

# Self-Similarity in the Collection of $\omega$ -Limit Sets

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**Abstract.** Let  $\omega$  be the map which takes  $(x, f)$  in  $I \times C(I \times I)$  to the  $\omega$ -limit set  $\omega(x, f)$  with  $\mathcal{L}$  the map taking  $f$  in  $C(I, I)$  to the family of  $\omega$ -limit sets  $\{\omega(x, f) : x \in I\}$ . We study  $\mathcal{R}(\omega) = \{\omega(x, f) : (x, f) \in I \times C(I, I)\}$ , the range of  $\omega$ , and  $\mathcal{R}(\mathcal{L}) = \{\mathcal{L}(f) : f \in C(I, I)\}$ , the range of  $\mathcal{L}$ . In particular,  $\mathcal{R}(\omega)$  and its complement are both dense,  $\mathcal{R}(\omega)$  is path-connected, and  $\mathcal{R}(\omega)$  is the disjoint union of a dense  $G_\delta$  set and a first category  $F_\sigma$  set. We see that  $\mathcal{R}(\mathcal{L})$  is porous and path-connected, and its closure contains  $\mathcal{K} = \{F \subseteq [0, 1] : F \text{ is closed}\}$ . Moreover, each of the sets  $\mathcal{R}(\omega)$  and  $\mathcal{R}(\mathcal{L})$  demonstrates a self-similar structure.

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## 1. Introduction

Fundamental to the notion of chaos is the idea that points arbitrarily close together can generate trajectories or  $\omega$ -limit sets that are far apart. In particular, if  $f$  is a continuous self-map of  $I = [0, 1]$ , and  $x \in I$ , then  $\gamma(x, f) = \{x, f(x), f(f(x)), \dots\}$  is the trajectory of  $x$  generated by  $f$ , with the collection of subsequential limits of  $\gamma(x, f)$  being the  $\omega$ -limit set  $\omega(x, f)$ . Equivalently,

$$\omega(x, f) = \bigcap_{m \geq 0} \overline{\bigcup_{n \geq m} f^n(x)}.$$

These  $\omega$ -limit sets are the focus of our analysis, and we begin with a brief overview of some of their properties. Immediate consequences of the definition are that

- (1)  $\omega(x, f)$  is closed, and
- (2)  $f(\omega(x, f)) = \omega(x, f)$ , that is  $\omega(x, f)$  is strongly invariant,

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for all  $(x, f)$  in  $I \times C(I, I)$ .

While all  $\omega$ -limit sets are closed, only certain classes of closed sets are actually generated as  $\omega$ -limit sets. We make frequent use of the following characterization of  $\omega$ -limit sets found in [1].

**Theorem 1.1.** *Let  $F \subseteq [0, 1]$  be closed. Then  $F$  is an  $\omega$ -limit set for some  $f$  in  $C(I, I)$  if and only if  $F$  is either nowhere dense, or a finite union of nondegenerate closed intervals.*

As the following shows, the preponderance of  $\omega$ -limit sets are nowhere dense and perfect.

**Theorem 1.2.** ([2, Theorem 5]) *For a residual set of points  $(x, f)$  in  $I \times C(I, I)$ ,  $\omega(x, f)$  is nowhere dense and perfect.*

The main results of [1] are replicated in [11] with a much simpler analysis, and [12] characterizes those  $\omega$ -limit sets generated by functions with zero topological entropy. Several articles, including [13] and [14], continue the study of typical behavior initiated with [2]. In [13] one finds that if  $M$  is the Cantor space or an  $n$ -dimensional manifold, then there is a residual set of points  $(x, f)$  in  $M \times C(M, M)$  all of which generate as their  $\omega$ -limit set a particular, unique type of adding machine.

Bruckner and Ceder provide in [10] a very interesting study of the map  $\omega_f : I \rightarrow \mathcal{K}$  given by  $x \mapsto \omega(x, f)$ , where  $f \in C(I, I)$  is fixed. The authors establish a notion of chaos strictly intermediate to positive topological entropy and the existence of an uncountable scrambled set. One also finds a comprehensive analysis of the behavior of a continuous function on its symple systems. Bruckner and Ceder’s work foreshadows some of what is found in this article.

As mentioned earlier,  $\omega(x, f)$  is necessarily closed whenever  $(x, f)$  is in  $I \times C(I, I)$ . Much less obvious is that  $\Lambda(f) = \cup_{x \in I} \omega(x, f)$  is closed in  $[0, 1]$  whenever  $f \in C(I, I)$ , and that  $\mathcal{L}(f) = \{\omega(x, f) : x \in I\}$  is closed with respect to the Hausdorff metric [4, 18].

In what follows, we consider two maps which deal directly with the  $\omega$ -limit sets generated by continuous self-maps of  $[0, 1]$ :

$$\omega : I \times C(I, I) \rightarrow \mathcal{K} \quad \text{given by} \quad (x, f) \mapsto \omega(x, f)$$

and

$$\mathcal{L} : C(I, I) \rightarrow \mathcal{K}^* \quad \text{given by} \quad f \mapsto \mathcal{L}(f).$$

Here,  $\mathcal{K}$  is the metric space composed of the class of nonempty closed sets in  $I$  endowed with the Hausdorff metric  $\mathcal{H}$  given by  $\mathcal{H}(E, F) = \inf\{\delta > 0 : E \subset B_\delta(F), F \subset B_\delta(E)\}$ . This space is compact [9].

The metric space  $\mathcal{K}^*$  consists of the nonempty closed subsets of  $\mathcal{K}$ . Thus,  $K \in \mathcal{K}^*$  if  $K$  is a nonempty family of nonempty closed sets in  $I$  such that  $K$

is closed in  $\mathcal{K}$  with respect to  $\mathcal{H}$ . We endow  $\mathcal{K}^*$  with the metric  $\mathcal{H}^*$  so that  $K_1$  and  $K_2$  are close with respect to  $\mathcal{H}^*$  if each member of  $K_1$  is close to some member of  $K_2$  with respect to  $\mathcal{H}$ , and vice-versa. This metric space also is compact [8].

Here are some of our results. Let

$$\mathcal{R}(\omega) = \{\omega(x, f) : (x, f) \in I \times C(I, I)\}$$

be the range of  $\omega$ . We show that

- (1) both  $\mathcal{R}(\omega)$  and  $\mathcal{K} \setminus \mathcal{R}(\omega)$  are dense in  $\mathcal{K}$ ,
- (2)  $\mathcal{R}(\omega)$  is path-connected,
- (3)  $\mathcal{R}(\omega)$  is the disjoint union of a dense  $G_\delta$  subset of  $\mathcal{K}$  and a first category  $F_\sigma$  subset of  $\mathcal{K}$ .

The set  $\mathcal{R}(\omega)$  also is self-similar. Let  $h_{[a,b],I} : [a, b] \rightarrow I$  be the linear homeomorphism such that  $h_{[a,b],I}(a) = 0$  and  $h_{[a,b],I}(b) = 1$ . If  $\mathcal{S}_{[a,b]} = \{F \in \mathcal{R}(\omega) : F \subseteq [a, b]\}$ , then  $\mathcal{R}(\omega) = h_{[a,b],I}(\mathcal{S}_{[a,b]})$ .

Similarly, let

$$\mathcal{R}(\mathcal{L}) = \{\mathcal{L}(f) : f \in C(I, I)\}$$

be the range of  $\mathcal{L}$  in  $\mathcal{K}^*$ . We show that

- (1)  $\mathcal{R}(\mathcal{L})$  is a porous subset of  $\mathcal{K}^*$ ,
- (2)  $\mathcal{R}(\mathcal{L})$  is path-connected,
- (3)  $\mathcal{K} \in \overline{\mathcal{R}(\mathcal{L})}$ ,
- (4)  $\mathcal{R}(\mathcal{L}) \subsetneq \overline{\mathcal{R}(\mathcal{L})}$ .

If  $F \in \mathcal{R}(\mathcal{L})$ , by  $F \subseteq (a, b)$  we mean that  $\omega \subseteq (a, b)$  for every  $\omega \in F$ . Now, let  $(a, b) \subseteq [0, 1]$  and set  $\mathcal{T}_{(a,b)} = \{F \in \mathcal{L}(f) : F \subseteq (a, b)\}$ , and  $\mathcal{T}_{(0,1)} = \{F \in \mathcal{L}(f) : F \subseteq (0, 1)\}$ . Then,  $\mathcal{R}(\mathcal{L})$  also demonstrates a self-similar structure, as  $h_{[a,b],I}(\mathcal{T}_{(a,b)}) = \mathcal{T}_{(0,1)}$ .

We proceed through several sections. After establishing notation and definitions in Section 2, we study the map  $\mathcal{L} : C(I, I) \rightarrow \mathcal{K}^*$  in Section 3. Section 4 focuses on the results concerning  $\omega : I \times C(I, I) \rightarrow \mathcal{K}$ .

## 2. Definitions and background material

Let  $X = (X, d)$  be a compact metric space and let  $\mathcal{C}(X, X)$  be the class of continuous self-maps of  $X$ .

**Definition 2.1.** A topological dynamical system  $(X, f)$  is a compact metric space  $X$  and a map  $f \in \mathcal{C}(X, X)$ .

In the following  $X$  will always denote a compact metric space. For  $f \in \mathcal{C}(X, X)$  and any integer  $n$ ,  $f^n$  denotes the  $n$ -th iterate of  $f$ . Let  $P(f)$

be the set of periodic points of  $f$ . For each  $x \in X$ , we denote by  $\omega(x, f)$  the  $\omega$ -limit set of  $f$ ; that is, the set of limit points of the sequence  $\{f^k(x)\}_{k \geq 0}$ . Let  $\Lambda(f) = \cup_{x \in X} \omega(x, f)$  and  $\mathcal{L}(f) = \{\omega(x, f) : x \in X\}$ . We let  $I = [0, 1]$ , the closed unit interval of the real line. If  $f \in \mathcal{C}(I, I)$ , then  $\Lambda(f)$  is closed [18].

**Porosity.** Let  $P = (P, d)$  be a metric space, with  $B_r(x) = \{y \in P : d(x, y) < r\}$  for  $x \in P$  and  $r > 0$ . Take  $M \subseteq P$ ,  $x \in P$  and  $R > 0$ . Let

$$r(x, R, M) = \sup\{r > 0 : \text{there exists } z \text{ in } P \text{ such that } B_r(z) \subset B_R(x) \setminus M\}.$$

The number

$$P(M, x) = 2 \limsup_{R \rightarrow 0^+} \frac{r(x, R, M)}{R},$$

is called the *porosity of  $M$  at  $x$*  [20].

**Solenoidal sets.** [5] An interval  $J$  is called periodic (of period  $k$ ) or  $k$ -periodic if  $J, \dots, f^{k-1}(J)$  are pairwise disjoint and  $f^k(J) = J$ . The set  $\cup_{i=0}^{k-1} f^i(J)$  is the orbit of  $J$  and is denoted by  $\text{orb } J$ .

Let  $J_0 \supset J_1 \supset \dots$  be periodic intervals with periods  $m_0, m_1, \dots$ . Obviously  $m_{i+1}$  is a multiple of  $m_i$  for all  $i$ . If  $m_i \rightarrow \infty$  then the intervals  $\{J_i\}_{i=0}^\infty$  are said to be generating and any invariant closed set  $S \subseteq Q = \cap_{i=0}^\infty \text{orb } J_i$  is called a solenoidal set; if  $Q$  is nowhere dense then we call  $Q$  a solenoid.

**Basic sets.** [5] Let  $J$  be an  $n$ -periodic interval, and let  $M = \text{orb } J$  be the orbit of  $J$ . Consider a set

$$\{x \in M : \text{for any relative neighborhood } U \text{ of } x \text{ in } M \text{ we have } \overline{\text{orb } U} = M\};$$

it is easy to see that this is a closed invariant set. It is called a basic set and denoted by  $B(M, f)$  provided it is infinite. The set  $B(M, f)$  is perfect [5, Theorem 4.1].

**Path-connected topological spaces.** A topological space  $X$  is *path-connected* (or *pathwise connected*) if for every two points  $x, y$  in  $X$ , there is a continuous function  $f$  from  $[0, 1]$  to  $X$  such that  $f(0) = x$  and  $f(1) = y$ .

### 3. The map $\mathcal{L} : C(I, I) \rightarrow \mathcal{K}^*$

In this section we focus our attention on the map  $\mathcal{L} : C(I, I) \rightarrow \mathcal{K}^*$  which takes  $f$  in  $C(I, I)$  to its collection of  $\omega$ -limit sets  $\mathcal{L}(f) = \{\omega(x, f) : x \in I\}$ . As our first result shows, the elements of  $\mathcal{R}(\mathcal{L})$  can be extremely complicated, as  $\mathcal{K}$  is contained in the closure of  $\mathcal{R}(\mathcal{L})$ .

**Proposition 3.1.** *The set  $\mathcal{K} = \{F \subseteq [0, 1] : F \text{ is closed}\}$  is contained in the closure of  $\mathcal{R}(\mathcal{L})$ .*

*Proof.* As  $\mathcal{K}$  is a compact metric space, it is totally bounded. Hence, fixed  $\epsilon > 0$ , there exists an  $\epsilon$ -net; that is, there exists a finite collection  $\mathcal{T}_\epsilon = \{T_1, T_2, \dots, T_m\}$  of elements of  $\mathcal{K}$  compact such that  $\mathcal{K} \subseteq \cup_{i=1}^m B_\epsilon(T_i)$ ,  $T_i \cap T_j = \emptyset$  whenever  $i \neq j$ , and  $|T_i|$  is finite for all  $i$ . Let  $f \in C(I, I)$  so that  $T_i \in \mathcal{L}(f)$  for all  $1 \leq i \leq m$ . Then,  $\mathcal{H}^*(\mathcal{K}, \mathcal{L}(f)) < \epsilon$ .  $\square$

As mentioned in the introduction,  $\Lambda(f)$  and  $\mathcal{L}(f)$  are closed for any  $f$  in  $C(I, I)$ , as is each of the  $\omega$ -limit sets  $\omega(x, f)$ . The next two examples show, however, that  $\mathcal{R}(\mathcal{L})$  is not a closed subset of  $\mathcal{K}^*$ .

**Example 3.2.** Recall that  $\mathcal{K}$  is contained in the closure of  $\mathcal{R}(\mathcal{L})$ , and  $\{\{x\} : x \in [0, 1]\} \subsetneq \mathcal{K}$ . If  $f \in C(I, I)$  such that  $\{\{x\} : x \in [0, 1]\} \subseteq \mathcal{L}(f)$ , then  $\omega(x, f) = \{x\}$  for any  $x$  in  $[0, 1]$ , and this precludes  $T \in \mathcal{L}(f)$  for any  $T$  in  $\mathcal{K} \setminus \{\{x\} : x \in [0, 1]\}$ .

**Example 3.3.** Let  $f(x) = x$  on  $I$ , and for any  $\epsilon > 0$ , choose  $\frac{1}{n} < \epsilon$ . An appropriate polygonal function (*the Bruckner sawtooth function*) that possesses the orbit

$$0 \rightarrow \frac{1}{n} \rightarrow \frac{2}{n} \rightarrow \dots \rightarrow \frac{n-1}{n} \rightarrow 1 \rightarrow \frac{n-\frac{1}{2}}{n} \rightarrow \frac{n-\frac{3}{2}}{n} \rightarrow \dots \rightarrow \frac{1}{2} \rightarrow 0$$

has a periodic orbit that spans  $I$ , and has the property that  $\|f - f_n\| \leq \frac{1}{n}$ . Then  $f_n$  uniformly converges to  $f$ , and since  $\mathcal{K}^*$  is compact there exists  $\{f_{n_k}\}_{k \in \mathbb{N}} \subseteq \{f_n\}_{n \in \mathbb{N}}$  so that  $\lim_{k \rightarrow \infty} \mathcal{L}(f_{n_k}) = K^*$  exists. Then  $\{\{x\} : x \in [0, 1]\} \cup [0, 1] \subseteq K^*$ . If there exists  $g \in C(I, I)$  so that  $\{\{x\} : x \in [0, 1]\} \subseteq \mathcal{L}(g)$ , then  $\omega(x, g) = \{x\}$  for any  $x$  in  $[0, 1]$ , so that  $[0, 1] \notin \mathcal{L}(g)$ .

Two of the principal results of this section are found with Theorems 3.4 and 3.5. The first result shows just how particular the elements  $\mathcal{L}(f)$  are in  $\mathcal{K}^*$ , as  $\mathcal{R}(\mathcal{L})$  is porous in  $\mathcal{K}^*$ . Interestingly enough, while nowhere dense,  $\mathcal{R}(\mathcal{L})$  has no isolated point, and it is, in fact, path-connected.

**Theorem 3.4.**  $\mathcal{R}(\mathcal{L})$  is porous in  $\mathcal{K}^*$ . In particular,  $P(\mathcal{R}(\mathcal{L}), \mathcal{L}(f)) = 1$  for all  $f$  in  $C(I, I)$ .

*Proof.* Fix  $f$  in  $C(I, I)$ ,  $n \in \mathbb{N}$ , and  $0 < \epsilon < \frac{1}{2}$ . Since  $\mathcal{L}(f)$  is compact in  $\mathcal{K}^*$ , we can take  $K^* = \{K_1, K_2, \dots, K_m\}$  in  $\mathcal{K}^*$  so that

- (1)  $K^*$  is an  $\epsilon$ -net of  $\mathcal{L}(f)$ ;
- (2)  $|K_i| \geq 2$  for any  $i$ ;
- (3)  $\text{diam}(K_i) \geq \frac{n-1}{n}2\epsilon$  for any  $i$ .

Now, if  $E^* \in \mathcal{K}^*$  such that  $\mathcal{H}^*(E^*, K^*) < \frac{n-1}{n}\epsilon$ , then  $|K| \geq 2$  for any  $K \in E^*$ . In particular,

$$\mathcal{R}(\mathcal{L}) \cap B_{\frac{n-1}{n}\epsilon}(K^*) = \emptyset, \quad \text{and} \quad P(\mathcal{R}(\mathcal{L}), \mathcal{L}(f)) \geq 2 \left[ \frac{\frac{n-1}{n}\epsilon}{2\epsilon} \right] = \frac{n-1}{n}.$$

Now, let  $n \rightarrow +\infty$ .  $\square$

**Theorem 3.5.**  $\mathcal{R}(\mathcal{L})$  is path-connected in  $\mathcal{K}^*$ .

*Proof.* Let  $f_{\frac{1}{2}} : I \rightarrow I$  be the constant map given by  $f_{\frac{1}{2}}(x) = \frac{1}{2}$ , for all  $x \in I$ . Since, by [19, Theorem 1.4],  $\mathcal{L} : C(I, I) \rightarrow \mathcal{K}^*$  is continuous at every constant map, it is, in particular, continuous at  $f_{\frac{1}{2}}$ . Therefore, for any  $\epsilon > 0$  there is  $\delta > 0$  so that  $\mathcal{L}(g) \subseteq B_\epsilon(\{\frac{1}{2}\})$ , whenever  $\|g - f_{\frac{1}{2}}\| < \delta$ . Now, fix some  $g$  in  $C(I, I)$  and take  $0 < \epsilon \leq 1$ . Consider the homeomorphism  $h_\epsilon : I \rightarrow J = [\frac{1}{2} - \frac{\epsilon}{2}, \frac{1}{2} + \frac{\epsilon}{2}]$  so that  $h_\epsilon(0) = \frac{1}{2} - \frac{\epsilon}{2}$ ,  $h_\epsilon(1) = \frac{1}{2} + \frac{\epsilon}{2}$ , and  $h_\epsilon$  is linear on  $[0, 1]$ . Let  $f_g^\epsilon = h_\epsilon \circ g \circ h_\epsilon^{-1} : J \rightarrow J$ , and define  $\tilde{f}_g^\epsilon : I \rightarrow I$  so that

1.  $\tilde{f}_g^\epsilon|_J = f_g^\epsilon$ ,
2.  $\tilde{f}_g^\epsilon|_J = \begin{cases} f_g^\epsilon(\frac{1}{2} - \frac{\epsilon}{2}) & \text{if } x \in [0, \frac{1}{2} - \frac{\epsilon}{2}] \\ f_g^\epsilon(\frac{1}{2} + \frac{\epsilon}{2}) & \text{if } x \in [\frac{1}{2} + \frac{\epsilon}{2}, 1]. \end{cases}$

It follows that  $\mathcal{L}(\tilde{f}_g^\epsilon) = \mathcal{L}(f_g^\epsilon)$  since  $\|\tilde{f}_g^\epsilon - f_{\frac{1}{2}}\| \leq \frac{\epsilon}{2}$ , so that  $\tilde{f}_g^\epsilon([0, 1]) \subseteq J$  and  $f_g^\epsilon(J) \subseteq J$ . Since  $\mathcal{L}$  is continuous at  $f_{\frac{1}{2}}$ , it follows that  $\mathcal{L}(\tilde{f}_g^\epsilon) \rightarrow \{\{\frac{1}{2}\}\}$  as  $\epsilon \rightarrow 0$ , for any  $g \in C(I, I)$ . Since  $g$  and  $f_g^\epsilon$  are topologically conjugate, it follows that  $h_\epsilon(\mathcal{L}(g)) = \mathcal{L}(f_g^\epsilon) = \mathcal{L}(\tilde{f}_g^\epsilon)$ , and since as  $\epsilon \rightarrow 1$   $h_\epsilon \rightarrow i_d$ , where  $i_d$  denotes the identity map on  $[0, 1]$ , we conclude that  $\mathcal{L}(\tilde{f}_g^\epsilon) \rightarrow \mathcal{L}(g)$  as  $\epsilon \rightarrow 1$ . In particular,  $\mathcal{L}(g)$  and  $\mathcal{L}(f_{\frac{1}{2}}) = \{\{\frac{1}{2}\}\}$  are in the same path-connected component of  $\mathcal{R}(\mathcal{L})$ , for any  $g$  in  $C(I, I)$ .  $\square$

**Remark 3.6.** While  $\mathcal{R}(\mathcal{L})$  is path-connected, the paths established in the theorem are not the only ones found between elements of  $\mathcal{R}(\mathcal{L})$ . If  $f \neq g$  in  $C(I, I)$  are topologically conjugate, then  $\mathcal{L}(f)$  and  $\mathcal{L}(g)$  are path-wise connected. Suppose  $f \neq g$  in  $C(I, I)$  with  $h : I \rightarrow I$  a homeomorphism such that  $g = h \circ f \circ h^{-1}$ . Let  $h_\alpha$ ,  $\alpha \in [0, 1]$ , be a continuous injective deformation such that  $h_0 = i_d$ ,  $h_1 = h$ . Then  $\{\mathcal{L}(h_\alpha \circ f \circ h_\alpha^{-1}) : 0 \leq \alpha \leq 1\}$  is a path in  $\mathcal{R}(\mathcal{L})$  with  $\mathcal{L}(f) = \mathcal{L}(h_0 \circ f \circ h_0^{-1})$  and  $\mathcal{L}(g) = \mathcal{L}(h_1 \circ f \circ h_1^{-1})$ .

With the next theorem, we begin a series of results which establish self-similarity in the range of  $\mathcal{L}$ . Theorem 3.7 shows that for any interval  $[a, b]$  in  $[0, 1]$ , we can find a function  $g$  in  $C(I, I)$  so that  $C(I, I)$  is replicated in miniature by  $\overline{B_\epsilon(g)}$  on  $[a, b]$ , where  $\epsilon = \frac{b-a}{2}$ .

**Theorem 3.7.** Let  $[a, b] \subseteq [0, 1]$  and set  $\epsilon = \frac{b-a}{2}$ . There exists  $g$  in  $C(I, I)$  so that  $\overline{B_\epsilon(g)}|_{[a, b]} = h_{I, [a, b]} \circ C(I, I) \circ h_{[a, b], I}$ .

*Proof.* Let  $g \in C(I, I)$  so that  $g(x) = \frac{a+b}{2}$  for any  $x$  in  $[a, b]$ . If  $f \in C(I, I)$  so that  $\|f - g\| \leq \epsilon = \frac{b-a}{2}$ , then

$$\frac{a+b}{2} - \frac{b-a}{2} = a \leq f(x) \leq b = \frac{a+b}{2} + \frac{b-a}{2},$$

for any  $x$  in  $[a, b]$ , so that  $f([a, b]) \subseteq [a, b]$ . Therefore,  $\overline{B_\epsilon(g)}|_{[a, b]} \subseteq C([a, b], [a, b])$ . Clearly,

$$C([a, b], [a, b]) \subseteq B_\epsilon(g)|_{[a, b]} \subseteq \overline{B_\epsilon(g)}|_{[a, b]}.$$

Since  $h_{I, [a, b]}$  and  $h_{[a, b], I}$  are continuous,  $h_{I, [a, b]} \circ f \circ h_{[a, b], I} : [a, b] \rightarrow [a, b]$  is continuous for every  $f$  in  $C(I, I)$ , so that  $h_{I, [a, b]} \circ C(I, I) \circ h_{[a, b], I} \subseteq C([a, b], [a, b])$ .

If  $l \in C([a, b], [a, b])$  then  $f = h_{[a, b], I} \circ l \circ h_{I, [a, b]} \in C(I, I)$  so that  $l = h_{I, [a, b]} \circ f \circ h_{[a, b], I}$ . Thus,  $h_{I, [a, b]} \circ C(I, I) \circ h_{[a, b], I} = C([a, b], [a, b])$ . Finally, of course, if  $f \neq l$  in  $C(I, I)$ , then  $h_{I, [a, b]} \circ f \circ h_{[a, b], I} \neq h_{I, [a, b]} \circ l \circ h_{[a, b], I}$  in  $C([a, b], [a, b])$  so that the transformation from  $C(I, I)$  to  $C([a, b], [a, b])$  is also one to one.  $\square$

**Corollary 3.8.** *Let  $[a, b] \subseteq [0, 1]$  and  $\epsilon = \frac{b-a}{2}$ . There exists  $g$  in  $C(I, I)$  so that the range of  $\mathcal{L}$  restricted to  $\overline{B_\epsilon(g)}|_{[a, b]}$  satisfies*

$$\mathcal{R}(\mathcal{L} : \overline{B_\epsilon(g)}|_{[a, b]} \rightarrow \mathcal{K}^*) = h_{I, [a, b]}(\mathcal{R}(\mathcal{L})).$$

In Theorem 3.7 we begin with an interval  $[a, b]$  in  $I$ , and find an appropriate function  $g$  in  $C(I, I)$ . Our next two results show that we can just as well begin with a function  $f$  in  $C(I, I)$  and an  $\epsilon > 0$ , and find an appropriate  $g$  in  $B_\epsilon(f)$  with a corresponding interval  $[a, b]$ .

**Theorem 3.9.** *For every  $f$  in  $C(I, I)$  and any  $0 < \epsilon \leq 1$  there exist  $g$  in  $B_\epsilon(f)$ ,  $0 < \delta < \epsilon$  and  $[a, b] \subseteq I$  so that  $b - a = 2\delta$ ,  $\overline{B_\delta(g)} \subset B_\epsilon(f)$ , and  $\overline{B_\delta(g)}|_{[a, b]} = h_{I, [a, b]} \circ C(I, I) \circ h_{[a, b], I}$ .*

*Proof.* Let  $f \in C(I, I)$  with  $\epsilon > 0$ . Since  $f$  is uniformly continuous, there exist  $0 < \delta' < \frac{\epsilon}{2}$  so that  $|x - y| < \delta'$  implies  $|f(x) - f(y)| < \frac{\epsilon}{2}$ , and  $z$  in  $[0, 1]$  so that  $f(z) = z$ . Now, suppose that  $z \in (0, 1)$ , and choose  $\delta$  so that  $\delta < \min\{\delta', z, 1 - z\}$ . Let  $g \in C(I, I)$  so that  $g \in B_{\frac{\epsilon}{2}}(f)$  and  $g(y) = z$  for any  $y \in [z - \delta, z + \delta] = [a, b]$ , and consider  $\overline{B_\delta(g)}$ .

Now, suppose that  $z \in \{0, 1\}$ . We assume that  $z = 0$ ; the case that  $z = 1$  is similar. Set  $\delta = \frac{\delta'}{2}$ , and take  $g$  in  $C(I, I)$  so that  $g \in B_{\frac{\epsilon}{2}}(f)$  and  $g(y) = \delta$  for any  $y$  in  $[0, \delta'] = [a, b]$ . Consider  $\overline{B_\delta(g)}$ .

In either case, we show that  $\overline{B_\delta(g)}$  is the set which satisfies our theorem's conclusion. This is done as in our previous theorem's proof.  $\square$

**Corollary 3.10.** *For every  $f$  in  $C(I, I)$  and any  $\epsilon > 0$  there exist  $g$  in  $B_\epsilon(f)$ ,  $0 < \delta < \epsilon$  and  $[a, b] \subseteq I$  so that  $b - a = 2\delta$  and*

$$\overline{B_\delta(g)} \subset B_\epsilon(f),$$

and

$$\mathcal{R}(\mathcal{L} : \overline{B_\delta(g)}|_{[a, b]} \rightarrow \mathcal{K}^*) = h_{I, [a, b]} \circ \mathcal{R}(\mathcal{L}).$$

We conclude our study of  $\mathcal{R}(\mathcal{L})$  with the next theorem. Stronger than Corollaries 3.8 and 3.10, Theorem 3.11 shows that all of the elements of  $\mathcal{R}(\mathcal{L})$  which lie in any interval  $(a, b)$  found in  $I$  are a scaled copy of those found in  $(0, 1)$ .

**Theorem 3.11.** *Let  $(a, b) \subseteq [0, 1]$ , and set  $\mathcal{T}_{(0,1)} = \{\mathcal{L}(f) : \mathcal{L}(f) \subseteq (0, 1), f \in C(I, I)\}$ ,  $\mathcal{T}_{(a,b)} = \{\mathcal{L}(f) : \mathcal{L}(f) \subseteq (a, b), f \in C(I, I)\}$ . Then*

$$\mathcal{T}_{(0,1)} = h_{[a,b],I}(\mathcal{T}_{(a,b)}),$$

so that  $\mathcal{T}_{(0,1)}$  and  $\mathcal{T}_{(a,b)}$  are homeomorphic.

*Proof.* For each  $f$  in  $C(I, I)$ ,  $\mathcal{L}(f)$  is closed in  $(\mathcal{K}, \mathcal{H})$  by [4]. Let  $f \in C(I, I)$ . By  $\mathcal{L}(f) \subseteq (a, b)$  we intend  $\omega(x, f) \subseteq (a, b)$  for all  $x$  in  $I$ .

We first show that  $h_{I,[a,b]}(\mathcal{T}_{(0,1)}) \subseteq \mathcal{T}_{(a,b)}$ . Let  $g \in C(I, I)$ , so that  $\mathcal{L}(g) \in \mathcal{T}_{(0,1)}$ , and set  $f_g = h_{I,[a,b]} \circ g \circ h_{[a,b],I}$ . Since  $g \in C(I, I)$ , it follows that  $f_g \in C([a, b], [a, b])$  and  $\mathcal{L}(f_g) = h_{I,[a,b]}(\mathcal{L}(g)) \subseteq (a, b)$ . We extend  $f_g : [a, b] \rightarrow [a, b]$  to  $f : I \rightarrow I$  so that

$$f(x) = \begin{cases} f_g(a) & \text{if } x \in [0, a] \\ f_g(x) & \text{if } x \in [a, b] \\ f_g(b) & \text{if } x \in [b, 1]. \end{cases}$$

Since  $\mathcal{L}(f) = \mathcal{L}(f_g)$ , we have  $h_{I,[a,b]}(\mathcal{L}(g)) = \mathcal{L}(f)$  contained in  $\mathcal{T}_{(a,b)}$ , so that  $h_{I,[a,b]}(\mathcal{T}_{(0,1)}) \subseteq \mathcal{T}_{(a,b)}$ .

It remains to show that  $h_{[a,b],I}(\mathcal{T}_{(0,1)}) \supseteq \mathcal{T}_{(a,b)}$ . Let  $F \in \mathcal{T}_{(a,b)}$ , so that  $F = \mathcal{L}(f)$  for some  $f$  in  $C(I, I)$ , and  $\mathcal{L}(f) \subseteq (a, b)$ . It suffices to show that  $F = \mathcal{L}(g)$ , where  $g \in C([a, b], [a, b])$ . Now, since  $\mathcal{L}(f) \subseteq (a, b)$ , there exists  $\epsilon > 0$  so that  $\overline{B_\epsilon(\Lambda(f))} \subset (a, b)$  and since  $f(\Lambda(f)) = \Lambda(f)$ ,  $f(\overline{B_\epsilon(\Lambda(f))}) \subset \overline{B_\epsilon(\Lambda(f))}$ , too. Now, let  $x \in I$ . There exists  $N = N(x) \in \mathbb{N}$  so that  $f^n(x) \in \overline{B_\epsilon(\Lambda(f))}$  whenever  $n > N(x)$ . If we let  $y = f^{N+1}(x)$ , then  $\omega(y, g) = \omega(x, f)$ , where  $g$  is any extension of  $f|_{\overline{B_\epsilon(\Lambda(f))}}$  to all of  $[a, b]$ . In particular,  $\mathcal{L}(f) \subseteq \mathcal{L}(g)$ . It remains to show that we can take  $g$  so that  $\mathcal{L}(f) = \mathcal{L}(g)$ .

Set  $[\alpha, \beta] = \overline{\text{conv}}(\Lambda(f))$ , the closed convex hull of  $\Lambda(f)$ , and let  $y_1 \in (\alpha - \epsilon, \alpha)$  so that  $\gamma(y_1, f) \subseteq \overline{B_\epsilon(\Lambda(f))}$ . By [3, Corollary IV.10] this would actually imply that  $\gamma(y_1, f) \subseteq \overline{B_\epsilon(\Lambda(f))} \cap (y_1, \beta + \epsilon)$ . If no such  $y_1$  exists, set  $y_1 = \alpha$ . Let  $M = \max \gamma(y_1, f)$ . If  $M > \beta$ , take  $y_2 \in \gamma(y_1, f)$  so that  $\beta < y_2 < M$ . If  $M \leq \beta$ , take  $y_2 \in (\beta, \beta + \epsilon)$  so that  $\gamma(y_2, f) \subseteq \overline{B_\epsilon(\Lambda(f))} \cap (y_1, \beta + \epsilon)$ . Again, by [3, Corollary IV.10], this would imply that  $\gamma(y_2, f) \subseteq (y_1, y_2)$ . If no such  $y_2$  exists, set  $y_2 = \beta$ . We note that, by our choice of  $y_1$  and  $y_2$ ,  $\{\omega(x, f) : x \in \overline{B_\epsilon(\Lambda(f))} \cap [y_1, y_2]\} = \mathcal{L}(f)$ .

We now define  $g : [a, b] \rightarrow [a, b]$

$$g(x) = \begin{cases} f(y_1) & \text{if } x \in [a, y_1] \\ f(x) & \text{if } x \in [y_1, \alpha] \cup [\beta, y_2] \\ f(y_2) & \text{if } x \in [y_2, b] \end{cases}$$



and if  $x \in [\alpha, \beta]$ , then

$$g(x) = \begin{cases} y_1 & \text{whenever } f(x) \leq y_1 \\ f(x) & \text{whenever } y_1 \leq f(x) \leq y_2 \\ y_2 & \text{whenever } f(x) \geq y_2. \end{cases}$$

It remains to verify that  $\mathcal{L}(g) \subseteq \mathcal{L}(f)$ .

If  $x \in [a, y_1]$ , then  $\omega(x, g) = \omega(y_1, f) \in \mathcal{L}(f)$ , and if  $x \in [y_2, b]$ , then  $\omega(x, g) = \omega(y_2, f) \in \mathcal{L}(f)$ . Now, let  $x \in (y_1, y_2)$ , and consider  $\gamma(x, g)$ . If  $\gamma(x, g) \subseteq (y_1, y_2)$ , then  $\gamma(x, g) = \gamma(x, f)$ , so that  $\omega(x, g) = \omega(x, f) \in \mathcal{L}(f)$ . If  $\gamma(x, g) \cap \{y_1, y_2\} \neq \emptyset$ , we can take  $n \in \mathbb{N}$  minimal so that  $g^n(x) = y_i \in \{y_1, y_2\}$ . Then  $\omega(x, g) = \omega(y_i, f) \in \mathcal{L}(f)$ .  $\square$

As the next proposition shows, we cannot extend the conclusion of Theorem 3.11 to those elements of  $\mathcal{R}(\mathcal{L})$  found in the closed interval  $[a, b]$ .

**Proposition 3.12.** *Let  $[a, b] \subseteq [0, 1]$  so that  $0 < a < b < 1$ . There exists  $F \in \mathcal{R}(\mathcal{L})$  such that  $\omega \subseteq [a, b]$  for any  $\omega \in F$ , but  $F \notin \{\mathcal{L}(f) : f \in C([a, b], [a, b])\}$ .*

*Proof.* Let  $f \in C(I, I)$  so that  $f$  has a unique infinite and maximal  $\omega$ -limit set  $\omega_0$ , which is generated by a solenoidal system. It follows that  $\omega_0 = Q\dot{U}C$ , where  $Q$  is a Cantor set and  $C$  is a dense and countable set of points isolated in  $\omega_0$ . Now, suppose that  $a = \min \omega_0 \in C$ ,  $b = \max \omega_0 \in C$ , and  $\omega \subseteq [a, b]$  for all  $\omega$  in  $\mathcal{L}(f)$ . (The reader is referred to [10] for the construction of such a function  $f$ .) If  $x \in I$  for which  $\omega(x, f) = \omega_0$ , then  $\gamma(x, f) \cap [0, a] \neq \emptyset$  and  $\gamma(x, f) \cap [b, 1] \neq \emptyset$ , since each of the intervals  $[a, \min Q]$  and  $[\max Q, b]$  is wandering. Moreover,  $a$  and  $b$  are isolated in  $\Lambda(f)$ . We conclude that if  $F = \mathcal{L}(f)$ , then  $F \notin \{\mathcal{L}(g) : g \in C([a, b], [a, b])\}$ . In particular, if  $\omega_0 \in \mathcal{L}(g)$  for some  $g \in C([a, b], [a, b])$ , then as we saw earlier, the maximal  $\omega$ -limit set which contains  $\omega_0$  cannot be solenoidal. But if  $\omega_0$  is contained in the basic set  $B(M, g)$ , then  $a$  and  $b$  are no longer isolated points of  $\Lambda(g)$ , since  $B(M, g)$  is perfect.  $\square$

#### 4. The map $\omega : I \times C(I, I)$

This section concerns the map  $\omega : I \times C(I, I) \rightarrow \mathcal{K}$  which takes  $(x, f)$  in  $I \times C(I, I)$  to the  $\omega$ -limit set  $\omega(x, f)$ . Fundamental to much of the analysis is the characterization of  $\omega$ -limit sets for continuous self-maps of the interval developed in [1]. The first result is an elementary lemma which takes advantage of the density of the finite sets in  $\mathcal{K}$ .

**Lemma 4.1.**  *$\mathcal{K}$  is contained in the closure of  $\mathcal{R}(\omega)$ .*

*Proof.* Let  $\epsilon > 0$ . Any element  $F \in \mathcal{K}$  can be  $\epsilon$ -approximated by a finite set  $S$  in  $\mathcal{K}$  so that  $\mathcal{H}(F, S) < \epsilon$ . Moreover, there exists  $f$  in  $C(I, I)$  so that  $\omega(x, f) = S$ .  $\square$

We record several immediate corollaries of Lemma 4.1.

**Corollary 4.2.**  $\mathcal{R}(\omega)$  and  $\mathcal{K} \setminus \mathcal{R}(\omega)$  are dense in  $\mathcal{K}$ , so that  $\mathcal{R}(\omega) \subsetneq \overline{\mathcal{R}(\omega)}$  and  $\text{int}(\mathcal{R}(\omega)) = \emptyset$ .

*Proof.* From [1] it follows that

$$\mathcal{K} \setminus \{\omega(x, f) : x \in I, f \in C(I, I)\}$$

is dense in  $(\mathcal{K}, \mathcal{H})$ . Precisely, every  $K \in \mathcal{K}$  is approximable by finite sets. Fix  $K \in \mathcal{K}$  and  $\epsilon > 0$ . There exists  $F$  finite such that  $\mathcal{H}(K, F) < \frac{\epsilon}{2}$ . Replace one point of  $F$  with a suitably small interval around it and obtain a new compact set  $F'$  such that  $F' \notin \mathcal{R}(\omega)$  and  $\mathcal{H}(F, F') < \frac{\epsilon}{2}$ . Hence,  $\mathcal{H}(K, F') < \epsilon$ .  $\square$

Theorem 3.5 establishes that  $\mathcal{R}(\mathcal{L})$  is path-connected in  $\mathcal{K}^*$ , as any element of  $\mathcal{L}(f)$  in  $\mathcal{R}(\mathcal{L})$  is path-connected to  $\{\{\frac{1}{2}\}\}$ , also in  $\mathcal{R}(\mathcal{L})$ . If  $F \in \mathcal{R}(\omega)$ , then  $F \in \mathcal{L}(f)$  for some  $f$  in  $C(I, I)$ , so that  $F$  is, in fact, path connected to  $\{\frac{1}{2}\} \in \mathcal{R}(\omega)$ .

**Corollary 4.3.**  $\mathcal{R}(\omega)$  is path-connected in  $\mathcal{K}$ .

A main result of this section is the following theorem.

**Theorem 4.4.**  $\mathcal{R}(\omega)$  is the disjoint union of a dense  $G_\delta$  subset of  $\mathcal{K}$  and a first category  $F_\sigma$  subset of  $\mathcal{K}$ .

Theorem 4.4 is an immediate consequence of Propositions 4.5 and 4.6. Obviously, this result relies on the work found in [1]. The lack of a “clean” characterization of the elements of  $\mathcal{R}(\mathcal{L})$  seems a serious obstacle to the development of an analogous result for the range of  $\mathcal{L} : C(I, I) \rightarrow \mathcal{K}^*$ .

**Proposition 4.5.**  $\{F \in \mathcal{K} : F \text{ is nowhere dense}\}$  is a dense  $G_\delta$  subset of  $\mathcal{K}$ .

*Proof.* Let  $I_j$  be an enumeration of the open intervals in  $(0, 1)$  with rational end-points, and set  $\mathcal{K}_j = \{F \in \mathcal{K} : I_j \subset F\}$ . One verifies easily that  $\mathcal{K}_j$  is closed in  $\mathcal{K}$ .

Suppose now that  $F \in \mathcal{K}$  is not nowhere dense, so that for some  $a \leq b$  in  $[0, 1]$  we have  $[a, b] \subseteq F$ . There exists some  $I_j \subset [a, b]$ , so that  $I_j \subset F$  and  $F \in \mathcal{K}_j$ . In particular,  $\{F \in \mathcal{K} : F \text{ is nowhere dense}\} = \mathcal{K} \setminus \cup_{j=1}^\infty \mathcal{K}_j$  is a  $G_\delta$  subset of  $\mathcal{K}$ . That  $\{F \in \mathcal{K} : F \text{ is nowhere dense}\}$  is dense in  $\mathcal{K}$  follows from the observation that the finite sets are dense in  $\mathcal{K}$ .  $\square$

**Proposition 4.6.** *The set*

$$\{F \in \mathcal{K} : F \text{ is a finite union of nondegenerate closed intervals}\}$$

*is a first category  $F_\sigma$  subset of  $\mathcal{K}$ .*

*Proof.* We show that

$$F_{n,m} = \{F \in \mathcal{K} : F = \dot{\cup}_{i=1}^k I_i \text{ s.t. } k \leq n \text{ and } I_i = [a_i, b_i] \text{ with } b_i - a_i \geq \frac{1}{m} \text{ for all } i\}$$

is closed in  $\mathcal{K}$ . Let  $\{F_i\}_{i \in \mathbb{N}} \subseteq F_{n,m}$  so that  $F_i \rightarrow F$  in  $\mathcal{K}$ . We show that  $F \in F_{n,m}$ . Suppose, to the contrary, that there exist disjoint open intervals  $\{(a_i, b_i)\}_{i=1}^l$  with  $l \geq n$ , such that  $F \subset \cup_{i=1}^l (a_i, b_i)$  and  $F \cap (a_i, b_i) \neq \emptyset$  for all  $i$ . Since  $F_i \rightarrow F$  in  $\mathcal{K}$ , there is  $N$  in  $\mathbb{N}$  so that, whenever  $j > N$ ,  $F_j \subset \cup_{i=1}^l (a_i, b_i)$  and  $F_j \cap (a_i, b_i) \neq \emptyset$ ,  $1 \leq i \leq l$ . But this contradicts  $F_j$  having at most  $n$  components. Now, suppose that there exists an open interval  $(a, b)$  so that  $(a, b) \cap F$  is closed, non-empty, and  $b - a < \frac{1}{m}$ . Since  $F_i \rightarrow F$ , for sufficiently large  $j$ ,  $F_j \cap (a, b)$  also is both closed and non-empty. But this contradicts  $F_j$  having components of length at least  $\frac{1}{m}$ . Our conclusion follows from the observation that  $\cup_{n=1}^{\infty} \cup_{m=1}^{\infty} F_{n,m} = \{F \in \mathcal{K} : F \text{ is a finite union of nondegenerate closed intervals}\}$ .  $\square$

**Theorem 4.7.**  $\mathcal{R}(\omega)$  is a dense  $G_{\delta\sigma}$  subset of  $\mathcal{K}$ .

*Proof.* The theorem follows from Propositions 4.5 and 4.6, and Theorem 1.1, the characterization of  $\omega$ -limit sets found in [1].  $\square$

The following two corollaries are consequences of Theorem 3.7 and Theorem 3.9, respectively.

**Corollary 4.8.** Let  $[a, b] \subseteq [0, 1]$  and set  $\epsilon = \frac{b-a}{2}$ . There exists  $g$  in  $C(I, I)$  so that

$$\mathcal{R}(\omega : [a, b] \times \overline{B_\epsilon(g)} \rightarrow \mathcal{K}) = h_{I, [a, b]}(\mathcal{R}(\omega)).$$

**Corollary 4.9.** For every  $f$  in  $C(I, I)$  and any  $\epsilon > 0$  there exist  $g$  in  $B_\epsilon(f)$ ,  $0 < \delta < \epsilon$  and  $[a, b] \subseteq I$  so that  $\overline{B_\delta(g)} \subset B_\epsilon(f)$ ,  $b - a = 2\delta$ , and  $\mathcal{R}(\omega : [a, b] \times \overline{B_\delta(g)} \rightarrow \mathcal{K}) = h_{I, [a, b]}(\mathcal{R}(\omega))$ .

Another main result of the section is Theorem 4.10. While similar to Theorem 3.11, it is a bit stronger as we may consider all of the  $\omega$ -limit sets found in  $[a, b]$ , and not just those found in  $(a, b)$ .

**Theorem 4.10.** Let  $[a, b] \subseteq [0, 1]$ , and set

$$S_{[a, b]} = \{\omega(x, f) : \omega(x, f) \subseteq [a, b], x \in I, f \in C(I, I)\}.$$

Then  $\mathcal{R}(\omega) = h_{[a, b], I}(S_{[a, b]})$ .

*Proof.* We first show that  $\mathcal{R}(\omega) \subseteq h_{[a, b], I}(S_{[a, b]})$ . This is equivalent to showing that  $h_{I, [a, b]}(\mathcal{R}(\omega)) \subseteq S_{[a, b]}$ . Let  $\tilde{\omega} \in \mathcal{R}(\omega)$ ; say  $\tilde{\omega} = \omega(\tilde{x}, \tilde{f})$ , where  $(\tilde{x}, \tilde{f}) \in I \times C(I, I)$ . Then  $h_{I, [a, b]}(\tilde{\omega}) = \omega = \omega(h_{I, [a, b]}(\tilde{x}), h_{I, [a, b]} \circ \tilde{f} \circ h_{[a, b], I})$ , where  $h_{I, [a, b]}(\tilde{\omega}) = \omega \subseteq [a, b]$ ,  $h_{I, [a, b]}(\tilde{x}) \in [a, b] \subseteq I$ , and  $h_{I, [a, b]} \circ \tilde{f} \circ h_{[a, b], I} \in C([a, b], [a, b])$ . We now extend  $h_{I, [a, b]} \circ \tilde{f} \circ h_{[a, b], I}$  to  $f \in C(I, I)$  via Tietze extension theorem, so that

- (1)  $h_{I,[a,b]}(\tilde{\omega}) = \omega = \omega(h_{I,[a,b]}(\tilde{x}), f) \subseteq [a, b]$ ,
- (2)  $f \in C(I, I)$ .

It follows that  $h_{I,[a,b]}(\tilde{\omega}) \in S_{[a,b]}$ , so that

$$h_{I,[a,b]}(\mathcal{R}(\omega)) \subseteq S_{[a,b]}.$$

We now show that  $h_{[a,b],I}(S_{[a,b]}) \subseteq \mathcal{R}(\omega)$ .

Let  $\omega \in S_{[a,b]}$ . Then, by [1],  $\omega$  is either a finite union of nondegenerate closed intervals or a closed and nowhere dense set in  $[a, b]$ . Let  $h_{[a,b],I}(\omega) = \tilde{\omega}$ . Clearly,  $\tilde{\omega}$  is either a finite union of nondegenerate closed intervals or a closed and nowhere dense set in  $[0, 1]$ . Thus, again, by [1], there exists  $(\tilde{x}, \tilde{f}) \in I \times C(I, I)$  so that  $\tilde{\omega} = \omega(\tilde{x}, \tilde{f})$ , so that  $\tilde{\omega} \in \mathcal{R}(\omega)$ . Thus,  $h_{[a,b],I}(S_{[a,b]}) \subseteq \mathcal{R}(\omega)$ . Our conclusion follows.  $\square$

The main result of [4] shows that, for a fixed  $f$  in  $C(I, I)$ , the set  $\{\omega(x, f) : x \in I\}$  is closed in  $\mathcal{K}$ . The next result fixes, instead,  $x$  in  $[0, 1]$  and considers the set  $\{\omega(x, f) : f \in C(I, I)\}$ .

**Proposition 4.11.** *Let  $x \in [0, 1]$  with  $\mathcal{S}_x = \{\omega(x, f) : f \in C(I, I)\}$ . Then  $\mathcal{S}_x$  contains a dense and open subset of  $\mathcal{R}(\omega)$ .*

*Proof.* Let  $F \in \mathcal{R}(\omega)$  so that  $x \notin F$ , with  $f \in C(I, I)$  and  $y \in I$  such that  $\omega(y, f) = F$ , and  $\epsilon > 0$  such that  $x \notin \overline{B_\epsilon(\omega(y, f))}$ . Take  $f_1$  so that

- (1)  $f_1|_{\overline{B_\epsilon(\omega(y, f))}} = f|_{\overline{B_\epsilon(\omega(y, f))}}$ ,
- (2)  $f_1(x) = z \in \gamma(y, f) \cap B_\epsilon(\omega(y, f))$ ,

such that  $\gamma(z, f) \subseteq B_\epsilon(\omega(y, f))$ , and extend  $f_1$  defined on  $\overline{B_\epsilon(\omega(y, f))} \cup \{x\}$  to all of  $I$  via the Tietz extension theorem.

By  $\omega(x, f_1) = \omega(z, f_1)$ ,  $\gamma(z, f_1) = \gamma(z, f)$ , it follows that  $\omega(x, f_1) = \omega(z, f)$ . Since  $z \in \gamma(y, f)$ , it follows that  $\omega(z, f) = \omega(y, f)$ . Thus,  $\omega(x, f_1) = F \in \mathcal{S}_x$ . Let  $\mathcal{D}_x = \{F \in \mathcal{R}(\omega) : F \text{ is finite and } x \notin F\}$ . Then  $\mathcal{D}_x \subseteq \mathcal{S}_x$ , and since  $\mathcal{D}_x$  is dense in  $\mathcal{R}(\omega)$ ,  $\mathcal{S}_x$  is dense in  $\mathcal{R}(\omega)$ , too. Moreover, if  $F \in \mathcal{D}_x$ , then there is  $\epsilon > 0$  so that  $x \notin B_\epsilon(F)$ . Should  $F_1 \in \mathcal{R}(\omega)$  such that  $\mathcal{H}(F, F_1) < \epsilon$ , then  $x \notin F_1$ , and  $F_1 \in \mathcal{S}_x$ .  $\square$

For a fixed  $x$ ,  $\{\omega(x, f) : f \in C(I, I)\}$  is dense and open in  $\mathcal{K}$ . The next lemma describes the origin of the “holes” found in  $\mathcal{R}(\omega) \setminus \{\omega(x, f) : f \in C(I, I)\}$ .

**Lemma 4.12.** *Suppose  $F \in \mathcal{K}$  is nowhere dense, infinite and contains an isolated point. If  $x_0 \in F$ , then  $F \notin \{\omega(x_0, f) : f \in C(I, I)\}$ .*

*Proof.* Suppose, to the contrary, that there exists  $f$  in  $C(I, I)$  such that  $\omega(x, f) = F$ , with  $y \in F$  and  $\epsilon > 0$  so that  $F \cap B_\epsilon(y) = y$ . Since  $F$  is strongly invariant with respect to  $f$ , it follows that  $\gamma(x, f) \subseteq F$ , and since  $y \in F$ , there exists  $\{n_k\}_{k \in \mathbb{N}} \subseteq \mathbb{N}$  such that  $f^{n_k}(x) \rightarrow y$ . Moreover,  $y$  is isolated in  $F$ , so

we can just as well take  $\{n_k\} \subseteq \mathbb{N}$  such that  $f^{n_k}(x) = y$ . Now, if  $f^{n_1}(x) = y$  and  $f^{n_2}(x) = y$ , with  $0 < k = n_2 - n_1$ , then  $f^k(y) = y$ . We conclude that  $\omega(x, f) = \omega(y, f)$  is periodic, and this contradicts  $\omega(x, f) = F$ .  $\square$

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