# Deleting and Inserting Fixed Point Manifolds under the Weak Gap Condition

Dedicated to Professor Krzysztof Pawałowski on his 60th birthday

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# Abstract

Let G be a finite group and X a compact smooth manifold. It is of interest which smooth manifolds can be the G-fixed point sets of smooth G-actions on X. The deleting-inserting theorem of this paper is related to this problem and has applications to one-fixed-point actions on spheres as well as to Smith equivalence.

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## §1. Introduction

Let G be a finite group. In this paper, a manifold and a G-manifold mean a smooth manifold and a smooth G-manifold, respectively. Given a manifold X, it is a fundamental problem to study which manifolds and real vector bundles can be the G-fixed point sets and the normal bundles of G-fixed point sets, respectively, of smooth G-actions on X. This problem for the case where X is a disk was studied by B. Oliver [15], and for X a sphere in [11] under the gap condition. The Smith problem on tangential representations at fixed points on spheres is a part of the problem above and has been studied by various authors. It has been useful for the study of the problem to delete (or insert) manifolds from (or to) a given manifold X as G-fixed point sets. More precisely, for a given G-manifold Y having the diffeomorphism type of X and the G-fixed point set

$$Y^G = F_1 \amalg \cdots \amalg F_m$$

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and given integers  $1 \le r_1 \le \cdots \le r_n \le m$ , it is of interest whether there exists a *G*-manifold *Z* having the diffeomorphism type of *X* and the *G*-fixed point set

$$Z^G = F_{r_1} \amalg \cdots \amalg F_{r_n}$$

A finite group G is called an *Oliver group* if there exists a smooth G-action on a disk without G-fixed points, or equivalently if there never exists a normal series  $P \leq H \leq G$  such that P and G/H have prime power order and H/P is a cyclic group (cf. [16, 15, 6]). We studied such deleting-inserting methods for an Oliver group G invoking the gap condition for which the main requirement is

$$2\dim Y^g < \dim Y$$

for all non-trivial elements g of G, i.e.  $g \neq e$ . In the current paper we give a deleting-inserting theorem (Theorem 5.1) for an Oliver group under the weak gap condition which allows the case that  $2 \dim Y^g = \dim Y$  for  $g \in G$ . This theorem yields Theorems 1.3–1.10 below as applications.

Let  $\mathcal{S}(G)$  denote the set of all subgroups of G, and  $\mathcal{P}(G)$  the set of all primepower-order subgroups of G, where by convention  $\{e\} \in \mathcal{P}(G)$ . For a prime p, let  $G^{\{p\}}$  denote the smallest normal subgroup N of G such that |G/N| is a power of p, possibly |G/N| = 1. Let  $\mathcal{L}(G)$  denote the set of all subgroups H containing  $G^{\{p\}}$  for some prime p. A (finite-dimensional) real G-module V is called  $\mathcal{L}$ -free if  $V^L = 0$  for all  $L \in \mathcal{L}(G)$ . We define a G-submodule  $V_{\mathcal{L}}$  of V by

$$V_{\mathcal{L}} = (V - V^G) - \bigoplus_{p \text{ prime}} (V^{G^{\{p\}}} - V^G).$$

Let  $\mathbb{R}[G]$  denote the group ring of G with real coefficients having the canonical (left) G-action. Recall the following fact.

**Lemma 1.1** ([6, Theorem 2.3]). The real G-module  $V = \mathbb{R}[G]_{\mathcal{L}}$  has the following properties:

- (1.1.1)  $V^H = 0$  if and only if  $H \in \mathcal{L}(G)$ .
- (1.1.2) dim  $V^H \ge |K:H|$  dim  $V^K$  for all  $H \le K \in \mathcal{S}(G)$ .
- (1.1.3) The equality dim  $V^H = 2 \dim V^K$  holds, where  $H \le K \in \mathcal{S}(G)$ , if and only if |K:H| = 2,  $|KG^{\{2\}}: HG^{\{2\}}| = 2$ , and  $HG^{\{q\}} = G$  for all odd primes q.

By straightforward computation, we can show the next lemma.

**Lemma 1.2** ([13, Proposition 1.9]). If G is an Oliver group then  $\dim (\mathbb{R}[G]_{\mathcal{L}})^P \ge 2$  for all  $P \in \mathcal{P}(G)$ .

The following two theorems are an elaboration of [6, Theorem B]. In particular, for m = 1 they give smooth one-fixed-point actions on spheres.

**Theorem 1.3.** Let G be an Oliver group and m a positive integer. Then for any integer  $\ell \geq 3$  there exists a G-action on the standard sphere S of dimension

$$d_{\ell} = \ell \cdot \left\{ (|G| - 1) - \sum_{p \mid |G|} (|G/G^{\{p\}}| - 1) \right\}$$

with exactly m G-fixed points  $x_1, \ldots, x_m$  for which the tangential representations  $T_{x_i}(S)$  are all isomorphic to the  $\ell$ -fold direct sum  $\mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$  of  $\mathbb{R}[G]_{\mathcal{L}}$ .

Let  $\mathcal{PH}(G)$  denote the set of all pairs (P, H) consisting of  $P \in \mathcal{P}(G)$  and  $H \in \mathcal{S}(G)$  with P < H. Let  $\mathcal{PH}_2(G)$  denote the set of all pairs  $(P, H) \in \mathcal{PH}(G)$  such that |H : P| = 2,  $|HG^{\{2\}} : PG^{\{2\}}| = 2$ , and  $PG^{\{q\}} = G$  for all odd primes q. For a set  $\mathcal{A}$  of pairs (H, K) with  $H < K \in \mathcal{S}(G)$ , we say that a real G-module V satisfies the gap condition (resp. the weak gap condition) on  $\mathcal{A}$  if

(1.1)  $\dim V^H > 2 \dim V^K \quad (\text{resp. } \dim V^H \ge 2 \dim V^K)$ 

for any  $(H, K) \in \mathcal{A}$ . It should be remarked that if an  $\mathcal{L}$ -free real G-module V satisfies the weak gap condition on  $\mathcal{PH}_2(G)$  then  $V \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus m}$  satisfies the weak gap condition on  $\mathcal{PH}(G)$  for any  $m \geq \dim V$ .

**Theorem 1.4.** Let G be an Oliver group, m a positive integer, and V an  $\mathcal{L}$ -free real G-module satisfying the weak gap condition on  $\mathcal{PH}_2(G)$ . Then there exists an integer N such that for every integer  $\ell \geq N$  there exists a G-action on the standard sphere S with exactly m G-fixed points  $x_1, \ldots, x_m$  for which the tangential representations  $T_{x_i}(S)$  are all isomorphic to  $V \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$ .

Let  $\operatorname{RO}(G)$  denote the real representation ring. For a subset A of  $\operatorname{RO}(G)$ ,  $A_{\mathcal{P}}$  stands for the set

$$A \cap \bigcap_{P \in \mathcal{P}(G)} \operatorname{Ker}[\operatorname{res}_{P}^{G} : \operatorname{RO}(G) \to \operatorname{RO}(P)].$$

Real G-modules V and W are called *Smith equivalent* if there exists a homotopy sphere  $\Sigma$  with a G-action such that  $\Sigma^G$  consists of exactly two points a and b, and the tangential representations  $T_a(\Sigma)$  and  $T_b(\Sigma)$  are isomorphic to V and W, respectively. Let Sm(G) denote the *Smith set* of G, i.e.

$$Sm(G) = \{ [V] - [W] \in RO(G) \mid V \text{ is Smith equivalent to } W \}.$$

The subset  $\operatorname{Sm}(G)_{\mathcal{P}}$  is called the *primary Smith set* of G. For a subset A of  $\operatorname{RO}(G)$ ,  $A^{\mathcal{L}}$  stands for the set

$$\{[V] - [W] \in A \mid V^L = 0 \text{ and } W^L = 0 \text{ for all } L \in \mathcal{L}(G)\}.$$

We say that two real G-modules V and W are  $\mathcal{P}$ -matched if  $\operatorname{res}_P^G V$  and  $\operatorname{res}_P^G W$  are isomorphic for all  $P \in \mathcal{P}(G)$ .

**Theorem 1.5.** Let G be an Oliver group. Let  $V_1, \ldots, V_m$  be  $\mathcal{L}$ -free real G-modules satisfying the weak gap condition on  $\mathcal{PH}_2(G)$ , of which arbitrary two are  $\mathcal{P}$ -matched. Then there exists an integer N such that for any integer  $\ell \geq N$ , there exists a smooth G-action on the standard sphere S with exactly m G-fixed points  $x_1, \ldots, x_m$ for which the tangential representation  $T_{x_i}(S)$  is isomorphic to  $V_i \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$ ,  $1 \leq i \leq m$ .

In the case m = 2, we obtain the next theorem on Smith equivalence.

**Theorem 1.6.** Let G be an Oliver group and let V and W be  $\mathcal{P}$ -matched and  $\mathcal{L}$ -free real G-modules both satisfying the weak gap condition on  $\mathcal{PH}_2(G)$ . Then there exists an integer N such that for any integer  $\ell \geq N$  there exists a smooth G-action on the standard sphere S with exactly two G-fixed points  $x_1$  and  $x_2$  for which the tangential representations  $T_{x_1}(S)$  and  $T_{x_2}(S)$  are isomorphic to  $V \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$  and  $W \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$ , respectively. In particular, V and W are stably Smith equivalent.

Let X be a G-manifold and S a smooth G-action on the standard sphere with exactly one G-fixed point a and  $T_a(S) \cong \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$ . Then the cartesian product  $Y = X \times S$  has the diagonal G-action and the G-fixed point set of Y is  $X^G \times \{a\}$ . For each  $x \in X^G$ , the tangential representation  $T_{(x,a)}(Y)$  is isomorphic to  $T_x(X) \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$ . The next theorem follows from Theorems 1.3 and 1.6.

**Theorem 1.7.** Let G be an Oliver group and  $(V_i, W_i)$  a pair of  $\mathcal{L}$ -free  $\mathcal{P}$ -matched real G-modules  $V_i$  and  $W_i$  for each  $1 \leq i \leq m$ . Suppose all  $V_i$  and  $W_i$ ,  $1 \leq i \leq m$ , satisfy the weak gap condition on  $\mathcal{PH}_2(G)$ . Let X be a G-manifold with G-fixed point set

$$X^G = \{x_1\} \amalg \cdots \amalg \{x_m\} \amalg F \quad (disjoint \ union)$$

such that for each  $1 \leq i \leq m$ , the tangential representation  $T_{x_i}(X)$  is isomorphic to  $V_i$ , where F is a union of connected components of  $X^G$ . Then there exists an integer N such that for any integer  $\ell \geq N$  there exists a G-manifold Y with G-fixed point set  $X^G$  for which the underlying space is diffeomorphic to  $X \times S(\mathbb{R} \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell})$ and the tangential representation  $T_{x_i}(Y)$  is isomorphic to  $W_i \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$  for each  $1 \leq i \leq m$ .

A finite group G is called a gap group if each element x of  $\operatorname{RO}(G)_{\mathcal{P}}^{\mathcal{L}}$  can be written in the form x = [V] - [W] with  $\mathcal{L}$ -free real G-modules V and W satisfying the gap condition on  $\mathcal{PH}(G)$ . We remark that G with  $\mathcal{L}(G) \cap \mathcal{P}(G) = \emptyset$  is a gap group if and only if there exists an  $\mathcal{L}$ -free real G-module V satisfying the gap condition on  $\mathcal{PH}_2(G)$ . An Oliver group G is a gap group if G is nilpotent, or  $G = G^{\{2\}}$ , or  $G \neq G^{\{p\}}$  for at least two odd primes p. In the case where G is a gap Oliver group, we could determine the geometrically defined set  $\operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}$ in algebraic terms:  $\operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}$  coincides with  $\operatorname{RO}(G)_{\mathcal{P}}^{\mathcal{L}}$  (cf. [17, p. 850, Realization Theorem]). But it is difficult to determine  $\operatorname{Sm}(G)$  or even  $\operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}$  when G is not a gap group. Let us call a finite group G a weak gap group if each element x of  $\operatorname{RO}(G)_{\mathcal{P}}^{\mathcal{L}}$  can be written in the form x = [V] - [W] with  $\mathcal{L}$ -free real G-modules V and W satisfying the weak gap condition on  $\mathcal{PH}(G)$ . For example,  $G = S_5 \times C_2 \times \cdots \times C_2$ is not a gap group but a weak gap group (cf. [4]), where  $S_5$  is the symmetric group on five letters and  $C_2$  is a group of order 2. Since  $\operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}} \subset \operatorname{RO}(G)_{\mathcal{P}}^{\mathcal{L}}$ , we obtain the next result.

**Theorem 1.8.** If G is a weak gap Oliver group then  $\operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}$  coincides with  $\operatorname{RO}(G)_{\mathcal{P}}^{\mathcal{L}}$ .

Let H be a subgroup of G. For a real H-module V, we denote by  $\operatorname{ind}_{H}^{G} V$  the real G-module  $\mathbb{R}[G] \otimes_{\mathbb{R}[H]} V$ . If V satisfies the weak gap condition on  $\mathcal{PH}(H)$  then  $\operatorname{ind}_{H}^{G} V$  satisfies the weak gap condition on  $\mathcal{PH}(G)$ ; if V is  $\mathcal{L}$ -free then  $\operatorname{ind}_{H}^{G} V$ is also  $\mathcal{L}$ -free; and if V and W are  $\mathcal{P}$ -matched real H-modules then  $\operatorname{ind}_{H}^{G} V$  and  $\operatorname{ind}_{H}^{G} W$  are  $\mathcal{P}$ -matched real G-modules. Let  $\operatorname{ind}_{H}^{G}$  denote the induction homomorphism  $\operatorname{RO}(H) \to \operatorname{RO}(G)$ . Then the inclusion  $\operatorname{ind}_{H}^{G}(\operatorname{RO}(H)_{\mathcal{P}}^{\mathcal{L}}) \subset \operatorname{RO}(G)_{\mathcal{P}}^{\mathcal{L}}$  holds. Thus we obtain the next result from Theorem 1.6.

**Theorem 1.9.** Let H be a subgroup of an Oliver group G.

- (1.9.1) If V and W are  $\mathcal{L}$ -free  $\mathcal{P}$ -matched real H-modules satisfying the weak gap condition on  $\mathcal{PH}_2(H)$  then  $[\operatorname{ind}_H^G V] [\operatorname{ind}_H^G W]$  belongs to  $\operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}$ .
- (1.9.2) If H is a weak gap group then

$$\operatorname{ind}_{H}^{G}(\operatorname{Sm}(H)_{\mathcal{P}}^{\mathcal{L}}) \subset \operatorname{ind}_{H}^{G}(\operatorname{RO}(H)_{\mathcal{P}}^{\mathcal{L}}) \subset \operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}.$$

Let  $\mathcal{H}(G)$  denote the set of all subgroups H of G for which there exists  $P \in \mathcal{P}(G)$  such that  $P \leq H$  and  $|H:P| \leq 2$ . For a subset  $A \subset \operatorname{RO}(G)$ , we define  $A_{\mathcal{H}}$  to be the set of all elements  $x \in A$  such that  $\operatorname{res}_{H}^{G} x = 0$  for all  $H \in \mathcal{H}(G)$ . It is obvious that  $A_{\mathcal{H}}^{\mathcal{L}} \subset \operatorname{RO}(G)_{\mathcal{P}}^{\mathcal{L}}$ .

**Theorem 1.10.** If H is a subgroup of an Oliver group G then

$$\operatorname{ind}_{H}^{G}(\operatorname{RO}(H)_{\mathcal{H}}^{\mathcal{L}}) \subset \operatorname{Sm}(G)_{\mathcal{H}}^{\mathcal{L}} \subset \operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}$$

This paper is organized as follows. Section 2 is devoted to preparation of basic terms and notation concerning G-manifolds and G-framed maps. In Section 3, we discuss equivariant surgery to obtain homology equivalences on even-dimensional manifolds satisfying the weak gap condition. Theorem 3.5 describes a surgery obstruction to  $\mathbb{Z}_{(p)}$ -homology equivalence in algebraic terms. Section 4 is devoted to the induction theory of equivariant surgery obstruction groups. In Section 5 we prove Theorem 5.1 which provides a method of deleting or inserting fixed point manifolds. Theorems 1.3–1.5 and 1.10 are proved in Section 6.

#### §2. Preliminaries

For families  $\mathcal{A}, \mathcal{B}$  of sets closed under intersection, and a map  $f : \mathcal{A} \to \mathcal{B}$ , we say that f preserves intersection or is intersection preserving if

$$f(A_1 \cap A_2) = f(A_1) \cap f(A_2) \quad \text{for all } A_1, A_2 \in \mathcal{A}.$$

Let  $\Theta$  be a *G*-set,  $\rho : \Theta \to S(G)$  a *G*-map, where *G* acts on S(G) by conjugation, and *S* a conjugation invariant subset of *G* consisting of elements of order 2. The group *G* acts on *S* by conjugation. The set  $\Theta$  is called  $(\rho, S)$ -simple if for each  $t \in \Theta$ , the set  $\rho(t)$  contains at most one element in *S*.

**Definition 2.1.** For a  $(\rho, S)$ -simple *G*-set  $\Theta$ , we define the *S*-contraction  $(\Theta/S, \rho/S)$  of  $(\Theta, \rho)$  as follows. Let  $\sim_S$  denote the equivalence relation on  $\Theta$  such that  $t \sim_S t'$  if and only if  $\rho(t) \cap S = \rho(t') \cap S$ . Denote by  $\Theta/S$  the set of equivalence classes with respect to  $\sim_S$ . The map  $\rho/S : \Theta/S \to \mathcal{S}(G)$  is defined by

$$\rho/S([t]) = \{e\} \cup (\rho(t) \cap S)$$

for the  $\sim_S$ -equivalence class [t] of  $t \in \Theta$ . Then  $\Theta/S$  has a canonical *G*-action and  $\rho/S: \Theta/S \to \mathcal{S}(G)$  is a *G*-map.

A G-map  $\rho : \Theta \to \mathcal{S}(G)$  is called *S*-injective (resp. *S*-bijective) if for each  $s \in S$ , there exists at most one (resp. exactly one) element  $t \in \Theta$  such that  $\rho(t)$  contains s.

Let  $\mathfrak{P}(\Theta)$  denote the set of all subsets of  $\Theta$ . Clearly  $\mathfrak{P}(\Theta)$  has the induced G-action. A G-map  $f : \mathcal{S}(G) \to \mathfrak{P}(\Theta)$  is called  $\rho$ -compatible if  $\rho(f(H)) \subset \mathcal{S}(H)$  for all  $H \in \mathcal{S}(G)$ . A G-map  $f : \mathcal{S}(G) \to \mathfrak{P}(\Theta)$  is called  $(\rho, S)$ -saturated if

(2.1)  $f(H) \supset \{t \in \Theta \mid \rho(t) \cap S \cap H \neq \emptyset\} \text{ for all } H \in \mathcal{S}(G).$ 

It is straightforward to verify the next lemma.

**Lemma 2.2.** Let  $f : S(G) \to \mathfrak{P}(\Theta)$  be an intersection preserving  $\rho$ -compatible *G*-map and set  $\Theta_H = f(H)$  and  $\rho_H = \rho|_{\Theta_H} : \Theta_H \to S(H)$ .

- (2.2.1) If  $\Theta$  is  $(\rho, S)$ -simple, then  $\Theta_H$  is  $(\rho_H, S \cap H)$ -simple for  $H \in \mathcal{S}(G)$  and the associated map  $\rho/S : \Theta/S \to \mathcal{S}(G)$  is S-injective.
- (2.2.2) If  $\rho: \Theta \to \mathcal{S}(G)$  is S-injective then  $\rho_H: \Theta_H \to \mathcal{S}(H)$  is  $(S \cap H)$ -injective for  $H \in \mathcal{S}(G)$ .
- (2.2.3) If  $\rho : \Theta \to \mathcal{S}(G)$  is S-bijective and  $f : \mathcal{S}(G) \to \mathfrak{P}(\Theta)$  is  $(\rho, S)$ -saturated then  $\rho_H : \Theta_H \to \mathcal{S}(H)$  is  $(S \cap H)$ -bijective for  $H \in \mathcal{S}(G)$ .

Let X be a compact, connected G-manifold, possibly with boundary  $\partial X$ . The singular set  $X_{sing}$  of X is defined by

$$X_{\text{sing}} = \bigcup_{g \in G \smallsetminus \{e\}} X^g.$$

We say that X satisfies the weak gap condition if

(2.2) 
$$\dim X_{\rm sing} \le \frac{1}{2} \dim X.$$

In the case where X has even dimension 2k and satisfies the weak gap condition, we say that X satisfies the k-tame condition if

(2.3) 
$$\dim X^{K} \leq k - 2$$
whenever  $H < K \in \mathcal{S}(G)$ ,  $\dim X^{H} = k$ , and  $H = \bigcap_{x \in X^{H}} G_{x}$ ,

where  $G_x$  stands for the isotropy subgroup of G at the point x. Let G(2) denote the set of all elements of G of order 2. In the case where X has even dimension 2kand satisfies the weak gap condition, we say that X satisfies the G(2)-condition if

(2.4) 
$$|H| = 2$$
 whenever  $H \in \mathcal{S}(G)$  and  $2 \dim X^H = \dim X$ .

For a subgroup H and an integer  $\ell \geq 0$ , let  $\pi_0(X^H, \ell)$  denote the set of all connected components of dimension  $\ell$  of  $X^H$ . For  $\alpha \in \pi_0(X^H, \ell)$ , we denote by  $X_{\alpha}$  or  $X^H_{\alpha}$  the underlying space of  $\alpha$ . Each  $\alpha \in \pi_0(X^H, \ell)$  determines the group

$$\rho_X(\alpha) = \bigcap_{x \in X_\alpha} G_x.$$

**Definition 2.3.** Let X be a compact, connected G-manifold, possibly with boundary, satisfying the weak gap condition. Then we set

 $S(X) = \{ g \in G \mid 2 \dim X^g = \dim X \},\$   $Q(X) = \{ g \in G \mid \dim X^g = [(\dim X - 1)/2] \},\$  $\Sigma(X) = \{ \alpha \mid H \in \mathcal{S}(G), \ \alpha \in \pi_0(X^H, \dim X/2), \text{ and } \rho_X(\alpha) = H \},\$  М. Могімото

where for a real number x, [x] denotes the greatest integer not exceeding x. The  $(\dim X/2)$ -dimensional singular structure  $\mathfrak{S}(X)$  associated with X is defined to be the set of all  $X_s, s \in \Sigma(X)$ . For each  $s \in \Sigma(X)$ , the manifold  $X_s$  has the unique orientation class  $t_s$  in  $H_k(X_s, \partial X_s; \mathbb{Z}_2)$ . The G-set  $\Theta^{(2)}(X)$  is defined to be the set of all  $t_s$ , where s runs over  $\Sigma(X)$ . The correspondence  $s \mapsto t_s$  gives a bijection  $\Sigma(X) \to \Theta^{(2)}(X)$ . The map  $\rho_X^{(2)}: \Theta^{(2)}(X) \to \mathcal{S}(G)$  is defined by  $\rho_X^{(2)}(t_s) = \rho_X(s)$ for  $s \in \Sigma(X)$ .

The proof of the next lemma is straightforward.

**Lemma 2.4.** Let X be a G-manifold as in Definition 2.3. Suppose that X has even dimension n = 2k and satisfies the G(2)-condition. Then the following hold:

- $\begin{array}{ll} (2.4.1) \ \Theta^{(2)}(X) \ is \ (\rho_X^{(2)}, S(X)) \text{-simple.} \\ (2.4.2) \ \rho_X^{(2)}/S(X) : \Theta^{(2)}(X)/S(X) \to \mathcal{S}(G) \ is \ S(X) \text{-bijective.} \end{array}$
- (2.4.3) For  $H \in \mathcal{S}(G)$ ,  $S(\operatorname{res}_{H}^{G} X)$  coincides with  $S(X) \cap H$ . Thus the map  $H \mapsto$  $S(\operatorname{res}_{H}^{G} X)$  is intersection preserving.
- (2.4.4) For  $H \in \mathcal{S}(G)$ ,  $\Theta^{(2)}(\operatorname{res}_{H}^{G}X)$  coincides with  $\{t \in \Theta^{(2)}(X) \mid \rho_{X}^{(2)}(t) \subset H\}$ . Hence the map  $f : \mathcal{S}(G) \to \mathfrak{P}(\Theta^{(2)}(X)); H \mapsto \Theta^{(2)}(\operatorname{res}_{H}^{G}X)$ , is intersection preserving,  $\rho_{X}^{(2)}$ -compatible, and  $(\rho_{X}^{(2)}, S(X))$ -saturated, and furthermore  $f(G) = \Theta^{(2)}(X)$ .
- (2.4.5) The canonical map  $\gamma: \Theta^{(2)}(X) \to \Theta^{(2)}(X)/S(X)$  is a G-map, the diagram



commutes, and

$$\gamma(\Theta^{(2)}(X)) = \Theta^{(2)}(X) / S(X)$$

Let X be a compact, connected, oriented G-manifold of dimension  $n \ge 5$ , possibly with boundary  $\partial X$ . Let R be a commutative ring with 1 and with trivial anti-involution  $\overline{\cdot}$ . The group ring R[G] has the anti-involution  $\overline{\cdot}$  derived from the orientation homomorphism  $w_X : G \to \{\pm 1\}$  of X, i.e.

$$\left(\sum_{g\in G} r_g g\right)^- = \sum_{g\in G} r_g w_X(g) g^{-1},$$

where  $r_g \in R$ . Let  $\widetilde{X}$  denote the universal covering space of X. Let  $\widetilde{G}$  denote the fundamental group  $\pi_1(EG \times_G X)$ , where EG is a contractible G-CW complex with

a free G-action. We have the exact sequence

$$1 \to \pi_1(X) \to \widetilde{G} \to G \to 1.$$

If  $X^G$  is nonempty then this sequence splits, i.e.  $\widetilde{G} = \pi_1(X) \rtimes G$ .

Let Y be a compact, connected, oriented G-manifold of dimension n, possibly with boundary  $\partial Y$ . Let  $\mathbf{f} = (f, b)$  be a G-framed map, where  $f : (X, \partial X) \to (Y, \partial Y)$  is a G-map such that  $f : X \to Y$  is 1-connected, and  $b : T(X) \oplus f^* \eta \to f^* \xi$ is a real G-vector bundle isomorphism for real G-vector bundles  $\eta$  and  $\xi$  over Y such that  $\eta \supset \varepsilon_Y(\mathbb{R}^n)$  (cf. [2, Lemma 6.1]). Then  $\mathbf{f}$  is covered by the induced  $\widetilde{G}$ -framed map  $\widetilde{\mathbf{f}} = (\widetilde{f}, \widetilde{b})$  consisting of a  $\widetilde{\varphi}$ -map  $\widetilde{f} : (\widetilde{X}, \partial \widetilde{X}) \to (\widetilde{Y}, \partial \widetilde{Y})$  and a real  $\widetilde{G}$ -vector bundle isomorphism  $\widetilde{b} : T(\widetilde{X}) \oplus \widetilde{f}^* \widetilde{\eta} \to \widetilde{f}^* \widetilde{\xi}$ , where  $\widetilde{Y}$  is the universal covering space of Y,  $\widetilde{\varphi}$  is the canonical homomorphism  $\widetilde{G} = \pi_1(EG \times_G X) \to \pi_1(EG \times_G Y) = \widehat{G}$ , and  $\widetilde{\eta}$  and  $\widetilde{\xi}$  are the real  $\widehat{G}$ -vector bundles over  $\widetilde{Y}$  induced from  $\eta$  and  $\xi$ , respectively:

$$\begin{array}{c|c} \widetilde{X} & \xrightarrow{\widetilde{f}} \widetilde{Y} \\ \pi_{\widetilde{X},X} & & & & \\ & & & & \\ & & & & \\ X & \xrightarrow{f} & Y \end{array}$$

We note that the map  $\widetilde{f}: (\widetilde{X}, \partial \widetilde{X}) \to (\widetilde{Y}, \partial \widetilde{Y})$  is not necessarily of degree one.

# §3. G-surgery maps on even-dimensional manifolds

Let X be a compact, connected, oriented G-manifold of even dimension  $n = 2k \ge 6$ , possibly with boundary  $\partial X$ . Throughout this section, we assume that X satisfies the weak gap condition and the k-tame condition. Let R be a commutative ring with 1 and with trivial anti-involution  $\overline{\cdot}$ . We set  $\lambda = (-1)^k$ , S = S(X) and Q = Q(X); further define

$$(Q)_R = R[Q] + \{x - \lambda \overline{x} \mid x \in R[G]\}, \quad (S)_R = R[S] + \{x + \lambda \overline{x} \mid x \in R[G]\}.$$

Then

$$\boldsymbol{A}_X = (R[G], (\bar{\cdot}, \lambda), (S)_R, G, R[S], (Q)_R + R[S])$$

is a double parameter algebra in the sense of [2, Definition 2.5].

Let  $\mathfrak{S} = \{X_s \mid s \in \Sigma\}$  be a set of compact connected k-dimensional neat submanifolds of X, where  $\Sigma$  is a G-set, such that  $gX_s = X_{gs}$  for all  $g \in G$  and  $s \in \Sigma$ . Set

$$X_{\mathfrak{S}} = \bigcup_{s \in \Sigma} X_s.$$

In this paper, we assume that  $\mathfrak{S}$  satisfies the *k*-tame condition, i.e.

(3.1) 
$$X_s \cap X_t$$
 is a neat submanifold of  $X_s$  of dimension  $\leq k-2$ 

for all  $s, t \in \Sigma$ ,  $s \neq t$ . If  $\mathfrak{S} \supset \mathfrak{S}(X)$  then we call  $\mathfrak{S}$  a k-singular structure of X. The index set  $\Sigma$  decomposes into the disjoint union of  $\Sigma_+$  and  $\Sigma_-$  consisting of all elements  $s \in \Sigma$  such that  $X_s$  is orientable and non-orientable, respectively. Let  $\Theta^{(0)}(\mathfrak{S})$  denote the set of all generators of  $H_k(X_s, \partial X_s; \mathbb{Z})$ , where s runs over  $\Sigma_+$ , and let  $\Theta^{(2)}(\mathfrak{S})$  denote the set of all generators of  $H_k(X_s, \partial X_s; \mathbb{Z}_2)$ , where s runs over  $\Sigma$ . The sets  $\Theta^{(0)}(\mathfrak{S})$  and  $\Theta^{(2)}(\mathfrak{S})$  have canonical actions of  $G \times \{\pm 1\}$  and G, respectively. In addition, there is a canonical map  $p_{\mathfrak{S}} : \Theta^{(0)}(\mathfrak{S}) \to \Theta^{(2)}(\mathfrak{S})$ ; for a generator x of  $H_k(X_s, X_s; \mathbb{Z})$ ,  $p_{\mathfrak{S}}(x)$  is the generator of  $H_k(X_s, X_s; \mathbb{Z}_2)$ . We have a natural one-to-one correspondence from  $\Sigma$  to  $\Theta^{(2)}(\mathfrak{S})$ . Thus we often identify  $\Theta^{(2)}(\mathfrak{S})$  with  $\Sigma$  as G-sets. On the other hand, we may not have a  $(G \times \{\pm 1\})$ bijection from  $\Theta^{(0)}(\mathfrak{S})$  to  $\Sigma_+ \times \{\pm 1\}$ , although there is a non-equivariant bijection between these sets. Let  $\rho_{\mathfrak{S}}$  denote the map  $\Theta^{(2)}(\mathfrak{S}) = \Sigma \to \mathcal{S}(G)$  defined by

$$\rho_{\mathfrak{S}}(s) = \bigcap_{x \in X_s} G_x \quad (s \in \Sigma)$$

Let  $\Theta(\mathfrak{S})$  denote the datum

$$(\Theta^{(0)}(\mathfrak{S}), \Theta^{(2)}(\mathfrak{S}), p_{\mathfrak{S}}, \rho_{\mathfrak{S}}).$$

 $\operatorname{Set}$ 

$$\begin{split} \widetilde{Q} &= Q_{\widetilde{X}} \ (= \{g \in \widetilde{G}(2) \mid \dim \widetilde{X}^g = k - 1\}), \\ \widetilde{S} &= S_{\widetilde{X}} \ (= \{g \in \widetilde{G}(2) \mid \dim \widetilde{X}^g = k\}), \\ (\widetilde{Q})_R &= R[\widetilde{Q}] + \{x - \lambda \overline{x} \mid x \in R[\widetilde{G}]\}, \quad (\widetilde{S})_R = R[\widetilde{S}] + \{x + \lambda \overline{x} \mid x \in R[\widetilde{G}]\}. \end{split}$$

Then

$$\widetilde{\boldsymbol{A}} = \boldsymbol{A}_{\widetilde{X}} = (R[\widetilde{G}], (\bar{\cdot}, \lambda), (\widetilde{S})_R, \widetilde{G}, R[\widetilde{S}], (\widetilde{Q})_R + R[\widetilde{S}])$$

is a double parameter algebra.

Let  $\mathfrak{S}=\{X_s\mid s\in\Sigma\}$  be a k-singular structure of X as above. Consider the set

$$\widetilde{\mathfrak{S}} = \{ \widetilde{X}_t \mid t \in \widetilde{\Sigma} \}$$

of all connected components  $\widetilde{X}_t$  of  $\pi_{\widetilde{X},X}^{-1}(X_s)$ ,  $s \in \Sigma$ , where  $\pi_{\widetilde{X},X}$  is the canonical projection  $\widetilde{X} \to X$ . Here we have canonical surjections  $\widetilde{\mathfrak{S}} \to \mathfrak{S}$  and  $\widetilde{\Sigma} \to \Sigma$ . We call  $\widetilde{\mathfrak{S}}$  the *k*-singular structure of  $\widetilde{X}$  induced from  $\mathfrak{S}$ . Note that  $\widetilde{X}$  and  $\widetilde{X}_t$ are possibly non-compact. The index set  $\widetilde{\Sigma}$  decomposes into the disjoint union of  $\widetilde{\Sigma}_+$  and  $\widetilde{\Sigma}_-$  consisting of all elements  $t \in \widetilde{\Sigma}$  such that  $\widetilde{X}_t$  is orientable and non-orientable, respectively. Let  $\Theta^{(0)}(\widetilde{\mathfrak{S}})$  denote the set of all generators of  $H_k^{\text{loc.fin.}}(\widetilde{X}_t, \partial \widetilde{X}_t; \mathbb{Z})$ , where t runs over  $\widetilde{\Sigma}_+$ , and let  $\Theta^{(2)}(\widetilde{\mathfrak{S}})$  denote the set of all generators of  $H_k^{\text{loc.fin.}}(\widetilde{X}_t, \partial \widetilde{X}_t; \mathbb{Z}_2)$ , where t runs over  $\widetilde{\Sigma}$ . The sets  $\Theta^{(0)}(\widetilde{\mathfrak{S}})$  and  $\Theta^{(2)}(\widetilde{\mathfrak{S}})$  have canonical actions of  $\widetilde{G} \times \{\pm 1\}$  and  $\widetilde{G}$ , respectively. In addition, we have the canonical map  $p_{\widetilde{\mathfrak{S}}}: \Theta^{(0)}(\widetilde{\mathfrak{S}}) \to \Theta^{(2)}(\widetilde{\mathfrak{S}})$ . Define the map

$$\rho_{\widetilde{\mathfrak{S}}}: \Theta^{(2)}(\widetilde{\mathfrak{S}}) = \widetilde{\mathfrak{S}} = \widetilde{\Sigma} \to \mathcal{S}(\widetilde{G}) \quad \text{by} \quad \rho_{\widetilde{\mathfrak{S}}}(t) = \bigcap_{x \in \widetilde{X}_t} \ \widetilde{G}_x$$

Let  $\Theta(\widetilde{\mathfrak{S}})$  denote the datum

$$(\Theta^{(0)}(\widetilde{\mathfrak{S}}), \Theta^{(2)}(\widetilde{\mathfrak{S}}), p_{\widetilde{\mathfrak{S}}}, \rho_{\widetilde{\mathfrak{S}}}).$$

The next lemma is well-known.

**Lemma 3.1.** Let  $\mathbf{f} = (f, b)$  be a *G*-framed map and  $\mathfrak{S}$  a *k*-singular structure of *X* as above. Suppose the map  $f : (X, \partial X) \to (Y, \partial Y)$  has degree one. Then  $\mathbf{f}$  can be converted to a *G*-framed map  $\mathbf{f}' = (f', b')$ , where  $f' : (X', \partial X') \to (Y, \partial Y)$  and  $b' : T(X') \oplus f'^*\eta \to f'^*\xi$ , such that  $f' : X' \to Y$  is *k*-connected, by a *G*-surgery on *X* relative to  $X_{sing} \cup X_{\mathfrak{S}} \cup \partial X$ .

First, note that the degree of the resulting map  $f': (X', \partial X') \to (Y, \partial Y)$ above is 1. Second, note that if  $f: X \to Y$  is k-connected then the mapping cylinder  $M_{\tilde{f}}$  of  $\tilde{f}: \tilde{X} \to \tilde{Y}$  is the universal covering space of the mapping cylinder  $M_f$  of  $f: X \to Y$ , the group  $\pi_{k+1}(\tilde{f})$  can be identified with  $\pi_{k+1}(f)$ , and the canonical homomorphism  $\pi_{k+1}(\tilde{f}) \to K_k(\tilde{f}; \mathbb{Z})$  is an isomorphism, where  $\pi_{k+1}(\tilde{f}) = \pi_{k+1}(M_{\tilde{f}}, \tilde{X})$  and

$$K_k(\widetilde{f};\mathbb{Z}) = \operatorname{Ker}[\widetilde{f}_* : H_k(\widetilde{X};\mathbb{Z}) \to H_k(\widetilde{Y};\mathbb{Z})].$$

Now let R be  $\mathbb{Z}$  or  $\mathbb{Z}_{(p)}$  for a prime p. We denote by  $\mathcal{P}_p(G)$  the set of all subgroups of G with p-power order. Thus we have

$$\mathcal{P}(G) = \bigcup_{p \text{ prime}} \mathcal{P}_p(G)$$

Let  $\mathbf{f} = (f, b), f: (X, \partial X) \to (Y, \partial Y)$  be a *G*-framed map and  $\mathfrak{S}$  a *k*-singular structure of X as above. Then let  $\tilde{\mathbf{f}} = (\tilde{f}, \tilde{b}), \tilde{f}: (\tilde{X}, \partial \tilde{X}) \to (\tilde{Y}, \partial \tilde{Y})$ , denote the  $\tilde{G}$ -framed map induced from  $\mathbf{f}$ , where  $\tilde{X}$  and  $\tilde{Y}$  are the universal covering spaces of X and Y, respectively. Let  $\mathfrak{S}$  denote the induced *k*-singular structure of  $\tilde{X}$ .

**Definition 3.2.** Let f be the *G*-framed map above. We define the  $R[\widetilde{G}]$ -module  $M(\widetilde{f}; R)$  by

$$M(\widetilde{f};R) = \pi_{k+1}(\widetilde{f}) \otimes R.$$

We call f a (G, R)-surgery map if the following conditions are fulfilled:

- (3.2.1)  $f: X \to Y$  is of degree one.
- (3.2.2)  $f: X \to Y$  is 1-connected.
- (3.2.3)  $f_*: H_j(X; R) \to H_j(Y; R), j < k$ , are all isomorphisms, and  $f_*: H_k(X; R) \to H_k(Y; R)$  is surjective.
- (3.2.4)  $\partial f_*: H_j(\partial X; R) \to H_j(\partial Y; R), j \le n-1$ , are all isomorphisms.
- (3.2.5)  $f: X \to Y$  is k-connected, or the canonical map  $M(\tilde{f}; R) \otimes_{R[\tilde{G}]} R[G] \to K_k(f; R)$  is an isomorphism, where

$$K_k(f;R) = \operatorname{Ker}[f_*: H_k(X;R) \to H_k(Y;R)].$$

- (3.2.6) In the case  $R = \mathbb{Z}, f^P : X^P \to Y^P$  are  $\mathbb{Z}_q$ -homology equivalences for all subgroups  $P \in \mathcal{P}(G)$  with  $P \neq \{e\}$ , and primes q dividing |P|. In the case  $R = \mathbb{Z}_{(p)}, f^P : X^P \to Y^P$  are  $\mathbb{Z}_p$ -homology equivalences for all  $P \in \mathcal{P}_p(G)$  with  $P \neq \{e\}$ .
- (3.2.7)  $\chi(X^g) = \chi(Y^g)$  for all  $g \in G, g \neq e$ .

We have the Poincaré pairing

$$H_k^{\text{loc.fin.}}(\widetilde{X}, \partial \widetilde{X}; \mathbb{Z}) \times H_k(\widetilde{X}; \mathbb{Z}) \to \mathbb{Z}.$$

Passing along the canonical homomorphisms

$$\pi_{k+1}(\widetilde{f}) \to H_{k+1}(M_{\widetilde{f}}, \widetilde{X}; \mathbb{Z}) \to K_k(\widetilde{f}; \mathbb{Z}) \subset H_k(\widetilde{X}; \mathbb{Z}) \to H_k^{\text{loc.fin.}}(\widetilde{X}, \partial \widetilde{X}; \mathbb{Z})$$

we obtain the intersection form  $\widetilde{B}_0: M(\widetilde{f}; R) \times M(\widetilde{f}; R) \to R$ , and hence the  $\widetilde{G}$ -equivariant intersection form

$$\widetilde{B}: M(\widetilde{f}; R) \times M(\widetilde{f}; R) \to R[\widetilde{G}]; \ \widetilde{B}(x, y) = \sum_{g \in \widetilde{G}} \widetilde{B}_0(x, g^{-1}y)g.$$

Let  $x \in \pi_{k+1}(\widetilde{f})$ . Then x is represented by a commutative diagram

By virtue of this diagram and the bundle isomorphism b, the induced bundle  $\alpha^*T(\widetilde{X})$  is stably trivial. Thus x is represented by an immersion  $\alpha: S^k \to \widetilde{X}$  with trivial normal bundle. Let g be an element in  $\widetilde{G}$  of order 2 satisfying dim  $\widetilde{X}^g \leq k-2$ . Then the regular homotopy classes of immersions  $S^k \to \widetilde{X}$  correspond in a one-to-one way to the regular homotopy classes of immersions  $S^k \to \widetilde{X} \sim \widetilde{X}^g$ . Hence

Theorem 5.2 of [18] provides the  $\langle g \rangle$ -equivariant self-intersection form

$$\widetilde{q}_{\langle g \rangle} : \pi_{k+1}(\widetilde{f}) \to \mathbb{Z}[\langle g \rangle] / \{a - \lambda \overline{a} \mid a \in \mathbb{Z}[\langle g \rangle]\}$$

Assembling the data of the  $\tilde{G}$ -equivariant intersection form  $\tilde{B}$  and the  $\langle g \rangle$ -equivariant self-intersection forms  $\tilde{q}_{\langle g \rangle}$  (cf. [2, Definition 4.11]), we obtain the  $\tilde{G}$ -equivariant self-intersection form

$$\widetilde{q}: M(\widetilde{f}; R) \to R[\widetilde{G}]/((Q_{\widetilde{X}})_R + R[S_{\widetilde{X}}]) \quad \text{ (cf. [2, p. 567, \ell. 3])}.$$

For a generator  $\alpha \in H_k^{\text{loc.fin.}}(\widetilde{X}_t, \partial \widetilde{X}_t; \mathbb{Z})$ , where  $t \in \widetilde{\Sigma}_+$ , we have the element

$$j_* \alpha \in H_k^{\text{loc.fin.}}(X, \partial X; \mathbb{Z}),$$

where  $j_* : H_k^{\text{loc.fin.}}(\widetilde{X}_t, \partial \widetilde{X}_t; \mathbb{Z}) \to H_k^{\text{loc.fin.}}(\widetilde{X}, \partial \widetilde{X}; \mathbb{Z})$  is the canonical homomorphism. Via the intersection paring (or the Poincaré pairing up to sign)

$$H_k^{\text{loc.fin.}}(\widetilde{X}, \partial \widetilde{X}; \mathbb{Z}) \times H_k(\widetilde{X}; \mathbb{Z}) \to \mathbb{Z}$$

and the canonical map  $M(\tilde{f};\mathbb{Z}) \to H_k(\tilde{X};\mathbb{Z}), j_*\alpha$  determines an element

$$\widetilde{\theta}^{(0)}(\alpha) \in M(\widetilde{f}; \mathbb{Z})^{\#}, \quad \text{where} \quad M(\widetilde{f}; \mathbb{Z})^{\#} = \text{Hom}_{\mathbb{Z}[\widetilde{G}]}(M(\widetilde{f}; \mathbb{Z}), \mathbb{Z}[\widetilde{G}]).$$

Thus we obtain the  $(\widetilde{G} \times \{\pm 1\})$ -map

$$\widetilde{\theta}^{(0)}: \Theta^{(0)}(\widetilde{\mathfrak{S}}) \to M(\widetilde{f}; R)^{\#}, \quad \text{where} \quad M(\widetilde{f}; R)^{\#} = \text{Hom}_{R[\widetilde{G}]}(M(\widetilde{f}; R), R[\widetilde{G}]).$$

Similarly we obtain the  $\tilde{G}$ -map

$$\widetilde{\Theta}^{(2)}: \Theta^{(2)}(\widetilde{\mathfrak{S}}) \to M(\widetilde{f}; R/2R)^{\#}$$

where

$$M(\widetilde{f}; R/2R)^{\#} = \operatorname{Hom}_{R/2R[\widetilde{G}]}(M(\widetilde{f}; R/2R), R/2R[\widetilde{G}]).$$

Putting all this together, we obtain the surgery module

$$\boldsymbol{M}_{\widetilde{\boldsymbol{f}},\widetilde{\mathfrak{S}}} = (M(\widetilde{f};R),\widetilde{B},\widetilde{q},\widetilde{\theta}^{(0)},\widetilde{\theta}^{(2)}).$$

By the hypothesis  $M(\widetilde{f};R)\otimes_{R[\widetilde{G}]}R[G]=K_k(f;R),$  we obtain the commutative diagram

$$\begin{array}{cccc} \Theta^{(0)}(\widetilde{\mathfrak{S}}) & \longrightarrow & H_k^{\mathrm{loc.fin.}}(\widetilde{X}, \partial \widetilde{X}; R) & \longrightarrow & M(\widetilde{f}; R)^{\#} \\ & & & & \downarrow & & \downarrow \\ \Theta^{(2)}(\widetilde{\mathfrak{S}}) & \longrightarrow & H_k^{\mathrm{loc.fin.}}(\widetilde{X}, \partial \widetilde{X}; R/2R) & \longrightarrow & M(\widetilde{f}; R/2R)^{\#} \\ & & & \downarrow & & \downarrow \\ \Theta^{(2)}(\mathfrak{S}) & \longrightarrow & K_k(f, \partial f; R/2R) & \longrightarrow & K(f; R/2R)^{\#} \end{array}$$

Moreover we note

$$K_k(f, \partial f; R) = K_k(f; R), \quad K_k(f, \partial f; R/2R) = K_k(f; R/2R),$$
  

$$K_k(f; R)^{\#} = K_k(f; R) \quad \text{and} \quad K_k(f; R/2R)^{\#} = K_k(f; R/2R).$$

Thus by the hypothesis  $M(\tilde{f}; R) \otimes_{R[\tilde{G}]} R[G] = K_k(f; R)$ , we obtain the surgery module

$$\boldsymbol{M}_{\boldsymbol{f},\mathfrak{S}} = \boldsymbol{M}_{\boldsymbol{\tilde{f}},\boldsymbol{\tilde{S}}} \otimes_{R[\boldsymbol{\tilde{G}}]} R[\boldsymbol{G}] = (K_k(f;R), B_f, q_{\boldsymbol{f}}, \theta^{(0)}, \theta^{(2)}),$$

where

$$B_f: K_k(f; R) \times K_k(f; R) \to R[G]$$

is the G-equivariant intersection form,

$$q_{\mathbf{f}}: K_k(f; R) \to R[G]/((Q)_R + R[S])$$

is the G-equivariant self-intersection form, and

$$\theta^{(0)} : \Theta^{(0)}(\mathfrak{S}) \to K_k(f; R)^{\#} = K_k(f; R), \theta^{(2)} : \Theta^{(2)}(\mathfrak{S}) \to K_k(f; R/2R)^{\#} = K_k(f; R/2R)$$

are positioning maps (cf. [2, §5, pp. 563–564]).

By similar arguments to [2, p. 575,  $\ell$ . 24 – p. 578,  $\ell$ . 2], we obtain the next lemma.

**Lemma 3.3.** Let  $\mathbf{f}$  be a (G, R)-surgery map and  $\mathfrak{S}$  a k-singular structure as above. If there exists an  $R[\tilde{G}]$ -submodule  $\tilde{L}$  of  $M(\tilde{f}; R)$  satisfying the conditions below then  $\mathbf{f}$  can be converted to a (G, R)-surgery map  $\mathbf{f}' = (f', b')$ , where f':  $(X', \partial X') \to (Y, \partial Y)$  and  $b': T(X') \oplus f'^*\eta \to f'^*\xi$ , such that  $f': X' \to Y$  is an R-homology equivalence via G-surgery on X relative to  $X_{sing} \cup X_{\mathfrak{S}} \cup \partial X$ .

- (3.3.1)  $\tilde{\theta}^{(0)}(\alpha)(\tilde{L}) = 0$  for all  $\alpha \in \Theta^{(0)}(\tilde{\mathfrak{S}})$  and  $\tilde{\theta}^{(2)}(\beta)(\tilde{L}) = 0$  for all  $\beta \in \Theta^{(2)}(\tilde{\mathfrak{S}})$ .
- $(\mathbf{3.3.2}) \ \widetilde{B}(\widetilde{L},\widetilde{L}) = 0.$
- (3.3.3)  $\tilde{q}(\tilde{L}) = 0.$
- (3.3.4) The canonical image L in  $K_k(f; R)$  of  $\tilde{L}$  is an R[G]-free direct summand of  $K_k(f; R)$  of half the rank, i.e.  $2 \cdot \operatorname{rank}_R L = \operatorname{rank}_R K_k(f; R)$ .

**Lemma 3.4.** Let p be a prime and  $R = \mathbb{Z}_{(p)}$ . Let  $\mathbf{f} = (f, b)$  be a (G, R)-surgery map and  $\mathfrak{S}$  a k-singular structure of X as above. Suppose the following.

(3.4.1)  $\pi_1(X)$  is finite and  $|\pi_1(X)|$  is prime to p.

(3.4.2) the canonical homomorphism  $\widetilde{G} \to G$  has a splitting, i.e.  $\widetilde{G} = \pi_1(X) \rtimes G$ .

(3.4.3)  $f: X \to Y$  is k-connected.

(3.4.4)  $\pi_{\widetilde{X}_X}(\widetilde{X}_t)$  are orientable for all  $t \in \widetilde{\Sigma}_+$ .

If the module

$$\boldsymbol{M}_{\boldsymbol{f},\mathfrak{S}} = (K_k(f;R), B_f, q_{\boldsymbol{f}}, \theta^{(0)}, \theta^{(2)})$$

has an R[G]-free Lagrangian L, then there exists a submodule  $\tilde{L}$  of M(f; R) satisfying the conditions (3.3.1)–(3.3.4).

Before proving this lemma, we give an important application of the two lemmas above. Let

$$W_n(\boldsymbol{A}_X, \boldsymbol{\Theta}(\mathfrak{S}))_{\text{free}}$$

denote the surgery obstruction group

$$W_n(R,G,Q_X,S_X,\boldsymbol{\Theta}(\mathfrak{S}))_{ ext{free}}$$

defined in [2, p. 545, Definition 3.33]. In the case  $R = \mathbb{Z}_{(p)}$ , a (G, R)-surgery map  $\boldsymbol{f}$  with k-singular structure  $\mathfrak{S}$  determines the module  $\boldsymbol{M}_{\boldsymbol{f},\mathfrak{S}}$  above, and further the element  $\sigma(\boldsymbol{f},\mathfrak{S})$  of  $W_n(\boldsymbol{A}_X, \boldsymbol{\Theta}(\mathfrak{S}))_{\text{free}}$  as the equivalence class of  $\boldsymbol{M}_{\boldsymbol{f},\mathfrak{S}}$ . By Lemmas 3.3, 3.4 and [18, Lemma 5.5], we obtain the next theorem.

**Theorem 3.5.** Let  $R = \mathbb{Z}_{(p)}$  for a prime p,  $\mathbf{f}$  a (G, R)-surgery map and  $\mathfrak{S}$  a k-singular structure satisfying the conditions (3.4.1)–(3.4.4). If  $\sigma(\mathbf{f}, \mathfrak{S}) = 0$  in  $W_n(\mathbf{A}_X, \Theta(\mathfrak{S}))_{\text{free}}$  then  $\mathbf{f}$  can be converted to  $\mathbf{f}' = (f', b')$  such that  $f' : X' \to Y$  is an R-homology equivalence via a G-surgery on X relative to  $X_{\text{sing}} \cup X_{\mathfrak{S}} \cup \partial X$ .

Proof of Lemma 3.4. Let L be an R[G]-free Lagrangian of  $M_{f,\mathfrak{S}}$ . Let  $\{x_1, \ldots, x_m\}$  be an R[G]-basis of L and  $\{y_1, \ldots, y_m\}$  be elements of  $K_k(f; R)$  such that

$$B_f(x_i, y_j) = \delta_{ij}$$

for  $1 \leq i, j \leq m$ . Thus  $\{x_1, \ldots, x_m, y_1, \ldots, y_m\}$  is an R[G]-basis of  $K_k(f; R)$ . Arbitrarily choose liftings  $\tilde{x}_1, \ldots, \tilde{x}_m, \tilde{y}_1, \ldots, \tilde{y}_m \in M(\tilde{f}; R)$  of  $x_1, \ldots, x_m, y_1, \ldots, y_m$ , respectively. Define a map  $\tau : K_k(f; R) \to M(\tilde{f}; R)$  by

$$\tau\left(\sum_{i}(a_{i}x_{i}+b_{i}y_{i})\right)=\frac{1}{|\pi_{1}(X)|}\sum_{i}\sum_{h\in\pi_{1}(X)}(ha_{i}\widetilde{x_{i}}+hb_{i}\widetilde{y_{i}}).$$

This map is an R[G]-splitting of the canonical map  $M(\tilde{f}; R) \to K_k(f; R)$ . Clearly,  $\pi_1(X)$  acts trivially on the image of  $\tau$ . Set

$$\tilde{L} = \tau(L).$$

That  $\widetilde{B}(\widetilde{L},\widetilde{L}) = 0$  and  $\widetilde{q}(\widetilde{L}) = 0$  follows from Steps 1 and 2 in the proof of [11, Theorem 2.6].

Thus it suffices to show that  $\tilde{\theta}^{(0)}(\alpha)(\tilde{L}) = 0$  for  $\alpha \in \Theta^{(0)}(\tilde{\mathfrak{S}})$ , and  $\tilde{\theta}^{(2)}(\beta)(\tilde{L}) = 0$  for  $\beta \in \Theta^{(2)}(\tilde{\mathfrak{S}})$ . Let  $\tilde{\varepsilon} : R[\tilde{G}] \to R$  and  $\varepsilon : R[G] \to R$  be the

homomorphisms of taking the coefficients of the identity elements of  $\widetilde{G}$  and G, respectively. For  $\alpha \in \Theta^{(0)}(\widetilde{\mathfrak{S}})$ , let  $[\alpha]$  denote the canonical image of  $\alpha$  in  $\Theta^{(0)}(\mathfrak{S})$ and let  $\pi_1(X)_{\alpha}$  denote the isotropy subgroup of the  $\pi_1(X)$ -action on  $\Theta^{(0)}(\widetilde{\mathfrak{S}})$  at the point  $\alpha$ . Then the canonical map  $M(\widetilde{f}; R) \to K_k(f; R)$  assigns  $m\theta^{(0)}([\alpha])$  to  $\widetilde{\theta}^{(0)}(\alpha)$  with  $m = |\pi_1(X)_{\alpha}|$ . Thus for  $x \in L$ , we get

$$\varepsilon(\theta^{(0)}([\alpha])(x)) = \sum_{h \in \pi_1(X)} \widetilde{\varepsilon} \left( \frac{1}{m} \widetilde{\theta}^{(0)}(\alpha)(h^{-1}\tau(x)) \right)$$
$$= \sum_{h \in \pi_1(X)} \widetilde{\varepsilon} \left( \frac{1}{m} \widetilde{\theta}^{(0)}(\alpha)(\tau(x)) \right)$$
$$= |\pi_1(X) : \pi_1(X)_{\alpha}| \widetilde{\varepsilon} \left( \widetilde{\theta}^{(0)}(\alpha)(\tau(x)) \right),$$

and hence

$$\widetilde{\varepsilon}\big(\widetilde{\theta}^{(0)}(\alpha)(\tau(x))\big) = \frac{|\pi_1(X)_\alpha|}{|\pi_1(X)|} \varepsilon\big(\theta^{(0)}([\alpha])(x)\big) = 0$$

Since

$$\widetilde{\theta}^{(0)}(\alpha)(\tau(x)) = \sum_{g \in \widetilde{G}} \widetilde{\varepsilon} \big( \widetilde{\theta}^{(0)}(\alpha)(\tau(g^{-1}x)) \big) g,$$

the triviality  $\theta^{(0)}([\alpha])(L) = 0$  implies  $\tilde{\theta}^{(0)}(\alpha)(\tau(x)) = 0$ .

We can similarly show that  $\tilde{\theta}^{(2)}(\beta)(\tau(x)) = 0$ .

# §4. The Mackey structure of surgery obstruction groups

In this section, let R be a principal ideal domain, hence necessarily a commutative ring, with 1 satisfying the square condition, i.e.

(4.1) 
$$r \equiv r^2 \mod 2R$$
 for each  $r \in R$ .

Let  $\Theta$  be a finite G-set,  $\rho : \Theta \to S(G)$  a G-map, and S a conjugation invariant subset of G(2). The map  $S(G) \to \mathfrak{P}(S)$ ;  $H \mapsto S_H = S \cap H$ , preserves intersection. Let  $SGW_0(R, G, S, \Theta)$  denote the special Grothendieck–Witt group defined in [10, p. 2358].

**Lemma 4.1** ([10, Proposition 5.4]). If  $\rho$  is S-injective then SGW<sub>0</sub>(R, G, S,  $\Theta$ ) is a commutative ring possibly without 1, and moreover the canonical map

$$\mathrm{SGW}_0(\mathbb{Z}, G, S, \Theta) \to \mathrm{SGW}_0(R, G, S, \Theta)$$

of ring change is a ring homomorphism. If  $\rho$  is S-bijective then SGW<sub>0</sub>(R, G, S,  $\Theta$ ) possesses the unit 1.

Let

$$f: \mathcal{S}(G) \to \mathfrak{P}(\Theta); \ H \mapsto \Theta_H,$$

be an intersection preserving  $\rho$ -compatible *G*-map and let  $w : G \to \{\pm 1\}$  be a homomorphism. We denote by  $w_H$  the restriction  $w|_H : H \to \{\pm 1\}$ .

**Definition 4.2** (cf. [10, p. 2357]). For a  $\Theta$ -positioning Hermitian form  $\boldsymbol{M} = (M, B, \theta)$ , where M is an R-free R[G]-module,  $B: M \times M \to R$  is a G-invariant (or w-invariant) symmetric bilinear form, and  $\theta: \Theta \to M$  is a G-map, and for  $s \in S, x \in M$ , we define the trace  $\Delta_{\theta}(s) \in M$  of  $(\theta, \rho)$  at s and the  $\nabla$ -invariant  $\nabla_{\boldsymbol{M}}(x)(s) \in R/2R$  of  $\boldsymbol{M}$  at (x, s) by

$$\Delta_{\boldsymbol{\theta}}(s) = \sum_{t \in \Theta} \{\boldsymbol{\theta}(t) \mid \boldsymbol{\rho}(t) \ni s\}, \quad \nabla_{\boldsymbol{M}}(x)(s) = [B(\Delta_{\boldsymbol{\theta}}(s) - x, sx)].$$

We remark that what we precisely need for the definition is  $B: M \times M \to R/2R$ rather than  $B: M \times M \to R$ .

**Lemma 4.3.** Let H and K be subgroups of G and let  $\varphi = (\varphi, \psi)$  be a pair consisting of a monomorphism  $\varphi : H \to K$  which is a composition of inclusion and conjugation and the associated injective  $\varphi$ -map  $\psi : \Theta_H \to \Theta_K$ . Let  $g_1, \ldots, g_m \in K$  be a complete set of representatives of  $K/\varphi(H)$ . Further let  $\mathbf{M} = (M, B, \alpha)$  be a positioning Hermitian module, where M is an R-free R[H]-module,  $B : M \times M \to R$  is an H-invariant (or  $w_H$ -invariant) symmetric bilinear form, and  $\alpha : \Theta_H \to M$  is an H-map. Then the  $\nabla$ -invariant of the induced module  $\mathbf{M}' = \varphi_{\#}M$  satisfies

$$\nabla_{\boldsymbol{M}'}(g_i \otimes_{\varphi} x)(s') = \begin{cases} \nabla_{\boldsymbol{M}}(x)(\varphi^{-1}(g_i^{-1}s'g_i)) & (g_i^{-1}s'g_i \in \varphi(H)), \\ 0 & (g_i^{-1}s'g_i \notin \varphi(H)), \end{cases}$$

for  $x \in M$  and  $s' \in S_K = S \cap K$ .

*Proof.* By definition,  $\mathbf{M}' = (M', B', \alpha')$  is given by  $M' = R[K] \otimes_{R[H], \varphi} M$ ,

$$B'(g_j \otimes_{\varphi} x, g_k \otimes_{\varphi} y) = \delta_{jk} B(x, y), \text{ and}$$
$$\alpha'(t') = \sum_{(i,t)} \{g_i \otimes \alpha(t) \mid t \in \Theta_H, g_i \psi(t) = t'\},$$

where  $x, y \in M, t' \in \Theta_K$ . Let  $s' \in S_K$ . We have

$$\nabla_{\boldsymbol{M}'}(g_i \otimes_{\varphi} x)(s') = B'(\Delta_{\alpha'}(s') - g_i \otimes_{\varphi} x, s'(g_i \otimes_{\varphi} x)).$$

Moreover the following equalities hold:

$$\begin{split} B'(\Delta_{\alpha'}(s'), s'(g_i \otimes_{\varphi} x)) &= B'(\Delta_{\alpha'}(s'), g_i \otimes_{\varphi} x) \\ &= \sum_{t' \in \Theta_K} \{B'(\psi_{\#}\alpha(t'), g_i \otimes_{\varphi} x) \mid \rho_K(t') \ni s'\} \\ &= \sum_{t' \in \Theta_K} \sum_{j,t} \{B'(g_j \otimes_{\varphi} \alpha(t), g_i \otimes_{\varphi} x) \mid t \in \Theta_H, g_j \psi(t) = t', g_j \varphi(\rho_H(t)) g_j^{-1} \ni s'\} \\ &= \sum_{t' \in \Theta_K} \sum_t \{B(\alpha(t), x) \mid t \in \Theta_H, g_i \psi(t) = t', g_i \varphi(\rho_H(t)) g_i^{-1} \ni s'\} \\ &= \sum_{t \in \Theta_H} \{B(\alpha(t), x) \mid \varphi(\rho_H(t)) \ni g_i^{-1} s' g_i\} \\ &= \sum_{t \in \Theta_H} \{B(\alpha(t), x) \mid \rho_H(t) \ni \varphi^{-1}(g_i^{-1} s' g_i)\}. \end{split}$$

On the other hand, we have

$$B'(g_i \otimes_{\varphi} x, s'(g_i \otimes_{\varphi} x)) = \begin{cases} B(x, \varphi^{-1}(g_i^{-1}s'g_i)x) & (g_i^{-1}s'g_i \in \varphi(H)), \\ 0 & (g_i^{-1}s'g_i \notin \varphi(H)). \end{cases}$$

Thus we obtain

$$\nabla_{\boldsymbol{M}'}(g_i \otimes_{\varphi} x)(s') = \begin{cases} \nabla_{\boldsymbol{M}}(x)(\varphi^{-1}(g_i^{-1}s'g_i)) & (g_i^{-1}s'g_i \in \varphi(H)), \\ 0 & (g_i^{-1}s'g_i \notin \varphi(H)). \end{cases}$$

**Lemma 4.4.** If  $f : S(G) \to \mathfrak{P}(\Theta)$  is  $(\rho, S)$ -saturated then the correspondence

$$H \mapsto \mathrm{SGW}_0(R, H, S_H, \Theta_H) \quad (H \in \mathcal{S}(G))$$

affords a Mackey functor.

*Proof.* This follows from the proof of [10, Proposition 11.2] with a modification using Lemma 4.3.

**Lemma 4.5** ([10, Theorem 11.3]). If  $\rho : \Theta \to S(G)$  is S-bijective and f is  $(\rho, S)$ -saturated then the correspondence

$$H \mapsto \mathrm{SGW}_0(R, H, S_H, \Theta_H) \quad (H \in \mathcal{S}(G))$$

affords a Green functor. Moreover, the canonical homomorphisms

$$\mathrm{SGW}_0(\mathbb{Z}, H, S_H, \Theta_H) \to \mathrm{SGW}_0(R, H, S_H, \Theta_H)$$

of ring change afford a natural transformation of Green functors.

Let  $w : G \to \{\pm 1\}$  be a homomorphism and let  $\overline{\cdot}$  denote the anti-involution on  $\mathbb{Z}[G]$  associated with w. Let  $\lambda = (-1)^k$ . Then  $(\overline{\cdot}, \lambda)$  is an anti-structure of  $\mathbb{Z}[G]$ . Let Q be a conjugation invariant subset of G(2). Suppose

$$S \subset G(2)^{\lambda} = \{g \in G(2) \mid g = \lambda \overline{g}\}, \quad Q \subset G(2)^{-\lambda} = \{g \in G(2) \mid g = -\lambda \overline{g}\}.$$

Then we obtain the double parameter algebra

$$\boldsymbol{A} = (R[G], (\bar{\cdot}, \lambda), (S)_R, G, R[S], (Q)_R + R[S])$$

in the sense of [2, Definition 2.5]. Let  $\Theta^{(0)}$  and  $\Theta^{(2)}$  be a finite  $(G \times \{\pm 1\})$ set and a finite *G*-set, respectively and let  $p_{\Theta^{(0)}} : \Theta^{(0)} \to \Theta^{(2)}$  be a *G*-map. Throughout this paper we assume that  $\{\pm 1\}$  acts freely on  $\Theta^{(0)}$  and  $p_{\Theta^{(0)}}^{-1}(p_{\Theta^{(0)}}(t))$ coincides with  $\{t, -t\}$  for all  $t \in \Theta^{(0)}$ . Let  $\rho_{\Theta^{(2)}} : \Theta^{(2)} \to \mathcal{S}(G)$  be a *G*-map and set  $\mathbf{\Theta} = (\Theta^{(0)}, \Theta^{(2)}, p_{\Theta^{(0)}}, \rho_{\Theta^{(2)}})$ . We use the notation

$$W_n(\boldsymbol{A},\boldsymbol{\Theta})_{\text{free}} = W_n(R,G,Q,S,\boldsymbol{\Theta})_{\text{free}}, \quad W_n(\boldsymbol{A},\boldsymbol{\Theta})_{\text{proj}} = W_n(R,G,Q,S,\boldsymbol{\Theta})_{\text{proj}},$$

where n = 2k, defined in [2, Definition 3.33].

Let  $\Theta$  be a finite G-set and  $\rho: \Theta \to \mathcal{S}(G)$  a G-map. Let  $\gamma: \Theta^{(2)} \to \Theta$  be a G-map such that the diagram

commutes and

(4.3) 
$$\gamma(\Theta^{(2)}) = \Theta.$$

**Lemma 4.6.** If  $\rho : \Theta \to S(G)$  is S-bijective then  $W_n(\mathbf{A}, \mathbf{\Theta})_{\text{free}}$  is a module over  $SGW_0(R, G, S, \Theta)$ .

Proof. Let  $\mathbf{M}_1 = (M_1, B_1, \alpha_1)$  be a  $\Theta$ -positioning, non-singular Hermitian R[G]module with trivial  $\nabla$ -invariant, where M is an R-free R[G]-module,  $B_1 : M_1 \times M_1$  $\rightarrow R$  and  $\alpha_1 : \Theta \rightarrow M$ . Let  $\mathbf{M}_2 = (M_2, B_2, q_2, \alpha^{(0)}, \alpha^{(2)})$  be an object in  $\nabla \mathcal{Q}(\mathbf{A}, \Theta)$ defined in [2, p. 535] such that  $M_2$  is a stably R[G]-free module, where  $B_2 :$  $M_2 \times M_2 \rightarrow R[G], q_2 : M_2 \rightarrow R[G]/((Q)_R + R[S]), \alpha^{(0)} : \Theta^{(0)} \rightarrow M_2$ , and  $\alpha^{(2)} : \Theta^{(2)} \rightarrow M_2/2M_2$ . Then we define

$$\boldsymbol{M} = \boldsymbol{M}_1 \cdot \boldsymbol{M}_2 = (M, B, q, \theta^{(0)}, \theta^{(2)}) \in \mathcal{Q}(\boldsymbol{A}, \boldsymbol{\Theta})$$

as follows. The triple (M, B, q) is described in [10, §9]. The map  $\theta^{(0)} : \Theta^{(0)} \to M = M_1 \otimes_R M_2$  is given by

$$\theta^{(0)}(t) = \alpha_1(\gamma(p_{\Theta^{(0)}}(t))) \otimes_R \alpha^{(0)}(t) \quad \text{for } t \in \Theta^{(0)},$$

and the map  $\theta^{(2)}: \Theta^{(2)} \to M/2M$  is given by

 $\theta^{(2)}(t) = \alpha_1(\gamma(t)) \otimes_B \alpha^{(2)}(t)$ 

for  $t \in \Theta^{(2)}$ . It is easy to verify the  $\nabla$ -triviality of  $\boldsymbol{M}$ , i.e.  $\boldsymbol{M} \in \nabla \mathcal{Q}(\boldsymbol{A}, \boldsymbol{\Theta})$ . The correspondence  $(\boldsymbol{M}_1, \boldsymbol{M}_2) \mapsto \boldsymbol{M}$  affords the module structure

$$\mathrm{SGW}_0(R, G, S, \Theta) \times W_n(\boldsymbol{A}, \boldsymbol{\Theta})_{\mathrm{free}} \mapsto W_n(\boldsymbol{A}, \boldsymbol{\Theta})_{\mathrm{free}}$$

In this section we set

$$Q_H = Q \cap H$$
 for  $H \in \mathcal{S}(G)$ .

Then the map  $\mathcal{S}(G) \to \mathfrak{P}(Q)$ ;  $H \mapsto Q_H$ , preserves intersection.

We regard  $\mathcal{S}(G)$  as a  $(G \times \{\pm 1\})$ -set, with the trivial  $\{\pm 1\}$ -action. Let  $f_{\Theta} = (f_{\Theta^{(0)}}, f_{\Theta^{(2)}})$  be a pair of an intersection preserving  $(G \times \{\pm 1\})$ -map  $f_{\Theta^{(0)}} : \mathcal{S}(G) \to \mathfrak{P}(\Theta^{(0)}); H \mapsto \Theta_{H}^{(0)}$ , and an intersection preserving  $\rho_{\Theta^{(2)}}$ -compatible *G*-map  $f_{\Theta^{(2)}} : \mathcal{S}(G) \to \mathfrak{P}(\Theta^{(2)}); H \mapsto \Theta_{H}^{(2)}$ , satisfying

$$p_{\Theta^{(0)}}(\Theta_H^{(0)}) \subset \Theta_H^{(2)}$$

for  $H \in \mathcal{S}(G)$ . Define  $p_{\Theta_{H}^{(0)}} : \Theta_{H}^{(0)} \to \Theta_{H}^{(2)}$  as the restriction of  $p_{\Theta^{(0)}}$ , and  $\rho_{\Theta_{H}^{(2)}} : \Theta_{H}^{(2)} \to \mathcal{S}(H)$  as the restriction of  $\rho_{\Theta^{(2)}}$ . Then we obtain the double parameter algebras

$$\boldsymbol{A}_{H} = (R[H], (\bar{\cdot}, \lambda), (S_{H})_{R}, H, R[S_{H}], (Q_{H})_{R} + R[S_{H}])_{R}$$

where  $S_H = S \cap H$ , and the positioning data

$$\boldsymbol{\Theta}_{H} = (\Theta_{H}^{(0)}, \Theta_{H}^{(2)}, p_{\Theta_{H}^{(0)}}, \rho_{\Theta_{H}^{(2)}}), \quad \text{where } H \in \mathcal{S}(G).$$

**Lemma 4.7.** If  $f_{\Theta^{(2)}} : \mathcal{S}(G) \to \mathfrak{P}(\Theta^{(2)})$  is  $(\rho_{\Theta^{(2)}}, S)$ -saturated then the correspondences

$$H \mapsto W_n(\boldsymbol{A}_H, \boldsymbol{\Theta}_H)_{\text{proj}} \quad (H \in \mathcal{S}(G))$$

and

$$H \mapsto W_n(\boldsymbol{A}_H, \boldsymbol{\Theta}_H)_{\text{free}} \quad (H \in \mathcal{S}(G))$$

afford Mackey functors, respectively.

*Proof.* Recalling [10, Proposition 10.3], we will prove the lemma by showing that

$$H \mapsto W_n(\boldsymbol{A}_H, \boldsymbol{\Theta}_H)_{\text{proj}}, W_n(\boldsymbol{A}_H, \boldsymbol{\Theta}_H)_{\text{free}} \quad (H \in \mathcal{S}(G))$$

are w-Mackey functors. Most of the proof is already given in the proof of Theorem 12.10 of [10]. It suffices to discuss the part concerning the  $(H \times \{\pm 1\})$ -sets  $\Theta_H^{(0)}$ , where  $H \in \mathcal{S}(G)$ .

Let H and K be subgroups of G. Given an injective homomorphism  $\varphi$ :  $H \to K$ , we have the canonical injective homomorphism  $\varphi_{\pm}$ :  $H \times \{\pm 1\} \to K \times \{\pm 1\}$  defined by  $\varphi_{\pm}(h, \epsilon) = (\varphi(h), \epsilon)$  for  $h \in H$  and  $\epsilon \in \{\pm 1\}$ . The sets  $\Theta_{H}^{(0)}$  and  $\Theta_{K}^{(0)}$  are an  $(H \times \{\pm 1\})$ -set and a  $(K \times \{\pm 1\})$ -set, respectively, on which the group  $\{\pm 1\}$  acts freely. Let  $\psi : \Theta_{H}^{(0)} \to \Theta_{K}^{(0)}$  be a  $\varphi_{\pm}$ -map, i.e.

$$\psi((h,\epsilon)t) = \varphi_{\pm}(h,\epsilon)\psi(t) \ (= (\varphi(h),\epsilon)\psi(t))$$

for  $h \in H$ ,  $\epsilon \in \{\pm 1\}$ , and  $t \in \Theta_H^{(0)}$ . Let  $\varphi$  denote the pair  $(\varphi, \psi)$ .

An R[K]-module N is usually regarded as an  $R[K \times \{\pm 1\}]$ -module via  $(k, \epsilon)x = \epsilon(kx)$  for  $k \in K$ ,  $\epsilon \in \{\pm 1\}$ , and  $x \in N$ . For a pair  $\mathbf{N} = (N, \beta)$  consisting of an R[K]-module N and a  $(K \times \{\pm\})$ -map  $\beta : \Theta_K^{(0)} \to N$ , we define  $\varphi^{\#} \mathbf{N} = (\varphi^{\#}N, \psi^{\#}\beta)$ , where  $\varphi^{\#}N$  is an R[H]-module and  $\psi^{\#}\beta : \Theta_H^{(0)} \to \varphi^{\#}N$ , so that the underlying R-module of  $\varphi^{\#}N$  is the same as N but the H-action on  $\varphi^{\#}N$  is given by  $(h, x) \mapsto \varphi(h)x$  for  $h \in H$  and  $x \in \varphi^{\#}N$ , and  $\psi^{\#}\beta(t) = \beta(\psi(t))$  for  $t \in \Theta_H^{(0)}$ .

For a pair  $\boldsymbol{M} = (M, \alpha)$  consisting of an R[H]-module M and an  $(H \times \{\pm 1\})$ map  $\alpha : \Theta_{H}^{(0)} \to M$ , we define  $\boldsymbol{\varphi}_{\#}\boldsymbol{M} = (\varphi_{\#}M, \psi_{\#}\alpha)$ , where  $\varphi_{\#}M$  is an R[K]module and  $\psi_{\#}\alpha : \Theta_{K}^{(0)} \to \varphi_{\#}M$ , by  $\varphi_{\#}M = R[K] \otimes_{R[H],\varphi} M$  and

$$\psi_{\#}\alpha(t) = \sum_{[g,t']} \{g \otimes \alpha(t') \mid [g,t'] \in K \times_{H,\varphi} \Theta_H^{(0)} \text{ such that } g\psi(t') = t\}$$

for  $t \in \Theta_K^{(0)}$ .

These  $\varphi^{\#}N$  and  $\varphi_{\#}M$  are simple analogies of those in [10, p. 2347]. Thus the conclusion of the lemma above follows from the same arguments used in the proof of Theorem 12.10 of [10].

Let  $\rho: \Theta \to \mathcal{S}(G)$  be a *G*-map and  $f: \mathcal{S}(G) \to \mathfrak{P}(\Theta); H \mapsto \Theta_H$ , an intersection preserving,  $\rho$ -compatible *G*-map such that  $f(G) = \Theta$ . Let  $\gamma: \Theta^{(2)} \to \Theta$  be a *G*-map such that the diagram (4.2) commutes and

(4.4) 
$$\gamma(\Theta_H^{(2)}) = \Theta_H \quad (H \in \mathcal{S}(G)).$$

**Lemma 4.8.** If  $\rho: \Theta \to \mathcal{S}(G)$  is S-bijective,  $f: \mathcal{S}(G) \to \mathfrak{P}(\Theta)$  is  $(\rho, S)$ -saturated and  $f_{\Theta^{(2)}}: \mathcal{S}(G) \to \mathfrak{P}(\Theta^{(2)})$  is  $(\rho^{(2)}, S)$ -saturated, then the correspondence

$$H \mapsto W_n(\boldsymbol{A}_H, \boldsymbol{\Theta}_H)_{\text{free}} \quad (H \in \mathcal{S}(G))$$

is a module over the Green functor

$$H \mapsto \mathrm{SGW}_0(R, H, S_H, \Theta_H) \quad (H \in \mathcal{S}(G)).$$

*Proof.* We can argue in the same way as in the proof of [10, Theorem 12.10] with a modification using Lemma 4.6.

# §5. A deleting-inserting theorem

Deleting (resp. inserting) *G*-fixed submanifolds from (resp. to) given ambient *G*manifolds is useful for the study of fixed point data of *G*-manifolds. For example, it has been applied to the study of the Smith problem on tangential representations at fixed points on spheres. In this section we prove Theorem 5.1 below. Let  $\mathcal{G}_p^1(G)$ denote the set of all subgroups *H* of *G* possessing normal subgroups  $P \trianglelefteq H$  such that *P* has *p*-power order and H/P is cyclic, where *P* is possibly the trivial group. An element *H* of  $\mathcal{G}_p^1(G)$  is called a *mod*- $\mathcal{P}_p$  cyclic group. We set

$$\mathcal{G}^1(G) = \bigcup_{p \text{ prime}} \mathcal{G}^1_p(G).$$

If H lies in  $\mathcal{G}^1(G)$  then H is referred to as a mod- $\mathcal{P}$  cyclic group.

**Theorem 5.1** (Deleting-inserting theorem). Let G be a finite Oliver group and Y a smooth G-manifold such that the underlying manifold of Y is diffeomorphic to the disk of dimension  $n \ge 5$  and  $Y^G \ne \emptyset$ . Let  $F_1, \ldots, F_t$  denote all the underlying spaces of connected components of  $Y^G$ , and let  $n_1, \ldots, n_t$  be non-negative integers. Suppose the following:

- (5.1.1) Y satisfies the weak gap condition on  $\mathcal{PH}(G)$ .
- (5.1.2) dim  $Y^{=H} \ge 3$  for any  $H \in \mathcal{G}^1(G)$ .
- (5.1.3) dim  $Y^P \ge 5$  for any  $P \in \mathcal{P}(G)$ .
- (5.1.4)  $\pi_1(Y^P)$  is finite and of order prime to |P| for any  $P \in \mathcal{P}(G)$ .
- (5.1.5) For  $1 \le i, j \le t$ ,  $n_i$  coincides with  $n_j$  if some connected component  $Y^H_{\alpha}$  of  $Y^H$ ,  $H \in \mathcal{L}(G)$ , contains both  $F_i$  and  $F_j$ .
- (5.1.6) For  $1 \leq i \leq t$ ,  $n_i$  is equal to 1 if some connected component  $Y^H_{\alpha}$  of  $Y^H$ ,  $H \in \mathcal{L}(G)$ , contains  $F_i$  and  $\partial Y^H_{\alpha} \neq \emptyset$ .
- (5.1.7) If dim  $Y^P = 2 \dim Y^H$  for  $(P, H) \in \mathcal{PH}(G)$  then  $(P, H) \in \mathcal{PH}_2(G)$  and  $\dim Y^{>H} < \dim Y^H 2$ .

Then there exists a smooth G-action on the disk D of dimension n such that

(i)  $\partial D$  is G-diffeomorphic to  $\partial Y$ ,

(ii)  $D^G$  has the form of the disjoint union of copies of  $F_i$ 's:

$$D^{G} = \prod_{i=1}^{t} \prod_{j=1}^{n_{i}} F_{i,j} \quad (each \ F_{i,j} \ is \ diffeomorphic \ to \ F_{i}), \ and$$

(iii) the normal bundle  $\nu(F_{i,j}, D)$  is G-isomorphic to  $\nu(F_i, Y)$ .

Furthermore if  $Y^H$  (resp.  $Y^P$ ) is connected (resp. simply connected) for an element  $H \in \mathcal{G}^1(G)$  (resp.  $P \in \mathcal{P}(G)$ ), then one can choose the G-action so that  $D^H$  (resp.  $D^P$ ) is connected (resp. simply connected) for the subgroup H (resp. P).

Proof. The procedure is the same as that of proving Theorem 1.3 of [11, §5]. Let  $\mathbf{f} = (f, b), f : (X, \partial X) \to (Y, \partial Y)$  and  $b : T(X) \oplus \varepsilon_X(\mathbb{R}^u) \to f^*T(Y) \oplus \varepsilon_X(\mathbb{R}^u)$ , be the degree-one *G*-framed map obtained in Section 4 of [11]. Note that for  $P \in \mathcal{P}(G), Y^P$  is orientable and the map  $f^P : (X^P, \partial X^P) \to (Y^P, \partial Y^P)$  has degree one.

The details of the proof differ in some points from the proof of Theorem 1.3 of [11, §5]. The differences occur in Steps A and B below.

- **Step A.** The step converting  $f^P : X^P \to Y^P$  to a mod p homology equivalence, where  $P \in \mathcal{P}(G)$  possesses  $H \in \mathcal{S}(G)$  such that  $2 \dim X^H = \dim X^P$  and p is the prime dividing |P|.
- **Step B.** The step converting  $f: X \to Y$  to a homotopy equivalence, when there is (at least one)  $H \in \mathcal{S}(G)$  such that  $2 \dim X^H = \dim X$ .

In these steps, the condition (5.1.7) is used to get rid of technical difficulties.

Step A. In this step, we set  $n_P = \dim X^P$ ,  $k_P = n_P/2$ ,  $\lambda = (-1)^{k_P}$ ,  $T = N_G(P)/P$ ,  $w = w_{X^P} : T \to \{\pm 1\}$ , and furthermore

$$\begin{split} R &= \mathbb{Z}_{(p)}, \\ S &= \{g \in T(2) \mid \dim(X^P)^g = k_P\} \ (= S(X^P)), \\ Q &= \{g \in T(2) \mid \dim(X^P)^g = k_P - 1\} \ (= Q(X^P)), \\ \mathfrak{S} &= \{(X^P)^g \mid g \in S\} \ (= \mathfrak{S}(X^P)), \\ \Theta^{(0)} &= \Theta^{(0)}(X^P), \quad \Theta^{(2)} = \Theta^{(2)}(X^P), \\ \rho &= \rho_{X^P}^{(2)} : \Theta^{(2)} \to \mathcal{S}(T), \quad \mathbf{\Theta} = (\Theta^{(0)}, \Theta^{(2)}, p_{\Theta^{(0)}}, \rho), \end{split}$$

where  $p_{\Theta^{(0)}}: \Theta^{(0)} \to \Theta^{(2)}$  is the canonical map. Without any loss of generality we can suppose that  $f^P: X^P \to Y^P$  is  $k_P$ -connected. Then by Theorem 3.5 the *T*-surgery obstruction  $\sigma(f^P, b^P)$  to the (T, R)-surgery map  $(f^P, b^P)$  being a  $\mathbb{Z}_{(p)}$ -homology equivalence lies in  $W_{n_P}(R, T, S, Q, \Theta)_{\text{free}}$ . Μ. Μογιμοτο

For a subgroup K of T, set  $S_K = S(\operatorname{res}_K^T X^P)$ ,  $Q_K = Q(\operatorname{res}_K^T X^P)$ ,  $\mathfrak{S}_K = \mathfrak{S}(\operatorname{res}_K^T X^P)$ ,  $\Theta_K^{(0)} = \Theta^{(0)}(\operatorname{res}_K^T X^P)$ ,  $\Theta_K^{(2)} = \Theta^{(2)}(\operatorname{res}_K^T X^P)$ ,  $\rho_K = \rho_{\operatorname{res}_K^T X^P}^{(2)}$ :  $\Theta_K^{(2)} \to \mathcal{S}(K)$ , and

$$\boldsymbol{\Theta}_{K} = (\Theta_{K}^{(0)}, \Theta_{K}^{(2)}, p_{\Theta_{K}^{(0)}}, \rho_{K}).$$

By Lemmas 2.4, 4.7 and 4.8, the correspondence

$$K \mapsto W_{n_P}(R, K, S_K, Q_K, \boldsymbol{\Theta}_K)_{\text{free}} \quad (K \in \mathcal{S}(T))$$

affords a Mackey functor, and moreover a module over the Green functor

$$K \mapsto \mathrm{SGW}_0(\mathbb{Z}, K, S_K, \Theta_K^{(2)}/S_K) \quad (K \in \mathcal{S}(T)).$$

 $\langle \alpha \rangle$ 

Thus the argument in [11, §5, Case 2] using the relation between the equivariant connected sum operation and the  $\Omega(T)$ -action on the surgery obstruction group (cf. [11, (5.2)], works in the present situation. This ensures that by using equivariant connected sum and G-surgery of isotropy type (P), we can convert  $f^P: X^P \to Y^P$ to a  $\mathbb{Z}_{(p)}$ -homology equivalence.

Step B. In this case, Y is 1-connected and  $n = \dim Y = \dim X$ . We set k = n/2,  $\begin{array}{l} \lambda = (-1)^k, \ w = w_X : G \to \{\pm 1\}, \ R = \mathbb{Z}, \ S = S(X), \ Q = Q(X), \ \mathfrak{S} = \mathfrak{S}(X), \\ \Theta^{(0)} = \Theta^{(0)}(X), \ \Theta^{(2)} = \Theta^{(2)}(X), \ \rho = \rho_X^{(2)} : \Theta^{(2)} \to \mathcal{S}(G), \ \mathrm{and} \end{array}$ 

$$\boldsymbol{\Theta} = (\Theta^{(0)}, \Theta^{(2)}, p_{\Theta^{(0)}}, \rho),$$

where  $p_{\Theta^{(0)}}: \Theta^{(0)} \to \Theta^{(2)}$  is the canonical map. Without loss of generality we can suppose that  $f: X \to Y$  is k-connected. Since

$$K_k(f;R) = \operatorname{Ker}[f_*: H_k(X;R) \to H_k(Y;R)]$$

is a projective R[G]-module but not necessarily a stably free R[G]-module, Theorem 6.3 in [2] says that the G-surgery obstruction  $\sigma(f, b)$  to the (G, R)surgery map (f, b) being a homotopy equivalence lies in the obstruction group  $W_n(R, G, S, Q, \Theta)_{\text{proj}}$ . But by employing the relation

$$(1 + (-\beta)^{\%})\widetilde{K}_0(R[G]) = 0$$

described in [11, §5, Case 3] and by taking a suitable equivariant connected sum, we may assume that  $K_k(f; R)$  is a stably free R[G]-module. Then  $\sigma(f, b)$  lies in the obstruction group  $W_n(R, G, S, Q, \Theta)_{\text{free}}$ .

For a subgroup K of G, set  $S_K = S(\operatorname{res}_K^G X), Q_K = Q(\operatorname{res}_K^G X), \mathfrak{S}_K = \mathfrak{S}(\operatorname{res}_K^G X), \Theta_K^{(0)} = \Theta^{(0)}(\operatorname{res}_K^G X), \Theta_K^{(2)} = \Theta^{(2)}(\operatorname{res}_K^G X), \rho_K = \rho_{\operatorname{res}_K^G X}^{(2)} : \Theta_K^{(2)} \to \mathfrak{S}_K^{(2)}$  $\mathcal{S}(K)$ , and  $(\Omega^{(0)} \ \Omega^{(2)})$ e

$$\boldsymbol{\Theta}_K = (\Theta_K^{(0)}, \Theta_K^{(2)}, p_{\Theta_K^{(0)}}, \rho_K).$$

By Lemmas 2.4, 4.7 and 4.8, the correspondence

$$K \mapsto W_n(R, K, S_K, Q_K, \boldsymbol{\Theta}_K)_{\text{free}} \quad (K \in \mathcal{S}(G))$$

affords a Mackey functor, and a module over the Green functor

$$K \mapsto \mathrm{SGW}_0(\mathbb{Z}, K, S_K, \Theta_K^{(2)}/S_K) \quad (K \in \mathcal{S}(G)).$$

Thus the argument in [11, §5, Case 3] works in the present situation. Hence, by using equivariant connected sum and G-surgery of isotropy type ( $\{e\}$ ), we can convert  $f: X \to Y$  to a homotopy equivalence.

Putting all this together, we have proved the theorem above.

# §6. Applications of the deleting-inserting theorem

Let G be a finite group. One may conjecture that if V and W are  $\mathcal{P}$ -matched  $\mathcal{L}$ -free real G-modules then V and W are stably Smith equivalent, with which the following is concerned.

**Definition 6.1.** We call a real G-module V admissible if it satisfies the following conditions.

- (6.1.1) V satisfies the weak gap condition on  $\mathcal{PH}(G)$ .
- (6.1.2) dim  $V^{=H} \ge 3$  for any  $H \in \mathcal{G}^1(G)$ .
- (6.1.3) dim  $V^P \ge 5$  for any  $P \in \mathcal{P}(G)$ .
- (6.1.4) If dim  $V^P = 2 \dim V^H$  for  $(P, H) \in \mathcal{PH}(G)$  then (P, H) belongs to  $\mathcal{PH}_2(G)$ and dim  $V^{>H} \leq \dim V^H - 2$ .

The next lemma is an elaboration of [6, Theorem B]. In [6], we worked with real G-modules V such that all transformations  $g: V^H \to V^{gHg^{-1}}$  are orientation preserving for  $g \in G$  and  $H \in \mathcal{S}(G)$  (cf. [6, p. 491 (3.3.6)]).

**Lemma 6.2.** Let G be an Oliver group, m a positive integer, and V an admissible real G-module. Then there exists a smooth G-action on the standard sphere  $S_V$  such that  $S_V^G$  consists of m points  $x_1, \ldots, x_m$  and each  $T_{x_i}(S_V)$ ,  $1 \le i \le m$ , is isomorphic to V.

*Proof.* Let Y be the unit disk D(V) of V with respect to some G-invariant inner product. Then Y satisfies the conditions (5.1.1)–(5.1.7). By Theorem 5.1, we obtain a smooth G-action on a disk  $D_0$  such that  $D_0$  does not have G-fixed points and  $\partial D_0$  is G-diffeomorphic to  $S(V) = \partial D(V)$ . On the other hand, by Theorem 5.1 there exists a smooth G-action on a disk  $D_m$  such that  $D_m^G$  consists of m points  $x_1, \ldots, x_m, \partial D_0$  is G-diffeomorphic to  $S(V) = \partial D(V)$ , and the tangential representations  $T_{x_i}(D_m)$  are all isomorphic to V. Then glue  $D_0$  and  $D_m$  along the boundary and obtain a smooth G-action on a homotopy sphere  $\Sigma_V$  such that  $\Sigma_V^G$  consists of m points  $x_1, \ldots, x_m$  and  $T_{x_i}(\Sigma_V)$  are isomorphic to V. Taking the equivariant connected sum of copies of  $\Sigma_V$  (cf. [7, Proposition 1.3, Example 1.2]), we can obtain a smooth G-action on the standard sphere as desired.

Lemma 1.1 implies that  $\mathbb{R}[G]_{\mathcal{L}}^{\oplus 3}$  is an admissible real *G*-module. Hence Theorems 1.3 and 1.4 immediately follow from the lemma above.

**Theorem 6.3.** Let G be an Oliver group. Let  $V_1, \ldots, V_m$  be  $\mathcal{L}$ -free real G-modules any two of which are  $\mathcal{P}$ -matched. Then there exists an integer  $N_1$  such that for any integer  $\ell \geq N_1$ , there exists a smooth G-action on the disk D with exactly m G-fixed points  $x_1, \ldots, x_m$  for which the tangential representation  $T_{x_i}(D)$  is isomorphic to  $V_i \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}$  for  $1 \leq i \leq m$ .

*Proof.* Consider the space  $F = \{x_1, \ldots, x_m\}$  with the trivial *G*-action. We have the  $\mathcal{L}$ -free real *G*-vector bundle  $\nu = \varepsilon_{\{x_1\}}(V_1) \amalg \cdots \amalg \varepsilon_{\{x_m\}}(V_m)$  over *F*. Clearly res<sup>*G*</sup><sub>{*e*}</sub> $\nu$  is isomorphic to  $\varepsilon_F(\mathbb{R}^n)$  for  $n = \dim V_1$  and res<sup>*G*</sup><sub>*P*</sub> $\nu$  is isomorphic to  $\varepsilon_F(\operatorname{res}^{G}_{P}V_1)$  for any  $P \in \mathcal{P}(G)$ . By [14, Theorem 21], there exists an integer  $N_1$  as desired.

Proof of Theorem 1.5. Let  $N_1$  be the non-negative integer obtained in Theorem 6.3 for the *G*-modules  $V_1, \ldots, V_m$ . There exists an integer  $N \ge N_1$  such that the real *G*-modules  $V_i \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus N}$ ,  $1 \le i \le m$ , are all admissible. Then for all  $\ell \ge N$ , the real *G*-modules

$$W_i = V_i \oplus \mathbb{R}[G]_{\mathcal{L}}^{\oplus \ell}, \quad 1 \le i \le m,$$

are also admissible. Again by Theorem 6.3, there exists a smooth G-action on the disk Y such that  $Y^G = \{x_1, \ldots, x_m\}$  and  $T_{x_i}(Y) \cong W_i$  for  $1 \leq i \leq m$ . Let Z denote the double  $Y \cup_{\partial Y} Y$  of Y. Then Z is a sphere having the G-fixed points  $x_1, \ldots, x_m$ ,  $x'_1, \ldots, x'_m$  such that  $T_{x_i}(Z) \cong T_{x'_i}(Z) \cong W_i$  for  $1 \leq i \leq m$ . By Lemma 6.2, there exist smooth G-actions on spheres  $S_i$ ,  $1 \leq i \leq m$ , such that  $S_i^G = \{x''_i\}$  and  $T_{x''_i}(S_i) \cong W_i$ . Let S denote the G-manifold obtained as the G-connected sum of Z and  $S_i$ ,  $1 \leq i \leq m$ , at pairs  $(x'_i, x''_i) \in Z \times S_i$ . Then the underlying manifold of S is diffeomorphic to the standard sphere and moreover S possesses the properties required in Theorem 1.5.

Let WP(G) denote the set consisting of  $[V] - [W] \in \operatorname{RO}(G)^{\mathcal{L}}$  such that V and W both are  $\mathcal{L}$ -free and satisfy the weak gap condition on  $\mathcal{PH}_2(G)$ . Note that G is a weak gap group if and only if WP(G)<sub> $\mathcal{P}$ </sub> = RO(G)<sup> $\mathcal{L}$ </sup>. Since the set

$$-WP(G) = \{-x \in RO(G) \mid x \in WP(G)\}$$

coincides with WP(G), we can prove the next proposition without difficulties.

**Proposition 6.4.** The set WP(G) is a subgroup of RO(G).

Theorem 1.9 can be reformulated as follows:

**Theorem 6.5.** If H is a subgroup of an Oliver group G then

 $\operatorname{ind}_{H}^{G}(WP(H)_{\mathcal{P}}) \subset \operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}.$ 

For a pair  $(P, H) \in \mathcal{PH}(G)$ , define a  $\mathbb{Z}$ -linear map  $f_{P,H} : \mathrm{RO}(G) \to \mathbb{Z}$  by

 $f_{P,H}([V]) = \dim V^P - 2\dim V^H.$ 

Next define

$$\mathbf{P}_{+}(\mathcal{PH}_{2}(G)) = \{ x \in \mathrm{RO}(G)^{\mathcal{L}} \mid f_{P,H}(x) \ge 0 \text{ for all } (P,H) \in \mathcal{PH}_{2}(G) \}$$

 $P_{-}(\mathcal{PH}_{2}(G)) = \{ x \in \mathrm{RO}(G)^{\mathcal{L}} \mid f_{P,H}(x) \leq 0 \text{ for all } (P,H) \in \mathcal{PH}_{2}(G) \}.$ 

It is clear that  $P_{-}(\mathcal{PH}_{2}(G)) = -P_{+}(\mathcal{PH}_{2}(G)).$ 

**Lemma 6.6.** For an arbitrary finite group G, we have

 $\mathcal{P}_+(\mathcal{PH}_2(G)) \cup \mathcal{P}_-(\mathcal{PH}_2(G)) \subset \mathcal{WP}(G).$ 

*Proof.* Let  $x = [V] - [W] \in P_+(\mathcal{PH}_2(G))$ , where V and W are  $\mathcal{L}$ -free real G-modules. By [13, Proposition 2.3], W is isomorphic to a G-submodule of  $\mathbb{R}[G]_{\mathcal{L}}^{\oplus m}$ , where  $m = \dim W$ . Thus we can assume  $W = \mathbb{R}[G]_{\mathcal{L}}^{\oplus m}$  without any loss of generality. Then the inequality

$$f_{P,H}(x) = (\dim V^P - 2\dim V^H) - m(\dim (\mathbb{R}[G]_{\mathcal{L}})^P - 2\dim (\mathbb{R}[G]_{\mathcal{L}})^H) \ge 0$$

for  $(P, H) \in \mathcal{PH}_2(G)$  reads

$$\dim V^P - 2\dim V^H \ge m(\dim \left(\mathbb{R}[G]_{\mathcal{L}}\right)^P - 2\dim \left(\mathbb{R}[G]_{\mathcal{L}}\right)^H)$$

Since the right-hand side above is non-negative, V satisfies the weak gap condition on  $\mathcal{PH}_2(G)$  as also does  $W = \mathbb{R}[G]_{\mathcal{L}}^{\oplus m}$ , which ensures that the element x = [V] - [W] belongs to WP(G), hence  $P_+(\mathcal{PH}_2(G)) \subset WP(G)$ .

In addition, we have

$$P_{-}(\mathcal{PH}_{2}(G)) = -P_{+}(\mathcal{PH}_{2}(G)) \subset -WP(G) = WP(G).$$

This completes the proof.

The next claim immediately follows from Theorem 6.5 and Lemma 6.6.

**Theorem 6.7.** If H is a subgroup of an Oliver group G then

$$\operatorname{ind}_{H}^{G}\left(\mathcal{P}_{+}(\mathcal{P}\mathcal{H}_{2}(H))_{\mathcal{P}}\cup\mathcal{P}_{-}(\mathcal{P}\mathcal{H}_{2}(H))_{\mathcal{P}}\right)\subset \operatorname{Sm}(G)_{\mathcal{P}}^{\mathcal{L}}$$

Proof of Theorem 1.10. It is clear that

$$\operatorname{RO}(H)_{\mathcal{H}}^{\mathcal{L}} \subset \operatorname{P}_{+}(\mathcal{PH}_{2}(H))_{\mathcal{H}} \subset \operatorname{P}_{+}(\mathcal{PH}_{2}(H))_{\mathcal{P}}$$

and

$$\operatorname{ind}_{H}^{G}(\operatorname{RO}(H)_{\mathcal{H}}) \subset \operatorname{RO}(G)_{\mathcal{H}}.$$

Thus Theorem 1.10 follows from Theorem 6.7.

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