

# Stability of Kähler Metrics in Deformations of Non-Compact Complex Manifolds of Dimension Two

*Dedicated to Professor S. Nakano on his 60th birthday*

By

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## Introduction

In deformations of non-compact complex manifolds, not much is known about the stability theorem. As in deformations of compact complex manifolds (see [5]), it seems to be a fundamental problem to establish some stability theorem in the non-compact case. In this paper, we prove the following stability theorem.

**Main Theorem.** *Suppose  $\pi: \mathcal{M} \rightarrow B$  is a differentiable family of non-compact complex manifolds of dimension two over a ball  $B$  centered at the origin of  $\mathbf{R}^m$  and the fibre  $M_0 = \pi^{-1}(0)$ ,  $t=0 \in B$ , is provided with a Kähler metric. Then for any relatively compact domain  $X_0$  of  $M_0$ , any sufficiently small deformation  $X_t \subset M_t = \pi^{-1}(t)$ ,  $t \in B$ , of  $X_0$  admits a Kähler metric. Moreover for given any Kähler metric on  $M_0$ , we can choose a Kähler metric on each domain  $X_t$  which depends differentiably on  $t$  and coincides on  $X_0$  with the given Kähler metric.*

In the case  $\pi: \mathcal{M} \rightarrow B$  being a differentiable family of compact complex manifolds of arbitrary dimension, the Main Theorem was proved by Kodaira and Spencer for  $M_t$  using an elliptic differential operator of fourth order ([5]). On the other hand, in the case  $\dim_{\mathbb{C}} M_t = 1$ , the Main Theorem is more or less known as a special case of the pseudo-rigidity of Stein manifolds of arbitrary dimension ([1]). Our method of the proof is based on the theory of elliptic differential equations of second order on bounded domains with smooth bound-

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ary. But our method can not apply to the case  $\dim_{\mathbb{C}} M_t \geq 3$ .

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### § 1. Preliminaries

Let  $\pi: \mathcal{M} \rightarrow B$  be a differentiable family of non-compact complex manifolds of dimension  $n$  over a ball  $B$  centered at the origin of  $\mathbb{R}^m$  where  $\pi$  is a surjective differentiable map of maximal rank. We denote  $M_t = \pi^{-1}(t)$  for  $t \in B$ . Let  $\pi: \mathcal{X} \rightarrow B$  be a differentiable family of bounded domains with smooth boundary i.e. each domain  $X_t = \pi^{-1}_{\mathcal{X}}(t)$  is relatively compact in  $M_t$  and its boundary  $\partial X_t$  is defined by a real valued  $C^\infty$ -function  $h_t$  on  $M_t$  depending differentiably on  $t$  in such a way that  $X_t = \{h_t > 0\}$  and the gradient of  $h_t$  nowhere vanishes on  $\partial X_t$ . Then replacing each  $M_t$  by a relatively compact neighborhood of  $\bar{X}_t = X_t \cup \partial X_t$  and shrinking  $B$  arbitrarily, we can assume that there exists a diffeomorphism  $f: \mathcal{M} \rightarrow M_0 \times B$  such that i)  $p \circ f = \pi$  ( $p: M_0 \times B \rightarrow B$ ) ii) each restriction  $f_t$  of  $f$  onto  $M_t$  yields a diffeomorphism from  $M_t$  onto  $M_0$  and  $f_0 = \text{identity}$  iii) each  $f_t$  maps  $\partial X_t$  diffeomorphically onto  $\partial X_0$ . We set  $f_{st} = f_s^{-1} \circ f_t$  for  $s$  and  $t \in B$ . From now on, we fix the above diffeomorphism  $f$ .

We denote by  $\Theta \rightarrow \mathcal{M}$  the complex vector bundle of holomorphic tangent vectors along the fibres of  $M$ . We denote by  $\Theta^*$ ,  $\bar{\Theta}$  and  $\wedge^p \Theta$ , the dual, the conjugate and  $p$ -tuple exterior product of  $\Theta$ . Let  $\Theta^*(p, q) = (\wedge^p \Theta^*) \wedge (\wedge^q \bar{\Theta}^*)$  and let  $\Theta_t^*(p, q)$  be the restriction of  $\Theta^*(p, q)$  to the fibre  $M_t$ . We denote by  $C^{p,q}(M_t)$  (resp.  $C^{p,q}(X_t)$ ) the space of sections of class  $C^\infty$  of  $\Theta_t(p, q)$  over  $M_t$  (resp.  $X_t$ ) and set  $C^{p,q}(\bar{X}_t) = \text{Image}(C^{p,q}(M_t) \rightarrow C^{p,q}(X_t))$ . We denote by  $C^{p,q}(\mathcal{M})$  (resp.  $C^{p,q}(\mathcal{X})$ ) the space of sections of class  $C^\infty$  of  $\Theta^*(p, q)$  over  $\mathcal{M}$  (resp.  $\mathcal{X}$ ) and set  $C^{p,q}(\bar{\mathcal{X}}) = \text{Image}(C^{p,q}(\mathcal{M}) \rightarrow C^{p,q}(\mathcal{X}))$ .

Now we introduce hermitian metrics  $\{ds_t^2\}_{t \in B}$  on the fibres  $M_t$  which depend differentiably on  $t$  and from now on we fix this family of hermitian metrics. Then the inner product  $(\ , \ )_t$  on the space  $C^{p,q}(\bar{X}_t)$  is defined by  $ds_t^2$  as usual. Let  $L^{p,q}(X_t)$  be the Hilbert space obtained by completing the space of sections in  $C^{p,q}(X_t)$  with compact supports under the norm  $\| \ \|_t = (\ , \ )_t$ . Let  $d_t$ ,  $\partial_t$  and  $\bar{\partial}_t$  be the  $d$ -operator, the  $\partial$ -operator and the  $\bar{\partial}$ -operator on  $M_t$  with  $d_t = \partial_t + \bar{\partial}_t$ . We denote by  $\vartheta_t$  the formal adjoint operator of  $\bar{\partial}_t$ . We denote again by  $\bar{\partial}_t$  the closed maximal extension of the original  $\bar{\partial}_t$  and denote by  $\bar{\partial}_t^*$  the adjoint operator of  $\bar{\partial}_t$  in the Hilbert spaces  $L^{p,q}(X_t)$  respec-

tively. Moreover we consider the restricted Laplace-Beltrami operator  $L_t = \bar{\partial}_t \bar{\partial}_t^* + \bar{\partial}_t^* \bar{\partial}_t$  in the spaces  $L^{p,q}(X_t)$ . These operators are densely defined closed operators. For a given densely defined operator  $T: L^{p,q}(X_t) \rightarrow L^{r,s}(X_t)$ , we denote the domains, ranges and nullities of  $T$  and its adjoint operator  $T^*$  by  $D_T^{p,q}, D_{T^*}^{r,s}, R_T^{p,q}, R_{T^*}^{r,s}, N_T^{p,q}$  and  $N_{T^*}^{r,s}$ .

We define the subspace  $B^{p,q}(\bar{X}_t)$  of  $C^{p,q}(\bar{X}_t)$  by

$$B^{p,q}(\bar{X}_t) := \{\varphi_t \in C^{p,q}(\bar{X}_t) \mid \partial_t h_t \wedge *_t \varphi_t = 0 \text{ on } \partial X_t\}$$

where  $*$  is the star operator with respect to  $ds_t^2$ . The space  $B^{p,q}(\bar{X}_t)$  describes the boundary condition of the  $\bar{\partial}$ -Neumann problem as follows (see [2] (1.3.2) and (1.3.5) Propositions).

$$(1.1) \quad C^{p,q}(\bar{X}_t) \cap D_{L_t}^{p,q} = \{\varphi_t \in B^{p,q}(\bar{X}_t) \text{ and } \bar{\partial}_t \varphi_t \in B^{p,q+1}(\bar{X}_t)\}$$

and  $L_t = \square_t$  on  $C^{p,q}(\bar{X}_t) \cap D_{L_t}^{p,q}$ , where  $\square_t = \bar{\partial}_t \vartheta_t + \vartheta_t \bar{\partial}_t$  is the Laplace-Beltrami operator associated to  $ds_t^2$ .

In particular, when  $q=n$  ( $n = \dim_{\mathbb{C}} M_t$ ), by (1.1) we obtain

$$(1.2) \quad C^{p,n}(\bar{X}_t) \cap D_{L_t}^{p,n} = \{\varphi_t \in C^{p,n}(\bar{X}_t) \mid \varphi_t = 0 \text{ on } \partial X_t\}.$$

Namely in this case the  $\bar{\partial}$ -Neumann boundary conditions reduce to the Dirichlet boundary condition. Hence the  $\bar{\partial}$ -Neumann problem for  $(p, n)$  forms on  $X_t$  is solvable (see Sect. 2., Proposition 1 and Theorem 2). Moreover this boundary condition is invariant under the transformation  $f_t^*$ .

Lastly we define the hermitian form  $Q_t$  on the space  $B^{p,q}(\bar{X}_t)$  by

$$Q_t(\varphi_t, \psi_t) = (\bar{\partial}_t \varphi_t, \bar{\partial}_t \psi_t)_t + (\vartheta_t \varphi_t, \vartheta_t \psi_t)_t + (\varphi_t, \psi_t)_t$$

for  $\varphi_t, \psi_t \in B^{p,q}(\bar{X}_t)$  and  $t \in B$ . Here we remark that  $B^{p,q}(\bar{X}_t) = C^{p,q}(\bar{X}_t) \cap D_{\bar{\partial}_t^*}^{p,q}$  and  $\bar{\partial}_t^* = \vartheta_t$  on  $B^{p,q}(\bar{X}_t)$  (see [2] (1.3.2) Proposition).

### § 2. The Parametrized $\bar{\partial}$ -Neumann Problem

In this section, using the solvability of the  $\bar{\partial}$ -Neumann problem for  $(p, n)$  forms on  $X_t$  and the vanishing theorem for  $L^2$ -harmonic  $(p, n)$  forms on  $X_t$ , we show that the Neumann operator  $N_t$  depends differentiably on  $t$ . We begin with the following estimate (see [2] (3.2.13) Corollary).

**Proposition 1** (*a priori estimate for  $(p, n)$  forms*). *There exists a continuous function  $C(t) > 0$  such that*

$$(2.1) \quad \|\varphi_t\|_{1,t}^2 \leq C(t) Q_t(\varphi_t, \varphi_t), \quad \varphi_t \in B^{p,n}(\bar{X}_t), \quad t \in B.$$

Here we denote by  $\|\cdot\|_{\nu,t}$  the Sobolev  $\nu$ -norm on the spaces  $C^{p,q}(\bar{X}_t)$ ,  $\nu=1, 2, \dots$ . The following theorem is deduced from the above proposition (see [2]).

**Theorem 2** (Solvability of the  $\bar{\partial}$ -Neumann problem for  $(p, n)$  forms). *For each  $t \in B$ , the nullity  $N_{L_t}^{p,n}$  of  $L_t = \bar{\partial}_t \bar{\partial}_t^* + \bar{\partial}_t^* \bar{\partial}_t$  is a finite dimensional subspace of  $C^{p,n}(\bar{X}_t)$  and there exists a unique bounded self-adjoint operator  $N_t: L^{p,n}(X_t) \rightarrow L^{p,n}(X_t)$ , which is called the Neumann operator associated to the operator  $L_t$ , such that*

- 1)  $D_{N_t}^{p,n} = L^{p,n}(X_t)$ ,  $R_{N_t}^{p,n} \subset D_{L_t}^{p,n}$ ,  $R_{N_t}^{p,n} \perp N_{L_t}^{p,n}$  and  $N_{N_t}^{p,n} = N_{L_t}^{p,n}$
- 2) for any  $\alpha_t \in L^{p,n}(X_t)$ ,  $\alpha_t = \bar{\partial}_t \bar{\partial}_t^* N_t \alpha_t + H_t \alpha_t$ , where  $H_t$  is the orthogonal projection onto the space  $N_{L_t}^{p,n}$ .
- 3)  $N_t L_t = L_t N_t = I - H_t$  on  $D_{L_t}^{p,n}$  and  $P_t = I - \bar{\partial}_t^* N_t \bar{\partial}_t$  on  $D_{\bar{\partial}_t}^{p,n-1}$ , where  $P_t$  is the orthogonal projection onto the space  $N_{\bar{\partial}_t}^{p,n-1}$
- 4)  $N_t$  maps  $C^{p,n}(\bar{X}_t)$  into  $C^{p,n}(\bar{X}_t)$
- 5) for any non-negative integer  $\nu$ , there exists a continuous function  $C_\nu(t) > 0$  such that

$$(2.2) \quad \|\varphi_t\|_{\nu+2,t} \leq C_\nu(t) (\|\square_t \varphi_t\|_{\nu,t} + \|\varphi_t\|_t) \\ \varphi_t \in C^{p,n}(\bar{X}_t) \cap D_{L_t}^{p,n} \text{ and } t \in B.$$

We first prove the following.

**Proposition 3.** *For each  $t \in B$ ,  $L_t: L^{p,n}(X_t) \rightarrow L^{p,n}(X_t)$  is surjective and there exist a neighborhood  $W_t \subset B$  of  $t$  and a positive constant  $C_t$  such that*

$$(2.3) \quad \|\varphi_s\|_s \leq C_t \|L_s \varphi_s\|_s, \quad \varphi_s \in D_{L_s}^{p,n} \text{ and } s \in W_t.$$

*Proof.* First we prove the former assertion. By Theorem 2, 2), we have only to show

$$N_{L_t}^{p,n} = \{0\}, \quad t \in B.$$

We fix a point  $t \in B$ . If  $\delta_0 > 0$  is sufficiently small, then we can apply Proposition 1 and Theorem 2 to each domain  $X_{t,\delta} = \{h_t < \delta\}$ ,  $0 < \delta < \delta_0$ . We define the homomorphism  $\rho_{t,\delta}: N_{L_{t,\delta}}^{p,n} \rightarrow N_{L_t}^{p,n}$  by  $\rho_{t,\delta} := H_t \circ r_{t,\delta}$  where  $r_{t,\delta}: L^{p,n}(X_{t,\delta}) \rightarrow L^{p,n}(X_t)$  is the restriction homomorphism. Then there exists a positive constant  $\delta_1$  such that  $\rho_{t,\delta}: N_{L_{t,\delta}}^{p,n} \rightarrow N_{L_t}^{p,n}$  is an isomorphism,  $0 < \delta < \delta_1$ . The existence of  $\delta_1$  and the injectivity of  $\rho_{t,\delta}$  are proved as follows. Suppose that there were sequences  $\{\delta_k\}$  and  $\{\theta_{t,k}\}$  such that  $\delta_k \rightarrow 0$  as  $k \rightarrow \infty$ ,  $\theta_{t,k} \in N_{L_{t,\delta_k}}^{p,n}$ ,  $\|\theta_{t,k}\|_{t,\delta_k} = 1$  and  $\rho_{t,\delta_k}(\theta_{t,k}) = 0$ . Since the value  $C(t)$  of the inequality (2.1) can be taken independently of  $\delta$  if  $\delta$  is sufficiently small, combining Theo-

rem 2 with the inequality (2.1),  $\|\theta_{t,k}\|_{1,t}$  bounded. By Rellich's lemma (see [2] (A.2.3) Proposition), taking a subsequence,  $\theta_{t,k}$  converges to some  $\theta_t \in L^{p,n}(X_t)$  such that  $H_t \theta_t = 0$  and  $\|\theta_t\|_t = 1$  since the inner product  $(\cdot, \cdot)_t$  depends continuously on  $t$ . On the other hand, we recall that  $\varphi_t \in D_{\bar{\partial}_t}^{p,n}$  if and only if for some positive constant  $C$ ,  $|(\varphi_t, \bar{\partial}_t \psi_t)_t| \leq C \|\psi_t\|_t$ ,  $\psi_t \in C^{p,n-1}(\bar{X}_t)$ . Since  $\bar{\partial}_{t,\delta}^* \theta_{t,k} = 0$ ,  $(\theta_t, \bar{\partial}_t \psi_t)_t = 0$ ,  $\psi_t \in C^{p,n-1}(\bar{X}_t)$ . Hence  $\theta_t \in N_{L_t}^{p,n} \cap N_{L_t}^{p,n \perp} = \{0\}$ . This is a contradiction. The surjectivity of  $\rho_{t,\delta}$  is proved as follows. If  $\rho_{t,\delta}$  were not surjective ( $0 < \delta < \delta_1$ ), then there would be a non-zero element  $\omega_t$  of  $N_{L_t}^{p,n}$  with  $\omega_t \perp \rho_{t,\delta}(N_{L_t}^{p,n})$ . Extending the definition of  $\omega_t$  by setting  $\omega_t = 0$  on  $X_{t,\delta} \setminus X_t$ , we denote it by  $\omega'_t$ . Then since  $\omega'_t \in L^{p,n}(X_{t,\delta})$  and  $\omega'_t \perp N_{L_{t,\delta}}^{p,n}$ , from Theorem 2, 2),  $\omega'_t = \bar{\partial}_{t,\delta} \bar{\partial}_{t,\delta}^* N_{t,\delta} \omega'_t$ . Setting  $\psi'_t = \bar{\partial}_{t,\delta}^* N_{t,\delta} \omega'_t$ ,  $(\omega_t, \theta_t)_t = (\bar{\partial}_t r_{t,\delta}(\psi'_t), \theta_t)_t = (r_{t,\delta}(\psi'_t), \bar{\partial}_t^* \theta_t)_t = 0$  for any  $\theta_t \in N_{L_t}^{p,n}$ . Hence  $\omega_t = 0$ . This is a contradiction. Therefore our assertion holds:

To show  $N_{L_t}^{p,n} = \{0\}$ , we have only to prove that  $\rho_{t,\delta}: N_{L_{t,\delta}}^{p,n} \rightarrow N_{L_t}^{p,n}$  is the zero map for  $0 < \delta < \delta_1$ . For any element  $\theta_{t,\delta}$  of  $N_{L_{t,\delta}}^{p,n}$ , combining the fact  $H^n(X_{t,\delta}, \mathcal{Q}^p) = 0$  ([6] Theorem) with the Dolbeault theorem, there exists  $\eta_{t,\delta} \in C^{p,n-1}(X_{t,\delta})$  with  $\theta_{t,\delta} = \bar{\partial}_{t,\delta} \eta_{t,\delta}$ . Hence  $\rho_{t,\delta}(\theta_{t,\delta}) = 0$ . Therefore we have  $N_{L_t}^{p,n} = \{0\}$ .

Next we prove the latter assertion. We may put  $t=0$ . Suppose that there were sequences  $\{t_k\}$  and  $\{\varphi_k\}$  such that  $t_k \rightarrow 0$  as  $k \rightarrow \infty$ ,  $\varphi_k \in D_{L_{t_k}}^{p,n}$ ,  $\|\varphi_k\|_{t_k} = 1$  and  $\|L_{t_k} \varphi_k\|_{t_k} \rightarrow 0$  as  $k \rightarrow \infty$ . Since  $B^{p,n}(\bar{X}_t)$  is dense in  $D_{\bar{\partial}_t}^{p,n}$  with respect to the form  $\mathcal{Q}_t$  (see [3] Proposition 1.2.3 and 1.2.4), the inequality (2.1) holds for any form contained in  $D_{L_t}^{p,n}$ . Hence we may assume that  $\|\varphi_k\|_{1,t_k}$  is bounded. From the local invariance of the Sobolev spaces under coordinate transformations and Rellich's lemma, there exists  $\varphi_0 \in L^{p,n}(X_0)$  such that  $\|f_{t_k}^* \varphi_k - \varphi_0\|_0 \rightarrow 0$  as  $k \rightarrow \infty$  in  $\sum_{r+s=p+n} L^{r,s}(X_0)$ . Then  $\|\varphi_0\|_0 > 0$ . On the other hand, using  $\|L_{t_k} \varphi_k\|_{t_k} \rightarrow 0$  as  $k \rightarrow \infty$ ,  $(\varphi_0, \bar{\partial}_0 \psi_0)_0 = 0$  for any  $\psi_0 \in C^{p,n-1}(\bar{X}_0)$ . Hence  $\varphi_0 \in N_{L_0}^{p,n} = \{0\}$ . This is a contradiction. q.e.d.

Any section  $\varphi \in C^{p,q}(\bar{\mathcal{X}})$  determines a family  $\{r_t(\varphi) | t \in B\}$  of sections  $r_t(\varphi) \in C^{p,q}(\bar{X}_t)$ , where  $r_t: C^{p,q}(\bar{\mathcal{X}}) \rightarrow C^{p,q}(\bar{X}_t)$  is the restriction homomorphism. Given, for each  $t \in B$ , a form  $\varphi_t \in C^{p,q}(\bar{X}_t)$ , we say that  $\varphi_t$  depends *differentially* on  $t$  if and only if there exists  $\varphi \in C^{p,q}(\bar{\mathcal{X}})$  such that

$$\varphi_t = r_t(\varphi), t \in B.$$

Given, for each  $t \in B$ , a linear operator  $A_t$  of  $L^{p,q}(X_t)$  into  $L^{r,s}(X_t)$ , we say

that  $A_t$  depends differentially on  $t$  if and only if  $A_t r_t(\varphi)$  depends differentially on  $t$  for any section  $\varphi \in C^{p,q}(\bar{X})$ . Next we prove the following proposition.

**Proposition 4.** *The Neumann operator  $N_t: L^{p,n}(X_t) \rightarrow L^{p,n}(X_t)$  defined in Theorem 2 depends differentially on  $t$ .*

*Proof.* By the inequalities (2.2) and (2.3), we get

$$\|\eta_s\|_{\nu+2,s} \leq C_\nu \|\square_s \eta_s\|_{\nu,s}$$

if  $\eta_s \in C^{p,n}(\bar{X}_s) \cap D_{L_s}^{p,n}$ ,  $\nu \geq 0$  and  $s \in W_t$ , where  $C_\nu$  is a positive constant not depending on  $s \in W_t$ . By Sobolev's lemma (see [2] (A.2.3) Proposition), we get

$$(2.4) \quad |\eta_s|_{l,s} \leq C_l \|\square_s \eta_s\|_{\nu,s}$$

if  $\eta_s \in C^{p,n}(\bar{X}_s) \cap D_{L_s}^{p,n}$ ,  $\nu \geq n+l-1$  and  $s \in W_t$ , where  $|\cdot|_{l,s}$  is the supremum norm up to the  $l$ -th derivatives on  $C^{p,n}(\bar{X}_s)$  and  $C_l$  is a positive constant not depending on  $s \in W_t$ .

Consider a family  $\{\varphi_t | t \in B\}$  of sections  $\varphi_t \in C^{p,n}(\bar{X}_t)$ . We say that  $\varphi_t$  is of class  $C^\kappa$  in  $t$  if and only if all derivatives of  $\varphi_t$  with respect to the fibre coordinates  $z_i^\alpha$  and  $z_i^\beta$  are of class  $C^\kappa$  in  $t$ . We denote by  $\prod_t^{p,n}$  the projection of  $\sum_{0 \leq i+j \leq 2n} C^{i,j}(\bar{X}_t)$  onto  $C^{p,q}(\bar{X}_t)$ . Since  $\prod_t^{p,n}(f^{-1})^*$  induces a differentiable isomorphism of  $\Theta^*(p, n)|_{W_t}$  onto  $\Theta^*(p, n) \times W_t$ ,  $\varphi_t$  is of class  $C^\kappa$  in  $t$  if and only if for any  $t \in B$ , all derivatives of  $\prod_t^{p,n} f_{s_t}^* \varphi_s$  with respect to the fibre coordinates  $z_i^\alpha$  and  $z_i^\beta$  are of class  $C^\kappa$  in  $s$ . If  $\varphi_t$  is of class  $C^\kappa$  in  $t$  for every  $0 \leq \kappa < \infty$ , then clearly  $\varphi_t$  depends differentially on  $t$ .

By Theorem 2, 4), we have only to prove that  $\varphi_t := N_t \psi_t$  depends differentially on  $t$  for any family  $\{\psi_t | t \in B\}$  of sections  $\psi_t \in C^{p,n}(\bar{X}_t)$  depending differentially on  $t$ . We prove this statement in several steps. We first prove the following assertion.

i) *If  $\psi_t$  is continuous (i.e. of class  $C^0$ ) in  $t$ , then  $\varphi_t$  is continuous in  $t$ .*

*Proof.* We set  $\varphi_s^* = \prod_t^{p,n} f_{s_t}^* \varphi_s$ . By (1.2), we get

$$(2.5) \quad \varphi_s^* \in C^{p,n}(\bar{X}_t) \cap D_{L_t}^{p,n}.$$

Replacing  $\eta_s$  by  $\varphi_s$  and  $\varphi_s^* - \varphi_t^*$  ( $\varphi_t^* = \varphi_t$ ), we have from (2.4) and (2.5) the following inequalities

$$(2.6) \quad |\varphi_s|_{l,s} \leq C_l \|\psi_s\|_{\nu,s}$$

$$(2.7) \quad \begin{aligned} &|\varphi_s^* - \varphi_t^*|_{l,t} \\ &\leq C_l(\|f_{s,t}^* \psi_s - \psi_t\|_{\nu,t} + \|(\square_t f_{s,t}^* - f_{s,t}^* \square_s) \varphi_s\|_{\nu,t}) \end{aligned}$$

if  $\nu > n + l - 1$ . Since  $\psi_t$  is continuous in  $t$  and the coefficients of the operator  $\square_t$  depend differentiably on  $t$ , from (2.6) and (2.7), we have

$$|\varphi_s^* - \varphi_t^*|_{l,t} \rightarrow 0 \text{ as } s \rightarrow t, \quad l \geq 0.$$

Hence  $\varphi_t$  is continuous in  $t$ .

ii) If  $\psi_t$  is of class  $C^1$  in  $t$ , then  $\varphi_t$  is of class  $C^1$  in  $t$ .

*Proof.* We define the linear operator  $F_s: C^r(\bar{X}_t) \rightarrow C^r(\bar{X}_t)$  by  $F_s := f_{s,t}^* \square_s \prod_{s+q=r}^{p,n} f_{s,t}^*$  where  $C^r(\bar{X}_t) = \sum_{p+q=r} C^{p,q}(\bar{X}_t)$ . We denote by  $\frac{\partial F_t}{\partial t_\mu}$  the operator obtained from  $F_t$  by applying  $\frac{\partial}{\partial t_\mu}$  to each coefficient of  $F_t$  ( $1 \leq \mu \leq m$ ) i.e.  $\frac{\partial F_t}{\partial t_\mu} = \left( \frac{\partial}{\partial s_\mu} F_s \right)_{s=t}$ . We define  $\frac{\partial \psi_t}{\partial t_\mu}$  by  $\left( \frac{\partial}{\partial s_\mu} (f_{s,t}^* \psi_s) \right)_{s=t}$ . We set

$$\eta_t = N_t \left( \prod_{i,n}^{p,n} \left( \frac{\partial \psi_t}{\partial t_\mu} - \frac{\partial F_t}{\partial t_\mu} \varphi_t \right) \right)$$

and

$$\chi_t(h) = \frac{1}{h} (\varphi_{t+h}^* - \varphi_t^*) - \eta_t$$

for  $t+h = (t_1, \dots, t_{\mu-1}, t_\mu+h, t_{\mu+1}, \dots, t_m)$ . Then  $\chi_t(h)$  is written as follows using (2.5) and Theorem 2, 3).

$$(2.8) \quad \begin{aligned} \chi_t(h) &= N_t \left( \prod_{i,n}^{p,n} \left( \frac{1}{h} (f_{t+h,t}^* \psi_{t+h} - \psi_t) - \frac{\partial \psi_t}{\partial t_\mu} \right) \right) \\ &\quad - N_t \left( \prod_{i,n}^{p,n} \left( \frac{1}{h} (F_{t+h} - F_t) f_{t+h,t}^* \varphi_{t+h} - \frac{\partial F_t}{\partial t_\mu} \varphi_t \right) \right). \end{aligned}$$

Since  $\chi_t(h) \in D_{l,t}^{p,n}$  for any  $h \neq 0$  by (2.8), applying  $\chi_t(h)$  to (2.4), we have

$$(2.9) \quad |\chi_t(h)|_{l,t} \rightarrow 0 \text{ as } h \rightarrow 0, \quad l \geq 0.$$

This means that  $\varphi_t$  is of class  $C^1$  in  $t$ .

iii) If  $\psi_t$  is of class  $C^\kappa$  in  $t$ , then  $\varphi_t$  is of class  $C^\kappa$  in  $t$ .

*Proof.* By induction on  $\kappa$ . Assume that the statement is true for  $\kappa - 1$  ( $\kappa \geq 2$ ). Let  $U$  and  $V$  be local coordinate neighborhoods on  $M_t$  such that

$U \subseteq V$  and  $U \cap \bar{X}_t \neq \emptyset$  and let  $(x_1, \dots, x_{2n})$  be a system of real coordinates on  $V$ . Then from (2.9) we have

$$(2.10) \quad \frac{\partial}{\partial t_\mu} D^\sigma(\varphi_{t, A_p \bar{B}_n}) = D^\sigma(N_t \left( \prod_{i=1}^{2n} \left( \frac{\partial \psi_t}{\partial t_\mu} - \frac{\partial \mathbf{F}_t}{\partial t_\mu} \varphi_t \right) \right)_{A_p \bar{B}_n}) \text{ on } U$$

where  $1 \leq \mu \leq m$ ,  $\sigma = (\sigma_1, \dots, \sigma_{2n})$ ,  $D^\sigma = \prod_{i=1}^{2n} \left( \frac{\partial}{\partial x_i} \right)^{\sigma_i}$  and  $\varphi_t = \frac{1}{p!n!} \sum_{A_p B_n} \varphi_{t, A_p \bar{B}_n} dz^{A_p} \wedge dz^{\bar{B}_n}$  and so on. By inductive hypothesis,  $N_t \left( \prod_{i=1}^{2n} \left( \frac{\partial \psi_t}{\partial t_\mu} - \frac{\partial \mathbf{F}_t}{\partial t_\mu} \varphi_t \right) \right)$  is of class  $C^{k-1}$  in  $t$ . Hence the equality (2.10) implies that  $\varphi_t$  is of class  $C^k$  in  $t$ . This completes the proof of Proposition 4.

We summarize the results obtained in this section.

**Theorem 5.** 1) For any  $\alpha_t \in L^{p,n}(X_t)$  and  $t \in B$ ,  $\alpha_t = \bar{\partial}_t^* \bar{\partial}_t^* N_t \alpha_t$ .

2) The operators  $N_t: L^{p,n}(X_t) \rightarrow L^{p,n}(X_t)$  and  $\mathbf{P}_t: L^{p,n-1}(X_t) \rightarrow L^{p,n-1}(X_t)$  depend differentiably on  $t$ .

### § 3. Proof of Main Theorem

We take an exhaustion function  $\Phi_0$  of class  $C^\infty$  on  $M_0$ . Since any relatively compact domain on  $M_0$  is contained in a sublevel set  $\{\Phi_0 < c\}$ ,  $c \in \mathbb{R}$ , we may replace its domain by such a sublevel set. We take a non-critical value  $c$  of  $\Phi_0$  and set  $X_0 = \{\Phi_0 < c\}$ . Extending  $\Phi_0$  to a neighborhood of  $X_0$  in  $\mathcal{M}$  and shrinking  $B$  arbitrarily, we obtain a differentiable family  $\pi: \mathcal{X} \rightarrow B$  of bounded domains with smooth boundary such that  $\pi|_{\mathcal{X}}^{-1}(0) = X_0$ . We fix the diffeomorphism  $f$  as taken in Sect. 1. To prove the theorem, we have only to prove the following assertion.

**Assertion.** For given any Kähler metric  $d\sigma^2$  on  $M_0$ , there exist a neighborhood  $W$  of  $t=0$  in  $B$  and a family  $\{ds_t^2 = \sum g_{i, \alpha\bar{\beta}} dz_{t,i}^\alpha dz_{t,i}^{\bar{\beta}}\}_{t \in W}$  of hermitian metrics such that 1)  $ds_t^2$  is a Kähler metric on  $X_t$ ,  $t \in W$  and  $ds_0^2 = d\sigma^2$  on  $X_0$   
 2) the functions  $g_{i, \alpha\bar{\beta}}(z_i, \bar{z}_i, t)$  are of class  $C^\infty$  in  $z_i, \bar{z}_i$  and  $t$ .

*Proof.* Let  $\omega_0$  be the Kähler form associated to  $d\sigma^2$  on  $M_0$ . We set

$$\omega'_t = f_{0t}^* \omega_0, \quad t \in B.$$

Then  $\omega'_t$  is a  $d_t$ -closed real two form on  $\bar{X}_t$  depending differentiably on  $t$ . Since  $\dim_C M_t = 2$ , we can apply Theorem 5 to  $(p, 2)$  forms of class  $C^\infty$  on  $\bar{X}_t$ . Combining the  $d_t$ -closedness of  $\omega'_t$  with Theorem 5, each  $\omega'_t$  satisfies the following

differential equations.

$$\bar{\partial}_t(\Pi_t^{1,1}\omega'_t - \partial_t\vartheta_t N_t \Pi_t^{0,2}\omega'_t) = 0$$

\*)<sub>t</sub>

$$\partial_t(\Pi_t^{1,1}\omega'_t - \overline{\partial_t\vartheta_t N_t \Pi_t^{0,2}\omega'_t}) = 0$$

Hence we set

$$\omega_t = \Pi_t^{1,1}\omega'_t - \partial_t\vartheta_t N_t \Pi_t^{0,2}\omega'_t - \overline{\partial_t\vartheta_t N_t \Pi_t^{0,2}\omega'_t}, \quad t \in B.$$

From the equation \*)<sub>t</sub>,  $\omega_t$  is a  $d_t$ -closed real (1,1) differential form on  $\bar{X}_t$  such that  $\omega_0 = \omega$  on  $\bar{X}_0$ . Since  $\omega_t$  depends differentiably on  $t$  by Theorem 5, 2),  $\omega_t$  gives a Kähler form on  $X_t$  for each  $t \in W$  if  $W$  is a sufficiently small neighborhood of  $t=0$  in  $B$ . Hence the assertion is now clear. This completes the proof of Main Theorem.

*Remark.* Using Theorem 5, we can prove the following theorem too.

**Theorem.** *Let  $\pi: \mathcal{M} \rightarrow B$  be a differentiable family of non-compact complex manifolds of dimension two. Then for any relatively compact domain in  $M_0$ , any holomorphic line bundle on  $M_0$  can be extended to a differentiable family of holomorphic line bundles on a neighborhood of its domain in  $\mathcal{M}$  whose restriction to its domain coincides with the given holomorphic line bundle.*

Since the idea of the proof is quite similar to the idea of Sect. 13 in [4], the detail is left to the reader.

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