0$, (4.3) can be reduced to a single equation for $w_{jk}(z)$:

$$\{(\tau D_{jk} - \beta)(D_{jk} - \beta)(D_{jk} - \sigma^{-1}\beta)D_{jk} + \alpha_{jk}^2[\lambda(\tau D_{jk} - \beta) - \eta(D_{jk} - \beta)]\}w_{jk} = 0 \quad (4.4)$$

$$w_{jk} = w''_{jk} = w_{jk}^{(4)} = w_{jk}^{(6)} = 0 \quad \text{at } z = 0, 1, \quad (4.5)$$

for $j, k \in \mathbb{Z}$. Thanks to (4.5), w_{jk} can be expanded in a Fourier sine series

$$w_{jk}(z) = \sum_{l=1}^{\infty} w_{jkl} \sin l\pi z, \quad (4.6)$$

for $(j, k) \in \mathbb{Z} \times \mathbb{Z}$. Substituting (4.6) into (4.4), we see that the corresponding eigenvalues β of Problem (4.1) satisfy the cubic equations

$$\beta^3 + (\sigma + \tau + 1)\gamma_{jkl}^2\beta^2 + [(\sigma + \tau + \sigma\tau)\gamma_{jkl}^4 - \sigma\alpha_{jk}^2\gamma_{jkl}^{-2}(\lambda - \eta)]\beta + \sigma\tau\gamma_{jkl}^6 + \sigma\alpha_{jk}^2(\eta - \tau\lambda) = 0, \quad (4.7)$$

for $j, k \in \mathbb{Z}$ and $l \in \mathbb{N}$, where $\gamma_{jkl}^2 = \alpha_{jk}^2 + l^2\pi^2$.

For the sake of convenience to analyze the distribution of the eigenvalues, we now introduce some notations. For fixed parameters σ, τ, η and λ , let

$$\begin{aligned} g_{jkl}(\beta) &= \beta^3 + (\sigma + \tau + 1)\gamma_{jkl}^2\beta^2 + (\sigma + \tau + \sigma\tau)\gamma_{jkl}^4\beta + \sigma\tau\gamma_{jkl}^6 \\ h_{jkl}(\beta) &= [\sigma\alpha_{jk}^2\gamma_{jkl}^{-2}(\lambda - \eta)]\beta - \sigma\alpha_{jk}^2(\eta - \tau\lambda) \\ f_{jkl}(\beta) &= g_{jkl}(\beta) - h_{jkl}(\beta) \end{aligned}$$

$$\eta_c = \frac{27}{4}\pi^4\tau^2(1 + \sigma^{-1})(1 - \tau)^{-1}, \quad \eta_{c1} = \frac{27}{4}\pi^4\tau^3(1 - \tau^2)^{-1}, \quad \lambda_c = \frac{\eta}{\tau} + \frac{27}{4}\pi^4.$$

Furthermore, let $\beta_{jkl1}, \beta_{jkl2}$ and β_{jkl3} be the zeros of f_{jkl} with $\text{Re}\beta_{jkl1} \geq \text{Re}\beta_{jkl2} \geq \text{Re}\beta_{jkl3}$, and let $\beta_{jkl\sigma} = -\sigma\gamma_{jkl}^2$.

The following lemma characterizes the eigenvectors of $L_{\lambda\eta}$ with zero w -components; the proof is straightforward and we omit the details.

Lemma 4.1. For $l \in 0 \cup \mathbb{N}$ and $(j, k) \in \mathbb{Z}^2$, $\beta_{jkl\sigma}$ is an eigenvalue of problem (4.1). Moreover, the following assertions are true:

1. If $(j, k) = (0, 0)$ and $l > 0$, the corresponding eigenvectors are

$$\psi_1^{\beta_{00l\sigma}} = (\cos l\pi z, 0, 0, 0, 0)^t, \quad \psi_2^{\beta_{00l\sigma}} = (0, \cos l\pi z, 0, 0, 0)^t.$$

2. If $j^2 + k^2 \neq 0$ and $l \in 0 \cup \mathbb{N}$, the corresponding eigenvectors are

$$\begin{aligned} \psi_1^{\beta_{jkl\sigma}} &= (k \cos(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, -j \cos(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, 0, 0, 0)^t \\ \psi_2^{\beta_{jkl\sigma}} &= (k \sin(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, -j \sin(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, 0, 0, 0) \end{aligned}$$

In the following discussions, we shall focus on the following diffusive regime:

$$\sigma > 1 > \tau > 0, \quad \eta < \eta_c \quad \text{and} \quad \lambda \approx \lambda_c. \tag{4.8}$$

Lemma 4.2. Suppose that $\alpha_{jk}^2 = \frac{\pi^2}{2}$ and (4.8) holds true, then $f_{jk1}(\beta)$ has three simple real zeros.

Proof. Since $\lambda \approx \lambda_c$, it suffices to prove this statement for $\lambda = \lambda_c$. In this case,

$$f_{jk1}(\beta) = \beta^3 + \left[\frac{3\pi^2}{2}(\sigma + \tau + 1) \right] \beta^2 + \left[\frac{9\pi^4}{4}(\sigma + \tau + \sigma\tau) - \frac{\sigma}{3}(\lambda_c - \eta) \right] \beta = f(\beta)\beta.$$

Since $\eta < \eta_c$, the constant term of $f(\beta)$ is positive. Hence $\beta_{jk11} = 0$ is a simple zero of f_{jk1} . Moreover, the quadratic discriminant of $f(\beta)$ is $\frac{9\pi^4}{4}(\sigma + 1 - \tau)^2 + \frac{4\sigma\eta(1-\tau)}{3\tau} > 0$. This implies f_{jk1} has three simple real zeros. \square

We summarize the following important lemma about the distribution of the zeros of f_{jkl} . From the physical point of view, this lemma verifies the principle of exchange of stabilities (PES).

Lemma 4.3. Assume that either 1) $0 < \eta < \eta_c$ with $\tau < 1$ or 2) $\eta > 0$ with $\tau > 1$ holds true, then:

$$\begin{aligned} \operatorname{Re} \beta_{jk11}(\lambda) &\begin{cases} < 0 & \text{if } \lambda < \lambda_c \\ = 0 & \text{if } \lambda = \lambda_c \\ > 0 & \text{if } \lambda > \lambda_c \end{cases} \quad \text{if } \alpha_{jk}^2 = \frac{\pi^2}{2} \\ \operatorname{Re} \beta_{jklq}(\lambda) &< 0 \quad \text{if } (\alpha_{jk}^2, l, q) \neq \left(\frac{\pi^2}{2}, 1, 1 \right). \end{aligned}$$

Remark 4.4. The distribution of the zeros of f_{jkl} was first partially analyzed by Veronis [19]; see also Baines [1]. The complete proof of this lemma is similar to the 2D case in [8], we shall omit it.

To check that the operators $-L_{\lambda\eta}$ satisfy condition (3.4), we prove the following lemma.

Lemma 4.5.

1. All but finitely many zeros of $f_{jkl}(\beta)$ are negative real numbers for $(j, k, l) \in \mathbb{Z}^2 \times \mathbb{N}$.
2. $\beta_{jklq} \rightarrow -\infty$ if $j^2 + k^2 + l^2 \rightarrow \infty$.

Proof. Since $f_{jkl} = g_{jkl} - h_{jkl}$, β is a zero of $f_{jkl}(\beta)$ if and only if β satisfies the equation

$$g_{jkl}(\beta) = h_{jkl}(\beta). \tag{4.9}$$

Plugging $\beta = \gamma_{jkl}^2 \beta^*$ into (4.9), we obtain

$$(\beta^* + 1)(\beta^* + \tau)(\beta^* + \sigma) = \vartheta_{jkl}[(\lambda - \eta)\beta^* - (\eta - \tau\lambda)], \tag{4.10}$$

where $\vartheta_{jkl} = \frac{\sigma\alpha_{jk}^2}{\gamma_{jkl}^6}$. Since $\lim_{j^2+k^2+l^2 \rightarrow \infty} \vartheta_{jkl} = 0$, the roots of (4.10) must be negative real numbers near the interval $[-\sigma, -\tau]$ when $(j^2 + k^2 + l^2)$ is large. This completes the proof. \square

4.2. Eigenvectors. We now make some observations to analyze the spectrum of $L_{\lambda\eta}$. Since

$$g_{jkl}(\beta) = (\beta + \gamma_{jkl}^2)(\beta + \tau\gamma_{jkl}^2)(\beta + \sigma\gamma_{jkl}^2), \quad h_{jkl} = \sigma\alpha_{jk}^2\gamma_{jkl}^{-2}[(\lambda - \eta)\beta - (\eta - \tau\lambda)\gamma_{jkl}^2],$$

it is easy to check that $\beta = -\gamma_{jkl}^2$ or $\beta = -\tau\gamma_{jkl}^2$ is a zero of $f_{jkl}(\beta)$ if and only if $\alpha_{jk} = 0$. In the case of $\alpha_{jk}^2 = 0$, the zeros of f_{00l} are $-\tau\gamma_{00l}^2$ (β_{00l1}), $-\gamma_{00l}^2$ (β_{00l2}) and $-\sigma\gamma_{00l}^2$ (β_{00l3}). The corresponding eigenvectors are

$$\begin{aligned} \psi^{\beta_{00l1}}(x, y, z) &= (0, 0, 0, 0, \sin l\pi z)^t, & \psi^{\beta_{00l2}}(x, y, z) &= (0, 0, 0, \sin l\pi z, 0)^t \\ \psi_1^{\beta_{00l\sigma}}(x, y, z) &= (\cos l\pi z, 0, 0, 0, 0)^t, & \psi_2^{\beta_{00l\sigma}}(x, y, z) &= (0, \cos l\pi z, 0, 0, 0)^t. \end{aligned}$$

To analyze the structure of the eigenspaces of (4.1), for $k \in \mathbb{Z}$, $j \in \{0\} \cup \mathbb{N}$ and $l \in \mathbb{N}$, we define

$$\begin{aligned} \phi_{jkl}^1 &= \left(\frac{j\alpha_1 l\pi}{\alpha_{jk}^2} \cos(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, \frac{k\alpha_2 l\pi}{\alpha_{jk}^2} \cos(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, \right. \\ &\quad \left. \sin(j\alpha_1 x + k\alpha_2 y) \sin l\pi z, 0, 0 \right)^t \\ \phi_{jkl}^2 &= (0, 0, 0, \sin(j\alpha_1 x + k\alpha_2 y) \sin l\pi z, 0)^t \\ \phi_{jkl}^3 &= (0, 0, 0, 0, \sin(j\alpha_1 x + k\alpha_2 y) \sin l\pi z)^t \end{aligned}$$

$$\phi_{jkl}^4 = \left(-\frac{j\alpha_1 l\pi}{\alpha_{jk}^2} \sin(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, -\frac{k\alpha_2 l\pi}{\alpha_{jk}^2} \sin(j\alpha_1 x + k\alpha_2 y) \cos l\pi z, \right. \\ \left. \cos(j\alpha_1 x + k\alpha_2 y) \sin l\pi z, 0, 0 \right)^t$$

$$\phi_{jkl}^5 = (0, 0, 0, \cos(j\alpha_1 x + k\alpha_2 y) \sin l\pi z, 0)^t$$

$$\phi_{jkl}^6 = (0, 0, 0, 0, \cos(j\alpha_1 x + k\alpha_2 y) \sin l\pi z)^t.$$

The next lemma follows from (4.1)–(4.7).

Lemma 4.6. *If $j^2 + k^2 \neq 0$ and β_{jklq} ($q = 1, 2, 3$) is a zero of f_{jkl} , then we have:*

1. *The eigenvector corresponding to β_{jklq} in the complexified space of H is*

$$\psi^{\beta_{jklq}} = e^{i(j\alpha_1 x + k\alpha_2 y)} \left(\frac{ij\alpha_1 l\pi}{\alpha_{jk}^2} \cos l\pi z, \frac{ik\alpha_2 l\pi}{\alpha_{jk}^2} \cos l\pi z, \sin l\pi z, \right. \\ \left. A_1(\beta_{jklq}) \sin l\pi z, A_2(\beta_{jklq}) \sin l\pi z \right)^t,$$

$$\text{where } A_1(\beta_{jklq}) = \frac{1}{\beta_{jklq} + \gamma_{jkl}^2}, \quad A_2(\beta_{jklq}) = \frac{1}{\beta_{jklq} + \tau\gamma_{jkl}^2}.$$

2. *If β_{jklq} is a real number, the corresponding eigenvectors are given by*

$$\psi_1^{\beta_{jklq}} = \phi_{jkl}^1 + A_1(\beta_{jklq})\phi_{jkl}^2 + A_2(\beta_{jklq})\phi_{jkl}^3 \\ \psi_2^{\beta_{jklq}} = \phi_{jkl}^4 + A_1(\beta_{jklq})\phi_{jkl}^5 + A_2(\beta_{jklq})\phi_{jkl}^6.$$

3. *If $\text{Im } \beta_{jklq} \neq 0$, the generalized eigenvectors corresponding to β_{jklq} and $\bar{\beta}_{jklq}$ are*

$$\psi_1^{\beta_{jklq}} = \phi_{jkl}^1 + R_1(\beta_{jklq})\phi_{jkl}^2 + R_2(\beta_{jklq})\phi_{jkl}^3 + I_1(\beta_{jklq})\phi_{jkl}^5 + I_2(\beta_{jklq})\phi_{jkl}^6 \\ \psi_2^{\beta_{jklq}} = -I_1(\beta_{jklq})\phi_{jkl}^2 - I_2(\beta_{jklq})\phi_{jkl}^3 + \phi_{jkl}^4 + R_1(\beta_{jklq})\phi_{jkl}^5 + R_2(\beta_{jklq})\phi_{jkl}^6 \\ \psi_1^{\bar{\beta}_{jklq}} = \phi_{jkl}^1 + R_1(\bar{\beta}_{jklq})\phi_{jkl}^2 + R_2(\bar{\beta}_{jklq})\phi_{jkl}^3 + I_1(\bar{\beta}_{jklq})\phi_{jkl}^5 + I_2(\bar{\beta}_{jklq})\phi_{jkl}^6 \\ \psi_2^{\bar{\beta}_{jklq}} = -I_1(\bar{\beta}_{jklq})\phi_{jkl}^2 - I_2(\bar{\beta}_{jklq})\phi_{jkl}^3 + \phi_{jkl}^4 + R_1(\bar{\beta}_{jklq})\phi_{jkl}^5 + R_2(\bar{\beta}_{jklq})\phi_{jkl}^6,$$

where $R_1(\beta) = \text{Re } A_1(\beta)$, $I_1(\beta) = \text{Im } A_1(\beta)$, $R_2(\beta) = \text{Re } A_2(\beta)$ and $I_2(\beta) = \text{Im } A_2(\beta)$.

Definition 4.7.

1. If $j = k = 0$, for each $l \in \mathbb{N}$, we define

$$E_{00l} = \text{span}\{\psi^{\beta_{00l1}}, \psi^{\beta_{00l2}}\}, \quad E_{00l}^\sigma = \text{span}\{\psi_1^{\beta_{00l\sigma}}, \psi_2^{\beta_{00l\sigma}}\}.$$

2. For $j^2 + k^2 \neq 0$, we define

$$\begin{aligned} E_{jkl}^1 &= \text{span}\{\phi_{jkl}^1, \phi_{jkl}^2, \phi_{jkl}^3\}, & E_{jkl}^2 &= \text{span}\{\phi_{jkl}^4, \phi_{jkl}^5, \phi_{jkl}^6\}, \\ E_{jkl} &= E_{jkl}^1 \oplus E_{jkl}^2, & E_{jkl}^\sigma &= \text{span}\{\psi_1^{\beta_{jkl}^\sigma}, \psi_2^{\beta_{jkl}^\sigma}\}. \end{aligned}$$

3. For $(j, k, l) \in \mathbb{Z}^2 \times \mathbb{N}$, we define $E_{f_{jkl}}$ as the eigenspace spanned by the eigenvectors and the generalized eigenvectors corresponding to the zeros of f_{jkl} .

Remark 4.8.

1. It is easy to see from the Fourier expansion that $\{E_{jkl} \cup E_{jkl}^\sigma\}_{j,l=0,k=-\infty}^\infty$ is a basis of H_1 .
2. E_{jkl} (resp., E_{jkl}^σ) is orthogonal to $E_{j_1k_1l_1}$ (resp., $E_{j_1k_1l_1}^\sigma$) for $(j, k, l) \neq (j_1, k_1, l_1)$, and E_{jkl} is always orthogonal to $E_{j_1k_2l_2}^\sigma$.

The following theorem together with Lemmas 4.1 and 4.3 complete the analysis of the eigenvalue problem (4.1).

Theorem 4.9. *Under the assumption (4.8), we have:*

1. $E_{f_{jkl}} = E_{jkl}$ for $j \in \{0\} \cup \mathbb{N}$, $k \in \mathbb{Z}$, and $l \in \mathbb{N}$; and
2. $L_{\lambda\mu}|E_{jkl}$ is strictly negative definite for each $(j, k, l) \in \mathbb{Z}^2 \times \mathbb{N}$ when $\lambda < \lambda_c$.

Proof. The first assertion follows by the fact that E_{jkl} is an invariant subspace of $L_{\lambda\eta}$ and f_{jkl} is the characteristic polynomial of $L_{\lambda\eta}|E_{jkl}$. Assertion 1, Lemma 4.3 together with the fact that f_{jkl} does not have a zero of multiplicity three imply Assertion 2. □

We conclude the above analysis as follows:

1. The eigenvalues of $L_{\lambda\eta} : H_1 \rightarrow H$ consist of $\{\beta_{jklq}, \beta_{jkl\sigma}\}_{j,l=0,k=-\infty}^\infty$.
2. The (generalized) eigenvectors of $L_{\lambda\eta}$ form a basis of H .
3. $-L_{\lambda\eta}$ is a sectorial operator.
4. For the rectangle case, the multiplicity of the first eigenvalue, $\beta_{1011}(\lambda)$, is 2, and the corresponding eigenvectors are $\psi_1^{\beta_{1011}}$ and $\psi_2^{\beta_{1011}}$.
5. For the square case, the multiplicity of the first eigenvalue $\beta_{1111}(\lambda) = \beta_{1-111}(\lambda)$ is 4, and the corresponding eigenvectors are $\psi_1^{\beta_{1111}}, \psi_2^{\beta_{1111}}, \psi_1^{\beta_{1-111}}$ and $\psi_2^{\beta_{1-111}}$.

Verification of G satisfying (3.3): We let $\frac{3}{4} < \mu < 1$, then for $\psi \in H_\mu \subset H$, by Sobolev’s inequality,

$$|G(\psi)|_H^2 \leq \int_0^1 \int_0^{\frac{2\pi}{\alpha_2}} \int_0^{\frac{2\pi}{\alpha_1}} |\psi|^2 |\nabla \psi|^2 dx dy dz \leq |\psi|_{L^\infty}^2 |\psi|_{H_{1/2}}^2 \leq C |\psi|_{H_\mu}^4,$$

where C is some constant. Hence, $G(\psi) = o(|\psi|_{H_\mu})$.

4.3. Dual basis. Since E_{jkl} is finite dimensional for each (j, k, l) , there exists a vector $\Psi_p^{\beta_{jklq}} \in E_{jkl}$ ($q = 1, 2, 3$ and $p = 1, 2$) such that

$$\langle \Psi_p^{\beta_{jklq}}, \psi_{p^*}^{\beta_{jklq^*}} \rangle_H \begin{cases} \neq 0 & \text{if } (q^*, p^*) = (q, p) \\ = 0 & \text{if } (q^*, p^*) \neq (q, p). \end{cases}$$

Choose $\Psi_p^{\beta_{jkl\sigma}} = \psi_p^{\beta_{jkl\sigma}}$. By orthogonality of E_{jkl} and E_{jkl}^σ , $\{\Psi_p^{\beta_{jklq}}, \Psi_p^{\beta_{jkl\sigma}}\}_{j,l=0,k=-\infty}^\infty$ form a dual basis of H corresponding to $\{E_{jkl}, E_{jkl}^\sigma\}_{j,l=0,k=-\infty}^\infty$ in the sense that

$$\langle \Psi_p^\beta, \psi_{p^*}^{\beta^*} \rangle_H \begin{cases} \neq 0 & \text{if } (\beta^*, p^*) = (\beta, p) \\ = 0 & \text{if } (\beta^*, p^*) \neq (\beta, p). \end{cases}$$

The proof of Lemma 4.5 implies that all but finitely many of f_{jkl} have three distinct real zeros. For such f_{jkl} with $j^2 + k^2 \neq 0$, $\Psi_1^{\beta_{jklq}}$ and $\Psi_2^{\beta_{jklq}}$ could be chosen as

$$\begin{cases} \Psi_1^{\beta_{jklq}} = \phi_{jkl}^1 + C_1(\beta_{jklq})\phi_{jkl}^2 + C_2(\beta_{jklq})\phi_{jkl}^3 \\ \Psi_2^{\beta_{jklq}} = \phi_{jkl}^4 + C_1(\beta_{jklq})\phi_{jkl}^5 + C_2(\beta_{jklq})\phi_{jkl}^6, \end{cases}$$

where

$$\begin{cases} C_1(\beta_{jklq}) = \frac{\sigma\lambda}{\beta_{jklq} + \gamma_{jkl}^2} = \sigma\lambda A_1(\beta_{jklq}) \\ C_2(\beta_{jklq}) = \frac{-\sigma\eta}{\beta_{jklq} + \tau\gamma_{jkl}^2} = -\sigma\eta A_2(\beta_{jklq}). \end{cases}$$

5. The proofs of the main theorems

We are now in a position to reduce equations of (2.1)–(2.4) to the center manifold. We would like to fix $\eta < \eta_c$, and let $\lambda \approx \lambda_c$ be the bifurcation parameter. For any $\psi = (U, T, S) \in H$, we have

$$\psi = \sum_{k=-\infty}^\infty \sum_{j=0, l=1}^\infty \sum_{q=1}^3 \left(x_{jklq} \psi_1^{\beta_{jklq}} + y_{jklq} \psi_2^{\beta_{jklq}} \right) + \sum_{k=-\infty}^\infty \sum_{j, l=0}^\infty \left(x_{jkl\sigma} \psi_1^{\beta_{jkl\sigma}} + y_{jkl\sigma} \psi_2^{\beta_{jkl\sigma}} \right).$$

For the square case, we assume $\alpha_1 = \alpha_2 = \frac{\pi}{2}$. Hence $\beta_{1111}(\lambda) = \beta_{1-111}(\lambda)$ are the first eigenvalues.

For brevity, we let $\beta_0(\lambda) = \beta_{1111}(\lambda) = \beta_{1-111}(\lambda)$, then the reduced equations

are given by

$$\left\{ \begin{aligned} \frac{dx_{1111}}{dt} &= \beta_0(\lambda)x_{1111} + \frac{1}{\langle \psi_1^{\beta_{1111}}, \Psi_1^{\beta_{1111}} \rangle_H} \langle G(\psi, \psi), \Psi_1^{\beta_{1111}} \rangle_H \\ \frac{dy_{1111}}{dt} &= \beta_0(\lambda)y_{1111} + \frac{1}{\langle \psi_2^{\beta_{1111}}, \Psi_2^{\beta_{1111}} \rangle_H} \langle G(\psi, \psi), \Psi_2^{\beta_{1111}} \rangle_H \\ \frac{dx_{1-111}}{dt} &= \beta_0(\lambda)x_{1-111} + \frac{1}{\langle \psi_1^{\beta_{1-111}}, \Psi_1^{\beta_{1-111}} \rangle_H} \langle G(\psi, \psi), \Psi_1^{\beta_{1-111}} \rangle_H \\ \frac{dy_{1-111}}{dt} &= \beta_0(\lambda)y_{1-111} + \frac{1}{\langle \psi_2^{\beta_{1-111}}, \Psi_2^{\beta_{1-111}} \rangle_H} \langle G(\psi, \psi), \Psi_2^{\beta_{1-111}} \rangle_H. \end{aligned} \right. \quad (5.1)$$

Here for $\psi_1 = (U_1, T_1, S_1)$, $\psi_2 = (U_2, T_2, S_2)$ and $\psi_3 = (U_3, T_3, S_3)$,

$$\begin{aligned} \langle G(\psi_1, \psi_2), \psi_3 \rangle_H &= - \int_0^1 \int_0^{\frac{2\pi}{\alpha_2}} \int_0^{\frac{2\pi}{\alpha_1}} [\langle (U_1 \cdot \nabla)U_2, U_3 \rangle_{\mathbb{R}^3} \\ &\quad + (U_1 \cdot \nabla)T_2T_3 + (U_1 \cdot \nabla)S_2S_3] dx dy dz. \end{aligned}$$

Let the center manifold function be denoted by

$$\Phi = \sum_{\substack{\beta \neq \beta_{1111} \\ \beta \neq \beta_{1-111}}} \left(\Phi_1^\beta(x_{1111}, y_{1111}, x_{1-111}, y_{1-111})\psi_1^\beta + \Phi_2^\beta(x_{1111}, y_{1111}, x_{1-111}, y_{1-111})\psi_2^\beta \right).$$

Note that for any $\psi_i \in H_1$ ($i = 1, 2, 3$), $\langle G(\psi_1, \psi_2), \psi_2 \rangle_H = 0$, $\langle G(\psi_1, \psi_2), \psi_3 \rangle_H = -\langle G(\psi_1, \psi_3), \psi_2 \rangle_H$, and for any $\psi_i \in E_{jkl}$ ($i = 1, 2, 3$), $\langle G(\psi_1, \psi_2), \psi_3 \rangle_H = 0$.

Applying Theorem 3.8 in [11], we obtain

$$\begin{aligned} \Phi^{\beta_{0021}} &= \frac{A_2\pi}{2\beta_{0021}} [x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2] + o(2) \\ \Phi^{\beta_{0022}} &= \frac{A_1\pi}{2\beta_{0022}} [x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2] + o(2) \\ \Phi_1^{\beta_{202q}} &= B(\beta_{202q})(x_{1111}y_{1-111} + x_{1-111}y_{1111}) + o(2) \\ \Phi_2^{\beta_{202q}} &= B(\beta_{202q})(-x_{1111}x_{1-111} + y_{1111}y_{1-111}) + o(2) \\ \Phi_1^{\beta_{022q}} &= B(\beta_{022q})(x_{1111}y_{1-111} - x_{1-111}y_{1111}) + o(2) \\ \Phi_2^{\beta_{022q}} &= B(\beta_{022q})(x_{1111}x_{1-111} + y_{1111}y_{1-111}) + o(2) \end{aligned}$$

and

$$\begin{aligned} \Phi(x_{1111}, y_{1111}, x_{1-111}, y_{1-111}) &= \Phi^{\beta_{0021}}\psi^{\beta_{0021}} + \Phi^{\beta_{0022}}\psi^{\beta_{0022}} \\ &\quad + \sum_{q=1}^3 \left(\Phi_1^{\beta_{202q}}\psi_1^{\beta_{202q}} + \Phi_2^{\beta_{202q}}\psi_2^{\beta_{202q}} \right. \\ &\quad \left. + \Phi_1^{\beta_{022q}}\psi_1^{\beta_{022q}} + \Phi_2^{\beta_{022q}}\psi_2^{\beta_{022q}} \right) + o(2), \end{aligned} \quad (5.2)$$

where

$$\begin{aligned}
 B(\beta) &= \frac{\pi(3 + A_1(\beta_0)C_1(\beta) + A_2(\beta_0)C_2(\beta))}{2\beta(5 + A_1(\beta)C_1(\beta) + A_2(\beta)C_2(\beta))} \\
 C_1(\beta) &= \frac{\sigma\lambda}{(\beta + \gamma_{202}^2)} \\
 C_2(\beta) &= \frac{\sigma\eta}{(\beta + \tau\gamma_{202}^2)} \\
 o(2) &= o(x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2) \\
 &\quad + O(|\beta_0(\lambda)| \cdot (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)).
 \end{aligned}$$

Hereafter, we make the following convention:

$$\begin{aligned}
 o(3) &= o\left((x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)^{\frac{3}{2}}\right) \\
 &\quad + O\left(|\beta_0(\lambda)| \cdot (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)^{\frac{3}{2}}\right) \\
 o(4) &= o\left((x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)^2\right) \\
 &\quad + O\left(|\beta_0(\lambda)| \cdot (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)^2\right).
 \end{aligned}$$

By (5.2) and the fact that $\beta_{022q} = \beta_{202q}$, we obtain

$$\begin{aligned}
 &\langle G(\psi, \psi), \Psi_1^{\beta_{1111}} \rangle_H \\
 &= \langle G(\psi_1^{\beta_{1111}}, \Phi), \Psi_1^{\beta_{1111}} \rangle_H + \langle G(\psi_2^{\beta_{1111}}, \Phi), \Psi_1^{\beta_{1111}} \rangle_H \\
 &\quad + \langle G(\psi_1^{\beta_{1-111}}, \Phi), \Psi_1^{\beta_{1111}} \rangle_H + \langle G(\psi_2^{\beta_{1-111}}, \Phi), \Psi_1^{\beta_{1111}} \rangle_H + o(3) \\
 &= -\langle G(\psi_1^{\beta_{1111}}, \Psi_1^{\beta_{1111}}), \Phi \rangle_H - \langle G(\psi_2^{\beta_{1111}}, \Psi_1^{\beta_{1111}}), \Phi \rangle_H \\
 &\quad - \langle G(\psi_1^{\beta_{1-111}}, \Psi_1^{\beta_{1111}}), \Phi \rangle_H - \langle G(\psi_2^{\beta_{1-111}}, \Psi_1^{\beta_{1111}}), \Phi \rangle_H + o(3) \\
 &= 2\pi^2 \left(\frac{A_1 C_1}{\beta_{0022}} + \frac{A_2 C_2}{\beta_{0021}} \right) (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)x_{1111} \\
 &\quad + 2 \sum_{q=1}^3 B^*(\beta_{202q})B(\beta_{202q})(x_{1-111}^2 + y_{1-111}^2)x_{1111} + o(3),
 \end{aligned}$$

where $B^*(\beta) = \pi(3 + A_1(\beta)C_1(\beta_0) + A_2(\beta)C_2(\beta_0))$. Similarly, we derive that

$$\begin{aligned}
 &\langle G(\psi, \psi), \Psi_2^{\beta_{1111}} \rangle_H \\
 &= 2\pi^2 \left(\frac{A_1 C_1}{\beta_{0022}} + \frac{A_2 C_2}{\beta_{0021}} \right) (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)y_{1111} \\
 &\quad + 2 \sum_{q=1}^3 B^*(\beta_{202q})B(\beta_{202q})(x_{1-111}^2 + y_{1-111}^2)y_{1111} + o(3)
 \end{aligned}$$

$$\begin{aligned}
 & \langle G(\psi, \psi), \Psi_1^{\beta_{1-111}} \rangle_H \\
 &= 2\pi^2 \left(\frac{A_1 C_1}{\beta_{0022}} + \frac{A_2 C_2}{\beta_{0021}} \right) (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2) x_{1-111} \\
 & \quad + 2 \sum_{q=1}^3 B^*(\beta_{202q}) B(\beta_{202q}) (x_{1111}^2 + y_{1111}^2) x_{1-111} + o(3) \\
 & \langle G(\psi, \psi), \Psi_2^{\beta_{1-111}} \rangle_H \\
 &= 2\pi^2 \left(\frac{A_1 C_1}{\beta_{0022}} + \frac{A_2 C_2}{\beta_{0021}} \right) (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2) y_{1-111} \\
 & \quad + 2 \sum_{q=1}^3 B^*(\beta_{202q}) B(\beta_{202q}) (x_{1111}^2 + y_{1111}^2) y_{1-111} + o(3).
 \end{aligned}$$

Therefore, (5.1) can be rewritten as

$$\left\{ \begin{aligned}
 \frac{dx_{1111}}{dt} &= \beta_0(\lambda)x_{1111} + \delta_1 E x_{1111} + \delta_2 (x_{1-111}^2 + y_{1-111}^2)x_{1111} + o(3) \\
 \frac{dy_{1111}}{dt} &= \beta_0(\lambda)y_{1111} + \delta_1 E y_{1111} + \delta_2 (x_{1-111}^2 + y_{1-111}^2)y_{1111} + o(3) \\
 \frac{dx_{1-111}}{dt} &= \beta_0(\lambda)x_{1-111} + \delta_1 E x_{1-111} + \delta_2 (x_{1111}^2 + y_{1111}^2)x_{1-111} + o(3) \\
 \frac{dy_{1-111}}{dt} &= \beta_0(\lambda)y_{1-111} + \delta_1 E y_{1-111} + \delta_2 (x_{1111}^2 + y_{1111}^2)y_{1-111} + o(3),
 \end{aligned} \right. \tag{5.3}$$

where $E = (x_{1111}^2 + y_{1111}^2 + x_{1-111}^2 + y_{1-111}^2)$,

$$\delta_1 = \delta_1(\lambda, \eta) = \frac{2\pi^2 \left(\frac{A_1 C_1}{\beta_{0022}} + \frac{A_2 C_2}{\beta_{0021}} \right)}{4(3 + A_1 C_1 + A_2 C_2)} = -\frac{(A_1 C_1 + \tau^{-1} A_2 C_2)}{8(3 + A_1 C_1 + A_2 C_2)} \tag{5.4}$$

$$\delta_2 = \delta_2(\lambda, \eta) = 2 \sum_{q=1}^3 \frac{B^*(\beta_{202q}) B(\beta_{202q})}{4(3 + A_1 C_1 + A_2 C_2)}. \tag{5.5}$$

The energy estimate of (5.3) is given by

$$\frac{1}{2} \frac{dE}{dt} = \beta_0(\lambda)E + \delta_1 E^2 + 2\delta_2 (x_{1111}^2 + y_{1111}^2)(x_{1-111}^2 + y_{1-111}^2) + o(4).$$

If the quadratic form

$$\delta_1 E^2 + 2\delta_2 (x_{1111}^2 + y_{1111}^2)(x_{1-111}^2 + y_{1-111}^2), \tag{5.6}$$

is negative definite at $\lambda = \lambda_c$, we conclude that $(U, T, S) = 0$ is a locally asymptotically stable equilibrium point of (2.1)–(2.4). We then obtain Theorem 3.5 by Theorem 3.1 directly. And if the quadratic form (5.6) is positive definite,

we obtain the subcritical bifurcation. This completes the proofs of Theorem 3.5 and Theorem 3.6.

For the rectangle case, the first eigenspace is of dimension two. The reduced equations on the center manifold are given by

$$\begin{cases} \frac{dx_{1011}}{dt} = \beta_{1011}(\lambda)x_{1011} + \delta_1(x_{1011}^2 + y_{1011}^2)x_{1011} + o(3) \\ \frac{dy_{1011}}{dt} = \beta_{1011}(\lambda)y_{1011} + \delta_1(x_{1011}^2 + y_{1011}^2)y_{1011} + o(3). \end{cases}$$

The rest part of the proofs of Theorem 3.2, Theorem 3.3 and Theorem 3.4 is similar to the 2D case in [8]. In this case, we can use Theorem 5.10 in [13] or invariant sphere theorem in [4] to conclude the S^1 structure of the bifurcating solution. \square

Remark 5.1.

1. As we have already proved in [8], we know that

$$\delta_1 \begin{cases} < 0 & \text{if } \eta < \eta_{c1} \\ > 0 & \text{if } \eta > \eta_{c1}. \end{cases}$$

2. When σ , τ , λ and η are given, δ_1 and δ_2 can be evaluated numerically.

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