

A Remark on Singular Perturbation Methods via the Lyapunov-Schmidt Reduction

By

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Abstract

For some reaction-diffusion equations, Lyapunov-Schmidt reduction was shown to be applicable to construct singularly perturbed equilibrium solutions. For this application, it is indispensable to show that some inverse operator are uniformly bounded. In this paper, we give an elementary proof of this fact.

§ 1. Introduction

For differential equations containing a small parameter in the spatial derivatives, there often exist solutions with internal transition layers. Hale and Sakamoto [1] applied Lyapunov-Schmidt reduction to construct singularly perturbed equilibrium solutions to Equation (1) below. This method also gave the stability condition for the solutions simultaneously.

In the following, we briefly sketch the method of [1], with special attention to the part where our present contribution appears. We consider the following equation

$$(1) \quad \begin{aligned} u_t &= \varepsilon^2 u_{xx} + f(u, x) & -1 < x < 1, t > 0, \\ u_x(-1, t) &= 0 = u_x(1, t). & t > 0. \end{aligned}$$

The function f satisfies the following assumptions.

1. $f: \mathbf{R} \times [-1, 1] \rightarrow \mathbf{R}$ is of class C^∞ with $f(0, x) \equiv 0, f(1, x) \equiv 0$.
2. There exists a positive constant β such that

$$f_u(0, x) \leq -3\beta^2, \quad f_u(1, x) \leq -3\beta^2 \quad \text{for } -1 \leq x \leq 1.$$

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3. Let $J(x) = \int_0^1 f(s, x) ds$. Then $J(0) = 0$ with $J'(0) \neq 0$, and $\int_0^u f(s, 0) ds < 0$ for $u \in (0, 1)$.

To construct unknown equilibrium solution u of (1), we begin with a smooth approximate equilibrium solution $U(x, \epsilon)$ of (1) that exhibits a transition layer at $x = 0$. We denote $u - U(x, \epsilon)$ by u . Then u must satisfy

$$(2) \quad 0 = \mathcal{L}^\epsilon u + G(\epsilon) + F(u, \epsilon),$$

where

$$(3) \quad \mathcal{L}^\epsilon u = \epsilon^2 u_{xx} + f_u(U(x, \epsilon), x)u,$$

$$(4) \quad G(\epsilon)(x) = \epsilon^2 U_{xx}(x, \epsilon) + f(U(x, \epsilon), x),$$

$$(5) \quad F(u, \epsilon) = f(U(x, \epsilon) + u, x) - f(U(x, \epsilon), x) - f_u(U(x, \epsilon), x)u.$$

The approximate solution $U(x, \epsilon)$ is constructed to satisfy $\sup_{x \in [-1, 1]} |G(\epsilon)(x)| = O(\epsilon^2)$. The operator \mathcal{L}^ϵ turns out to have exactly one eigenvalue $\lambda_1(\epsilon)$ that approaches zero as $\epsilon \rightarrow 0$, and there are some $\epsilon_0 > 0, \mu_0 > 0$ such that the remaining eigenvalues are less than $-\mu_0$ for $0 < \epsilon \leq \epsilon_0$. Moreover the eigenspace $\lambda_1(\epsilon)$ is one-dimensional, and $\lambda_1(\epsilon) = k_1\epsilon + o(\epsilon)$ as $\epsilon \rightarrow 0$ for some constant k_1 . Let $Y = C[-1, 1]$ with the norm

$$|h|_0 = \sup_{x \in [-1, 1]} |h(x)| \quad \text{for } h \in Y,$$

and let $X = \{u \in C^2[-1, 1]; u_x(-1) = 0 = u_x(1)\}$ with the norm

$$|u|_{2, \epsilon} = |u|_0 + \epsilon |u_x|_0 + \epsilon^2 |u_{xx}|_0 \quad \text{for } u \in X.$$

Let $\phi_1(\epsilon)$ be an eigenfunction associated with $\lambda_1(\epsilon)$ normalized as (12). Let E be the following projection onto the span of $\phi_1(\epsilon)$:

$$Eu = \int_{-1}^1 u(x)\phi_1(x, \epsilon) dx \phi_1(\cdot, \epsilon) / \|\phi_1(\cdot, \epsilon)\|_{L^2(-1, 1)}^2,$$

and let Y_1, X_1 be the null spaces of E in Y, X , respectively. Using the decompositions

$$Y = \text{span}\{\phi_1(\epsilon)\} \oplus Y_1, \quad X = \text{span}\{\phi_1(\epsilon)\} \oplus X_1,$$

we split (2) into

$$(6) \quad \lambda_1(\epsilon)\alpha\phi_1(\epsilon) + EG(\epsilon) + EF(\alpha\phi_1(\epsilon) + w, \epsilon) = 0,$$

$$(7) \quad \mathcal{L}^\varepsilon w + (I-E)G(\varepsilon) + (I-E)F(\alpha\phi_1(\varepsilon) + w, \varepsilon) = 0,$$

where $u = \alpha\phi_1(x, \varepsilon) + w$ with $\alpha \in \mathbf{R}$, $w \in X_1$. Hale and Sakamoto [1] solved (7) as $w = w^*(\alpha, \varepsilon)$ with

$$(8) \quad |w^*(\alpha, \varepsilon)|_{2, \varepsilon} = O(\alpha^2 + \varepsilon^2) \quad \text{as } |\alpha| + \varepsilon \rightarrow 0,$$

by estimating the second and the third terms of (7) and using the contraction mapping principle. We substitute $w = w^*(\alpha, \varepsilon)$ into (6), and obtain an equation for α , which we denote by $B(\alpha, \varepsilon) = 0$. Using the fact $|G(\varepsilon)|_0 = O(\varepsilon^2)$ and $\lambda_1(\varepsilon) = k\varepsilon + o(\varepsilon)$, we can solve $B(\alpha, \varepsilon) = 0$ as $\alpha = \alpha^*(\varepsilon)$. Here $\alpha^*(\varepsilon) = O(\varepsilon)$ as $\varepsilon \downarrow 0$. Now the desired equilibrium solution of (1) is obtained by

$$(9) \quad u = U(x, \varepsilon) + \alpha^*(\varepsilon)\phi_1(x, \varepsilon) + w^*(\alpha^*(\varepsilon), \varepsilon).$$

In order to obtain the crucial estimate (8), Hale and Sakamoto [1] used the fact that $(\mathcal{L}^\varepsilon)^{-1} : Y_1 \rightarrow Y_1$ is bounded uniformly in $\varepsilon \in (0, \varepsilon_0]$. If the topology of Y_1 is that of $L^2(-1, 1)$, it suffices for the boundedness that there are no eigenvalues of $\mathcal{L}^\varepsilon|_{Y_1}$ around 0, which is known for many years. However, now that Y_1 is a subspace of $C[-1, 1]$, it is not obvious for the author to conclude the uniform boundedness directly from the distribution of eigenvalues.

The main issue of this paper is to give a proof to the fact stated above.

Theorem 1. *The operator $(\mathcal{L}^\varepsilon)^{-1} : Y_1 \rightarrow Y_1$ is bounded uniformly in sufficiently small $\varepsilon > 0$.*

§ 2. Preliminaries

We describe how to construct $U(x, \varepsilon)$ and collect properties of \mathcal{L}^ε following Hale and Sakamoto [1].

Let $\zeta_0(x)$, $\zeta_+(x)$ be cutoff functions of class $C^\infty[-1, 1]$ with

$$\zeta_0(x) = \begin{cases} 1 & |x| \leq 1/4 \\ 0 & |x| \geq 1/2 \\ 0 \leq \zeta_0(x) \leq 1 & x \in [-1, 1], \end{cases} \quad \zeta_+(x) = \begin{cases} 0 & x \in [-1, 0] \\ 1 - \zeta_0(x) & x \in [0, 1]. \end{cases}$$

$U(x, \varepsilon)$ is given by

$$(10) \quad U(x, \varepsilon) = \zeta_0(x) \{z_0(\eta) + \varepsilon z_1(\eta)\} + \zeta_+(x),$$

where $\eta = x/\varepsilon$. Here z_0, z_1 are some smooth and bounded functions on \mathbf{R} . In particular z_0 satisfies $d^2z_0/d\eta^2 + f(z_0(\eta), 0) = 0$ with $z_0(-\infty) = 0, z_0(\infty) = 1$ and

$$(11) \quad \left| \frac{dz_0}{d\eta}(\eta) \right| \leq k_0 \exp(-2\beta|\eta|)$$

with some constant $k_0 > 0$. Then $U(x, \varepsilon)$ satisfies $|G(\varepsilon)|_0 = O(\varepsilon^2)$ as in Lemma 2.1 of [1].

Let $\lambda_1(\varepsilon)$ be the principal eigenvalue of \mathcal{L}^ε , and let $\phi_1(\varepsilon)$ be the eigenfunction associated with $\lambda_1(\varepsilon)$ normalized as

$$(12) \quad \phi_1(0, \varepsilon) = dz_0/d\eta(0).$$

Proposition 1 (Theorem 3.1 and Lemma 3.4 in [1]). *There exists $\varepsilon_0 > 0$ such that the following assertions are valid:*

(i) $\lambda_1(\varepsilon)$ is simple for $0 < \varepsilon < \varepsilon_0$, and satisfies $\lim_{\varepsilon \rightarrow 0} \lambda_1(\varepsilon)/\varepsilon = k_1$, where

$$(13) \quad k_1 = -J'(0) / \|dz_0/d\eta\|_{L^2(\mathbf{R})}^2.$$

(ii) *There exists a constant $\mu_0 > 0$ such that, all other eigenvalues of \mathcal{L}^ε are less than $-\mu_0$.*

(iii) *There exists a constant $k_2 > 0$ such that $|\phi_1(x, \varepsilon)| \leq k_2 \exp(-2\beta|x|/\varepsilon)$ for $0 < \varepsilon < \varepsilon_0$.*

(iv) *Let $\tilde{\phi}_1(\eta, \varepsilon) = \phi_1(\varepsilon\eta, \varepsilon)$. Then $\tilde{\phi}(\cdot, \varepsilon)$ converges to $dz_0/d\eta$ in $C^2(K)$ as $\varepsilon \rightarrow 0$, where K is any compact set in \mathbf{R} .*

Remark 1. The equilibrium solution (1) is stable if $k_1 < 0$, and is unstable if $k_1 > 0$. See [1] for the proof.

There exists a constant $k_3 > 0$ such that $|Eu|_0 \leq k_3|u|_0$ for $u \in Y$, $0 < \varepsilon < \varepsilon_0$.

§ 3. Proof of Theorem 1

The following arguments are similar to those given by Ni and Takagi [2], where the inverse operator of another elliptic operator is studied.

We prove by contradiction. Assume that there exist $\varepsilon_1 > \varepsilon_2 > \dots > \varepsilon_j > \dots > 0$ with $\lim_{j \rightarrow \infty} \varepsilon_j = 0$ such that there exist $\phi_j \in X_1$ and $h_j \in Y_1$ satisfying

$$(14) \quad \begin{aligned} \mathcal{L}^{\varepsilon_j} \phi_j &= h_j && \text{in } (-1, 1), \\ \frac{d\phi_j}{dx}(-1) &= 0 = \frac{d\phi_j}{dx}(1), \end{aligned}$$

with

$$|\phi_j|_0 = 1, \quad |h_j|_0 < 1/j,$$

for each $j = 1, 2, \dots$. Let

$$\begin{aligned} \tilde{\phi}_j(\eta) &= \phi_j(\varepsilon_j\eta, \varepsilon_j) \\ \tilde{h}_j(\eta) &= h_j(\varepsilon_j\eta, \varepsilon_j) \\ \tilde{U}_j(\eta, \varepsilon_j) &= U_j(\varepsilon_j\eta, \varepsilon_j) \end{aligned} \quad \text{for } \eta \in (-1/\varepsilon_j, 1/\varepsilon_j).$$

Then

$$(15) \quad \frac{d^2\tilde{\phi}_j}{d\eta^2} + f_u(\tilde{U}(\eta, \varepsilon_j), \varepsilon_j\eta)\tilde{\phi}_j = \tilde{h}_j$$

in $(-1/\varepsilon_j, 1/\varepsilon_j)$. Let $K = [-n, n]$ for arbitrarily fixed $n \in \mathbf{N}$. We consider (15) in K for sufficiently large j . Since $|\phi_j|_0 = 1$, the sequence $\{\tilde{\phi}_j\}$ remains bounded in $C(K)$. We can also see that

$$f_u(\tilde{U}(\eta, \varepsilon_j), \varepsilon_j\eta) = f_u(\zeta_0(\varepsilon_j\eta) \{z_0(\eta) + \varepsilon_j z_1(\eta)\} + \zeta_+(\varepsilon_j\eta), \varepsilon_j\eta)$$

is bounded in $C(K)$ uniformly in j . The sequence $\{\tilde{h}_j\}$ is bounded in $C(K)$. Hence from (15), $\{d^2\tilde{\phi}_j/d\eta^2\}$ is also bounded in $C(K)$. From the following interpolation inequality

$$\left\| \frac{d\tilde{\phi}_j}{d\eta} \right\|_{C(K)} \leq \delta \left\| \frac{d^2\tilde{\phi}_j}{d\eta^2} \right\|_{C(K)} + \frac{2}{\delta} \|\tilde{\phi}_j\|_{C(K)},$$

for every $\delta > 0$, the sequence $\{\tilde{\phi}_j\}_{j=1}^\infty$ remains bounded in $C^2(K)$. For any $\theta \in (0,1)$, the imbedding $C^2(K) \subset C^{1,\theta}(K)$ is compact. By taking a subsequence, we can assume that $\{\tilde{\phi}_j\}_{j=1}^\infty$ converges in $C^{1,\theta}(K)$. As $j \rightarrow \infty$, we have

$$\begin{aligned} f_u(\tilde{U}(\eta, \varepsilon_j), \varepsilon_j\eta) &\rightarrow f_u(z_0(\eta), 0), \\ \tilde{h}_j(\eta) &\rightarrow 0 \end{aligned}$$

uniformly in $\eta \in K$. Thus $d^2\tilde{\phi}_j/d\eta^2(\eta)$ converges uniformly in $\eta \in K$. It follows that $\{\tilde{\phi}_j\}$ converges in $C^2(K)$. Let $\tilde{\phi}_\infty = \lim_{j \rightarrow \infty} \tilde{\phi}_j$ in $C^2(K)$. Then $\|\tilde{\phi}_\infty\|_{C(K)} \leq 1$.

We apply the argument stated above for each $K = [-n, n]$ with $n = 1, 2, \dots$. Then it turns out that $\tilde{\phi}_\infty$ is a bounded function of class $C^\infty(\mathbf{R})$ and satisfies

$$\frac{d^2\tilde{\phi}_\infty}{d\eta^2} + f_u(z_0(\eta), 0)\tilde{\phi}_\infty(\eta) = 0 \quad \text{in } \mathbf{R}.$$

This equation has two linearly independent solutions, that is,

$$\frac{dz_0}{d\eta}(\eta), \quad \frac{dz_0}{d\eta}(\eta) \int_0^\eta \left(\frac{dz_0}{d\eta}(\eta) \right)^{-2} d\eta.$$

The latter one goes to infinity as $\eta \rightarrow \infty$. Since $\tilde{\phi}_\infty$ is a bounded solution, there must be a constant c such that

$$(16) \quad \tilde{\phi}_\infty(\eta) = c \frac{dz_0}{d\eta}(\eta).$$

Here $c \neq 0$ follows from the next lemma, the proof of which is stated at the end of § 3.

Lemma 1. *Let an arbitrary x with $|\phi_j(x)| = 1$ be denoted by x_j . Then x_j/ε_j must remain bounded as $j \rightarrow \infty$.*

Indeed, taking a subsequence, x_j/ε_j converges to some $\eta_\infty \in \mathbf{R}$. From

$$|\tilde{\phi}_j(x_j/\varepsilon_j)| = |\phi_j(x_j)| = 1,$$

we have $|\tilde{\phi}_\infty(\eta_\infty)| = 1$. Hence $c \neq 0$.

Since $\phi_j \in X_1$, we have $\int_{-1}^1 \phi_j(x) \phi_1(x, \varepsilon) dx = 0$, that is,

$$\int_{-\frac{1}{\varepsilon_j}}^{\frac{1}{\varepsilon_j}} \tilde{\phi}_j(\eta) \tilde{\phi}_1(\eta, \varepsilon_j) d\eta = 0.$$

Combining $|\tilde{\phi}_1(\eta, \varepsilon_j)| \leq k_2 \exp(-2\beta|\eta|)$ and $\|\tilde{\phi}_j\|_{C[-1/\varepsilon_j, 1/\varepsilon_j]} = 1$, we have

$$|\tilde{\phi}_j(\eta) \tilde{\phi}_1(\eta, \varepsilon_j)| \leq k_2 \exp(-2\beta|\eta|).$$

From Lebesgue's dominated convergence theorem,

$$\int_{-\infty}^\infty \tilde{\phi}_\infty(\eta) z_0(\eta) d\eta = 0,$$

which contradicts (16) when $c \neq 0$. This completes the proof of Theorem 1. \square

Proof of Lemma 1. We prove by contradiction. Assume the contrary. Then by taking a subsequence, we have

$$\lim_{j \rightarrow \infty} x_j/\varepsilon_j = \infty \quad \text{or} \quad \lim_{j \rightarrow \infty} x_j/\varepsilon_j = -\infty.$$

Without loss of generality, we assume $\lim_{j \rightarrow \infty} x_j/\varepsilon_j = \infty$. Let

$$\begin{aligned} \hat{\phi}_j(\eta) &= \phi_j(\varepsilon_j\eta + x_j) \\ \hat{h}_j(\eta) &= h_j(\varepsilon_j\eta + x_j) \quad \text{for } (-1-x_j)/\varepsilon_j \leq \eta \leq (1-x_j)/\varepsilon_j. \\ \widehat{U}(\eta, \varepsilon_j) &= U_j(\varepsilon_j\eta + x_j, \varepsilon_j). \end{aligned}$$

These functions can be defined at least for $-1 \leq \eta \leq 0$ for sufficiently large j . From (14),

$$\frac{d^2\hat{\phi}_j}{d\eta^2} + f_u(\widehat{U}(\eta, \varepsilon_j), \varepsilon_j\eta + x_j)\hat{\phi}_j = \hat{h}_j \quad \text{in } (-1, 0).$$

Using $|\phi_j(x_j)| = 1$ and $d\phi_j/dx(x_j) = 0$, we have

$$\frac{d\hat{\phi}_j}{d\eta}(0) = 0, \quad |\hat{\phi}_j(0)| = 1.$$

By taking a subsequence, we can assume $\{x_j\}_{j=1}^\infty$ converges to some $x_\infty \in [-1, 1]$. From $\lim_{j \rightarrow \infty} x_j/\varepsilon_j = \infty$, we have $\varepsilon_j\eta + x_j > 0$. Hence

$$\zeta_0(\varepsilon_j\eta + x_j) + \zeta_+(\varepsilon_j\eta + x_j) = 1.$$

Using $\lim_{j \rightarrow \infty} x_j/\varepsilon_j = \infty$ again, we obtain

$$z_0(\eta + x_j/\varepsilon_j) + \varepsilon_j z_1(\eta + x_j/\varepsilon_j) \rightarrow 1,$$

uniformly in $\eta \in [-1, 0]$. Therefore

$$\widehat{U}(\eta, \varepsilon_j) = \zeta_0(\varepsilon_j\eta + x_j) \{z_0(\eta + x_j/\varepsilon_j) + \varepsilon_j z_1(\eta + x_j/\varepsilon_j)\} + \zeta_+(\varepsilon_j\eta + x_j)$$

converges to 1 uniformly in $-1 \leq \eta \leq 0$. By quite the same argument as in the proof of Theorem 1, we can assume $\hat{\phi}_j$ converges to some $\hat{\phi}_\infty$ in $C^2[-1, 0]$. The function $\hat{\phi}_\infty$ satisfies

$$\begin{aligned} \frac{d^2\hat{\phi}_\infty}{d\eta^2} + f_u(1, x_\infty)\hat{\phi}_\infty &= 0 \quad \text{in } (-1, 0), \\ \frac{d\hat{\phi}_\infty}{d\eta}(0) &= 0, \quad |\hat{\phi}_\infty(0)| = 1, \\ |\hat{\phi}_\infty(\eta)| &\leq 1 \quad \text{in } [-1, 0]. \end{aligned}$$

By the assumptions for f , $f_u(1, x_\infty) < 0$. This contradicts the maximum principle (see for example, [3]). The proof of Lemma 1 is completed. \square

§ 4. Uniform Boundedness of Another Inverse Operator

In Sakamoto [4], the following system of equations

$$(17) \quad \begin{aligned} u_t &= \varepsilon^2 u_{xx} + f(u, v) \\ v_t &= \frac{1}{\sigma} v_{xx} + g(u, v) \end{aligned} \quad \text{in } 0 < x < 1, t > 0,$$

with the Neumann boundary condition

$$\begin{aligned} u_x(0, t) = 0 &= u_x(1, t) \\ v_x(0, t) = 0 &= v_x(1, t) \end{aligned} \quad t > 0$$

is studied. For the assumption of f and g , see § 1 of [4]. Singularly perturbed equilibrium solutions of (17) are constructed in [4] for every $(\varepsilon, \sigma) \in (0, \varepsilon_0] \times (0, \sigma_0]$ via the Lyapunov-Schmidt reduction. Here ε_0, σ_0 are some positive constants. Let

$$(18) \quad L^{\varepsilon, \sigma} = \varepsilon^2 \frac{d^2}{dx^2} + f_u(U(x, \varepsilon, \sigma), V(x, \varepsilon, \sigma)),$$

where $U(x, \varepsilon, \sigma), V(x, \varepsilon, \sigma)$ are approximate equilibrium solutions of (17) as in § 2 of [4]. We denote a complete orthonormal system in $L^2(0, 1)$ of eigenfunctions and eigenvalues by $\{\phi_n(\varepsilon, \sigma), \lambda_n(\varepsilon, \sigma)\}$, where $\lambda_1(\varepsilon, \sigma) > \lambda_2(\varepsilon, \sigma) \geq \lambda_3(\varepsilon, \sigma) \geq \dots$. The principal eigenvalue $\lambda_1(\varepsilon, \sigma)$ approaches zero as $\varepsilon \rightarrow 0$, and there exists a constant $\mu_1 > 0$ such that all other ones are less than $-\mu_1$. Let E denote the orthogonal projection onto $\text{span } \{\phi_1(\varepsilon, \sigma)\}$, that is, $Eu = (u, \phi_1(\varepsilon, \sigma))_{L^2(0, 1)} \phi_1(\varepsilon, \sigma)$.

The following assertion is a part of Corollary 3.2 of [4].

Theorem 2. *The linear operator*

$$(L^{\varepsilon, \sigma})^{-1}(I - E) : C[0, 1] \rightarrow C[0, 1]$$

is bounded uniformly in $(\varepsilon, \sigma) \in (0, \varepsilon_0] \times (0, \sigma_0]$. Here I is the identical operator.

The argument as in the proof of Theorem 1 is valid to prove Theorem 2.

Proof of Theorem 2. We prove by contradiction. Assume there exist $\varepsilon_1 > \dots > \varepsilon_j > \dots > 0$ with $\lim_{j \rightarrow \infty} \varepsilon_j = 0$ and $\{\sigma_j\}_{j=1}^{\infty} \subset (0, \sigma_0]$ such that the following holds. There exist ϕ_j and h_j satisfying

$$(\varepsilon_j)^2 \frac{d^2 \phi_j}{dx^2} + f_u(U(x, \varepsilon_j, \sigma_j), V(x, \varepsilon_j, \sigma_j)) \phi_j = h_j \quad \text{in } (0, 1),$$

$$\frac{d\phi_j}{dx}(0) = 0 = \frac{d\phi_j}{dx}(1),$$

with $|\phi_j|_0 = 1$, $|h_j|_0 < 1/j$, and $\int_0^1 h_j(x)\phi_1(\varepsilon_j, \sigma_j)dx = 0$. Since $L^{\varepsilon, \sigma}$ is self-adjoint, we have

$$\int_0^1 \phi_j(x)\phi_1(\varepsilon_j, \sigma_j)dx = 0.$$

If we replace Lemma 1 by the following lemma and Proposition 1 by Lemma 3.1 of [4] respectively, the similar argument for Theorem 1 is applicable. We omit the detail. \square

Let $x^*(\sigma_j)$ is as in § 2 of Sakamoto [4]. Corresponding Lemma 1, we have the following:

Lemma 2. *Let an arbitrary x with $|\phi_j(x)| = 1$ be denoted by x_j . Then $(x_j - x^*(\sigma_j))/\varepsilon_j$ remains bounded as $j \rightarrow \infty$.*

Proof of Lemma 2. We only sketch the proof. Assume the contrary. Without loss of generality, we can assume $\lim_{j \rightarrow \infty} (x_j - x^*(\sigma_j))/\varepsilon_j = \infty$. Taking a subsequence, we can also assume $\{x_j\}_{j=1}^\infty$ converges to some $x_\infty \in [0, 1]$, and that $\{\sigma_j\}_{j=1}^\infty$ converges to $\sigma_\infty \in [0, \sigma_0]$. Let $\hat{\phi}_j(\eta) = \phi_j(\varepsilon_j\eta + x_j)$, which can be defined at least on $[-1, 0]$ for sufficiently large j . By the same argument as in the proof of Lemma 1, we can take a subsequence such that $\{\hat{\phi}_j\}$ converges to some $\hat{\phi}_\infty$ in $C^2[-1, 0]$. The function $\hat{\phi}_\infty$ satisfies

$$\begin{aligned} &\frac{d^2\hat{\phi}_\infty}{d\eta^2} + f_u(h_+(\hat{V}(x_\infty, \sigma_\infty)), \hat{V}(x_\infty, \sigma_\infty))\hat{\phi}_\infty = 0 \quad \text{in } (-1, 0), \\ (19) \quad &\frac{d\hat{\phi}_\infty}{d\eta}(0) = 0, \quad |\hat{\phi}_\infty(0)| = 1, \\ &|\hat{\phi}_\infty(\eta)| \leq 1 \quad \text{in } [-1, 0]. \end{aligned}$$

For the definitions for $h_+(\cdot)$ and \hat{V} , see [4]. In view of the assumptions on f in § 1 of [4], we have

$$f_u(h_+(\hat{V}(x_\infty, \sigma_\infty)), \hat{V}(x_\infty, \sigma_\infty)) < 0,$$

which combined with (19) contradicts the maximum principle. The proof of Lemma 2 is completed. \square

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