

Convex Monotone Semigroups on Lattices of Continuous Functions

by

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Abstract

We consider convex monotone C_0 -semigroups on a Banach lattice, which is assumed to be a Riesz subspace of a σ -Dedekind complete Banach lattice. Typical examples include the space of all bounded uniformly continuous functions and the space of all continuous functions vanishing at infinity. We show that the domain of the classical generator of a convex semigroup is typically not invariant. Therefore, we propose alternative versions for the domain, such as the monotone domain and the Lipschitz set, for which we prove invariance under the semigroup. As a main result, we obtain the uniqueness of the semigroup in terms of an extended version of the generator. The results are illustrated with several examples related to Hamilton–Jacobi–Bellman equations, including nonlinear versions of the shift semigroup and the heat equation. In particular, we determine their symmetric Lipschitz sets, which are invariant and allow us to define the generators in a weak sense.

2020 Mathematics Subject Classification: Primary 47H20; Secondary 35A02, 35F21.

Keywords: Convex semigroup, nonlinear Cauchy problem, Lipschitz set, monotone generator, Hamilton–Jacobi–Bellman equation.

§1. Introduction

The topic of model uncertainty or ambiguity in the fields of mathematical economics and mathematical finance has been extensively studied in the last decades. Hereby, a particular focus has been put on parameter uncertainty of stochastic processes describing the evolution of an underlying asset. Examples include a

Communicated by N. Ozawa. Received October 8, 2020. Revised May 4, 2021.

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Brownian motion with drift uncertainty (cf. Coquet et al. [6]) or volatility uncertainty (cf. Peng [30, 31]), a Black–Scholes model with volatility uncertainty (cf. Avellaneda et al. [2], Epstein and Ji [14], Vorbrink [35]), and Lévy processes with uncertainty in the Lévy triplet (cf. Hu and Peng [19], Neufeld and Nutz [27], Hollender [18], Kühn [22]). In the case of a Brownian motion with uncertain volatility within an interval $[\underline{\sigma}, \bar{\sigma}]$ for $0 \leq \underline{\sigma} \leq \bar{\sigma}$, this leads to the equation

$$(1.1) \quad \partial_t u(t, x) = \sup_{\sigma \in [\underline{\sigma}, \bar{\sigma}]} \frac{\sigma^2}{2} \partial_{xx} u(t, x) \quad \text{for } t \geq 0 \text{ and } x \in \mathbb{R}.$$

The latter is referred to as the G -heat equation, and their solutions (for different initial values) can be represented by means of the so-called G -expectation; cf. Peng [30, 31].

Equation (1.1) falls into the class of Hamilton–Jacobi–Bellman (HJB) equations, which closely relate to (stochastic) optimal control problems. On a meta (and structurally very reduced) level, a control problem consists of a nonempty control set Λ , and a family of semigroups $(S_\lambda)_{\lambda \in \Lambda}$, where S_λ relates to the value of a cost functional under the static control $\lambda \in \Lambda$. Allowing for a dynamic state-dependent choice from the control set Λ leads to a convex semigroup S , which on an abstract level is given as a (viscosity) solution to an HJB equation of the form

$$(1.2) \quad \partial_t u = \sup_{\lambda \in \Lambda} A_\lambda u,$$

where A_λ is the generator of the affine linear semigroup S_λ for all $\lambda \in \Lambda$. Inspired by a construction of Nisio [28], such equations have been studied using a semigroup-theoretic framework for spaces of continuous functions by Denk et al. [12] and Nenel and Röckner [26]. Choosing $A_\lambda := \frac{\lambda^2}{2} \partial_{xx}$ for $\lambda \in \Lambda := [\underline{\sigma}, \bar{\sigma}]$, the G -heat equation (1.1) is a particular instance of (1.2). The related control problem is the one of optimally choosing a volatility from the control set $[\underline{\sigma}, \bar{\sigma}]$. We refer to Denis et al. [10] for a detailed illustration of this relation. In the context of optimal control theory, the uniqueness and regularity of solutions to Hamilton–Jacobi–Bellman equations are fundamental in order to come up with verification theorems; ensuring that the solution to the HJB equation is in fact the value function of an optimal control problem; cf. Fleming and Soner [17], Pham [33], and Yong and Zhou [36]. In an even broader sense, the G -heat equation and HJB equations of the form (1.2) are examples for convex differential equations and the related value functions (their solutions) form a convex semigroup on suitable spaces of continuous functions, where the semigroup property is the abstract analogon of

the dynamic programming principle. We refer to Denk et al. [12] and Nendel and Röckner [26] for more details on this relation.

One classical approach to treat nonlinear equations uses the theory of maximal monotone or m -accretive operators; cf. Barbu [3], Bénéilan and Crandall [4], Brézis [5], Evans [15], Kato [20], and the references therein. To show that an accretive operator is m -accretive, one has to prove that $1 + hA$ is surjective for $h > 0$, and in many cases it is quite delicate to verify this condition; see Example 5.2 below. Moreover, it is known that m -accretive operators lead to the existence of a mild solution, but the existence of strong solutions is only known under additional assumptions on the underlying Banach space, including reflexivity; see [3, Sect. 4.1]. In terms of nonlinear semigroups, this means that even if the initial value is smooth, the solution (the semigroup applied to the initial value) does not belong to the domain of the operator for positive time, so the domain of the operator is not invariant under the semigroup; see [8, Sect. 4] or Example 5.4 below. Therefore, in the context of HJB equations, one typically considers a more general solution concept, so-called viscosity solutions; cf. Crandall et al. [7], Crandall and Lions [9], and the discussion in Evans [15, Sect. 4].

In this paper, we study convex monotone semigroups on spaces of continuous functions and construct invariant domains with a particular interest in the regularity and uniqueness of the solution. The main object and the starting point of our investigation is a convex C_0 -semigroup $S = (S(t))_{t \geq 0}$ on a Banach lattice X which is a Riesz subspace of some Dedekind σ -complete Riesz space \bar{X} . Typical examples for X are the space BUC of all bounded uniformly continuous functions, the space C_0 of all continuous functions vanishing at infinity, or spaces of uniformly continuous functions with certain growth at infinity. We focus on monotone semigroups that are continuous from above, meaning that $S(t)x_n \downarrow 0$ for all $t \geq 0$, whenever $x_n \downarrow 0$. This additional continuity property allows us to extend the semigroup to the set X_δ of all $x \in \bar{X}$ for which there exists a sequence $(x_n)_{n \in \mathbb{N}}$ in X such that $x_n \downarrow x$. Likewise, the generator A of the semigroup extends to the so-called monotone generator A_δ , whose domain is defined as the set of all $x \in X$ such that, for every sequence $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ with $h_n \downarrow 0$, there exists an approximating sequence $(y_n)_{n \in \mathbb{N}}$ in X such that

$$\left\| \frac{S(h_n)x - x}{h_n} - y_n \right\| \rightarrow 0 \quad \text{and} \quad y_n \downarrow y =: A_\delta x.$$

The main results in Sections 3 and 4 state that a convex monotone C_0 -semigroup leaves the domain $D(A_\delta)$ of its monotone generator invariant, and that the semigroup is uniquely determined by A_δ on $D(A_\delta)$. We also study even weaker forms of domains requiring only the local Lipschitz continuity of the map $t \mapsto S(t)x$,

or, in other words, a weak Sobolev regularity of the map $t \mapsto S(t)x$, i.e., for every continuous linear functional μ , the map $(t \mapsto \mu S(t)x) \in W_{\text{loc}}^{1,\infty}([0, \infty))$. These domains are shown to be invariant as well, and we discuss their relation to one another.

In Section 5 we consider the example of the uncertain shift semigroup on the space BUC, which corresponds to the fully nonlinear PDE

$$(1.3) \quad \partial_t u(t, x) = |\partial_x u(t, x)|, \quad u(0, \cdot) = f.$$

Here, the nonlinear generator is given by $Au = |\partial_x u|$ for sufficiently regular $u \in \text{BUC}$. In that case, it holds that $\text{BUC}^1 \subset D(A_\delta) \subset W^{1,\infty}$ and $W^{1,\infty}$ is invariant under the corresponding semigroup. Note that (1.3) is a special case of the Hamilton–Jacobi PDE, where, under appropriate conditions on the nonlinearity, the viscosity solution is given by the Hopf–Lax formula; see e.g. [16, Sect. 3.3], [24, Sect. 11.1]. Similarly, for the second-order differential operator $Au = \frac{1}{2} \max\{\underline{\sigma}^2 \partial_{xx} u, \bar{\sigma}^2 \partial_{xx} u\}$ with $0 \leq \underline{\sigma} \leq \bar{\sigma}$, we derive that $W^{2,\infty}$ is invariant under the respective semigroup S , which corresponds to the G -heat equation. Moreover, we show that the equality $\lim_{h \downarrow 0} \frac{S(h)u - u}{h} = \frac{1}{2} \max\{\underline{\sigma}^2 \partial_{xx} u, \bar{\sigma}^2 \partial_{xx} u\}$ holds on $W^{2,\infty}$ in a pointwise sense almost everywhere. We remark that in the parabolic situation $\underline{\sigma} > 0$, many results on the solvability of this second-order fully nonlinear equation in Sobolev and Hölder spaces were obtained by Krylov; see [21, Chaps. 12 and 13].

§2. Setup and notation

Throughout this article, we assume that X is a real Banach lattice which is a Riesz subspace of a Dedekind σ -complete Riesz space \bar{X} . A typical example is the space BUC as a subspace of the space \mathcal{L}^∞ of all bounded measurable functions. We denote by X' the dual space of X , i.e., the space of all continuous linear functionals $X \rightarrow \mathbb{R}$. For a sequence $(x_n)_{n \in \mathbb{N}}$ in X , we write $x_n \downarrow x$ if $(x_n)_{n \in \mathbb{N}}$ is decreasing, bounded from below, and $x = \inf_n x_n \in \bar{X}$. We define

$$X_\delta := \{x \in \bar{X} : x_n \downarrow x \text{ for some sequence } (x_n)_{n \in \mathbb{N}} \text{ in } X\}.$$

Let M be the space of all positive linear functionals $\mu: X \rightarrow \mathbb{R}$ which are continuous from above, i.e., $\mu x_n \downarrow 0$ for every sequence $(x_n)_{n \in \mathbb{N}}$ in X such that $x_n \downarrow 0$. Every $\mu \in M$ has a unique extension $\mu: X_\delta \rightarrow \mathbb{R}$ which is continuous from above, i.e., $\mu x_n \downarrow \mu x$ for every sequence $(x_n)_{n \in \mathbb{N}}$ in X_δ such that $x_n \downarrow x \in X_\delta$; see e.g. [11, Lem. 3.9]. We assume that the set M separates the points of X_δ , i.e., for every $x, y \in X_\delta$ with $x \neq y$ there exists some $\mu \in M$ with $\mu x \neq \mu y$. For an operator

$S: X \rightarrow X$, we define

$$\|S\|_r := \sup_{x \in B(0,r)} \|Sx\|$$

for all $r > 0$, where $B(x_0, r) := \{x \in X : \|x - x_0\| \leq r\}$ for $x_0 \in X$. We say that an operator $S: X \rightarrow X$ is *convex* if $S(\lambda x + (1 - \lambda)y) \leq \lambda Sx + (1 - \lambda)Sy$ for all $\lambda \in [0, 1]$, *positive homogeneous* if $S(\lambda x) = \lambda Sx$ for all $\lambda > 0$, *sublinear* if S is convex and positive homogeneous, *monotone* if $x \leq y$ implies $Sx \leq Sy$ for all $x, y \in X$, and *bounded* if $\|S\|_r < \infty$ for all $r > 0$. For $x \in X$, we define the convex operator $S_x: X \rightarrow X$ by

$$S_x y := S(x + y) - Sx.$$

Definition 2.1. A family $S = (S(t))_{t \geq 0}$ of bounded operators $X \rightarrow X$ is called a C_0 -semigroup on X if

- (S1) $S(0)x = x$ for all $x \in X$,
- (S2) $S(t + s)x = S(t)S(s)x$ for all $x \in X$ and $s, t \in [0, \infty)$,
- (S3) $S(t)x \rightarrow x$ as $t \downarrow 0$ for all $x \in X$.

We say that S is *monotone*, *convex*, or *sublinear* if $S(t)$ is monotone, convex, or sublinear for all $t \geq 0$, respectively.

We conclude with a notion of continuity, which we will require on several occasions.

Definition 2.2. A monotone C_0 -semigroup S is called *continuous from above* if $S(t)x_n \downarrow S(t)0$ for all $t \in [0, \infty)$ and every sequence $(x_n)_{n \in \mathbb{N}}$ in X with $x_n \downarrow 0$.

§3. Invariant domains

In this section, we discuss the invariance of various notions of generators and domains. Throughout, let S be a convex C_0 -semigroup on X . In contrast to [13], where the Banach lattice X is Dedekind σ -complete with order continuous norm, the domain

$$D(A) := \left\{ x \in X : \frac{S(h)x - x}{h} \text{ is convergent in } X \text{ for } h \downarrow 0 \right\}$$

is in general not invariant under the semigroup. For instance, for the uncertain semigroup $(S(t))_{t \in [0, \infty)}$ in Section 5.1, there exists some $x \in D(A)$ such that $S(t)x \notin D(A)$ for some $t \in (0, \infty)$. We therefore introduce the following modified versions of the domain.

Definition 3.1. The domain $D(A_\delta)$ of the *monotone generator* A_δ of S is defined as the set of all $x \in X$ such that, for every $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ with $h_n \downarrow 0$, there

exists a sequence $(A_n x)_{n \in \mathbb{N}}$ in X and some $y \in X_\delta$ such that

$$(3.1) \quad \left\| \frac{S(h_n)x - x}{h_n} - A_n x \right\| \rightarrow 0 \quad \text{and} \quad A_n x \downarrow y.$$

We define the monotone generator $A_\delta: D(A_\delta) \subset X \rightarrow X_\delta$ by $A_\delta x := y$ for $x \in D(A_\delta)$, where y is the limit in (3.1), which is uniquely determined by Lemma B.1.

Definition 3.2. The *Lipschitz set* of the semigroup S is defined as

$$(3.2) \quad D_L := \left\{ x \in X : \sup_{h \in (0, h_0]} \left\| \frac{S(h)x - x}{h} \right\| < \infty \text{ for some } h_0 > 0 \right\}.$$

We further define the *symmetric Lipschitz set* of the semigroup S by

$$D_L^s := \{ x \in X : x, -x \in D_L \}.$$

Let $W_{\text{loc}}^{1,\infty}([0, \infty))$ denote the space of all functions $f: [0, \infty) \rightarrow \mathbb{R}$ in the space $L_{\text{loc}}^\infty([0, \infty))$ with weak derivative $f' \in L_{\text{loc}}^\infty([0, \infty))$. Recall that $W_{\text{loc}}^{1,\infty}([0, \infty))$ coincides with space of all locally Lipschitz continuous functions. The following observation is one of the basic ingredients in the proof of Section 4, below.

Remark 3.3. Let $x \in X$. Then $x \in D_L$ if and only if

$$(t \mapsto \mu S(t)x) \in W_{\text{loc}}^{1,\infty}([0, \infty)) \quad \text{for all } \mu \in X'.$$

In fact, by Proposition A.4, the map $[0, \infty) \rightarrow X, t \mapsto \mu S(t)x$ is locally Lipschitz for every $x \in D_L$ and $\mu \in X'$, which proves one direction of the equivalence. Now, assume that $(t \mapsto \mu S(t)x) \in W_{\text{loc}}^{1,\infty}([0, \infty))$ for all $\mu \in X'$. Then, for every $\mu \in X'$,

$$\sup_{h \in (0, 1]} \left| \mu \left(\frac{S(h)x - x}{h} \right) \right| < \infty.$$

By the Banach–Steinhaus theorem, it follows that $x \in D_L$. If $\sup_{t \geq 0} \|S(t)\|_r < \infty$ for all $r \geq 0$, as, for example, in Sections 5.1 and 5.2, we obtain that $x \in D_L$ if and only if

$$(t \mapsto \mu S(t)x) \in W^{1,\infty}([0, \infty)) \quad \text{for all } \mu \in X'.$$

We say that the norm $\|\cdot\|$ on X is *σ -order continuous* if $\lim_{n \rightarrow \infty} \|x_n\| = 0$ for every decreasing sequence $(x_n)_{n \in \mathbb{N}}$ with $\inf_{n \in \mathbb{N}} x_n = 0$. The prime example for a Banach lattice with σ -order continuous norm is the closure C_0 w.r.t. the supremum norm $\|\cdot\|_\infty$ of the space C_c of all continuous functions $\Omega \rightarrow \mathbb{R}$ with compact support, where Ω is a locally compact metric space. Moreover, we say that the norm $\|\cdot\|$ on X is *order continuous* if, for every net $(x_\alpha)_\alpha$ with $x_\alpha \downarrow 0$, we have $\|x_\alpha\| \rightarrow 0$. Notice that order continuity of the norm is, for example, implied by separability of X together with *Dedekind σ -completeness* of X ; cf. [25, Exe. 2.4.1]

or [34, Cor. to Thm. II.5.14]. Typical examples for Banach lattices with order continuous norm are the spaces $L^p(\mu)$ for $p \in [1, \infty)$ and an arbitrary measure μ , the space c_0 of all sequences vanishing at infinity, and Orlicz spaces. We would like to point out that, due to its strong implications, we avoid order continuity of the norm in the present paper. A detailed study of convex semigroups on Banach lattices with order continuous norm can be found in [13].

We have the following relations between the domains and generators.

Lemma 3.4. *One has $D(A) \subset D(A_\delta) \subset D_L$, and $A_\delta|_{D(A)} = A$. If the norm $\|\cdot\|$ on X is σ -order continuous, then $x \in D(A_\delta)$ with $A_\delta x \in X$ implies $x \in D(A)$ and $A_\delta x = Ax$. If X is σ -Dedekind complete with σ -order continuous norm, then $A_\delta = A$.*

Proof. We first assume that $x \in D(A)$. Then, for every $h_n \downarrow 0$ and $A_n x := Ax$ for all $n \in \mathbb{N}$, one has

$$\left\| \frac{S(h_n)x - x}{h_n} - A_n x \right\| \rightarrow 0,$$

which shows that $x \in D(A_\delta)$ with $A_\delta x = Ax$.

We next assume that $x \in D(A_\delta)$. Then there exists some $h_0 > 0$ such that

$$\sup_{h \in (0, h_0]} \left\| \frac{S(h)x - x}{h} \right\| < \infty.$$

Otherwise, there exists a sequence $h_n \downarrow 0$ such that $\left\| \frac{S(h_n)x - x}{h_n} \right\| \geq n$ for all n . Since $x \in D(A_\delta)$ there exists a bounded decreasing sequence $(A_n x)_{n \in \mathbb{N}}$ in X such that $A_n x \downarrow A_\delta x$ and

$$\left\| \frac{S(h_n)x - x}{h_n} - A_n x \right\| \rightarrow 0.$$

But then,

$$\sup_{n \in \mathbb{N}} \left\| \frac{S(h_n)x - x}{h_n} \right\| \leq \sup_{n \in \mathbb{N}} \left\| \frac{S(h_n)x - x}{h_n} - A_n x \right\| + \sup_{n \in \mathbb{N}} \|A_n x\| < \infty,$$

which is a contradiction. This shows that $x \in D_L$.

If the norm $\|\cdot\|$ on X is σ -order continuous and $x \in D(A_\delta)$ with $A_\delta x \in X$, then $\|A_n x - A_\delta x\| \rightarrow 0$, so that $\frac{S(h_n)x - x}{h_n} \rightarrow A_\delta x$. If, in addition, X is σ -Dedekind complete, then $A_\delta x \in X$ for all $x \in D(A_\delta)$, which shows that $A_\delta = A$. □

For every $x \in X$ and $y \in X_\delta$, the directional derivative is defined as

$$S'_+(t, x)y := \inf_{h > 0} \frac{S(t)(x + hy) - S(t)x}{h} \in X_\delta.$$

For further details on the directional derivative we refer to Appendix B. The following main result of this subsection provides invariance for D_L and $D(A_\delta)$, and states regularity properties in the time variable.

Theorem 3.5. *For every $x \in D_L$, one has*

- (i) $S(t)x \in D_L$ for all $t \in [0, \infty)$,
- (ii) for every $\mu \in M$ there is a locally bounded measurable function $f_\mu: [0, \infty) \rightarrow \mathbb{R}$ with $\mu S(t)x = \mu x + \int_0^t f_\mu(s) ds$ for all $x \in D(A_\delta)$ and $t \geq 0$.

For every $x \in D(A)$, it holds that

- (iii) $S(t)x \in D(A_\delta)$ for all $t \geq 0$ with $A_\delta S(t)x = S'_+(t, x)A_\delta x$,
- (iv) $\mu S(t)x = \mu x + \int_0^t \mu S'_+(s, x)A_\delta x ds$ for every $\mu \in M$ and all $t \geq 0$. In particular, $f_\mu(s) = \mu S'_+(s, x)A_\delta x$ for almost every $s \in [0, \infty)$.

Moreover, (iii) and (iv) hold for all $x \in D(A_\delta)$ if, in addition, the semigroup is monotone and continuous from above.

Proof. (i) Fix $t \geq 0$. By Corollary A.2 there exist $L \geq 0$ and $r > 0$ such that

$$\|S(t)(y + x) - S(t)x\| \leq L\|y\|$$

for all $y \in B(x, r)$. Since $S(h)x \rightarrow x$ as $h \downarrow 0$, it follows that

$$\left\| \frac{S(h)S(t)x - S(t)x}{h} \right\| = \left\| \frac{S(t)S(h)x - S(t)x}{h} \right\| \leq L \left\| \frac{S(h)x - x}{h} \right\| < \infty$$

for all $h \in (0, h'_0]$ and some $h'_0 > 0$.

(ii) Since $x \in D_L$, it follows from Proposition A.4 that the map $[0, \infty) \rightarrow X$, $t \mapsto S(t)x$ is locally Lipschitz continuous. Fix $\mu \in M$. Since μ is continuous on X , see e.g. [1, Thm. 9.6], the map $[0, \infty) \rightarrow \mathbb{R}$, $t \mapsto \mu S(t)x$ is also locally Lipschitz continuous and is therefore in $W_{\text{loc}}^{1, \infty}([0, \infty))$ by Lebesgue's theorem. That is, there exists a locally bounded measurable function $f_\mu: [0, \infty) \rightarrow \mathbb{R}$ with $\mu S(t)x = \mu x + \int_0^t f_\mu(s) ds$.

(iii) Fix $t > 0$, let $(h_n)_{n \in \mathbb{N}}$ be a sequence in $(0, \infty)$ with $h_n \downarrow 0$, and $x \in D(A)$. By Corollary A.2, there exists some $L > 0$ such that

$$\begin{aligned} & \left\| \frac{S(t + h_n)x - S(t)x}{h_n} - \frac{S(t)(x + h_n Ax) - S(t)x}{h_n} \right\| \\ &= \left\| \frac{S(t)S(h_n)x - S(t)(x + h_n Ax)}{h_n} \right\| \\ &\leq L \left\| \frac{S(h_n)x - x - h_n Ax}{h_n} \right\| = L \left\| \frac{S(h_n)x - x}{h_n} - Ax \right\| \rightarrow 0 \quad \text{as } n \rightarrow \infty. \end{aligned}$$

Moreover, the sequence

$$A_n(S(t)x) := \frac{S(t)(x + h_n Ax) - S(t)x}{h_n}$$

is decreasing and satisfies $A_n(S(t)x) \downarrow S'_+(t, x)Ax$. This shows that $S(t)x \in D(A_\delta)$ with $A_\delta S(t)x = S'_+(t, x)Ax$. Recall that $Ax = A_\delta x$ for all $x \in D(A)$ by Lemma 3.4.

If, in addition, S is monotone, continuous from above, and $x \in D(A_\delta)$, then there exists a bounded decreasing sequence $(A_n x)_{n \in \mathbb{N}}$ in X such that

$$\left\| \frac{S(h_n)x - x}{h_n} - A_n x \right\| \rightarrow 0 \quad \text{and} \quad A_n x \downarrow A_\delta x.$$

By Corollary A.2, there exists some $L > 0$ such that

$$\left\| \frac{S(t + h_n)x - S(t)x}{h_n} - \frac{S(t)(x + h_n A_n x) - S(t)x}{h_n} \right\| \leq L \left\| \frac{S(h_n)x - x}{h_n} - A_n x \right\| \rightarrow 0$$

as $n \rightarrow \infty$. By Lemma B.4, the sequence $(A_n S(t)x)$ given by

$$A_n S(t)x := \frac{S(t)(x + h_n A_n x) - S(t)x}{h_n}$$

is decreasing and satisfies $A_n S(t)x \downarrow S'_+(t, x)A_\delta x$. This shows that $S(t)x \in D(A_\delta)$ with $A_\delta S(t)x = S'_+(t, x)A_\delta x$.

(iv) Since $x \in D(A_\delta)$, it follows from Lemma 3.4 that $x \in D_L$. Fix $\mu \in M$. By (ii) one has

$$\mu S(t)x = \mu x + \int_0^t f_\mu(s) \, ds$$

for all $t \geq 0$. In particular, $t \mapsto \mu S(t)x$ is differentiable almost everywhere. Since μ is continuous from above it follows from the previous step (iii) that the derivative is almost everywhere given by

$$f_\mu(t) = \lim_{h \downarrow 0} \frac{\mu S(t+h)x - \mu S(t)x}{h} = \mu A_\delta S(t)x = \mu S'_+(t, x)A_\delta x.$$

The proof is complete. □

For the symmetric Lipschitz set of a sublinear monotone semigroup, we have the following result.

Proposition 3.6. *Let S be sublinear and monotone. Then the symmetric Lipschitz set D_L^s is a linear subspace of X . If*

$$(3.3) \quad -S(s)(-S(t)x) \geq S(t)(-S(s)(-x)) \quad \text{for all } s, t \geq 0 \text{ and } x \in X,$$

then $S(t)x \in D_L^s$ for all $t \geq 0$ and $x \in D_L^s$.

Proof. The sublinearity of S implies that

$$S(t)(x + \lambda y) - (x + \lambda y) \leq S(t)x - x + \lambda(S(t)y - y)$$

and

$$-S(t)(x + \lambda y) + x + \lambda y \leq S(t)(-x) + x + \lambda(S(t)(-y) + y)$$

for all $x, y \in X$ and $\lambda > 0$. Consequently,

$$\begin{aligned} & \|S(t)(x + \lambda y) - (x + \lambda y)\| \\ & \leq \|S(t)x - x\| + \|S(t)(-x) + x\| + \lambda(\|S(t)y - y\| + \|S(t)(-y) + y\|) \end{aligned}$$

for all $x, y \in X$ and $\lambda > 0$, which shows that $x + \lambda y \in D_L^s$ for all $x, y \in D_L^s$ and $\lambda > 0$. Since $-x \in D_L^s$ for all $x \in D_L^s$, it follows that D_L^s is a linear subspace of X .

Now let $x \in D_L^s$ and $t \geq 0$. Since $S(t)$ is sublinear and bounded, it is globally Lipschitz with some Lipschitz constant $L > 0$ (cf. Lemma A.1). Therefore,

$$\|S(h)S(t)x - S(t)x\| \leq L\|S(h)x - x\|,$$

i.e., $S(t)x \in D_L$. It remains to show that $-S(t)x \in D_L$. First, observe that

$$-S(t)x - S(h)(-S(t)x) \leq -S(t)x + S(h)S(t)x \leq S(t)(S(h)x - x)$$

and, by (3.3),

$$S(h)(-S(t)x) + S(t)x \leq -S(t)(-S(t)(-x)) + S(t)x \leq S(t)(S(h)(-x) + x).$$

Therefore,

$$\|S(h)(-S(t)x) + S(t)x\| \leq L(\|S(h)x - x\| + \|(S(h)(-x) + x)\|),$$

which shows that $-S(t)x \in D_L$. □

Example 3.7. Let S be a translation-invariant sublinear monotone semigroup on the space $\text{BUC} = \text{BUC}(G)$, where G is an abelian group with a translation-invariant metric d such that (G, d) is separable and complete. Here, *translation invariant* means that

$$(S(t)f(x + \cdot))(0) = (S(t)f)(x) \quad \text{for all } f \in \text{BUC}, x \in G, \text{ and } t \geq 0.$$

The space BUC of all bounded uniformly continuous functions $f: G \rightarrow \mathbb{R}$ is endowed with the supremum norm $\|f\|_\infty := \sup_{x \in G} |f(x)|$. Under mild continuity assumptions, the semigroup has a dual representation

$$(3.4) \quad (S(t)f)(x) = \sup_{\mu \in \mathcal{P}_t} \int_G f(x + y) \, d\mu_t(y) \quad \text{for all } f \in \text{BUC}, x \in G, \text{ and } t \geq 0,$$

where \mathcal{P}_t is a convex set of Borel measures on G for all $t \geq 0$. For further details on dual representations we refer to [11] and, for further examples, we refer to [12]. Notice that, under (3.4),

$$-(S(t)(-f))(x) = \inf_{\mu \in \mathcal{P}_t} \int_G f(x+y) \, d\mu_t(y) \quad \text{for all } f \in \text{BUC}, x \in G, \text{ and } t \geq 0.$$

Then, for $f \in \text{BUC}$, $x \in G$, $\mu_t \in \mathcal{P}_t$, and $\mu_s \in \mathcal{P}_s$, it follows from (3.4) and Fubini's theorem that

$$\begin{aligned} \int_G (S(t)f)(x+y) \, d\mu_s(y) &\geq \int_G \int_G f(x+y+z) \, d\mu_t(z) \, d\mu_s(y) \\ &= \int_G \int_G f(x+y+z) \, d\mu_s(y) \, d\mu_t(z) \\ &\geq \int_G -(S(s)(-f))(x+z) \, d\mu_t(z). \end{aligned}$$

Taking the infimum over all $\mu_s \in \mathcal{P}_t$ and supremum over all $\mu_t \in \mathcal{P}_s$ yields

$$-S(s)(-S(t)f) \geq S(t)(-S(s)(f)).$$

By Proposition 3.6, we thus find that D_L^s is $S(t)$ -invariant for all $t \geq 0$.

Remark 3.8. Consider the setup of the previous example. Given $C \geq 0$ and $h_0 > 0$, let $D_L^s(C, h_0)$ denote the set of all $f \in D_L^s$ such that $\|S(h)f - f\|_\infty \leq Ch$ and $\|S(h)(-f) + f\|_\infty \leq Ch$ for all $h \in [0, h_0]$. Let $f \in D_L^s(C, h_0)$ and ν be a Borel probability measure on G . Then it holds that $f_\nu \in D_L^s(C, h_0)$, where $f_\nu(x) := \int_G f(x+y) \, \nu(dy)$. In fact, by a Banach-space-valued version of Jensen's inequality (cf. [12] or [26]) and the translation invariance of S ,

$$\begin{aligned} S(h)f_\nu - f_\nu &= S(h) \left(\int_G f(\cdot + y) \, d\nu(y) \right) - f_\nu \leq \int_G (S(h)f)(\cdot + y) \, d\nu(y) - f_\nu \\ &= \int_G (S(h)f)(\cdot + y) - f(\cdot + y) \, d\nu(y) \leq Ch \end{aligned}$$

for all $h \geq 0$. In a similar way, it follows that

$$S(h)(-f_\nu) + f_\nu \leq \int_G (S(h)(-f))(\cdot + y) + f(\cdot + y) \, d\nu(y) \leq Ch$$

for all $h \in [0, h_0]$. Combining these two estimates yields

$$\|S(h)f_\nu - f_\nu\|_\infty \leq Ch \quad \text{and} \quad \|S(h)(-f_\nu) + f_\nu\|_\infty \leq Ch$$

for all $h \in [0, h_0]$. This shows that $f_\nu \in D_L^s(C, h_0)$.

§4. Uniqueness

In this section we show that a convex semigroup is uniquely determined on $D(A_\delta)$ through its generator A_δ if the semigroup is, in addition, monotone and continuous from above. The following is the main result of this paper.

Theorem 4.1. *Let S be a convex monotone C_0 -semigroup on X which is continuous from above with monotone generator A_δ . Let $y: [0, \infty) \rightarrow X$ be a continuous function with $y(t) \in D(A_\delta)$ for all $t \geq 0$, and assume that, for all $t \geq 0$ and $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ with $h_n \downarrow 0$, there exists a bounded decreasing sequence $(B_n y(t))_{n \in \mathbb{N}}$ in X such that*

$$\left\| \frac{y(t + h_n) - y(t)}{h_n} - B_n y(t) \right\| \rightarrow 0 \quad \text{and} \quad B_n y(t) \downarrow A_\delta y(t).$$

Then $y(t) = S(t)x$ for all $t \geq 0$, where $x := y(0)$.

Proof. Let $t > 0$ and $g(s) := S(t - s)y(s)$ for all $s \in [0, t]$. Fix $s \in (0, t)$. For every $h > 0$ with $h < t - s$ one has

$$\begin{aligned} \frac{g(s + h) - g(s)}{h} &= \frac{S(t - s - h)y(s + h) - S(t - s)y(s)}{h} \\ &= \frac{S(t - s - h)y(s + h) - S(t - s - h)y(s)}{h} \\ &\quad - \frac{S(t - s - h)S(h)y(s) - S(t - s - h)y(s)}{h}. \end{aligned}$$

Let $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ with $h_n \downarrow 0$ and $\mu \in M$. By assumption, for $y := y(s) \in D(A_\delta)$, there exists a bounded decreasing sequence $(B_n y)_{n \in \mathbb{N}}$ in X with

$$(4.1) \quad \left\| \frac{y(s + h_n) - y(s)}{h_n} - B_n y \right\| \rightarrow 0 \quad \text{and} \quad B_n y \downarrow A_\delta y.$$

We define

$$\nu_n z := \frac{\mu S(t - s - h_n)(y + h_n z) - \mu S(t - s - h_n)y}{h_n}$$

for all $z \in X_\delta$ and $n \in \mathbb{N}$ with $t - s - h_n > 0$, where we take the unique extension of S to X_δ given by Lemma B.2. Moreover, let

$$\nu z := \limsup_{n \rightarrow \infty} \nu_n z \quad \text{for all } z \in X.$$

We first show that

$$(4.2) \quad \nu z \leq \inf_{h > 0} \frac{\mu S(t - s)(y + h z) - \mu S(t - s)y}{h} \quad \text{for all } z \in X.$$

Indeed, for every $\varepsilon > 0$ there exists some $h_0 > 0$ and, by Corollary A.3, there exists some $m_0 \in \mathbb{N}$ such that

$$\begin{aligned} \inf_{h>0} \frac{\mu S(t-s)(y+hz) - \mu S(t-s)y}{h} + 2\varepsilon &\geq \frac{\mu S(t-s)(y+h_0z) - \mu S(t-s)y}{h_0} + \varepsilon \\ &\geq \frac{\mu S(t-s-h_m)(y+h_0z) - \mu S(t-s-h_m)y}{h_0} \end{aligned}$$

for all $m \geq m_0$. Hence, for all $n \geq m_0$, which satisfy $h_n \leq h_0$, one has

$$\begin{aligned} \inf_{h>0} \frac{\mu S(t-s)(y+hz) - \mu S(t-s)y}{h} + 2\varepsilon \\ \geq \frac{\mu S(t-s-h_n)(y+h_nz) - \mu S(t-s-h_n)y}{h_n} = \nu_n z, \end{aligned}$$

which shows (4.2) by taking the limit superior as $n \rightarrow \infty$ and letting $\varepsilon \downarrow 0$. As a consequence of (4.2), it follows that ν is continuous from above (on X). Indeed, for every sequence $(z_n)_{n \in \mathbb{N}}$ in X with $z_n \downarrow 0$, one has

$$0 \leq \inf_{n \in \mathbb{N}} \nu z_n \leq \inf_{h>0} \inf_{n \in \mathbb{N}} \frac{\mu S(t-s)(y+hz_n) - \mu S(t-s)y}{h} = 0$$

so that $\nu z_n \downarrow 0$. Moreover, by definition, $\nu z = \lim_{n \rightarrow \infty} \sup_{k \geq n} \nu_k z$ for all $z \in X$, and therefore $\nu: X \rightarrow \mathbb{R}$ is convex. By [11, Lem. 3.9], ν uniquely extends to a convex monotone functional $\bar{\nu}: X_\delta \rightarrow \mathbb{R}$, which is continuous from above. We next show that

$$(4.3) \quad \limsup_{n \rightarrow \infty} \nu_n B_n y = \bar{\nu} A_\delta y.$$

To that end, let $\varepsilon > 0$. Then there exist $n_0, m_0 \in \mathbb{N}$ such that

$$\bar{\nu} A_\delta y + 2\varepsilon \geq \bar{\nu} B_{n_0} y + \varepsilon = \nu B_{n_0} y + \varepsilon \geq \nu_m B_{n_0} y \geq \nu_m B_m y$$

for all $m \geq m_0 \vee n_0$, where the last inequality follows by monotonicity of ν_m . This shows that

$$\bar{\nu} A_\delta y \geq \limsup_{n \rightarrow \infty} \nu_n B_n y.$$

Further,

$$\begin{aligned} \bar{\nu} A_\delta y &= \inf_{m \in \mathbb{N}} \nu B_m y = \inf_{m \in \mathbb{N}} \inf_{n \in \mathbb{N}} \sup_{k \geq n} \nu_k B_m y = \inf_{n \in \mathbb{N}} \inf_{m \in \mathbb{N}} \sup_{k \geq n} \nu_k B_m y \\ &\leq \inf_{n \in \mathbb{N}} \sup_{k \geq n} \nu_k B_k y = \limsup_{n \rightarrow \infty} \nu_n B_n y. \end{aligned}$$

By Lemma A.2 there exists some $L > 0$ such that

$$\begin{aligned} & \left\| \frac{S(t-s-h_n)y(s+h_n) - S(t-s-h_n)(y+h_nB_ny)}{h_n} \right\| \\ & \leq L \left\| \frac{y(s+h_n) - y}{h_n} - B_ny \right\| \rightarrow 0 \end{aligned}$$

as $n \rightarrow \infty$. Therefore, we conclude that

$$(4.4) \quad \limsup_{n \rightarrow \infty} \mu \left(\frac{S(t-s-h_n)y(s+h_n) - S(t-s-h_n)y}{h_n} \right) = \limsup_{n \rightarrow \infty} \nu_n B_n y = \bar{\nu} A_\delta y.$$

Since $y = y(s) \in D(A_\delta)$, it follows from (3.1) that there exists a bounded decreasing sequence $(A_n y)_{n \in \mathbb{N}}$ with

$$\left\| \frac{S(h_n)y - y}{h_n} - A_n y \right\| \rightarrow 0 \quad \text{and} \quad A_n y \downarrow A_\delta y.$$

By the same arguments as before, we get

$$(4.5) \quad \limsup_{n \rightarrow \infty} \mu \left(\frac{S(t-s-h_n)S(h_n)y - S(t-s-h_n)y}{h_n} \right) = \limsup_{n \rightarrow \infty} \nu_n A_n y = \bar{\nu} A_\delta y.$$

Hence, in combination with (4.4), we get

$$(4.6) \quad \begin{aligned} & \limsup_{n \rightarrow \infty} \mu \left(\frac{S(t-s-h_n)y(s+h_n) - S(t-s-h_n)y(s)}{h_n} \right) \\ & = \limsup_{n \rightarrow \infty} \mu \left(\frac{S(t-s-h_n)S(h_n)y(s) - S(t-s-h_n)y(s)}{h_n} \right) \end{aligned}$$

for every sequence $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ with $h_n \downarrow 0$ and all $\mu \in M$. As a consequence, we conclude that

$$(4.7) \quad \frac{\mu g(s+h_n) - \mu g(s)}{h_n} \rightarrow 0$$

for every sequence $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ with $h_n \downarrow 0$ and all $\mu \in M$. Indeed, by passing to a subsequence $(n_k)_{k \in \mathbb{N}}$, we may assume that

$$\limsup_{n \rightarrow \infty} \frac{\mu g(s+h_n) - \mu g(s)}{h_n} = \lim_{k \rightarrow \infty} \frac{\mu g(s+h_{n_k}) - \mu g(s)}{h_{n_k}}.$$

By passing to another subsequence, which we still denote by $(n_k)_k$, we can further assume that

$$(4.8) \quad \begin{aligned} & \liminf_{k \rightarrow \infty} \mu \left(\frac{S(t-s-h_{n_k})S(h_{n_k})y(s) - S(t-s-h_{n_k})y(s)}{h_{n_k}} \right) \\ & = \limsup_{k \rightarrow \infty} \mu \left(\frac{S(t-s-h_{n_k})S(h_{n_k})y(s) - S(t-s-h_{n_k})y(s)}{h_{n_k}} \right). \end{aligned}$$

Then, by applying the equality (4.6) to the subsequence $(h_{n_k})_{k \in \mathbb{N}}$, we obtain

$$\begin{aligned} \limsup_{n \rightarrow \infty} \frac{\mu g(s+h_n) - \mu g(s)}{h_n} &= \lim_{k \rightarrow \infty} \frac{\mu g(s+h_{n_k}) - \mu g(s)}{h_{n_k}} \\ &\leq \limsup_{k \rightarrow \infty} \mu \left(\frac{S(t-s-h_{n_k})y(s+h_{n_k}) - S(t-s-h_{n_k})y(s)}{h_{n_k}} \right) \\ &\quad - \liminf_{k \rightarrow \infty} \mu \left(\frac{S(t-s-h_{n_k})S(h_{n_k})y(s) - S(t-s-h_{n_k})y(s)}{h_{n_k}} \right) = 0, \end{aligned}$$

where the last equality follows from (4.6) and (4.8). With similar arguments, we also obtain $\liminf_{n \rightarrow \infty} \frac{\mu g(s+h_n) - \mu g(s)}{h_n} \geq 0$, which shows (4.7).

Since μ is continuous on X , see e.g. [1, Thm. 9.6], it follows by the same arguments as in the proof of [13, Thm. 3.5] that $s \mapsto \mu g(s)$ is continuous on $[0, t]$. By [29, Lem. 1.1, Chap. 2], we conclude that the map $s \mapsto \mu g(s)$ is constant on $[0, t]$, since it is continuous and its right derivative vanishes on $[0, t)$. In particular, $\mu y(t) = \mu g(t) = \mu g(0) = \mu S(t)y(0)$ for all $\mu \in M$. This shows that $y(t) = S(t)y(0)$ as M separates the points of X . □

Corollary 4.2. *Let S be a convex monotone C_0 -semigroup on X which is continuous from above with monotone generator A_δ , and let T be a convex C_0 -semigroup on X with generator B and monotone generator B_δ such that $B_\delta \subset A_\delta$. If $\overline{D(B)} = X$, then $S(t) = T(t)$ for all $t \geq 0$.*

Proof. For every $x \in D(B)$, the mapping $y: [0, \infty) \rightarrow X, y(t) := T(t)x$ satisfies the assumptions of Theorem 4.1. Indeed, $y(0) = x$ by definition, $t \mapsto y(t)$ is continuous by Corollary A.3, and $y(t) \in D(B_\delta) \subset D(A_\delta)$ by Theorem 3.5 with

$$\left\| \frac{y(t+h_n) - y(t)}{h_n} - B_n y(t) \right\| \rightarrow 0 \quad \text{and} \quad B_n y(t) \downarrow B_\delta y(t) = A_\delta y(t),$$

where $B_n y(t) := \frac{T(t)(x+h_n Bx) - T(t)x}{h_n}$ for all $n \in \mathbb{N}$. Hence, by Theorem 4.1, it follows that $T(t)x = y(t) = S(t)x$ for all $t \geq 0$. Since, by Lemma A.1, the bounded convex functions $T(t)$ and $S(t)$ are continuous, and $\overline{D(B)} = X$, it holds that $S(t) = T(t)$ for all $t \geq 0$. □

§5. Examples

§5.1. The uncertain shift semigroup

Let G be a convex set endowed with a metric $d: G \times G \rightarrow [0, \infty)$. We assume that, for every $x, y \in G$ and $\lambda \in (0, 1)$, there exists some $\lambda(x, y) \in G$ such that $d(x, \lambda(x, y)) = \lambda d(x, y)$ and $d(\lambda(x, y), y) = (1 - \lambda)d(x, y)$. The space of all bounded uniformly continuous functions $f: G \rightarrow \mathbb{R}$ is denoted by $\text{BUC} = \text{BUC}(G)$ and endowed with the supremum norm $\|f\|_\infty := \sup_{x \in G} |f(x)|$. Notice that BUC is a Riesz subspace of the Dedekind σ -complete Riesz space \mathcal{L}^∞ of all bounded Borel measurable functions $f: G \rightarrow \mathbb{R}$. On \mathcal{L}^∞ we consider the partial order $f \leq g$ whenever $f(x) \leq g(x)$ for all $x \in G$.

The *uncertain shift semigroup* S on BUC is defined by

$$(S(t)f)(x) := \sup_{d(x,y) \leq t} f(y) \quad \text{for all } f \in \text{BUC}, x \in G, \text{ and } t \geq 0.$$

Lemma 5.1. *The family $S = (S(t))_{t \geq 0}$ is a sublinear monotone C_0 -semigroup on BUC . Moreover,*

$$D_L = D_L^s = \text{Lip}_b,$$

where $\text{Lip}_b = \text{Lip}_b(G)$ is the space of all bounded Lipschitz continuous functions $G \rightarrow \mathbb{R}$.

Proof. We first show that $S(t): \text{BUC} \rightarrow \text{BUC}$ is well defined and bounded. To this end, fix $f \in \text{BUC}$. Since

$$|S(t)f(x)| \leq \sup_{d(x,y) \leq t} |f(y)| \leq \|f\|_\infty \quad \text{for all } x \in G,$$

it follows that $\|S(t)f\|_\infty \leq \|f\|_\infty$. Fix $\varepsilon > 0$ and $\delta > 0$ such that $|f(x) - f(y)| \leq \varepsilon$ for all $x, y \in G$ with $d(x, y) \leq \delta$. Let $x, y \in G$ with $d(x, y) \leq \delta$ and $z \in G$ with $d(x, z) \leq t$. Then, for $\lambda := \frac{t}{t+\delta}$, one has

$$d(y, \lambda(y, z)) = \lambda d(y, z) \leq \lambda(t + \delta) = t$$

and

$$d(z, \lambda(y, z)) = (1 - \lambda)d(y, z) \leq (1 - \lambda)(t + \delta) = \delta.$$

Hence,

$$f(z) - (S(t)f)(y) \leq f(z) - f(\lambda(y, z)) \leq \varepsilon.$$

Taking the supremum over all $z \in G$ with $d(x, z) \leq t$, it follows that

$$(S(t)f)(x) - (S(t)f)(y) \leq \varepsilon.$$

By a symmetry argument, we obtain that $|S(t)f(x) - S(t)f(y)| \leq \varepsilon$, showing that $S(t)f$ is uniformly continuous with the same modulus of continuity as f . We thus have shown that $S(t): \text{BUC} \rightarrow \text{BUC}$ is well defined and bounded. By definition, each $S(t)$ is sublinear and monotone, and $S(0)f = f$ for all $f \in \text{BUC}$. Moreover, for $t \leq \delta$,

$$|(S(t)f)(x) - f(x)| \leq \sup_{d(x,y) \leq t} |f(y) - f(x)| \leq \varepsilon$$

for all $x \in G$. Hence, $\|S(t)f - f\|_\infty \leq \varepsilon$ for all $t \leq \delta$, which shows that S is strongly continuous. It remains to show that S satisfies the semigroup property. Let $s, t \geq 0$. Further, let $x \in G$ and $z \in G$ with $d(x, z) \leq s + t$. Then, for $\lambda := \frac{t}{s+t}$, it holds that

$$d(z, \lambda(x, z)) = (1 - \lambda)d(x, z) \leq s$$

and

$$d(x, \lambda(x, z)) = \lambda d(x, z) \leq t.$$

Hence,

$$\begin{aligned} f(z) &\leq \sup_{d(\lambda(x,z), y) \leq s} f(y) = (S(s)f)(\lambda(x, z)) \leq \sup_{d(x,y) \leq t} (S(s)f)(y) \\ &= (S(t)S(s)f)(x). \end{aligned}$$

Taking the supremum over all $z \in G$ with $d(x, z) \leq s + t$, it follows that

$$(S(s + t)f)(x) \leq (S(t)S(s)f)(x).$$

Now let $z \in G$ with $d(x, z) \leq t$. Then there exists a sequence $(z_n)_{n \in \mathbb{N}}$ in G with $d(z, z_n) \leq s$ and $f(z_n) \rightarrow (S(s)f)(z)$. Then

$$(S(s)f)(z) = \lim_{n \rightarrow \infty} f(z_n) \leq \sup_{d(x,y) \leq s+t} f(y) = (S(s + t)f)(x).$$

Taking the supremum over all $z \in G$ with $d(x, z) \leq t$, yields that

$$(S(t)S(s)f)(x) \leq (S(s + t)f)(x).$$

Altogether, we have shown that S is a sublinear monotone C_0 -semigroup on BUC .

Now let $f \in D_L$. Then there exist $h_0 > 0$ and $C \geq 0$ such that $\|S(h)f - f\|_\infty \leq Ch$ for all $h \in [0, h_0]$. Hence, for all $x, y \in G$ with $d(x, y) =: h \leq h_0$,

$$f(x) - f(y) \leq (S(h)f)(y) - f(y) \quad \text{and} \quad f(y) - f(x) \leq (S(h)f)(x) - f(x).$$

This implies that $|f(x) - f(y)| \leq \|S(h)f - f\|_\infty \leq Ch = Cd(x, y)$. Since $f \in \text{BUC}$ is bounded, it follows that $f \in \text{Lip}_b$. On the other hand, if $f \in \text{Lip}_b \subset \text{BUC}$ with Lipschitz constant $C > 0$, it follows that

$$\|(S(h)f)(x) - f(x)\| \leq \sup_{d(x,y) \leq h} |f(y) - f(x)| \leq Cd(x, y) \leq Ch$$

for all $x \in G$ and $h \geq 0$. Therefore, $f \in D_L$. Since $-f \in \text{Lip}_b$ for all $f \in \text{Lip}_b$, it follows that $\text{Lip}_b \subset D_L^s$. Since, by definition, $D_L^s \subset D_L$, the assertion follows. \square

We now specialize to the case where $G = \mathbb{R}$ endowed with the Euclidean distance $d(x, y) = |x - y|$. In this case, the uncertain shift semigroup is given by

$$(S(t)f)(x) = \sup_{|y| \leq t} f(x + y)$$

for all $x \in \mathbb{R}$ and $t \in [0, \infty)$. By Lemma 5.1, it follows that S is a sublinear monotone C_0 -semigroup on BUC. In addition, by Dini's lemma, it is continuous from above. Denote by $A_\delta: D(A_\delta) \subset \text{BUC} \rightarrow \text{BUC}_\delta$ the monotone generator of S . Notice that BUC_δ is the space of all bounded upper semicontinuous functions $\mathbb{R} \rightarrow \mathbb{R}$. Moreover, by Lemma 5.1, we have that $D_L = D_L^s = W^{1,\infty}$. Recall that the space of all Lipschitz continuous functions coincides with the space $W^{1,\infty}$ of all functions with weak derivative $f' \in L^\infty$ (w.r.t. the Lebesgue measure). As usual, we denote by BUC^1 the space of all $f \in \text{BUC}$ which are differentiable with $f' \in \text{BUC}$. From a PDE point of view, one might consider BUC^1 to be the canonical choice for the domain of the generator of S . However, the following example shows that this does not yield an m-accretive operator.

Example 5.2. Let $X = \text{BUC}$ and $B: D(B) \rightarrow X$ with $Bf := |f'|$ for $f \in D(B) := \text{BUC}^1$. Then B is accretive, i.e., for some (equivalently, for any) $h > 0$, $1 + hB$ is injective and

$$\|(1 + hB)^{-1}g_1 - (1 + hB)^{-1}g_2\| \leq \|g_1 - g_2\| \quad \text{for all } g_1, g_2 \in R(1 + hB);$$

cf. [3, Prop. 3.1] and [8, Form. (8)]. To see this, let $f_1, f_2 \in D(B)$ and $h > 0$. We set $g := f_1 - f_2$ and choose a sequence $(x_k)_{k \in \mathbb{N}}$ in \mathbb{R} with $|g(x_k)| \rightarrow \|g\|_\infty$ as $k \rightarrow \infty$. If $(x_k)_{k \in \mathbb{N}}$ has a finite accumulation point x_0 , then we have $|g(x_0)| = \|g\|_\infty$, and the function g has a local extremum at x_0 . Consequently, $g'(x_0) = 0$ and therefore $f_1'(x_0) = f_2'(x_0)$. We obtain

$$\begin{aligned} \|f_1 - f_2 + h(|f_1'| - |f_2'|)\|_\infty &\geq |f_1(x_0) - f_2(x_0) + h(|f_1'(x_0)| - |f_2'(x_0)|)| \\ &= |f_1(x_0) - f_2(x_0)| = |g(x_0)| = \|g\|_\infty = \|f_1 - f_2\|_\infty. \end{aligned}$$

If $(x_k)_{k \in \mathbb{N}}$ has no finite accumulation point, we may w.l.o.g. assume that $x_k \rightarrow \infty$ as $k \rightarrow \infty$. Moreover, taking a subsequence we may also assume that $g(x_k) \rightarrow \pm \|g\|_\infty$ as $k \rightarrow \infty$. Again, w.l.o.g. let $g(x_k) \rightarrow \|g\|_\infty$ as $k \rightarrow \infty$. Let $\varepsilon > 0$, and choose $k_0 \in \mathbb{N}$ with

$$\|g\|_\infty - \tilde{\varepsilon} \leq g(x_k) \leq \|g\|_\infty \quad \text{for all } k \geq k_0,$$

where we have set $\tilde{\varepsilon} := \min\{\frac{\varepsilon}{2}, \frac{\varepsilon}{2h}\}$. Let $\ell_0 > k_0$ with $x_{\ell_0} \geq x_{k_0} + 1$. As $g \in \text{BUC}^1$, there exists some $y_0 \in (x_{k_0}, x_{\ell_0})$ with

$$\tilde{\varepsilon} \geq |g(x_{\ell_0}) - g(x_{k_0})| = |g'(y_0)| |x_{\ell_0} - x_{k_0}| \geq |g'(y_0)|.$$

We obtain

$$\begin{aligned} \|f_1 - f_2 + h(|f'_1| - |f'_2|)\|_\infty &\geq |f_1(y_0) - f_2(y_0) + h(|f'_1(y_0)| - |f'_2(y_0)|)| \\ &\geq |f_1(y_0) - f_2(y_0)| - h||f'_1(y_0)| - |f'_2(y_0)|| \\ &\geq |f_1(y_0) - f_2(y_0)| - h|f'_1(y_0) - f'_2(y_0)| \\ &= |g(y_0)| - h|g'(y_0)| \geq \|g\|_\infty - \frac{\varepsilon}{2} - h\frac{\varepsilon}{2h} \\ &= \|f_1 - f_2\|_\infty - \varepsilon. \end{aligned}$$

As $\varepsilon > 0$ was arbitrary, we see that also in this case the inequality

$$\|f_1 - f_2 + h(|f'_1| - |f'_2|)\|_\infty \geq \|f_1 - f_2\|_\infty$$

holds, which shows that B is accretive.

However, the operator B is not m-accretive, i.e., the operator $1 + hB$ is not surjective. For this, let $h > 0$, and set $u(x) := (1 - |x|)\mathbf{1}_{[-1,1]}(x)$ for $x \in \mathbb{R}$. Assume that there exists some $f \in D(B)$ with

$$(5.1) \quad f(x) + h|f'(x)| = u(x) \quad \text{for } x \in \mathbb{R}.$$

As u is an even function, we see that the function \bar{f} defined by $\bar{f}(x) := f(-x)$ is also a solution of (5.1). As B is accretive, the operator $1 + hB$ is injective, which shows that $\bar{f} = f$, i.e., the solution f is an even function too. As $f \in \text{BUC}^1$, we get $f'(0) = 0$ and therefore $f(0) = u(0) = 1$. Now, the differentiability of f leads to a contradiction with $f(x) \leq u(x)$ for all $x \in \mathbb{R}$, which holds by (5.1).

Proposition 5.3. *Let $G = \mathbb{R}$. Then $\text{BUC}^1 \subset D(A) \subset D(A_\delta) \subset D_L = D_L^s = W^{1,\infty}$. In particular, $S(t)f \in W^{1,\infty}$ for every $f \in W^{1,\infty}$ and all $t \geq 0$. Further, for $f \in D(A_\delta)$, one has $A_\delta f = |f'|$ almost everywhere.*

Proof. If $f \in \text{BUC}^1$, it follows from Taylor's theorem that

$$\left\| \frac{S(h)f - f}{h} - |f'| \right\|_\infty \rightarrow 0 \quad \text{as } h \downarrow 0.$$

Hence, by Lemmas 3.4 and 5.1,

$$\text{BUC}^1 \subset D(A) \subset D(A_\delta) \subset D_L = D_L^s = W^{1,\infty}.$$

In particular, $W^{1,\infty}$ is invariant under the uncertain shift semigroup by Theorem 3.5.

Let $f \in W^{1,\infty}$. By Rademacher’s theorem the function f is differentiable almost everywhere. If f is differentiable at x , then

$$\begin{aligned} \lim_{h \downarrow 0} \frac{(S(h)f)(x) - f(x)}{h} &= \lim_{h \downarrow 0} \sup_{|y| \leq h} \frac{f(x+y) - f(x)}{h} \\ &= \lim_{h \downarrow 0} \sup_{|y|=h} \frac{f(x+y) - f(y)}{h} = |f'(x)|. \end{aligned}$$

Since, for $f \in D(A_\delta)$, one has

$$(A_\delta f)(x) = \lim_{h \downarrow 0} \frac{(S(h)f)(x) - f(x)}{h}$$

for all $x \in \mathbb{R}^d$, we conclude that $A_\delta f = |f'|$ almost everywhere. Here, f' is understood as the weak derivative in L^∞ . □

The following example shows that, in general, $D(A)$ is not invariant under the semigroup $(S(t))_{t \geq 0}$.

Example 5.4. Consider the case $G = \mathbb{R}$, and let $f \in \text{BUC}^1$ with

$$f(x) = \begin{cases} x^2, & x \in [0, 2], \\ x^4, & x \in [-2, 0). \end{cases}$$

Then, by Proposition 5.3, $S(1)f \in D(A_\delta) \subset W^{1,\infty}$ with $A_\delta S(1)f = |(S(1)f)'$. By definition of $S(1)$,

$$(S(1)f)(x) = \begin{cases} (x+1)^2, & x \in [0, 1], \\ (x-1)^4, & x \in [-1, 0), \end{cases}$$

which implies that

$$(S(1)f)'(x) = \begin{cases} 2(x+1), & x \in (0, 1), \\ 4(x-1)^3, & x \in (-1, 0). \end{cases}$$

Therefore, $A_\delta S(1)f = |(S(1)f)'| \notin \text{BUC}$ and, in particular, $S(1)f \notin D(A)$.

§5.2. The G -expectation

Let $0 \leq \underline{\sigma} \leq \bar{\sigma}$. We consider the G -expectation on $\text{BUC} = \text{BUC}(\mathbb{R})$, which corresponds to the sublinear semigroup

$$(S(t)f)(x) := \sup_{\sigma \in \Sigma} \mathbb{E} \left[f \left(x + \int_0^t \sigma_s \, dW_s \right) \right] \quad \text{for } f \in \text{BUC}, x \in G, \text{ and } t \geq 0,$$

where W is a Brownian motion on a filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ and Σ denotes the set of all progressively measurable processes with values in $[\underline{\sigma}, \bar{\sigma}]$; see e.g. [10] and [32] for an overview on G -expectations. Note that we do not assume that $\underline{\sigma} > 0$, which is a standard assumption in PDE theory for obtaining regularity results in Hölder spaces (cf. Lieberman [23, Chap. XIV] and Peng [32, App. C, §4] for a short survey). An inspection shows that S is a translation-invariant sublinear C_0 -semigroup on BUC which is continuous from above. Moreover, an application of Itô's formula leads to

$$(5.2) \quad \lim_{h \downarrow 0} \frac{S(h)f - f}{h} = \frac{1}{2} \max\{\underline{\sigma}^2 f'', \bar{\sigma}^2 f''\} \quad \text{for all } f \in BUC^2,$$

where BUC^2 denotes the set of all $f \in BUC^1$ with first derivative $f' \in BUC^1$. In particular, $BUC^2 \subset D(A)$. We next determine the symmetric Lipschitz set.

Lemma 5.5. *The symmetric Lipschitz set is given by $D_L^s = W^{2,\infty}$.*

Proof. First, we show that $D_L^s \subset W^{2,\infty}$. To that end, fix $f \in D_L^s$. By definition of the symmetric Lipschitz set, there exist $C > 0$ and $h_0 > 0$ such that $f \in D_L^s(C, h_0)$. For every $\delta > 0$, we define $f_\delta(x) := \int_{\mathbb{R}} f(x + y) \nu_\delta(dy)$, where ν_δ is the normal distribution $\mathcal{N}(0, \delta)$ with mean zero and variance δ . Then it holds that $f_\delta \in BUC^2$ for all $\delta > 0$, and $\|f_\delta - f\|_\infty \rightarrow 0$ as $\delta \downarrow 0$. It follows from Remark 3.8 that

$$S(h)f_\delta - f_\delta \leq Ch \quad \text{and} \quad -S(h)(-f_\delta) - f_\delta \geq -Ch$$

for all $h \in [0, h_0]$ and $\delta > 0$. Hence, letting $h \downarrow 0$, we obtain

$$\frac{1}{2} \bar{\sigma}^2 f''_\delta \leq C \quad \text{and} \quad \frac{1}{2} \underline{\sigma}^2 f''_\delta \geq -C.$$

This shows that $\|f''_\delta\|_\infty$ is uniformly bounded in $\delta > 0$. Hence, there exists a sequence $\delta_n \downarrow 0$ such that $\int_x^y f''_{\delta_n}(z) dz \rightarrow 0$ for all $x, y \in \mathbb{R}$ with $x < y$ and some $g \in L^\infty$. By the dominated convergence theorem, we obtain

$$\begin{aligned} \frac{f(x+h) - f(x)}{h} &= \lim_{n \rightarrow \infty} \left(\frac{f_{\delta_n}(x+h) - f_{\delta_n}(x)}{h} \right) \\ &= \lim_{n \rightarrow \infty} \left(f'_{\delta_n}(x) + \frac{1}{h} \int_x^{x+h} \int_x^y f''_{\delta_n}(z) dz dy \right) \\ &= \lim_{n \rightarrow \infty} f'_{\delta_n}(x) + \frac{1}{h} \int_x^{x+h} \int_x^y g(z) dz dy \end{aligned}$$

for all $x \in \mathbb{R}$ and $h > 0$. Since $\lim_{h \downarrow 0} \frac{1}{h} \int_x^{x+h} \int_x^y g(z) dz dy \rightarrow 0$ for all $x \in \mathbb{R}$, we conclude that f is differentiable with $f'(x) = \lim_{n \rightarrow \infty} f'_{\delta_n}(x)$ and second weak derivative $f'' = g$. For the special choice $h = 1$, we observe that $f' \in L^\infty$. This shows that $f \in W^{2,\infty}$.

Second, we show that $W^{2,\infty} \subset D_L^s$. Fix $f \in W^{2,\infty}$ and set $f_n := \int_{\mathbb{R}} f(\cdot + y) \nu_{\delta_n}(dy)$ for all $n \in \mathbb{N}$. Then $f_n \in \text{BUC}^2$ with $\|f'_n\|_\infty \leq \|f'\|_\infty$ and $\|f''_n\|_\infty \leq \|f''\|_\infty$ for all $n \in \mathbb{N}$. For all $\sigma \in \Sigma$, $x \in \mathbb{R}$, and $n \in \mathbb{N}$, it follows from Itô's formula that

$$\mathbb{E} \left[f_n \left(x + \int_0^h \sigma_s dW_s \right) \right] - f_n(x) \leq \frac{1}{2} \|f''\|_\infty \bar{\sigma}^2 h.$$

Since $f_n \rightarrow f$ pointwise and $\|f_n\|_\infty \leq \|f\|_\infty$, we obtain from the dominated convergence theorem that

$$\mathbb{E} \left[f \left(x + \int_0^h \sigma_s dW_s \right) \right] - f(x) \leq \frac{1}{2} \|f''\|_\infty \bar{\sigma}^2 h.$$

Taking the supremum over all $\sigma \in \Sigma$, replacing f by $-f$, and using the subadditivity of $S(h)$ yield

$$S(h)f - f \leq \frac{1}{2} \|f''\|_\infty \bar{\sigma}^2 h \quad \text{and} \quad -S(h)f + f \leq S(h)(-f) + f \leq \frac{1}{2} \|f''\|_\infty \bar{\sigma}^2 h.$$

Combining the previous two estimates implies that $f \in D_L^s$. □

The previous result can be seen as a regularity result, ensuring that $W^{2,\infty}$ -regularity of the initial value is preserved under the semigroup. The following proposition shows that the equality (5.2) extends from BUC^2 to $W^{2,\infty}$ in a pointwise sense almost everywhere.

Proposition 5.6. *Let $f \in W^{2,\infty}$. Then $S(t)f \in W^{2,\infty}$ for all $t \geq 0$. Moreover,*

$$\lim_{h \downarrow 0} \frac{S(h)f - f}{h} = \frac{1}{2} \max \{ \underline{\sigma}^2 f'', \bar{\sigma}^2 f'' \} \quad \text{almost everywhere,}$$

where the limit on the left-hand side exists pointwise almost everywhere.

Proof. Fix $f \in W^{2,\infty}$. As an application of Proposition 3.6 and Lemma 5.5, we obtain that $D_L^s = W^{2,\infty}$ is invariant under the semigroup S , i.e., $S(t)f \in W^{2,\infty}$ for all $t \geq 0$.

For $\sigma \in \Sigma$, we consider the stochastic integral $X_{\sigma,t} := \int_0^t \sigma_s dW_s$ for all $t \geq 0$. Since $f \in W^{2,\infty}$, it holds that $f' \in \text{Lip}_b$ and, by Rademacher's theorem, the function f' is differentiable almost everywhere, and the pointwise derivative coincides with the weak derivative $f'' \in L^\infty$ almost everywhere. Suppose that f' is differentiable at $x \in \mathbb{R}$ with $|f''(x)| \leq \|f''\|_\infty$, so that $f(x + \xi) =$

$f(x) + f'(x)\xi + \frac{1}{2}f''(x)\xi^2 + o(\xi^2)$ as $|\xi| \rightarrow 0$.¹ Then we obtain for every $h > 0$,

$$\begin{aligned} & \left| \frac{(S(h)f)(x) - f(x)}{h} - \frac{1}{2} \max\{\underline{\sigma}^2 f''(x), \bar{\sigma}^2 f''(x)\} \right| \\ &= \left| \frac{(S(h)f)(x) - f(x)}{h} - \sup_{\sigma \in \Sigma} \frac{1}{2} f''(x) \mathbb{E} \left[\frac{X_{\sigma,h}^2}{h} \right] \right| \\ &\leq \sup_{\sigma \in \Sigma} \left| \frac{1}{h} \mathbb{E} \left[f(x + X_{\sigma,h}) - f(x) - \frac{1}{2} f''(x) X_{\sigma,h}^2 \right] \right| \\ &= \sup_{\sigma \in \Sigma} \left| \frac{1}{h} \mathbb{E}[R(X_{\sigma,h})] \right| \quad \text{with } R(\xi) := f(x + \xi) - f(x) - f'(x)\xi - \frac{1}{2} f''(x)\xi^2. \end{aligned}$$

Note that $(X_{\sigma,t})_{t \geq 0}$ is a martingale, so that $\mathbb{E}[X_{\sigma,t}] = 0$ for all $t \geq 0$. Since the first derivative f' of f is Lipschitz with Lipschitz constant $\|f''\|_\infty$ and $|f''(x)| \leq \|f''\|_\infty$, it follows that

$$|R(\xi)| \leq \int_0^1 |(f'(x + \tau\xi) - f'(x))\xi - \tau\xi^2 f''(x)| \, d\tau \leq 2\|f''\|_\infty \xi^2 \quad \text{for all } \xi \in \mathbb{R},$$

and the Burkholder–Davis–Gundy inequality implies that there exists a constant $C > 0$, such that

$$\begin{aligned} \sup_{\sigma \in \Sigma} \left| \frac{1}{h} \mathbb{E}[R(X_{\sigma,h}) \mathbf{1}_{\{|X_{\sigma,h}| \geq \delta\}}] \right| &\leq \sup_{\sigma \in \Sigma} \frac{1}{h} \mathbb{E}[R(X_{\sigma,h})^2]^{1/2} \cdot \mathbb{P}(|X_{\sigma,h}| \geq \delta)^{1/2} \\ &\leq \frac{1}{h} \cdot C\bar{\sigma}^2 h \cdot \frac{\bar{\sigma}\sqrt{h}}{\delta} \leq \frac{C\bar{\sigma}^3\sqrt{h}}{\delta} \quad \text{for all } \delta > 0. \end{aligned}$$

Let $\varepsilon > 0$. Since $R(\xi) = o(\xi^2)$, there exists some $\delta > 0$ such that $R(\xi) \leq \varepsilon\xi^2$ for $|\xi| < \delta$. Hence,

$$\begin{aligned} \sup_{\sigma \in \Sigma} \left| \frac{1}{h} \mathbb{E}[R(X_{\sigma,h})] \right| &\leq \frac{C\bar{\sigma}^3\sqrt{h}}{\delta} + \sup_{\sigma \in \Sigma} \left| \frac{1}{h} \mathbb{E}[R(X_{\sigma,h}) \mathbf{1}_{\{|X_{\sigma,h}| < \delta\}}] \right| \\ &\leq \frac{C\bar{\sigma}^3\sqrt{h}}{\delta} + \varepsilon\bar{\sigma}^2. \end{aligned}$$

Letting $h \downarrow 0$, this shows that $\frac{(S(h)f)(x) - f(x)}{h} \rightarrow \frac{1}{2} \max\{\underline{\sigma}^2 f''(x), \bar{\sigma}^2 f''(x)\}$. The proof is complete. □

Appendix A. Some auxiliary results

In this section, we list some basic properties for convex operators and semigroups, which can be found, for example, in [13].

¹Indeed, since f' is differentiable at x , it holds that $\sup_{0 \leq \tau \leq 1} |f'(x + \tau\xi) - f'(x) - \tau\xi f''(x)| = o(\xi)$. Integrating w.r.t. τ yields $|\frac{f(x+\xi) - f(x)}{\xi} - f'(x) - \frac{1}{2}\xi f''(x)| \leq \int_0^1 |f'(x + \tau\xi) - f'(x) - \tau\xi f''(x)| \, d\tau = o(\xi)$.

Lemma A.1 ([13, Cor. A.4]). *Let $S: X \rightarrow X$ be a bounded and convex operator. Then S is Lipschitz on bounded subsets, i.e., for every $r > 0$, there exists some $L > 0$ such that $\|Sx - Sy\| \leq L\|x - y\|$ for all $x, y \in B(0, r)$.*

For the remainder of this subsection, let S be a convex C_0 -semigroup on X .

Lemma A.2 ([13, Cor. 2.4]). *Let $T > 0$ and $x_0 \in X$. Then there exist $L \geq 0$ and $r > 0$ such that*

$$\sup_{t \in [0, T]} \|S(t)y - S(t)z\| \leq L\|y - z\|$$

for all $y, z \in B(x_0, r)$.

Corollary A.3 ([13, Cor. 2.5]). *The map $[0, \infty) \rightarrow X, t \mapsto S(t)x$ is continuous for all $x \in X$.*

Proposition A.4 ([13, Prop. 2.7]). *Let $x \in X$ with*

$$\sup_{h \in (0, h_0]} \left\| \frac{S(h)x - x}{h} \right\| < \infty \quad \text{for some } h_0 > 0.$$

Then the map $[0, \infty) \rightarrow X, t \mapsto S(t)x$ is locally Lipschitz continuous, i.e., for every $T > 0$, there exists some $L_T \geq 0$ such that $\|S(t)x - S(s)x\| \leq L_T|t - s|$ for all $s, t \in [0, T]$.

Appendix B. Directional derivatives of convex operators

In this section, we provide some results on directional derivatives of convex operators.

Lemma B.1. *Let $(x_n)_{n \in \mathbb{N}}$ be a sequence in X . If $(y_n)_{n \in \mathbb{N}}$ and $(z_n)_{n \in \mathbb{N}}$ are decreasing sequences in X which are bounded from below such that $\|x_n - y_n\| \rightarrow 0$ and $\|x_n - z_n\| \rightarrow 0$, then $\inf_{n \in \mathbb{N}} y_n = \inf_{n \in \mathbb{N}} z_n$.*

Proof. Fix $\mu \in M$. Since μ is continuous on X , see e.g. [1, Thm. 9.6], one has

$$\mu(y_n - z_n) = \mu(y_n - x_n) + \mu(x_n - z_n) \rightarrow 0,$$

which shows that

$$\mu\left(\inf_{n \in \mathbb{N}} y_n\right) = \lim_{n \rightarrow \infty} \mu y_n + \lim_{n \rightarrow \infty} \mu(z_n - y_n) = \lim_{n \rightarrow \infty} \mu z_n = \mu\left(\inf_{n \in \mathbb{N}} z_n\right).$$

Since $\inf_{n \in \mathbb{N}} y_n, \inf_{n \in \mathbb{N}} z_n \in X_\delta$, and M separates the points of X_δ , it follows that $\inf_{n \in \mathbb{N}} y_n = \inf_{n \in \mathbb{N}} z_n$. □

Lemma B.2. *Let $S: X \rightarrow X$ be a convex monotone operator which is continuous from above. Then it has a unique monotone convex extension $S: X_\delta \rightarrow X_\delta$ which is continuous from above.*

Proof. For each $\mu \in M$, the convex monotone functional $\mu S: X \rightarrow \mathbb{R}$ is continuous from above. Thus, by [11, Lem. 3.9], it has a unique extension to a convex monotone functional $\mu S: X_\delta \rightarrow \mathbb{R}$ which is continuous from above.

Fix $x \in X_\delta$. For $(x_n)_{n \in \mathbb{N}}$ and $(y_n)_{n \in \mathbb{N}}$ in X with $x_n \downarrow x$ and $y_n \downarrow x$, one has

$$\begin{aligned} \mu\left(\inf_{n \in \mathbb{N}} Sx_n\right) &= \inf_{n \in \mathbb{N}} \mu Sx_n = \mu S\left(\inf_{n \in \mathbb{N}} x_n\right) = \mu S\left(\inf_{n \in \mathbb{N}} y_n\right) \\ &= \inf_{n \in \mathbb{N}} \mu Sy_n = \mu\left(\inf_{n \in \mathbb{N}} Sy_n\right). \end{aligned}$$

Hence, $Sx := \inf_{n \in \mathbb{N}} Sx_n$ is well defined as M separates the points of X_δ . Then S is convex and continuous from above as

$$\mu\left(\inf_{n \in \mathbb{N}} Sx_n\right) = \inf_{n \in \mathbb{N}} \mu Sx_n = \mu Sx$$

for every $(x_n)_{n \in \mathbb{N}}$ in X_δ with $x_n \downarrow x \in X_\delta$. Moreover, if \tilde{S} is another extension which is continuous from above, then $\tilde{S}x = \lim_{n \rightarrow \infty} \tilde{S}x_n = \lim_{n \rightarrow \infty} Sx_n = Sx$ for every $(x_n)_{n \in \mathbb{N}}$ in X with $x_n \downarrow x \in X_\delta$, which shows that such an extension is unique. □

Let $S: X \rightarrow X$ be a convex operator. Then the function

$$\mathbb{R} \setminus \{0\} \rightarrow X, \quad h \mapsto \frac{S(x + hy) - Sx}{h}$$

is increasing for all $x, y \in X$. Hence, for all $x \in X$, the operators

$$(B.1) \quad S'_+(x)y := \inf_{h>0} \frac{S(x + hy) - Sx}{h} \quad \text{and} \quad S'_-(x)y := \sup_{h<0} \frac{S(x + hy) - Sx}{h}$$

for $y \in X$ are well defined with values in \bar{X} since

$$S'_+(x)y = \inf_{n \in \mathbb{N}} \frac{S(x + h_n y) - Sx}{h_n} \in X_\delta$$

and

$$S'_-(x)y = \sup_{n \in \mathbb{N}} \frac{Sx - S(x - h_n y)}{h_n} \in -X_\delta$$

for every sequence $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ with $h_n \rightarrow 0$. The following properties follow directly from the definition.

Remark B.3. For every $x, y \in X$, it holds that

- (i) $S'_-(x)y = -S'_+(x)(-y)$,
- (ii) $S'_-(x)y \leq S'_+(x)y$,
- (iii) $S'_+(x)y = S'_-(x)y = Sy$ if S is linear.

If $S: X \rightarrow X$ is a convex monotone operator which is continuous from above, then by Lemma B.2, it has a unique convex monotone extension $S: X_\delta \rightarrow X_\delta$ which is continuous from above. Therefore, $S(x + hy) \in X_\delta$ for all $y \in X_\delta$ and $h > 0$. Hence, $S'_+(x)$ extends to

$$S'_+(x): X_\delta \rightarrow X_\delta, \quad y \mapsto \inf_{h>0} \frac{S(x + hy) - Sx}{h}$$

for all $x \in X$.

Lemma B.4. Let $S: X \rightarrow X$ be a convex monotone operator which is continuous from above. For every $x \in X$, the mapping $S'_+(x)$ has the following properties:

- (i) $S'_+(x)y \leq S_x y$ for all $y \in X_\delta$,
- (ii) $S'_+(x): X_\delta \rightarrow X_\delta$ is convex and positive homogeneous,
- (iii) $S'_+(x)$ is continuous from above,
- (iv) $\frac{S(x+h_n y_n) - Sx}{h_n} \downarrow S'_+(x)y$ for all sequences $(h_n)_{n \in \mathbb{N}}$ in $(0, \infty)$ and $(y_n)_{n \in \mathbb{N}}$ in X_δ which satisfy $h_n \downarrow 0$ and $y_n \downarrow y \in X_\delta$.

Proof. (i) For every $y \in X_\delta$, one has $S'_+(x)y \leq S(x + y) - S(x) = S_x(y)$.
 (ii) For $\varepsilon > 0$, $\mu \in M$, and $\lambda \in [0, 1]$, there exists some $h > 0$ such that

$$\begin{aligned} & \mu(\lambda S'_+(x)y_1 + (1 - \lambda)S'_+(x)y_2) + \varepsilon \\ & \geq \lambda \frac{\mu S(x + hy_1) - \mu S(x)}{h} + (1 - \lambda) \frac{\mu S(x + hy_2) - \mu S(x)}{h} \\ & \geq \frac{\mu S(x + h(\lambda y_1 + (1 - \lambda)y_2)) - \mu S(x)}{h} \\ & \geq \mu S'_+(x)(\lambda y_1 + (1 - \lambda)y_2). \end{aligned}$$

This shows that $S'_+(x)$ is convex on X_δ . Moreover, for $\lambda > 0$ and $y \in X_\delta$, it holds that

$$\begin{aligned} S'_+(x)(\lambda y) &= \inf_{h>0} \frac{S(x + \lambda hy) - Sx}{h} \\ &= \lambda \inf_{h>0} \left(\frac{S(x + \lambda hy) - Sx}{\lambda h} \right) = \lambda S'_+(x)y. \end{aligned}$$

(iii) For every $y_n \downarrow y$,

$$\begin{aligned} \inf_{n \in \mathbb{N}} S'_+(x)y_n &= \inf_{h > 0} \inf_{n \in \mathbb{N}} \frac{S(x + hy_n) - S(x)}{h} \\ &= \inf_{h > 0} \frac{S(x + hy) - S(x)}{h} = S'_+(x)y. \end{aligned}$$

(iv) Fix $\varepsilon > 0$, and $\mu \in M$. By definition of S'_+ and continuity from above of S , there exist $n_0, m_0 \in \mathbb{N}$ such that

$$\begin{aligned} \mu S'_+(x)y + 2\varepsilon &\geq \frac{\mu S(x + h_{n_0}y) - \mu Sx}{h_{n_0}} + \varepsilon \\ &\geq \frac{\mu S(x + h_{n_0}y_{m_0}) - \mu Sx}{h_{n_0}} \\ &\geq \frac{\mu S(x + h_{n_1}y_{n_1}) - \mu Sx}{h_{n_1}} \end{aligned}$$

for $n_1 := n_0 \vee m_0$. This shows that $\frac{S(x+h_n y_n)-Sx}{h_n} \downarrow S'_+(x)y$. The proof is complete. \square

Acknowledgements

We thank Daniel Bartl, Jonas Blessing, Liming Yin, and José Miguel Zapata García for helpful discussions and comments. Financial support through the German Research Foundation via CRC 1283 is gratefully acknowledged by the third author.

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