

Magnetic Pseudodifferential Operators with Coefficients in C^* -Algebras

by

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Abstract

In previous articles, a magnetic pseudodifferential calculus and a family of C^* -algebras associated with twisted dynamical systems were introduced and the connections between them have been established. We extend this formalism to symbol classes of Hörmander type with an x -behavior modeled by an abelian C^* -algebra. Some of these classes generate C^* -algebras associated with the twisted dynamical system. We show the relevance of these classes to the spectral analysis of pseudodifferential operators with anisotropic symbols and magnetic fields.

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§1. Introduction

In previous works [13, 25, 27] a twisted form of the usual Weyl calculus and of the corresponding crossed product C^* -algebras has been introduced. We refer to [15, 16, 22, 23, 29] for related works. The twisting is defined by a 2-cocycle on the group \mathbb{R}^n with values in the unitary group of a function algebra. The calculus is meant to model the family of observables of a physical system consisting of a spin-

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less particle moving in the euclidean space \mathbb{R}^n under the influence of a variable magnetic field B . It goes without saying that the standard theory is recovered for $B = 0$. The 2-cocycle is defined by fluxes of the magnetic field over simplexes and it corresponds to a modification of the canonical symplectic structure of the phase space \mathbb{R}^{2n} by a magnetic contribution. Actually the modified symplectic form defines a new Poisson algebra structure on the smooth classical observables on \mathbb{R}^{2n} and it was shown in [26] that the twisted form of the Weyl calculus constitutes a strict deformation quantization in the sense of Rieffel [17, 35] of the usual Poisson algebra.

A basic requirement for a magnetic pseudodifferential theory is gauge covariance. The magnetic field B being a closed 2-form in \mathbb{R}^n , it can be generated in many equivalent ways by derivatives of 1-forms, traditionally named vector potentials. These vector potentials are involved in the process of prescribing operators (intended to represent quantum observables) to classical functions defined on the phase space. Different equivalent choices should lead to unitarily equivalent operators, and this is indeed the case for our formalism (see Section 2.2), in contrast to previous wrong attempts.

Most often the usual pseudodifferential calculus is studied in the framework of the Hörmander symbol classes $S_{\rho,\delta}^m(\mathbb{R}^{2n})$. The necessary magnetic adaptations, nontrivial because of the bad behavior of the derivatives of the magnetic flux, were performed in [13]. Among others, the following results were obtained: good composition properties, asymptotic developments, an extension of the Calderón–Vaillancourt result on L^2 -boundedness, self-adjointness of elliptic operators on magnetic Sobolev spaces and positivity properties. A short recall of the magnetic pseudodifferential theory may be found in Sections 2.1 and 2.2.

Besides the order of a pseudodifferential operator defined by a symbol f , another useful information is the properties of the coefficients, i.e. the behavior of the function $x \mapsto f(x, \xi)$ at fixed ξ . One possible way to take them into account is to confine them to some abelian C^* -algebra \mathcal{A} of functions on \mathbb{R}^n . In the framework of the standard calculus this was performed in a variety of situations, with a special emphasis on almost periodic functions, and with various purposes; see for example [3, 4, 5, 6, 36]. In Section 2 of the present paper, we investigate the corresponding magnetic case, insisting on composition properties. In this respect, we extend the results of [13] on magnetic composition of symbols by considering a more refined and flexible setting. The techniques of oscillatory integrals are again used, but an improved control on the x -behavior of the symbols is necessary and does not follow from our previous works. We also use this opportunity to improve some results of [13] on asymptotic developments.

As soon as the symbol spaces with coefficients in \mathcal{A} are shown to possess good properties, they can be used to define non-commutative C^* -algebras composed of distributions in phase space. Such algebras are investigated in Section 3.1. Then a partial Fourier transformation makes the connection with the approach of [27] recalled in Section 3.2. In that reference, relying on general constructions of [31, 32], magnetic C^* -algebras were introduced in relation with twisted C^* -dynamical systems. These C^* -algebras are called twisted crossed products and can be defined by a universal property with respect to covariant representations. And once again the 2-cocycle obtained by the flux of the magnetic field is the main relevant object, defining both the twisted action and the algebraico-topological structure of the non-commutative C^* -algebras. Through various representations, these algebras will become concrete C^* -algebras of magnetic pseudodifferential operators in natural Hilbert spaces.

Non-commutative C^* -algebras composed of distributions in phase space can be generated by \mathcal{A} -valued symbols of strictly negative orders, as shown in Section 3.1. But having in mind applications to the spectral analysis of unbounded operators, we undertake in Section 3.4 the task to relate positive order symbols to these algebras. The key ingredient for that purpose is to understand inversion with respect to the magnetic composition law, or equivalently, to understand inversion of magnetic pseudodifferential operators. This is the subject of Section 3.3. Among other things we show that the inverse of a real elliptic symbol of order $m > 0$ with coefficients in \mathcal{A} is a symbol of order $-m$, also with coefficients in \mathcal{A} . Combined with results of the previous section, this implies that such a symbol defines an affiliated observable, meaning that its C_0 -functional calculus is contained in the twisted crossed product C^* -algebra. We also deduce that the \mathcal{A} -valued symbols of order 0 form a Ψ^* -algebra, and in particular that this algebra is spectrally invariant.

These results on inversion rely at a crucial step on a theorem from [14]. This theorem, which characterizes magnetic pseudodifferential operators of suitable classes by their behaviors under successive commutators, is an extension of classical results of Beals and Bony. For the sake of completeness, we give an independent proof for the affiliation in an Appendix, extending the approach of [28].

Our main motivation was spectral analysis, and the last section is devoted to this subject. Even for the simplest magnetic differential operator the determination of its spectrum involves a rather high degree of complexity. The main reason is that even though the magnetic field is the relevant physical object, the operators are defined by a vector potential. Such vector potentials are not unique and one problem is to show the independence of the result from a particular choice. Another

difficulty is that usually any vector potential defining a magnetic field will be ill-behaved compared to the magnetic field itself. For example, bounded magnetic fields might not admit any bounded vector potential, certain periodic magnetic fields are only defined by non-periodic vector potentials, etc. And on top of all that, general pseudodifferential operators with magnetic fields were not even correctly defined a couple of years ago.

So Section 4 is devoted to spectral theory. We investigate the essential spectrum of magnetic pseudodifferential operators affiliated to the non-commutative algebras mentioned before. The key of this approach is the use of the structure of twisted crossed products; see [7, 8, 9, 24, 34] for related approaches in the absence of magnetic field, and also [11, 18] for a description of the essential spectrum for certain classes of magnetic fields. We will show how to find information on the essential spectrum in the quasi-orbit structure of the Gelfand spectrum of the C^* -algebra \mathcal{A} .

In particular, this allows us to express in Section 4.2 the essential spectrum of any elliptic magnetic pseudodifferential operators defined by a symbol of positive order and with coefficients in \mathcal{A} in terms of simpler operators that are defined on quasi-orbits at infinity. For example, our approach covers generalized Schrödinger operators of the form $h(-i\partial - A) + V$, with h a real elliptic symbol of positive order, and with V and the components of the magnetic field B in some smooth subalgebra of \mathcal{A} . But more generally, our approach works for any operator of the form $f(-i\partial - A, X)$, once suitably defined, for f a real and elliptic symbol of positive order with coefficients in \mathcal{A} . We stress that there is no condition on A , only the components of the magnetic fields have to satisfy some smoothness conditions and have to belong to \mathcal{A} . We also emphasize that even in the degenerate case $B = 0$, we have not been able to locate in the literature a procedure for the calculation of the essential spectrum of such general pseudodifferential operators with coefficients in some abelian C^* -algebra \mathcal{A} .

It is rather obvious that the formalism and techniques of this article can be further developed and extended. More general twisted actions can be taken into account (cf. [35] for the untwisted case). This would open the way towards applications to random magnetic operators, which is the topic of a forthcoming article. Our approach might also be relevant for index theory. On the other hand, the groupoid setting has shown its role in pseudodifferential theory, in C^* -algebraic spectral analysis and in quantization; we cite for example [17, 20, 21, 30]. Groupoids with 2-cocycles and associated C^* -algebras are available [33], but they are still largely ignored in connection with applications. Extending the pseudodifferential calculus and the spectral theory to such a framework would be an interesting topic.

§2. Pseudodifferential theory

§2.1. The magnetic Moyal algebra

We recall the structure and the basic properties of the magnetic Weyl calculus in a variable magnetic field. The main references are [25] and [13], which contain further details and technical developments.

Let $\mathcal{X} := \mathbb{R}^n$ and let us denote by \mathcal{X}^* the dual space of \mathcal{X} ; the duality is given by $\mathcal{X} \times \mathcal{X}^* \ni (x, \xi) \mapsto x \cdot \xi$. The Lebesgue measures on \mathcal{X} and \mathcal{X}^* are normalized in such a way that the Fourier transform $(\mathcal{F}f)(\xi) = \int_{\mathcal{X}} dx e^{ix \cdot \xi} f(x)$ induces a unitary map from $L^2(\mathcal{X})$ to $L^2(\mathcal{X}^*)$. The phase space is $\Xi := T^*\mathcal{X} \equiv \mathcal{X} \times \mathcal{X}^*$ and the notations $X = (x, \xi)$, $Y = (y, \eta)$ and $Z = (z, \zeta)$ will be systematically used for its points. If no magnetic field is present, the standard symplectic form on Ξ is given by

$$(2.1) \quad \sigma(X, Y) \equiv \sigma((x, \xi), (y, \eta)) := y \cdot \xi - x \cdot \eta.$$

The magnetic field is described by a closed 2-form B on \mathcal{X} . In the standard coordinates system on \mathcal{X} it is represented by a function taking real and antisymmetric matrix values $\{B_{jk}\}$, with $j, k \in \{1, \dots, n\}$, and satisfying the relation $\partial_j B_{kl} + \partial_k B_{lj} + \partial_l B_{jk} = 0$. We shall always assume that the components of magnetic fields are smooth functions, and additional requirements will be imposed when needed.

Classically, the effect of B is to change the geometry of phase space, by adding an extra term to (2.1): $\sigma^B := \sigma + \pi^* B$, where π^* is the pull-back associated to the cotangent bundle projection $\pi : \Xi \rightarrow \mathcal{X}$. In coordinates one has

$$(\sigma^B)_{(Z)}(X, Y) = y \cdot \xi - x \cdot \eta + B(z)(x, y) = \sum_{j=1}^n (y_j \xi_j - x_j \eta_j) + \sum_{j,k=1}^n B_{jk}(z) x_j y_k.$$

Associated with this new symplectic form is the Poisson bracket acting on elements $f, g \in C^\infty(\Xi)$:

$$\{f, g\}^B = \sum_{j=1}^n (\partial_{\xi_j} f \partial_{x_j} g - \partial_{\xi_j} g \partial_{x_j} f) + \sum_{j,k=1}^n B_{jk} \partial_{\xi_j} f \partial_{\xi_k} g.$$

It is a standard fact that $C^\infty(\Xi; \mathbb{R})$ endowed with $\{\cdot, \cdot\}^B$ and with pointwise multiplication is a *Poisson algebra*, i.e. $C^\infty(\Xi; \mathbb{R})$ is a real abelian algebra and $\{\cdot, \cdot\}^B : C^\infty(\Xi; \mathbb{R}) \times C^\infty(\Xi; \mathbb{R}) \rightarrow C^\infty(\Xi; \mathbb{R})$ is an antisymmetric bilinear composition law that satisfies the Jacobi identity and is a derivation with respect to the usual product.

In the quantum picture, the magnetic field B comes into play in defining a new composition law in terms of its fluxes through triangles. For $x, y, z \in \mathcal{X}$, let $\langle x, y, z \rangle$ denote the triangle in \mathcal{X} of vertices x, y and z and set

$$\Gamma^B(\langle x, y, z \rangle) := \int_{\langle x, y, z \rangle} B$$

for the flux of B through this triangle (integration of a 2-form over a 2-simplex). With this notation, one defines the *Moyal product* by the formula

$$(2.2) \quad (f \#^B g)(X) := 4^n \int_{\Xi} dY \int_{\Xi} dZ e^{-2i\sigma(Y,Z)} e^{-i\Gamma^B(\langle x-y-z, x+y-z, x-y+z \rangle)} f(X-Y)g(X-Z)$$

for $f, g : \Xi \rightarrow \mathbb{C}$. For $B = 0$ it coincides with the Weyl composition of symbols in pseudodifferential theory. The composition law $\#^B$ provides an intrinsic algebraic structure underlying the multiplication of *magnetic pseudodifferential operators* that are going to be defined below.

The integrals defining $f \#^B g$ are absolutely convergent only for a restricted class of symbols. In order to deal with more general distributions, an extension by duality was proposed in [26] under an additional condition on the magnetic field. So let us assume that the components of the magnetic field are $C_{\text{pol}}^\infty(\mathcal{X})$ -functions, i.e. they are indefinitely derivable and each derivative is polynomially bounded, and let $\mathcal{S}(\Xi)$ denote the Schwartz space on Ξ . Its dual is denoted by $\mathcal{S}'(\Xi)$. Then $\mathcal{S}(\Xi)$ is stable under $\#^B$, and the product can be extended to maps $\mathcal{S}(\Xi) \times \mathcal{S}'(\Xi) \rightarrow \mathcal{S}'(\Xi)$ and $\mathcal{S}'(\Xi) \times \mathcal{S}(\Xi) \rightarrow \mathcal{S}'(\Xi)$. Denoting by $\mathcal{M}^B(\Xi)$ the largest subspace of $\mathcal{S}'(\Xi)$ for which $\mathcal{S}(\Xi) \#^B \mathcal{M}^B(\Xi) \subset \mathcal{S}(\Xi)$ and $\mathcal{M}^B(\Xi) \#^B \mathcal{S}(\Xi) \subset \mathcal{S}(\Xi)$, it can be shown that $\mathcal{M}^B(\Xi)$ is an involutive algebra under $\#^B$ and under the involution $\#^B$ obtained by complex conjugation. Note that one also has $\mathcal{S}'(\Xi) \#^B \mathcal{M}^B(\Xi) \subset \mathcal{S}'(\Xi)$ and $\mathcal{M}^B(\Xi) \#^B \mathcal{S}'(\Xi) \subset \mathcal{S}'(\Xi)$.

The *Moyal algebra* $\mathcal{M}^B(\Xi)$ is quite a large class of distributions, containing the Fourier transform of all bounded measures on Ξ as well as the class $C_{\text{pol,u}}^\infty(\Xi)$ of all smooth functions on Ξ having polynomial growth at infinity uniformly in all the derivatives. In addition, if we assume that all the derivatives of the functions B_{jk} are bounded, the Hörmander classes of symbols $S_{\rho,\delta}^{m_j}(\Xi)$ are contained in $\mathcal{M}^B(\Xi)$ and compose in the usual way under $\#^B$:

$$(2.3) \quad S_{\rho,\delta}^{m_1}(\Xi) \#^B S_{\rho,\delta}^{m_2}(\Xi) \subset S_{\rho,\delta}^{m_1+m_2}(\Xi)$$

for $m_1, m_2 \in \mathbb{R}$ and $0 \leq \delta < \rho \leq 1$ or $\rho = \delta = 0$. Here we have used the following standard definition:

Definition 2.1. The space $S_{\rho,\delta}^m(\Xi)$ of symbols of order m and of type (ρ, δ) is

$$\{f \in C^\infty(\Xi) \mid \forall \alpha, a \in \mathbb{N}^n, \exists C_{\alpha a} < \infty \text{ such that} \\ |(\partial_x^a \partial_\xi^\alpha f)(x, \xi)| \leq C_{\alpha a} \langle \xi \rangle^{m-\rho|\alpha|+\delta|a|}, \forall (x, \xi) \in \Xi\}.$$

It is well known that $S_{\rho,\delta}^m(\Xi)$ is a Fréchet space under the family of seminorms $\{\sigma_m^{\alpha a}\}_{\alpha, a \in \mathbb{N}^n}$, where $\sigma_m^{\alpha a} : S_{\rho,\delta}^m(\Xi) \rightarrow \mathbb{R}_+$ is defined by

$$\sigma_m^{\alpha a}(f) := \sup_{(x, \xi) \in \Xi} \langle \xi \rangle^{-m+\rho|\alpha|-\delta|a|} |(\partial_x^a \partial_\xi^\alpha f)(x, \xi)|.$$

Remark 2.2. The product formula (2.3) was proved in [13, Thm. 2.2] under the assumption $0 \leq \delta < \rho \leq 1$. But the special case $\rho = \delta = 0$ is a consequence of the statement contained in [14].

§2.2. Magnetic pseudodifferential operators

Being a closed 2-form in \mathcal{X} , the magnetic field can be written as $B = dA$ for some 1-form A called a *vector potential*. Any equivalent choice $A' = A + d\psi$, with $\psi : \mathcal{X} \rightarrow \mathbb{R}$ of suitable smoothness, will give the same magnetic field. It is easy to see that if B is of class $C_{\text{pol}}^\infty(\mathcal{X})$, then A can be chosen in the same class, which is tacitly assumed in what follows. For example, the vector potential in the so-called “transversal gauge” satisfies this property.

For any vector potential A defining the magnetic field B , and for $x, y \in \mathcal{X}$, let us write

$$\Gamma^A([x, y]) := \int_{[x, y]} A$$

for the circulation of A along the linear segment $[x, y]$ (integration of a 1-form over a 1-simplex). We can then define for $u : \mathcal{X} \rightarrow \mathbb{C}$ the map

$$(2.4) \quad [\mathfrak{Dp}^A(f)u](x) := \int_{\mathcal{X}} dy \int_{\mathcal{X}^*} d\eta e^{i(x-y)\cdot\eta} e^{-i\Gamma^A([x, y])} f\left(\frac{x+y}{2}, \eta\right) u(y).$$

For $A = 0$ one recognizes the Weyl quantization, associating to functions or distributions on Ξ linear operators acting on function spaces on \mathcal{X} . Suitably interpreted and by using rather simple duality arguments, \mathfrak{Dp}^A defines a representation of the $*$ -algebra $\mathcal{M}^B(\Xi)$ by continuous linear operators $\mathcal{S}(\mathcal{X}) \rightarrow \mathcal{S}(\mathcal{X})$. This means that $\mathfrak{Dp}^A(f \sharp^B g) = \mathfrak{Dp}^A(f)\mathfrak{Dp}^A(g)$ and $\mathfrak{Dp}^A(\bar{f}) = \mathfrak{Dp}^A(f)^*$ for any $f, g \in \mathcal{M}^B(\Xi)$. In addition, \mathfrak{Dp}^A restricts to an isomorphism between $\mathcal{S}(\Xi)$ and $\mathcal{B}(\mathcal{S}'(\mathcal{X}), \mathcal{S}(\mathcal{X}))$, and extends to an isomorphism between $\mathcal{S}'(\Xi)$ and $\mathcal{B}(\mathcal{S}(\mathcal{X}), \mathcal{S}'(\mathcal{X}))$, where $\mathcal{B}(\mathcal{R}, \mathcal{T})$ is the family of all continuous linear operators between the topological vector spaces \mathcal{R} and \mathcal{T} .

An important property of (2.4) is *gauge covariance*: if $A' = A + d\psi$ defines the same magnetic field as A , then $\mathfrak{Dp}^{A'}(f) = e^{i\psi} \mathfrak{Dp}^A(f) e^{-i\psi}$. Such a property would not hold for the wrong quantization, appearing in the literature,

$$[\mathfrak{Dp}_A(f)u](x) := \int_{\mathcal{X}} dy \int_{\mathcal{X}^*} d\eta e^{i(x-y)\cdot\eta} f\left(\frac{x+y}{2}, \eta - A\left(\frac{x+y}{2}\right)\right)u(y).$$

Another important result is a magnetic version of the Calderón–Vaillancourt theorem:

Theorem 2.3. *Assume that the components of the magnetic field belong to $BC^\infty(\mathcal{X})$, and let $f \in S_{\rho,\rho}^0(\Xi)$ for some $\rho \in [0, 1)$. Then $\mathfrak{Dp}^A(f) \in \mathcal{B}(L^2(\mathcal{X}))$ and we have the inequality*

$$\|\mathfrak{Dp}^A(f)\|_{\mathcal{B}(L^2(\mathcal{X}))} \leq c(n) \sup_{|\alpha| \leq p(n)} \sup_{|\alpha| \leq p(n)} \sup_{(x,\xi) \in \Xi} \langle \xi \rangle^{\rho(|\alpha| - |\alpha|)} |\partial_x^\alpha \partial_\xi^\alpha f(x, \xi)|,$$

where $c(n)$ and $p(n)$ are constants depending only on the dimension of the configuration space.

§2.3. Symbol spaces with coefficients in \mathcal{A}

We first introduce the coefficient C^* -algebra \mathcal{A} , which can be thought of as a way to encode the behavior of the magnetic fields and of the configurational part of the symbols.

Let \mathcal{A} be a unital C^* -subalgebra of $BC_u(\mathcal{X})$, the set of bounded and uniformly continuous functions on \mathcal{X} . Depending on the context, the L^∞ -norm of this algebra will be denoted either by $\|\cdot\|_{\mathcal{A}}$ or by $\|\cdot\|_\infty$. We shall always assume that \mathcal{A} is stable under translations, i.e. $\theta_x(\varphi) := \varphi(\cdot + x) \in \mathcal{A}$ for all $\varphi \in \mathcal{A}$ and $x \in \mathcal{X}$, and sometimes we require that $C_0(\mathcal{X})$ is contained in \mathcal{A} . Here, $C_0(\mathcal{X})$ denotes the algebra of continuous functions on \mathcal{X} that vanish at infinity.

The following definition is general and applies to any C^* -algebra \mathcal{A} endowed with an action of \mathcal{X} .

Definition 2.4. Let us define $\mathcal{A}^\infty := \{\varphi \in \mathcal{A} \mid \text{the map } \mathcal{X} \ni x \mapsto \theta_x(\varphi) \in \mathcal{A} \text{ is } C^\infty\}$. For $a \in \mathbb{N}^n$ we set

- (a) $\delta^a : \mathcal{A}^\infty \ni \varphi \mapsto \delta^a(\varphi) := \partial_x^a(\theta_x(\varphi))|_{x=0} \in \mathcal{A}^\infty$,
- (b) $s^a : \mathcal{A}^\infty \ni \varphi \mapsto s^a(\varphi) := \|\delta^a(\varphi)\|_{\mathcal{A}} \in \mathbb{R}_+$.

It is known that \mathcal{A}^∞ is a dense $*$ -subalgebra of \mathcal{A} , as well as a Fréchet $*$ -algebra with the family of seminorms $\{s^a \mid a \in \mathbb{N}^n\}$. But our setting is quite special: \mathcal{A} is an abelian C^* -algebra composed of bounded and uniformly continuous complex functions defined on the group \mathcal{X} itself. The easy proof of the next result is left to the reader.

Lemma 2.5. \mathcal{A}^∞ coincides with $\{\varphi \in C^\infty(\mathcal{X}) \mid \partial^a \varphi \in \mathcal{A}, \forall a \in \mathbb{N}^n\}$. Furthermore, for any $a \in \mathbb{N}^n$ and $\varphi \in \mathcal{A}^\infty$, one has $\delta^a(\varphi) = \partial_x^a \varphi$.

We now introduce the anisotropic version of the Hörmander classes of symbols (cf. also [3, 4, 5, 6, 36]). For any $f : \Xi \rightarrow \mathbb{C}$ and $(x, \xi) \in \Xi$, we will often write $f(\xi)$ for $f(\cdot, \xi)$ and $[f(\xi)](x)$ for $f(x, \xi)$. In that situation, f will be seen as a function on \mathcal{X}^* taking values in some space of functions defined on \mathcal{X} .

Definition 2.6. The space $S_{\rho, \delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ of \mathcal{A} -anisotropic symbols of order m and type (ρ, δ) is

$$\{f \in C^\infty(\mathcal{X}^*; \mathcal{A}^\infty) \mid \forall \alpha, a \in \mathbb{N}^n, \exists C_{\alpha a} < \infty \text{ such that } s^a[(\partial_\xi^\alpha f)(\xi)] \leq C_{\alpha a} \langle \xi \rangle^{m-\rho|\alpha|+\delta|a|}, \forall \xi \in \mathcal{X}^*\}.$$

Due to the very specific nature of the C^* -algebra \mathcal{A} , we have again some simplifications:

Lemma 2.7. *The following equality holds:*

$$(2.5) \quad S_{\rho, \delta}^m(\mathcal{X}^*; \mathcal{A}^\infty) = \{f \in S_{\rho, \delta}^m(\Xi) \mid (\partial_x^a \partial_\xi^\alpha f)(\xi) \in \mathcal{A}, \forall \xi \in \mathcal{X}^* \text{ and } \alpha, a \in \mathbb{N}^n\}.$$

Proof. First we notice that the conditions

$$s^a[(\partial_\xi^\alpha f)(\xi)] \leq C_{\alpha a} \langle \xi \rangle^{m-\rho|\alpha|+\delta|a|}, \quad \forall \xi \in \mathcal{X}^*,$$

and

$$|(\partial_x^a \partial_\xi^\alpha f)(x, \xi)| \leq C_{\alpha a} \langle \xi \rangle^{m-\rho|\alpha|+\delta|a|}, \quad \forall (x, \xi) \in \Xi,$$

are identical. On the other hand, by Lemma 2.5,

$$(\partial_\xi^\alpha f)(\xi) \in \mathcal{A}^\infty \Leftrightarrow (\partial_x^a \partial_\xi^\alpha f)(\xi) \in \mathcal{A}, \quad \forall a \in \mathbb{N}^n.$$

It thus follows that $S_{\rho, \delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ is included in the r.h.s. of (2.5), and we are then left with proving that if $f \in S_{\rho, \delta}^m(\Xi)$ and $(\partial_\xi^\alpha f)(\xi) \in \mathcal{A}^\infty$ for all α and ξ , then $f \in C^\infty(\mathcal{X}^*; \mathcal{A}^\infty)$.

We first show that $f : \mathcal{X}^* \rightarrow \mathcal{A}^\infty$ is differentiable, that is, for each $a \in \mathbb{N}^n$,

$$s^a \left[\frac{1}{t} [f(\xi + te_j) - f(\xi)] - (\partial_{\xi_j} f)(\xi) \right] \xrightarrow{t \rightarrow 0} 0, \quad \forall j = 1, \dots, n,$$

where e_1, \dots, e_n is the canonical basis in $\mathcal{X}^* \cong \mathbb{R}^n$. Indeed, for $t > 0$ we have

$$\begin{aligned} & \sup_{x \in \mathcal{X}} \left| \frac{1}{t} [(\partial_x^a f)(x, \xi + te_j) - (\partial_x^a f)(x, \xi)] - (\partial_x^a \partial_{\xi_j} f)(x, \xi) \right| \\ &= \sup_{x \in \mathcal{X}} \left| \frac{1}{t} \int_0^t ds \int_0^s du (\partial_x^a \partial_{\xi_j}^2 f)(x, \xi + ue_j) \right| \\ &\leq \sup_{x \in \mathcal{X}} \frac{1}{t} \int_0^t ds \int_0^s du C_a \langle \xi + ue_j \rangle^{m-2\rho+\delta|a|} \\ &\leq C'_a \langle \xi \rangle^{m-2\rho+\delta|a|} \frac{1}{t} \int_0^t ds \int_0^s du \langle u \rangle^{m-2\rho+\delta|a|} \\ &\leq C''_a \langle \xi \rangle^{m-2\rho+\delta|a|} \frac{1}{t} (t^2 - 0) \xrightarrow{t \rightarrow 0} 0, \end{aligned}$$

and similarly for $t < 0$. We can then apply this procedure to the resulting derivative $\partial_{\xi_j} f \in S_{\rho,\delta}^{m-\rho}(\Xi)$ and finish the proof by recurrence. \square

In particular, for $\mathcal{A} = BC_u(\mathcal{X})$, it is easy to see that

$$\begin{aligned} BC_u(\mathcal{X})^\infty &= \{ \varphi \in C^\infty(\mathcal{X}) \mid \partial^a \varphi \in BC_u(\mathcal{X}), \forall a \in \mathbb{N}^n \} \\ &= \{ \varphi \in C^\infty(\mathcal{X}) \mid \partial^a \varphi \in BC(\mathcal{X}), \forall a \in \mathbb{N}^n \} =: BC^\infty(\mathcal{X}). \end{aligned}$$

Then it follows from the previous lemma that

$$S_{\rho,\delta}^m(\mathcal{X}^*; BC_u(\mathcal{X})^\infty) = S_{\rho,\delta}^m(\mathcal{X}^*; BC^\infty(\mathcal{X})) = S_{\rho,\delta}^m(\Xi).$$

Proposition 2.8. (a) $S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ is a closed subspace of the Fréchet space $S_{\rho,\delta}^m(\Xi)$.

(b) For any $m_1, m_2 \in \mathbb{R}$, $S_{\rho,\delta}^{m_1}(\mathcal{X}^*; \mathcal{A}^\infty) \cdot S_{\rho,\delta}^{m_2}(\mathcal{X}^*; \mathcal{A}^\infty) \subset S_{\rho,\delta}^{m_1+m_2}(\mathcal{X}^*; \mathcal{A}^\infty)$,

(c) For any $\alpha, a \in \mathbb{N}^n$, $\partial_x^a \partial_\xi^\alpha S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty) \subset S_{\rho,\delta}^{m-\rho|\alpha|+\delta|a|}(\mathcal{X}^*; \mathcal{A}^\infty)$.

Proof. (a) We have to show that if $f_n \in S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ and $f \in S_{\rho,\delta}^m(\Xi)$, and if $\sigma_m^{\alpha a}(f_n - f) \rightarrow 0$ as $n \rightarrow \infty$, then $(\partial_x^a \partial_\xi^\alpha f)(\xi) \in \mathcal{A}$ for all α, a, ξ . But since \mathcal{A} is closed, it is enough to show that for any $a, \alpha \in \mathbb{N}^n$, the following statement holds: if $g_n \in S_{\rho,\delta}^m(\Xi)$ and $\sigma_m^{\alpha a}(g_n) \rightarrow 0$ as $n \rightarrow \infty$, then $\|(\partial_x^a \partial_\xi^\alpha g_n)(\xi)\|_\infty \rightarrow 0$ as $n \rightarrow \infty$ for all $\xi \in \mathcal{X}^*$. This follows from the definition of $\sigma_m^{\alpha a}$.

Statement (b) follows by applying Lemma 2.7, Leibniz’s rule and the fact that \mathcal{A} is an algebra. Statement (c) is a direct consequence of Lemma 2.7. \square

§2.4. Symbol composition

In this section we study the product of two symbols under the composition law \sharp^B defined in (2.2). For simplicity, we introduce ω_B and Γ_B (low indices) by the relations

$$\omega_B(x, y, z) = e^{-i\Gamma_B(x,y,z)} := e^{-i\Gamma^B(\langle x-y-z, x+y-z, x-y+z \rangle)}.$$

One has explicitly

$$(2.6) \quad \Gamma_B(x, y, z) = \sum_{j,k=1}^n y_j z_k \int_0^2 ds \int_0^1 dt s B_{jk}(x + (s - st - 1)y + (st - 1)z)$$

and (2.2) reads

$$(2.7) \quad [f \#^B g](X) := 4^n \int_{\Xi} dY \int_{\Xi} dZ e^{-2i\sigma(Y,Z)} \omega_B(x, y, z) f(X - Y) g(X - Z).$$

We state the main result of this section:

Theorem 2.9. *Assume that each component B_{jk} belongs to \mathcal{A}^∞ . Then, for any $m_1, m_2 \in \mathbb{R}$ and $0 \leq \delta < \rho \leq 1$ or $\rho = \delta = 0$, one has*

$$(2.8) \quad S_{\rho,\delta}^{m_1}(\mathcal{X}^*; \mathcal{A}^\infty) \#^B S_{\rho,\delta}^{m_2}(\mathcal{X}^*; \mathcal{A}^\infty) \subset S_{\rho,\delta}^{m_1+m_2}(\mathcal{X}^*; \mathcal{A}^\infty).$$

Before proving this theorem, we need a technical lemma.

Lemma 2.10. *Assume that each component B_{jk} belongs to \mathcal{A}^∞ . Then, for all $a, b, c \in \mathbb{N}^n$ and all $x, y, z \in \mathcal{X}$, one has:*

- (a) $(\partial_x^a \partial_y^b \partial_z^c \Gamma_B)(\cdot, y, z) \in \mathcal{A}$,
- (b) $(\partial_x^a \partial_y^b \partial_z^c \omega_B)(\cdot, y, z) \in \mathcal{A}$,
- (c) $|(\partial_x^a \partial_y^b \partial_z^c \omega_B)(x, y, z)| \leq C_{abc}(\langle y \rangle + \langle z \rangle)^{|a|+|b|+|c|}$.

Proof. The expressions $(\partial_x^a \partial_y^b \partial_z^c \Gamma_B)(\cdot, y, z)$ can be explicitly calculated by using (2.6), (a) follows from the completeness of \mathcal{A} , and (b) easily follows from (a). Statement (c) is borrowed from [13]. □

Proof of Theorem 2.9. Since the components of the magnetic field belong to $BC^\infty(\mathcal{X}) \subset C_{\text{pol}}^\infty(\mathcal{X})$, it follows from Lemma 2.7 and [13, Lem. 1.2] that $S_{\rho,\delta}^{m_j}(\mathcal{X}^*; \mathcal{A}^\infty) \subset S_{\rho,\delta}^{m_j}(\Xi) \subset \mathcal{M}^B(\Xi)$ for $j \in \{1, 2\}$, and thus the $\#^B$ -product in (2.8) is well defined in $\mathcal{M}^B(\Xi)$, as explained in Section 2.1. Under the additional hypothesis that $B_{jk} \in BC^\infty(\mathcal{X})$, it has even been proved in [13, Thm. 2.2] (see also Remark 2.2) that the product belongs to $S_{\rho,\delta}^{m_1+m_2}(\Xi)$ and can also be defined by the usual oscillatory integral techniques. Thus, thanks to Lemma 2.7, it only remains to show that for any $\alpha, a \in \mathbb{N}^n$, $f \in S_{\rho,\delta}^{m_1}(\mathcal{X}^*; \mathcal{A}^\infty)$ and $g \in S_{\rho,\delta}^{m_2}(\mathcal{X}^*; \mathcal{A}^\infty)$, the expression $[\partial_x^\alpha \partial_\xi^\alpha (f \#^B g)](\xi)$ belongs to \mathcal{A} for all $\xi \in \mathcal{X}^*$.

For that purpose, let $\alpha^1, \alpha^2, a^0, a^1, a^2 \in \mathbb{N}^n$ with $\alpha^1 + \alpha^2 = \alpha$ and $a^0 + a^1 + a^2 = a$. We define $F_{\alpha^1 a^1} := \partial_x^{\alpha^1} \partial_\xi^{\alpha^1} f \in S_{\rho,\delta}^{p_1}(\mathcal{X}^*; \mathcal{A}^\infty)$, $G_{\alpha^2 a^2} := \partial_x^{\alpha^2} \partial_\xi^{\alpha^2} g \in S_{\rho,\delta}^{p_2}(\mathcal{X}^*; \mathcal{A}^\infty)$ and $\Omega_B^{a^0} := \partial_x^{a^0} \omega_B$. Then $p_j = m_j - \rho|\alpha^j| + \delta|a^j|$ for $j \in \{1, 2\}$ and $\Omega_B^{a^0}$ satisfies the properties of Lemma 2.10. We have to study the x -behavior of

the expression

$$(2.9) \quad [\partial_x^a \partial_\xi^\alpha (f \#^B g)](x, \xi) = \sum_{\substack{a^0+a^1+a^2=a \\ \alpha^1+\alpha^2=\alpha}} C_{a^0 a^1 a^2}^{\alpha^1 \alpha^2} \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2iz \cdot \eta} e^{2iy \cdot \zeta} \Omega_B^{a^0}(x, y, z) \cdot F_{\alpha^1 a^1}(x - y, \xi - \eta) G_{\alpha^2 a^2}(x - z, \xi - \zeta).$$

The precise definition of these integrals involves rewriting $e^{-2iz \cdot \eta} e^{2iy \cdot \zeta}$ as

$$(2.10) \quad \langle y \rangle^{-2q} \langle z \rangle^{-2q} \langle D_\zeta \rangle^{2q} \langle D_\eta \rangle^{2q} \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle D_z \rangle^{2p} \langle D_y \rangle^{2p} (e^{-2iz \cdot \eta} e^{2iy \cdot \zeta})$$

where $D := \frac{1}{2i} \partial$ and $p, q \in \mathbb{N}$, and integrating by parts. So the r.h.s. of (2.9) contains the integrals

$$\int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2iz \cdot \eta} e^{2iy \cdot \zeta} \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \cdot \langle D_z \rangle^{2p} \langle D_y \rangle^{2p} \{ \langle y \rangle^{-2q} \langle z \rangle^{-2q} \Omega_B^{a^0}(x, y, z) \langle D_\zeta \rangle^{2q} \langle D_\eta \rangle^{2q} \cdot [F_{\alpha^1 a^1}(x - y, \xi - \eta) G_{\alpha^2 a^2}(x - z, \xi - \zeta)] \},$$

which will now be proved to be absolutely convergent for p, q large enough.

For this, one has to estimate

$$\begin{aligned} & \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle D_z \rangle^{2p} \langle D_y \rangle^{2p} \{ \langle y \rangle^{-2q} \langle z \rangle^{-2q} \Omega_B^{a^0}(x, y, z) \langle D_\zeta \rangle^{2q} \langle D_\eta \rangle^{2q} \\ & \quad \cdot [F_{\alpha^1 a^1}(x - y, \xi - \eta) G_{\alpha^2 a^2}(x - z, \xi - \zeta)] \} \\ &= \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle z \rangle^{-2q} \langle y \rangle^{-2q} \sum_{\substack{|b^1|+|b^2|+|b^3|=2p \\ |c^1|+|c^2|+|c^3|=2p \\ |\beta^1| \leq q, |\beta^2| \leq q}} C_{b^1 b^2 b^3 \beta^1}^{c^1 c^2 c^3 \beta^2} \varphi_{qc^1}(z) \psi_{qb^1}(y) \\ & \quad \cdot (\partial_y^{b^2} \partial_z^{c^2} \Omega_B^{a^0})(x, y, z) (\partial_y^{b^3} \partial_\xi^{2\beta^1} F_{\alpha^1 a^1})(x - y, \xi - \eta) (\partial_z^{c^3} \partial_\xi^{2\beta^2} G_{\alpha^2 a^2})(x - z, \xi - \zeta), \end{aligned}$$

where $b^1, b^2, b^3, c^1, c^2, c^3, \beta^1, \beta^2 \in \mathbb{N}^n$, and φ_{qc^1} and ψ_{qb^1} are bounded functions produced by differentiating the factors $\langle z \rangle^{-2q}$ and $\langle y \rangle^{-2q}$, respectively. By using the estimates obtained in Lemma 2.10 for $\Omega_B^{a^0}$, and the a priori estimates on $F_{\alpha^1 a^1}$ and $G_{\alpha^2 a^2}$, the absolute value of the above expression is dominated by

$$\begin{aligned} & C_{pq} \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle z \rangle^{-2q} \langle y \rangle^{-2q} \sum_{\substack{|b^1|+|b^2|+|b^3|=2p \\ |c^1|+|c^2|+|c^3|=2p \\ |\beta^1| \leq q, |\beta^2| \leq q}} (\langle y \rangle + \langle z \rangle)^{|a^0|+|b^2|+|c^2|} \\ & \quad \cdot \langle \xi - \eta \rangle^{p_1 - 2\rho|\beta^1| + \delta|b^3|} \langle \xi - \zeta \rangle^{p_2 - 2\rho|\beta^2| + \delta|c^3|} \\ & \leq C_{pq}(\xi) \langle \eta \rangle^{-2p(1-\delta)+p_1} \langle \zeta \rangle^{-2p(1-\delta)+p_2} \langle y \rangle^{-2q+|a|+4p} \langle z \rangle^{-2q+|a|+4p}. \end{aligned}$$

Since $1 - \delta > 0$, the factors involving η and ζ will be integrable for p large enough. Fixing a suitable p , for an even larger q we also ensure integrability in y and z .

To sum up, $[\partial_x^a \partial_\xi^\alpha (f \#^B g)](x, \xi)$ is given by an absolutely convergent integral, the integrand being a function of x which belongs to \mathcal{A} for all values of ξ, y, η, z, ζ . It is easy to conclude, by the Dominated Convergence Theorem, that the map $x \mapsto [\partial_x^a \partial_\xi^\alpha (f \#^B g)](x, \xi)$ also belongs to \mathcal{A} , and this finishes the proof. \square

§2.5. Asymptotic developments

In this section we simplify and generalize to \mathcal{A} -valued symbols the asymptotic expansion of the magnetic product of two symbols already derived in [13]. We refer to [22] for parameter-dependent developments.

For any multi-index $\alpha \in \mathbb{N}^m$, we use the notation $\alpha! = \alpha_1! \dots \alpha_m!$. For brevity we shall also write $\mathbf{a} := (a, \alpha)$ and $\mathbf{b} := (b, \beta)$, with $\mathbf{a}, \mathbf{b} \in \mathbb{N}^{2n}$.

Theorem 2.11. *Assume that the each component B_{jk} belongs to \mathcal{A}^∞ and let $m_1, m_2 \in \mathbb{R}$ and $\rho \in (0, 1]$. Then for any $f \in S_{\rho,0}^{m_1}(\mathcal{X}^*; \mathcal{A}^\infty)$, $g \in S_{\rho,0}^{m_2}(\mathcal{X}^*; \mathcal{A}^\infty)$ and $N \in \mathbb{N}^*$ one has*

$$f \#^B g = \sum_{l=0}^{N-1} h_l + R_N$$

with

$$h_l = \sum_{\substack{a,b,\alpha,\beta \in \mathbb{N}^n \\ a \leq \beta, b \leq \alpha \\ |\alpha|+|\beta|=l}} h_{\mathbf{a},\mathbf{b}} \in S_{\rho,0}^{m_1+m_2-\rho l}(\mathcal{X}^*; \mathcal{A}^\infty)$$

and

$$h_{\mathbf{a},\mathbf{b}}(x, \xi) = C_{\mathbf{a}\mathbf{b}} [(\partial_y^{\beta-a} \partial_z^{\alpha-b} \omega_B)(x, 0, 0)] [(\partial_x^a \partial_\xi^\alpha f)(x, \xi)] [(\partial_x^b \partial_\xi^\beta g)(x, \xi)],$$

and the constants are given by

$$C_{\mathbf{a}\mathbf{b}} = \left(\frac{i}{2}\right)^l \frac{(-1)^{|a|+|b|+|\beta|}}{a!b!(\alpha-b)!(\beta-a)!}.$$

The remainder term R_N belongs to $S_{\rho,0}^{m_1+m_2-\rho N}(\mathcal{X}^*; \mathcal{A}^\infty)$.

Remark 2.12. If $B = 0$, which implies $\omega_B = 1$, one has $h_{\mathbf{a},\mathbf{b}} \neq 0$ only if $a = \beta$ and $b = \alpha$; by setting $\hat{\mathbf{a}}$ for (α, a) , one has $h_{\mathbf{a},\hat{\mathbf{a}}} = \frac{(-1)^{|\alpha|}}{a!} \left(\frac{i}{2}\right)^{|\alpha|} \partial^a f \partial^{\hat{\mathbf{a}}} g$.

Before proving the theorem, we list the first two terms in the development:

$$h_0 = fg, \quad h_1 = \frac{i}{2} \{f, g\} = \frac{i}{2} \sum_{j=1}^n (\partial_{x_j} f \partial_{\xi_j} g - \partial_{\xi_j} f \partial_{x_j} g).$$

Proof of Theorem 2.11. In the formula (2.7) we shall use the Taylor series

$$(f \otimes g)(X - Y, X - Z) = \sum_{|(\mathbf{a}, \mathbf{b})| < N} \frac{(-1)^{|\mathbf{a}, \mathbf{b}|}}{(\mathbf{a}, \mathbf{b})!} (Y, Z)^{(\mathbf{a}, \mathbf{b})} [\partial^{(\mathbf{a}, \mathbf{b})} (f \otimes g)](X, X) + r_{f, g}(X, Y, Z),$$

where the remainder $r_{f, g}$ will be specified later. It follows that

$$f \#^B g = \sum_{|(\mathbf{a}, \mathbf{b})| < N} h_{\mathbf{a}, \mathbf{b}} + R_N$$

with

$$h_{\mathbf{a}, \mathbf{b}}(X) = \frac{(-1)^{|\mathbf{a}, \mathbf{b}|}}{(\mathbf{a}, \mathbf{b})!} [\partial^{(\mathbf{a}, \mathbf{b})} (f \otimes g)](X, X) \cdot 4^n \int_{\Xi} dY \int_{\Xi} dZ (Y, Z)^{(\mathbf{a}, \mathbf{b})} e^{-2i\sigma(Y, Z)} \omega_B(x, y, z).$$

In other words, one has

$$h_{\mathbf{a}, \mathbf{b}} = \frac{(-1)^{|\mathbf{a}|+|\mathbf{b}|+|\alpha|+|\beta|}}{a!b!\alpha!\beta!} [\partial_x^\alpha \partial_\xi^\alpha f][\partial_x^b \partial_\xi^\beta g] \Omega_{\mathbf{a}, \mathbf{b}},$$

with $\Omega_{\mathbf{a}, \mathbf{b}}(x)$ given by

$$\begin{aligned} 4^n \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz y^a z^b \omega_B(x, y, z) \left[\int_{\mathcal{X}^*} d\eta e^{-2iz \cdot \eta} \eta^\alpha \right] \left[\int_{\mathcal{X}^*} d\zeta e^{2iy \cdot \zeta} \zeta^\beta \right] \\ = \frac{(-i)^{|\alpha|} i^{|\beta|}}{2^{|\alpha|+|\beta|}} \partial_y^\beta \partial_z^\alpha \{y^a z^b \omega_B(x, y, z)\} |_{y=z=0}. \end{aligned}$$

The following factor vanishes unless $b \leq \alpha$ and $a \leq \beta$:

$$\partial_y^\beta \partial_z^\alpha \{y^a z^b \omega_B(x, y, z)\} |_{y=z=0} = \frac{\alpha! \beta!}{(\alpha - b)! (\beta - a)!} (\partial_y^{\beta-a} \partial_z^{\alpha-b} \omega_B)(x, 0, 0).$$

So, restricting to the case $b \leq \alpha$ and $a \leq \beta$, we can write

$$\begin{aligned} h_{\mathbf{a}, \mathbf{b}}(x, \xi) = \frac{(-1)^{|\mathbf{a}|+|\mathbf{b}|} i^{|\alpha|} (-i)^{|\beta|}}{a!b!(\alpha - b)! (\beta - a)!} \left(\frac{1}{2}\right)^{|\alpha|+|\beta|} [(\partial_y^{\beta-a} \partial_z^{\alpha-b} \omega_B)(x, 0, 0)] \\ \cdot [(\partial_x^\alpha \partial_\xi^\alpha f)(x, \xi)][(\partial_x^b \partial_\xi^\beta g)(x, \xi)]. \end{aligned}$$

By Proposition 2.8 and Lemma 2.10, one finally obtains

$$h_{\mathbf{a}, \mathbf{b}} \in S_{\rho, 0}^{m_1+m_2-\rho(|\alpha|+|\beta|)}(\mathcal{X}^*; \mathcal{A}^\infty).$$

We now treat the remainder $R_N(X)$ given by

$$\begin{aligned}
 & 4^n \int_{\Xi} dY \int_{\Xi} dZ e^{-2i\sigma(Y,Z)} \omega_B(x, y, z) \sum_{|(\mathbf{a}, \mathbf{b})|=N} \frac{(Y, Z)^{(\mathbf{a}, \mathbf{b})}}{(\mathbf{a}, \mathbf{b})!} \\
 & \quad \cdot N \int_0^1 d\tau (1-\tau)^{N-1} [\partial^{(\mathbf{a}, \mathbf{b})}(f \otimes g)](X - \tau Y, X - \tau Z) \\
 & = \sum_{|a|+|b|+|\alpha|+|\beta|=N} \frac{4^n N}{a!b!\alpha!\beta!} \\
 & \quad \cdot \int_0^1 d\tau (1-\tau)^{N-1} \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta \omega_B(x, y, z) \\
 & \quad \cdot y^a z^b \eta^\alpha \zeta^\beta e^{-2i\sigma(Y,Z)} [\partial_x^a \partial_\xi^\alpha f](x - \tau y, \xi - \tau \eta) [\partial_x^b \partial_\xi^\beta g](x - \tau z, \xi - \tau \zeta).
 \end{aligned}$$

In order to show that this term belongs to $S_{\rho,0}^{m_1+m_2-\rho N}(\mathcal{X}^*; \mathcal{A}^\infty)$, we take into account

$$y^a z^b \eta^\alpha \zeta^\beta e^{-2i\sigma(Y,Z)} = \frac{1}{(2i)^{|a|}(-2i)^{|\alpha|}(-2i)^{|b|}(2i)^{|\beta|}} \partial_\zeta^a \partial_z^\alpha \partial_\eta^b \partial_y^\beta e^{-2i\sigma(Y,Z)},$$

and insert it into $R_N(X)$, which can then be rewritten as

$$\begin{aligned}
 & \sum_{|a|+|b|+|\alpha|+|\beta|=N} \frac{4^n N (-1)^{|a|+|\beta|}}{a!b!\alpha!\beta!(2i)^N} \\
 & \quad \cdot \int_0^1 d\tau (1-\tau)^{N-1} \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2i\sigma(Y,Z)} \phi_{\mathbf{a}, \mathbf{b}}^\tau(X, Y, Z)
 \end{aligned}$$

with

$$\begin{aligned}
 & \phi_{\mathbf{a}, \mathbf{b}}^\tau(X, Y, Z) \\
 & := \partial_\zeta^a \partial_z^\alpha \partial_\eta^b \partial_y^\beta [\omega_B(x, y, z) [\partial_x^a \partial_\xi^\alpha f](x - \tau y, \xi - \tau \eta) [\partial_x^b \partial_\xi^\beta g](x - \tau z, \xi - \tau \zeta)] \\
 & = \sum_{\alpha' \leq \alpha} \sum_{\beta' \leq \beta} \binom{\alpha}{\alpha'} \binom{\beta}{\beta'} [\partial_z^{\alpha-\alpha'} \partial_y^{\beta-\beta'} \omega_B](x, y, z) \\
 & \quad \cdot \partial_y^{\beta'} \partial_\eta^b [(\partial_x^a \partial_\xi^\alpha f)(x - \tau y, \xi - \tau \eta)] \partial_z^{\alpha'} \partial_\zeta^a [(\partial_x^b \partial_\xi^\beta g)(x - \tau z, \xi - \tau \zeta)] \\
 & = \sum_{\alpha' \leq \alpha} \sum_{\beta' \leq \beta} \binom{\alpha}{\alpha'} \binom{\beta}{\beta'} (-\tau)^{|b|+|a|+|\beta'|+|\alpha'|} [\partial_z^{\alpha-\alpha'} \partial_y^{\beta-\beta'} \omega_B](x, y, z) \\
 & \quad \cdot [\partial_x^{a+\beta'} \partial_\xi^{\alpha+\beta} f](x - \tau y, \xi - \tau \eta) [\partial_x^{b+\alpha'} \partial_\xi^{a+\beta} g](x - \tau z, \xi - \tau \zeta).
 \end{aligned}$$

So we have

$$(2.11) \quad R_N(X) = \sum_{\substack{a, b, \alpha, \beta, \alpha', \beta' \\ \alpha' \leq \alpha, \beta' \leq \beta \\ |a|+|b|+|\alpha|+|\beta|=N}} \int_0^1 d\tau \text{pol}_{\mathbf{a}, \mathbf{b}}^{\alpha', \beta'}(\tau) I_{\tau, \mathbf{a}, \mathbf{b}}^{\alpha', \beta'}(X),$$

where $\text{pol}_{\mathbf{a},\mathbf{b}}^{\alpha',\beta'} : [0, 1] \rightarrow \mathbb{C}$ are polynomials and

$$I_{\tau,\mathbf{a},\mathbf{b}}^{\alpha',\beta'}(X) := \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2i\sigma(Y,Z)} [\partial_z^{\alpha-\alpha'} \partial_y^{\beta-\beta'} \omega_B](x, y, z) \cdot [\partial_x^{a+\beta'} \partial_\xi^{\alpha+b} f](x - \tau y, \xi - \tau\eta) [\partial_x^{b+\alpha'} \partial_\xi^{a+\beta} g](x - \tau z, \xi - \tau\zeta).$$

Retaining only its essential features, we shall rewrite this last expression as

$$I_\tau(X) := \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2i\sigma(Y,Z)} \cdot \Sigma_B(x, y, z) F(x - \tau y, \xi - \tau\eta) G(x - \tau z, \xi - \tau\zeta).$$

In order to show that R_N belongs to $S_{\rho,0}^{m_1+m_2-\rho N}(\Xi)$, let us calculate $\partial_x^d \partial_\xi^\delta I_\tau$. Actually, by using (2.10), the oscillatory integral definition of the expression $[\partial_x^d \partial_\xi^\delta I_\tau](X)$ is

$$\sum_{\substack{d^0+d^1+d^2=d \\ \delta^1+\delta^2=\delta}} C_{d^0,d^1,d^2}^{\delta^1,\delta^2} \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2i\sigma(Y,Z)} L_{p,q,d^0,d^1,d^2}^{\tau,\delta^1,\delta^2}(X, Y, Z),$$

where, for suitable integers p, q , the expression $L_{p,q,d^0,d^1,d^2}^{\tau,\delta^1,\delta^2}(X, Y, Z)$ is given by

$$\begin{aligned} & \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle D_y \rangle^{2p} \langle D_z \rangle^{2p} [\langle y \rangle^{-2q} \langle z \rangle^{-2q} [\partial_x^{d^0} \Sigma_B](x, y, z) \\ & \quad \cdot \langle D_\eta \rangle^{2q} \langle D_\zeta \rangle^{2q} [\partial_x^{d^1} \partial_\xi^{\delta^1} F](x - \tau y, \xi - \tau\eta) [\partial_x^{d^2} \partial_\xi^{\delta^2} G](x - \tau z, \xi - \tau\zeta)] \\ & = \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle y \rangle^{-2q} \langle z \rangle^{-2q} \sum_{\substack{|b^1|+|b^2|+|b^3|=2p \\ |c^1|+|c^2|+|c^3|=2p \\ |q^1| \leq q, |q^2| \leq q}} C_{b^1,b^2,b^3}^{q^1,q^2,c^1,c^2,c^3} \varphi_{qc^1}(z) \psi_{qb^1}(y) \\ & \quad \cdot [\partial_x^{d^0} \partial_y^{b^2} \partial_z^{c^2} \Sigma_B](x, y, z) (-\tau)^{2|q^1|+2|q^2|+|b^3|+|c^3|} \\ & \quad \cdot [\partial_x^{d^1+b^3} \partial_\xi^{\delta^1+2q^1} F](x - \tau y, \xi - \tau\eta) [\partial_x^{d^2+c^3} \partial_\xi^{\delta^2+2q^2} G](x - \tau z, \xi - \tau\zeta), \end{aligned}$$

where φ_{qc^1} and ψ_{qb^1} are bounded functions produced by differentiating the factors $\langle z \rangle^{-2q}$ and $\langle y \rangle^{-2q}$, respectively. By taking the explicit form of Σ_B, F, G and Lemma 2.10 into account, one has

$$\begin{aligned} & |L_{p,q,d^0,d^1,d^2}^{\tau,\delta^1,\delta^2}(X, Y, Z)| \\ & \leq C_{pq,d^0,d^1,d^2}^{\delta^1,\delta^2} \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle y \rangle^{-2q} \langle z \rangle^{-2q} (\langle y \rangle + \langle z \rangle)^{|d|+|\alpha|+|\beta|+4p} \\ & \quad \cdot \langle \xi - \tau\eta \rangle^{m_1-\rho(|\alpha|+|b|+|\delta^1|+2|q^1|)} \langle \xi - \tau\zeta \rangle^{m_2-\rho(|\alpha|+|\beta|+|\delta^2|+2|q^2|)} \\ & \leq D_{pq,d^0,d^1,d^2}^{\delta^1,\delta^2} \langle y \rangle^{-2q+N+4p+|d|} \langle z \rangle^{-2q+N+4p+|d|} \langle \xi \rangle^{m_1+m_2-\rho(N+|\delta|)} \\ & \quad \cdot \langle \eta \rangle^{-2p+|m_1-\rho(|\alpha|+|b|+|\delta^1|)} \langle \zeta \rangle^{-2p+|m_2-\rho(|\alpha|+|\beta|+|\delta^2|)}. \end{aligned}$$

Then it only remains to insert this estimate into the expression of R_N given in (2.11), and to observe that by choosing p large enough, one gets absolute integrability in η and ζ . A subsequent choice of q also ensures integrability in y and z . The behavior in ξ is finally the one expected for $\partial_x^d \partial_\xi^\delta R_N$.

Thus, we have shown so far that R_N belongs to $S_{\rho,0}^{m_1+m_2-\rho N}(\Xi)$. By taking then Theorem 2.9 and the properties of h_l into account, one has

$$[\partial_x^d \partial_\xi^\delta R_N](\cdot, \xi) = \partial_x^d \partial_\xi^\delta \left[f \#^B g - \sum_{l=0}^{N-1} h_l \right](\cdot, \xi) \in \mathcal{A}$$

for any $\xi \in \mathcal{X}^*$. It finally follows from Lemma 2.7 that R_N belongs to $S_{\rho,0}^{m_1+m_2-\rho N}(\mathcal{X}^*; \mathcal{A}^\infty)$. \square

§3. C^* -algebras

§3.1. C^* -algebras generated by symbols

We continue to assume that all components of the magnetic field belong to \mathcal{A}^∞ and let $\mathcal{H} := L^2(\mathcal{X})$. As already mentioned, we choose a vector potential A that belongs to $C_{\text{pol}}^\infty(\mathcal{X})$ and thus the map \mathfrak{Dp}^A extends to a linear topological isomorphism $\mathcal{S}'(\Xi) \rightarrow \mathcal{B}(\mathcal{S}(\mathcal{X}), \mathcal{S}'(\mathcal{X}))$. Since $\mathcal{B}(\mathcal{H})$ is continuously embedded in $\mathcal{B}(\mathcal{S}(\mathcal{X}), \mathcal{S}'(\mathcal{X}))$, one can define

$$\mathfrak{A}^B(\Xi) := (\mathfrak{Dp}^A)^{-1}[\mathcal{B}(\mathcal{H})].$$

It is obviously a vector subspace of $\mathcal{S}'(\Xi)$ which only depends on the magnetic field (by gauge covariance). On convenient subsets, for example on $\mathfrak{A}^B(\Xi) \cap \mathcal{M}^B(\Xi)$, the transported product from $\mathcal{B}(\mathcal{H})$ coincides with $\#^B$, and the adjoint in $\mathcal{B}(\mathcal{H})$ corresponds to the involution $\#^B$. Endowed with the transported norm $\|f\|_B \equiv \|f\|_{\mathfrak{A}^B(\Xi)} := \|\mathfrak{Dp}^A(f)\|_{\mathcal{B}(\mathcal{H})}$, $\mathfrak{A}^B(\Xi)$ is a C^* -algebra.

With these notations and due to the inclusion $S_{\rho,\delta}^m(\Xi) \subset S_{\delta,\delta}^m(\Xi)$ for $\delta < \rho$, Theorem 2.3 can be rephrased as follows:

Proposition 3.1. *For any $0 \leq \delta \leq \rho \leq 1$ with $\delta \neq 1$, the following continuous embedding holds:*

$$S_{\rho,\delta}^0(\Xi) \hookrightarrow \mathfrak{A}^B(\Xi).$$

We shall now define two \mathcal{A} -depending C^* -subalgebras of $\mathfrak{A}^B(\Xi)$.

Definition 3.2. We write

(a) $\mathfrak{B}_\mathcal{A}^B$ for the C^* -subalgebra of $\mathfrak{A}^B(\Xi)$ generated by

$$\mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty) \equiv S^{-\infty}(\mathcal{X}^*; \mathcal{A}^\infty) := \bigcap_{m \in \mathbb{R}} S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty);$$

(b) $\mathfrak{M}_\mathcal{A}^B$ for the C^* -subalgebra of $\mathfrak{A}^B(\Xi)$ generated by $S_{0,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$.

It is easily observed that $\mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty)$ is indeed independent of ρ and δ . Part of our interest in the algebra \mathfrak{B}_A^B is due to the following proposition and its corollary. We first recall that

$$S_{\rho,\delta}^{-0}(\mathcal{X}^*; \mathcal{A}^\infty) := \bigcup_{m < 0} S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty).$$

Proposition 3.3. *For every $0 \leq \delta \leq \rho \leq 1$ with $\delta \neq 1$, the space $S_{\rho,\delta}^{-0}(\mathcal{X}^*; \mathcal{A}^\infty)$ is contained in \mathfrak{B}_A^B .*

Proof. We adapt the proof of Proposition 1.1.11 in [12] to show that any $f \in S_{\rho,\delta}^{-0}(\mathcal{X}^*; \mathcal{A}^\infty)$ is the limit of a sequence $\{f_\epsilon\}_{0 \leq \epsilon \leq 1} \in \mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty)$ in the topology of $S_{\rho,\delta}^0(\mathcal{X}^*; \mathcal{A}^\infty)$ (see also [10, Sec. 1] for more details). This and Proposition 3.1 will imply the result.

Let $f \in S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ for some $m < 0$, $0 \leq \delta \leq \rho \leq 1$, $\delta \neq 1$, and let $\chi \in \mathcal{S}(\mathcal{X}^*)$ with $\chi(0) = 1$. We set $f_\epsilon(x, \xi) := \chi(\epsilon\xi)f(x, \xi)$ for $0 \leq \epsilon \leq 1$. By using Proposition 2.8(b), one has $f_\epsilon \in \mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty)$ for all $\epsilon > 0$, and $\{f_\epsilon\}_{0 \leq \epsilon \leq 1}$ is a bounded subset of $S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$. Finally, one easily concludes that f_ϵ converges to f as $\epsilon \rightarrow 0$ in the topology of $S_{\rho,\delta}^0(\mathcal{X}^*; \mathcal{A}^\infty)$. \square

Remark 3.4. With the same proof one shows the density of $\mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty)$ in $S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ with respect to the topology of $S_{\rho,\delta}^{m'}(\mathcal{X}^*; \mathcal{A}^\infty)$ for arbitrary $m' > m$.

Corollary 3.5. *The C^* -algebra \mathfrak{M}_A^B is contained in the multiplier algebra $\mathcal{M}(\mathfrak{B}_A^B)$ of \mathfrak{B}_A^B .*

Proof. This follows from the fact that $\mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty)$ is a two-sided ideal in $S_{0,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$ with respect to \sharp^B , from the definition of \mathfrak{B}_A^B and \mathfrak{M}_A^B , and from a density argument. \square

Let us observe that $\mathfrak{B}_\mathbb{C}^B = C_0(\mathcal{X}^*)$ and $\mathfrak{M}_\mathbb{C}^B = BC_u(\mathcal{X}^*)$, while $\mathcal{M}(\mathfrak{B}_\mathbb{C}^B) = BC(\mathcal{X}^*)$; so, in the corollary, the inclusion could be strict.

§3.2. Magnetic twisted crossed products

In the previous section we introduced some C^* -algebras through a representation that was constructed with a vector potential A . However, all these algebras did not depend on the choice of a particular A . Starting from a magnetic twisted C^* -dynamical system, we shall now recall the constructions of magnetic twisted C^* -algebras [27] and relate them to the previous algebras. These are particular instances of twisted C^* -algebras extensively studied in [31] and [32] (see also references therein).

We recall that Gelfand theory describes completely the structure of abelian C^* -algebras. The Gelfand spectrum S_A of \mathcal{A} is the family of all characters of \mathcal{A} (a

character is just a morphism $\kappa : \mathcal{A} \rightarrow \mathbb{C}$). With the topology of simple convergence $S_{\mathcal{A}}$ is a locally compact space, which is compact exactly when \mathcal{A} is unital.

Since $\mathcal{A} \subset BC(\mathcal{X})$, there exists a continuous surjection $\iota_{\mathcal{A}} : \beta(\mathcal{X}) \rightarrow S_{\mathcal{A}}$, where $\beta(\mathcal{X})$ is the Stone-Ćech compactification of the locally compact space \mathcal{X} . By restriction, we get a continuous mapping with dense image (also denoted by $\iota_{\mathcal{A}} : \mathcal{X} \rightarrow S_{\mathcal{A}}$). This one is injective exactly when $C_0(\mathcal{X}) \subset \mathcal{A}$, in which case $S_{\mathcal{A}}$ is a compactification of \mathcal{X} . The isomorphism between \mathcal{A} and $C(S_{\mathcal{A}})$ can be precisely expressed as follows: $\varphi : \mathcal{X} \rightarrow \mathbb{C}$ belongs to \mathcal{A} if and only if there is a (necessarily unique) $\tilde{\varphi} \in C(S_{\mathcal{A}})$ such that $\varphi = \tilde{\varphi} \circ \iota_{\mathcal{A}}$. We shall extend the notation to functions depending on extra variables. For example, if $f : \Xi = \mathcal{X} \times \mathcal{X}^* \rightarrow \mathbb{C}$ is some convenient function, we define $\tilde{f} : S_{\mathcal{A}} \times \mathcal{X}^* \rightarrow \mathbb{C}$ by the property $f(x, \xi) = \tilde{f}(\iota_{\mathcal{A}}(x), \xi)$ for all $(x, \xi) \in \Xi$.

Let us finally mention that the map $\theta : \mathcal{X} \times \mathcal{X} \rightarrow \mathcal{X}$, $\theta(x, y) := x + y$, extends to a continuous map $\theta : S_{\mathcal{A}} \times \mathcal{X} \rightarrow S_{\mathcal{A}}$, because \mathcal{A} was assumed to be stable under translations. We also use the notations $\theta(\kappa, y) = \theta_y(\kappa) = \theta^\kappa(y)$ for $(\kappa, y) \in S_{\mathcal{A}} \times \mathcal{X}$ and get a topological dynamical system $(S_{\mathcal{A}}, \theta, \mathcal{X})$ with compact space $S_{\mathcal{A}}$. Obviously one has $\iota_{\mathcal{A}} \circ \theta_y = \theta_y \circ \iota_{\mathcal{A}}$ for any $y \in \mathcal{X}$.

Now assume that the components B_{jk} of the magnetic field belong to \mathcal{A} . We define for each $x, y, z \in \mathcal{X}$ the expression

$$\omega^B(x; y, z) := e^{-i\Gamma^B((x, x+y, x+y+z))}.$$

For fixed x and y , the function $\omega^B(\cdot; x, y) \equiv \omega^B(x, y)$ belongs to the unitary group $\mathcal{U}(\mathcal{A})$ of \mathcal{A} . Moreover, the mapping $\mathcal{X} \times \mathcal{X} \ni (x, y) \mapsto \omega^B(x, y) \in \mathcal{U}(\mathcal{A})$ is a strictly continuous and normalized 2-cocycle on \mathcal{X} , i.e. for all $x, y, z \in \mathcal{X}$ the following relations hold:

$$\omega^B(x + y, z)\omega^B(x, y) = \theta_x[\omega^B(y, z)]\omega^B(x, y + z), \quad \omega^B(x, 0) = \omega^B(0, x) = 1.$$

The quadruplet $(\mathcal{A}, \theta, \omega^B, \mathcal{X})$ is a particular case of a *twisted C^* -dynamical system* $(\mathcal{A}, \theta, \omega, \mathcal{X})$. In the general case \mathcal{X} is a locally compact group, \mathcal{A} is a C^* -algebra, θ is a continuous morphism from \mathcal{X} to the group of automorphisms of \mathcal{A} , and ω is a strictly continuous 2-cocycle with values in the unitary group of the multiplier algebra of \mathcal{A} . We refer to [27, Def. 2.1] for more explanations.

Let $L^1(\mathcal{X}; \mathcal{A})$ be the set of Bochner integrable functions on \mathcal{X} with values in \mathcal{A} , with the L^1 -norm $\|F\|_1 := \int_{\mathcal{X}} dx \|F(x)\|_{\mathcal{A}}$. For any $F, G \in L^1(\mathcal{X}; \mathcal{A})$ and $x \in \mathcal{X}$, we define the product

$$(F \diamond^B G)(x) := \int_{\mathcal{X}} dy \theta_{(y-x)/2}[F(y)]\theta_{y/2}[G(x-y)]\theta_{-x/2}[\omega^B(y, x-y)]$$

and the involution

$$F^{\diamond B}(x) := \overline{F(-x)}.$$

Definition 3.6. The enveloping C^* -algebra of $L^1(\mathcal{X}; \mathcal{A})$ is called the *twisted crossed product* and is denoted by $\mathcal{A} \rtimes_{\theta}^{\omega^B} \mathcal{X}$, or simply by \mathfrak{C}_A^B .

The C^* -algebras \mathfrak{C}_A^B and \mathfrak{B}_A^B are related by the partial Fourier transform

$$[\mathfrak{F}(F)](\xi, x) := \int_{\mathcal{X}} dy e^{iy \cdot \xi} F(y, x).$$

Theorem 3.7. *The partial Fourier transform $\mathfrak{F} : \mathcal{S}'(\mathcal{X} \times \mathcal{X}) \rightarrow \mathcal{S}'(\mathcal{X}^* \times \mathcal{X})$ restricts to a C^* -isomorphism $\mathfrak{F} : \mathfrak{C}_A^B \rightarrow \mathfrak{B}_A^B$.*

Proof. The partial Fourier transform \mathfrak{F} is an isomorphism from $\mathcal{S}(\mathcal{X}; \mathcal{A}^\infty)$ to $\mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty)$ which intertwines the products and the involutions:

$$\mathfrak{F}(F) \sharp^B \mathfrak{F}(G) = \mathfrak{F}[F \diamond^B G], \quad (\mathfrak{F}(F))^\sharp^B = \mathfrak{F}(F^{\diamond B}).$$

The statement then follows from the density of $\mathcal{S}(\mathcal{X}^*; \mathcal{A}^\infty)$ in \mathfrak{B}_A^B , and from the density of $\mathcal{S}(\mathcal{X}; \mathcal{A}^\infty)$ in $L^1(\mathcal{X}; \mathcal{A})$, and hence also in \mathfrak{C}_A^B . \square

Remark 3.8. In Definition 3.2, the algebra \mathfrak{B}_A^B was introduced as a closure of a set of smooth elements, but it can easily be guessed that non-smooth elements also belong to \mathfrak{B}_A^B . Indeed, by [28, Lemma A.4] for any $m < 0$ the set $\mathfrak{F}^{-1}[S_1^m(\mathcal{X}^*; \mathcal{A})]$ is contained in $L^1(\mathcal{X}; \mathcal{A})$, which implies that $S_1^m(\mathcal{X}^*; \mathcal{A}) \subset \mathfrak{B}_A^B$. Here we have used the notation $S_1^m(\mathcal{X}^*; \mathcal{A})$ for the set of all functions $f : \Xi \rightarrow \mathbb{C}$ that satisfy: (i) $f(\cdot, \xi) \in \mathcal{A}$ for all $\xi \in \mathcal{X}^*$, (ii) $f(x, \cdot) \in C^\infty(\mathcal{X}^*)$ for all $x \in \mathcal{X}$, and (iii) for each $\alpha \in \mathbb{N}^n$ one has $\sigma_m^{\alpha 0}(f) < \infty$. Even more simply, one can also observe that the partial Fourier transforms of elements in $L^1(\mathcal{X}; \mathcal{A})$ belong to \mathfrak{B}_A^B , and that these elements do not necessarily possess any smoothness except continuity.

Remark 3.9. In the same vein, let us mention that a trivial extension of the same lemma [28, Lem. A.4] to arbitrary δ implies that $\mathfrak{F}^{-1}[S_{1,\delta}^{-0}(\mathcal{X}^*; \mathcal{A}^\infty)]$ is also contained in $L^1(\mathcal{X}; \mathcal{A})$. But by a remark in [1, p. 17] such an inclusion is no longer true for $\rho \neq 1$. It follows that for $0 \leq \delta \leq \rho < 1$ many elements of $\mathfrak{F}^{-1}[S_{\rho,\delta}^{-0}(\mathcal{X}^*; \mathcal{A}^\infty)]$ only belong to $\mathfrak{C}_A^B \setminus L^1(\mathcal{X}; \mathcal{A})$.

We finally state a result about how the algebra \mathfrak{B}_A^B can be generated from a simpler set of its elements. It is an adaptation of [27, Prop. 2.6].

Proposition 3.10. *The norm closure in $\mathfrak{A}^B(\Xi)$ of the subspaces generated either by $\{a \sharp^B b \mid a \in \mathcal{A}, b \in \mathcal{S}(\mathcal{X}^*)\}$ or by $\{b \sharp^B a \mid b \in \mathcal{A}, a \in \mathcal{S}(\mathcal{X}^*)\}$ are equal and coincide with the C^* -algebra \mathfrak{B}_A^B .*

We now recall the definition of a covariant representation of a magnetic C^* -dynamical system. We denote by $\mathcal{U}(\mathcal{H})$ the group of unitary operators in the Hilbert space \mathcal{H} .

Definition 3.11. Given a magnetic C^* -dynamical system $(\mathcal{A}, \theta, \omega^B, \mathcal{X})$ we define a *covariant representation* (\mathcal{H}, r, T) to be a Hilbert space \mathcal{H} together with two maps $r : \mathcal{A} \rightarrow \mathcal{B}(\mathcal{H})$ and $T : \mathcal{X} \rightarrow \mathcal{U}(\mathcal{H})$ satisfying

- (a) r is a non-degenerate representation,
- (b) T is strongly continuous and $T(x)T(y) = r[\omega^B(x, y)]T(x + y)$ for all $x, y \in \mathcal{X}$,
- (c) $T(x)r(\varphi)T(x)^* = r[\theta_x(\varphi)]$ for all $x \in \mathcal{X}$ and $\varphi \in \mathcal{A}$.

Lemma 3.12. *If (\mathcal{H}, r, T) is a covariant representation of the magnetic C^* -dynamical system $(\mathcal{A}, \theta, \omega^B, \mathcal{X})$, then \mathfrak{Rep}_r^T defined on $L^1(\mathcal{X}; \mathcal{A})$ by*

$$\mathfrak{Rep}_r^T(F) := \int_{\mathcal{X}} dx r[\theta_{x/2}(F(x))]T(x)$$

extends to a representation of $\mathfrak{C}_A^B = \mathcal{A} \rtimes_{\theta}^{\omega^B} \mathcal{X}$.

One can recover the covariant representation from \mathfrak{Rep}_r^T . Actually, there is a one-to-one correspondence between covariant representations of a twisted C^* -dynamical system and non-degenerate representations of the twisted crossed product, which preserves unitary equivalence, irreducibility and direct sums.

By composing with the partial Fourier transformation, one gets the most general representations of the pseudodifferential C^* -algebra \mathfrak{B}_A^B , denoted by

$$\mathfrak{Op}_r^T : \mathfrak{B}_A^B \rightarrow \mathcal{B}(\mathcal{H}), \quad \mathfrak{Op}_r^T(f) := \mathfrak{Rep}_r^T[\mathfrak{F}^{-1}(f)].$$

Given any continuous vector potential A we construct a representation of \mathfrak{C}_A^B in $\mathcal{H} = L^2(\mathcal{X})$. For any $u \in \mathcal{H}$ and $x, y \in \mathcal{X}$, we define the *magnetic translations*

$$[T^A(y)u](x) := \lambda^A(x; y)u(x + y) = e^{-i\Gamma^A([x, x+y])}u(x + y).$$

Let us also set $r(\varphi) := \varphi(Q)$ for any $\varphi \in \mathcal{A}$, where $\varphi(Q)$ denotes an operator of multiplication in \mathcal{H} . Then the triple (\mathcal{H}, r, T^A) is a covariant representation of the magnetic C^* -dynamical system (see [27, Sec. 4] for details). The corresponding representation $\mathfrak{Rep}_r^{T^A}$ of the algebra \mathfrak{C}_A^B , denoted by \mathfrak{Rep}^A , is explicitly given for any $F \in L^1(\mathcal{X}; \mathcal{A})$ and any $u \in \mathcal{H}$ by

$$(3.1) \quad [\mathfrak{Rep}^A(F)u](x) = \int_{\mathcal{X}} dy \lambda^A(x; y - x)F(\frac{1}{2}(x + y); y - x)u(y).$$

This representation is called the *Schrödinger representation of \mathfrak{C}_A^B associated with the vector potential A* . It is proved in [27, Prop. 2.17] that this representation is

faithful. We recall that the choice of another vector potential generating the same magnetic field would lead to a unitarily equivalent representation of \mathfrak{C}_A^B in $\mathcal{B}(\mathcal{H})$. By comparing (2.4) and (3.1), one sees that $\mathfrak{Op}^A \equiv \mathfrak{Op}_r^{T^A}$ and \mathfrak{Rep}^A are connected by the partial Fourier transform: $\mathfrak{Op}^A(f) = \mathfrak{Rep}^A[\mathfrak{F}^{-1}(f)]$ for suitable f .

§3.3. Inversion

The following approach is mainly inspired by a similar construction in [14, Sec. 7.1]. It also relies on some basic results on Ψ^* -algebras that we borrow from [19, Sec. 2] (see also [20] and references therein).

Let \mathfrak{C} be a C^* -algebra with unit 1, and let \mathfrak{S} be a $*$ -subalgebra of \mathfrak{C} with $1 \in \mathfrak{S}$. \mathfrak{S} is called *spectrally invariant* if $\mathfrak{S} \cap \mathfrak{C}^{-1} = \mathfrak{S}^{-1}$, where \mathfrak{S}^{-1} , resp. \mathfrak{C}^{-1} , denotes the set of invertible elements in \mathfrak{S} , resp. \mathfrak{C} . Furthermore, \mathfrak{S} is called a Ψ^* -algebra if it is spectrally invariant and endowed with a Fréchet topology such that the embedding $\mathfrak{S} \hookrightarrow \mathfrak{C}$ is continuous. It is shown in [19, Cor. 2.5] that a closed $*$ -subalgebra of a Ψ^* -algebra (also containing 1), endowed with the restricted topology, is also a Ψ^* -algebra.

It has been proved in [14] that for $\rho \in [0, 1]$, $S_{\rho,0}^0(\Xi)$ is a Ψ^* -algebra in $\mathfrak{A}^B(\Xi)$. Then, since $S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$ is a closed $*$ -subalgebra of $S_{\rho,0}^0(\Xi)$ by our Lemma 2.8(a) and Theorem 2.9, it follows that $S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$ is a Ψ^* -algebra in $\mathfrak{A}^B(\Xi)$. In particular, if $f \in S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$ has an inverse in $\mathfrak{A}^B(\Xi)$ with respect to \sharp^B , denoted by $f^{(-1)B}$, then this inverse belongs to $S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$. As by-products of the theory of Ψ^* -algebras, one can state

Proposition 3.13. *$S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$ is a Ψ^* -algebra, it is stable under the holomorphic functional calculus, $[S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)]^{(-1)B}$ is open and the map*

$$[S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)]^{(-1)B} \ni f \mapsto f^{(-1)B} \in S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$$

is continuous.

In order to state the next lemma some notations are needed. For $m > 0$, $\lambda > 0$ and $\xi \in \mathcal{X}^*$, set

$$\mathfrak{p}_{m,\lambda}(\xi) := \langle \xi \rangle^m + \lambda.$$

The map $\mathfrak{p}_{m,\lambda}$ is clearly an element of $S_{1,0}^m(\mathcal{X}^*; \mathcal{A}^\infty)$, and its pointwise inverse an element of $S_{1,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty)$. It has been proved in [28, Thm. 1.8] that for λ large enough, $\mathfrak{p}_{m,\lambda}$ is invertible with respect to the composition law \sharp^B and that its inverse $\mathfrak{p}_{m,\lambda}^{(-1)B}$ belongs to \mathfrak{B}_A^B . So for any $m > 0$ we can fix $\lambda = \lambda(m)$ such that $\mathfrak{p}_{m,\lambda(m)}$ is invertible. Then, for arbitrary $m \in \mathbb{R}$, we set

$$\mathfrak{r}_m := \begin{cases} \mathfrak{p}_{m,\lambda(m)} & \text{for } m > 0, \\ \mathfrak{p}_{|m|,\lambda(|m|)}^{(-1)B} & \text{for } m < 0, \end{cases}$$

and $\tau_0 := 1$. The relation $\tau_m^{(-1)B} = \tau_{-m}$ clearly holds for all $m \in \mathbb{R}$. Let us show another important property of τ_m .

Lemma 3.14. *For any $m \in \mathbb{R}$, one has $\tau_m \in S_{1,0}^m(\mathcal{X}^*; \mathcal{A}^\infty)$.*

Proof. For $m \geq 0$, the statement is trivial from the definition of τ_m . But for $m < 0$ the function τ_m will also depend on the variable x , so one has to take the proof of [28, Thm. 1.8] into account. Indeed, it has been shown there that for λ large enough, $\mathfrak{p} := \mathfrak{p}_{|m|, \lambda(|m|)}$ is invertible with respect to the composition law \sharp^B , and that its inverse is given by the formula

$$(3.2) \quad \mathfrak{p}^{(-1)B} = \mathfrak{p}^{-1} \sharp^B (\mathfrak{p} \sharp^B \mathfrak{p}^{-1})^{(-1)B},$$

where \mathfrak{p}^{-1} is the inverse of \mathfrak{p} with respect to pointwise multiplication, and λ has been chosen such that $(\mathfrak{p} \sharp^B \mathfrak{p}^{-1})^{(-1)B}$ is well defined and belongs to $\mathfrak{A}^B(\Xi)$. Furthermore, since \mathfrak{p}^{-1} belongs to $S_{1,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty)$, the product $\mathfrak{p} \sharp^B \mathfrak{p}^{-1}$ belongs to $S_{1,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$. It then follows that the inverse of $\mathfrak{p} \sharp^B \mathfrak{p}^{-1}$ also belongs to $S_{1,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$ by the Ψ^* -property of $S_{1,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$. One concludes by observing that the r.h.s. of (3.2) belongs to $S_{1,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty)$, and corresponds to τ_m for $m < 0$. \square

Proposition 3.15. *Let $m > 0$, $\rho \in [0, 1]$ and $f \in S_{\rho,0}^m(\mathcal{X}^*; \mathcal{A}^\infty)$. If f is invertible in $\mathfrak{M}^B(\Xi)$ and $\tau_m \sharp^B f^{(-1)B} \in \mathfrak{A}^B(\Xi)$, then $f^{(-1)B}$ belongs to $S_{\rho,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty)$.*

Proof. Let us first observe that

$$f \sharp^B \tau_{-m} \in S_{\rho,0}^m(\mathcal{X}^*; \mathcal{A}^\infty) \sharp^B S_{1,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty) \subset S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty).$$

This element is invertible in $\mathfrak{A}^B(\Xi)$ since its inverse $(f \sharp^B \tau_{-m})^{(-1)B}$ is equal to $\tau_m \sharp^B f^{(-1)B}$, which belongs to $\mathfrak{A}^B(\Xi)$. By the Ψ^* -property of $S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$, it then follows that $(f \sharp^B \tau_{-m})^{(-1)B}$ belongs to $S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty)$, and so does $\tau_m \sharp^B f^{(-1)B}$. Consequently, one has

$$f^{(-1)B} = \tau_{-m} \sharp^B [\tau_m \sharp^B f^{(-1)B}] \in S_{\rho,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty) \sharp^B S_{\rho,0}^0(\mathcal{X}^*; \mathcal{A}^\infty) \subset S_{\rho,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty). \quad \square$$

In order to verify the hypotheses of the above proposition, a condition of ellipticity is usually needed.

Definition 3.16. A symbol $f \in S_{\rho,\delta}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ is called *elliptic* if there exist $R, C > 0$ such that

$$|f(x, \xi)| \geq C \langle \xi \rangle^m \quad \text{for all } x \in \mathcal{X} \text{ and } |\xi| > R.$$

We are now in a position to state and prove our main theorem on inversion (see also the Appendix):

Theorem 3.17. *Let $m > 0$, $\rho \in [0, 1]$ and f be a real-valued elliptic element of $S_{\rho,0}^m(\mathcal{X}^*; \mathcal{A}^\infty)$. Then for any $z \in \mathbb{C} \setminus \mathbb{R}$ the function $f - z$ is invertible in $\mathcal{M}^B(\Xi)$ and its inverse $(f - z)^{(-1)B}$ belongs to $S_{\rho,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty)$.*

Proof. It has been proved in [13, Thm. 4.1] that $\mathfrak{Op}^A(f)$ defines a self-adjoint operator in $\mathcal{H} := L^2(\mathcal{X})$ for any vector potential A whose components belong to $C_{\text{pol}}^\infty(\mathcal{X})$. In particular, z does not belong to the spectrum of $\mathfrak{Op}^A(f)$, which is independent of A by gauge covariance, and $\mathfrak{Op}^A(f) - z = \mathfrak{Op}^A(f - z)$ is invertible. Its inverse belongs to $\mathcal{B}(\mathcal{H})$, which means that $(f - z)^{(-1)B}$ exists in $\mathcal{M}^B(\Xi)$ and belongs to $\mathfrak{A}^B(\Xi)$. Moreover, Theorem 4.1 of [13] also implies $\mathfrak{Op}^A[(f - z) \sharp^B \mathfrak{r}_m^{(-1)B}]$ is a bijection on \mathcal{H} , and thus $\mathfrak{r}_m \sharp^B (f - z)^{(-1)B} = [(f - z) \sharp^B \mathfrak{r}_m^{(-1)B}]^{(-1)B} \in \mathfrak{A}^B(\Xi)$. One finally concludes by taking Proposition 3.15 into account. \square

§3.4. Affiliation

We start by recalling the meaning of affiliation, borrowed from [1]. We shall then prove that some of the classes of symbols introduced in Section 2 define observables affiliated to \mathfrak{B}_A^B .

Definition 3.18. An observable affiliated to a C^* -algebra \mathfrak{C} is a morphism $\Phi : C_0(\mathbb{R}) \rightarrow \mathfrak{C}$.

For example, if \mathcal{H} is a Hilbert space and \mathfrak{C} is a C^* -subalgebra of $\mathcal{B}(\mathcal{H})$, then a self-adjoint operator H in \mathcal{H} defines an observable Φ_H affiliated to \mathfrak{C} if and only if $\Phi_H(\eta) := \eta(H)$ belongs to \mathfrak{C} for all $\eta \in C_0(\mathbb{R})$. A sufficient condition is that $(H - z)^{-1} \in \mathfrak{C}$ for some $z \in \mathbb{C}$ with $\text{Im } z \neq 0$. Thus an observable affiliated to a C^* -algebra is the abstract version of the functional calculus of a self-adjoint operator.

The next result is a rather simple corollary of our previous results. We call it a theorem to stress its importance in our subsequent spectral results.

Theorem 3.19. *For $m > 0$ and $\rho \in [0, 1]$, any real-valued elliptic element $f \in S_{\rho,0}^m(\mathcal{X}^*; \mathcal{A}^\infty)$ defines an observable affiliated to the C^* -algebra \mathfrak{B}_A^B .*

Proof. For $z \in \mathbb{C} \setminus \mathbb{R}$, let us set $r_z := (f - z)^{-1}$. We also define $\Phi(r_z) := (f - z)^{(-1)B}$. We first prove that the family $\{\Phi(r_z) \mid z \in \mathbb{C} \setminus \mathbb{R}\}$ satisfies the resolvent equation. Indeed, for any $z, z' \in \mathbb{C} \setminus \mathbb{R}$, one has

$$(f - z) \sharp^B \Phi(r_z) = 1 \quad \text{and} \quad (f - z') \sharp^B \Phi(r_{z'}) = 1.$$

By subtraction, one obtains $(f - z) \sharp^B [\Phi(r_z) - \Phi(r_{z'})] + (z' - z)\Phi(r_{z'}) = 0$. By multiplication on the left with $\Phi(r_z)$ and using associativity, one then gets the

resolvent equation

$$\Phi(r_z) - \Phi(r_{z'}) = (z - z')\Phi(r_z) \#^B \Phi(r_{z'}).$$

We have thus obtained a map $\mathbb{C} \setminus \mathbb{R} \ni z \mapsto \Phi(r_z) \in S_{\rho,0}^{-m}(\mathcal{X}^*; \mathcal{A}^\infty) \subset \mathfrak{B}_A^B$, where Theorem 3.17 and Proposition 3.3 have been taken into account. Furthermore, the relation $\Phi(r_z) \#^B = \Phi(r_{\bar{z}})$ clearly holds. A general argument presented in [1, p. 364] allows one now to extend the map Φ in a unique way to a C^* -algebra morphism $C_0(\mathbb{R}) \rightarrow \mathfrak{B}_A^B$. \square

§4. Spectral analysis

§4.1. Preliminaries

Recall that \mathcal{A} is a C^* -subalgebra of $BC_u(\mathcal{X})$ which is invariant under translations. Such an algebra is called *admissible*. It is also unital, but most of the constructions do not require this. For any $\varphi \in \mathcal{A}$ we systematically denote by $\tilde{\varphi}$ the unique element of $C(S_A)$ satisfying $\varphi = \tilde{\varphi} \circ \iota_A$. In fact, $\tilde{\varphi}$ corresponds to the image of φ under the Gelfand isomorphism $\mathcal{G}_A : \mathcal{A} \rightarrow C(S_A)$.

A basic fact is that \mathcal{A} comes together with a family of short exact sequences

$$(4.1) \quad 0 \rightarrow \mathcal{A}^{\mathcal{Q}} \rightarrow \mathcal{A} \xrightarrow{\pi_{\mathcal{Q}}} \mathcal{A}_{\mathcal{Q}} \rightarrow 0$$

indexed by \mathbf{Q}_A , the set of all quasi-orbits of the topological dynamical space $(S_A, \theta, \mathcal{X})$. We recall that a quasi-orbit is the closure of an orbit, and let us now explain the meaning of (4.1).

For $\mathcal{Q} \in \mathbf{Q}_A$ we say that the element $\kappa \in S_A$ *generates* \mathcal{Q} if the orbit of κ is dense in \mathcal{Q} . In general not all the elements of \mathcal{Q} generate it. There is a canonical epimorphism $p_{\mathcal{Q}} : C(S_A) \rightarrow C(\mathcal{Q})$, coming from the inclusion of the closed set \mathcal{Q} in S_A . On the other hand, if κ generates \mathcal{Q} , we set $\mathcal{A}_{\kappa} := \{\varphi_{\kappa} := \tilde{\varphi} \circ \theta^{\kappa} \mid \tilde{\varphi} \in C(\mathcal{Q})\}$. It is clear that \mathcal{A}_{κ} is an admissible C^* -algebra isomorphic to $C(\mathcal{Q})$. Indeed, by taking into account the surjectivity of the morphism $p_{\mathcal{Q}}$ and the continuity of translations in $\mathcal{A} \subset BC_u(\mathcal{X})$, one easily sees that $\varphi_{\kappa} : \mathcal{X} \rightarrow \mathbb{C}$ belongs to $BC_u(\mathcal{X})$. Furthermore, the induced action of \mathcal{X} on φ_{κ} coincides with the natural action of \mathcal{X} on $BC_u(\mathcal{X})$. Thus, we get an epimorphism $\pi_{\kappa} : \mathcal{A} \rightarrow \mathcal{A}_{\kappa}$ by setting $\pi_{\kappa} := \theta^{\kappa} \circ p_{\mathcal{Q}} \circ \mathcal{G}_A$. We note that in general \mathcal{A}_{κ} has no reason to be contained in \mathcal{A} .

It is clear that the kernel of this epimorphism is $\mathcal{A}^{\mathcal{Q}} = \{\varphi \in \mathcal{A} \mid \tilde{\varphi}|_{\mathcal{Q}} = 0\}$. Furthermore, if κ and κ' generate the same quasi-orbit \mathcal{Q} , the algebras \mathcal{A}_{κ} and $\mathcal{A}_{\kappa'}$ are isomorphic. So by a slight abuse of notation, we call them *generically* $\mathcal{A}_{\mathcal{Q}}$, and denote the corresponding morphism by $\pi_{\mathcal{Q}}$. This finishes our explanation of (4.1).

We now recall some more definitions in relation to spectral analysis in a C^* -algebraic framework (cf. [1]). Let Φ be an observable affiliated to a C^* -algebra \mathfrak{C}

and let \mathfrak{K} be an ideal of \mathfrak{C} . Then the \mathfrak{K} -essential spectrum of Φ is

$$\sigma_{\mathfrak{K}}(\Phi) := \{\lambda \in \mathbb{R} \mid \text{if } \eta \in C_0(\mathbb{R}) \text{ and } \eta(\lambda) \neq 0, \text{ then } \Phi(\eta) \notin \mathfrak{K}\}.$$

If π denotes the canonical morphism $\mathfrak{C} \rightarrow \mathfrak{C}/\mathfrak{K}$, then $\pi[\Phi] : C_0(\mathbb{R}) \rightarrow \mathfrak{C}/\mathfrak{K}$ given by $(\pi[\Phi])(\eta) := \pi[\Phi(\eta)]$ is an observable affiliated to the quotient algebra, and one has $\sigma_{\mathfrak{K}}(\Phi) = \sigma_{\{0\}}(\pi[\Phi]) \equiv \sigma(\pi[\Phi])$. Assume now that \mathfrak{C} is a C^* -subalgebra of $\mathcal{B}(\mathcal{H})$ for some Hilbert space \mathcal{H} and that \mathfrak{C} contains the ideal $\mathcal{K}(\mathcal{H})$ of compact operators on \mathcal{H} . Furthermore, let H be a self-adjoint operator in \mathcal{H} affiliated to \mathfrak{C} . Then $\sigma_{\mathcal{K}(\mathcal{H})}(\Phi_H)$ is equal to the essential spectrum $\sigma_{\text{ess}}(H)$ of H . Here we shall be mainly interested in the usual spectrum and in the essential spectrum. The need for the \mathfrak{K} -essential spectrum with \mathfrak{K} different from $\{0\}$ or $\mathcal{K}(\mathcal{H})$ is relevant in the context of Remark 4.5 below.

§4.2. The essential spectrum of anisotropic magnetic operators

We again consider the magnetic twisted C^* -dynamical system $(\mathcal{A}, \theta, \omega^B, \mathcal{X})$ and explain how to calculate the essential spectrum of any observable affiliated to the twisted crossed product algebra $\mathfrak{C}_{\mathcal{A}}^B$. Then, by using the results of the previous sections, we particularize to the case of magnetic pseudodifferential operators and prove our main result concerning their essential spectrum. For simplicity, in this section we omit the subscript B on the 2-cocycle ω^B .

We now follow the strategy of [24, 28] (see also references therein). We are going to assume that \mathcal{A} contains $C_0(\mathcal{X})$, so $S_{\mathcal{A}}$ is a compact space and \mathcal{X} can be identified with a dense open subset of $S_{\mathcal{A}}$. Since the group law $\theta : \mathcal{X} \times \mathcal{X} \rightarrow \mathcal{X}$ extends to a continuous map $\theta : \mathcal{X} \times S_{\mathcal{A}} \rightarrow S_{\mathcal{A}}$, the complement $F_{\mathcal{A}}$ of \mathcal{X} in $S_{\mathcal{A}}$ is closed and invariant; it is the space of a compact topological dynamical system. For any quasi-orbit \mathcal{Q} , the algebra $\mathcal{A}^{\mathcal{Q}}$ is clearly an invariant ideal of \mathcal{A} . The abelian twisted dynamical system $(\mathcal{A}^{\mathcal{Q}}, \theta, \omega, \mathcal{X})$ obtained by replacing \mathcal{A} with $\mathcal{A}^{\mathcal{Q}}$ and performing suitable restrictions is well defined. Furthermore, the twisted crossed product $\mathcal{A}^{\mathcal{Q}} \rtimes_{\theta}^{\omega} \mathcal{X}$ may be identified with an ideal of $\mathcal{A} \rtimes_{\theta}^{\omega} \mathcal{X}$ [32, Prop. 2.2].

In order to have an explicit description of the quotient, let us first note that $\mathcal{A}/\mathcal{A}^{\mathcal{Q}}$ is canonically isomorphic to the unital C^* -algebra $C(\mathcal{Q})$ of all continuous functions on \mathcal{Q} . The natural action of \mathcal{X} on $\tilde{\varphi} \in C(\mathcal{Q})$ is given by $(\theta_x \tilde{\varphi})(\kappa) = \tilde{\varphi}(\theta_x[\kappa])$ for each $x \in \mathcal{X}$ and $\kappa \in \mathcal{Q}$. Now, the restriction of ω to \mathcal{Q} gives rise to a 2-cocycle $\omega_{\mathcal{Q}} : \mathcal{X} \times \mathcal{X} \rightarrow \mathcal{U}(C(\mathcal{Q}))$ precisely defined by $\omega_{\mathcal{Q}}(x, y) := p_{\mathcal{Q}}[\mathcal{G}_{\mathcal{A}}(\omega(x, y))]$ for each $x, y \in \mathcal{X}$. Thus $(C(\mathcal{Q}), \theta, \omega_{\mathcal{Q}}, \mathcal{X})$ is a well-defined abelian twisted C^* -dynamical system. Moreover, the quotient $\mathcal{A} \rtimes_{\theta}^{\omega} \mathcal{X} / \mathcal{A}^{\mathcal{Q}} \rtimes_{\theta}^{\omega} \mathcal{X}$ may be identified with the corresponding twisted crossed product $C(\mathcal{Q}) \rtimes_{\theta}^{\omega_{\mathcal{Q}}} \mathcal{X}$. This follows from [32, Prop. 2.2] if \mathcal{A} is separable. For the non-separable case, just perform obvious modifications in the proof of [8, Th. 2.10] to accommodate the 2-cocycle. Finally,

by taking the isomorphisms π_Q introduced in Section 4.1 into account, the algebra $C(Q) \rtimes_{\theta}^{\omega_Q} \mathcal{X}$ is isomorphic to $\mathcal{A}_Q \rtimes_{\theta}^{\omega_Q} \mathcal{X}$, and the canonical morphism $\Pi_Q : \mathcal{A} \rtimes_{\theta}^{\omega} \mathcal{X} \rightarrow \mathcal{A}_Q \rtimes_{\theta}^{\omega_Q} \mathcal{X}$ is defined on any $F \in L^1(\mathcal{X}; \mathcal{A})$ by $(\Pi_Q[F])(x) = \pi_Q(F(x))$ for all $x \in \mathcal{X}$.

Let us now consider $\mathbf{Q} \subset \mathbf{Q}_A$ such that the elements Q of \mathbf{Q} define a covering of F_A . At the algebraic level, the covering requirement reads $\bigcap_{Q \in \mathbf{Q}} \mathcal{A}^Q = C_0(\mathcal{X})$. This immediately implies the equality

$$\bigcap_{Q \in \mathbf{Q}} \mathcal{A}^Q \rtimes_{\theta}^{\omega} \mathcal{X} = C_0(\mathcal{X}) \rtimes_{\theta}^{\omega} \mathcal{X}.$$

By putting all these together one obtains (cf. also [24, Prop. 1.5]):

Proposition 4.1. *Let $\mathbf{Q} \subset \mathbf{Q}_A$ define a covering of F_A by quasi-orbits.*

- (a) *There exists an injective morphism $\mathcal{A} \rtimes_{\theta}^{\omega} \mathcal{X} / C_0(\mathcal{X}) \rtimes_{\theta}^{\omega} \mathcal{X} \hookrightarrow \prod_{Q \in \mathbf{Q}} \mathcal{A}_Q \rtimes_{\theta}^{\omega_Q} \mathcal{X}$.*
- (b) *If Φ is an observable affiliated to $\mathcal{A} \rtimes_{\theta}^{\omega} \mathcal{X}$ and $\mathfrak{K} := C_0(\mathcal{X}) \rtimes_{\theta}^{\omega} \mathcal{X}$, then*

$$(4.2) \quad \sigma_{\mathfrak{K}}(\Phi) = \overline{\bigcup_{Q \in \mathbf{Q}} \sigma(\Pi_Q[\Phi])}.$$

We now introduce a represented version of this proposition in the Hilbert space $\mathcal{H} := L^2(\mathcal{X})$. We recall that for any continuous vector potential A , a representation \mathfrak{Rep}^A of $\mathcal{A} \rtimes_{\theta}^{\omega} \mathcal{X}$ has been introduced in (3.1), and that this representation is irreducible and faithful [27, Prop. 2.17]. Furthermore, it is proved there that $\mathfrak{Rep}^A(C_0(\mathcal{X}) \rtimes_{\theta}^{\omega} \mathcal{X})$ is equal to $\mathcal{K}(\mathcal{H})$. If Φ is an observable affiliated to $\mathcal{A} \rtimes_{\theta}^{\omega} \mathcal{X}$, then the l.h.s. term of (4.2) is equal to $\sigma_{\text{ess}}(\mathfrak{Rep}^A(\Phi))$, and it does not depend on the choice of A .

We are now in a position to prove a concrete result for the calculation of the essential spectrum of any magnetic pseudodifferential operator. It consists essentially in an application of Proposition 4.1 together with a partial Fourier transformation. It also relies on the affiliation result obtained in Theorem 3.19. The components of the magnetic field B_Q are defined by $\pi_Q(B_{jk})$.

Theorem 4.2. *Let $m > 0$, $\rho \in [0, 1]$ and let $\mathbf{Q} \subset \mathbf{Q}_A$ define a covering of F_A . Then, for any real-valued elliptic element f of $S_{\rho,0}^m(\mathcal{X}^*; \mathcal{A}^{\infty})$, one has*

$$\sigma_{\text{ess}}[\mathfrak{Op}^A(f)] = \overline{\bigcup_{Q \in \mathbf{Q}} \sigma[\mathfrak{Op}^{A_Q}(f_Q)]},$$

where A and A_Q are continuous vector potentials for B and B_Q , and $f_Q \in S_{\rho,0}^m(\mathcal{X}^*; \mathcal{A}_Q)$ is the image of f through π_Q .

Proof. Let us first observe that the morphism

$$\mathfrak{F}(L^1(X; \mathcal{A})) \ni g \mapsto \mathfrak{F}(\Pi_Q[\mathfrak{F}^{-1}(g)]) \in \mathfrak{F}[L^1(X; C(Q))]$$

extends to a surjective morphism $\tilde{\Pi}_{\mathcal{Q}} : \mathfrak{B}_A^B \rightarrow \mathfrak{B}_{A_{\mathcal{Q}}}^{B_{\mathcal{Q}}}$. The equality (4.2) can then be rewritten in this framework, and for any observable f affiliated to \mathfrak{B}_A^B ,

$$\sigma_{\mathfrak{K}}(f) = \overline{\bigcup_{\mathcal{Q} \in \mathcal{Q}} \sigma(\tilde{\Pi}_{\mathcal{Q}}[f])},$$

where \mathfrak{K} is now the ideal of \mathfrak{B}_A^B given by the image of $C_0(\mathcal{X}) \times_{\theta}^{\omega} \mathcal{X}$ under the map \mathfrak{F} . The result now follows from the crucial observation that $\tilde{\Pi}_{\mathcal{Q}}[f]$ is equal to $f_{\mathcal{Q}}$ and by considering faithful representations of \mathfrak{B}_A^B through \mathfrak{Op}^A and of $\mathfrak{B}_{A_{\mathcal{Q}}}^{B_{\mathcal{Q}}}$ through $\mathfrak{Op}^{A_{\mathcal{Q}}}$. \square

Remark 4.3. Combining our approach with techniques from [1, 7, 8], one could extend the result above to more singular symbols f . We shall not do this; our main goal was to cover functions f which have no specific dependence on the variable in Ξ (as $f(x, \xi) = h(\xi) + V(x)$ for instance) in a pseudodifferential setting.

Remark 4.4. To have a good understanding of (4.2), one needs admissible algebras \mathcal{A} for which the space $\mathcal{Q}_{\mathcal{A}}$ is explicit enough. Many examples are scattered through [1, 2, 7, 9, 8, 24, 28, 34] and we will not reconsider this topic here.

Remark 4.5. Non-propagation results easily follow from this algebraic framework. They have been explicitly exhibited in the non-magnetic case in [2] and in the magnetic case in [28]. In these references, the authors were mainly concerned with generalized Schrödinger operators and their results were stated for these operators. But the proof relies only on the C^* -algebraic framework, and the results extend mutatis mutandis to the classes of symbols introduced in the present paper. For brevity, we do not present these propagation estimates here, but statements and proofs can easily be mimicked from these references.

Appendix: An independent proof for the affiliation

In this Appendix, we give a second proof of Theorem 3.19, independent of the results contained in [14].

Let us consider $m > 0$, $\rho \in (0, 1]$ and a real-valued elliptic element f of $S_{\rho, 0}^m(\mathcal{X}^*; \mathcal{A}^{\infty})$. For some $z \in \mathbb{C}$, we are first going to show that $(f - z)^{(-1)B}$ belongs to \mathfrak{B}_A^B by writing down a series for the inverse $(f - z)^{(-1)B}$ of the form

$$(f - z)^{(-1)B} = (f - z)^{-1} \sharp^B \sum_{k=0}^{\infty} [1 - (f - z) \sharp^B (f - z)^{-1}]^{k \sharp^B},$$

with $(f - z)^{-1}$ the pointwise inverse of $f - z$. Notice that $(f - z)^{-1}$ belongs to $S_{\rho, 0}^{-m}(\mathcal{X}^*; \mathcal{A}^{\infty}) \subset \mathfrak{B}_A^B$ by ellipticity, and that $g^{k \sharp^B}$ denotes the k th power of g with

respect to \sharp^B . By the asymptotic development, one knows that the remainder $R_z := (f - z) \sharp^B (f - z)^{-1} - 1$ belongs to $S_{\rho,0}^{-\rho}(\mathcal{X}^*; \mathcal{A}^\infty) \subset \mathfrak{B}_A^B$. However, an additional argument is needed to show that the $\|\cdot\|_B$ -norm of R_z is subunitary for suitable z , ensuring the convergence of the Neumann series.

For that purpose, we recall from Section 3 that $\|R_z\|_B \equiv \|R_z\|_{\mathfrak{B}^B(\Xi)} := \|\mathfrak{Op}^A(R_z)\|_{\mathcal{B}(\mathcal{H})}$. Furthermore, from the magnetic Calderón–Vaillancourt theorem this norm can be estimated from above by expressions of the form

$$(4.3) \quad \sup_{(x,\xi) \in \Xi} \langle \xi \rangle^{\rho(|\delta|-|d|)} |\partial_x^d \partial_\xi^\delta R_z(x, \xi)|$$

for a finite number of multi-indices $\delta, d \in \mathbb{N}^n$ (see Theorem 2.3 for the precise statement). Thus it remains to study the dependence on z of (4.3). Fortunately, a similar expression has already been studied in the proof of the asymptotic development and we shall rely on some of the expressions derived in the proof of Theorem 2.11.

Since f is an elliptic symbol of strictly positive order we can fix $z \in \mathbb{R}_-$ with $z \leq \inf f - 1$. The pointwise inverse of $f - z$ is thus well defined, and is denoted by $(f - z)^{-1}$. We recall from the proof of Theorem 2.11 that

$$(4.4) \quad R_z(X) = \sum_{\substack{a,b,\alpha,\beta,\alpha',\beta' \\ \alpha' \leq \alpha, \beta' \leq \beta \\ |a|+|b|+|\alpha|+|\beta|=1}} \int_0^1 d\tau \operatorname{pol}_{a,b}^{\alpha',\beta'}(\tau) I_{\tau,z,a,b}^{\alpha',\beta'}(X),$$

where $\operatorname{pol}_{a,b}^{\alpha',\beta'} : [0, 1] \rightarrow \mathbb{C}$ are polynomials and

$$\begin{aligned} I_{\tau,z,a,b}^{\alpha',\beta'}(X) &:= \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2i\sigma(Y,Z)} [\partial_z^{\alpha-\alpha'} \partial_y^{\beta-\beta'} \omega_B](x, y, z) \\ &\quad \cdot [\partial_x^{a+\beta'} \partial_\xi^{\alpha+b}(f - z)](x - \tau y, \xi - \tau \eta) [\partial_x^{b+\alpha'} \partial_\xi^{a+\beta}(f - z)^{-1}](x - \tau z, \xi - \tau \zeta). \end{aligned}$$

Retaining only its essential features, we shall rewrite this last expression as

$$\begin{aligned} I_{\tau,z}(X) &:= \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2i\sigma(Y,Z)} \Sigma_B(x, y, z) \\ &\quad \cdot F_z(x - \tau y, \xi - \tau \eta) G_z(x - \tau z, \xi - \tau \zeta). \end{aligned}$$

In order to obtain estimates for (4.3), let us calculate $\partial_x^d \partial_\xi^\delta I_{\tau,z}$. Actually, by using (2.10), the oscillatory integral definition of $\partial_x^d \partial_\xi^\delta I_{\tau,z}$ is

$$[\partial_x^d \partial_\xi^\delta I_{\tau,z}](X) = \sum_{\substack{d^0+d^1+d^2=d \\ \delta^1+\delta^2=\delta}} C_{d^0 d^1 d^2}^{\delta^1 \delta^2} \int_{\mathcal{X}} dy \int_{\mathcal{X}} dz \int_{\mathcal{X}^*} d\eta \int_{\mathcal{X}^*} d\zeta e^{-2i\sigma(Y,Z)} \cdot L_{p,q,d^0,d^1,d^2}^{\tau,z,\delta^1,\delta^2}(X,Y,Z),$$

where, for suitable integers p, q , the expression $L_{p,q,d^0,d^1,d^2}^{\tau,z,\delta^1,\delta^2}(X, Y, Z)$ is given by

$$\begin{aligned} &\langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle y \rangle^{-2q} \langle z \rangle^{-2q} \sum_{\substack{|b^1|+|b^2|+|b^3|=2p \\ |c^1|+|c^2|+|c^3|=2p \\ |q^1| \leq q, |q^2| \leq q}} C_{b^1 b^2 b^3}^{q^1 q^2 c^1 c^2 c^3} \varphi_{qc^1}(z) \psi_{qb^1}(y) \\ &\cdot [\partial_x^{d^0} \partial_y^{b^2} \partial_z^{c^2} \Sigma_B](x, y, z) (-\tau)^{2|q^1|+2|q^2|+|b^3|+|c^3|} \\ &\cdot [\partial_x^{d^1+b^3} \partial_\xi^{\delta^1+2q^1} F_z](x - \tau y, \xi - \tau \eta) [\partial_x^{d^2+c^3} \partial_\xi^{\delta^2+2q^2} G_z](x - \tau z, \xi - \tau \zeta), \end{aligned}$$

where φ_{qc^1} and ψ_{qb^1} are bounded functions produced by differentiating the factors $\langle z \rangle^{-2q}$ and $\langle y \rangle^{-2q}$, respectively. We now need an explicit dependence on z of the last two factors.

Let us first recall that $F_z = \partial_x^{a+\beta'} \partial_\xi^{\alpha+b}(f-z)$, and hence two distinct situations occur: If $a = \beta' = \alpha = b = d^1 = b^3 = \delta^1 = q^1 = 0$, then

$$|[\partial_x^{d^1+b^3} \partial_\xi^{\delta^1+2q^1} F_z](x - \tau y, \xi - \tau \eta)| \equiv |f(x - \tau y, \xi - \tau \eta) - z|$$

and this is the annoying contribution that has to be dealt with separately below. But if any of the above multi-indices is non-null, then the dependence on z vanishes, and one has

$$|[\partial_x^{d^1+b^3} \partial_\xi^{\delta^1+2q^1} F_z](x - \tau y, \xi - \tau \eta)| \leq c \langle \xi - \tau \eta \rangle^{m-\rho(|\alpha|+|b|+|\delta^1|+2|q^1|)}$$

with c independent of x, y, ξ, η, τ and z .

We now study the dependence on z of $|f(x - \tau z, \xi - \tau \zeta) - z|^{-1}$. Clearly, if $z' \leq z$, then $|f(x - \tau z, \xi - \tau \zeta) - z'|^{-1} \leq |f(x - \tau z, \xi - \tau \zeta) - z|^{-1}$, but this trivial estimate is going to be necessary but not sufficient. Then, by using the ellipticity of f , one finds that there exist $\kappa, \kappa_1, \kappa_2 \in \mathbb{R}_+$, depending only on f , such that for $|z|$ large enough one has $|f(x - \tau z, \xi - \tau \zeta) - z|^{-1} \leq \kappa_1 \langle \tau \zeta \rangle^m (\kappa_2 \langle \xi \rangle^m + |z| - \kappa)^{-1}$. One can then take into account the inequality $\kappa_2 \langle \xi \rangle^m + |z| - \kappa \geq \mu^{1/\mu} (\nu \kappa_2)^{1/\nu} (|z| - \kappa)^{1/\mu} \langle \xi \rangle^{m/\nu}$, valid for any $\mu, \nu \geq 1$ with $\mu^{-1} + \nu^{-1} = 1$, and obtain

$$|f(x - \tau z, \xi - \tau \zeta) - z|^{-1} \leq c (|z| - \kappa)^{-1/\mu} \langle \zeta \rangle^m \langle \xi \rangle^{-m/\nu}$$

with c dependent only on f, μ and ν .

Now, recall that $G_z = \partial_x^{b+\alpha'} \partial_\xi^{a+\beta}(f-z)^{-1}$. Similarly to F_z two distinct situations have to be considered: If $b = \alpha' = a = \beta = d^2 = c^3 = \delta^2 = q^2 = 0$,

then

$$|[\partial_x^{d^2+c^3} \partial_\xi^{\delta^2+2q^2} G_z](x - \tau z, \xi - \tau \zeta)| \equiv |f(x - \tau z, \xi - \tau \zeta) - z|^{-1}.$$

But if any of these multi-indices is non-null, then it is not difficult to obtain

$$(4.5) \quad \begin{aligned} &|[\partial_x^{d^2+c^3} \partial_\xi^{\delta^2+2q^2} G_z](x - \tau z, \xi - \tau \zeta)| \\ &\leq d|f(x - \tau z, \xi - \tau \zeta) - z|^{-2} \langle \xi - \tau \zeta \rangle^{m-\rho(|\alpha|+|\beta|+|\delta^2|+2|q^2|)} \end{aligned}$$

with d independent of x, z, ξ, ζ, τ and z .

So, let us first consider the simple situation, i.e. at least one of the multi-indices $a, \beta', \alpha, b, d^1, b^3, \delta^1, q^1$ is non-null. Then, by taking into account the above estimates, the explicit form of Σ_B and Lemma 2.10, one finds that for any $\tau \in [0, 1]$ the following inequalities hold:

$$\begin{aligned} &|L_{p,q,d^0,d^1,d^2}^{\tau,z,\delta^1,\delta^2}(X, Y, Z)| \\ &\leq C_{pqd^0d^1d^2}^{\delta^1\delta^2} \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle y \rangle^{-2q} \langle z \rangle^{-2q} (\langle y \rangle + \langle z \rangle)^{|d|+|\alpha|+|\beta|+4p} \\ &\quad \cdot \langle \xi - \tau \eta \rangle^{m-\rho(|\alpha|+|\beta|+|\delta^1|+2|q^1|)} |f(x - \tau z, \xi - \tau \zeta) - z|^{-1} \\ &\quad \cdot \langle \xi - \tau \zeta \rangle^{-\rho(|\alpha|+|\beta|+|\delta^2|+2|q^2|)} \\ &\leq D_{pqd^0d^1d^2}^{\delta^1\delta^2} (|z| - \kappa)^{-1/\mu} \langle \eta \rangle^{-2p+|m-\rho(|\alpha|+|\beta|+|\delta^1|)|} \langle \zeta \rangle^{-2p+m+\rho(|\alpha|+|\beta|+|\delta^2|)} \\ &\quad \cdot \langle y \rangle^{-2q+|\alpha|+|\beta|+4p+|d|} \langle z \rangle^{-2q+|\alpha|+|\beta|+4p+|d|} \langle \xi \rangle^{m(1-1/\nu)-\rho(1+|\delta|)}, \end{aligned}$$

where the trivial inequality mentioned above has been used once for the first inequality.

In the critical case, i.e. $a = \beta' = \alpha = b = d^1 = b^3 = \delta^1 = q^1 = 0$, one has $|\beta| = 1$ because of the definition of R_z given in (4.4). Thus, we are not in the exceptional case for G_z and (4.5) always holds. So, let us consider the following inequalities:

$$\begin{aligned} &\left| \frac{f(x - \tau y, \xi - \tau \eta) - z}{f(x - \tau z, \xi - \tau \zeta) - z} \right| \\ &\leq 1 + \left| \sum_{j=1}^n \tau(z_j - y_j) \frac{\int_0^1 ds [\partial_{x_j} f](x - \tau z + s\tau(z - y), \xi - \tau \zeta + s\tau(\zeta - \eta))}{f(x - \tau z, \xi - \tau \zeta) - z} \right| \\ &\quad + \left| \sum_{j=1}^n \tau(\zeta_j - \eta_j) \frac{\int_0^1 ds [\partial_{\xi_j} f](x - \tau z + s\tau(z - y), \xi - \tau \zeta + s\tau(\zeta - \eta))}{f(x - \tau z, \xi - \tau \zeta) - z} \right| \\ &\leq 1 + c|f(x - \tau z, \xi - \tau \zeta) - z|^{-1} \langle y \rangle \langle z \rangle \langle \eta \rangle^{m+1-\rho} \langle \zeta \rangle^{m+1-\rho} \langle \xi \rangle^m \\ &\leq 1 + d \langle y \rangle \langle z \rangle \langle \eta \rangle^{m+1-\rho} \langle \zeta \rangle^{2m+1-\rho} \end{aligned}$$

with c, d independent of all variables and of z . By using these inequalities one obtains in the critical case

$$\begin{aligned} & |L_{p,q,d^0,d^1,d^2}^{\tau,z,\delta^1,\delta^2}(X, Y, Z)| \\ & \leq C_{pqd^0,d^1,d^2}^{\delta^1,\delta^2} \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle y \rangle^{-2q} \langle z \rangle^{-2q} (\langle y \rangle + \langle z \rangle)^{|d|+1+4p} \\ & \quad \cdot \left| \frac{f(x - \tau y, \xi - \tau \eta) - z}{f(x - \tau z, \xi - \tau \zeta) - z} \right| |f(x - \tau z, \xi - \tau \zeta) - z|^{-1} \langle \xi - \tau \zeta \rangle^{m-\rho(1+|\delta^2|+2|q^2|)} \\ & \leq D_{pqd^0,d^1,d^2}^{\delta^1,\delta^2} (|z| - \kappa)^{-1/\mu} \langle \eta \rangle^{-2p} \langle \zeta \rangle^{-2p} \langle y \rangle^{-2q+1+4p+|d|} \langle z \rangle^{-2q+1+4p+|d|} \\ & \quad \cdot [1 + d \langle y \rangle \langle z \rangle \langle \eta \rangle^{m+1-\rho} \langle \zeta \rangle^{2m+1-\rho}] \langle \zeta \rangle^{m+|m-\rho(1+|\delta|)} \langle \xi \rangle^{m(1-1/\nu)-\rho(1+|\delta|)}. \end{aligned}$$

Then it only remains to insert these estimates for $L_{p,q,d^0,d^1,d^2}^{\tau,z,\delta^1,\delta^2}$ into the expression of R_z , and to observe that by choosing p large enough, one gets absolute integrability in η and ζ . A subsequent choice of q also ensures integrability in y and z .

We are now in a position to obtain estimates for (4.3). By summing the contributions in the critical case and in the regular one, we obtain

$$\langle \xi \rangle^{\rho(|\delta|-|d|)} |\partial_x^d \partial_\xi^\delta R_z(x, \xi)| \leq c(|z| - \kappa)^{-1/\mu} \langle \xi \rangle^{m(1-1/\nu)-\rho(1+|d|)}$$

with c independent of z, x and ξ . Then, by choosing ν close enough to 1 such that $m(1 - 1/\nu) - \rho < 0$, the expression decreases as $|z|$ increases. Thus, for $|z|$ large enough, $\|R_z\|_B$ is strictly less than 1 and the Neumann series is then convergent. It follows that $(f - z)^{(-1)_B}$ belongs to \mathfrak{B}_A^B for any $z \in \mathbb{R}_-$ with $|z|$ large enough. Finally, by an argument similar to the one proposed in the proof of Theorem 1.8 of [28], one can extend this result to any $z \in \mathbb{C} \setminus \mathbb{R}$ and show that the resolvent equation is satisfied. Then the general argument already quoted in the proof of Theorem 3.19 allows us to conclude.

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