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Optimal transportation networks and stations

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We study a model of optimal transportation networks that includes the cost of constructing stations. The model is expressed in terms of the Federer–Fleming language of currents.

1. Introduction

Various authors consider the Monge–Kantorovich problem of irrigating a signed measure; see, e.g., Ambrosio [1] for an overview. Given $\mu \triangleq \mu^+ - \mu^-$ with $\mu^+(\mathbb{R}^m) = \mu^-(\mathbb{R}^m) < \infty$ to be irrigated, one way to formulate the problem is to find a transport plan π that attains

$$\min\left\{\int c(x, y) \,\mathrm{d}\pi(x, y) \,\middle|\, \pi_1 = \mu^-, \ \pi_2 = \mu^+\right\}. \tag{1.1}$$

Here *c* is a given lower semicontinuous cost function, and π_i are the marginals of π . In the typical case $c(x, y) = ||x - y||^p$, $p \ge 1$, and the *p*th root of the minimum in (1.1) is then called the *p*-Wasserstein distance $W_p(\mu^+, \mu^-)$ between μ^+ and μ^- .

Brancolini and Buttazzo [6], Buttazzo and Stepanov [8], and Buttazzo et al. [7], among other works, consider a variant of the problem with two different media. The object is then to find a onedimensional network or track Σ that attains (1.1) when the cost *c* of travelling between *x* and *y* is defined in such a way that it is cheaper to travel on Σ than outside it.

Another variant of the problem is considered by Bernot et al. [5], and Xia [17, 18, 19], among others. Although employing a single medium, this version also attempts to include the cost of building the transportation network by considering a target functional that attempts to group together the paths taken by mass travelling from μ^+ to μ^- , forming a rectifiable network. In the language of Federer–Fleming currents, this can be formulated as finding a current *T* of optimal weighted area $\mathbb{M}^{\alpha}(T)$ ($\alpha \in [0, 1)$) such that $\partial T = \mu$.

Paolini and Stepanov [14] also study a variant of the two-media problem in the language of currents: that of minimising the functional

$$(W, R) \mapsto A\mathbb{M}^{\alpha}(W) + B\mathbb{M}^{\beta}(R) + H(\mathbb{M}^{\delta}(R)) \quad \text{with} \quad \partial(W+R) = \mu.$$
(1.2)

The first term of the functional describes the cost of the portion of paths that are to be travelled by "own means", the second term describes the cost of travelling the network modelled by the real rectifiable current R, and the last term describes the cost of constructing this network.

In application to construction of (small scale) urban transportation networks, none of these models is yet entirely realistic. One apparent flaw, which we intend to remedy in this paper, is that they do not take into account the cost of constructing stations or stops, which are nicely modelled

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by ∂R in the language of currents. Indeed, ∂R may have infinite mass, or even be unrectifiable, the corresponding measure being absolutely continuous with respect to the Lebesgue measure. Traffic may enter the network from anywhere. The next examples demonstrate these problems.

EXAMPLE 1.1 Let $x_1 = 0 < x_2 < \cdots < x_{\infty} = 1$, $x_i \nearrow 1$. Set $\mu^- \triangleq \delta_{x_1} + (2/3) \sum_{i=1}^{\infty} 2^{-i} \delta_{x_{2i+1}}$, and $\mu^+ \triangleq \sum_{i=1}^{\infty} 2^{-i} \delta_{x_{2i}} + (2/3) \delta_{x_{\infty}}$. Then $\mu^+(\mathbb{R}) = \mu^-(\mathbb{R}) = 1 + 2/3 < \infty$, and the optimal current connecting μ^+ with μ^- is $T = \sum_{i=1}^{\infty} [\phi_i [x_{2i-1}, x_{2i}]] + (\phi_i - 2^{-i}) [x_{2i}, x_{2i+1}]]$, where $\phi_i \triangleq 1 - (1/3) \sum_{j=1}^{i-1} 2^{-j}$. This is because some mass must be transported from x_1 to x_{∞} , and Tmust be supported in the convex hull of the support of μ . In the model (1.2), T splits into W and Rby a parameter-dependent threshold on the density of T [14, Theorem 10.4], which alternates here above and below $2/3 = \lim_{i\to\infty} \phi_i$, with $\phi_i - 2^{-i} < 2/3 < \phi_i$. Therefore, a suitable choice of parameters ensures $R = \sum_{i=1}^{\infty} \phi_i [x_{2i-1}, x_{2i}]$. But then $\mathbb{M}(\partial R) = 2 \sum_{i=1}^{\infty} \phi_i = \infty$.

EXAMPLE 1.2 Let $\mu \triangleq \operatorname{id}(\mathcal{H}^1 [-1, 1] \times \{0\})$ in \mathbb{R}^2 . Then the corresponding optimal current must be $T \triangleq [[(-1, 0), (1, 0)]] \cup \theta$, where $\theta(t) = \int_{-1}^t -s \, ds = (1 - t^2)/2$. As above, $R = T \cup \{\theta \ge \alpha\}$ for some $\alpha \ge 0$. If $\alpha < 1/2$, then for $\tau \triangleq \sqrt{1 - 2\alpha}$, $\partial R(\omega) = \int_{-\tau}^{\tau} \omega'(t)\theta(t) \, dt = \alpha[\omega(\tau) - \omega(-\tau)] + \int_{-\tau}^{\tau} \omega(s) s \, ds$, which is unrectifiable, not being a countable sum of Dirac masses.

Our task in this paper is thus to add a cost for ∂R , and to study the properties that follow for R.

The rest of this paper is laid out as follows. First in Section 2, we present some background information on currents and transportation problems. Then, in Section 3, we study notions of connectedness of currents. This section forms the main part of the paper, and allows us to work in a rather abstract and even discrete manner in the following Section 4. There we introduce our cost functional in a general form and study the properties of optimal *R* that follow under some abstract assumptions. In the final Section 5 we provide a more detailed analysis of the problem when the cost functional has a specific form employing weighted areas \mathbb{M}^{α} . In Appendix A we also consider connectedness in a special case related to functions of bounded variation, and previous notions of indecomposability for sets of finite perimeter.

2. Preliminaries

2.1 Basics on currents

Following Federer [11] or Morgan [13], a *k*-dimensional *current* $T \in \mathcal{D}_k(\mathbb{R}^m)$ is defined as a linear functional on *k*-dimensional differential forms in \mathbb{R}^m . When k > 1, the *boundary* is the k - 1-dimensional current defined by $\partial T(\omega) \triangleq T(d\omega)$. The *support* is the smallest closed set supp T such that $T(\omega) = 0$ whenever supp $\omega \cap$ supp T = 0. The *mass* is defined as $\mathbb{M}(T) \triangleq \sup\{T(\omega) \mid \|\omega\|_{\infty} \leq 1\}$. T is *representable by integration* if $T(\omega) = \tau_T \wedge \mu_T \triangleq \int \langle \omega, \tau_T \rangle d\mu_T$ for some measure μ_T and a unit vector field τ_T . Such a representation exists when $\mathbb{M}(T) < \infty$.

When θ is a C^{∞} function, we define $(T \sqcup \theta)(\omega) = T(\theta \land \omega)$. When *T* is representable by integration, this may be extended to other Borel functions. In particular, for the indicator function χ_A of a Borel set *A*, we set $(T \sqcup A)(\omega) = T(\chi_A \land \omega) = \int_A \langle \omega, \tau_T \rangle d\mu_T$. *T* is a *normal current* if the support is compact and $\mathbb{M}(T) + \mathbb{M}(\partial T) < \infty$. If we define the *flat*

T is a *normal current* if the support is compact and $\mathbb{M}(T) + \mathbb{M}(\partial T) < \infty$. If we define the *flat norm* $\mathbb{F}(T) \triangleq \inf{\mathbb{M}(T - \partial Q) + \mathbb{M}(Q) | Q \in \mathcal{D}_{k+1}(\mathbb{R}^m)}$, then the *flat chains* are the closure of the space of normal currents in this norm.

T is said to be *real rectifiable* if $\mu_T = \theta \mathcal{H}^k \llcorner \Sigma$ for a Borel map θ , a rectifiable set Σ , i.e., a countable union of images of Lipschitz maps, and τ_T a tangent vector field of Σ . When τ_T is

implicit, we denote $T = [\![\Sigma]\!] \sqcup \theta$. If Σ is a finite union of k-dimensional simplices, and θ is constant on each simplex, then T is a *polyhedral current*.

If $\gamma : [0,1] \to \mathbb{R}^m$ is a Lipschitz curve, we define the one-dimensional current $[\![\gamma]\!]$ by $[\![\gamma]\!](\omega) \triangleq \int_0^1 \langle \gamma'(t), \omega(\gamma(t)) \rangle dt$. The result is independent of the parametrisation. We also let $[\![x, y]\!] \triangleq [\![t \mapsto x + t(y - x)]\!]$ denote the current corresponding to the straight line segment from x to $y (\partial[\![x, y]\!] = \delta_y - \delta_x)$.

When S is a 0-dimensional current with finite mass, hence a signed measure, we denote by S^+ and S^- the positive and negative parts of S (as a measure).

2.2 Subcurrents

Following Paolini and Stepanov [14], we say that S is a *subcurrent* of T, denoted $S \leq T$, if

$$\mathbb{M}(T-S) + \mathbb{M}(S) \leqslant \mathbb{M}(T).$$
(2.1)

When *T* is representable by integration as $T = \tau_T \wedge \mu_T$, and $S \leq T$, there is according to [14, Lemma 3.7] a Borel function $\sigma : \mathbb{R}^m \to [0, 1]$ such that $S = T \llcorner \sigma = \tau_T \wedge \sigma \mu_T$.

The current *C* is a *cycle* if $\partial C = 0$. *T* is said to be *acyclic* if $C \leq T$ being a cycle implies C = 0. A *circuit* of *T* is a pair of distinct subcurrents $C_1, C_2 \leq T$ such that $C_1 - C_2$ is a cycle, i.e., $\partial(C_1 - C_2) = 0$. *T* containing no circuit obviously implies acyclicity.

2.3 Transport measures

Let $\gamma_1, \gamma_2 : [0, 1] \to \mathbb{R}^m$ be Lipschitz curves. We equip them with the distance

$$d_{\bar{\Gamma}}(\gamma_1, \gamma_2) = \inf\{\max_{t \in [0, 1]} \|\hat{\gamma}_1(t) - \hat{\gamma}_2(t)\| \mid \hat{\gamma}_i \text{ is a parametrisation of } \gamma_i\},\$$

where " $\hat{\gamma}$ is a parametrisation of γ " means that $\hat{\gamma}$ is a Lipschitz curve satisfying $\hat{\gamma} = \gamma \circ \psi$ for some continuous surjective non-decreasing map $\psi : [0, 1] \rightarrow [0, 1]$. We often identify curves with the corresponding parametrisation equivalence class, and denote the space of the latter by $\bar{\Gamma}$. Then $d_{\bar{\Gamma}}$ forms a metric on $\bar{\Gamma}$.

We now recall from [14, Theorem 6.3] that an acyclic 1-dimensional normal current T can be represented by a transport measure, in the form

$$T(\omega) = \llbracket \eta \rrbracket(\omega) \triangleq \int \llbracket \gamma \rrbracket(\omega) \, \mathrm{d}\eta(\gamma).$$
(2.2)

Here η is a Borel measure over $\overline{\Gamma}$ such that $\eta_0 = (\partial T)^-$, $\eta_1 = (\partial T)^+$, and $\eta_i(D) \triangleq \eta\{\gamma \mid \gamma(i) \in D\} = (p_i)_{\#}\eta(D)$, $p_i(\gamma) \triangleq \gamma(i)$ for Borel sets D. In fact, we may take the γ to be a.e. arcs, i.e., non-self-crossing.

We then have $\mu_T(D) = \int \mathbb{M}(\llbracket \gamma \rrbracket \Box D) d\eta(\gamma)$ and $T \sqcup D(\omega) = \int \llbracket \gamma \rrbracket \Box D(\omega) d\eta(\gamma)$ for Borel sets *D*. Also every restriction of the transport integral on a Borel set Γ of (equivalence classes of) curves, forms a subcurrent $\omega \mapsto \int_{\Gamma} \llbracket \gamma \rrbracket (\omega) d\eta(\gamma)$ of *R*.

We recall that the *transiting mass function* is defined as $\alpha_{\eta}(x) \triangleq \eta(\{\gamma \mid x \in \text{img } \gamma\})$, and that $\theta = \alpha_{\eta} \mathcal{H}^1$ -a.e. whenever $T = [\![\eta]\!] = [\![\Sigma]\!]_{\sqcup} \theta$ is normal real rectifiable and acyclic [14, Lemmas 7.1 & 7.2].

We will occasionally be stopping curves upon entrance or leaving a closed set, along the theme of the next lemma.

LEMMA 2.1 Let *D* be a closed set, and suppose $\overline{\Gamma}$ is equipped with a σ -finite measure. Then there exists an almost everywhere defined Borel measurable extension to $\overline{\Gamma}$ of the map $v : \gamma \mapsto \gamma \lfloor [0, \inf\{t \ge 0 \mid \gamma(t) \in D\}]$, when for $a \le b$ and a Lipschitz curve γ , we define

 $\gamma \llcorner [a, b] : t \in [0, 1] \mapsto \gamma(\max\{a, \min\{t, b\}\}).$

Proof. We first consider the measurability of v on individual curves (instead of equivalence classes), with metric $d(\gamma_1, \gamma_2) \triangleq \max_{t \in [0,1]} \|\gamma_1(t) - \gamma_2(t)\|$. We define the entrance time $\tau(\gamma) = \inf\{t \ge 0 \mid \gamma(t) \in D\}$, the helper function $f(\gamma, t)(s) \triangleq \gamma(\min\{s, t\})$, and the stopped path $v(\gamma) \triangleq f(\gamma, \tau(\gamma))$. The entrance time τ is upper-semicontinuous and hence measurable: If $\max_{t \in [0,1]} \|\gamma_k(t) - \gamma(t)\| \to 0$, then (for a subsequence) $D \ni \gamma_k(\tau(\gamma_k)) \to \gamma(\lim_k \tau(\gamma_k))$. Since D is closed, $\gamma(\lim_k \tau(\gamma_k)) \in D$, so $\lim_k \tau(\gamma_k) \ge \tau(\gamma)$. The transformation v is therefore measurable as a function on individual Lipschitz curves. Since f is a Carathéodory function, being continuous in each variable separately with the other fixed, and the space of Lipschitz curves is a subset of the complete separable space of continuous functions, the transformation v is thus measurable as a function on individual Lipschitz curves (see, e.g., [4, Lemma 8.2.3]).

Finally, we extend v to equivalence classes as $g \circ v \circ h$, where $g : \gamma \mapsto \overline{\gamma}$ maps γ to the corresponding equivalence class $\overline{\gamma}$, and h is a selection of g^{-1} . The function g is continuous, hence measurable. We want h to be measurable as well. Towards that end, note that the graph of g is measurable by the continuity of g. Also, the set of Lipschitz paths is a Borel measurable subset of the complete separable space of continuous functions (every subset of curves with Lipschitz factor bounded by a given constant being closed). Hence, by the Neumann–Aumann measurable selection theorem (see, e.g., [12, 9]), there is a measurable function h such that $h(\overline{\gamma}) \in g^{-1}(\overline{\gamma})$ a.e. Therefore $g \circ v \circ h$ is measurable.

3. Notions of connectedness of currents

3.1 Intersections and unions of currents

DEFINITION 3.1 Given two finite-mass currents *S* and *T*, we define the intersection $S \wedge T$ as the greatest current *R* (in the subcurrent order) such that $R \leq S$, *T*. Likewise, when $S, T \leq S + T$, the union $S \vee T$ is defined to be the smallest current *R* such that $S, T \leq R$.

LEMMA 3.1 $S \wedge T$ and $S \vee T$ are well-defined. Furthermore, $S \vee T = S + T - S \wedge T$ when defined.

Proof. Since the currents are assumed to have finite mass, $S = \tau_S \wedge \mu_S$ and $T = \tau_T \wedge \mu_T$ can be represented by integration. Consequently, any current R such that $R \leq S$, T has $R = \tau_S \wedge \sigma_S \mu_S = \tau_T \wedge \sigma_T \mu_T$ for some Borel maps $\sigma_S, \sigma_T : \mathbb{R}^m \to [0, 1]$. This says that $R \leq \hat{R} \triangleq \tau_S \wedge [(\mu_S \wedge \mu_T) \sqcup D]$, where $D \triangleq \{x \in \mathbb{R}^m \mid \tau_S(x) = \tau_T(x)\}$. We must then have $S \wedge T = \hat{R}$, which means that it is well-defined.

As for $S \lor T$, suppose $S, T \leq R \leq S + T$. Then

$$S + T - R \leqslant S, T, \tag{3.1}$$

as follows from applying the definition of subcurrents: Combining $\mathbb{M}(R) + \mathbb{M}(R - (S + T)) \leq \mathbb{M}(S+T)$ and $\mathbb{M}(R-T) + \mathbb{M}(T) \leq \mathbb{M}(R)$ gives $\mathbb{M}(R-T) + \mathbb{M}(R-(S+T)) \leq \mathbb{M}(S+T) - \mathbb{M}(T) \leq \mathbb{M}(S)$, which is just $S + T - R \leq S$. The proof for *T* is analogous. The minimal current *R* for which (3.1) can hold is given by $S + T - R = S \wedge T$.

REMARK 3.1 If $S_i = \tau_i \wedge \sigma_i \mu_T$, $\sigma_i \ge 0$, i = 1, 2, then $S_1 \wedge S_2 = \tau_T \wedge \min\{\sigma_1, \sigma_2\}\mu_T$, and $S_1 \vee S_2 = \tau_T \wedge \max\{\sigma_1, \sigma_2\}\mu_T$.

If S_3 has a similar expression, one easily observes that also $(S_1 \vee S_2) \wedge S_3 = (S_1 \wedge S_3) \vee (S_2 \wedge S_3)$ and $(S_1 \wedge S_2) \wedge S_3 = (S_1 \wedge S_3) \wedge (S_2 \wedge S_3)$. In particular, $(S_1 \vee S_2) \sqcup V = (S_1 \sqcup V) \vee (S_2 \sqcup V)$ and $(S_1 \wedge S_2) \sqcup V = (S_2 \sqcup V) \wedge (S_2 \sqcup V)$ for a Borel set V.

LEMMA 3.2 Suppose $S_1, S_2 \leq T$. Then $T = S_1 \vee S_2 + (T - S_1) \wedge (T - S_2)$.

Proof. If $X \leq T$, then $S_1, S_2 \leq X$ if and only if $T - X \leq T - S_1, T - S_2$ by the definition (2.1) of a subcurrent. Thus, taking $X = S_1 \vee S_2$, we find $T - S_1 \vee S_2 \leq (T - S_1) \wedge (T - S_2)$. Likewise, taking $X' \triangleq T - (T - S_1) \wedge (T - S_2)$, we find $S_1 \vee S_2 \leq T - (T - S_1) \wedge (T - S_2)$. We thus have $T - X \leq T - X'$ and $X \leq X'$. As also $X, X' \leq T$, we find $\mathbb{M}(X - X') = 0$ or X = X' by application of the definition (2.1).

LEMMA 3.3 Suppose S_1 , S_2 and T are finite mass currents, and that $S_1 \vee S_2$ is defined. Then $T \wedge (S_1 + S_2) \leq T \wedge S_1 + T \wedge S_2$. If $(T \wedge S_1) \wedge (T \wedge S_2) = 0$, then equality holds. In particular, if $S_1 \wedge T = 0$, then $T \wedge (S_1 + S_2) = T \wedge S_2$.

Proof. Since $S \triangleq S_1 \lor S_2$ is defined, we may express $S_i = S \llcorner \sigma_i$, where $\sigma_i : \mathbb{R}^m \to [0, 1]$ are Borel maps. We may further assume the similar expression $T = S \llcorner \sigma_T$, possibly after redefining Tas $T \land (S_1 + S_2)$, the remainder not playing a role since $T \land S_i = T \land S_i \land (S_1 + S_2)$. Therefore $T \land (S_1 + S_2) = S \llcorner \min\{\sigma_T, \sigma_1 + \sigma_2\} \leq S \llcorner (\min\{\sigma_T, \sigma_1\} + \min\{\sigma_T, \sigma_2\}) = T \land S_1 + T \land S_2$.

Now, if $T \wedge S_1 = 0$, clearly $T \wedge (S_1 + S_2) \leq T \wedge S_2$ from the first part. For the other direction, recall that $S_1 \vee S_2$ is defined when $S_1, S_2 \leq S_1 + S_2$. Therefore, if $X \leq S_2, T$, then $X \leq S_1 + S_2, T$. In particular, with $X \triangleq T \wedge S_2$, we find $T \wedge S_2 \leq T \wedge (S_1 + S_2)$.

Finally, rewriting $T \land (S_1 + S_2) = T \land (S_1 \lor S_2 + S_1 \land S_2)$ and employing the assumption $0 = (T \land S_1) \land (T \land S_2) = T \land (S_1 \land S_2)$ in the result of the previous paragraph, we find $T \land (S_1 + S_2) = T \land (S_1 \lor S_2) = (T \land S_1) \lor (T \land S_2) = (T \land S_1) + (T \land S_2) - (T \land S_1) \land (T \land S_2) = (T \land S_1) + (T \land S_2).$

3.2 Connectedness by splitting

DEFINITION 3.2 Suppose T is a current with finite mass, and V is a Borel set, assumed to be \mathbb{R}^m if left unspecified.

- (i) The subcurrents $A, B \leq T$ split T if A + B = T and $A \wedge B = 0$.
- (ii) The currents A, B primitive-decompose a normal current S in V if they split S, are normal, and $\partial A_{\perp}V$, $\partial B_{\perp}V$ split $\partial S_{\perp}V$.¹
- (iii) Two currents A, B are said to decompose T into a pair of *disjoint* components in V if A and B split $T \sqcup V$, and every normal subcurrent $S \leq T \sqcup V$ is primitive-decomposed in V by $A \land S$ and $B \land S$.
- (iv) The current T is said to be *connected* in V if A, B decomposing T into a pair of disjoint components in V implies $A = T \sqcup V$ or $B = T \sqcup V$.
- (v) A disjoint component S of T in V, which is connected in V, is called a *connected component* (of T in V).

¹ The precedence in our notation is $\partial A \sqcup V = (\partial A) \sqcup V$.

REMARK 3.2 From the definitions, we observe:

- (i) $B = T \sqcup V A$. It is often more convenient to explicitly mention B, however.
- (ii) If A, B split T, then since $(A \land S) \land (B \land S) = S \land (A \land B) = 0$, according to Lemma 3.3, $A \land S, B \land S$ split $S \leq T$. Consequently, one immediately observes that if A, B decompose T into disjoint components in V, then $A \land S, B \land S$ decompose any $S \leq T$ into disjoint components in V.
- (iii) If T is not connected, it consists of at least two disjoint components, given by the A, B violating the definition.
- (iv) If T has no non-trivial normal subcurrent, and has non-singleton support, then it is not connected.

REMARK 3.3 The notion of *T* being connected is less strict than that of an *indecomposable current* as defined by Federer [11] for integral currents. It amounts to the non-existence of a non-trivial integral current $A \leq T$ with $\partial A \leq \partial T$. The current of the next example is decomposable.

With regard to the notion of indecomposability of sets of finite perimeter considered in, e.g., Ambrosio et al. [3, 2] and references therein, closer equivalence can be shown, as in this case the subcurrent splitting requirements become superfluous. We relegate this study to Appendix A.

EXAMPLE 3.1 Consider $T \triangleq A + B \triangleq [-1, 0] + [1, 0]$. Then the individual segments satisfy all the conditions for disjointness, except $\partial A \wedge \partial B = 0$. Thus our notion of connectedness allows "traversing *T* in reverse"; it is akin to connectedness of support sets.

EXAMPLE 3.2 Let $T \triangleq [[(-1, -1), (1, 1)]] + [[(1, -1), (-1, 1)]]$. Then itself T is primitive-decomposed by $A \triangleq [[(-1, -1), 0]] + [[0, (-1, 1)]]$ and $B \triangleq T - A$, but the subcurrent $S \triangleq [[(-1, -1), (1, 1)]]$ is not primitive-decomposed by $A \land S = [[(-1, -1), 0]]$ and $B \land S = [[0, (1, 1)]]$.

We need to show that the definition of a disjoint component is sound. This is done by the following lemmas.

LEMMA 3.4 Suppose A is a disjoint component of a finite mass current T in V, and C a disjoint (resp. connected) component of A in $U \subset V$. Then C is a disjoint (resp. connected) component of T in U.

Proof. Let $B = T \sqcup V - A$, $D = A \sqcup U - C$, and $E = T \sqcup U - C = B \sqcup U + D$. Clearly C and E split $T \sqcup U$, since $C \leq A \sqcup U \leq T \sqcup U$. Also note that $D \leq A \sqcup U$, while $B \land D = 0$.

Suppose then that $S \leq T \sqcup U$ is normal. Then $C \land S = C \land (A \land S)$ is also normal, since *A* primitive-decomposes *S* in $U \subset V$, whence $A \land S \leq A \sqcup U$ is normal and therefore primitive-decomposed by *C*. Likewise $E \land S = B \land S + D \land S$ is normal, after noting that $(B \sqcup U) \land S = B \land (S \sqcup U) = B \land S$.

By the same primitive-decomposition properties, we also have $\partial(C \wedge S) \sqcup U = \partial(C \wedge (A \wedge S)) \sqcup U \leq \partial(A \wedge S) \sqcup U \leq \partial S \sqcup U$. Likewise $\partial(D \wedge S) \sqcup U \leq \partial(A \wedge S) \sqcup U \leq \partial S \sqcup U$, and $\partial((B \sqcup U) \wedge S) \sqcup U = \partial(B \wedge S) \sqcup U \leq \partial S \sqcup U$. Therefore, we can also calculate $\partial(B \wedge S) \wedge \partial(D \wedge S) \sqcup U \leq \partial(B \wedge S) \wedge \partial(A \wedge S) \sqcup U = 0$. Consequently, applying Lemma 3.3, also $\partial(E \wedge S) \sqcup U = \partial(B \wedge S) \sqcup U \leq \partial S \sqcup U$.

Finally, Lemma 3.3 also allows us to deduce $\partial (C \wedge S) \wedge \partial (E \wedge S) \sqcup U = \partial (C \wedge S) \wedge \partial (B \wedge S) \sqcup U + \partial (C \wedge S) \wedge \partial (D \wedge S) \sqcup U = 0$. The last equality follows because *C* and *D* decompose *A* into disjoint components in *U*, because $\partial (C \wedge S) \sqcup U \leq \partial (A \wedge S) \sqcup U$, as shown above, and, finally, because *A* and *B* decompose *T* into disjoint components in $V \supset U$.

Thus we have shown that C remains a disjoint component of T in U. Since the definition of connectedness of C in U does not depend on T, it remains a connected component of T in U. \Box

REMARK 3.4 In particular, taking V = U, we find that a disjoint component of a disjoint component of T, is a disjoint component of T (all in V).

LEMMA 3.5 Suppose A_i , B_i decompose the finite mass current T into disjoint components in the Borel set V_i for i = 1, 2. Then $A_1 \wedge A_2$ is a (possibly zero) disjoint component of T in $V \triangleq V_1 \cap V_2$. The same applies to $(A_1 \vee A_2) \sqcup V$.

Proof. As noted in Remark 3.2, $A_1 \wedge A_2$ is a disjoint component of A_2 in V_1 , hence also $V \subset V_1$. By Lemma 3.4, $A_1 \wedge A_2$ is then a disjoint component of T in V.

The claim on the union follows from the claim on the intersection. Applying Lemma 3.2 in the second equality, we find

$$(A_1 \lor A_2) \llcorner V = (A_1 \llcorner V) \lor (A_2 \llcorner V) = T \llcorner V - (T \llcorner V - A_1 \llcorner V) \land (T \llcorner V - A_2 \llcorner V)$$
$$= T \llcorner V - (T \llcorner V_1 - A_1) \land (T \llcorner V_2 - A_2) \llcorner V = T \llcorner V - B_1 \land B_2.$$

But $B_1 \wedge B_2$ is a disjoint component of T in V by the first part.

LEMMA 3.6 Suppose T_1 and T_2 are finite mass currents connected in V, and that $T_1 \lor T_2$ is defined. If there are $S_i \leq T_i \sqcup V$, i = 1, 2, such that either $S_1 \land S_2 \neq 0$, or S_i are normal and $(\partial S_1 \land \partial S_2) \sqcup V \neq 0$, then $T_1 \lor T_2$ is connected in V.

Proof. Let $T \triangleq T_1 \lor T_2$. Suppose $A, B \leqslant T \llcorner V$ decompose T into disjoint components in V. Then (for every $S_i \leqslant T_i \leqslant T$) we find $A \land S_i = A_i \land S_i \triangleq (A \land T_i) \land S_i$ and $B \land S_i = B_i \land S_i \triangleq (B \land T_i) \land S_i$. Consequently $A_i, B_i \leqslant T_i \llcorner V = T_i \land (T \llcorner V)$ are disjoint components of T_i in V. But, since T_i is connected in V, either $A_i = T_i \llcorner V$ or $B_i = T_i \llcorner V$ for both i = 1, 2. We may assume $A_1 = T_1 \llcorner V$.

Suppose $B_2 = T_{2 \sqcup} V$. Then $A_2 = A \land T_2 = 0$. We have $T_{1 \sqcup} V = A_1 = A \land T_1 = A \land (T - T_2 - T_1 \land T_2)$, whence Lemma 3.3 allows us to deduce $T_{1 \sqcup} V = A \land T = A$. Analogously we obtain $T_{2 \sqcup} V = B$.

But now $S_1 = S_1 \land (T_1 \sqcup V) = S_1 \land A$ and $S_2 = S_2 \land (T_2 \sqcup V) = S_2 \land B$. Therefore $S_1 \land S_2 = (S_1 \land S_2) \land (A \land B) = 0$, providing a contradiction if $S_1 \land S_2 \neq 0$. Otherwise, $S \triangleq S_1 + S_2 = S_1 \lor S_2 \leq T \sqcup V$ is normal, and $S \land A = S_1$ and $S \land B = S_2$. Therefore, since A and B primitive-decompose S, $(\partial S_1 \land \partial S_2) \sqcup V = 0$, contrary to assumption.

We may consequently assume that also $A_2 = T_2 \sqcup V$, whence $B_i = B \land T_i = 0$ for i = 1, 2. Therefore $B = B \land T \sqcup V = B \land (T_1 + T_2 - T_1 \land T_2) \sqcup V = 0$, by employing Lemma 3.3 again. Consequently, we must have $A = T \sqcup V$, and accordingly $T_1 \lor T_2$ is connected.

LEMMA 3.7 Suppose T has finite mass and $U \subset V$ are Borel sets with $\mu_T(V \setminus U) = 0$. If A is a disjoint component of T in V, then A is a disjoint component of T in U. Consequently, if T is connected in U, then it is connected in V.

Proof. $T \sqcup U$ and 0 trivially decompose T into disjoint components in U. Therefore, by Lemma 3.5, $A \land (T \sqcup U) = A \sqcup U$ is a disjoint component of T in $U = V \cap U$. Now, if $\mu_T(V \setminus U) = 0$, then $A \sqcup U = A \sqcup V = A$. Therefore A is a disjoint component of T in U. The claim on connectedness follows from the definition and the first claim. (Note, however, that A being connected in V does not imply the same in U.)

LEMMA 3.8 Suppose $U \subset V$ are Borel sets such that $\mu_T(V^c) = 0$. If A is a disjoint component of T in U, and $\partial (A \wedge S) \cup V^c = 0$ for all normal $S \leq T \cup U$, then A is a disjoint component of T in $U \cup V^c$.

Proof. Clearly A and $T \sqcup U - A$ split $T \sqcup (U \cup V^c) = T \sqcup U$, since $\mu_T(V^c) = 0$. Also, $\partial(A \land S) \sqcup (U \cup V^c) = \partial(A \land S) \sqcup U + \partial(A \land S) \sqcup V^c = \partial(A \land S) \sqcup U$, since $U \cap V^c = U \setminus V = \emptyset$. Thus the boundary-splitting requirements continue to hold.

3.3 Connections and edges

In this subsection, we consider one-dimensional normal currents *T* with real rectifiable boundary. Thus $\partial T = \sum_{i=1}^{\infty} \alpha_i \delta_{x_i}, \alpha_i \neq 0$. We call the points x_i the *boundary points* of *T*, and use the notation img $\psi \triangleq \{x \mid \alpha \delta_x \leq \psi, \alpha \neq 0\}$ for real rectifiable 0-dimensional currents ψ of finite mass, such as ∂T . This can differ from the support, which is a closed set. We also abuse notation slightly and set $\psi(x) \triangleq \alpha$ whenever $\psi \llcorner \{x\} = \alpha \delta_x$.

DEFINITION 3.3 Suppose V is an open set, and T a normal current. We then make the following definitions:

- (i) A normal acyclic subcurrent $E \leq T$ is an *edge* of T in V if supp $E \subset V$, and $\partial E = \alpha(\delta_x \delta_y)$ for some $x, y \in \mathbb{R}^m$ and $\alpha \neq 0$.
- (ii) A finite sequence of edges $E_1, \ldots, E_n \leq T$ in V and directions $\tau_i \in \{-1, +1\}$ with $\partial E_i = \tau_i \alpha(\delta_{x_{i+1}} \delta_{x_i})$ forms a *connection* between x_1 and x_{n+1} in V. The number $\alpha > 0$ is called the *strength* of the connection.
- (iii) If ∂T is real rectifiable, *T* is *edge-connected* in *V* if there exists a connection in *V* between every $x, y \in img(\partial T \sqcup V)$.

REMARK 3.5 The existence of a connection between two points is an equivalence relation, thus in particular transitive.

EXAMPLE 3.3 Consider again the polyhedral 1-dimensional chain T = [-1, 0] + [1, 0] in \mathbb{R} . There exists no single edge between -1 and 1, but $E_1 \triangleq [-1, 0]$ and $E_2 \triangleq [1, 0]$ connect these points.

LEMMA 3.9 Suppose T is a normal current and V an open set. Then every edge E of T in V is connected in V.

Proof. If $A \leq T$ is normal, the compact support and finite $\mathbb{M}(\partial A)$ imply $\mu_{\partial A}(\mathbb{R}^m) = 0$. Furthermore, if $A \leq E$, then since supp $A \subset \text{supp } E \subset V$, we have $A = A \sqcup V$ and $\partial A = \partial A \sqcup V$. Therefore we may assume $V = \mathbb{R}^m$.

Now, if $A \leq E$ and E - A primitive-decompose E, then $\partial A \leq \partial E = \alpha(\delta_y - \delta_x)$. Thus $\partial A = \beta(\delta_y - \delta_x)$ for some $\beta \in [0, \alpha]$. But then from $\partial A \wedge \partial(E - A) = 0$ we have $\beta = 0$ or $\beta = 1$. By the acyclicity of E, $\partial A = 0$ implies A = 0, while $\partial A = \partial E$ implies A = E. Thus E is connected.

LEMMA 3.10 Suppose *E* is an edge with no circuits. Then $E = \alpha [\![\gamma]\!]$ for a Lipschitz path γ and $\alpha > 0$.

Proof. Since E is normal, we may express $E = [\![\eta]\!]$ for a transport measure η . We claim that η must be concentrated on a single path γ . For, if there were disjoint measurable sets Γ and Γ' with

 $\eta \llcorner \Gamma, \eta \llcorner \Gamma' \neq 0$, then these restrictions would form a circuit in violation of that assumption. It remains to show that such sets can be found if η is not concentrated on a single path. Let Ω be a compact convex set such that supp $E \subset \Omega$, and $\Gamma_{\ell} \triangleq \{\gamma \in \overline{\Gamma} \mid \mathcal{H}^1(\operatorname{img} \gamma) \leq \ell, \operatorname{supp} \gamma \subset \Omega\}$. We may assume η is concentrated on Γ_{ℓ} for some $\ell > 0$, for otherwise Γ_{ℓ} and Γ_{ℓ}^c are the sets we are after. But $\Gamma^1 \triangleq \Gamma_{\ell}$ is compact [7]. Therefore, we can find a finite cover of open balls, $\{U(\gamma_i, 1) \mid i = 1, \ldots, n\}$. If there are two balls with indices *i* and *j* such that $\eta(U(\gamma_i, 1) \setminus U(\gamma_j, 1)) > 0$ and $\eta(U(\gamma_j, 1) \setminus U(\gamma_i, 1)) > 0$, we have found our sets Γ and Γ' . Otherwise η is concentrated on $\Gamma^2 \triangleq B(\gamma_i, 1) \cap \Gamma^1$ for some *i*, and we continue by covering Γ^2 with balls of diameter 1/2. By recursively repeating the process this way, eventually $\bigcap_{i=1}^{\infty} \Gamma^i = \{\gamma\}$, since $\{\Gamma^i\}$ is a nested sequence of closed sets of diameters tending to zero. Thus η is concentrated on $\{\gamma\}$.

LEMMA 3.11 Suppose T contains no circuit. Then any connection E_1, \ldots, E_n in T can be assumed to consist of Lipschitz paths $E_i = \alpha [\![\gamma_i]\!]$ with $E_i \wedge E_j = 0$ for $i \neq j$.

Proof. By Lemma 3.10, $E_i = \alpha[[\gamma_i]]$, while by definition $\partial E_i = \tau_i \alpha(\delta_{x_{i+1}} - \delta_{x_i})$. If $\gamma_i(t_i) = \gamma_j(t_j)$ for $t_i, t_j \in (0, 1)$ $(i \leq j)$, we may remove the edges E_{i+1}, \ldots, E_{j-1} from the connection, and replace E_i (resp. E_j) by the segment before or after t_i depending on the direction τ_i .

3.4 Equivalence

To show partial equivalence between the notion of connectedness in Definitions 3.2 and 3.3, we require the following concept of a *bundle*, and some related results. As can be seen from the proof of Lemma 3.12 below, the notion bears some resemblance to the *trunk trees* of Bernot et al. [5], but we do not require the single-path property.

DEFINITION 3.4 An acyclic normal current *S* is called a *bundle* if there is a point $x \in \mathbb{R}^m$ such that *S* can be primitive-decomposed in $\{x\}^c$ into *A* and *B* with $\partial A_{\perp}\{x\}^c = -(\partial S)^{-}_{\perp}\{x\}^c$ and $\partial B_{\perp}\{x\}^c = (\partial S)^{+}_{\perp}\{x\}^c$.

A bundle $S \leq T \sqcup V$ with $\partial S \sqcup V \leq \partial T \sqcup V$ is called a *V*-subbundle.

LEMMA 3.12 Suppose S is a one-dimensional bundle. Then there exists a transport measure $[\![\eta]\!] = S$, and connections in S between all $z \in \mathbb{R}^m$ with $\alpha_\eta(z) > 0$.

Proof. Let $x, A = \llbracket \eta_A \rrbracket$, and $B = \llbracket \eta_B \rrbracket$ be as in Definition 3.4. For X = A, B, we let $m_X \triangleq \eta_X(\bar{\Gamma})$ $(= \eta_{X,0}(\mathbb{R}^m) = \eta_{X,1}(\mathbb{R}^m))$, and assume that $m_A + m_B > 0$, the case S = 0 being trivial.

For $\gamma_A \in \text{supp } A$ and $\gamma_B \in \text{supp } B$, let

$$(\gamma_A \cdot \gamma_B)(t) \triangleq \begin{cases} \gamma_A(2t), & t \in [0, 1/2], \\ \gamma_B(2t-1), & t \in (1/2, 1]. \end{cases}$$

Clearly (·) is continuous, hence measurable. Also $[\![\gamma_A \cdot \gamma_B]\!] = [\![\gamma_A]\!] + [\![\gamma_B]\!]$. Thus, if we let $\tilde{\eta} \triangleq$ (·)_#($\eta_A \times \eta_B$), then $[\![\tilde{\eta}]\!] = m_B[\![\eta_A]\!] + m_A[\![\eta_B]\!]$. Furthermore, $\tilde{\eta}_0 = m_B(\partial A)^- = m_B(\partial S)^- \lfloor \{x\}^c$, and $\tilde{\eta}_1 = m_A(\partial B)^+ = m_A(\partial S)^+ \lfloor \{x\}^c$, since $\gamma_A(1) = \gamma_B(0) = x$ a.e. Thus, with

$$\eta \triangleq \begin{cases} \tilde{\eta}/m_A + (1 - m_B/m_A)\eta_A, & m_A \ge m_B, \\ \tilde{\eta}/m_B + (1 - m_A/m_B)\eta_B, & m_A < m_B, \end{cases}$$

we have $\llbracket \eta \rrbracket = \llbracket \eta_A \rrbracket + \llbracket \eta_B \rrbracket = S$, $\eta_1 = (\partial S)^+$, and $\eta_0 = (\partial S)^-$. Therefore η is a transport measure for *S*.

Now, as one can see by application of Fubini's theorem,

$$\begin{aligned} \alpha_{\bar{\eta}}(z) &= \int \int \chi_{\mathrm{img}(\gamma_A \cdot \gamma_B)}(z) \, \mathrm{d}\eta(\gamma_A) \, \mathrm{d}\eta(\gamma_B) \leqslant \int \int (\chi_{\mathrm{img}\,\gamma_A}(z) + \chi_{\mathrm{img}\,\gamma_B}(z)) \, \mathrm{d}\eta(\gamma_A) \, \mathrm{d}\eta(\gamma_B) \\ &\leqslant m_B \alpha_{\eta_A}(z) + m_A \alpha_{\eta_B}(z). \end{aligned}$$

Therefore $\alpha_{\eta}(z) > 0$ implies that either $\alpha_{\eta_A}(z) > 0$ or $\alpha_{\eta_B}(z) > 0$. We assume the former, the latter case being analogous.

Let then $\Gamma \triangleq \{\gamma \in \operatorname{supp} \eta_A \mid z \in \operatorname{img} \gamma\}$. Define $\tau(\gamma) \triangleq \inf\{t \mid \gamma(t) = z\}$ and $v(\gamma) \triangleq \gamma \lfloor \tau(\gamma), 1 \rfloor$ for $\gamma \in \Gamma$. Then v is seen to be measurable by adapting Lemma 2.1. Also let $E \triangleq \llbracket v_{\#}(\eta \lfloor \Gamma) \rrbracket$, i.e., $E(\omega) = \int_{\Gamma} \llbracket \gamma \lfloor \tau(\gamma), 1 \rfloor \rrbracket (\omega) \, d\eta_A(\gamma)$. Then $\partial E = \alpha_{\eta_A}(z) (\delta_x - \delta_z)$, because $\gamma(1) = x \eta_A$ -a.e. and $\alpha_{\eta_A}(z) = \eta_A(\Gamma)$. Thus we have found an edge between x and z. Such edges connect all z with $\alpha_{\eta}(z) > 0$ via x.

LEMMA 3.13 Suppose $S \leq T$ is a one-dimensional bundle and $S' \leq T$ a normal current with $0 \neq -\partial S' \leq \partial S$. Then S + S' contains a cycle if non-zero.

Proof. Since $-\partial S' \leq \partial S$, there is a density $f = f^+ + f^-$ such that $\partial S' = -f\partial S$ $((\partial S')^{\mp} = f^{\pm}(\partial S)^{\pm})$. Let $x \in \mathbb{R}^m$, $A = \llbracket \eta_A \rrbracket$ and $B = \llbracket \eta_B \rrbracket$ be as in Definition 3.4. Define $A' \triangleq \llbracket (f^- \circ p_0) \eta_A \rrbracket$ and $B' \triangleq \llbracket (f^+ \circ p_1) \eta_B \rrbracket$. Then

$$\partial A'(\omega) = \int \llbracket \gamma \rrbracket (d\omega) (f^- \circ p_0)(\gamma) \, d\eta_A(\gamma)$$

$$= \int (\delta_{p_1(\gamma)}(\omega) - \delta_{p_0(\gamma)}(\omega)) (f^- \circ p_0)(\gamma) \, d\eta_A(\gamma)$$

$$= \int \delta_x(\omega) (f^- \circ p_0)(\gamma) \, d\eta_A(\gamma) - \int \delta_z(\omega) f^-(z) \, d\eta_{A,0}(z)$$

$$= \delta_x(\omega) (f^- \eta_{A,0}) (\mathbb{R}^m) - (f^- \eta_{A,0})(\omega)$$

$$= (\partial S')^+ (\{x\}^c) \delta_x(\omega) - (\partial S')^+ (\{x\}^c)(\omega).$$
(3.2)

Likewise,

$$\partial B'(\omega) = -(\partial S')^{-}(\{x\}^{c})\delta_{x}(\omega) + (\partial S')^{-} \llcorner \{x\}^{c}(\omega).$$

Thus

$$\partial A' + \partial B' + \partial S' = \partial S'(\{x\}^c)\delta_x - \partial S' \lfloor \{x\}^c + \partial S' = 0$$

where the latter equality follows because $\partial S'(\{x\}^c) + \partial S'(\{x\}) = \partial S'(\mathbb{R}^m) = 0$ by the compactness of the support of S'. Finally, we cannot have both $S' \leq T$ and $-S' = A' + B' \leq S \leq T$ unless S' = 0, so $A' + B' + S' \neq 0$.

LEMMA 3.14 Suppose *S* is an acyclic one-dimensional real rectifiable normal current. Then $S = \sum_{i=1}^{\infty} S_i$, with each S_i a subbundle of *S*.

Proof. We may assume $S \neq 0$. Represent $S = [\![\eta]\!]$. Let $a_1 = \operatorname{ess} \sup \alpha_\eta$ (in \mathcal{H}^1 sense). Then $a_1 > 0$ by the rectifiability of S. Choose x such that $\alpha_\eta(x) \ge a_1$; such a point exists because α_η is uppersemicontinuous by [14, Lemma 7.2], and has compact support. Let $\Gamma_1 \triangleq \{\gamma \in \operatorname{supp} \eta \mid x \in \operatorname{img} \gamma\}$ and $S_1 \triangleq [\![\eta \llcorner \Gamma_1]\!]$. Then $\mathbb{M}(\partial S_1)/2 \ge a_1$ and $\partial S_1 \le \partial S$. Indeed, S_1 is a subbundle of S, as seen by cutting each $\gamma \in \Gamma_1$ into two parts at x as follows: Similarly to the proof of Lemma 3.12, define

 $f_A(\gamma) \triangleq \gamma \lfloor [0, \inf\{t \mid \gamma(t) = x\}]$ and $f_B(\gamma) \triangleq \gamma \lfloor [\inf\{t \mid \gamma(t) = x\}, 1]$, measurable on Γ_1 by adapting Lemma 2.1. Then let $X = [[(f_X)_{\#}(\eta \lfloor \Gamma_1)]]$ for X = A, B.

Next we form S_2 similarly from $S - S_1 = [\![\eta \llcorner \Gamma_1^c]\!]$, and recursively continue the process. Let $S' \triangleq S - \sum_{i=1}^{\infty} S_i = [\![\eta \llcorner (\bigcup_{i=1}^{\infty} \Gamma_i)^c]\!]$. We get ess $\sup \alpha_{\eta \llcorner (\bigcup \Gamma_i)^c} \leq \lim_{i \to \infty} a_i = 0$ thanks to the bound $\sum_{i=1}^{\infty} a_i \leq \mathbb{M}(\partial S)/2 < \infty$ from the construction. Therefore S' = 0, that is, $S = \sum_{i=1}^{\infty} S_i$. \Box LEMMA 3.15 Suppose *T* is an acyclic normal current, *V* an open set, and $S \leq T \llcorner V$ a one-dimensional bundle. Then there is a *V*-subbundle *T'* of *T* with $S \leq T'$ and $\partial S \land \partial T \llcorner V \leq \partial T'$.

Proof. We first consider the case $V = \mathbb{R}^m$. Let $I \triangleq \partial S \land \partial (S - T)$. Since $I \leq \partial S$, $\partial (S - T)$, there are densities $f \triangleq f^+ + f^-$ and $g \triangleq g^+ + g^-$ with $f^{\pm}(x), g^{\pm}(x) \in [0, 1]$ a.e., $I^{\pm} = f^{\pm}(\partial S)^{\pm}$, and $I^{\mp} = g^{\pm}(\partial (S - T))^{\mp} = g^{\pm}(\partial (T - S))^{\pm}$. (Note the signs!) Now,

$$\partial T = \partial S + \partial (T - S) = f \partial S + (1 - f) \partial S + g \partial (T - S) + (1 - g) \partial (T - S)$$

= I + (1 - f) \delta S - I + (1 - g) \delta (T - S) = (1 - f) \delta S + (1 - g) \delta (T - S).

Since a.e. $f^{\pm} \leq f^{\pm} + (1 - f^{\pm})(1 - g^{\mp}) = 1 - (1 - f^{\pm})g^{\mp} \leq 1$ and $g^{\mp} \leq g^{\mp} + (1 - f^{\pm})(1 - g^{\mp}) = 1 - (1 - g^{\mp})g^{\pm} \leq 1$, we must have $(1 - f^{\pm})(1 - g^{\mp}) = 0$ a.e., for otherwise I^{\pm} could not be the maximal subcurrent of both ∂S and $\partial (S - T)$. Therefore, $((1 - f)\partial S)^{\pm} \wedge ((1 - g)\partial (T - S))^{\mp} = 0$, and consequently also

$$(\partial T)^{\pm} = (1 - f^{\pm})(\partial S)^{\pm} + (1 - g^{\pm})(\partial (T - S))^{\pm}.$$
(3.3)

Represent $T - S = [\![\eta]\!]$, and let $A' \triangleq A + [\![(g^+ \circ p_1)\eta]\!]$ and $B' \triangleq B + [\![(g^- \circ p_0)\eta]\!]$, where A and B are as in Definition 3.4. Then, following the derivation of (3.2),

$$\partial A'(\omega) = \partial A(\omega) + \int \delta_z(\omega) g^+(z) d\eta_1(z) - \int \delta_{p_0(\gamma)}(\omega) (g^+ \circ p_1)(\gamma) d\eta(\gamma)$$

= $\partial A(\omega) + I^-(\omega) - \int \delta_{p_0(\cdot)}(\omega) (g^+ \circ p_1) ((1 - g^-) \circ p_0) d\eta$
= $\partial A(\omega) + (f^-(\partial S)^-)(\omega) - (h^-(\partial (T - S))^-)(\omega)$ (3.4)

for some density $h^- \leq 1 - g^-$. The second equality holds because $(1 - g^-) \circ p_0 = 1$ a.e. for $(g^+ \circ p_1)\eta$. Otherwise we would have $\eta(\{\gamma \mid (g^- \circ p_0)(\gamma)(g^+ \circ p_1)(\gamma) > 0\}) > 0$, and then a cycle could be constructed by application of Lemma 3.13 with $S' \triangleq [[(g^- \circ p_0)(g^+ \circ p_1)\eta]]$. The existence of h^- follows from noting that $((1 - g)\partial(T - S))^-(\omega) = \int \omega(1 - g^-) d\eta_0 = \int \delta_{p_0(\cdot)}(\omega)((1 - g^-) \circ p_0) d\eta$.

Similarly to (3.4),

$$\partial B'(\omega) = \partial B(\omega) - (f^+(\partial S)^+)(\omega) + (h^+(\partial (T-S))^+)(\omega).$$

Since $\partial A_{\perp}\{x\}^{c} = -(\partial S)^{-}_{\perp}\{x\}^{c}$ and $\partial B_{\perp}\{x\}^{c} = (\partial S)^{+}_{\perp}\{x\}^{c}$, we have

$$\partial A' \llcorner \{x\}^c = -[(1 - f^-)(\partial S)^- + h^-(\partial (T - S))^-] \llcorner \{x\}^c, \partial B' \llcorner \{x\}^c = [(1 - f^+)(\partial S)^+ + h^+(\partial (T - S))^+] \llcorner \{x\}^c.$$

Letting $T' \triangleq A' + B'$ and recalling that $\partial A + \partial B = \partial S$, we have

$$\partial T' = (1 - f)\partial S + h\partial (T - S), \text{ with } h \triangleq h^+ + h^- \ge 0.$$

Since $h^{\pm} \leq 1 - g^{\pm}$ a.e., we see by reasoning similarly to (3.3) that $(\partial T')^{\pm} = (1 - f^{\pm})(\partial S)^{\pm} + h^{\pm}(\partial(T - S))^{\pm}$. Hence $\partial T' \leq \partial T$. Also, from this property, $\partial A' \lfloor \{x\}^c = -(\partial T')^- \lfloor \{x\}^c$ and $\partial B' \lfloor \{x\}^c = (\partial T')^+ \lfloor \{x\}^c$. Thus T' is a subbundle of T with $S \leq T'$.

Finally, by (3.3), Lemma 3.3 and the fact

$$(1-g^{\pm})(\partial(T-S))^{\pm} \wedge f^{\pm}(\partial S)^{\pm} = (1-g^{\pm})(\partial(T-S))^{\pm} \wedge g^{\mp}(\partial(T-S))^{\mp} = 0,$$

we find $(\partial S \wedge \partial T)^{\pm} = (\partial S)^{\pm} \wedge (\partial T)^{\pm} = (1 - f^{\pm})(\partial S)^{\pm}$. Hence $(\partial S \wedge \partial T)^{\pm} \leq (\partial T')^{\pm}$. The case $V = \mathbb{R}^m$ has been shown.

If $V \subseteq \mathbb{R}^m$, we replace all the paths in the support of $A' - A = [[(g^+ \circ p_1)\eta]]$ by the paths only beginning upon entering V. This is done by defining the map $v(\gamma) \triangleq \gamma \lfloor [\sup\{t \ge 0 \mid \gamma(t) \in V^c\}, 1]$ for $\gamma \in \Gamma_V \triangleq \{\gamma \in \sup p\eta \mid \gamma(1) \in V\}$. Then v is measurable by adapting Lemma 2.1. For $(g^+ \circ p_1)v_{\#}(\eta \lfloor \Gamma_V)$ -a.e. path γ , $\operatorname{img} \gamma \setminus \{\gamma(0)\} \subset V$. We may thus redefine $A' \triangleq A + [[(g^+ \circ p_1)v_{\#}(\eta \lfloor \Gamma_V)]]$. Similarly to (3.4), we then get for some density h^- , zero outside V,

$$\partial A' \llcorner V(\omega) = \partial A \llcorner V(\omega) + \int_{V} \delta_{z}(\omega) g^{+}(z) d\eta_{1}(z) - \int_{\operatorname{img} \gamma \subset V} \delta_{p_{0}(\gamma)}(\omega) (g^{+} \circ p_{1})(\gamma) d\eta(\gamma)$$

= $\partial A \llcorner V(\omega) + (f^{-}(\partial S)^{-} \llcorner V)(\omega) - (h^{-}(\partial (T - S))^{-})(\omega).$

We do a similar modification for the paths of $B' - B = [[(g^- \circ p_0)\eta]]$, tracing from t = 0. The entire reasoning above then continues to hold after masking the boundaries with *V*.

DEFINITION 3.5 *C* is a *V*-cycle if $\partial C \sqcup V = 0$ and $C \sqcup V \neq 0$.

THEOREM 3.1 Suppose T is a one-dimensional normal current with real rectifiable boundary, and V an open set. Then we have the following equivalences:

- (i) If T is edge-connected in V, contains no V-cycle disjoint in V, and $T \sqcup V$ is normal, then T is connected in V.
- (ii) If T is connected in V, acyclic, and real rectifiable, then T is edge-connected in V.

Proof. (i) We may assume that $T \neq 0$. To reach a contradiction, suppose therefore that A and B decompose T into non-trivial disjoint components in V. A and B are normal since $T \sqcup V$ was assumed to be. Furthermore, $\partial A \sqcup V$, $\partial B \sqcup V \leq \partial T \sqcup V$ are non-zero, because T was assumed to contain no V-cycle disjoint in V.

Suppose *E* is an edge of *T* in *V*. By the definition of disjointness, the fact supp $E \subset V$, and *V* being open, we have $\partial(A \wedge E)$, $\partial(B \wedge E) \leq \partial E$ and $\partial(A \wedge E) + \partial(B \wedge E) = \partial E$. But $\partial E = \alpha(\delta_x - \delta_y)$, whence the compact support of *T* implies that either $\partial(A \wedge E) = 0$ or $\partial(B \wedge E) = 0$. We may assume the latter, the other case being analogous. Then, by acyclicity, $B \wedge E = 0$, so $E = A \wedge E$, i.e., $E \leq A$.

Suppose that $S_B \leq B$ is normal, and let $S \triangleq E + S_B$. Then $(\partial E \wedge \partial S_B) \sqcup V = \partial (A \wedge S) \wedge \partial (B \wedge S) \sqcup V = 0$, as well as $\partial S_B \sqcup V \leq \partial S \sqcup V = (\partial S_B + \partial E) \sqcup V$. Therefore, if $a \in \operatorname{img} \partial E$, then $a \notin \operatorname{img} \partial S_B$.

Let then E_1, \ldots, E_n be a connection of T in V between any $a \in \operatorname{img}(\partial A \cup V)$ and $b \in \operatorname{img}(\partial B \cup V)$, existing by edge-connectedness and $0 \neq \partial A \cup V$, $\partial B \cup V \leq \partial T \cup V$. By the argument of the previous paragraph (with $S_B = B$, and assuming $E = E_n \leq A$), we find $E_n \leq B$. But since there is always some x with $x \in \operatorname{img} \partial E_i \cap \operatorname{img} \partial E_{i+1}$, the argument above (with $S_B = E_{i+1}$) again tells us that $E_i \leq B$ for all $i = 1, \ldots, n$. But $a \in \operatorname{img} \partial A$ and $a \in \operatorname{img} \partial E_1$ is then a contradiction of the same result. Therefore T must be connected in V.

(ii) We say that x_0 is *V*-bundle-connected to x_n if there exists a finite sequence of *V*-subbundles $T_i = [\![\eta_i]\!], i = 1, ..., n$, with $\alpha_{\eta_1}(x_0), \alpha_{\eta_n}(x_n) > 0$, and either $T_i \wedge T_{i+1} \neq 0$, or $\partial T_i \wedge \partial T_{i+1} \cup V \neq 0$ (i = 1, ..., n - 1). In the former case $\mathcal{H}^1(\{x \in \mathbb{R}^m \mid \alpha_{\eta_i}(x), \alpha_{\eta_{i+1}}(x) > 0\}) > 0$, and in the latter case there exists $x \in img \partial T \cup V$ with $\alpha_{\eta_i}(x), \alpha_{\eta_{i+1}}(x) > 0$. Thus we find that there exist points x_i (i = 1, ..., n - 1) with $\alpha_{\eta_i}(x_i), \alpha_{\eta_{i+1}}(x_i) > 0$. Lemma 3.12 now shows that x_0 and x_n are edge-connected.

Choose then $x_0 \in \operatorname{img} \partial T$, and let Σ be the set of points *V*-bundled-connected to x_0 . By Lemma 3.12, $T' \llcorner \Sigma = T'$ or $T' \llcorner \Sigma = 0$ for any *V*-subbundle of *T*. Define $T_A = T \llcorner \Sigma$ and $T_B = T \llcorner V - A$. We now intend to show that T_A and T_B are disjoint components of *T* in *V*. Since $T \llcorner \Sigma \neq 0$, we must in fact have $T \llcorner \Sigma = T$. This in particular implies that there is a connection between any boundary points of *T*. (Otherwise a different base point x'_0 would yield Σ' with $\Sigma' \cap \Sigma = 0$ and $T \llcorner \Sigma' \neq 0$.)

Clearly T_A and T_B split any $S \leq T \sqcup V$. To show that ∂S is split in V, more work is needed. Towards that end, decompose S into subbundles S_1, S_2, \ldots , as shown by Lemma 3.14. (Since $S = S \sqcup V$, the S_i are also V-subbundles.) According to Lemma 3.15 these bundles can be extended to V-subbundles T_i of T. Consequently, by the construction of Σ , $S_i \sqcup \Sigma = S_i$ or 0. Thus, letting $I \triangleq \{i \mid S_i \sqcup \Sigma = S_i\}$, we have $T_A \land S = \sum_{i \in I} S_i$ and $T_B \land S = \sum_{i \notin I} S_i$. Therefore also $T_A \land S$ and $T_B \land S$ are normal, $\partial(T_A \land S) \sqcup V$, $\partial(T_B \land S) \sqcup V \leq \partial S \sqcup V$, and $\partial(T_A \land S) \sqcup V + \partial(T_B \land S) \sqcup V = \partial S \sqcup V$.

If $\partial(T_A \wedge S) \wedge \partial(T_B \wedge S) \cup V \neq 0$, then $\partial S_i \wedge \partial S_j \cup V \neq 0$ for some $i \in I$, $j \notin I$. There exists a density $h \triangleq h^+ + h^-$ with $(\partial S_i \wedge \partial S_j)^{\pm} \cup V = h^{\pm}(\partial S_i)^{\pm}$. We may assume that $h^-(\partial S_i)^- \neq 0$, the case $h^+(\partial S_i)^+ \neq 0$ being similar. Let $A_k = [\![\eta_k]\!]$, and B_k be the A and B from Definition 3.4 for $S_k, k = i$, j. Denote by $A'_i = A_i + [\![\eta']\!]$ and B'_i the corresponding unindexed variables for S_i from Lemma 3.15. Let $\hat{A}_j = A_j + [\![(h^- \circ p_1)\eta']\!]$, $\hat{B}_j = B_j$, and $\hat{S}_j = \hat{A}_j + \hat{B}_j$. Finally, extend \hat{S}_j as a Vsubbundle \hat{T}_j of T by Lemma 3.15. We must have either $T_i \wedge \hat{T}_j \neq 0$, or $(\partial T_i)^- \wedge (\partial \hat{T}_j)^- \cup V \neq 0$, both of which imply $j \in I$, since $\hat{T}_j \geq S_j$. The former follows if $[\![(h^- \circ p_1)\eta']\!] \neq 0$, since $[\![(h^- \circ p_1)\eta']\!] \leq A'_i, \hat{A}_j$. Otherwise, if $[\![(h^- \circ p_1)\eta']\!] = 0$, then $h^-(\partial S_i)^- \wedge (\partial(T - S_i))^+ = 0$, so $h^-(\partial S_i)^- \leq (\partial T)^-$. But then $0 \neq h^-(\partial S_i)^- \leq (\partial T_i)^- \cup V$, $(\partial \hat{T}_j)^- \cup V$ by Lemma 3.15. We have thus established the contradiction $j \in I$, so T must be edge-connected. \Box

3.5 The case of finite V^c

With the partial equivalence of connectedness and edge-connectedness now at hand, we consider additional properties that follow when V has the form $\{x_1, \ldots, x_n\}^c$.

DEFINITION 3.6 A collection A of currents is said to be *mutually disjoint* in V if for all $A, B \in A$ with $A \neq B$, A and B decompose A + B into a pair of disjoint components in V.

REMARK 3.6 Any collection of connected components in V of a normal current T is mutually disjoint: Suppose $A_1 \neq A_2$ are connected components of T in V. By Lemma 3.5, $A_1 \lor A_2$ is a disjoint component of T in V, and then of A_i by Remark 3.2(ii). Thus $A_1 \land A_2 = 0$ and $A_1 + A_2 =$ $A_1 \lor A_2$. Since $T \sqcup V - A_1$ and A_1 split $A_1 \lor A_2$, the same remark says that $(T \sqcup V - A_1) \land (A_1 \lor A_2) =$ $(A_1 \lor A_2) - A_1 = A_2$ and $A_1 \land (A_1 \lor A_2) = A_1$ are disjoint components of $A_1 + A_2$.

If T is normal, any finite or countable sum of mutually disjoint (disjoint) components of T in V is a disjoint component of T in V. This can be seen by repeated application in Definition 3.2 of the equalities

 $(A_1 + A_2) \land S = (A_1 \land S) + (A_2 \land S) = (A_1 \land S) \lor (A_2 \land S) \leqslant S, \quad A_1, A_2 \in \mathcal{A},$

from Lemmas 3.3 and 3.1, and their boundary and V-restricted variants.

LEMMA 3.16 Suppose T is an acyclic one-dimensional normal current with real rectifiable boundary. Then T is a sum of at most countably many connected components in V whenever V^c is a singleton or empty. If T is real rectifiable and contains no circuit, the claim holds whenever V^c is finite.

Proof. Any disjoint component $A = A \wedge T$ of T in V is normal (since T is) with $\partial A \sqcup V \leq \partial T \sqcup V$, $\partial A \sqcup V + \partial (T - A) \sqcup V = \partial T \sqcup V$, and $\partial A \wedge \partial (T - A) \sqcup V = 0$. Therefore, actually $\partial A = \partial T \sqcup U + \sum_{x \in V^c} \alpha_x \delta_x$ for some set $U \subset V$ and $\alpha_x \in \mathbb{R}$.

Since ∂T is real rectifiable, there can be at most countably many mutually disjoint components with $\partial A_{\perp}U \neq 0$. So suppose $\partial A = \sum_{x \in V^c} \alpha_x \delta_x$. If V^c is empty, the claim follows by the acyclicity of T. If V^c is a singleton, and $\partial A = \alpha_x \delta_x$, compactness of the support implies $\alpha_x = 0$, and acyclicity implies A = 0. Thus the claim follows.

If V^c is simply finite, any disjoint component with boundary points in V^c may still be assumed connected (in \mathbb{R}^m !). Now, when *T* is real rectifiable, there exist edges between the boundary points, by Theorem 3.1. Since there are only finitely many possible boundary point combinations in V^c (although the weights can vary uncountably), a circuit can be constructed if there are uncountably many components of *T* mutually disjoint in *V*. But *T* had no circuits.

We have thus shown there are at most countably many disjoint components of T, hence at most countably many (mutually disjoint) connected components that sum to T.

LEMMA 3.17 Suppose *T* is a one-dimensional normal current containing no circuit, with real rectifiable boundary. Suppose *C* and *D* are disjoint components of *T* in $V \triangleq \{x_1, \ldots, x_n\}^c$, edge-connected in \mathbb{R}^m . Then for at most one $i \in \{1, \ldots, n\}$, neither *C* nor *D* is a disjoint component of *T* in $V \cup \{x_i\}$.

Proof. Employing the representation $T = [\![\eta]\!]$, we may observe that for any point x, $\mu_T(\{x\}) = \int \mathbb{M}([\![\gamma]\!]_{L}\{x\}) d\eta(\gamma) = \int \mathcal{H}^1(\operatorname{img} \gamma \cap \{x\}) d\eta(\gamma) = 0$. Therefore, if

$$\partial (S \wedge C) \llcorner \{x_1\} = 0 \quad \text{for all normal } S \leqslant T \llcorner V, \tag{3.5}$$

then by Lemma 3.8, *C* is a disjoint component of *T* in $V' \triangleq V \cup \{x_1\}$. Similar conclusions hold when *C* is replaced by *D* or x_1 is replaced by x_2 in (3.5). So assume that the condition is violated by all the four combinations.

Let therefore S be in violation of (3.5). We may assume $S = S \wedge C$. If $\partial C(x_1) \neq 0$, we choose $y_{C,1} = x_1$ and let $E_{C,1} = 0$. Otherwise, $\partial (C - S)(x_1) = -\partial S(x_1)$. We may also assume that $\operatorname{img}(\partial S)^+ = \{x_1\}$ or $\operatorname{img}(\partial S)^- = \{x_1\}$ after a possible redefinition restricting a transport measure for S to paths beginning or ending at x_1 . Since the construction for the other case is analogous, we assume for simplicity that actually $\operatorname{img}(\partial S)^+ = \{x_1\}$. Then S is a bundle, with A = S, and B = 0. We may by Lemma 3.15 extend it to a subbundle S' of C. In particular, by the proof, $-\partial A' {}_{\sqcup}\{x\}^c \leq (\partial C)^- \{x\}^c$, while still $\operatorname{img}(\partial A)^+ = \{x_1\}$. Thus A' consists of edges between x_1 and some points in $\operatorname{img}(\partial C)^-$, ∂C being an at most countable sum of Dirac measures. Choose one of these points as $y_{C,1}$, and denote the corresponding edge by $E_{C,1}$.

Similarly to the above, we may produce $E_{C,2}$, $E_{D,1}$, and $E_{D,2}$, connecting x_i to a boundary point $y_{X,i}$ of X = C, D for i = 1, 2. Since C and D are edge-connected we may also find connections between $y_{C,1}$ and $y_{C,2}$ in C, as well as between $y_{D,1}$ and $y_{D,2}$ in D. By composing these connections with $E_{C,1}$, $E_{C,2}$, $E_{D,1}$, and $E_{D,2}$, a circuit can be constructed in T. This is a contradiction.

3.6 Branches

We now assume that $R \in \mathcal{R}^*$, where the latter denotes the set of one-dimensional acyclic normal real rectifiable currents with real rectifiable boundary.

DEFINITION 3.7 Given a point $x \in \mathbb{R}^m$, the connected components of R in $\{x\}^c$ that are not connected components of R in \mathbb{R}^m , are called the *branches* of R at x. The point x is called a *branch point* if the cardinality of branches at x is at least 3. If the cardinality is at least 2, x is a *cut point*. If x is not a cut point, it is a *non-cut point*. (We only apply this last concept to boundary points.)

REMARK 3.7 According to Lemma 3.16, the definition is sound: R is a sum of at most countably many branches. Also, by the proof, all the branches continue to have real rectifiable boundary.

In fact, if *C* is a branch of *R* at *x*, then $\partial(S \wedge C) \sqcup \{x\} \neq 0$ for some normal $S \leq R$, because otherwise *C* would be a disjoint component of *R* in \mathbb{R}^m already. If *R* contains no circuit, then actually $\partial C(x) \neq 0$. Otherwise, similarly to the proof of Lemma 3.17, we could construct edges $E_1 \leq S' \leq C$ and $E_2 \leq C - S'$ connecting *x* and some $y_1, y_2 \in \operatorname{img} \partial C \setminus \{x\}$, and then form a circuit and a contradiction by connecting these points.

The next two lemmas are intuitively clear, but demand proof due to our abstract current-based definitions of the concepts involved.

LEMMA 3.18 Suppose R is connected, contains no circuit, and x_1 is a cut point of R. Then $x_2 \neq x_1$ is a cut (resp. branch) point of R if and only if it is a cut (resp. branch) point of one of the branches of R at x_1 .

Proof. Let C_i , i = 1, 2, ..., be the connected components of R in $V \triangleq \{x_1, x_2\}^c$. Again by Lemma 3.16, there are at most countably many of them. Let C_k , k = 1, 2, be the collection of those C_i that remain disjoint components of R in $\{x_k\}^c$. Since $C \in C_k$ is connected in V, it is connected in $\{x_k\}^c$ by Lemma 3.7. Therefore, $C \in C_k$ is a branch of R at x_k . Since R has no circuit and is real rectifiable, Lemma 3.17 shows that there is at most one index j such that $C_j \notin C_1 \cup C_2$.

Fix $k \in \{1, 2\}$ and let ℓ be the other element. Since R is normal, $\sum_{C \in C_k} C$ and $B_k \triangleq C_j + \sum_{C \in C_\ell} C = R - \sum_{C \in C_k} C$ decompose R into disjoint components in $\{x_k\}^c$; cf. Remark 3.6. B_k is also connected: any disjoint component A of B_k must be a disjoint component of R in $\{x_k\}^c$ by Lemma 3.4, as well as in V by Lemma 3.7. By the latter, A is a sum of $C \in C_\ell$ and C_j , which contradicts the former unless $A = B_k$ or A = 0. Since R was connected, B_k is a branch of R at x_k , as are $C \in C_k$.

Finally, $C \in C_{\ell}$ is a branch of B_k at x_{ℓ} , as is C_j . To see this, first observe that according to the previous paragraph, these are not disjoint components of B_k in \mathbb{R}^m . Secondly, observe that $C = C \wedge B_k$ is a disjoint component of B_k in $\{x_\ell\}^c$, being a disjoint component of R in $\{x_\ell\}^c$; cf. Remark 3.2. The same must hold of $C_j = B_k - \sum_{C \in C_\ell} C$. As these subcurrents are connected in $\{x_\ell\}^c$, we have shown the claim: to every branch at x_ℓ of R, there corresponds a branch of B_k at x_ℓ , while B_k is a branch of R at x_k .

LEMMA 3.19 Suppose R is connected with no circuits and no branch points. Then

- (i) At most two points of img ∂R are non-cut points.
- (ii) The points of img ∂R can be given a total order \prec satisfying: if A_1 and A_2 are the branches of R at a cut point $x \in \operatorname{img} \partial R$, then with either (i, j) = (1, 2) or (i, j) = (2, 1), we have $y \prec x$ for all $y \in \operatorname{img} \partial A_i$, and $x \prec z$ for all $z \in \operatorname{img} \partial A_i$.

Proof. (i) Suppose there are three non-cut points $a, b, c \in \operatorname{img} \partial R$. For each of these points, x = a, b, c, there would exist a connection $\mathcal{E}_x = \{(\tau_{x,i}, E_{x,i})\}_{i=1}^{n_x}$ in $\{x^c\}$ between the other two points. Here $\tau_{x,i} = \pm 1$ is the direction of the edge $E_{x,i}$. We may assume all the connections to have equal strength. We claim that $\mathcal{E} \triangleq \mathcal{E}_a \cup \mathcal{E}_b \cup \mathcal{E}_c$ would form a circuit in R.

By rectifiability and the finite number of edges in \mathcal{E} , we may, similarly to the proof of Lemma 3.11, assume that any edges with a non-zero intersection are equal, and that each edge occurs at most once in each of the connections \mathcal{E}_x , x = a, b, c. Note that $\sum_{(\tau, E) \in \mathcal{E}} \tau \partial E = 0$. Therefore, if the edges do not form a circuit, $\sum_{E \in \mathcal{E}} \tau_E E = 0$. Thus, positively weighted edges correspond exactly to negatively weighted edges: each edge occurs exactly twice; once in two of the three connections, with different direction.

Now, take, e.g., x = a. If there are two distinct edges in \mathcal{E} (disregarding direction) with x as a boundary point, then set w = x. Otherwise, disregard both copies of the sole edge E with x as a boundary point, and continue with x as the other boundary point of E. By repeating the process, eventually distinct edges and $w \neq b$, c must be found, to reach both b and c. Now, some of the remaining edges of \mathcal{E} form a connection between b and c and from a, passing through w. Therefore, if there exists a connection between any two of the points a, b, c in $\{w\}^c$, a circuit is found. If this does not happen, there must exist at least two connected components of R in $\{w\}^c$, i.e., w is a cut point in contradiction to our assumptions.

(ii) If there are only two points in img ∂R , they must both be non-cut points, and can be ordered arbitrarily.

Assume then that there are more than two points, and exactly one non-cut point $x_0 \in \operatorname{img} \partial R$. Let $x \in \operatorname{img} \partial R$ be a cut point, with A and B the branches of R at x. Since $\partial A_{\perp} \{x\}^c$ and $\partial B_{\perp} \{x\}^c$ split ∂R , we may assume that $x_0 \in \operatorname{img} \partial A$, possibly after replacing the roles of A and B. We then declare $y \prec x$ for all $y \in \operatorname{img} \partial A$.

Suppose that $y \neq x, x_0$. By Lemma 3.18, y is a cut boundary point of A. Let A_y and B_y be the branches of A at y, ordered so that $x_0 \in \operatorname{img} \partial A_y$ and $x \in \operatorname{img} \partial B_y$. This is doable by (i), as x and x_0 remain non-cut boundary points of either A_y or B_y , and y is by definition a non-cut boundary point of both. Now note that $B_y + B$ is edge-connected (via x), so $A_y \leq A$ and $B_y + B$ are the branches of R at $y \prec x$. This shows antisymmetry and transitivity of the relation \prec . Totality follows analogously by considering $y \in \operatorname{img} \partial B$.

If there is another non-cut boundary point x_1 of R, we set $x \prec x_1$ for all $x \in \operatorname{img} \partial R$, noting that we cannot have $x_1 \in \operatorname{img} \partial A$, i.e., $x_1 \prec x$, for any $x \in \operatorname{img} \partial R \setminus \{x_1\}$. For, otherwise all x_0, x_1 , and x would be non-cut boundary points of A, in contradiction to (i).

Finally, if there are no non-cut boundary points of R, we take some cut boundary point, apply the above process to the halves obtained that way, and combine the results, reversing the order on the other half.

4. Optimal networks

4.1 The problem

Given a signed measure $\mu = \mu^+ - \mu^-$ with compact support and $\mu^+(\mathbb{R}^m) = \mu^-(\mathbb{R}^m) < \infty$, we consider the problem

$$\min_{\Theta(W+R)=\mu} J(W,R), \quad J(W,R) \triangleq J_W(W) + J_R(R), \tag{P}$$

where W and R are one-dimensional real flat chains of finite mass. We assume that J_W is

subadditive:

$$J_W(W_1 + W_2) \leqslant J_W(W_1) + J_W(W_2),$$
 (A-S)

and J_R is strictly "quasi-concave on circuits":

$$\min\{J_R(R+C_1-C_2), J_R(R-C_1+C_2)\} < J_R(R)$$
(A-C)

whenever (C_1, C_2) is a circuit of R. To ensure a (real) rectifiable set of stations, we also assume

$$J_R(R) < \infty$$
 implies that ∂R is real rectifiable and R normal. (A-N)

Then both W and R are actually normal currents. In fact, R is real rectifiable and acyclic, i.e., $R \in \mathcal{R}^*$, as shown by Lemma 4.1 below.

By further assumptions on J_R , our plan is to show that the number of stations is actually finite, and consequently R is a Lipschitz image of a polyhedral current. These assumptions take the form

$$J_W(B) + J_R(R - B) < J_R(R)$$
 when $B \in \mathcal{B}$, (A-D)

for a varying set \mathcal{B} . Combining with (A-S) it then follows that J(W + B, R - B) < J(W, R), so that decrease is achieved while maintaining the constraint $\partial(W + R) = \mu$.

4.2 Circuits and rectifiability

The pair (W, R) of finite mass real flat chains is said to be *finitely optimal* if it solves (P) and $J(W, R) < \infty$. The same is said of just R if this holds with some W.

LEMMA 4.1 Any finitely optimal R contains no circuit and is real rectifiable. Thus $R \in \mathcal{R}^*$.

Proof. Clearly (A-C) and optimality exclude circuits, since $\partial R' = \partial R$ if $R' \triangleq R \pm (C_1 - C_2)$ and (C_1, C_2) is a circuit of R.

Since *R* contains no circuit, it is also acyclic (choose $C_2 = 0$). Therefore, we may use the representation (2.2) by transport measures, $R = [\![\eta]\!]$.

By (A-N), $\partial R = \sum_{i=1}^{\infty} \alpha_i \delta_{x_i}$ for some $\alpha_i \in \mathbb{R}$ and $x_i \in \mathbb{R}^m$. Therefore, for some pairs (i, j), there is a set $\Gamma^{ij} \subset \text{supp } \eta$ of non-zero η -measure of transport paths between x_i and x_j . According to Lemma 3.10, $\eta \sqcup \Gamma^{ij}$ is concentrated on a singleton $\{\gamma^{ij}\}$. Because there are at most countably many paths γ^{ij} (modulo equivalent parametrisations) corresponding to different pairs (i, j), R must be real rectifiable.

REMARK 4.1 Even if $R = [\![\eta]\!]$ is real rectifiable with real rectifiable boundary, η may not be concentrated on a countable set if R contains a circuit. Just consider the acyclic current on the sides of the unit rectangle, with boundary points of mass ± 1 at some of the two opposing corners. If copies scaled to 2^{-i} (i = 1, 2, ...) of the side length (but preserving boundary mass) are chained together at their opposing corners, one obtains a normal real rectifiable current with two boundary points that have $2^{\mathbb{N}}$, i.e., uncountably many possible paths between them.

4.3 Connected components

LEMMA 4.2 Suppose (A-D) holds for some $\beta > 0$ with

 $\mathcal{B}_{disi}^{\beta} \triangleq \{B \text{ is a disjoint component of } R \text{ with } \mathbb{M}(\partial B) \leq \beta \}.$

Then any finitely optimal R consists of finitely many connected components.

Proof. By Lemma 3.16, *R* is the sum of at most countably many connected components $\{R_i\}_{i=1}^{\infty}$. Since $\sum_{i=1}^{n} \partial R_i \subset \partial R$ for all finite subcollections, we have

$$\sum_{i=1}^{n} \mathbb{M}(\partial R_{i}) \leq \sum_{i=1}^{n} (\mathbb{M}(\partial R) - \mathbb{M}(\partial R - \partial R_{i}))$$
$$\leq \mathbb{M}(n\partial R) - \mathbb{M}\left(n\partial R - \sum_{i} \partial R_{i}\right) \leq \mathbb{M}\left(\sum_{i} \partial R_{i}\right) \leq \mathbb{M}(\partial R).$$

Thus $\limsup_{i\to\infty} \mathbb{M}(\partial R_i) = 0$. Consequently $\mathbb{M}(\partial R_i) < \beta$ for suitably large *i*, and an application of (A-D) yields a contradiction to optimality.

4.4 Branching

LEMMA 4.3 Suppose (A-D) holds for some $\beta > 0$ with

$$\mathcal{B}_{\text{disj},x}^{\rho} \triangleq \{B \text{ is a disjoint component of } R \text{ in } \{x\}^{c} \text{ with } \mathbb{M}(\partial B) \leq \beta \mid x \in \mathbb{R}\}.$$

If (W, R) is optimal and $J(W, R) < \infty$, then each connected component of R has finitely many branch points, each with finitely many branches.

Proof. Let *T* be a connected component of *R*. Let us denote the branch points of *T* by *X*. Choose some $x \in X$, and let $\{T_i\}_{i \in I}$ be the branches of *T* at *x*. Set $X' = \{x\}$. Then proceed recursively as follows.

Let $X'(T_i) \subset X'$ denote the smallest subset such that T_i remains a disjoint component of T in $(X'(T_i))^c$. Such a set exists, for if there are two contenders, finiteness of the sets $(\mu_T(X') = 0)$ and the definition of disjointness establishes that the intersection satisfies the requirements of Definition 3.2 as well. Let $I_x \subset I$ denote the indices i such that $X'(T_i) = \{x\}$, i.e., T_i is a branch of T at x (as is the case on the first iteration). If for some $i \in I_x$ we had $\mathbb{M}(\partial T_i) < \beta$, an application of (A-D) to $B = T_i$ would show that the cost J can be reduced. Therefore $\mathbb{M}(\partial T_i) \ge \beta$ for all $i \in I_x$. But $\sum_{i \in I_x} \mathbb{M}(\partial T_i) \le \sum_{i \in I_x} 2\mathbb{M}(\partial T_i \sqcup \{x\}^c) \le 2\mathbb{M}(\partial T \sqcup \{x\}^c) \le 2\mathbb{M}(\partial R) < \infty$. This implies that I_x is finite.

Note that according to Lemma 3.17, since *R* contains no circuit by Lemma 4.1, if $x' \in X' \setminus \{x\}$, then $x' \in X'(T_j)$ for at most one branch. Since X' is finite, there can thus only be finitely many branches T_i , $i \in I \setminus I_x$, that are not branches of *T* at *x*. Thus *I* is finite, which shows the second half of the claim of the lemma. For the first half, assume to the contrary that X is infinite. Then one of the branches, say T_j , continues to have infinitely many points of $X \setminus X'$ as its branch points, by Lemma 3.18.

Update $\tilde{T} \triangleq T_j$, and let \tilde{X} be the branch points of T that remain branch points of \tilde{T} . Choose a new point $\tilde{x} \in \tilde{X} \setminus X'$, and update also $\tilde{X}' \triangleq X'(\tilde{T}) \cup {\tilde{x}}$.

If there is at least one branch T_i distinct from \tilde{T} , such that $X'(T_i) = \{x\}$, then $\mathbb{M}(S) \ge \beta/2$ for $S \triangleq \partial T_i \sqcup \{x\}^c \le \partial T \le \partial R$. Therefore, by iterating the above arguments with $(T, X, X', x) \triangleq (\tilde{T}, \tilde{X}, \tilde{X}', \tilde{x})$, eventually a discardable low-mass branch must be found, violating the optimality of (W, R).

If it however happens that all the other branches have $X'(T_i) \supseteq \{x\}$, then $\#\tilde{X}' < \#X'$, as at least two points of X' are not contained in $X'(\tilde{T})$. This is due to Lemma 3.17 and x being a branch point of T, whence there are at least two branches other than \tilde{T} . Consequently, since X' is finite, this case can only happen finitely many times in uninterrupted sequence.

LEMMA 4.4 Let $B \triangleq \{x \in \mathbb{R}^m \mid x \text{ is a branch point of } R\}$. Then, under the assumptions of Lemma 4.3, every connected component of R in B^c has exactly two non-cut boundary points and no branch points.

Proof. Let *C* be one of the connected components of *R* in B^c . It has no circuits, by Lemma 4.1, and no branch points, by Lemma 3.18. Therefore, by Lemma 3.19(i), *C* has at most two non-cut boundary points. If *C* has finitely many cut boundary points, it must have exactly two non-cut boundary points. To see this, cut *C* into two halves at one of its cut boundary points *x*. If *C* has fewer than two non-cut boundary points, one of the halves will have at most *x* as a non-cut boundary point. Recursively continuing the process on this half until all the finitely many cut boundary points have been exhausted (recall Lemma 3.18) will yield a current with fewer than two boundary points. This is not possible by acyclicity and compact support.

Suppose then that *C* has countably many cut boundary points. Every $x \in B$ is a non-cut point, so at most two of them can be boundary points. If we denote this set by B_C , then *C* is a disjoint component of *R* in $(B_C)^c$. If B_C has at least two elements, we are done, so assume that it has fewer than two elements.

If y is a cut boundary point of C, then one of the branches, A, of C at y will be a disjoint component of R in $\{y\}^c$ by Lemma 3.17. If $\mathbb{M}(\partial A) < \beta$, then according to (A-D), cutting away A would improve cost. To reach a contradiction, it remains to choose y appropriately. This can be done by ordering the cut boundary points in a sequence y_1, y_2, \ldots , and choosing K to achieve $\sum_{i=K+1}^{\infty} |C(y_k)| < \beta$. Then we take $y \in Y \triangleq \{y_1, \ldots, y_K\}$ to be a minimal or maximal point of $Y \cup B_C$, in the order of Lemma 3.19(ii).

4.5 Finiteness

We finally show that there are actually only finitely many stations under certain assumptions.

LEMMA 4.5 Suppose (A-D) holds in either of the cases:

(i) For a given $\delta > 0$, with some $g : (0, \infty) \to (0, \infty)$ and

$$\mathcal{B}_{\text{seg}}^{\delta,g} = \{\partial R(y) \llbracket x, y \rrbracket \mid x, y \in \text{img} \, \partial R; \ y \in B(x,\delta); \ |\partial R(y)| \leqslant g(|\partial R(x)|)\}.$$

(ii) With $\mathcal{B}_{\text{disi},x}^{\beta}$ for some $\beta > 0$, and for some $g : (0, \infty) \to (0, \infty)$ and given $M, \theta > 0$ with

$$\mathcal{B}_{\text{conn}}^{M,\theta,g} = \left\{ \partial R(y)C \mid \begin{array}{l} x, y \in \text{img}\,\partial R; \ \theta C_1, \theta C_2 \leqslant R; \ C \triangleq C_1 - C_2\\ \partial C = \delta_y - \delta_x; \ \mathbb{M}(C) \leqslant M; \ |\partial R(y)| \leqslant g(|\partial R(x)|) \end{array} \right\}$$

Then the set img ∂R is finite if (W, R) is finitely optimal.

Proof. Write $m_x \triangleq \partial R(x)$. Under the assumption that R and then ∂R are supported on a compact set, the claims follow in both cases by showing that in a suitable fixed neighbourhood of each station $m_x \delta_x$, there can be only finitely many other stations $m_y \delta_y$. This in turn follows from showing that there is a lower limit on $|m_y|$ in this neighbourhood, since there can be only finitely many stations of greater mass.

(i) In this case, we may simply lay new track to fuse nearby stations. Given $\delta > 0$, finitely many balls $B(x, \delta)$ with $x \in \operatorname{img} \partial R$ cover $\operatorname{img} \partial R$. So suppose $y \in B(x, \delta)$ with $|m_y| \leq g(|m_x|)$. Then, by (A-D) and our assumptions, $J(W + m_y[x, y], R - m_y[x, y]) < J(W, R)$, yielding a contradiction to optimality.

(ii) Note that (A-D) holding for $\mathcal{B}_{\text{disj}}$ follows from it holding for $\mathcal{B}_{\text{disj,x}}$, thanks to the compact support of *R*. Therefore, *R* has finitely many connected components (in \mathbb{R}^m) by Lemma 4.2. By Lemma 4.3, each of them has finitely many branch points with finitely many branches. Therefore, if $\{R_i\}_{i=1}^{\infty}$ are the connected components of *R* in B^c , then at most finitely many of them are disjoint in \mathbb{R}^m or $\{x\}^c$ for *x* in *B*, the set of branch points of *R*. An application of Lemma 3.17 then shows that *R* can actually have only finitely many connected components R_1, \ldots, R_N in B^c . By Lemma 4.4, each R_i has no branch points, and exactly two non-cut boundary points $x_{i,0}$ and $x_{i,1}$.

Fix *i*, and let $E_1, \ldots, E_n \leq R_i$ be the connection between $x_{i,0}$ and $x_{i,1}$. Denote its strength by θ_i , and the traversal directions of the edges by $\tau_j = \pm 1$.

Let x and y be distinct cut boundary points of R_i . By Lemma 3.18, R_i decomposes into three connected components A, B_0 and B_1 in $\{x, y\}^c$, with A the unique one that is not a disjoint in $\{x\}^c$ or $\{y\}^c$, and $x_{i,j} \in \text{img } \partial B_j$, j = 0, 1. Then $E'_j \triangleq A \wedge E_j$ is a (possibly zero) edge in A. We cannot have $E'_i = 0$ for all *i*, because otherwise a circuit could be found by combining $E_1, \ldots, E_n \leq B_0 + B_1$ with connections of suitable pairs of x, y, $x_{i,0}$, and $x_{i,1}$ in A, B_1 , and B_2 . Likewise, we cannot have $E_i \wedge B_j = 0$ for all *i* for any j = 0, 1. Therefore, since x or y is in $\text{img } \partial E'_j$ whenever $0 \neq E'_j \neq E_j$, and the edges E'_j cannot form a circuit, we must have $x \in \text{img } \partial E'_i$ and $y \in \text{img } \partial E'_j$ for some $i, j \in \{1, \ldots, n\}$. Thus E'_1, \ldots, E'_n must form a connection between x and y. Let $C_1 = \sum_{\tau_j = \pm 1} E'_j / \theta_i$, $C_2 = \sum_{\tau_j = \mp 1} E'_j / \theta_i$, and $C = C_1 - C_2$, with the directions/signs

Let $C_1 = \sum_{\tau_j=\pm 1} E'_j/\theta_i$, $C_2 = \sum_{\tau_j=\mp 1} E'_j/\theta_i$, and $C = C_1 - C_2$, with the directions/signs summed over chosen in the order that achieves $\partial C = \delta_y - \delta_x$. Then $\mathbb{M}(C) \leq M_i \triangleq \sum_{j=1}^n \mathbb{M}(E_j)/\theta_i$, while $M_i \leq M \triangleq \max_{i=1,...,N} M_i$, and $\theta_i \geq \theta \triangleq \min_{i=1,...,N} \theta_i$. But then, by (A-D) and our assumptions, we have the contradiction $J(W + m_y C, R - m_y C) < J(W, R)$, provided $|m_y| < g(|m_x|)$.

The results of this section are summarised in the following theorem. To actually show the existence of a solution, it is more convenient to work with more specific objective functions. This is done in the next section.

THEOREM 4.1 Suppose the assumptions (A-S), (A-C), and (A-N) hold and that (A-D) holds with appropriate parameters for either (i) $\mathcal{B}_{\text{disj},x}^{M,\theta,g}$ and $\mathcal{B}_{\text{conn}}^{\beta}$, or (ii) $\mathcal{B}_{\text{seg}}^{\beta}$. Then any finitely optimal *R* is a Lipschitz image of a polyhedral current with no circuit.

Proof. By combining the above lemmas, *R* is real rectifiable, and has no circuit, while ∂R is finite. By considering $R = [\![\eta]\!] = \sum_{i=1}^{s} \sum_{j=1}^{d} \alpha_{ij} [\![\gamma_{ij}]\!]$, we find a finite collection of Lipschitz paths on which *R* is concentrated. This says that *R* is a Lipschitz image of a polyhedral current.

5. Weighted areas

5.1 Definitions and basic results

Let \mathcal{W} denote the set of non-decreasing concave functions $[0, \infty) \to [0, \infty)$ that take the value 0 at the origin. Such functions are subadditive as well. We symmetrically extend them to all of \mathbb{R} for convenience of notation. Throughout the section, $w, r, s \in \mathcal{W}$. We write $w \preccurlyeq r$ if $r \neq 0$ and for some $\tau > 0, w/r$ is a non-decreasing function in $(0, \tau)$ (and thus has a limit from the right at zero). If actually $\lim_{t \to 0} w(t)/r(t) = 0$, we write $w \preccurlyeq r$.

The identity function is denoted by id : $t \mapsto t$. Note that id $\leq r$ with $\tau = \infty$ for all $r \in W$ not identically zero (as follows from $0 \leq r'(t) \leq r(t)/t$ and $r(s) - r(t) \leq r'(t)(s - t)$, $s \geq t$). Other

important examples of functions in \mathcal{W} include $t \mapsto t^{\alpha}$ for $\alpha \in [0, 1)$ (with the convention $0^0 = 0$). If $\alpha < \beta$, then $t^{\beta} < t^{\alpha}$ with $\tau = \infty$.

Given a weight function $r \in W$, we define the *r*-mass of a *k*-dimensional real rectifiable current $T = [\![\Sigma]\!]_{\perp} \theta$ as

$$\mathbb{M}^r(T) \triangleq \int_{\Sigma} r(\theta) \, \mathrm{d}\mathcal{H}^k.$$

 \mathbb{M}^r is lower-semicontinuous on real rectifiable currents with regard to convergence in the Whitney flat distance \mathbb{F} (as follows similarly to the proof for (integer) rectifiable currents by De Pauw and Hardt [10] according to Paolini and Stepanov [14]). It may therefore be extended to a lowersemicontinuous function on the set of flat chains by taking the infimum of $\liminf \mathbb{M}^r(T_i)$ over all approximating sequences. According to White [15, 6], one could equally well use polyhedral currents in the approximating sequence. Clearly \mathbb{M}^r is also subadditive for real rectifiable T_1 and T_2 , i.e., $\mathbb{M}^r(T_1 + T_2) \leq \mathbb{M}^r(T_1) + \mathbb{M}^r(T_2)$, and otherwise the property follows by approximation.

LEMMA 5.1 Suppose id $\prec r$ and T is a flat chain with $\mathbb{M}(T) + \mathbb{M}^r(T) < \infty$. Then T is real rectifiable. If T is 0-dimensional and $r(\infty -) \triangleq \lim_{t\to\infty} r(t) = \infty$, then automatically $\mathbb{M}(T) \leq r^{-1}(\mathbb{M}^r(T))$, so it suffices to have $\mathbb{M}^r(T) < \infty$.

Proof. Since *r* increases at 0 faster than any linear function, there is no continuous non-constant curve of finite length when the distance between two points is given by $(x, y) \mapsto (id+r)(||x-y||)$. Thus the results of White [16, 8] show the rectifiability of *T*.

In the case that *T* is 0-dimensional with $\mathbb{M}^r(T) < \infty$, approximate *T* in \mathbb{F} by real rectifiable currents $T_k = \sum_{i=1}^{n_k} \alpha_{k,i} \delta_{x_{k,i}}$ with $\mathbb{M}^r(T_k) \to \mathbb{M}^r(T)$. Then $r(\mathbb{M}(T_k)) = r(\sum_i |\alpha_{k,i}|) \leq \sum_i r(\alpha_{k,i}) = \mathbb{M}^r(T_k)$. But $\mathbb{M}(T) \leq \liminf \mathbb{M}(T_k)$ and *r* is continuous and non-decreasing, whence $\mathbb{M}(T) \leq r^{-1}(\mathbb{M}^r(T)) < \infty$.

The next two lemmas adapt results of [14].

LEMMA 5.2 Suppose T is a real rectifiable current with $\mathbb{M}(T) < \infty$. Let $F(\sigma) \triangleq \mathbb{M}^r(T \sqcup \sigma)$ for $\sigma \in K \triangleq \{\sigma : \mathbb{R}^m \to [0, \infty) \mid \sigma \text{ Borel }\}$. Then F is concave on K.

In particular, if $\tilde{\sigma} : \mathbb{R}^m \to [-1, 1]$ is Borel, then $f(t) \triangleq F(1 + t\tilde{\sigma})$ is concave for $t \in [-1, 1]$, strictly if $T \llcorner \tilde{\sigma} \neq 0$ and r is strictly concave.

Proof. Since $T = \llbracket \Sigma \rrbracket \sqcup \theta$ and $T \sqcup \sigma = \llbracket \Sigma \rrbracket \sqcup (\sigma \theta)$, we get

$$\begin{split} \lambda F(\sigma) + (1-\lambda)F(\sigma') &= \int_{\Sigma} (\lambda r(\sigma\theta) + (1-\lambda)r(\sigma'\theta)) \, \mathrm{d}\mathcal{H}^k \\ &\leqslant \int_{\Sigma} r((\lambda\sigma + (1-\lambda)\sigma')\theta) \, \mathrm{d}\mathcal{H}^k = F(\lambda\sigma + (1-\lambda)\sigma'). \end{split}$$

Clearly, if r is strictly concave, then the inequality is strict for $\lambda \in (0, 1)$ unless $\theta \sigma = \theta \sigma' \mathcal{H}^k \bot \Sigma$ a.e. In the case of f this means $\tilde{\sigma} = 0$ a.e. for $\mu_T = \theta \mathcal{H}^k \bot \Sigma$, so the claim follows.

LEMMA 5.3 Suppose T is an acyclic one-dimensional real rectifiable normal current. If $w \leq r$ with non-decrease threshold τ , and $\mathbb{M}(\partial T)/2 \leq \tau$, then

$$\mathbb{M}^{w}(T) \leqslant \mathbb{M}^{r}(T) \bigg[\frac{w}{r} (\mathbb{M}(\partial T)/2) \bigg].$$
(5.1)

If $\tau = \infty$ and $(w/r)(\infty -) = \infty$, then it suffices to assume that T is an acyclic one-dimensional real rectifiable current of finite mass and compact support.

Proof. Clearly, if $(w/r)(\infty -) = \infty$, then (5.1) holds whenever $\mathbb{M}(\partial T) = \infty$, so we may assume $\mathbb{M}(\partial T) < \infty = \tau$, and the special case reduces to the generic one. We may also assume that $\mathbb{M}(\partial T) = 0$, as otherwise T = 0, and there is nothing to prove.

We have the expression $T = [\![\Sigma]\!]_{L}\theta$, where Σ is a rectifiable set. According to [14, Lemma 7.1 & Theorem 7.3], $\theta \leq \mathbb{M}(\partial T)/2 \mathcal{H}^1$ -a.e. Thus, because $\mathbb{M}(\partial T)/2 \leq \tau$ by assumption, we find

$$\mathbb{M}^{w}(T) = \int_{\Sigma} w(\theta) \, \mathrm{d}\mathcal{H}^{1} \leqslant \int_{\Sigma} \frac{w(\mathbb{M}(\partial T)/2)}{r(\mathbb{M}(\partial T)/2)} r(\theta) \, \mathrm{d}\mathcal{H}^{1} = \mathbb{M}^{r}(T) \bigg[\frac{w}{r} (\mathbb{M}(\partial T)/2) \bigg]. \qquad \Box$$

The next lemma provides a variant of standard approximation results, employing $\mathbb{M}^r(T)$ instead of $\mathbb{M}(T)$, and with preservation of rectifiable boundary.

LEMMA 5.4 Suppose $0 < r'(0) < \infty$, *T* is a one-dimensional real flat chain with compact support, and $\mathbb{M}^{r}(T) + \mathbb{M}(\partial T) < \infty$. Then, given $\epsilon > 0$, there exists a normal real rectifiable current *T'* with real rectifiable boundary, supp $T' \subset \text{conv} \text{supp } T + B(0, \epsilon)$, $\mathbb{M}(\partial T') \leq \mathbb{M}(\partial T) + \epsilon$, $\mathbb{M}^{r}(T') \leq \mathbb{M}^{r}(T) + \epsilon$, and $\mathbb{F}(T' - T) \leq \epsilon/r'(0)$.

If $\phi \leq \partial T$ is real rectifiable, then we can take $\phi \leq \partial T'$. In particular, if ∂T is real rectifiable, then $\partial T' = \partial T$.

Proof. Take $\phi = 0$ if not given. Denote $K \triangleq \operatorname{conv} \operatorname{supp} T$, and $\overline{B} \triangleq B(0, \min\{\epsilon, 1\})$. Choose a sequence $\{T_i\}_{i=1}^{\infty}$ of polyhedral currents with $T_i \stackrel{\mathbb{F}}{\to} T$, $\operatorname{supp} T_i \subset K + \overline{B}/3$, and $\mathbb{M}^r(T_i) \leq \mathbb{M}^r(T) + \epsilon/3$. Then $\mathbb{F}(\partial T - \partial T_i) \leq \mathbb{F}(T - T_i) \leq C\epsilon/12$ for *i* sufficiently large and $C \triangleq 1/[r'(0)(\operatorname{diam} K + 2)]$. Also choose a sequence $\{\phi'_i\}_{i=1}^{\infty}$ of polyhedral 0-dimensional currents with $\phi'_i \stackrel{\mathbb{F}}{\to} \partial T - \phi$, $\operatorname{supp} \phi'_i \subset K + \overline{B}/3$, and $\mathbb{M}(\phi'_i) \leq \mathbb{M}(\partial T - \phi) + \epsilon$. For sufficiently large *i*, again $\mathbb{F}((\partial T - \phi) - \phi'_i) \leq C\epsilon/24$. Since ϕ is a sum of Dirac masses with $\mathbb{M}(\phi) < \infty$, we may also find a polyhedral $\phi' \leq \phi$ with $\mathbb{M}(\phi) \leq \mathbb{M}(\phi') + C\epsilon/24$.

Letting $\phi_i \triangleq \phi' + \phi'_i$, we find

$$\mathbb{F}(\partial T - \phi_i) \leq \mathbb{M}(\phi - \phi') + \mathbb{F}((\partial T - \phi) - \phi'_i) \leq C\epsilon/12$$

Therefore, $\mathbb{F}(\phi_i - \partial T_i) \leq C\epsilon/6$. Since ϕ_i and ∂T_i are polyhedral, this implies by [11, Lemma 4.2.23] the existence of a polyhedral current Q_i with

$$\mathbb{M}(\phi_i - \partial T_i - \partial Q_i) + \mathbb{M}(Q_i) \leqslant C\epsilon/4$$

and supp $Q_i \subset K + \overline{B}/2$,

Now, consider $\psi_i \triangleq \phi + \phi'_i - \partial T_i - \partial Q_i$. It is supported on $K + \overline{B}/2$, and

$$\mathbb{M}(\psi_i) + \mathbb{M}(Q_i) \leq \mathbb{M}(\phi - \phi') + \mathbb{M}(\phi_i - \partial T_i - \partial Q_i) + \mathbb{M}(Q_i) \leq C\epsilon/3.$$

Thus $\psi_i^+(\mathbb{R}^m) = \psi_i^-(\mathbb{R}^m) = \mathbb{M}(\psi_i)/2 < \infty$. Since ψ_i is also real rectifiable, i.e., a countable weighted sum of Dirac measures, we may construct a real rectifiable current R_i with $\partial R_i = \psi_i$ and $\mathbb{M}(R_i) \leq \mathbb{M}(\psi_i) \operatorname{diam}(K + \overline{B})$. By convexity of K, we can take supp $R_i \subset K + \overline{B}$. Letting

$$T_i' \triangleq T_i + Q_i + R_i,$$

we therefore have supp $T'_i \subset K + \overline{B}$ and $\partial T'_i = \phi + \phi'_i$, whence

$$\mathbb{M}(\partial T'_i) \leqslant \mathbb{M}(\phi) + \mathbb{M}(\phi'_i) \leqslant \mathbb{M}(\phi) + \mathbb{M}(\partial T - \phi) + \epsilon = \mathbb{M}(\partial T) + \epsilon$$

We also have $\mathbb{M}(T'_i) < \infty$ and, moreover, $\mathbb{M}^r(T'_i) \leq \mathbb{M}^r(T_i) + \mathbb{M}^r(Q_i) + \mathbb{M}^r(R_i)$ by subadditivity. But, since $r \leq r'(0)$ id and

$$Cr'(0) = 1/(\operatorname{diam} K + 2) \leq 1,$$
 (5.2)

we get

$$\mathbb{M}^{r}(Q_{i}) \leq \mathbb{M}(Q_{i})r'(0) \leq Cr'(0)\epsilon/3 \leq \epsilon/3,$$

and likewise,

$$\mathbb{M}^{r}(R_{i}) \leq \mathbb{M}(R_{i})r'(0) \leq Cr'(0)\operatorname{diam}(K+B)\epsilon/3 \leq \epsilon/3.$$

Thus $\mathbb{M}^{r}(T'_{i}) \leq \mathbb{M}^{r}(T) + \epsilon$, and, employing (5.2) twice, we obtain

$$\mathbb{F}(T'_i - T) \leq \mathbb{F}(T_i - T) + \mathbb{M}(Q_i) + \mathbb{M}(R_i) \leq C\epsilon/12 + C\epsilon/4 + (C\epsilon/3)\operatorname{diam}(K + \bar{B}) \leq \epsilon/r'(0).$$

We have the first part of our claim.

Finally, since ϕ is real rectifiable, i.e., a countable sum of Dirac masses, while ϕ'_i is a finite sum of Dirac masses, we may choose ϕ'_i while maintaining $\phi \leq \phi + \phi'_i$. Hence $\phi_i \leq \partial T'_i = \phi + \phi'_i$. \Box LEMMA 5.5 Suppose $r \neq 0$ and T is a one-dimensional normal current. Then there exists a normal

current T' with supp $T' \subset K \triangleq \text{conv} \text{ supp} T + B(0, 1), \ \partial T' = \partial T, \ \mathbb{M}^r(T') \leqslant \mathbb{M}^r(T)$, and

$$\mathbb{M}(T') \leqslant \mathbb{M}^{r}(T) \left[\frac{\mathrm{id}}{r} (\mathbb{M}(\partial T)/2) \right].$$
(5.3)

If id $\prec r$ and $\mathbb{M}^r(T) < \infty$, then $T' \leq T$ is real rectifiable and acyclic.

Proof. If $\mathbb{M}(\partial T) = 0$, we may choose T' = 0. Therefore, we may assume $\mathbb{M}(\partial T) > 0$ and $\mathbb{M}^r(T) < \infty$, for otherwise there is nothing to prove.

Recall that id/r is non-decreasing on all of $(0, \infty)$, so $\tau = \infty$. If $id \prec r$, then Lemma 5.1 implies that T is real rectifiable. We are therefore done after removing cycles from T, as can be done by [14, Proposition 3.12], and applying Lemma 5.3.

Otherwise $0 < r'(0) < \infty$, and we may choose $\epsilon \in (0, 1)$ and apply Lemma 5.4 to yield normal real rectifiable T_{ϵ} with supp $T_{\epsilon} \subset K$, $\mathbb{M}^{r}(T_{\epsilon}) \leq \mathbb{M}^{r}(T) + \epsilon$, $\mathbb{M}(\partial T_{\epsilon}) \leq \mathbb{M}(\partial T) + \epsilon$, and $\mathbb{F}(T_{\epsilon} - T) \leq \epsilon/r'(0)$. We remove cycles from T_{ϵ} and denote the result by T'_{ϵ} . As $\partial T'_{\epsilon} = \partial T_{\epsilon}$, still supp $T'_{\epsilon} \subset K$, $\mathbb{M}^{r}(T'_{\epsilon}) \leq \mathbb{M}^{r}(T) + \epsilon$, $\mathbb{M}(\partial T'_{\epsilon}) \leq \mathbb{M}(\partial T) + \epsilon$, and $\mathbb{F}(\partial T_{\epsilon} - \partial T) \leq \epsilon/r'(0)$.

By Lemma 5.3, we now have

$$\mathbb{M}(T_{\epsilon}') \leq \mathbb{M}^{r}(T_{\epsilon}') \left[\frac{\mathrm{id}}{r} (\mathbb{M}(\partial T_{\epsilon}')/2) \right] \leq (\mathbb{M}^{r}(T) + \epsilon) \left[\frac{\mathrm{id}}{r} ((\mathbb{M}(\partial T) + \epsilon)/2) \right].$$
(5.4)

Thus, $\mathbb{M}(T'_{\epsilon})$ is uniformly bounded as $\epsilon \searrow 0$, as is $\mathbb{M}(\partial T'_{\epsilon}) \leqslant \mathbb{M}(\partial T) + \epsilon$, and $\operatorname{supp} T'_{\epsilon} \subset K$. We may therefore take T' as the \mathbb{F} -limit of a subsequence of $\{T'_{\epsilon}\}$. Note that in addition to being non-decreasing, id/r is concave, hence continuous in $(0, \infty)$. Therefore, the property $\mathbb{M}(T') \leqslant \lim \inf_{\epsilon \searrow 0} \mathbb{M}(T'_{\epsilon})$ and (5.4) take care of (5.3). \Box

5.2 Instances of problem (P)

We now consider problem (P) in the setting

$$J_W(W) \triangleq \mathbb{M}^w(W), \quad J_R(R) \triangleq \mathbb{M}^r(R) + \mathbb{M}^s(\partial R) + H(\mathbb{M}^{r_H}(R) + \mathbb{M}^{s_H}(\partial R)), \quad (J-WA)$$

where $w, r, s, r_H, s_H \in \mathcal{W}$, and $H : [0, \infty) \to [0, \infty]$ is lower-semicontinuous and nondecreasing, satisfying $H(\infty -) = \infty$. We also write $J_R(R) = \tilde{J}_R(R) + H(J_H(R))$.

THEOREM 5.1 Suppose that (i) $w \neq 0$, (ii) either id $\prec s$ and $s(\infty -) = \infty$, or id $\prec s_H$ and $s_H(\infty -) = \infty$, and (iii) either id $\prec r$, or id $\prec r_H$. Then there exists a solution to the problem (P)&(J-WA) with W normal and $R \in \mathbb{R}^*$.

Proof. If there were no solution with finite J(W, R), we could take as W the solution of the (1-Wasserstein distance) Monge–Kantorovich problem for μ , and R = 0. (A normal solution W exists; cf., e.g., [1, 17].) So suppose (W_i, R_i) is a pair of real flat chains of finite mass such that $J(W_i, R_i) < \infty$ and $\partial(W_i + R_i) = \mu$.

By the assumptions (ii) on s (or s_H), $J_R(R_i) < \infty$ implies that ∂R_i is rectifiable with $\mathbb{M}(\partial R_i) < s^{-1}(\mathbb{M}^s(\partial R_i)) < \infty$ through Lemma 5.1. Since μ is assumed to have compact support, we may assume that R_i and W_i are supported for all i on some compact set K, employing a standard projection argument. Thus W_i and R_i are actually normal currents.

We consider the case id $\prec r$, the case id $\prec r_H$ being similar. By the assumptions (iii) and Lemma 5.5, we may replace R_i with real rectifiable and acyclic R'_i satisfying $\partial R'_i = \partial R$, $\mathbb{M}^r(R'_i) \leq \mathbb{M}^r(R_i)$ and $\mathbb{M}(R'_i) \leq \mathbb{M}^r(R_i) \left[\frac{\mathrm{id}}{r}(\mathbb{M}(\partial R_i)/2)\right] \leq C$ for some constant C > 0. Since in the present case id $\prec r$, actually $R'_i \leq R_i$ by the lemma, we also have $\mathbb{M}^{r_H}(R'_i) \leq \mathbb{M}^{r_H}(R_i)$. Likewise, by the assumption (i) and Lemma 5.5, we get W'_i with $\partial W'_i = \partial W_i$, $\mathbb{M}^w(W'_i) \leq \mathbb{M}^w(W_i)$, and $\mathbb{M}(W'_i) \leq \mathbb{M}^w(W_i) \left[\frac{\mathrm{id}}{w}(\mathbb{M}(\partial W_i)/2)\right] \leq C$. Consequently, $J(W'_i, R'_i) \leq J(W_i, R_i)$. Furthermore, by the lemma, supp W'_i , supp $R'_i \subset K + B(0, 1)$.

Thus, given a minimising sequence $\{(W_i, R_i)\}_{i=1}^{\infty}$ for (P)&(J-WA), we can find another minimising sequence $\{(W'_i, R'_i)\}_{i=1}^{\infty}$ with uniformly bounded mass, boundary mass, and support. Therefore, we can find a subsequence \mathbb{F} -convergent to some normal currents W and R, that must solve the problem (P) by the lower-semicontinuity of J with regard to \mathbb{F} -convergence. Furthermore, R and ∂R remain rectifiable, and R can be taken acyclic, by the same arguments as above.

REMARK 5.1 We do not require that *H* is concave and finite-valued, as do Paolini and Stepanov [14]; it might even be used to "cap the costs" to an interval [0, *M*]. The convergence proof here also differs from the base steps of the one in that paper, in that we do not impose rectifiability requirements on *W* (which is where Lemma 5.4 becomes useful), and we do not force $W, R \leq W + R$. Indeed, since the construction of stations can be relatively expensive for small amounts of traffic, one might have to "walk along the track" in the opposite direction.

By the above proof, by restricting the area of definition of J to enforce compact support, (A-N) can be taken to hold. Clearly (A-S) also holds since \mathbb{M}^w is subadditive. In the remainder of this section, we intend to show (A-C) and (A-D) under various assumptions on w, r, s, r_H, s_H , and H.

DEFINITION 5.1 r_H is compatible with r if $r_H(t) = Ar(t) + Bt^0$, $A, B \ge 0$.

LEMMA 5.6 Suppose $R \in \mathbb{R}^*$. Then (A-C) holds in the following cases:

(i) r is strictly concave, and r_H compatible with r.

(ii) r_H is strictly concave, r compatible with r_H , and H strictly increasing.

- (iii) r is strictly concave, and H concave.
- (iv) r_H and H are strictly concave.

Proof. (i) Suppose (C_1, C_2) is a circuit of R. Define $C \triangleq C_1 - C_2$. Then $C = R \llcorner \sigma$ for some Borel $\sigma : \mathbb{R}^m \to [-1, 1]$, so $R \pm C = R \llcorner (1 \pm \sigma)$. By Lemma 5.2 and the strict concavity of $r, f : t \in [-1, 1] \mapsto \mathbb{M}^r (R \llcorner (1 + t\sigma))$ is strictly concave. We therefore find that (f(-1) + f(1))/2 < f(0),

whence

$$\min\{\mathbb{M}^r(R+C), \mathbb{M}^r(R-C)\} \leqslant \frac{1}{2}(\mathbb{M}^r(R+C) + \mathbb{M}^r(R-C)) < \mathbb{M}^r(R)$$

Since $C_1, C_2 \leq R$, we have $\mathbb{M}^{t \mapsto t^0}(R \pm C) \leq \mathbb{M}^{t \mapsto t^0}(R)$. The compatibility assumption on r_H then ensures that the minimising choice cannot increase \mathbb{M}^{r_H} . Also $\partial R = \partial(R \pm C)$, so the boundary costs are unaffected. Thus J_R is improved by replacing R by one of $R \pm C$.

(ii) This case is analogous to case (i), this time applying Lemma 5.2 with r_H . Since H is strictly increasing, the decrease is transferred to J_R .

(iii) & (iv) In these cases $f : t \in [-1, 1] \mapsto J_R(R \llcorner (1 + t\sigma))$ is strictly concave by Lemma 5.2 and the concavity assumptions on *H*. A similar reasoning now shows the claim.

LEMMA 5.7 Suppose $R \in \mathcal{R}^*$ and $w \prec r$. Then there is a $\beta > 0$ such that (A-D) holds for $\mathcal{B}^{\beta}_{\text{disj}}$ and $\mathcal{B}^{\beta}_{\text{disj},x}$.

Proof. We first consider the case of $\mathcal{B}_{disj}^{\beta}$. Denote the non-decrease threshold of w/r by $\tau > 0$. By Lemma 5.3, if *B* is a disjoint component of *R* with $\mathbb{M}(\partial B)/2 < \tau$ and $(w/r)(\mathbb{M}(\partial B)/2) \leq 1$, then $\mathbb{M}^w(B) \leq \mathbb{M}^r(B) \left[\frac{w}{r}(\mathbb{M}(\partial B)/2)\right] < \mathbb{M}^r(B)$. Thus, by disjointness of $B \leq R$ and R - B, $M^w(B) + \mathbb{M}^r(R - B) < \mathbb{M}^r(R)$. Since $\partial B \leq \partial R$, we have $\mathbb{M}^s(\partial R - \partial B) \leq \mathbb{M}^s(\partial R)$. Thus $J_W(B) + \tilde{J}_R(R - B) < \tilde{J}_R(R)$. We likewise get $J_H(R - B) \leq J_H(R)$, since in this case just w = 0. Therefore, $J_W(B) + J_R(R - B) < J_R(R)$, so (A-D) holds.

Let now *x* be a cut point. If *B* is a disjoint component of *R* in $\{x\}^c$, then the above estimates hold except possibly for *s* and s_H . To show that the costs do not increase, note that subtracting ∂B from ∂R adds mass only at *x* while all mass is removed from other points of img ∂B , since ∂B and $\partial(R - B)$ split ∂R in $\{x\}^c$. The mass removed is in total at least as much as that added at *x*, because $|B(x)| \leq (\partial B)^{\pm}(\mathbb{R}^m) = \mathbb{M}(\partial B)/2$. Therefore, if $\partial B = \sum_{y \in Y} m_y \delta_y$, then $\mathbb{M}^s(\partial R - \partial B) - \mathbb{M}^s(\partial R) \leq s(m_x) - \sum_{y \in Y \setminus \{x\}} s(|m_y|) \leq s(|m_x|) - s(\sum_{y \in Y \setminus \{x\}} |m_y|) \leq 0$. An analogous estimate holds for s_H .

The next two lemmas ensure the conditions of the cases of Lemma 4.5.

LEMMA 5.8 Suppose $R \in \mathcal{R}^*$, $w, r \prec s$, and $r_H \prec s_H$ (or $r_H = s_H = 0$). Then, given $\delta > 0$, there is a $g : (0, \infty) \to (0, \infty)$ such that (A-D) holds for $\mathcal{B}_{seg}^{\delta, g}$.

Proof. Let $x, y \in \operatorname{img} \partial R$ with $||x - y|| \leq \delta$. Write $m \triangleq \partial R(x)$ and $t \triangleq \partial R(y)$. Then

$$J_W(t[x, y]) + \tilde{J}_R(R - t[x, y]) - \tilde{J}_R(R)$$

$$\leq \mathbb{M}^w(t[x, y]) + \mathbb{M}^r(t[x, y]) + \mathbb{M}^s((m+t)\delta_x) - [\mathbb{M}^s(m\delta_x) + \mathbb{M}^s(t\delta_y)]$$

$$= ||x - y||(w(t) + r(t)) + s(m+t) - s(m) - s(t).$$

This value is dominated from above by

$$f(t) \triangleq \delta(w(t) + r(t)) + s(m+t) - s(m) - s(t).$$

= $s(m+t) - s(m) - s(t) \left[1 - \delta \frac{w(t) + r(t)}{s(t)} \right]$

Now, since $w, r \prec s$ and $m \neq 0$, $f(t)/t \rightarrow s'(m) - s'(0) = -\infty$ as $t \searrow 0$. Therefore, f(t) < f(0) = 0 for $t \in (0, \tilde{g}(m))$ and some $\tilde{g}(m) > 0$.

Similar estimates hold for $J_H(R - t[x, y]) - J_H(R)$, yielding threshold $g_H(m)$. Therefore, we get the claim with $g(m) = \min\{\tilde{g}(m), g_H(m)\}$.

LEMMA 5.9 Suppose $R \in \mathcal{R}^*$ and $w \prec s$. Then, given $M, \theta > 0$, there is a $g : (0, \infty) \to (0, \infty)$ such that (A-D) holds for $\mathcal{B}_{\text{conn}}^{M,\theta,g}$.

Proof. With the notation of Lemmas 5.8 and 4.5,

$$J_W(tC) + J_R(R - tC) - J_R(R)$$

$$\leq \mathbb{M}^w(tC) + \mathbb{M}^r(R - tC) - \mathbb{M}^r(R) + \mathbb{M}^s((m+t)\delta_x) - \mathbb{M}^s(m\delta_x) - \mathbb{M}^s(t\delta_y)$$

$$= \mathbb{M}^w(tC) + \mathbb{M}^r(R - tC) - \mathbb{M}^r(R) + s(m+t) - s(m) - s(t).$$

The right hand side is thus dominated as a function of t by

$$f(t) \triangleq \mathbb{M}^{r}(R-tC) - \mathbb{M}^{r}(R) + s(m+t) - s(m) - s(t) \left[1 - \frac{\mathbb{M}^{w}(tC)}{s(t)}\right].$$

Clearly f(0) = 0, while $f(t)/t \to \mathbb{M}^r(R + C)'(0) + s'(m) - s'(0) = -\infty$, if we can show that $\mathbb{M}^r(R + C)'(0) < \infty$ and $\lim_{t \to 0} \mathbb{M}^w(tC)/s(t) = 0$.

We may assume $C_1 \wedge C_2 = 0$, where $C \triangleq C_1 - C_2$ with $\theta C_1, \theta C_2 \leq R$. (Otherwise replace C_1 by $C_1 - C_1 \wedge C_2 = C_1 \vee C_2 - C_2$, etc., recalling Lemma 3.2.) Therefore, since *R* contains no circuit, *C* cannot contain one either. Since *C* is a rectifiable edge with $\partial C = \delta_y - \delta_x$, by Lemma 3.10, $C = [\gamma]$ for some Lipschitz path γ . Furthermore, $\mathcal{H}^1(\operatorname{img} \gamma) \leq M$, so

$$\mathbb{M}^{w}(tC) = \int_{\operatorname{img} \gamma} w(t) \, \mathrm{d}\mathcal{H}^{1} \leqslant w(t)\mathcal{H}^{1}(\operatorname{img} \gamma) \leqslant w(t)M.$$

Also $R = \llbracket \Sigma \rrbracket \sqcup \sigma_R$ for a rectifiable set Σ (with implicit tangent vector field) and Borel $\sigma_R : \mathbb{R}^m \to [0, \infty)$. Since $\operatorname{img} \gamma \subset \Sigma$, $C = \llbracket \Sigma \rrbracket \sqcup \sigma_C$ for some Borel $\sigma_C : \mathbb{R}^m \to \{-1, 0, 1\}$ with the estimate $\theta |\sigma_C| \leq \sigma_R$. Employing the fact that r' is non-negative and decreasing,

$$\mathbb{M}^{r}(R+\cdot C)'(0) = \int_{\Sigma} r(\sigma_{R}+\cdot \sigma_{C})'(0) \, \mathrm{d}\mathcal{H}^{1} \leqslant \int_{\Sigma} r'(\sigma_{R})|\sigma_{C}| \, \mathrm{d}\mathcal{H}^{1}$$
$$\leqslant \int_{\operatorname{img} \gamma} r'(\theta|\sigma_{C}|)|\sigma_{C}| \, \mathrm{d}\mathcal{H}^{1} \leqslant r'(\theta)M.$$

But $r'(\theta) < \infty$ since $\theta > 0$. Also $w(t)/s(t) \searrow 0$ as $t \searrow 0$. Therefore, the required estimates hold.

Similar estimates hold for J_H , as then essentially just w = 0. The rest now follows by combining the estimates as in Lemma 5.8.

Summarising, we finally get

THEOREM 5.2 Let μ be a signed measure with $\mu^+(\mathbb{R}^m) = \mu^-(\mathbb{R}^m) < \infty$. Suppose that $w, r, s, r_H, s_H \in \mathcal{W}, w \neq 0$, and that $H : [0, \infty) \to [0, \infty)$ is lower-semicontinuous and non-decreasing, satisfying $H(\infty -) = \infty$. Suppose also one of

- (i) r is strictly concave, and r_H compatible with r,
- (ii) r_H is strictly concave, r compatible with r_H , and H strictly increasing,
- (iii) r is strictly concave, and H concave,
- (iv) r_H and H are strictly concave,

as well as one of

(v) $w \prec r, s$, (vi) $w, r \prec s, r_H \prec s_H$ (or $r_H = s_H = 0$), and either id $\prec r$ or id $\prec r_H$,

along with

(vii) either $s(\infty -) = \infty$, or id $\prec s_H$ and $s_H(\infty -) = \infty$.

Then there exists an optimal solution to the problem (P)&(J-WA), and any finitely optimal R is polyhedral and contains no circuit.

Proof. The assumption $w \prec r$ implies id $\prec r$, and $w \prec s$ implies id $\prec s$. Therefore, the conditions of Theorem 5.1 hold in all cases, and any finitely optimal *R* is in \mathcal{R}^* . The conditions of Lemmas 5.6 through 5.9 also hold in the corresponding cases of Theorem 4.1. Consequently *R* is the Lipschitz image of a polyhedral current with no circuit. Finally, the current with the optimal weighted area between any two points is the straight line, whence *R* is actually polyhedral.

REMARK 5.2 Actually in Lemma 5.7, instead of $w \prec r$, we only need to assume $w \preccurlyeq r$ and (w/r)(0) < 1. Likewise in Lemma 5.8, it suffices to assume $w, r \preccurlyeq s, r_H \preccurlyeq s_H$, and id $\prec s, s_H$, if we allow the lemma to determine δ . Similarly, $w \preccurlyeq s$ and id $\prec s$ suffices for Lemma 5.9, if M is determined by it. Therefore, Theorem 5.2 can, without much effort but with some additional statement complexity, be made to hold in a slightly wider class of objective functions.

A. Connectedness and BV functions

Set $E \triangleq (e_1 \land \dots \land e_m) \land \mathcal{H}^m$, where $\{e_1, \dots, e_m\}$ is the canonical basis of \mathbb{R}^m . Denote by $P(G) = \mathbb{M}(\partial(E \sqcup G))$ the *perimeter* of a set G. Define the density

$$\Theta^*(G, x) \triangleq \limsup_{r \searrow 0} \frac{\mathcal{H}^m(G \cap B(x, r))}{\mathcal{H}^m(B(x, r))}$$

and denote the *essential boundary* and *essential closure* of G by

$$\partial^* G \triangleq \{x \in \mathbb{R}^m \mid \Theta^*(G, x) > 0, \ \Theta^*(G^c, x) > 0\}, \quad \overline{G} \triangleq \{x \in \mathbb{R}^m \mid \Theta^*(G, x) > 0\}.$$

See, e.g., [3, 2] for details.

THEOREM A.1 Suppose $f : \mathbb{R}^m \to [0, \infty)$ is a function of bounded variation, and $T \triangleq E \llcorner f$. Then A is a disjoint component of T if and only if A and T - A split T, and $\partial A \leq \partial T$.

Proof. As always, let $B \triangleq T - A$. The "only if" direction holds by definition. For the "if" direction, we must show that the requirement $\partial A \wedge \partial B = 0$ and, more generally, the subcurrent primitive-decomposition requirement are superfluous. Note that $\partial A \leq \partial T$ simply means $\mathbb{M}(\partial A) + \mathbb{M}(\partial B) = \mathbb{M}(\partial T)$.

As A and B split T, we have $A = T \sqcup a$ and $B = T \sqcup b$ for some BV functions $a, b : \mathbb{R}^m \to \mathbb{R}$ with $0 \le a, b \le f, a + b = f$, and $ab = 0 \mathcal{H}^m$ -a.e. Furthermore, the co-area formula for BV functions (e.g., [3]) gives

$$\mathbb{M}(\partial A) = \int_{-\infty}^{\infty} P(\{a > t\}) \,\mathrm{d}t,\tag{A1}$$

where the perimeters are finite \mathcal{H}^1 -a.e.

Denote $A_t \triangleq \{a > t\}$ and $B_t \triangleq \{b > t\}$. Since $\mathcal{H}^m(A_t \cap B_t) = 0$, when A_t and B_t have finite perimeter, by [2, Proposition 1],

$$P(A_t) + P(B_t) = P(A_t \cup B_t) + 2\mathcal{H}^{m-1}(\partial^* A_t \cap \partial^* B_t).$$

But $A_t \cup B_t = \{f > t\}$, so (A1) and $\mathbb{M}(\partial A) + \mathbb{M}(\partial B) = \mathbb{M}(\partial T)$ imply $\mathcal{H}^{m-1}(\partial^* A_t \cap \partial^* B_t) = 0$ for \mathcal{H}^1 -almost all t.

Let now $S \leq T$ be normal, i.e., $S = E {\scriptstyle {} \ } S$ for a BV function $s : \mathbb{R}^m \to \mathbb{R}$ (supported on a compact set). That $A \wedge S$ and $B \wedge S$ split S is automatic as before, as is the boundaries summing to ∂S , assuming normality of the former. We thus have to show that, moreover, $\mathbb{M}(\partial(A \wedge S)) + \mathbb{M}(\partial(B \wedge S)) = \mathbb{M}(\partial S)$ and $\partial(A \wedge S) \wedge \partial(B \wedge S) = 0$.

We have $A \wedge S = E_{\perp}(a \wedge s)$. Thus, for the first requirement it suffices by the co-area formula to show that $P(\{a \wedge s > t\}) + P(\{b \wedge s > t\}) = P(\{s > t\})$ for \mathcal{H}^1 -almost all t. Since $s \leq a$ a.e. when a > 0, we have $\{a \wedge s > t\} = \{s > t\} \cap \{a > u\}$ up to an \mathcal{H}^m -negligible set for any $0 < u \leq t$. We take u such that A_u and B_u have finite perimeter and satisfy $\mathcal{H}^{m-1}(\partial^*A_u \cap \partial^*B_u) = 0$. This and the fact $\mathcal{H}^m(A_u \cap B_u) = 0$ force $\mathcal{H}^{m-1}(\partial^*(A_u \cap S_t) \cap \partial^*(B_u \cap S_t)) = 0$ by the definition of the essential boundary. Thus, by another application of [2, Proposition 1], we get the required

$$P(A_u \cap S_t) + P(B_u \cap S_t) = P((A_u \cap S_t) \cup (B_u \cap S_t)) = P(S_t).$$

As for the intersection, it suffices to show that the total variation measures $\mu_{\partial(S \wedge A)}$ and $\mu_{\partial(S \wedge B)}$ are mutually singular. By the co-area formula, these can be written in the forms

$$\mu_{\partial A}(\Omega) = \int_{-\infty}^{\infty} P(A_t | \Omega) \, \mathrm{d}t = \int_{0}^{\infty} \mathcal{H}^{m-1}(\partial^* A_t \cap \Omega) \, \mathrm{d}t,$$

noting that for t < 0, $A_t = \mathbb{R}^m \pmod{\mathcal{H}^m}$, whence $\mathcal{H}^{m-1}(\partial^* A_t) = 0$.

Let $\tilde{A} \triangleq \bigcup_{u>0} \overline{A_u}$. Note that $\mu_{\partial A}(\tilde{A}) = \int \mathcal{H}^{m-1}(\partial^* A_t) dt = \mathbb{M}(\partial A)$ by the definitions of the essential boundary and closure. Thus $\mu_{\partial A}$ is concentrated on \tilde{A} , and it suffices to show that $\mathcal{H}^{m-1}(\partial^* A_t \cap \tilde{B}) = 0$ (for almost all t). This follows if $\mathcal{H}^{m-1}(\partial^* A_t \cap \overline{B_u}) = 0$ for the almost all $0 < u \leq t$ satisfying $\mathcal{H}^{m-1}(\partial^* A_u \cap \partial^* B_u) = 0$. Consider first $x \in \partial^* A_t \cap \partial^* B_u$. This implies $0 < \mathcal{O}^*(B_u, x) \leq \mathcal{O}^*(A_u^c, x)$, and $0 < \mathcal{O}^*(A_t, x) \leq \mathcal{O}^*(A_u, x)$. Thus $x \in \partial^* A_u$. But $\mathcal{H}^{m-1}(\partial^* A_u \cap \partial^* B_u) = 0$. Next, suppose $x \in (\overline{B_u} \setminus \partial^* B_u) \cap \partial^* A_t$. Then $\mathcal{O}^*(B_u, x) > 0$ but $0 = \mathcal{O}^*(B_u^c, x) \geq \mathcal{O}^*(A_u, x)$. Thus $x \notin \partial^* A_t$. The claim follows. \Box

COROLLARY A.1 When T' is a set of finite perimeter, $E_{\perp}\chi_{T'}$ being connected per Definition 3.2 is equivalent to the non-existence of sets A', B' with $\mathcal{H}^m(T' \triangle (A' \cup B')) = 0$, $\mathcal{H}^m(A' \cap B') = 0$, $\mathcal{H}^m(A')$, $\mathcal{H}^m(B') > 0$ and P(A') + P(B') = P(T').

Thus, in this case, connectedness is equivalent to indecomposability in the sense of [3, 2] up to \mathcal{H}^m -negligible sets. (In these references $\{A', B'\}$ is a partition of T'.)

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