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On Haar Systems for Groupoids

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Abstract. It is shown that a locally compact groupoid with open range map does not always admit a Haar system. It then is shown how to construct a Haar system if the stability groupoid and the quotient by the stability groupoid both admit one.

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1. Introduction

Topological groupoids occur naturally in encoding hidden symmetries like in fundamental groupoids or holonomy groupoids of foliations, see [7], for instance. In order to construct convolution algebras on groupoids [3,9], one needs continuous families of invariant measures, so called *Haar systems* [12], see also Section 2. These do not always exist. One known criterion is that a Haar system can only exist if the range map is open ([13, Corollary to Lemma 2], see also [15]).

A second criterion, which has been neglected in the literature, is the possibility of *failing support*, i.e., it is possible that, although the range map is open, the support condition of a Haar system cannot be satisfied, see Proposition 3.2. We conjecture, however, that there should always be a Haar system for a locally compact groupoid with open range map, if the groupoid is second countable.

We show how to construct Haar systems if the stability groupoid and its quotient both admit one.

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2. Locally compact groupoids

Definition 2.1. By a bundle of groups we understand a continuous map π : $G \to X$ between locally compact Hausdorff spaces together with a group structure on each fibre $G_x = \pi^{-1}(x), x \in X$ such that the following maps are

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continuous:

$$\begin{split} \varepsilon: X &\to G \quad \text{identity,} \\ m: G^{(2)} \to G \quad \text{multiplication,} \\ \iota: G &\to G \quad \text{inverse} \quad , \end{split}$$

where $G^{(2)}$ is the set of all $(x, y) \in G \times G$ with $\pi(x) = \pi(y)$.

Note that this implies that ε is a homeomorphism onto the image, so X carries the subspace topology but also X carries the quotient topology induced by the surjective map π . In all, the topology on X is determined by the one on G.

Definition 2.2. Each fibre G_x , being a locally compact group, carries a Haar measure which is unique up to scaling. A *coherent system* of Haar measures is a family $(\mu_x)_{x \in X}$, where μ_x is a Haar measure on G_x such that for each $\phi \in C_c(G)$ the map

$$x \mapsto \int_{G_x} \phi \, d\mu_x$$

is continuous.

Proposition 2.3. Let $\pi : G \to X$ be a bundle of groups over a paracompact space X. There exists a coherent system of Haar measures μ_x on G if and only if the map π is open.

Proof. This is [10, Lemma 1.3].

Definition 2.4. Let X be a set. By a *groupoid* over X we mean a category with object class X (so it is a small category) in which each arrow is an isomorphism. We write G for the set of arrows and we use the following notation

$r,s:G \to X$	range and source maps,
$\varepsilon:X\to G$	identity,
$G^{(2)} \subset G \times G$	set of composable pairs,
$m: G^{(2)} \to G$	composition,
$\iota:G\to G$	inverse.

Definition 2.5. A topological groupoid is a groupoid G over X together with topologies on G and X such that the structure maps $r, s, \varepsilon, m, \iota$ are continuous. Here $G \times G$ carries the product topology and $G^{(2)} \subset G \times G$ the subset topology. Note that if X is Hausdorff, then $G^{(2)} = \{(\alpha, \beta) \in G \times G : r(\beta) = s(\alpha)\}$ is a closed subset of $G \times G$.

A locally compact groupoid is a topological groupoid such that G and X are locally compact Hausdorff spaces.

From now on G is assumed to be a locally compact groupoid. We use the notation

$$G_x = \{g \in G : s(g) = x\},\$$

$$G^y = \{g \in G : r(g) = y\},\$$

$$G^y_x = G_x \cap G^y.$$

As X is Hausdorff, all three sets are closed in G.

Note that a bundle of groups is a special case of a groupoid G with $G_x^y = \emptyset$ if $x \neq y$.

Definition 2.6. For a groupoid G the *stability groupoid* is defined to be the subset

$$G' = \{ g \in G : r(g) = s(g) \}.$$

If G is a topological groupoid, then G' is a closed subgroupoid.

Definition 2.7. On a groupoid G we install an equivalence relation

$$g \sim h \quad \Leftrightarrow \quad r(g) = r(h) \text{ and } s(g) = s(h).$$

we write [g] for the equivalence class, i.e., $[g] = G_{s(g)}^{r(g)}$.

Now assume that $(\mu_x^x)_{x \in X}$ is a coherent family of measures on the bundle of groups $G' = \{g \in G : r(g) = s(g)\}$. We then get invariant measures $\mu_{[g]}$ on the classes [g] by setting

$$\int_{[g]} \phi(x) \, d\mu_{[g]}(x) = \int_{G_{s(g)}^{s(g)}} \phi(gx) \, d\mu_{s(g)}^{s(g)}(x).$$

The invariance of the μ_x^x yields the well-definedness of the $\mu_{[g]}$. The uniqueness of a Haar measure implies that $\mu_{[g]}$ is, up to scaling, the unique Radon measure on [g] being right-invariant under $G_{s(g)}^{s(g)}$ or left-invariant under $G_{r(g)}^{r(g)}$.

In the sequel, we shall identify a Radon measure with its positive linear functional, so we write $\mu_{[q]}(\phi)$ for the above integral.

Definition 2.8. We shall need the notion of a topological right-action of a topological groupoid H on a topological space Z. This is given by the following data: first there is a continuous surjection $\rho: Z \to X$, where X is the base set of H. We define

$$Z * H = \{(z, h) : \rho(z) = r(h)\}.$$

This is a closed subset of $Z \times H$ and we consider it equipped with the corresponding topology. Next the action is given by a map

$$Z * H \to Z,$$

(z, h) \mapsto zh,

such that $\rho(zh) = s(h)$ and $z \cdot 1 = z$ as well as z(hh') = (zh)h' holds for all $(z,h), (z,hh') \in Z * H$.

Note that the action defines an equivalence relation on Z given by $z \sim zh$ for $h \in H$. We naturally equip Z/H with the quotient topology.

Lemma 2.9. Assume the locally compact groupoid H acts on a locally compact space Z and that H has open range map. Then the projection $Z \to Z/H$ is open.

Proof. This is [6, Lemma 2.1]. However, in that paper the assertion was given under a stronger definition of H-actions then the one we use, as it was assumed that the map $\rho: Z \to X$ also be open. Lemma 2.1 and its proof in [6], however, are valid under our weaker assumptions. For the convenience of the reader we shall show this by reproducing the proof here: Let $V \subset Z$ be open, in order to show that its image in Z/H is open, it suffices to show that the union of orbits $VH = \{vh: v \in V, (v, h) \in Z * H\}$ is open in Z. So it suffices to show that any net $z_i \to vh$ with $v \in V$ and $h \in H$ eventually is in VH. But $\rho(z_i)$ converges to $\rho(vh) = s(h)$. As the range map of H is open, so is the source map s, hence the set s(H) is open and we can find a net h_i in H on the same index set, such that $\rho(z_i) = s(h_i)$ for all $i \ge i_0$ for some index i_0 . Further, the same applies to open neighborhoods of h, so we can choose the net so that $h_i \to h$. Then $z_i h_i^{-1}$ converges to v and thus is eventually in V and $z_i = z_i h_i^{-1} h_i$ is eventually in VH.

Definition 2.10. An action of a groupoid H on a space Z is called *free* if zh = z implies that $h = 1_{s(g)}$ and it is called *proper*, if the map $Z * H \to Z \times Z$, $(z, h) \mapsto (zh, z)$ is proper.

For any groupoid G the action of G' on G is easily seen to be free and proper.

Lemma 2.11. Let G be a locally compact groupoid over a paracompact space X and let $(\mu_x^x)_{x \in X}$ be a coherent system of Haar measures on the groups G_x^x , $x \in X$. Then for every $\phi \in C_c(G)$ the function

$$\phi: g \mapsto \mu_{[g]}(\phi)$$

is continuous.

Proof. Since the G' action is free and proper, this is immediate from [5, Lemma 2.9].

3. Haar systems

Definition 3.1. A *Haar system* on the locally compact groupoid G is a family $(\mu^x)_{x \in X}$ of Radon measures on G with

- (a) $\operatorname{supp}(\mu^x) = G^x$, (b) $\int_G \phi(\alpha g) d\mu^y(g) = \int_G \phi(g) d\mu^x$ for every $\phi \in C_c(G)$ and every $\alpha \in G_y^x$,
- (c) $x \mapsto \int_G \phi(g) d\mu^x(g)$ is continuous on X for every $\phi \in C_c(G)$.

If a locally compact groupoid G admits a Haar system, then the range map, and so the source map, too, is open, see [13, Corollary to Lemma 2], see also [15].

The question for the converse assertion, asked in [15], is answered in the negative by the following proposition.

Proposition 3.2. There exists a locally compact, even compact, groupoid G, whose range map is open, but no Haar system exists on G.

Proof. There are locally compact, even compact, Hausdorff spaces which cannot be the support of any Radon measure. Here are two examples:

- Let X be the unit ball of a Hilbert space of uncountable dimension and equip X with the weak topology. By the Banach-Alaoglu-Theorem, X is a compact Hausdorff space. By [1, Corollary 7.14.59 of volume 2], the set X cannot be the support of any Radon measure.
- (Williams) Let Y be an uncountable set with the discrete topology and let $X = Y \cup \{\infty\}$ be its one-point compactification. Then X cannot be the support of any Radon measure. To see this, let m be a Radon measure on X, then $m(X) < \infty$, as X is compact. Further, $m(Y) = \sum_{y \in Y} m(\{y\})$, as m is regular and the only compact subsets of Y are the finite sets. As $m(Y) < \infty$, the set M of all $y \in Y$ with $m(\{y\}) > 0$ is countable, therefore $M \neq Y$ and m is supported in $M \cup \{\infty\}$.

Let now X be any locally compact Hausdorff space which is not the support of a Radon measure. Let $G = X \times X$ with the product topology and make g a groupoid by setting (x, y)(y, z) = (x, z) and r(x, y) = x as well as s(x, y) = y. Then the source map is a homeomorphism between G^x and X, so G^x cannot be the support of any Radon measure, hence no Haar system exists. \Box

Conjecture 3.3. Every second countable, locally compact groupoid with open range map admits a Haar system.

Definition 3.4. Let G be a groupoid over X. We write $E(G) \subset X \times X$ for the image of the map $g \mapsto (s(g), r(g))$. Then E(G) is an equivalence relation on X.

We say that a groupoid G is a *principal groupoid* if $G_x^x = \{1_x\}$ for every $x \in X$. This means that the groupoid is completely described by its equivalence relation. Note, though, that for topological groupoids the topology on G generally differs from the one on E(G) as a subset of $X \times X$.

Lemma 3.5. Let G be a groupoid over a set X. Define an equivalence relation on G by

$$g \sim h \quad \Leftrightarrow \quad r(g) = r(h) \text{ and } s(g) = s(h).$$

Then the set $\overline{G} = G/\sim$ becomes a groupoid, indeed a principal groupoid, by setting [g][h] = [gh] whenever g and h are composable.

Proof. This is easily checked.

Theorem 3.6. Let G be a locally compact groupoid over a paracompact space X. Suppose that the stability groupoid G' has open range map.

- (a) The groupoid \overline{G} , when equipped with the quotient topology, is a locally compact groupoid. The quotient map $G \to \overline{G}$ is open.
- (b) If the range map of G is open, then so is the range map of \overline{G} .
- (c) If \overline{G} admits a Haar system, then G admits a Haar system.

Proof. Ad (a): By Proposition 2.3, the groupoid G' admits a coherent system of Haar measures $(\mu_x^x)_{x \in X}$. Let $g_0 \in G$ and let $\phi \in C_c^+(G)$ such that $\phi(g_0) > 0$. Let

$$\overline{\phi}: g \mapsto \int_{G^{r(g)}_{s(g)}} \phi(gh) \, d\mu^{r(g)}_{s(g)}(h).$$

By Lemma 2.11 the map $\overline{\phi}$ is continuous. It factors over \overline{G} , hence defines a continuous map of compact support on \overline{G} . The set $U = \{x \in \overline{G} : \overline{\phi}(x) > 0\}$ is an open neighborhood of $[g_0]$, so $\operatorname{supp}(\overline{\phi})$ is a compact neighborhood of $[g_0]$. Therefore \overline{G} is locally compact.

If $[g] \neq [h]$, then we can find $\phi, \psi \in C_c^+(G)$ such that $\overline{\phi}$ and $\overline{\psi}$ have disjoint supports and $\phi(g), \psi(h) > 0$. Considering the continuous function $\overline{\phi} - \overline{\psi}$ on \overline{G} , one sees that [h] and [g] have disjoint neighborhoods, so \overline{G} is a Hausdorff space. Together we infer that \overline{G} is a locally compact groupoid.

The quotient map $p: G \to \overline{G}$ is open by Lemma 2.9.

Ad (b): As the range map of \overline{G} is open and factors over the range map of \overline{G} , the range map of \overline{G} is open as well.

Ad (c): If (m^x) is a Haar system for \overline{G} , then

$$\phi\mapsto \int_{\overline{G}}\overline{\phi}(g)\,dm^x(g)$$

defines a Haar system on G.

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