

Rend. Lincei Mat. Appl. 17 (2006), 167[–174](#page-7-0)

Partial differential equations. — *Approximating the inverse matrix of the G-limit through changes of variables in the plane*, by GIOCONDA MOSCARIELLO, CARLO SBORDONE and FRANCOIS MURAT, communicated on 10 March 2006.

ABSTRACT. — Let A_j be a sequence of coercive symmetric matrices in $L^{\infty}(\mathbb{R}^2)^{2\times 2}$ with det $A_j = 1$ which G converges to A. We prove that there exists a sequence of K-quasiconformal mappings F_j which converge locally uniformly to a K-quasiconformal mapping F such that $A_j^{-1} \circ F_j^{-1}$ G-converges to $A^{-1} \circ F^{-1}$. The result is specific to the two-dimensional case but a similar result holds in dimension 1.

KEY WORDS: G-convergence; quasiconformal mappings; Beltrami operators; elliptic equations.

MATHEMATICS SUBJECT CLASSIFICATION (2000): 35J25, 30C62.

1. INTRODUCTION

Let K be a fixed real number such that $K \geq 1$. We denote by $\mathcal{M}(K)$ the set of 2×2 symmetric matrices

$$
A = A(x), \quad x \in \mathbb{R}^2,
$$

with $L^{\infty}(\mathbb{R}^2)$ coefficients which satisfy the ellipticity bounds

$$
(1.1) \t\t |\xi|^2/K \le \langle A(x)\xi, \xi \rangle \le K|\xi|^2 \quad \text{a.e. } x \in \mathbb{R}^2, \ \forall \xi \in \mathbb{R}^2.
$$

We denote by $\mathcal{M}_1(K)$ the subset of $\mathcal{M}(K)$ whose elements satisfy the condition

(1.2)
$$
\det A(x) = 1
$$
 a.e. $x \in \mathbb{R}^2$.

It is well known that $\mathcal{M}(K)$ is compact with respect to G-convergence ([\[M\]](#page-7-1), [\[S1\]](#page-7-2), [\[T\]](#page-7-3)) and rather surprising that $\mathcal{M}_1(K)$ enjoys the same property ([\[FM\]](#page-7-4)).

Our aim is to prove that $\mathcal{M}_1(K)$ enjoys another interesting property: if A_j is a sequence in $\mathcal{M}_1(K)$ and if we consider the inverse matrices A_j^{-1} , for a subsequence we may assume that

$$
A_j \stackrel{G}{\to} A \quad \text{and} \quad A_j^{-1} \stackrel{G}{\to} B^{-1},
$$

and in general B is different from A . Indeed, it is well known that the inverse of the G limit does not coincide with the G-limit of the inverses. However, the situation is different if we allow suitable changes of variables: we prove in the present paper that for every ball B there exists a sequence F_j of K-quasiconformal mappings in the plane which locally uniformly converges to a K-quasiconformal mapping F, such that defining \hat{A}_j and \hat{A} as A_i and A in the ball B and as the identity outside B, one has

$$
\hat{A}_j^{-1}\circ F_j^{-1}\overset{G}{\to}\hat{A}^{-1}\circ F^{-1}.
$$

Let us emphasize that our result is restricted to the two-dimensional case; a similar result holds in one dimension, but the result dramatically fails if $d \geq 3$.

2. DEFINITIONS AND PRELIMINARY RESULTS

Let us first recall the definition of the G-convergence (see [\[S1\]](#page-7-2), [\[T\]](#page-7-3)) of a sequence of 2×2 symmetric matrices $A_j = A_j(x)$ with $L^{\infty}(\mathbb{R}^2)$ coefficients which belong to $\mathcal{M}(K)$, i.e. satisfy (1.1) uniformly in j.

We say that a sequence $A_j \in \mathcal{M}(K)$ G-converges to A, and write

$$
A_j \stackrel{G}{\to} A,
$$

where A also belongs to $\mathcal{M}(K)$, if for every bounded open subset Ω of \mathbb{R}^2 and for every $f \in L^2(\Omega)$ one has

$$
u_j \rightharpoonup u \quad \text{ weakly in } W_0^{1,2}(\Omega),
$$

where u_i and u are defined by

$$
\begin{cases}\n-\operatorname{div}(A_j(x)\nabla u_j) = f & \text{in } \mathcal{D}'(\Omega), \\
u_j \in W_0^{1,2}(\Omega), \\
-\operatorname{div}(A(x)\nabla u) = f & \text{in } \mathcal{D}'(\Omega), \\
u \in W_0^{1,2}(\Omega).\n\end{cases}
$$

One of the main properties of the G-convergence in $\mathcal{M}(K)$ is its sequential compactness: from every sequence of matrices in $\mathcal{M}(K)$ one can extract a subsequence G-converging to a matrix which also belongs to $\mathcal{M}(K)$ (see [\[S1\]](#page-7-2), [\[T\]](#page-7-3)).

Despite the fact that the condition

$$
\det A_j(x) = 1 \quad \text{ a.e. } x \in \mathbb{R}^2
$$

is not necessarily preserved under any familiar weak convergence of the sequence A_j , it is preserved under G-convergence (see e.g. [\[FM\]](#page-7-4)). So the subset $\mathcal{M}_1(K)$ of $\mathcal{M}(K)$ consisting of matrices with determinant equal to one is G-closed. This result is specific to the two-dimensional case.

Let us now recall the definition of K -quasiconformal mappings (still in the twodimensional setting; see [\[AIM\]](#page-7-5)).

We say that F is a *K*-quasiconformal mapping if $F : \mathbb{R}^2 \to \mathbb{R}^2$ is a homeomorphism with F and F^{-1} in $W^{1,2}_{loc}(\mathbb{R}^2; \mathbb{R}^2)$ such that

(2.1)
$$
|DF(x)|^2 \le \left(K + \frac{1}{K}\right)J(x, F) \quad \text{a.e. } x \in \mathbb{R}^2,
$$

where $|DF(x)|$ stands for the Hilbert–Schmidt norm of the differential matrix $DF(x) \in$ $\mathbb{R}^{2\times 2}$ and $J(x, F)$ for the Jacobian determinant of F, i.e.

$$
J(x, F) = \det DF(x).
$$

3. MAIN RESULT

Let A_i be a sequence of matrices such that

$$
(3.1) \t\t A_j \in \mathcal{M}_1(K), \quad A_j \stackrel{G}{\to} A;
$$

then, as mentioned in Section 2, $A \in \mathcal{M}_1(K)$. Fix a ball B in \mathbb{R}^2 and define the matrices \hat{A}_j and \hat{A} by

$$
\hat{A}_j(x) = \begin{cases} A_j(x), & x \in B, \\ I, & x \notin B, \end{cases} \quad \hat{A}(x) = \begin{cases} A(x), & x \in B, \\ I, & x \notin B. \end{cases}
$$

Our main result is as follows.

THEOREM 3.1. *Under assumption* (3.1)*, there exists a sequence* F^j *of* K*-quasiconformal mappings which satisfies*

(3.2)
$$
F_j \to F \quad locally \; uniformly,
$$

with F *a* K*-quasiconformal mapping, such that*

(3.3)
$$
\hat{A}_j^{-1} \circ F_j^{-1} \stackrel{G}{\to} \hat{A}^{-1} \circ F^{-1}.
$$

PROOF. Since $\hat{A}_j \in \mathcal{M}_1(K)$, by the so-called measurable Riemann Mapping Theorem ([\[IM\]](#page-7-6)) there exists a unique K-quasiconformal mapping F_j : $\mathbb{R}^2 \to \mathbb{R}^2$ such that $F_j (0, 0) = (0, 0), F_j (1, 0) = (1, 0), F_j (\infty) = \infty$ and

(3.4)
$$
\hat{A}_j(x) = J(x, F_j) (DF_j)^{-1}(x)^t (DF_j)^{-1}(x),
$$

where ${}^{t}D$ and D^{-1} denote the transpose and the inverse of the matrix D. Note that a matrix A of the form

$$
A(x) = J(x, F) (DF)^{-1}(x)^{t} (DF)^{-1}(x) \quad \text{a.e. } x \in \mathbb{R}^2
$$

(whose determinant is always equal to 1) belongs to $\mathcal{M}_1(K)$ if and only if condition (2.1) holds true: indeed, since the Hilbert–Schmidt norm of the matrix D is given by

$$
|D|^2 = \text{tr } D^t D,
$$

the distortion inequality

$$
|D|^2 \le \left(K + \frac{1}{K}\right) \det D
$$

is equivalent to

$$
\operatorname{tr}\left(\frac{D}{\det D}\right) \leq K + \frac{1}{K};
$$

if λ and $1/\lambda$ are the eigenvalues of $D^{t}D/\text{det }D$ (this matrix is always symmetric, nonnegative and with determinant 1), then the last inequality is equivalent to

$$
\lambda + \frac{1}{\lambda} \leq K + \frac{1}{K},
$$

and to $1/K \leq \lambda \leq K$.

Since the mapping F_j is K-quasiconformal for every j, there exists (see [\[GIKMS,](#page-7-7) Lemma 5.2]) a subsequence F_{j_h} and a K-quasiconformal mapping F such that $F(0, 0) =$ $(0, 0), F(1, 0) = (1, 0), F(\infty) = \infty$ and

$$
F_{j_h} \to F \quad \text{locally uniformly.}
$$

By a result of S. Spagnolo ([\[S2,](#page-7-8) Theorem 2], see also [\[F\]](#page-7-9)) one has

$$
(3.6) \qquad J(x, F_{j_h}) \, (DF_{j_h})^{-1}(x)^t (DF_{j_h})^{-1}(x) \stackrel{G}{\to} J(x, F) \, (DF)^{-1}(x)^t (DF)^{-1}(x).
$$

Since \hat{A}_j G-converges to \hat{A} by the local character of G-convergence, we have

(3.7)
$$
\hat{A}(x) = J(x, F) (DF)^{-1}(x)^{t} (DF^{-1})(x) \text{ a.e. } x \in \mathbb{R}^2.
$$

Let us now show that the whole sequence F_j locally uniformly converges to F . Indeed, let F_{j_k} be any subsequence of F_j . By Lemma 5.2 of [\[GIKMS\]](#page-7-7) we can extract from F_{j_k} a further subsequence still denoted by F_{j_k} such that

$$
F_{j_k} \to \hat{F}
$$
 locally uniformly,

where \hat{F} is a K-quasiconformal mapping which satisfies $\hat{F}(0,0) = (0,0), \hat{F}(1,0) =$ $(1, 0)$, $\hat{F}(\infty) = \infty$. Again by Spagnolo's result we deduce that

(3.8)
$$
A(x) = J(x, \hat{F}) (D\hat{F})^{-1}(x)^t (D\hat{F}^{-1})(x) \text{ a.e. } x \in \mathbb{R}^2.
$$

Since the matrices of the right-hand sides of [\(3.7\)](#page-3-0) and [\(3.8\)](#page-3-1) coincide, there exists (see [\[LV\]](#page-7-10)) a Möbius transformation H such that

$$
\hat{F} = H \circ F.
$$

In complex notation, a Möbius transformation can be written as

$$
H(z) = \frac{az+b}{cz+d}, \quad z \in \mathbb{C},
$$

for some a, b, c, d in \mathbb{C} . In the same notation we have

$$
F(0) = 0
$$
, $F(1) = 1$, $F(\infty) = \infty$,

and

$$
\hat{F}(0) = 0
$$
, $\hat{F}(1) = 1$, $\hat{F}(\infty) = \infty$,

which together with (3.9) implies that

$$
H(z)=z,
$$

and therefore that $F = \hat{F}$. This implies that the whole sequence F_i converges to F. Applying the chain rule in [\(3.4\)](#page-2-0) allows one to write

(3.10)
$$
\hat{A}_j^{-1} \circ F_j^{-1}(y) = J(y, F_j^{-1})^t (DF_j^{-1})^{-1}(y) (DF_j^{-1})^{-1}(y).
$$

Since the inverse mappings F_j^{-1} are also K-quasiconformal and satisfy

$$
F_j^{-1} \to F^{-1} \quad \text{locally uniformly},
$$

applying once more Spagnolo's result, we infer that the sequence of matrices defined by the right-hand side of [\(3.10\)](#page-3-3) G-converges to

$$
J(y, F^{-1})^t (DF^{-1})^{-1}(y) (DF^{-1})^{-1}(y),
$$

which coincides with the matrix $\hat{A}^{-1} \circ F^{-1}$. This proves the desired result. \Box

4. THE ONE-DIMENSIONAL CASE

In this section we consider the one-dimensional case for which we prove a result similar to Theorem 3.1. Let $a_i \in L^{\infty}(\mathbb{R})$ be a sequence of measurable functions $a_i : \mathbb{R} \to \mathbb{R}$ satisfying the uniform bounds

$$
(4.1) \t1/K \le a_j(x) \le K \t a.e. x \in \mathbb{R},
$$

where $K \geq 1$ is a given constant. Up to a subsequence we may assume that

$$
(4.2) \t a_j \rightharpoonup a \quad \text{in } \sigma(L^{\infty}, L^1),
$$

(4.3)
$$
\frac{1}{a_j} \rightharpoonup \frac{1}{b} \quad \text{in } \sigma(L^{\infty}, L^1),
$$

for some functions $a, b \in L^{\infty}(\mathbb{R})$ with

$$
1/K \leq b(x) \leq a(x) \leq K \quad \text{ a.e. } x \in \mathbb{R}.
$$

Actually $b(x)$ may be strictly less than $a(x)$.

Nevertheless, the composition with suitable changes of variable $h_i : \mathbb{R} \to \mathbb{R}$ allows the inverses of a_i to weakly converge to the inverse of a .

THEOREM 4.1. *Let* $a_j \in L^{\infty}(\mathbb{R})$ *be a sequence satisfying* (4.1) *and* (4.2)*. Then there exists a sequence of increasing homeomorphisms* $h_i : \mathbb{R} \to \mathbb{R}$ which are uniformly *Lipschitz continuous together with their inverses and which converge locally uniformly on* \mathbb{R} *to a homeomorphism* $h : \mathbb{R} \to \mathbb{R}$ *such that*

(4.4)
$$
\frac{1}{a_j(h_j^{-1})} \rightharpoonup \frac{1}{a(h^{-1})} \quad \text{in } \sigma(L^{\infty}, L^1).
$$

PROOF. Define

(4.5)
$$
h_j(s) = c_j \int_0^s a_j(t) dt \quad \forall s \in \mathbb{R},
$$

where $c_i > 0$ is a sequence of constants which converges to some $c > 0$. Then

$$
h_j(s) \to h(s) = c \int_0^s a(t) dt \quad \forall s \in \mathbb{R},
$$

and also locally uniformly, because h_j is bounded in $W^{1,\infty}_{loc}(\mathbb{R})$.

By the chain rule, the inverse h_j^{-1} of h_j is given by

(4.6)
$$
h_j^{-1}(\sigma) = \int_0^{\sigma} \frac{1}{c_j a_j (h_j^{-1}(\tau))} d\tau \quad \forall \sigma \in \mathbb{R}.
$$

Since the sequence h_j^{-1} is bounded in $W_{loc}^{1,\infty}(\mathbb{R})$ and since the sequence h_j converges to h, one has

$$
h_j^{-1}(\sigma) \to h^{-1}(\sigma) \quad \forall \sigma \in \mathbb{R}
$$

where h^{-1} is given by

(4.7)
$$
h^{-1}(\sigma) = \int_0^{\sigma} \frac{1}{ca(h^{-1}(\tau))} d\tau.
$$

Since h_j^{-1} is bounded in $W_{loc}^{1,\infty}(\mathbb{R})$, h_j^{-1} also weak star converges to h^{-1} in $W_{loc}^{1,\infty}(\mathbb{R})$. The weak star convergence of the derivatives, namely

$$
(h_j^{-1})' \rightharpoonup (h^{-1})'
$$
 in $\sigma(L^{\infty}, L^1)$,

implies [\(4.4\)](#page-4-0) in view of [\(4.6\)](#page-5-0) and [\(4.7\)](#page-5-1), since c_i converges to c . \Box

REMARK 4.1. One could think that the definition (4.5) of h_j is the only possible choice in order to have (4.4) when (4.1) and (4.2) hold true, or in other words that h_j is uniquely determined up to the multiplicative constant c_j . We will prove in this remark that in general this is not the case, and that there are many other choices of functions h_i which satisfy (4.4) and the assumption of Theorem 4.1.

Observe indeed that (4.4) is equivalent to

$$
\int_0^{\sigma} \frac{1}{a_j(h_j^{-1}(\tau))} d\tau \to \int_0^{\sigma} \frac{1}{a(h^{-1}(\tau))} d\tau \quad \forall \sigma \in \mathbb{R}.
$$

By the changes of variable $h_j^{-1}(\tau) = t$, this can be rewritten as

(4.8)
$$
\int_0^{h_j^{-1}(\sigma)} \frac{h'_j(t)}{a_j(t)} dt \to \int_0^{h^{-1}(\sigma)} \frac{h'(t)}{a(t)} dt.
$$

Since h_j^{-1} tends to h^{-1} locally uniformly, (4.8), and therefore [\(4.4\)](#page-4-0), is equivalent to

$$
\int_0^s \frac{h'_j(t)}{a_j(t)} dt \to \int_0^s \frac{h'(t)}{a(t)} dt \quad \forall s \in \mathbb{R},
$$

that is, to

(4.9)
$$
\frac{h'_j}{a_j} \rightharpoonup \frac{h'}{a} \quad \text{in } \sigma(L^{\infty}, L^1).
$$

To prove that (4.5) is not the only possible choice for h_j , let us now consider the following example. Let a_j and h'_j be given by

$$
a_j(x) = \varphi(jx), \quad h'_j(x) = \psi(jx), \quad h_j(0) = 0,
$$

where φ and ψ are the periodic functions of period 1 defined on (0, 1) by

$$
\varphi(y) = A\chi_{(0,1/3)}(y) + B\chi_{(1/3,2/3)}(y) + C\chi_{(2/3,1)}(y),
$$

$$
\psi(y) = X\chi_{(0,1/3)}(y) + Y\chi_{(1/3,2/3)}(y) + Z\chi_{(2/3,1)}(y),
$$

where $\chi_{(a,b)}$ denotes the characteristic function of the interval (a, b) and where A, B, C, X, Y, Z are strictly positive constants. Then a_i satisfies (4.1) and (4.2) for some $K > 1$ and for a given by

$$
a(x) = \frac{1}{3}(A + B + C).
$$

The functions $h_i : \mathbb{R} \to \mathbb{R}$ are increasing homeomorphisms which are uniformly Lipschitz continuous together with their inverses, and which converge locally uniformly on $\mathbb R$ to the homeomorphism $h : \mathbb{R} \to \mathbb{R}$ defined by

$$
h'(x) = \frac{1}{3}(X + Y + Z), \quad h(0) = 0.
$$

In this example, convergence (4.9), which is equivalent to [\(4.4\)](#page-4-0), amounts to

(4.10)
$$
\frac{\frac{1}{3}(X+Y+Z)}{\frac{1}{3}(A+B+C)} = \frac{1}{3}\left(\frac{X}{A} + \frac{Y}{B} + \frac{Z}{C}\right),
$$

since the right-hand side of (4.10) is the $\sigma(L^{\infty}, L^{1})$ limit of h'_{j}/a_{j} . Formula (4.10) is equivalent to

(4.11)
$$
Z = \frac{3C(A + B + C)}{2C - (A + B)} \left[\frac{1}{3} \left(\frac{X}{A} + \frac{Y}{B} \right) - \frac{X + Y}{A + B + C} \right].
$$

For every A, B, X, $Y > 0$, if we choose $C > 0$ sufficiently large, then the number Z defined by (4.11) satisfies $Z > 0$, and all the assumptions of Theorem 4.1 are satisfied. But in general we do not have (4.5), since this would imply

$$
h'_j(s) = c_j a_j(s) \quad \forall s \in \mathbb{R},
$$

that is, $\psi(y) = c\varphi(y)$, an assertion which is false when we choose $X/A \neq Y/B$, a choice which is always possible.

ACKNOWLEDGEMENTS. Part of this work was done during a visit of the second author to the Dipartimento di Matematica e Applicazioni "R. Caccioppoli" dell'Universita di Napoli "Federico II", the hospitality of which is ` gratefully acknowledged. The work of the first and third authors was supported by MIUR/COFIN and GNAMPA-INdAM.

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Received 26 January 2006, and in revised form 3 March 2006.

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