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Partial Differential Equations — *The Neumann eigenvalue problem for the* ∞ -*Laplacian*, by L. ESPOSITO, B. KAWOHL, C. NITSCH and C. TROMBETTI, communicated on 12 December 2014.

ABSTRACT. — The first nontrivial eigenfunction of the Neumann eigenvalue problem for the *p*-Laplacian, suitably normalized, converges to a viscosity solution of an eigenvalue problem for the ∞ -Laplacian as $p \to \infty$. We show among other things that the limiting eigenvalue, at least for convex sets, is in fact the first nonzero eigenvalue of the limiting problem. We then derive a number of consequences, which are nonlinear analogues of well-known inequalities for the linear (2-)Laplacian.

KEY WORDS: Neumann eigenvalues, viscosity solutions, infinity Laplacian.

MATHEMATICS SUBJECT CLASSIFICATION 2010: 35P30, 35P15, 35J72, 35D40, 35J92, 35J70.

1. INTRODUCTION AND STATEMENTS

In this paper we study the ∞ -Laplacian eigenvalue problem under Neumann boundary conditions

(1)
$$\begin{cases} \min\{|\nabla u| - \Lambda u, -\Delta_{\infty} u\} = 0 & \text{in } \{u > 0\} \cap \Omega\\ \max\{-|\nabla u| - \Lambda u, -\Delta_{\infty} u\} = 0 & \text{in } \{u < 0\} \cap \Omega\\ -\Delta_{\infty} u = -\sum_{i,j=1}^{n} u_{x_i x_j} u_{x_j} u_{x_j} = 0 & \text{in } \{u = 0\} \cap \Omega\\ \frac{\partial u}{\partial y} = 0 & \text{on } \partial\Omega. \end{cases}$$

A solution *u* to this problem has to be understood in the viscosity sense, and the Neumann eigenvalue Λ is some nonnegative real constant. For $\Lambda = 0$ problem (1) has constant solutions. We consider those as trivial. Our main result is

THEOREM 1. Let Ω be a smooth bounded open convex set in \mathbb{R}^n then a necessary condition for the existence of nonconstant continuous solutions *u* to (1) is

(2)
$$\Lambda \ge \Lambda_{\infty} := \frac{2}{\operatorname{diam}(\Omega)}.$$

Moreover problem (1) admits a Lipschitz solution when $\Lambda = \frac{2}{\operatorname{diam}(\Omega)}$.

The results of this paper were presented on Sept. 09, 2014 by the second author in a seminar with the same title at Accademia Nazionale dei Lincei.

If Ω is merely bounded, connected and has Lipschitz boundary, then the notion of diameter can be generalized as in Definition 1. In that case solutions of (1) exist, see Section 2 or [16]. However, it is still unclear whether Λ_{∞} is always the first eigenvalue.

Theorem 1 has a number of interesting consequences, one of which we list right here. By the isodiametric inequality we may conclude

COROLLARY 1. If Ω^* denotes the ball of same volume as Ω , then the Szegö-Weinberger inequality $\Lambda_{\infty}(\Omega) \leq \Lambda_{\infty}(\Omega^*)$ holds.

For the case of the ordinary Laplacian (p = 2) this result was shown in [17] and [19]. For the 1-Laplacian case and convex plane Ω we refer to [9]. While the Faber-Krahn inequality $\lambda_p(\Omega^*) \leq \lambda_p(\Omega)$ holds for any p, the Szegö-Weinberger inequality has resisted attempts to be generalized to general p, and for general p we are unaware of any results in this direction. The reason why we call problem (1) ∞ -Laplacian eigenvalue problem under Neumann boundary conditions is that (1) can be derived as the limit $p \to \infty$ of Neumann eigenvalue problems for the p-Laplacian

(3)
$$\begin{cases} -\Delta_p u = \Lambda_p^p |u|^{p-2} u & \text{in } \Omega\\ |\nabla u|^{p-2} \frac{\partial u}{\partial n} = 0 & \text{on } \partial\Omega, \end{cases}$$

whenever Ω is a bounded open Lipschitz set of \mathbb{R}^n .

For the Dirichlet *p*-Laplacian eigenvalue problem on open bounded sets $\Omega \subset \mathbb{R}^n$

(4)
$$\begin{cases} -\Delta_p v = \lambda_p^p |v|^{p-2} v & \text{in } \Omega\\ v = 0 & \text{on } \partial\Omega, \end{cases}$$

the same limit was studied by Juutinen, Lindqvist and Manfredi in [12, 13]. They formulate and fully investigate the so-called Dirichlet ∞ -Laplacian eigenvalue problem employing the notion of viscosity solutions. Recall for instance that, when λ_p denotes for all $p \ge 1$ the first nontrivial eigenvalue of (4), the limit yields

$$\lim_{p\to\infty} \lambda_p = \lambda_\infty := \frac{1}{R(\Omega)},$$

where $R(\Omega)$ denotes inradius, i.e. the radius of the largest ball contained in Ω . Moreover, they identify the limiting eigenvalue problem as

(5)
$$\begin{cases} \min\{|\nabla v| - \lambda v, -\Delta_{\infty} v\} = 0 & \text{in } \Omega\\ v = 0 & \text{on } \partial\Omega, \end{cases}$$

in the sense that nonnegative normalized eigenfunctions of (4) converge, up to a subsequence, to a positive Lipschitz function v_{∞} which solves (5) in the viscosity sense with $\lambda(\Omega) = \lambda_{\infty}(\Omega)$. Finally they also show that the infinity Laplacian eigenvalue problem (5) admits nontrivial solutions if and only if $\lambda \ge \lambda_{\infty}$ and positive solutions if and only if $\lambda = \lambda_{\infty}$. Therefore they call λ_{∞} the principal eigenvalue of the ∞ -Laplacian eigenvalue problem under Dirichlet boundary condition.

In the Neumann case (see [16]) and for any bounded connected Ω with Lipschitz boundary the limiting problem $p \to \infty$ for (3) is given by (1).

In analogy to the Dirichlet case, the first nontrivial eigenvalues of (3) satisfy

(6)
$$\lim_{p\to\infty} \Lambda_p = \Lambda_\infty$$

Our result proves that on the class of convex sets the first nontrivial Neumann *p*-Laplacian eigenvalues converge to the first nontrivial Neumann ∞ -Laplacian eigenvalue, namely $\Lambda = \Lambda_{\infty}$ is in fact the first nontrivial eigenvalue in (1).

Therefore we can point out some consequences.

COROLLARY 2. For convex Ω the first positive Neumann eigenvalue $\Lambda_{\infty}(\Omega)$ is never larger than the first Dirichlet eigenvalue $\lambda_{\infty}(\Omega)$. Moreover $\lambda_{\infty}(\Omega) = \Lambda_{\infty}(\Omega)$ if and only if Ω is a ball.

The inequality $\Lambda_2(\Omega) < \lambda_2(\Omega)$ follows from a combination of the Szegö-Weinberger and the Faber-Krahn inequalities, see e.g. the books by Bandle or Kesavan [3, 14]. The strict inequality $\Lambda_p(\Omega) < \lambda_p(\Omega)$ for general p and any convex Ω has been recently proved in [2].

COROLLARY 3. For convex Ω any Neumann eigenfunction associated with $\Lambda_{\infty}(\Omega)$ cannot have a closed nodal domain inside Ω .

Since a Neumann eigenfunction u for the ∞ -Laplacian is in general just continuous, a closed nodal line inside Ω means that there exists an open subset $\Omega' \subset \Omega$ such that u > 0 in Ω' (or < 0 in Ω') and u = 0 on $\partial \Omega'$. Assuming that such a nodal line exists, we can use standard arguments. We observe that u is also a Dirichlet eigenfunction on Ω' with same eigenvalue. We get $\frac{2}{\operatorname{diam}(\Omega)} = \Lambda_{\infty}(\Omega) = \lambda_{\infty}(\Omega') = \frac{1}{R(\Omega')} \ge \frac{2}{\operatorname{diam}(\Omega)}$ and notice that the last inequality is strict for all sets other than balls. This proves the Corollary.

Next we recall that the Payne-Weinberger inequality states that on any convex subset $\Omega \subset \mathbb{R}^n$ the first nontrivial Neumann eigenvalue for the Laplacian is bounded from below by the quantity $\frac{\pi^2}{\operatorname{diam}(\Omega)^2}$. Recently such an estimate has been generalized to the first nontrivial Neumann *p*-Laplacian eigenvalues in [7, 8, 18] to get

(7)
$$\Lambda_p \ge (p-1)^{1/p} \left(\frac{2\pi}{p \operatorname{diam}(\Omega) \sin \frac{\pi}{p}} \right).$$

As $p \to \infty$ the right hand side in this Payne-Weinberger inequality (7) converges

$$\lim_{p \to \infty} (p-1)^{1/p} \left(\frac{2\pi}{p \operatorname{diam}(\Omega) \sin \frac{\pi}{p}} \right) = \frac{2}{\operatorname{diam}(\Omega)},$$

and in view of (6) we may therefore conclude that

COROLLARY 4. The Payne-Weinberger inequality (7) for the first Neumann eigenvalue of the p-Laplacian becomes an identity for $p = \infty$.

As a byproduct of our proofs we obtain also the following result, which is related to the hot-spot conjecture. The hot spot conjecture, see [4], says that a first nontrivial Neumann eigenfunction for the linear Laplace operator on a convex domain Ω should attain its maximum or minimum on the boundary $\partial \Omega$ and the proof of Lemma 1 will show that u_{∞} has this property as well. But there may be more than one eigenfunction associated to Λ_{∞} .

COROLLARY 5. If Ω is convex and smooth, then any first nontrivial Neumann eigenfunction, i.e. any viscosity solution to (1) for $\Lambda = \Lambda_{\infty}$ attains both its maximum and minimum only on the boundary $\partial \Omega$. Moreover the extrema of u are located at points that have maximal distance in $\overline{\Omega}$.

The proof of our main result, Theorem 1, will be a combination of Theorem 2 in Section 2 on the limiting problem as $p \to \infty$ and Proposition 1 in Section 3. Corollary 5 will be derived at the very end of this paper.

2. The limiting problem as $p \to \infty$

DEFINITION 1. Let Ω be a bounded open connected domain in \mathbb{R}^n . The intrinsic diameter of Ω , denoted by diam(Ω), is defined as

(8)
$$\operatorname{diam}(\Omega) := \sup_{x, y \in \Omega} d_{\Omega}(x, y)$$

whith d_{Ω} denoting geodetic distance in Ω .

Consider the eigenvalue problem

(9)
$$\Lambda_p^p = \min\left\{\frac{\int_{\Omega} |\nabla v|^p \, dx}{\int_{\Omega} |v|^p \, dx} : v \in W^{1,p}(\Omega), \int_{\Omega} |v|^{p-2} v \, dx = 0\right\}.$$

Let u_p be a minimizer of (9) such that $||u_p||_p = 1$, where $||f||_p^p = \frac{1}{|\Omega|} \int_{\Omega} |f|^p dx$. For every p > 1 u_p satisfies the Euler equation

(10)
$$\begin{cases} -\operatorname{div}(|\nabla u_p|^{p-2}\nabla u_p) = \Lambda_p^p |u_p|^{p-2} u_p & \text{in } \Omega\\ |\nabla u_p|^{p-2} \frac{\partial u_p}{\partial v} = 0 & \text{on } \partial\Omega \end{cases}$$

and

LEMMA 1. Let Ω be a connected bounded open set in \mathbb{R}^n with Lipschitz boundary, then

(11)
$$\lim_{p \to +\infty} \Lambda_p = \Lambda_{\infty} := \frac{2}{\operatorname{diam}(\Omega)}.$$

Here diam(Ω) denotes the intrinsic diameter as defined in (8).

PROOF. Step 1 $\limsup_{p\to\infty} \Lambda_p \leq \frac{2}{\operatorname{diam}(\Omega)}$.

We start proving that $\Lambda_{\infty} \leq 2/\text{diam}(\Omega)$. Let $x_0 \in \Omega$. We choose $c_p \in \mathbb{R}$ such that $w(x) = d_{\Omega}(x, x_0) - c_p$ is a good test function in (9), that is

$$\int_{\Omega} |w|^{p-2} w \, dx = 0.$$

Using this test function in (9) we get (recalling that $|\nabla d_{\Omega}(x, x_0)| \le 1$ a.e. in Ω)

(12)
$$\Lambda_p \leq \frac{1}{\left(\frac{1}{|\Omega|} \int_{\Omega} |d_{\Omega}(x, x_0) - c_p|^p\right)^{1/p}}$$

Now we observe that $0 \le c_p \le \text{diam}(\Omega)$ and thus up to a subsequence $c_p \to c$, with $0 \le c \le \text{diam}(\Omega)$, then we obtain

$$\liminf_{p \to \infty} \left(\frac{1}{|\Omega|} \int_{\Omega} |d(x, x_0) - c_p|^p \right)^{1/p} = \sup_{x \in \Omega} |d_{\Omega}(x, x_0) - c| \ge \operatorname{diam}(\Omega)/2$$

and then from (12) the Step 1 is proved.

Step 2 $\liminf_{p\to\infty} \Lambda_p \geq \frac{2}{\operatorname{diam}(\Omega)}$.

By definition we get

$$\left(\frac{1}{|\Omega|}\int_{\Omega}|\nabla u_p(x)|^p\,dx\right)^{1/p}=\Lambda_p.$$

Let us fix m > n. For p > m by Hölder inequality we have

$$\left(\frac{1}{|\Omega|}\int_{\Omega}|\nabla u_p(x)|^m dx\right)^{1/m} \leq \Lambda_p.$$

We can deduce that $\{u_p\}_{p\geq m}$ is uniformly bounded in $W^{1,m}(\Omega)$ and then assume that, up to a subsequence, u_p converges weakly in $W^{1,m}(\Omega)$ and in $C^0(\Omega)$ to a function $u_{\infty} \in W^{1,m}(\Omega)$. For q > m, by semicontinuity and Hölder inequality, we get

$$\frac{\left\|\nabla u_{\infty}\right\|_{q}}{\left\|u_{\infty}\right\|_{q}} \leq \liminf_{p \to \infty} \frac{\left(\frac{1}{\left|\Omega\right|} \int_{\Omega} \left|\nabla u_{p}(x)\right|^{q} dx\right)^{1/q}}{\left(\frac{1}{\left|\Omega\right|} \int_{\Omega} \left|u_{p}(x)\right|^{q} dx\right)^{1/q}} \leq \liminf_{p \to \infty} \frac{\left(\frac{1}{\left|\Omega\right|} \int_{\Omega} \left|\nabla u_{p}(x)\right|^{p} dx\right)^{1/p}}{\left(\frac{1}{\left|\Omega\right|} \int_{\Omega} \left|u_{p}(x)\right|^{q} dx\right)^{1/q}}$$

Thus

(13)
$$\frac{\|\nabla u_{\infty}\|_{q}}{\|u_{\infty}\|_{q}} \leq \frac{\|u_{\infty}\|_{\infty}}{\|u_{\infty}\|_{q}} \liminf_{p \to \infty} \Lambda_{p},$$

and letting $q \to \infty$ we get

(14)
$$\frac{\|\nabla u_{\infty}\|_{\infty}}{\|u_{\infty}\|_{\infty}} \leq \liminf_{p \to \infty} \Lambda_{p}.$$

Now we observe that condition $\int_{\Omega} |u_p|^{p-2} u_p = 0$ leads to

(15)
$$\sup u_{\infty} = -\inf u_{\infty},$$

infact we have

(16)
$$0 \leq | ||(u_{\infty})^{+}||_{p-1} - ||(u_{\infty})^{-}||_{p-1}| = | ||(u_{\infty})^{+}||_{p-1} - ||(u_{p})^{+}||_{p-1} + ||(u_{p})^{-}||_{p-1} - ||(u_{\infty})^{-}||_{p-1}| \leq | ||(u_{\infty})^{+}||_{p-1} - ||(u_{p})^{+}||_{p-1}| + ||(u_{\infty})^{-}||_{p-1} - ||(u_{p})^{-}||_{p-1}| \leq ||(u_{\infty})^{+} - (u_{p})^{+}||_{p-1} + ||(u_{\infty})^{-} - (u_{p})^{-}||_{p-1}.$$

Letting $p \to \infty$ we obtain (15). Using the following inequality (see for instance [5], p. 269)

$$|u_{\infty}(x) - u_{\infty}(y)| \le d_{\Omega}(x, y) \|\nabla u_{\infty}\|_{\infty} \le \operatorname{diam}(\Omega) \|\nabla u_{\infty}\|_{\infty},$$

we can conclude the proof by (14) observing that

$$2\|u\|_{\infty} = \sup u_{\infty} - \inf u_{\infty} \le \operatorname{diam}(\Omega) \|\nabla u_{\infty}\|_{\infty}.$$

REMARK 1. Our proof shows that u_{∞} increases with constant slope $\Lambda_{\infty} ||u_{\infty}||_{\infty}$ along the geodesic between two points spanning diam(Ω). In a rectangle this would be a diagonal.

Before proving Theorem 2 we recall the definition of viscosity super (sub) solution to

(17)
$$\begin{cases} F(u, \nabla u, \nabla^2 u) = \min\{|\nabla u| - \Lambda |u|, -\Delta_{\infty} u\} = 0 & \text{in } \{u > 0\} \cap \Omega \\ G(u, \nabla u, \nabla^2 u) = \max\{\Lambda |u| - |\nabla u|, -\Delta_{\infty} u\} = 0 & \text{in } \{u < 0\} \cap \Omega \\ H(\nabla^2 u) = -\Delta_{\infty} u = 0, & \text{in } \{u = 0\} \cap \Omega \\ \frac{\partial u}{\partial v} = 0 & \text{on } \partial\Omega. \end{cases}$$

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DEFINITION 2. An upper semicontinuous function *u* is a viscosity subsolution to (17) if whenever $x_0 \in \Omega$ and $\phi \in C^2(\Omega)$ are such that

$$u(x_0) = \phi(x_0)$$
, and $u(x) < \phi(x)$ if $x \neq x_0$, then

(18)
$$F(\phi(x_0), \nabla \phi(x_0), \nabla^2 \phi(x_0)) \le 0 \quad \text{if } u(x_0) > 0$$

(19)
$$G(\phi(x_0), \nabla \phi(x_0), \nabla^2 \phi(x_0)) \le 0 \quad \text{if } u(x_0) < 0$$

(20)
$$H(\nabla^2 \phi(x_0)) \le 0 \text{ if } u(x_0) = 0,$$

while if $x_0 \in \partial \Omega$ and $\phi \in C^2(\overline{\Omega})$ are such that

$$u(x_0) = \phi(x_0)$$
, and $u(x) < \phi(x)$ if $x \neq x_0$, then

(21)
$$\min\left\{F(\phi(x_0), \nabla\phi(x_0), \nabla^2\phi(x_0)), \frac{\partial\phi}{\partial\nu}(x_0)\right\} \le 0 \quad \text{if } u(x_0) > 0$$

(22)
$$\min\left\{G(\phi(x_0), \nabla\phi(x_0), \nabla^2\phi(x_0)), \frac{\partial\phi}{\partial\nu}(x_0)\right\} \le 0 \quad \text{if } u(x_0) < 0$$

(23)
$$\min\left\{H(\nabla^2\phi(x_0)), \frac{\partial\phi}{\partial\nu}(x_0)\right\} \le 0 \quad \text{if } u(x_0) = 0.$$

DEFINITION 3. A lower semicontinuous function u is a viscosity supersolution to (17) if whenever $x_0 \in \Omega$ and $\phi \in C^2(\Omega)$ are such that

(24)
$$u(x_0) = \phi(x_0), \quad \text{and} \quad u(x) > \phi(x) \quad \text{if } x \neq x_0, \quad \text{then}$$
$$F(\phi(x_0) \nabla \phi(x_0) \nabla^2 \phi(x_0)) > 0 \quad \text{if } u(x_0) > 0$$

(24)
$$F(\phi(x_0), \nabla\phi(x_0), \nabla^2\phi(x_0)) \ge 0$$
 if $u(x_0) > 0$

(25)
$$G(\phi(x_0), \nabla \phi(x_0), \nabla^2 \phi(x_0)) \ge 0 \text{ if } u(x_0) < 0$$

(26)
$$H(\nabla^2 \phi(x_0)) \ge 0 \text{ if } u(x_0) = 0,$$

while if $x_0 \in \partial \Omega$ and $\phi \in C^2(\overline{\Omega})$ are such that

$$u(x_0) = \phi(x_0)$$
, and $u(x) > \phi(x)$ if $x \neq x_0$,

then

(27)
$$\max\left\{F(\phi(x_0), \nabla\phi(x_0), \nabla^2\phi(x_0)), \frac{\partial\phi}{\partial\nu}(x_0)\right\} \ge 0 \quad \text{if } u(x_0) > 0$$

(28)
$$\max\left\{G(\phi(x_0), \nabla\phi(x_0), \nabla^2\phi(x_0)), \frac{\partial\phi}{\partial\nu}(x_0)\right\} \ge 0 \quad \text{if } u(x_0) < 0$$

(29)
$$\max\left\{H(\nabla^2\phi(x_0)), \frac{\partial\phi}{\partial\nu}(x_0)\right\} \ge 0 \quad \text{if } u(x_0) = 0.$$

DEFINITION 4. A continuous function u is a solution to (17) iff it is both a supersolution and a subsolution to (17).

REMARK 2. It is instructive to use the definition for checking that the onedimensional function $u(x) = x_1$ on the square $\Omega = (-1, 1) \times (-1, 1)$ is a viscosity solution of (17). In fact, $u \in C^2(\Omega)$, and $-\Delta_{\infty} u = 0$ in Ω .

So the first PDE in (17) is satisfied if also $1 = |\nabla u| \ge \Lambda u$ on $\{u > 0\}$, and that implies $\Lambda \le 1$.

The Neumann boundary condition is satisfied in classical sense on horizontal parts of $\partial \Omega$. However, for Neumann condition to hold in the viscosity sense on the right part, we must verify

$$\min\{\min\{|\nabla\phi| - \Lambda\phi, -\Delta_{\infty}\phi\}, \partial\phi/\partial\nu\}(x_0) \le 0$$

for any C^2 test function ϕ touching u in $x_0 \in \partial \Omega$ from above, and

$$\max\{\min\{|\nabla\psi| - \Lambda\psi, -\Delta_{\infty}\psi\}, \partial\psi/\partial\nu\}(x_0) \ge 0$$

for any smooth test function ψ touching *u* from below.

Recall $|\nabla u| = \partial u / \partial v = 1$ everywhere. Therefore only the very first constraint is active on the boundary and implies

 $\Lambda \geq 1.$

This shows that $u(x) = x_1$ is a viscosity solution to (17) with eigenvalue $\Lambda = 1$, but

$$\Lambda = 1 > \frac{1}{\sqrt{2}} = \frac{2}{\operatorname{diam}(\Omega)} = \Lambda_{\infty}.$$

In what follows we will use the notation

$$F_p(u, \nabla u, \nabla^2 u) = -(p-2)|\nabla u|^{p-4}\Delta_{\infty}u - |\nabla u|^{p-2}\Delta u - \Lambda_p^p|u|^{p-2}u$$

with

$$\Delta_{\infty} u = \sum_{i,j=1}^n u_{x_i} u_{x_i x_j} u_{x_j}.$$

LEMMA 2. Let $u \in W^{1,p}(\Omega)$ be a weak solution to

(30)
$$\begin{cases} -\operatorname{div}(|\nabla u|^{p-2}\nabla u) = \Lambda_p^p |u|^{p-2} u & \text{in } \Omega\\ |\nabla u|^{p-2} \frac{\partial u}{\partial v} = 0 & \text{on } \partial\Omega, \end{cases}$$

then u is a viscosity solution to

(31)
$$\begin{cases} F_p(u, \nabla u, \nabla^2 u) = 0 & \text{in } \Omega\\ |\nabla u|^{p-2} \frac{\partial u}{\partial v} = 0 & \text{on } \partial \Omega. \end{cases}$$

PROOF. That *u* is a viscosity solution to the differential equation $F_p = 0$ in Ω was shown in [13], Lemma 1.8. It remains to show that the Neumann boundary condition is satisfied in the viscosity sense as defined for instance in [10]. Let $x_0 \in \partial \Omega$, $\phi \in C^2(\overline{\Omega})$ such that $u(x_0) = \phi(x_0)$ and $\phi(x) < u(x)$ when $x \neq x_0$. Assume by contradiction that

(32)
$$\max\left\{|\nabla\phi(x_0)|^{p-2}\frac{\partial\phi}{\partial\nu}(x_0), F_p(\phi(x_0), \nabla\phi(x_0), \nabla^2\phi(x_0))\right\} < 0.$$

Then there exists a ball $B_r(x_0)$, centered at x_0 with radius r > 0, such that (32) holds true $\forall x \in \overline{\Omega} \cap B(x_0, r)$. Denote by $0 < m = \inf_{\overline{\Omega} \cap B_r(x_0)} (u(x) - \phi(x))$ and by $\psi(x) = \phi(x) + \frac{m}{2}$. Using $(\psi - u)^+$ as test function in the weak formulation we have both

$$\int_{\psi>u} |\nabla\psi|^{p-2} \nabla\psi\nabla(\psi-u) \, dx < \Lambda_p^p \int_{\psi>u} |\phi|^{p-2} \phi(\psi-u) \, dx$$

and

$$\int_{\psi>u} |\nabla u|^{p-2} \nabla u \nabla (\psi - u) \, dx = \Lambda_p^p \int_{\psi>u} |u|^{p-2} u(\psi - u) \, dx.$$

Subtraction yields the contradiction

$$(33) \qquad C \int_{\psi>u} |\nabla(\psi-u)|^p \, dx \le \int_{\psi>u} (|\nabla\psi|^{p-2}\nabla\psi - |\nabla u|^{p-2}\nabla u, \nabla(\psi-u)) \, dx$$
$$< \Lambda_p^p \int_{\psi>u} (|\phi|^{p-2}\phi - |u|^{p-2}u)(\psi-u) \, dx < 0. \qquad \Box$$

THEOREM 2. Let Ω be a bounded open connected set of \mathbb{R}^n . If u_{∞} and Λ_{∞} are defined as above then u_{∞} satisfies (17) in the viscosity sense with $\Lambda = \Lambda_{\infty}$.

PROOF. First we observe that in fact there exists a subsequence u_{p_i} uniformly converging to u_{∞} in Ω . Now let us prove that u_{∞} is a viscosity supersolution to (17) in Ω . Let $x_0 \in \Omega$ and let $\phi \in C^2(\Omega)$ be such that $\phi(x_0) = u_{\infty}(x_0)$ and $\phi(x) < u_{\infty}(x)$ for $x \in \Omega \setminus \{x_0\}$. Since $u_{p_i} \to u_{\infty}$ uniformly in $B_r(x_0)$ one can prove that $u_{p_i} - \phi$ has a local minimum in x_i , with $\lim_i x_i = x_0$. Recalling that u_{p_i} is a viscosity solution to (31), choosing $\psi(x) = \phi(x) - \phi(x_i) + u_{p_i}(x_i)$ as test function we obtain

(34)
$$-[(p_i - 2)|\nabla \phi(x_i)|^{p_i - 4} \Delta_{\infty} \phi(x_i) + |\nabla \phi(x_i)|^{p_i - 2} \Delta \phi(x_i)] \\ \ge \Lambda_{p_i}^{p_i} |u_{p_i}(x_i)|^{p_i - 2} u_{p_i}(x_i).$$

Three cases can occur.

• $u_{\infty}(x_0) > 0$. In this case (34) implies that $|\nabla \phi(x_i)| > 0$, hence dividing (34) by $|\nabla \phi(x_i)|^{p_i-4}(p_i-2)$ we have

(35)
$$-\frac{|\nabla\phi(x_i)|^2\Delta\phi(x_i)}{p_i-2} - \Delta_{\infty}\phi(x_i) \ge \left(\frac{\Lambda_{p_i}u_{p_i}(x_i)}{|\nabla\phi(x_i)|}\right)^{p_i-4}\frac{\Lambda_{p_i}^4u_{p_i}^3(x_i)}{p_i-2}.$$

Letting p_i go to $+\infty$ we have $\frac{\Lambda_{\infty}\phi(x_0)}{|\nabla\phi(x_0)|} \le 1$ and $-\Delta_{\infty}\phi(x_0) \ge 0$ hence

$$\min\{|\nabla\phi(x_0)| - \Lambda_{\infty}|\phi(x_0)|, -\Delta_{\infty}\phi(x_0)\} \ge 0.$$

• $u_{\infty}(x_0) < 0$. Also in this case (34) implies that $|\nabla \phi(x_i)| > 0$, and dividing by $|\nabla \phi(x_i)|^{p_i-4}(p_i-2)$ we have again (35). If $\frac{\Lambda_{\infty}\phi(x_0)}{|\nabla \phi(x_0)|} < 1$, letting p_i go to ∞ , we have $-\Delta_{\infty}\phi(x_0) \ge 0$, otherwise $\frac{\Lambda_{\infty}\phi(x_0)}{|\nabla \phi(x_0)|} \ge 1$. In both cases we have $\max\{\Lambda_{\infty}|\phi(x_0)| - |\nabla \phi(x_0)|, -\Delta_{\infty}\phi(x_0)\} \ge 0$.

•
$$u_{\infty}(x_0) = 0$$
. If $|\nabla \phi(x_0)| = 0$ then, by definition, we have $-\Delta_{\infty} \phi(x_0) = 0$. If $|\nabla \phi(x_0)| > 0$ then $\lim_i \frac{\Lambda_{p_i} |u_{p_i}(x_i)|}{|\nabla \phi(x_i)|} = 0$ hence (35) implies

$$-\Delta_{\infty}\phi(x_0) \ge 0.$$

It remains to prove that u_{∞} satisfies the boundary conditions in the viscosity sense.

Assume that $x_0 \in \partial \Omega$ and let $\phi \in C^2(\overline{\Omega})$ be such that $\phi(x_0) = u_{\infty}(x_0)$ and $\phi(x) < u_{\infty}(x)$ for $x \in \overline{\Omega} \setminus \{x_0\}$. Using again the uniform convergence of u_{p_i} to u_{∞} we obtain that $u_{p_i} - \phi$ has a minimum point $x_i \in \overline{\Omega}$, with $\lim_i x_i = x_0$.

If $x_i \in \Omega$ for infinitely many *i* arguing as before we get

$$\begin{split} \min\{|\nabla\phi(x_0)| - \Lambda_{\infty}|\phi(x_0)|, -\Delta_{\infty}\phi(x_0)\} &\geq 0 \quad \text{if } u(x_0) > 0\\ \max\{\Lambda_{\infty}|\phi(x_0)| - |\nabla\phi(x_0)|, -\Delta_{\infty}\phi(x_0)\} &\geq 0 \quad \text{if } u(x_0) < 0\\ -\Delta_{\infty}\phi(x_0) &\geq 0, \quad \text{if } u(x_0) = 0. \end{split}$$

If $x_i \in \partial \Omega$, since u_{p_i} is viscosity solution to (31), for infinitely many *i* we have

$$|\nabla \phi(x_i)|^{p_i-2} \frac{\partial \phi}{\partial v}(x_i) \ge 0$$

which concludes the proof.

Arguing in the same way we can prove that u_{∞} is a viscosity subsolution to (17) in Ω .

3. Λ_{∞} is the first non trivial eigenvalue

PROPOSITION 1. Let Ω be a smooth bounded open convex set in \mathbb{R}^n . If for some $\Lambda > 0$ problem (17) admits a nontrivial eigenfunction u, then $\Lambda \ge \Lambda_{\infty}$.

The main idea is to use a test function involving the distance from a suitable point $x_0 \in \Omega$. This function is smooth everywhere except x_0 . For the nonconvex case one may want to use intrinsic distance instead, which however is not of class C^2 , as pointed out in [1].

LEMMA 3. Let Ω , Λ and u be as in the statement of Proposition 1. Let Ω_1 be an open connected subset of Ω such that $u \ge m$ in $\overline{\Omega}_1$ for some positive constant m. Then u > m in Ω_1 .

PROOF. Let x_0 be any point in Ω_1 . Our aim is to show that $u(x_0) > m$. Obviously, for any given R > 0 such that $B_R(x_0) \subset \Omega_1$ we have $u \neq m$ in $B_R(x_0)$ otherwise we have in $B_R(x_0)$ that $|\nabla u| - \Lambda |u| < 0$ (in the viscosity sense) which violates the first equation in (17). This means that for any R > 0 such that $B_R(x_0) \subset \Omega_1$ it is possible to find $x_1 \in B_{R/4}(x_0)$ such that $u(x_1) > m$. The continuity of u implies that for some $\varepsilon > 0$ small enough, there exists $r \leq \text{dist}(x_0, x_1)$ such that $u > m + \varepsilon$ on $\partial B_r(x_1)$. Therefore the function

$$v(x) = m + \frac{\varepsilon}{\frac{R}{2} - r} \left(\frac{R}{2} - |x - x_1|\right) \quad \text{in } B_{R/2}(x_1) \setminus B_r(x_1)$$

is such that

$$-\Delta_{\infty}v = 0$$
 in $B_{R/2}(x_1) \setminus B_r(x_1)$.

Since

$$-\Delta_{\infty} u \ge 0$$
 in $B_{R/2}(x_1) \setminus B_r(x_1)$

in the viscosity sense, and

$$u \ge v$$
 on $\partial B_{R/2}(x_1) \cup \partial B_r(x_1)$

the comparison principle, see Theorem 2.1 in [11], implies that $u \ge v > m$ in $B_{R/2}(x_1) \setminus B_r(x_1)$ and therefore $u(x_0) > m$.

LEMMA 4. Let Ω , Λ and u be as in the statement of Proposition 1. Then u certainly changes sign.

PROOF. Since *u* is a nontrivial solution to (17), we can always assume, possibly changing the sign of the eigenfunction *u*, that it is positive somewhere. We shall prove that the minimum of *u* in $\overline{\Omega}$ is negative. We argue by contradiction and we assume that the minimum *m* is nonnegative. In view of Lemma 3 a positive minimum can not be attained in Ω . On the other hand zero as well can not

be attained as minimum in Ω . If so, since $u \neq 0$, there would exist a point $x_0 \in \Omega$ and a ball $B_R(x_0) \subset \Omega$ such that $u(x_0) = 0$ and $\max_{B_{R/4}(x_0)} u > 0$. Let $x_1 \in B_{R/4}(x_0)$ be such that $u(x_1) > 0$. The continuity of *u* implies that there exists $r \leq \operatorname{dist}(x_0, x_1)$ such that $u > u(x_1)/2$ on $\partial B_r(x_1)$. Therefore the function

$$v(x) = \frac{u(x_1)}{R - 2r} \left(\frac{R}{2} - |x - x_1|\right) \text{ in } B_{R/2}(x_1) \setminus B_r(x_1)$$

is such that

$$-\Delta_{\infty}v = 0$$
 in $B_{R/2}(x_1) \setminus B_r(x_1)$.

Since

 $-\Delta_{\infty} u \ge 0$ in $B_{R/2}(x_1) \setminus B_r(x_1)$

in the viscosity sense, and

$$u \ge v$$
 on $\partial B_{R/2}(x_1) \cup \partial B_r(x_1)$

the comparison principle, see Theorem 2.1 in [11], implies that $u \ge v > 0$ in $B_{R/2}(x_1) \setminus B_r(x_1)$ and therefore $u(x_0) > 0$.

Therefore the only possibility is that there exists $x_0 \in \partial \Omega$ nonnegative minimum point of *u*. We shall prove that $\frac{\partial u}{\partial v}(x_0) < 0$ in the viscosity sense in contradiction to (24)–(26). Indeed there certainly exist $\bar{x} \in \Omega$ and r > 0 such that the ball $B_r(\bar{x}) \subset \Omega$ is inner tangential to $\partial \Omega$ at x_0 and $\partial B_r(\bar{x}) \cap \partial \Omega = \{x_0\}$. Then the function

$$v(x) = u(\bar{x}) - \left(\frac{u(\bar{x}) - u(x_0)}{r}\right)(|x - \bar{x}|) \quad \text{in } B_r(\bar{x}) \setminus \{\bar{x}\}$$

satisfies

$$-\Delta_{\infty}v = 0$$
 in $B_r(\bar{x}) \setminus \{\bar{x}\}$

since

$$-\Delta_{\infty} u \ge 0$$
 in $B_r(\bar{x}) \setminus \{\bar{x}\}$

in the viscosity sense, and

$$u \ge v$$
 on $\partial B_r(\bar{x}) \cup \{\bar{x}\}$.

Using again the comparison principle, see Theorem 2.1 in [11], we get $u \ge v$ in $\overline{\Omega}$. Therefore the function

$$\phi = u(\bar{x}) - (u(\bar{x}) - u(x_0)) \left(\frac{|x - \bar{x}|}{r}\right)^{\frac{1}{2}}$$

is such that $\phi \in C^2(\overline{\Omega} - \{\overline{x}\}),$

$$\phi < v \le u \quad \text{in } B_r(\bar{x}) - \{\bar{x}\},$$

$$\phi(x) < u(x_0) \le u(x) \quad \text{in } \Omega \setminus B_r(\bar{x}),$$

and

$$u(x_0) = \phi(x_0).$$

However

(36)
$$\max\left\{F(\phi(x_0), \nabla\phi(x_0), \nabla^2\phi(x_0)), \frac{\partial\phi}{\partial\nu}(x_0)\right\} < 0$$

contradicts (24)-(26).

PROOF OF PROPOSITION 1. Let *u* be a non trivial eigenfunction of (17) and let us denote by $\Omega_+ = \{x \in \Omega : u(x) > 0\}$ and by $\Omega_- = \{x \in \Omega : u(x) < 0\}$. Lemma 4 ensures that they are both nonempty sets. Let us normalize the eigenfunction *u* such that

$$\max_{\overline{\Omega}} u = \frac{1}{\Lambda}.$$

Then $\Lambda u \leq 1$ which implies that

(37) $\min\{|\nabla u| - 1, -\Delta_{\infty}u\} \le 0 \quad \text{in } \Omega_+$

in the viscosity sense.

For every $x_0 \in \Omega \setminus \Omega_+$ and for every $\epsilon > 0$ and $\gamma > 0$ the function $g_{\epsilon,\gamma}(x) = (1+\epsilon)|x-x_0|-\gamma|x-x_0|^2$ belongs to $C^2(\Omega \setminus B_\rho(x_0))$ for every $\rho > 0$. If γ is small enough compared to ϵ , it verifies

(38)
$$\min\{|\nabla g_{\epsilon,\gamma}| - 1, -\Delta_{\infty} g_{\epsilon,\gamma}\} \ge 0 \quad \text{in } \Omega_+.$$

Therefore (a comparison) Theorem 2.1 in [11] ensures that

(39)
$$m = \inf_{x \in \Omega_+} (g_{\epsilon, \gamma}(x) - u(x)) = \inf_{x \in \partial \Omega_+} (g_{\epsilon, \gamma}(x) - u(x)).$$

Now $\partial \Omega_+$ contains certainly points in Ω and possibly on $\partial \Omega$. To rule out that the infimum in the right hand side of (39) is attained on $\partial \Omega$, assume that there exists $\bar{x} \in \partial \Omega \cap \partial \Omega_+$ such that $g_{\epsilon,\gamma}(\bar{x}) - u(\bar{x}) = m$ and choose $g_{\epsilon,\gamma} - m$ as test function in (21). By construction for every $x \in \partial \Omega \cap \partial \Omega_+$ and $\gamma < \frac{\epsilon}{2 \operatorname{diam}(\Omega)}$ it results that

$$\begin{aligned} |\nabla g_{\epsilon,\gamma}|(x) &= 1 + \epsilon - 2\gamma |x - x_0| > 1, \\ \frac{\partial g_{\epsilon,\gamma}}{\partial \nu}(x) &= ((1 + \epsilon) - 2\gamma |x - x_0|) \Big(\frac{x - x_0}{|x - x_0|}, \nu(x)\Big) > 0, \end{aligned}$$

and

$$-\Delta_\infty g_{\epsilon,\gamma}=2\gamma|
abla g_{\epsilon,\gamma}|^2>0$$

which give a contradiction to (21). Together with (39) this implies that

$$m = \inf_{x \in \Omega_+} (g_{\epsilon, \gamma}(x) - u(x)) = \inf_{x \in \partial \Omega_+ \cap \Omega} (g_{\epsilon, \gamma}(x) - u(x)) \ge 0.$$

Letting ϵ and γ go to zero we have that

(40)
$$|x - x_0| \ge u(x) \quad \forall x \in \{y : u(y) \ge 0\}, \quad \forall x_0 \in \{y : u(y) \le 0\}$$

hence

$$d^+ = \sup_{x \in \overline{\Omega}_+} \operatorname{dist}(x, \{u = 0\}) \ge \frac{1}{\Lambda}.$$

Arguing in the same way we obtain

$$d^- = \sup_{x \in \overline{\Omega}_-} \operatorname{dist}(x, \{u = 0\}) \ge \frac{1}{\Lambda}$$

hence

$$\operatorname{diam}(\Omega) \ge d^+ + d^- \ge \frac{2}{\Lambda},$$

which concludes the proof of our proposition.

Corollary 5 follows now easily. Returning to (40) pick $x = \bar{x}$ as the point in which *u* attains its maximum and correspondingly $x = \underline{x}$ as the point in which *u* attains its minimum. Then $d(\bar{x}, \Omega_{-}) \ge \frac{1}{\Lambda}$ and $d(\underline{x}, \Omega_{+}) \ge \frac{1}{\Lambda}$, so that diam $(\Omega) \ge |\bar{x} - \underline{x}| \ge \frac{2}{\Lambda}$. Since $\Lambda = \Lambda_{\infty}$, equality holds and the max and min of *u* are attained in boundary points which have farthest distance from each other.

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