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# Generalised Mean Averaging Interpolation by Discrete Cubic Splines

By

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#### Abstract

The aim of this work is to introduce for a discrete function, certain discrete integrals which may reduce in particular to usual Riemann Stieltjes integrals. We name them as Discrete Stieltjes integrals. The existence and convergence of a discrete cubic interpolatory spline whose discrete Stieltjes integrals between consecutive meshpoints match with the corresponding integrals of a given periodic discrete function, are studied.

**KEY WORDS:** Discrete Stieltjes Integrals, forward differences, central differences, Discrete Splines.

# §1. Introduction

Discrete integrals play a significant role in the theory of interpolation and approximation of functions defined on discrete subsets of the real line. Schumaker [8] and Lyche [4] have studied extensively the properties of discrete integrals. Here we introduce certain discrete integrals which we prefer to call Discrete Stieltjes (DS-) integrals, as they reduce in particular to the usual Riemann-Stieltjes integrals.

Schoenberg [7] and de Boor [1] have considered area matching interpolatory condition for even-degree splines. Considering Lebesgue integrals with respect to a non-negative measure, Sharma and Tzimbalario [9] have studied quadratic spline interpolants satisfying a fairly general mean-averaging condition. Similar interpolation problems for cubic splines and discrete cubic splines have been investigated in Dikshit [2] and Dikshit and Powar [3] respectively. Discrete splines are piecewise polynomials which satisfy smoothness requirements at knots in terms of differences. Our aim

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in this paper is to study the existence and convergence properties of a discrete cubic spline whose discrete Stieltjes integrals between consecutive meshpoints match with the corresponding integrals of a given discrete function. For terms and notations we refer to [11].

# §2. Discrete Cubic Interpolatory Spline

Given a real number h>0, let f be a bounded function and  $\alpha$  be a non decreasing function defined over a discrete interval  $[a,b]_h$ . The Discrete Stieltjes integral of f with respect to  $\alpha$  over  $[a,b]_h$  is defined as:

$$\int_{a}^{b} f(x) d_{h} \alpha(x) = \sum_{i=0}^{N-1} f(a+ih) \cdot [\alpha(a+(i+1)h) - \alpha(a+ih)], \qquad (2.1)$$

where it is assumed that b-a=Nh, N being a positive integer. The definition (2.1) remains valid if  $\alpha$  is monotonic non-increasing, or in fact, if  $\alpha$  is a function of bounded variation.

Let  $P = \{x_i\}_{i=0}^n$  with  $0 = x_0 < x_1 < \cdots < x_n = 1$ , be a uniform sequence of points in  $[0,1]_h$  such that  $x_i - x_{i-1} = p$ ,  $i = 1, 2, \cdots, n$ . A discrete cubic spline with knots in P is a piecewise cubic polynomial over [0,1] which satisfies the conditions:

$$D_{h}^{\{j\}}s_{i}(x_{i}) = D_{h}^{\{j\}}s_{i+1}(x_{i}) \qquad j = 0,1 \text{ and } 2,$$
  
$$i = 1,2, \dots n-1, \qquad (2.2)$$

where  $s_i$  is the restriction of s in  $[x_{i-1}, x_i]$  and  $D_h^{[j]}g$  is the  $j^{th}$  central difference of a function g. The space of discrete cubic splines with knots in P is denoted by S(4, P, h). Consider a non decreasing function  $\alpha$  defined over  $[0,1]_h$  such that

$$\alpha(x+p) - \alpha(x) = K; \tag{2.3}$$

K being a constant.

We shall investigate the following:

**Problem 2.1.** Given a 1-periodic discrete function f over  $[0,1]_h$ , does there exist a unique 1-periodic discrete cubic spline s in S(4,P,h) satisfying the interpolatory condition

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$$\int_{x_{i-1}}^{x_i} [f(x) - s(x)] d_h \alpha(x) = 0, \qquad i = 1, 2, \cdots, n?$$
(2.4)

A discrete cubic spline s can be represented in terms of its second central differences at meshpoints, as follows:

$$6 p s(x) = M_{i-1} (x_i - x)^{\{3\}} + M_i (x - x_{i-1})^{\{3\}} + 6c_i (x_i - x) + 6d_i (x - x_{i-1})$$
$$x_{i-1} \le x \le x_i, \qquad i = 1, 2, \dots, n;$$
(2.5)

where  $M_i = D_h^{\{2\}} s(x_i)$ . Also,  $c_i$  and  $d_i$  are arbitrary constants, which in view of conditions (2.2), are given by following relations

$$d_i = c_{i+1}$$
  

$$p^2 M_i = d_{i-1} - 2d_i + d_{i+1}.$$
(2.6)

For convenience, we set

$$\int_{x_{i-1}}^{x_i} f(x) d_h \alpha(x) = F_i, \quad \int_{x_{i-1}}^{x_i} (x_i - x)^{\{j\}} d_h \alpha(x) = A(j),$$

and

$$\int_{x_{i-1}}^{x_i} (x-x_{i-1})^{(j)} d_h \alpha(x) = B(j). \qquad j=1,2,\cdots,n.$$

In view of (2.3) we find that

$$A(j) = \int_{x_{r-1}}^{x_r} (x_r - x)^{\{j\}} d_h \alpha(x)$$
  

$$B(j) = \int_{x_{r-1}}^{x_r} (x - x_{r-1})^{\{j\}} d_h \alpha(x) \qquad r = 1, 2, \dots, n;$$
  

$$j = 1, 2, \dots$$

and

$$\int_{x_{i-1}}^{x_i} d_h \alpha = K = (1/p)[A(1) + B(1)], \quad \text{for each } i.$$

Thus, from interpolatory condition (2.4) we obtain the following

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$$6p \ F_i = M_{i-1}A(3) + M_i \ B(3) + 6 \ d_{i-1} \ A(1) + 6 \ d_i \ B(1).$$

Eliminating  $d_i$ 's in (2.6) and the above equation we get

$$B(3) \ M_{i+1} + [A(3) - 2 \ B(3) + 6 \ p^2 \ B(1)]M_i$$
  
+ [-2 \ A(3) + B(3) + 6p^2 \ A(1)]M\_{i-1} + A(3) \ M\_{i-2}  
= 6p(F<sub>i+1</sub> - 2F<sub>i</sub> + F<sub>i-1</sub>), i=1,2,...,n, (2.7)

where  $M_n = M_0$ ,  $M_{n+1} = M_1$ ,  $F_n = F_0$  and  $F_{n+1} = F_1$ . Now in view of the properties of Discrete Stieltjes integrals, it is easy to see that when p > 2h,

$$A(3) \ge 0, B(3) \ge 0$$
  
 $p^2 A(1) \ge A(3) \text{ and } p^2 B(1) \ge B(3).$ 

Therefore the coefficients of  $M_{i+1}$ ,  $M_i$ ,  $M_{i-1}$  and  $M_{i-2}$  are all nonnegative. Also, the excess of coefficient of  $M_{i-1}$  over the sum of coefficients of  $M_{i+1}$ ,  $M_i$  and  $M_{i-2}$  is

$$2[-2A(3) + B(3) + 3p^{2}(A(1) - B(1))]$$
  
=  $2\int_{0}^{p} [p^{\{3\}} + 3x^{\{3\}} - 6px^{2} + 3ph^{2}]d_{h}\alpha.$  (2.8)

Now if non-decreasing function  $\alpha$  is such that it remains constant after x = .466p in each mesh interval then the expression (2.8) is positive. The coefficient matrix of the system of equations (2.7) is then diagonally dominant and the system admits a unique solution.

Again, considering the excess of coefficient of  $M_i$  over the sum of coefficients of  $M_{i+1}$ ,  $M_{i-1}$ ,  $M_{i-2}$  we observe that if the function  $\alpha$  is such that it remains constant upto x = .533p in each subinterval  $[0,p]_h$ , then the coefficient matrix of the system of equations (2.7) is invertible and the system is uniquely solved.

We have thus proved the following:

**Theorem 2.1.** Given a 1-periodic function f and a non-decreasing function  $\alpha$  defined over  $[0,1]_h$  such that (2.3) holds, there exists a unique 1-periodic discrete cubic spline  $s \in S(4,P,h)$  with p > 2h, satisfying (2.4) provided  $\alpha$  is a function such that it remains constant either in  $[.466p,p]_h$  or in  $[0,.533p]_h$  for

each subinterval  $[0,p]_h$  of the mesh P.

### §3. Convergence

Now we aim to establish the convergence properties of the discrete cubic spline interpolant of Theorem 2.1. Let e=s-f denote the error function. We estimate the error-bounds in terms of *'discrete norm'* and *'discrete modulus of smoothness'* denoted by ||f|| and w(f,t) respectively (cf. [11]).

We shall prove the following:

**Theorem 3.1.** If  $f,\alpha$ , and  $s \in S(4,P,h)$  be as in Theorem 2.1, then

$$\|e_{i}^{\{2\}}\| \leq K_{1} w(f^{(2)}, p)$$
(3.1)

and

where  $K_1$  is a constant.

Proof of the theorem. Replacing  $M_i$  in (2.7) by  $e_i^{\{2\}} + f_i^{\{2\}}$ , we have

 $||e^{\{2\}}|| \leq (K_1+1)w(f^{(2)},p),$ 

$$B(3) \ e_{i+1}^{\{2\}} + [A(3) - 2B(3) + 6p^2 \ B(1)]e_i^{\{2\}} \\ + [-2A(3) + B(3) + 6p^2 \ A(1)]e_{i-1}^{\{2\}} + A(3)e_{i-2}^{\{2\}} = 6p(F_{i+1} - 2F_i + F_{i-1}) \\ - B(3)f_{i+1}^{\{2\}} - [A(3) - 2B(3) + 6p^2 \ B(1)]f_i^{\{2\}} \\ - [-2A(3) + B(3) + 6p^2A(1)]f_{i-1}^{\{2\}} - A(3)f_{i-2}^{\{2\}} \equiv R(\text{say}).$$

Expanding f(x) in each subinterval by Discrete Taylor formula we get

$$F_i = f_{i-1}K + f_{i-1}^{(1)} B(1) + \theta_i f^{(2)}(z_i) \bar{B}(2)$$

where  $0 \le \theta_i \le 1$ ,  $z_i \in (x_{i-1}, x_i)_h$ ;  $(x - x_{i-1})^{(2)} = (x - x_{i-1})(x - x_{i-1} - h)$  and

$$\bar{B}(2) = \int_{x_{i-1}}^{x_i} (x - x_{i-1})^{(2)} d_h \alpha(x).$$

We observe that

$$f_{i-2} - 2f_{i-1} + f_i = p^2 f^{(2)}(y_i);$$

where  $y_i \in (x_{i-2}, x_i)_h$ ; and

$$|f_{i-2}^{(1)} - 2f_{i-1}^{(1)} + f_i^{(1)}| \le 2p \ w(f^{(2)}, p).$$

(3.2)

Therefore,

$$|R| \le 2[A(3) + B(3) + 6p\bar{B}(2) + 6p^2B(1) + 3p^3K] w(f^{(2)}, p).$$

If  $|e_i^{\{2\}}| \ge |e_i^{\{2\}}|$ ,  $i=1,2,\dots,n$ ; then from (2.7) we have

$$2[A(3) - 2B(3) + 3p^{2}(B(1) - A(1))] |e_{i}^{\{2\}}| \leq |R|.$$

This directly leads to (3.1). It is easy to see from (2.5) that in  $[x_{i-1}, x_i]$ ,

$$ps^{\{2\}}(x) = M_{i-1}(x_i - x) + M_i(x - x_{i-1}).$$

Therefore,

$$p e^{\{2\}}(x) = [e_{i-1}^{\{2\}} + f^{\{2\}}(x) - f_{i-1}^{\{2\}}](x - x_{i-1}) + [e_{i}^{\{2\}} + f^{\{2\}}(x) - f_{i-1}^{\{2\}}](x_{i} - x).$$

A little calculation then leads to (3.2). This completes the proof of Theorem 3.1.

# Remarks.

1. In the case when  $\alpha(x) = x$  and  $h \to 0$ , the mean averaging condition (2.4) reduces to the area matching condition considered in [10].

2. When  $\alpha$  is a step function, for suitable choices of function  $\alpha$ , the interpolatory condition (2.4) reduces to different conditions of interpolation at one or more interior points in each mesh interval (cf. Meir and Sharma [6]). When  $\alpha$  has a single jump at one end point in each mesh interval then the discrete cubic spline of Theorem 2.1 reduces to that considered in Lyche [5]. For an other appropriate choice of function  $\alpha$  the interpolatory condition (2.4) reduces to the average-interpolation condition considered in [11].

3. The estimates (3.1) and (3.2) in Theorem 3.1 are sharp, i.e., as a functions of *n*, they decrease to zero, when  $n \to \infty$  like  $\beta \cdot n^{-1}$  where  $\beta$  is a constant.

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