# Ergodic Properties of the Equilibrium Process Associated with Infinitely Many Markovian Particles

By

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## §C. Introduction

Consider a system of independent identically distributed Markov processes which have an invariant measure  $\lambda$ . It is known that if each process starts from each point of a  $\lambda$ -Poisson point process at time zero, these particles are  $\lambda$ -Poisson distributed at every later time t > 0 [1].

In the present paper we are concerned with the ergodic properties of the stationary processes obtained from such a system of particles, which is called the equilibrium process. Sinai's ideal gas model is a special example of the equilibrium processes [4]. In §1 we will give some preliminaries and the definition of the equilibrium process, and §2 is devoted to the study of the ergodic properties (metrical transitivity, mixing properties and pure nondeterminism) of the equilibrium processes. In §3 we will discuss the Bernoulli property in the strong sense of the shift flow  $\{\Theta_i\}_{-\infty < t < \infty}$ defined in §1. The shift flow induced by the equilibrium process is a factor flow of  $\{\Theta_t\}$ . In §4 we prove a central limit theorem. Finally the authors would like to express their hearty gratitude to Professor H. Tanaka for his valuable advice.

# §1. Preliminaries

Let  $(X, \mathscr{B}_X, \lambda)$  be a  $\sigma$ -finite measure space, and denote by  $\mathscr{K}(X)$  a

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family of all the counting measures on X, i.e. each element of  $\mathscr{K}(X)$  is an integer-valued measure with a countable set as its support.  $\mathscr{K}(X)$  is equipped with a  $\sigma$ -field  $\mathscr{G}$  which is generated by  $\{\rho \in \mathscr{K}(X) : \rho(A) = n\}, n \ge 0, A \in \mathscr{B}_X$ . An element  $\rho$  of  $\mathscr{K}(X)$  is represent by  $\rho = \sum_i \delta_{xi}$  where  $\delta_x(A) = 1$  if  $x \in A$  and  $\delta_x(A) = 0$  if  $x \in A$ .

**Definition 1.1.** Let  $\Pi_{\lambda}$  be a probability measure on  $(\mathscr{K}(X), \mathscr{G})$ .  $\Pi_{\lambda}$  is  $\lambda$ -Poisson point process if it satisfies the following conditions;

(1.1) for any disjoint system  $A_1, ..., A_n$  of  $\mathscr{B}_X$  such that  $\lambda(A_i) < +\infty_{i=1,...,n}$   $\rho(A_1), ..., \rho(A_n)$  are independent random variables on  $(\mathscr{K}(X), \mathscr{G}, \Pi_{\lambda})$  and  $\Pi_{\lambda}\{\rho; \rho(A_i) = n\} = \frac{\lceil \lambda(A_i) \rceil^n}{n!} \exp [-\lambda(A_i) \rceil, i = 1, ..., n.$ 

Here we summarize some elementary facts on  $\lambda$ -Poisson point process.

#### Lemma 1.2.

(a) For any  $\sigma$ -finite measure space  $(X, \mathscr{B}_X, \lambda)$  there exists a  $\lambda$ -Poisson point process.

(b) A probability measure  $\Pi_{\lambda}$  on  $(\mathscr{K}(X), \mathscr{G})$  is a  $\lambda$ -Poisson point process if and only if

(1.2)  $\int e^{-\langle \varphi, \rho \rangle} \Pi_{\lambda}(d\rho) = e^{-\langle 1-e^{-\varphi}, \lambda \rangle}$  i) for every non-negative measurable function  $\varphi$  on  $(X, \mathscr{B}_X)$ ,

and moreover (1.2) is equivalent to the following condition;

(1.3) 
$$\int e^{i \langle \varphi, \rho \rangle} \Pi_{\lambda}(d\rho) = e^{-\langle 1-e^{i\varphi, \lambda \rangle}} \text{ for every } \lambda \text{-integrable function } \varphi.$$

For each A of  $\mathscr{B}_X$ , denote by  $\mathscr{G}(A)$  the  $\sigma$ -field generated by  $\{\rho \in \mathscr{K}(X); \rho(B) = n\}, n \ge 0, B \in \mathscr{B}_X, B \subset A$ .

#### Lemma 1.3.

(a) If  $A_1, \ldots, A_n$  are mutually disjoint,  $\mathscr{G}(A_1), \ldots, \mathscr{G}(A_n)$  are mutually independent  $\sigma$ -fields w.r.t.  $\Pi_{\lambda}$ .

1) For a function  $\varphi$  and a measure  $\lambda < \varphi$ ,  $\lambda > = \int \varphi(x)\lambda(dx)$ .

(b) If  $\{A_n\} \subset \mathscr{B}_X$  is non-increasing and  $\bigcap_n A_n = \phi$ ,  $\{\mathscr{G}(A_n)\}$  is also non-increasing and  $\bigcap_{\mathcal{G}} \mathscr{G}(A_n) = \{\phi, \mathscr{K}(X)\} \pmod{\Pi_{\lambda}}$ .

Next, we define the equilibrium processes associated with Markovian particles.

Let X be a locally compact separable Hausdorff space and  $\mathscr{B}_X$  be the topological Borel field of X. Denote by  $\mathscr{W}$  the path space of X, that is, each element of  $\mathscr{W}$  is a X-valued right continuous function with left limit defined on  $(-\infty, \infty)$ , and define the shift operators  $\{\theta_t\}_{-\infty < t < \infty}$  of  $\mathscr{W}$  as usual;  $(\theta_t f)_s = f_{t+s}$  for each f of  $\mathscr{W}$ .

Put  $S = \mathscr{K}(X)$  and  $\mathscr{Q} = \mathscr{K}(\mathscr{W})$ . Denote by  $\{\mathscr{O}_t\}_{-\infty < t < \infty}$  the shift operators on  $\mathscr{Q}$  induced by the shift operators  $\{\vartheta_t\}_{-\infty < t < \infty}$  on  $\mathscr{W}$ , i.e.

(1.4) 
$$\Theta_t \omega = \sum_i \delta_{\theta_i f^i} \quad \text{if} \quad \omega = \sum \delta_{f^i}$$

Define S-valued process  $\{\xi_t(\omega)\}_{-\infty < t < \infty}$  on  $\Omega$  as follows;

(1.5) 
$$\boldsymbol{\xi}_t(\boldsymbol{\omega}) = \sum_i \delta_{f_i^i} \quad \text{if} \quad \boldsymbol{\omega} = \sum_i \delta_{f^i}.$$

Then  $\xi_t(\omega)$  is right continuous in t in a natural topology.

In our situation a motion of one particle is given as a Markov process on X and denote by  $\{P_t(x, dy)\}$  its transition probabilities.

## Assumption.

 $\{P_t(x, dy)\}\$  is a conservative Feller Markov process and have a Radon invariant measure  $\lambda$ , that is,  $\{P_t(x, dy)\}\$  induces a semi-group of contraction operators  $\{T_t\}\$  on  $C_{\infty}(X)$ , and  $\int T_t f(x)\lambda(dx) = \int f(x)\lambda(dx)\$  for every f of  $C_0(X)$ .<sup>2)</sup>

Under this assumption  $\{T_t\}$  is, also, a semi-group of contraction operators on  $L^2(X, \mathscr{B}_X, \lambda)$ .

**Lemma 1.4.** There is only one  $\sigma$ -finite measure Q on  $(\mathcal{W}, \mathcal{B}_{\mathcal{W}})^{3}$ such that

<sup>2)</sup>  $C_{\infty}(X)$  is the family of all the continuous functions vanishing at infinity, and  $C_0(X)$  is the family of all the continuous functions with compact supports.

<sup>3)</sup>  $\mathscr{B}_{\mathscr{W}}$  is the  $\sigma$ -algebra generated by all the cylindrical subsets of  $\mathscr{W}$ .

Tokuzo Shiga and Yoichiro Takahashi

(1.6) for 
$$-\infty < t_1 < t_2 < \cdots < t_n < +\infty$$
 and  $\{A_i\}_{i=1, 2\dots, n}$   
 $Q[f; f_{i_1} \in A_1, f_{i_2} \in A_2, \dots, f_{i_n} \in A_n]$   
 $= \int_{A_1} \lambda(dx_1) \int_{A_2} P_{t_2 - t_1}(x_1, dx_2) \cdots \int_{A_n} P_{t_n - t_{n-1}}, (x_{n-1}, dx_n)$ 

In particular Q is  $\{\theta_t\}$ -invariant.

Denote by  $\mathbb{B}$  the  $\sigma$ -field generated by  $\{\omega \in \mathcal{Q}; \omega(A) = n\}, n \ge 0, A \in \mathscr{B}_X$ and put  $\mathbb{P} = \Pi_Q$  (Q-Poisson point process). We consider  $(\mathcal{Q}, \mathbb{B}, \mathbb{P})$  as our basic probability space.

**Proposition 1.5.**  $\{\mathcal{Q}, \mathcal{B}, \mathcal{P}; \{\xi_t\}_{-\infty < t < \infty}\}$  is a right-continuous Markov stationary process with  $\Pi_{\lambda}$  as its absolute law.

Proof. It is sufficient to prove the following formula;

(1.7) for  $-\infty < t_1 < t_2 < \cdots < t_n < \infty$  and  $\{\varphi_i\} \ge 0$  measurable functions on X

$$\mathbb{E}[e^{-\langle \varphi_1, \xi_{t_1} \rangle} \cdots e^{-\langle \varphi_n, \xi_t \rangle}] = \mathbb{E}[e^{-\langle \varphi_1, \xi_{t_1} \rangle} \cdots e^{-\langle \varphi_{n-1}, \xi_{t_{n-1}} \rangle} e^{\langle \log T_{t_n-t_{n-1}} e^{-\varphi_n, \xi_{t_{n-1}} \rangle}].$$

= the right-hand side of (1.7).

In particular  $\mathbb{E}\left[e^{-\langle \varphi, \xi_t \rangle}\right] = \exp{-\langle 1 - e^{-\varphi}, \lambda \rangle}.$ 

Definition 1.6. The Markov stationary process  $(\mathcal{Q}, \mathcal{B}, \mathcal{P}; \{\xi_t\}_{-\infty < t < \infty})$ 4) E denotes the expectation by P.

508

is called the equilibrium process associated with  $[\{T_t\}, \lambda]$ .

The following calculations are immediate from (1.7).

Proposition 1.7.

(i) 
$$\mathbb{E}[e^{-\langle \varphi, \xi_t \rangle} | \xi_s] = e^{\langle \log T_{t-s}e^{-\varphi}, \xi_s \rangle}$$
 for  $\forall \varphi \ge 0$  and  $s < t$ .  
(ii)  $\mathbb{E}[\langle \varphi, \xi_t \rangle | \xi_s] = \langle T_{t-s}\varphi, \xi_s \rangle$  for  $\forall \varphi \in L^2(X, \mathscr{B}_X, \lambda)$ .  
(iii)  $\mathbb{E}[\langle \varphi, \xi_t \rangle \langle \psi, \xi_t \rangle | \xi_s] = \langle T_{t-s}\varphi, \xi_s \rangle \langle T_{t-s}\psi, \xi_s \rangle$ 

$$\begin{split} & \text{for } \forall \varphi, \psi \in L^2(X, \mathscr{B}_X, \lambda) \cap L^1(X, \mathscr{B}_X, \lambda). \end{split}$$

## §2. Ergodic Properties

In this section we discuss the ergodic properties of the equilibrium processes.

**Proposition 2.1.** The following (i)  $\sim$  (iii) are equivalent.

(i)  $(\Omega, \mathbb{B}, \mathbb{P}; \{\xi_t\}_{-\infty < t < \infty})$  is metrically transitive.

(ii) 
$$\lim_{t \to \infty} \frac{1}{t} \int_0^t \int_K P_s(x, K) \lambda(dx) ds = 0 \quad for every compact subset K of X.$$

(iii) 
$$\lim_{t \to \infty} \frac{1}{t} \int_0^t (T_s f, g)_{L^2(\lambda)} ds = 0 \qquad \text{for all } f \text{ and } g \text{ of } L^2(X, \lambda)$$

*Proof.* It is easy to show the equivalence of (ii) and (iii). Moreover (i) is equivalent to

$$(2.1) \quad \lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} \mathbb{E}\left[e^{-\frac{n}{2} \langle \varphi_{i}, \xi_{s_{i}} \rangle} e^{-\frac{m}{2} \langle \varphi_{i}, \xi_{i_{j}+n} \rangle}\right] du$$
$$= \mathbb{E}\left[e^{-\frac{n}{2} \langle \varphi_{i}, \xi_{s_{i}} \rangle}\right] \mathbb{E}\left[e^{-\frac{m}{2} \langle \varphi_{j}, \xi_{r_{j}} \rangle}\right],$$
for any  $-\infty \langle s_{1} \langle s_{2} \langle \cdots \langle s_{n} \langle \infty, -\infty \langle r_{1} \langle r_{2} \langle \cdots \langle r_{m} \rangle$  and any  $\{\varphi_{i}\}_{i=1,\dots,n}, \{\psi_{j}\}_{j=1,\dots,m}$  of  $C_{0}^{+}(X)$ .

However it suffices to prove (2.1) for m=1 because of the Markov property of  $\{\xi_t\}$ . For  $s_n < r+u$ ,

5)  $C_0^+(X)$  is the family of non-negative elements of  $C_0(X)$ .

$$\begin{split} \mathbf{E} \begin{bmatrix} e^{-\sum_{1}^{n} < \xi_{i}, \xi_{s_{i}} > e^{-<\phi, \xi_{r+u} > j}} \end{bmatrix} \\ &= \exp - \int \lambda(dx)(1 - e^{-\varphi_{1}}T_{s_{2}-s_{1}}e^{-\varphi_{2}} \cdots e^{-\varphi_{n}}T_{r+u-s_{n}}e^{-\phi}) \\ &= \exp - \int \lambda(dx)((1 - e^{-\varphi_{1}}T_{s_{2}-s_{1}}e^{-\varphi_{2}} \cdots T_{s_{n}-s_{n-1}}e^{-\varphi_{n}}) \\ &+ e^{-\varphi_{1}}T_{s_{2}-s_{1}}e^{-\varphi_{2}} \cdots T_{s_{n}-s_{n-1}}e^{-\varphi_{n}}T_{r+u-s_{n}}(1 - e^{-\phi})) \\ &= \mathbf{E} \begin{bmatrix} e^{-\sum_{1}^{n} < \varphi_{i}, \xi_{s_{i}} > j} \end{bmatrix} \mathbf{E} \begin{bmatrix} e^{-<\phi, \xi_{r} > j} \\ e^{-\varphi_{1}}T_{s_{2}-s_{1}} \cdots T_{s_{n}-s_{n-1}}e^{-\varphi_{n}} \end{bmatrix} T_{r+u-s_{n}}(1 - e^{-\phi}). \end{split}$$

Therefore,

(2.2) 
$$\lim_{t\to\infty}\frac{1}{t}\int_0^t E\left[e^{-\sum\limits_{u=1}^n <\varphi_i,\,\xi_{s_u}} > e^{-<\phi,\,\xi_{r+u}}\right]du = E\left[e^{-\sum\limits_{1}^n <\varphi_i,\,\xi_{s_u}} > \right]E\left[e^{-<\phi,\,\xi_r}\right]$$

is equivalent to

(2.3) 
$$\lim_{t \to \infty} \frac{1}{t} \int_0^t \exp\left[\int \lambda(dx) \left[I - e^{-\varphi_1} T_{s_2 - s_1} e^{-\varphi_2} \cdots T_{s_n - s_{n-1}} e^{-\varphi_n}\right] \times T_u(1 - e^{-\varphi_1})\right] du = 1$$

or

(2.4) 
$$\lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} \left[ \int \lambda(dx) \left[ I - e^{-\varphi_{1}} T_{s_{2}-s_{1}} e^{-\varphi_{2}} \cdots T_{s_{n}-s_{n-1}} e^{-\varphi_{n}} \right] T_{u}(1 - e^{-\varphi}) \right] du = 0.$$

Note  $1 - e^{-\varphi_1} T_{s_2 - s_1} e^{-\varphi_2} \cdots T_{s_n - s_{n-1}} e^{-\varphi_n} \in L^2(X, \lambda)$  and  $(1 - e^{-\phi}) \in L^2(X, \lambda)$ .

Hence (iii) implies (i). On the other hand it is obvious (2.4) implies (ii) by putting  $n=1, \varphi_1=\psi \in C_0^+(X)$ .

Corollary 2.2. If {ξ<sub>t</sub>}<sub>-∞<t<∞</sub> is metrically transitive, then λ(X) = ∞.
Proposition 2.3. The following three statements are equivalent.
(i) (Ω, B, P; {ξ<sub>t</sub>}<sub>-∞<t<∞</sub>) has the mixing property.

510

Ergodic Properties of the Equilibrium Processes

(ii) 
$$\lim_{t \to \infty} \int_{K} \lambda(dx) P_{t}(x, K) = 0 \quad \text{for every compact subset } K \text{ of } X.$$
  
(iii) 
$$\lim_{t \to \infty} (T_{t}f, g)_{L^{2}(X, \lambda)} = 0 \quad \text{for all } f \text{ and } g \text{ of } L^{2}(X, \lambda).$$

Since the proof of Proposition 2.3 can be carried out by the similar method as Proposition 2.1, it is omitted.

Next, we consider the pure non-determinism of the equilibrium processes. In general, let  $(\Omega, \mathcal{F}, P; \{z_t\}_{-\infty < t < \infty})$  be a Markov stationary process on X associated with  $\{P_t(x, dy), \mu(dx)\}$ , where  $P_t(x, dy)$  is a transition probability measure and  $\mu$  is an invariant probability measure. Then the following criterion for the pure non-determinism is applicable.

**Lemma 2.4.**  $(\Omega, \mathcal{F}, P; \{z_t\}_{-\infty < t < \infty})$  is purely non-deterministic i.e.  $\bigcap_{t} \mathcal{F}_t(z) = \{\phi, \Omega\} \pmod{P}$  where  $\mathcal{F}_t(z)$  is the  $\sigma$ -field generated by  $\{z_s; s \le t\}$ , if and only if

(2.5) 
$$\lim_{t\to\infty} \int \left[ \int P_t(x, dy) f(y) - \int \mu(dy) f(y) \right]^2 \mu(dx) = 0 \quad for \quad \forall f \in L^2(X, \mu).$$

This lemma can be found in [6].

**Proposition 2.5.** The following three statements are equivalent.

- (i)  $(\Omega, B, P; \{\xi_t\}_{-\infty < t < \infty})$  is purely non-deterministic.
- (ii)  $\lim_{t \to \infty} \int_X \lambda(dx) [P_t(x, K)]^2 = 0 \quad \text{for every compact subset } K \text{ of } X.$ (iii)  $\lim_{t \to \infty} ||T_t f||_{L^2(X, \lambda)} = 0 \quad \text{for every } f \text{ of } L^2(X, \lambda).$

Proof. By Lemma 2.4 (i) is equivalent to

(2.6) 
$$\lim_{t\to\infty} \mathbf{E}[(\mathbf{E}[e^{-\langle\varphi,\xi_t\rangle}|\xi_0] - \mathbf{E}[e^{-\langle\xi_0,\varphi\rangle}])^2] = 0 \quad for \ \forall\varphi \in C_0^+(X).$$

Using Proposition 1.7 and Poisson properties, we have

$$\begin{split} E[(E[e^{-\langle\varphi,\xi_{l}\rangle}|\xi_{0}] - E[e^{-\langle\xi_{0},\varphi\rangle}])^{2}] &= E[(e^{\langle \log T_{l}e^{-\varphi},\xi_{0}\rangle} - e^{-\langle 1-e^{-\varphi},\lambda\rangle})^{2}] \\ &= E[e^{\langle \log (T_{l}e^{-\varphi})^{2},\xi_{0}\rangle} - e^{-2\langle 1-e^{-\varphi},\lambda\rangle}] = e^{-\langle 1-(T_{l}e^{-\varphi})^{2},\lambda\rangle} - e^{-2\langle 1-e^{-\varphi},\lambda\rangle} \\ &= (e^{\langle (T_{l}(1-e^{-\varphi}))^{2},\lambda\rangle} - 1)e^{-2\langle 1-e^{-\varphi},\lambda\rangle}. \end{split}$$

In the last equality we used  $< T_t(1-e^{-\varphi}), \ \lambda > = < 1-e^{-\varphi}, \ \lambda >$ . Therefore

the equivalence of (2.6) and the statement (ii) is obvious. Moreover the equivalence of (ii) and (iii) is trivial.

**Proposition 2.6.**  $(\Omega, \mathbb{B}, \mathbb{P}; \{\xi_t\}_{-\infty < t < \infty})$  is purely non-deterministic if and only if

 $E[\xi_t | \xi_0]$  converges to  $\lambda$  vaguely in probability, i.e. for every  $\varphi$  of  $C_0(X)$   $E[ < \varphi, \xi_t > | \xi_0]$  converges to  $< \varphi, \lambda >$  in probability.

Proof. By Proposition 1.7 and Poisson properties we have

 $\boldsymbol{E}[(\boldsymbol{E}[\langle\varphi,\xi_t\rangle|\xi_0]-\langle\varphi,\lambda\rangle)^2] = \langle (T_t\varphi)^2,\lambda\rangle = ||T_t\varphi||_{L^2(X,\lambda)}^2.$ 

Therefore Proposition 2.6 follows from Proposition 2.5.

**Remark 2.7.** If  $\{T_t\}$  has no finite invariant measure, the corresponding equilibrium process is metrically transitive.

**Remark 2.8.** If the equilibrium process associated with  $[\{T_t\}, \lambda]$  is metrically transitive and  $\{T_t\}$  are symmetric on  $L^2(X, \lambda)$ , then it is purely non-deterministic.

**Remark 2.9.** The equilibrium process associated with uniform motions on  $\mathbb{R}^n$  are mixing, but not purely non-deterministic. However the equilibrium processes associated with all the additive processes on  $\mathbb{R}^n$  except uniform motions are purely non-deterministic.

**Remark 2.10.** Let  $(\mathcal{Q}, \mathcal{F}, P_x, \{x_t\}_{t\geq 0})$  be a Hunt Markov process corresponding to  $\{T_t\}$ . If the equilibrium process associated with  $[\{T_t\}, \lambda]$ is metrically transitive, for almost all x (w.r.t.  $\lambda$ ) and any compact subset  $K, P_x[\omega; \tau_{K^c} < +\infty] = 1$ , where  $\tau_{K^c}$  denote the first hitting time for  $K^c$ .

## §3. The Bernoulli Property of the Shifs Flow

It is easy to see that  $\{\mathcal{O}_t\}_{-\infty < t < \infty}$ , which is defined by (1.4) in §1, is a flow on the probability space  $(\mathcal{Q} = \mathscr{K}(\mathscr{W}), \mathbb{B}, \mathbb{P} = \Pi_Q)$ . So, we discuss the Bernoulli property in the strong sense of the flow  $\{\mathcal{O}_t\}_{-\infty < t < \infty}$ .

**Definition 3.1.**  $(\Omega, \mathbb{B}, \mathbb{P}; \{\Theta_t\}_{-\infty < t < \infty})$  is called Bernoulli flow if it

satisfies the following conditions;

The following lemma is essentially due to H. Tanaka, and is a generalization of the Sinai-Volkoviskii's result on the K-property of the ideal gas model  $\lceil 4 \rceil$ .

**Lemma 3.2.** Suppose that there exists a real measurable function  $\tau(f)$ on the  $\sigma$ -finite measure space  $(\mathcal{W}, \mathcal{B}_{\mathcal{W}}, Q)$  such that for almost all f(Q)

(a) 
$$-\infty < \tau(f) < +\infty$$
  
(b)  $\tau(f) = t + \tau(\theta_t f)$  for all t of  $R^{1.6^{1}}$ 

Then,  $(\Omega, \mathbb{B}, \mathbb{P}; \{\Theta_t\}_{-\infty < t < \infty})$  is a Bernoulli flow.

*Proof.* May assume every f of  $\mathscr{W}$  satisfies the conditions (a), (b). Put  $\mathscr{W}_r^s = \{f; -r \ge \tau(f) > -s\}$ . Then  $\theta_t \mathscr{W}_r^s = \{f; -r - t \ge \tau(f) > -s - t\}$  by the condition (b). Obviously we have

(3.2) 
$$\theta_t \mathscr{W}_r^s = \mathscr{W}_{r+t}^{s+t}, \qquad \bigcup_{r < s} \mathscr{W}_r^s = \mathscr{W}$$

So, we denote by  $\zeta_r^s$  the  $\sigma$ -subfield  $\mathscr{G}(\mathscr{W}_r^s)$  which is generated by  $\{\omega; \omega(A) = n\}$ ,  $n \ge 0$ ,  $A \in \mathscr{B}_{\mathscr{W}}$ ,  $A \subset \mathscr{W}_r^s$ . Noting  $\mathscr{O}_t\{\omega; \omega(A) = n\} = \{\omega; \omega(\theta_t A) = n\}$ , we can see  $\zeta_{r+t}^{s+t} = \mathscr{O}_t \circ \zeta_r^s = \mathscr{G}(\theta_t \mathscr{W}_r^s)$ . Therefore  $\zeta_r^s$  satisfies the conditions (i)  $\sim$  (iv) in Definiton 3.1 by Lemma 1.3.

**Proposition 3.3.** Suppose that  $\{T_t\}$  is transient in following sense;  $\int_0^{\infty} (T_t \varphi, \varphi)_{L^2(X,\lambda)} dt < +\infty$  for every  $\varphi$  of  $C_0^+(X)$ . Then,  $(\Omega, \mathbb{B}, \mathbb{P}; \{\Theta_t\})$  is a Bernoulli flow.

Proof. First, we will show

<sup>6)</sup> Such a random time  $\tau(w)$  is called *L*-time which was introduced by M. Nagasawa [7].

(3.3)  $\int_{-\infty}^{\infty} \varphi(f_s) ds < +\infty$  for almost all f(Q) for every  $\varphi$  of  $C_0^+(X)$ . For any  $\varphi$  and  $\psi$  of  $C_0^+(X)$ ,

$$\begin{split} \int_{\mathscr{W}} \left[ \int_{-\infty}^{\infty} \varphi(f_s) \, ds \cdot \psi(f_0) \right] & Q(df) = \int_{\mathscr{W}} \left[ \int_{0}^{\infty} \varphi(f_s) \, ds \ \psi(f_0) \right] & Q(df) \\ & + \int_{\mathscr{W}} \left[ \int_{-\infty}^{0} \varphi(f_s) \, ds \ \psi(f_0) \right] & Q(df) \\ & = \int_{0}^{\infty} (T_s \varphi, \psi)_{L^2(X,\lambda)} \, ds + \int_{0}^{\infty} (\varphi, \ T_s \psi)_{L^2(X,\lambda)} \, ds < + \infty \end{split}$$

Therefore (3.3) holds.

Next, choose a countable sequence  $\{\varphi_n\}$  of  $C_0^+(X)$  such that  $\bigcup_n \{x \in X; \varphi_n(x) > 0\} = X$ . Putting  $\mathscr{W}_1 = \{f; 0 < \int_{-\infty}^{\infty} \varphi_1(f_s) ds < +\infty\}, \theta_t \mathscr{W}_1 = \mathscr{W}_1$ . And define  $\mathscr{W}_{n+1}$  by  $\{f; 0 < \int_{-\infty}^{\infty} \varphi_{n+1}(f_s) ds < +\infty\} \setminus \mathscr{W}_n$ . Thus we have a sequence of disjoint subsets of  $\mathscr{W}$  which are  $\{\theta_t\}$ -invariant. So define  $\tau(f) = \sup\{t; \int_{-\infty}^t \varphi_n(f_u) du \le \frac{1}{2} \int_{-\infty}^\infty \varphi_n(f_u) du\}$  if  $f \in \mathscr{W}_n$ . Then we have  $\{f; -\infty < \tau(f) < +\infty\} = \bigcup_n \mathscr{W}_n = \mathscr{W} \pmod{Q}$ , and if  $f \in \mathscr{W}_n \quad \theta_s f \in \mathscr{W}_n$  and  $\tau(\theta_s f) = \sup\{t; \int_{-\infty}^t \varphi_n(f_{u+s}) du \le \frac{1}{2} \int_{-\infty}^\infty \varphi_n(f_u) du\} = \tau(f) - s$ . Therefore  $\tau(f)$  satisfies the conditions of Lemma 3.2.

**Remark 3.4.** The equilibrium process  $\{\xi_t\}$  induces a factor flow of  $\{\Theta_t\}$ . Since a Bernoulli flow  $\{\Theta_t\}$  in the sense of (3.1) is a Bernoulli flow in the weak sense (i.e. the automorphism  $\Theta_t$  is Bernoulli for each  $t \neq 0$ ), the shift flow induced by  $\{\xi_t\}$  is also a Bernoulli flow in the weak sense by the theorem of Ornstein. [2]. But, perhaps, it may be a Bernoulli flow in the sense of (3.1).

**Remark 3.5.** In the ideal gas model of Sinai-Volkoviskii [4], the path space  $\mathscr{W}$  is identified to  $\mathbb{R}^n \times \mathbb{R}^n$  and  $\zeta_r^s$  in (3.1) is the  $\sigma$ -algebra generated by the functions  $\omega \longrightarrow \omega(E)$ ,  $E \subset V_r^s$ , where  $V_r^s = \{f = (q_1, ..., q_n, v_1, ..., v_n) \in \mathbb{R}^n \times \mathbb{R}^n | -r \ge \sum_{i=1}^n q_i v_i \ge -s\}$ . In this case the function  $\tau(f)$  in Lemma 3.2 is given by the last exit time of the set  $V_0^\infty$  for each  $f \in \mathbb{R}^n \times \mathbb{R}^n$ .

514

## §4. A Central Limit Theorem

Finally we will prove a central limit theorem related to the equilibrium process. Denote by  $G\varphi(x) = \int_0^\infty T_t \varphi(x) dt$  if the integral is well-defined.

**Proposition 4.1.** Consider any function  $\varphi \in L^2(X, \lambda)$  which satisfies  $(G|\varphi|, |\varphi|)_{(L^2X,\lambda)} < +\infty$ , and  $(G(|\varphi|G|\varphi|), |\varphi|)_{L^2(X,\lambda)} < +\infty$ . Then

$$\lim_{t \to \infty} \mathbb{P}\left[\omega; \alpha < \frac{\int_{0}^{t} <\varphi, \xi_{s} > ds - t <\varphi, \lambda >}{\sqrt{2(\varphi, G\varphi)_{L^{2}(\lambda)} \cdot t}} < \beta\right]$$
$$= \frac{1}{\sqrt{2\pi}} \int_{\alpha}^{\beta} e^{-\frac{x^{2}}{2}} dx \text{ for } \forall \alpha < \forall \beta.$$

Proof. It suffices to show

(4.1) 
$$\lim_{t \to \infty} \mathbb{E} \left[ \exp iz \frac{1}{\sqrt{t}} \left( \int_0^t \langle \varphi, \hat{\varsigma}_s \rangle ds - t \langle \varphi, \lambda \rangle \right) \right]$$
$$= \exp(-z^2(\varphi, G\varphi)_{L^2(X,\lambda)}).$$

$$\begin{split} \varPhi(f) &= \int_0^t \varphi(f_s) \, ds \text{ is a function on } \mathscr{W} \text{ and satisfies } < \varPhi, \, \omega > = \int_0^t < \varphi, \, \xi_s(\omega) > ds. \\ \mathbb{E}[\exp iz \int_0^t < \varphi, \, \xi_s > ds] &= \mathbb{E}[e^{iz < \varPhi, \, \omega >}] = \exp \int_{\mathscr{W}} (e^{iz \, \varPhi(f)} - 1) Q(df) \text{ by Lemma} \\ 1.2. \text{ Thus we have} \end{split}$$

(4.2) 
$$\mathbb{E}\left[\exp iz \frac{1}{\sqrt{t}} \left( \int_{0}^{t} \langle \varphi, \xi_{s} \rangle ds - t \langle \varphi, \lambda \rangle \right) \right]$$

$$= \exp\!\!\int_{\mathscr{W}} (e^{\frac{iz}{\sqrt{t}} \mathscr{G}(f)} - 1 - iz\sqrt{t} < \varphi, \lambda >) Q(df).$$

Noting  $e^{ix} - 1 - ix - \frac{(ix)^2}{2} = O(|x|^3)$ ,

(4.3) 
$$\int_{\mathscr{W}} (e^{\frac{iz}{\sqrt{t}} \mathscr{O}(f)} - 1 - iz\sqrt{t} < \varphi, \lambda >) Q(df)$$

$$\begin{split} &= \Bigl(\frac{iz}{\sqrt{t}} - \int_{\mathcal{W}} \varPhi(f) Q(df) - iz\sqrt{t} < \varphi, \ \lambda > \Bigr) + -\frac{1}{2} - \int_{\mathcal{W}} \Bigl(\frac{iz}{\sqrt{t}} - \varPhi(f) \Bigr)^2 Q(df) \\ &+ O\Bigl( \Bigl| \int_{\mathcal{W}} \Bigl(\frac{z}{\sqrt{t}} - \varPhi(f) \Bigr)^3 Q(df) \Bigr| \Bigr). \end{split}$$

The first term vanishes because of  $\int_{\mathcal{W}} \Phi(f)Q(df) = \int_0^t \left[ \int_{\mathcal{W}} \varphi(f_s)Q(df) \right] ds$  $= t < \varphi, \lambda > .$ 

$$\begin{split} \int_{\mathscr{W}} \boldsymbol{\varPhi}(f)^2 Q(df) &= \int_0^t du \int_0^t ds \int_{\mathscr{W}} \varphi(f_s) \varphi(f_u) Q(df) \\ &= 2 \int_0^t ds \int_0^s du \int_{\mathscr{W}} \varphi(f_s) \varphi(f_u) Q(df) \\ &= 2 \int_0^t ds \int_0^s dv(\varphi, T_v \varphi). \end{split}$$

Therefore the second term of the right-hand side of (4.3) converges to  $-z^2(G\varphi,\varphi)_{L^2(X,\lambda)}$ . By the similar calculation,

$$\left| \int \mathcal{\Phi}(f)^{3} Q(df) \right| = 6 \left| \int_{0}^{t} \int_{0}^{s} \int_{0}^{s-u} (T_{v} \varphi T_{u} \varphi, \varphi)_{L^{2}(\lambda)} du \, dv \, ds \right|$$
$$\leq 6t (G(|\varphi|G|\varphi|), |\varphi|)_{L^{2}(\lambda)}.$$

Therefore the third term converges to zero. Thus, we can complete the proof of Proposition 4.1.

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