

Integration in Abelian C^* -Dynamical Systems

By

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Abstract

Let $\mathcal{A} = C_0(X)$ be an abelian C^* -algebra and $t \in \mathbf{R} \rightarrow \sigma_t$ a strongly continuous group of $*$ -automorphisms with generator δ_0 . We consider derivations $\delta = \lambda \delta_0$, where λ is a multiplication operator on $C_0(X)$, and establish conditions on λ which ensure that δ has a unique generator extension. As a corollary we deduce that each derivation δ from $\bigcap_{n \geq 1} D(\delta_0^n)$ into $D(\delta_0)$ is closable and its closure is a generator. An analogous result is established for derivations defined on the smooth elements associated with the action of a compact Lie group on \mathcal{A} . Some results on local dissipations are also given.

§ 1. Introduction

Our aim is to analyze derivations δ defined on the smooth elements of an abelian C^* -dynamical system as generators of C_0 -groups of $*$ -automorphisms. The basic question is whether δ has a unique generator extension, and then a subsidiary problem is to relate this extension to δ . Since each abelian C^* -dynamical system determines a topological dynamical system, based on the spectrum of the abelian algebra, this question can be viewed as a problem of integration in topological dynamics. This approach appears particularly useful. In order to be more precise we introduce the following definition and notation.

Let $(\mathcal{A}, \mathbf{R}, \sigma)$ denote an abelian C^* -dynamical system. Thus \mathcal{A} is an abelian C^* -algebra and $t \in \mathbf{R} \rightarrow \sigma_t \in \text{Aut } \mathcal{A}$ is a strongly continuous one-parameter group of $*$ -automorphisms of \mathcal{A} . Next let δ_0 denote the generator of σ and define $\mathcal{A}_n = D(\delta_0^n)$, and

$$\mathcal{A}_\infty = \bigcap_{n \geq 1} \mathcal{A}_n.$$

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It follows automatically that \mathcal{A}_∞ is a norm dense *-subalgebra of \mathcal{A} . The principal object of this paper is a *-derivation δ on \mathcal{A} with domain $D(\delta)=\mathcal{A}_\infty$. Our main result, Theorem 3.1, states that *if $\delta: \mathcal{A}_\infty \rightarrow \mathcal{A}_1$ then δ is closable and its closure $\bar{\delta}$ generates a strongly continuous one-parameter group τ of *-automorphisms of \mathcal{A} . In particular $\bar{\delta}$ is the unique generator extension of δ . The group τ is closely related to σ but to describe this relationship it is necessary to introduce the underlying topological dynamical system.*

Let X denote the spectrum of \mathcal{A} . Then \mathcal{A} can be identified with $C_0(X)$, the continuous functions over X which vanish at infinity, and one can associate with σ a continuous one-parameter group S of homeomorphisms of X such that

$$(\sigma_t f)(\omega) = f(S_t \omega)$$

for all $t \in \mathbf{R}$, $\omega \in X$, and $f \in C_0(X)$. We note that strong continuity of σ is equivalent to joint continuity of the map $(t, \omega) \rightarrow S_t \omega$ (See Lemma 2.2 below).

Now consider the topological dynamical system (X, \mathbf{R}, S) . To each point $\omega \in X$ we associate the orbit

$$S_{\mathbf{R}} \omega = \{S_t \omega; t \in \mathbf{R}\}$$

and use X_0 to denote the set of fixed points of S , i. e.,

$$X_0 = \{\omega; S_t \omega = \omega \text{ for all } t \in \mathbf{R}\}$$

Next we associate to each $\omega \in X$ a period $p(\omega)$ by the definition

$$p(\omega) = \inf \{t > 0; S_t \omega = \omega\}$$

and $p(\omega) = +\infty$ if there is no $t > 0$ such that $S_t \omega = \omega$. Thus, for example, $\omega \in X_0$ if, and only if, $p(\omega) = 0$. Finally we associate to each $\omega \in X$ a frequency $\nu(\omega)$ by setting $\nu(\omega) = 0$ if $p(\omega) = +\infty$, $\nu(\omega) = 1/p(\omega)$ if $0 < p(\omega) < +\infty$, and $\nu(\omega) = +\infty$ if $p(\omega) = 0$.

The starting point of our analysis is a result of [6] which states that δ is a derivation from \mathcal{A}_∞ into \mathcal{A} if, and only if,

$$\delta = \lambda \delta_0 |_{\mathcal{A}_\infty}$$

where λ is a function which vanishes on X_0 and is continuous and polynomially bounded in the frequency on $X \setminus X_0$. By this last statement we mean that there is a $C > 0$ and an integer $n \geq 0$ such that

$$|\lambda(\omega)| \leq C(1 + \nu(\omega)^n)$$

for all $\omega \in X \setminus X_0$. (For earlier results of this nature see [3], [10], and for some further remarks on this result see [1].) Moreover δ maps \mathcal{A}_∞ into \mathcal{A}_1 if, and only if, $\delta_0 \lambda(\omega) = \lim_{t \rightarrow 0} (\lambda(S_t \omega) - \lambda(\omega))/t$ exists for $\omega \in X \setminus X_0$, $\delta_0 \lambda$ is a continuous function on $X \setminus X_0$, and both λ and $\delta_0 \lambda$ are polynomially bounded in the frequency. It is this special form $\delta = \lambda \delta_0$ which is crucial in our construction of an automorphism group with $\bar{\delta}$ as its generator. For example if $|\lambda|$ is bounded and bounded

away from zero then for $\varepsilon > 0$ (resp. $\varepsilon < 0$) sufficiently small, $\delta_0 - \varepsilon\delta$ is relatively bounded by δ_0 with relative bound $b < 1$ on the component of X where $\lambda > 0$ (resp. $\lambda < 0$), and as $\pm\delta$ clearly are dissipative, δ is a generator by perturbation theory. The general situation is much more complicated. If λ is only polynomially bounded in the frequency then difficulties can occur at points with very large frequency, i. e., at fixed points of S . Different difficulties can occur if λ has zeros on $X \setminus X_0$. Note that if $\omega \in X \setminus X_0$ and $\lambda(\omega) = 0$ then

$$(\delta f)(\omega) = \lambda(\omega)(\delta_0 f)(\omega) = 0$$

for all $f \in \mathcal{A}_\infty$ and thus ω is a fixed point of δ but not for δ_0 .

The key observation in our proof that $\bar{\delta}$ generates an automorphism group τ is the remark that each orbit of the associated homeomorphism group T on X should be contained in an orbit of S . Thus if T exists there should also exist functions $(t, \omega) \in \mathbf{R} \times X \rightarrow x_\omega(t) \in \mathbf{R}$ such that

$$T_t \omega = S_{x_\omega(t)} \omega.$$

Then, formally.

$$\begin{aligned} \lambda(T_t \omega)(\delta_0 f)(T_t \omega) &= (\delta \tau_t f)'(x_\omega) \\ &= \frac{d}{dt} (\tau_t f)(\omega) \\ &= \frac{d}{dt} f(S_{x_\omega(t)} \omega) \\ &= x'_\omega(t)(\delta_0 f)(T_t \omega). \end{aligned}$$

Consequently x_ω satisfies the first-order differential equation

$$x'_\omega(t) = \lambda_\omega(x_\omega(t))$$

where λ_ω is defined by

$$\lambda_\omega(t) = \lambda(S_t \omega).$$

Our main technical result, in Section 2, is a version of the Picard-Lindelöf theorem of ordinary differential equations (see, for example, [12] Theorem 2.3.1). The latter theorem proves the existence of a flow T on \mathbf{R} with the above structure whenever λ is a uniformly Lipschitz continuous function. In our version of the theorem the construction of T on each orbit follows from the classical Picard-Lindelöf theorem but the new problem, which has some analogue to stability problems in ordinary differential equations, is the proof of joint continuity of the map $(t, \omega) \in \mathbf{R} \times X \rightarrow T_t \omega$, which is necessary for the existence of τ . For this we need the Lipschitz constants for λ on the orbits to be uniformly bounded on each set of bounded frequency, and λ must satisfy a certain boundedness property at low-frequency points near X_0 .

In Section 3 we derive our main theorem as a corollary of the technical results of Section 2, and in Section 4 we discuss the generator question for local

dissipations (semi-derivations) defined on \mathcal{A}_∞ .

In Section 5 we derive the analogue of Theorem 3.1 with the action S of \mathbf{R} on X replaced by an action of a compact Lie group. Let \mathcal{A}_∞ (resp. \mathcal{A}_1) denote the algebra of infinitely (resp. once) differentiable elements for an action of a compact Lie group on $\mathcal{A}=C_0(X)$. If $\delta : \mathcal{A}_\infty \rightarrow \mathcal{A}_1$ is a *-derivation, then δ is closable and $\bar{\delta}$ is a generator.

§ 2. Picard-Lindelöf Theorems for Flows

In this section we establish the generalization of the Picard-Lindelöf theorem mentioned in the introduction and then characterize the generator of the flow constructed in this theorem.

Definition 2.1. Let X be a locally compact Hausdorff space, and $t \in \mathbf{R} \rightarrow S_t$ a one-parameter family of homeomorphisms of X . We define S to be a flow if

- a. S is a group, i. e.

$$S_t S_s = S_{t+s}, \quad t, s \in \mathbf{R},$$

- b. The map

$$(t, \omega) \in \mathbf{R} \times X \mapsto S_t \omega$$

is jointly continuous

Note that joint continuity does not generally follow from separate continuity, although it does if X is metrizable (see, for example, [17] Theorem 1.1). The relevance of joint continuity in the C^* -algebraic framework is a consequence of the following well-known lemma.

Lemma 2.2. Let $\mathcal{A}=C_0(X)$ be an abelian C^* -algebra with spectrum X , $t \in \mathbf{R} \rightarrow \sigma_t$ a one-parameter group of *-automorphisms of \mathcal{A} , and $t \in \mathbf{R} \rightarrow S_t$ the corresponding one-parameter group of homeomorphisms of X , i. e.

$$(\sigma_t f)(\omega) = f(S_t \omega), \quad f \in \mathcal{A}, t \in \mathbf{R}, \omega \in X.$$

The following conditions are equivalent:

- 1. $t \in \mathbf{R} \rightarrow \sigma_t$ is strongly continuous, i. e.

$$\|\sigma_t f - f\| \xrightarrow{t \rightarrow 0} 0 \quad \text{for all } f \in \mathcal{A},$$

- 2. $(t, \omega) \in \mathbf{R} \times X \rightarrow S_t \omega$ is jointly continuous

Proof. 1 \Rightarrow 2. Assume 1, and let $(t_\alpha, \omega_\alpha)$ be a net in $\mathbf{R} \times X$ converging to (t, ω) . If $f \in C_0(X)$, we have

$$|f(S_{t_\alpha} \omega_\alpha) - f(S_t \omega)| \leq \|\sigma_{t_\alpha} f - \sigma_t f\| + |(\sigma_{t_\alpha} f)(\omega_\alpha) - (\sigma_t f)(\omega)| \xrightarrow{\alpha \rightarrow \infty} 0 + 0$$

and as X is locally compact, it follows that

$$\lim_{\alpha} S_{t_{\alpha}} \omega_{\alpha} = S_t \omega$$

2 \Rightarrow 1. Assume that 1 is false, i. e. that there exists an $f \in C_0(X)$ such that

$$\overline{\lim}_{t \rightarrow 0} \|\sigma_t f - f\| = 2\varepsilon > 0$$

Then there exist sequences $t_n \neq 0$, $\omega_n \in X$ such that $t_n \rightarrow 0$ and

$$|f(S_{t_n} \omega_n) - f(\omega_n)| > \varepsilon$$

for all n . But there exists a compact set $K \subseteq X$ such that $|f(\omega)| < \varepsilon/2$ if $\omega \in K$, thus it follows for each n that $S_{t_n} \omega_n \in K$ or $\omega_n \in K$. If $S_{t_n} \omega_n \in K$ then replacing the pair (t_n, ω_n) by $(-t_n, S_{t_n} \omega_n)$, we may assume $\omega_n \in K$ for all n . Since K is compact there exists a subnet $(t_{\alpha}, \omega_{\alpha})$ of (t_n, ω_n) such that $t_{\alpha} \rightarrow 0$, $\omega_{\alpha} \rightarrow \omega \in K$. But as

$$|f(S_{t_{\alpha}} \omega_{\alpha}) - f(\omega_{\alpha})| > \varepsilon$$

for all α , we cannot have

$$\lim_{\alpha \rightarrow \infty} S_{t_{\alpha}} \omega_{\alpha} = \omega$$

and 2 does not hold.

Let S be a flow on X . If $\omega \in X$ recall that the period of ω is defined as

$$p(\omega) = \inf \{t > 0; S_t \omega = \omega\}$$

and the frequency of ω is

$$\nu(\omega) = 1/p(\omega)$$

In particular $\nu(\omega) = \infty$ if ω is a fixed point, and $\nu(\omega) = 0$ if $S_t \omega \neq \omega$ for all $t \neq 0$.

We shall need the following continuity property of the map $\omega \rightarrow \nu(\omega)$.

Lemma 2.3. *The map $\omega \rightarrow \nu(\omega)$ is upper semicontinuous, i. e. if $\omega_{\alpha} \rightarrow \omega$ then*

$$\nu(\omega) \geq \overline{\lim}_{\alpha} \nu(\omega_{\alpha}).$$

Furthermore, if in this situation $\nu(\omega) < \infty$ and $\bar{\nu} = \overline{\lim}_{\alpha} \nu(\omega_{\alpha}) > 0$, then

$$\frac{\nu(\omega)}{\bar{\nu}} \in \{1, 2, 3, \dots\}$$

Remark. Simple examples, like doubling an 8 into a 0, i. e. the standard flow on the Möbius strip, or the flow generated by $y(d/dx)$ on \mathbb{R}^2 , show that $\omega \rightarrow \nu(\omega)$ is not continuous in general.

Proof. If $\underline{p} = \underline{\lim}_{\alpha} p(\omega_{\alpha})$, it is enough to show that $p(\omega) \leq \underline{p}$, and that $\underline{p}/p(\omega)$ is an integer provided $p(\omega) > 0$ and $\underline{p} < \infty$. Assume first that $\underline{p} < \infty$. Then it is enough to show that $S_{\underline{p}} \omega = \omega$. We may assume that $\lim_{\alpha} p(\omega_{\alpha}) = \underline{p}$ exists by passing to a subnet. But as

$$S_{p(\omega_\alpha)}\omega_\alpha = \omega_\alpha$$

for all α , it follows by limiting, and by joint continuity of S , that

$$S_{\underline{p}}\omega = \omega.$$

If $\underline{p} = \infty$, the claim is trivial.

The following characterization of the generator of a flow will be useful, and is an elaboration of the well-known equivalence of weak and strong generators, [7], Corollary 3.1.8.

Lemma 2.4. *Let S be a flow on X , σ the corresponding automorphism group of $C_0(X)$ and δ the generator of σ , i. e. $f \in D(\delta)$ if, and only if, $\lim_{t \rightarrow 0} \|(\sigma_t(f) - f) / t - \delta(f)\| = 0$ for some $\delta(f) \in C_0(X)$.*

The following conditions are equivalent;

1. $f \in D(\delta)$
2. *The limit*

$$g(\omega) \equiv \lim_{t \rightarrow 0} (f(S_t\omega) - f(\omega)) / t$$

exists for each $\omega \in X$, and $g \in C_0(X)$. In this situation $g = \delta(f)$.

Proof. 1 \Rightarrow 2 and the last statement are trivial. Assume 2. Then

$$f(S_t\omega) - f(\omega) = \int_0^t ds \, g(S_s\omega)$$

and hence

$$\begin{aligned} |(f(S_t\omega) - f(\omega)) / t - g(\omega)| &= \left| \frac{1}{t} \int_0^t ds \, (g(S_s\omega) - g(\omega)) \right| \\ &\leq \sup_{|s| \leq |t|} \|\sigma_s(g) - g\|. \end{aligned}$$

But the last number is independent of ω and tends to zero as $t \rightarrow 0$ by strong continuity. Thus $f \in D(\delta)$.

For completeness, we state the following well known result on existence and uniqueness of solutions of first order ordinary differential equations.

Lemma 2.5. (Picard-Lindelöf) *Let $\lambda: \mathbf{R} \rightarrow \mathbf{R}$ be a function which is Lipschitz continuous in the sense that there exists a constant $K > 0$ such that*

$$|\lambda(x) - \lambda(y)| \leq K|x - y|$$

for all $x, y \in \mathbf{R}$. Then the initial-value problem

$$\begin{aligned} \frac{d}{dx} f(x) &= \lambda(f(x)), \\ f(0) &= y, \end{aligned}$$

has a unique solution $f_y : \mathbf{R} \rightarrow \mathbf{R}$ for each $y \in \mathbf{R}$. These solutions satisfy the group property

$$f_y(t+s) = f_{f_y(t)}(s)$$

and hence if we define

$$T_t y = f_y(t)$$

for $y, t \in \mathbf{R}$ then T is a flow on \mathbf{R} .

Remark. If τ is the one-parameter group of *-automorphisms of $C_0(\mathbf{R})$ defined by T , it is easy to see that the generator of τ is an extension of $\delta = \lambda(d/dx)$. We will show in Theorem 2.6 that this generator is the unique generator extension of δ . The Lipschitz condition on λ near the zeros of λ is of prime importance for this proof. If λ is merely continuous and bounded, δ may have a continuum of generator extensions, or none at all, see, for example, [4].

In Theorem 2.12 we show that if, in addition, λ is continuously differentiable, then the closure of δ is the generator of τ . A necessary and sufficient condition for a closed derivation on $C([0, 1])$ to be a generator has been given in [15].

Proof. The existence and uniqueness of the solution f_y follows by the method of successive approximations (see [12]). Since K is independent of x, y , the solution exists on all of \mathbf{R} . Since $\lambda(f)$ does not depend explicitly on x , the group property follows because

$$s \longrightarrow f_y(t+s)$$

$$s \longrightarrow f_{f_y(t)}(s)$$

are both solutions to the initial value problem

$$g'(s) = \lambda(g(s))$$

$$g(0) = f_y(t).$$

The proof of the joint continuity of $(t, y) \rightarrow T_t y$ will be shown in a more general setting in the proof of Theorem 2.6 (see Observation 1). But as $T_{-t} = (T_t)^{-1}$, each T_t is a homeomorphism.

The main theorem of this section is the following.

Theorem 2.6. *Let σ be a strongly continuous one-parameter group of *-automorphisms of an abelian C^* -algebra $\mathcal{A} = C_0(X)$ with generator δ_0 and associated flow S on X , and let $X_0 \subseteq X$ denote the fixed points of S . Assume that λ is a real continuous (not necessarily bounded) function on $X \setminus X_0$ which satisfies bounds of the type*

$$|\lambda(S_t \omega) - \lambda(\omega)| \leq K(\nu(\omega))|t|,$$

where $K : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ is a function which is bounded on bounded intervals. Assume

also that for any compact subset $C \subseteq X$ there exists an $\varepsilon > 0$ such that λ is uniformly bounded on

$$C \cap \{\omega \in X; \nu(\omega) < \varepsilon\}.$$

It follows that the derivation δ defined by

$$\delta f(\omega) = \begin{cases} \lambda(\omega)\delta_0 f(\omega) & \text{if } \omega \in X \setminus X_0 \\ 0 & \text{if } \omega \in X_0 \end{cases}$$

on

$$D(\delta) = \{f \in D(\delta_0); \text{ the right hand function above is in } C_0(X)\}$$

is densely defined and has a unique extension to a generator of a strongly continuous one-parameter group τ of *-automorphisms of \mathcal{A} .

Remark. The low frequency boundedness of λ is necessary because of examples such as $X = \mathbf{R}^2$, $\delta_0 = y(d/dx)$, $\lambda(x, y) = 1/y$.

Proof. We prove the existence part of this theorem by explicitly constructing the flow T corresponding to τ .

If $\omega \in X \setminus X_0$ define a function $\lambda_\omega : \mathbf{R} \rightarrow \mathbf{R}$ by

$$\lambda_\omega(t) = \lambda(S_t \omega).$$

Then

$$\begin{aligned} |\lambda_\omega(t) - \lambda_\omega(s)| &= |\lambda(S_{t-s} S_s \omega) - \lambda(S_s \omega)| \\ &\leq K(\nu(S_s \omega)) |t - s| = K(\nu(\omega)) |t - s| \end{aligned}$$

because ν is constant along S -orbits. It follows from Lemma 2.5 that the initial value problem

$$\begin{aligned} x'_\omega(t) &= \lambda_\omega(x_\omega(t)) \\ x_\omega(0) &= 0 \end{aligned}$$

has a unique solution $t \in \mathbf{R} \rightarrow x_\omega(t)$. Define

$$T_t \omega = S_{x_\omega(t)} \omega$$

for all $t \in \mathbf{R}$, and $\omega \in X \setminus X_0$. If $\omega \in X_0$, define $T_t \omega = \omega$. Then T is the candidate for the new flow generated by an extension of $\delta = \lambda \delta_0$. The group properties $T_t T_s = T_{t+s}$, $T_0 = 1$ follow immediately from Lemma 2.5. (Note that if $\nu(\omega) > 0$, λ_ω is periodic with period $1/\nu(\omega)$, and hence the function $f_y(t)$ of Lemma 2.5 has the property $f_{y+1/\nu(\omega)}(t) = f_y(t) + 1/\nu(\omega)$. Thus the definition of T is consistent).

Observation 1. *The map*

$$(t, \omega) \in \mathbf{R} \times X \longrightarrow T_t \omega \in X$$

is jointly continuous.

Proof. Let $(t_\alpha, \omega_\alpha) \rightarrow (t, \omega)$ in $\mathbf{R} \times X$. We have to show that $T_{t_\alpha} \omega_\alpha \rightarrow T_t \omega$ in X , i. e.

$$S_{x_{\omega_\alpha}(t_\alpha)} \omega_\alpha \longrightarrow S_{x_\omega(t)} \omega.$$

We divide the discussion into two cases.

Case 1. $\nu(\omega) < \infty$.

Since S is jointly continuous, by Lemma 2.2, it suffices to show that $x_{\omega_\alpha}(t_\alpha) \rightarrow x_\omega(t)$. But as

$$|x_\omega(t) - x_{\omega_\alpha}(t_\alpha)| \leq |x_\omega(t) - x_\omega(t_\alpha)| + |x_\omega(t_\alpha) - x_{\omega_\alpha}(t_\alpha)|$$

and $x_\omega(t_\alpha) \rightarrow x_\omega(t)$ it suffices to show that

$$x_\omega(t_\alpha) - x_{\omega_\alpha}(t_\alpha) \longrightarrow 0.$$

For this we first fix a $t_0 > 0$ and seek an estimate for $|x_\omega(t) - x_{\omega_\alpha}(t)|$ on the interval $[0, t_0]$. Now it follows from the differential equation for x that

$$(*) \quad |x_\omega(t) - x_{\omega_\alpha}(t)| \leq \int_0^t ds \, |\lambda_\omega(x_\omega(s)) - \lambda_{\omega_\alpha}(x_{\omega_\alpha}(s))|, \quad t \geq 0.$$

We are assuming that $\nu(\omega) < \infty$, and as $\nu(\omega) \geq \overline{\lim}_\alpha \nu(\omega_\alpha)$ by Lemma 2.3, it follows that the frequencies $\nu(\omega_\alpha)$ are uniformly bounded. Hence it follows from the hypothesis of the theorem that there exists a constant K such that

$$|\lambda_{\omega_\alpha}(x) - \lambda_{\omega_\alpha}(y)| \leq K|x - y|$$

for all $x, y \in \mathbf{R}$ and all α , and the same estimates hold for λ_ω as well. Also, since $\lambda_{\omega_\alpha}(0) = \lambda(\omega_\alpha) \rightarrow \lambda(\omega)$, we can choose the constant K so large that

$$|\lambda_{\omega_\alpha}(0)| \leq K$$

for all α , and then it follows from the previous estimate that

$$|\lambda_{\omega_\alpha}(x)| \leq (|x| + 1)K$$

for all $x \in \mathbf{R}$ and all α .

Now as x_{ω_α} satisfies the differential inequality

$$\begin{aligned} |x'_{\omega_\alpha}(t)| &= |\lambda_{\omega_\alpha}(x_{\omega_\alpha}(t))| \\ &\leq K(1 + |x_{\omega_\alpha}(t)|) \end{aligned}$$

and the unique solution of the differential equation

$$y' = K(1 + y)$$

with $y(0) = 0$ is $y(t) = e^{Kt} - 1$, we obtain the estimates

$$|x_{\omega_\alpha}(t)| \leq e^{Kt} - 1, \quad |x_\omega(t)| \leq e^{Kt} - 1$$

Hence we have the crude first estimate

$$|x_{\omega_\alpha}(t) - x_\omega(t)| \leq 2(e^{Kt} - 1).$$

We also have

$$(**) \quad |\lambda_{\omega_\alpha}(x_{\omega_\alpha}(s)) - \lambda_\omega(x_\omega(s))| \leq |\lambda_{\omega_\alpha}(x_{\omega_\alpha}(s)) - \lambda_{\omega_\alpha}(x_\omega(s))| + |\lambda_{\omega_\alpha}(x_\omega(s)) - \lambda_\omega(x_\omega(s))| \\ \leq K|x_{\omega_\alpha}(s) - x_\omega(s)| + M_\alpha$$

where

$$M_\alpha = \sup\{|\lambda_{\omega_\alpha}(x) - \lambda_\omega(x)|; |x| \leq e^{Kt_0} - 1\}.$$

Now, let M be a constant such that $e^{Ks} - 1 \leq Ms$ for $0 \leq s \leq t_0$. Inserting the crude first estimate into (**) and using $K \leq M$ we find

$$|\lambda_{\omega_\alpha}(x_{\omega_\alpha}(s)) - \lambda_\omega(x_\omega(s))| \leq 2M^2s + M_\alpha,$$

inserting this into (*) we then obtain

$$|x_{\omega_\alpha}(t) - x_\omega(t)| \leq M^2t^2 + M_\alpha t,$$

and inserting this improved estimate into (**) gives

$$|\lambda_{\omega_\alpha}(x_{\omega_\alpha}(s)) - \lambda_\omega(x_\omega(s))| \leq M^3s^2 + M_\alpha Ms + M_\alpha.$$

Reinserting this into (*) and iterating we finally find

$$|x_{\omega_\alpha}(t) - x_\omega(t)| \leq 2 \frac{M^n t^n}{n!} + \frac{M_\alpha}{M} \left(Mt + \frac{M^2 t^2}{2!} + \dots + \frac{M^{n-1} t^{n-1}}{(n-1)!} \right),$$

and

$$|\lambda_{\omega_\alpha}(x_{\omega_\alpha}(s)) - \lambda_\omega(x_\omega(s))| \leq 2 \frac{M^{n+1} s^n}{n!} + M_\alpha \left(1 + Ms + \frac{M^2 s^2}{2!} + \dots + \frac{M^{n-1} s^{n-1}}{(n-1)!} \right),$$

for all n . Thus

$$|x_{\omega_\alpha}(t) - x_\omega(t)| \leq M_\alpha(e^{Mt} - 1)/M,$$

where M and M_α are independent of $t \in [0, t_0]$. It follows that if $0 < t < t_0$ and $\lim t_\alpha = t$, so that $t_\alpha \in [0, t_0]$ for $\alpha \geq \alpha_0$, then

$$|x_{\omega_\alpha}(t_\alpha) - x_\omega(t_\alpha)| \leq M_\alpha(e^{Mt_0} - 1)/M \quad \text{for } \alpha \geq \alpha_0.$$

But since $\lambda_{\omega_\alpha}(s) = \lambda(S_s \omega_\alpha)$ converges pointwise in s to $\lambda_\omega(s) = \lambda(S_s \omega)$, and these functions are uniformly Lipschitz continuous, it follows that the convergence is uniform in compacts, and hence

$$M_\alpha = \sup\{|\lambda_{\omega_\alpha}(x) - \lambda_\omega(x)|; |x| \leq e^{Kt_0} - 1\} \rightarrow 0.$$

Consequently $|x_{\omega_\alpha}(t_\alpha) - x_\omega(t_\alpha)| \rightarrow 0$ and thus

$$\lim_\alpha x_{\omega_\alpha}(t_\alpha) = x_\omega(t).$$

The case $t (= \lim t_\alpha) \leq 0$ is treated similarly, and thus the proof of Case 1 is complete.

Case 2. $\nu(\omega) = \infty$, i. e. $\omega \in X_0$.

By passing to subnets it suffices to consider the following two situations :

Case 2.1. $\nu(\omega_\alpha) \rightarrow 0$.

By the low frequency boundedness of λ it follows that $\lambda(\omega_\alpha)$ is bounded in α , and combining this with the Lipschitz condition we deduce as in Case 1 that the functions x_{ω_α} are uniformly bounded on compact intervals, e. g.

$$|x_{\omega_\alpha}(t_\alpha)| \leq K \text{ for all } \alpha.$$

Again passing to a subnet, we can assume that $x_{\omega_\alpha}(t_\alpha) \rightarrow x$, and then it follows from the joint continuity of S that

$$T_{t_\alpha} \omega_\alpha = S_{x_{\omega_\alpha}(t_\alpha)} \omega_\alpha \longrightarrow S_x \omega = \omega.$$

Case 2.2. There is an $\varepsilon > 0$ such that $\varepsilon \leq \nu(\omega_\alpha)$ for all α .

Then

$$T_{t_\alpha} \omega_\alpha \subseteq S_R \omega_\alpha = S_{[0, 1/\varepsilon]} \omega_\alpha$$

for all α . Proceeding as in case 2.1 we deduce that

$$T_{t_\alpha} \omega_\alpha \longrightarrow \omega$$

This ends the proof of Observation 1, and it now follows from Lemma 2.2 that T determines a strongly continuous one-parameter group τ of *-automorphisms of $C_0(X)$ through

$$(\tau_t f)(\omega) = f(T_t \omega),$$

for $f \in C_0(X)$, $t \in \mathbf{R}$, $\omega \in X$. Let δ_T denote the generator of this group.

Observation 2. δ_T is an extension of δ .

Proof. By Lemma 2.4 it suffices to prove that

$$\lim_{t \rightarrow 0} (f(T_t \omega) - f(\omega)) / t = \lambda(\omega)(\delta_0 f)(\omega)$$

for all $\omega \in X \setminus X_0$ and all $f \in D(\delta_0)$. But

$$\begin{aligned} (f(T_t \omega) - f(\omega)) / t &= (f(S_{x_{\omega_\alpha}(t)} \omega) - f(\omega)) / t \longrightarrow (\delta_0 f)(\omega) \cdot x'_\omega(0) \\ &= \lambda(\omega)(\delta_0 f)(\omega) \end{aligned}$$

by the differential equation for x_ω and the chain rule.

Observations 1 and 2 establish the existence of the generator extension of δ . It remains to prove density of $D(\delta)$ and the uniqueness of the flow T . To do this and subsequently to discuss the generator δ_T of the flow T , we introduce "high frequency cutoffs", that is, algebras of functions which are constant on orbits of sufficiently high frequency. Recalling that $\mathcal{A}_n = D(\delta_0^n)$ and $\mathcal{A}_\infty = \bigcap_{n \geq 1} \mathcal{A}_n$, we define

$$\mathcal{D}_n = \{f \in \mathcal{A}_n; f \text{ has compact support and there exists an } M > 0 \text{ such that } f(S_t\omega) = f(\omega) \text{ whenever } \nu(\omega) \geq M \text{ and } t \in \mathbf{R}\}$$

where $n=0, 1, 2, \dots, \infty$. Then \mathcal{D}_n is clearly a *-algebra which is invariant under σ . Moreover \mathcal{D}_0 is also invariant under τ .

Lemma 2.7.

- (a) If $f \in \mathcal{A}_\infty$ has compact support in $X \setminus X_0$, then $f \in \mathcal{D}_\infty \cap D(\delta)$.
- (b) If $f \in C_0(X_0)$ has compact support and \mathcal{A} is a compact subset of $X \setminus X_0$, then there is a function $g \in \mathcal{D}_\infty \cap D(\delta)$ with compact support such that $g|_{X_0} = f$ and $g|_{\mathcal{A}} = 0$.
- (c) $\mathcal{D}_\infty \cap D(\delta)$ is dense in \mathcal{A} .
- (d) If $\omega \in X \setminus X_0$ and $f \in C(S_{[-1,1]}\omega)$ is a function such that $t \rightarrow f(S_t\omega)$ is infinitely often differentiable on $[-1, 1]$, then there is a $g \in \mathcal{D}_\infty \cap D(\delta)$ with compact support in $X \setminus X_0$ such that g extends f .

Proof.

(a) It follows from the upper semi-continuity of ν , Lemma 2.3, that ν is bounded on the compact set $\text{supp}(f)$. Hence f is zero on orbits of sufficiently high frequency. Also $\lambda\delta_0(f)$ is continuous with compact support on $X \setminus X_0$. Hence $f \in \mathcal{D}_\infty \cap D(\delta)$.

(b) Let V be an open neighbourhood of $\text{supp}(f)$ with compact closure. By hypothesis there is an $\varepsilon_0 > 0$ such that λ is bounded on

$$\bar{V} \cap \{\omega; \nu(\omega) < \varepsilon_0\}.$$

Let W be an open neighbourhood of $\text{supp}(f)$ such that

$$\bar{W} \subseteq V \setminus S_{[-2, (1/\varepsilon_0)+2]}\mathcal{A},$$

and let h be a continuous extension of f to the closed set

$$X_{\varepsilon_0} = \{\omega; \nu(\omega) \geq \varepsilon_0\}$$

with compact support in $W \cap X_{\varepsilon_0}$. Then define a function k on X_{ε_0} by taking the mean over each orbit, i. e.

$$k(\omega) = \begin{cases} \nu(\omega) \int_0^{1/\nu(\omega)} dt h(S_t\omega) & \text{if } \omega \in X_{\varepsilon_0} \setminus X_0 \\ h(\omega) & \text{if } \omega \in X_0. \end{cases}$$

Since $\nu(\omega) \geq \varepsilon_0$ on X_{ε_0} , it follows that k is well-defined, k has compact support in $S_{[-(1/\varepsilon_0), 0]}(\text{supp}(h)) \subseteq S_{[-(1/\varepsilon_0), 0]}\bar{W} \cap X_{\varepsilon_0}$, and k is constant on orbits in X_{ε_0} . We now argue that k is continuous.

Let ω_α be a net in X_{ε_0} such that $\omega_\alpha \rightarrow \omega'$ in X_{ε_0} . Then

$$\nu(\omega') \geq \overline{\lim} \nu(\omega_\alpha) \geq \varepsilon_0.$$

By passing to subsets we may assume that $\nu_0 = \lim_{\alpha} \nu(\omega_{\alpha})$ exists as a finite positive number or as $+\infty$. We therefore divide the discussions into these two cases.

Case 1. $\varepsilon_0 \leq \nu_0 < \infty$.

Since $1/\nu_0$ is a period for $t \rightarrow h(S_t \omega')$ by Lemma 2.3, we have

$$k(\omega') = \nu_0 \int_0^{1/\nu_0} dt \, h(S_t \omega'),$$

and

$$k(\omega_{\alpha}) = \nu(\omega_{\alpha}) \int_0^{1/\nu(\omega_{\alpha})} dt \, h(S_t \omega_{\alpha}).$$

Since the family of functions $t \rightarrow h(S_t \omega_{\alpha})$ converges pointwise to $t \rightarrow h(S_t \omega')$ and this family is uniformly equicontinuous by the strong continuity of σ , it follows that the convergence is uniform on $[0, 1/\nu_0]$ and hence

$$k(\omega') = \lim_{\alpha} k(\omega_{\alpha}).$$

Case 2. $\nu_0 = \infty$.

In this case $\nu(\omega') = \infty$, i. e. $\omega' \in X_0$, and $k(\omega') = h(\omega')$. Hence

$$|k(\omega_{\alpha}) - k(\omega')| \leq |k(\omega_{\alpha}) - h(\omega_{\alpha})| + |h(\omega_{\alpha}) - h(\omega')|.$$

The latter term converges to zero and the former is dominated by

$$\sup \{ \|\sigma_t h - h\| ; 0 \leq t \leq 1/\nu_{\alpha} \},$$

which also converges to zero by strong continuity of σ .

This completes the proof that k is continuous on X_{ε_0} .

Next extend k to a continuous function on X , also denoted k , with compact support in the open set $S_{[-1/\varepsilon_0, 0]}W$. Let $\phi \in C^{\infty}(\mathbb{R})$ be a positive function with support in $[-1, 1]$ and with total integral one, and define

$$g(\omega) = \int dt \, \phi(t) \, k(S_t \omega).$$

Clearly $g \in \mathcal{D}_{\infty}$, $g|_{X_0} = f$, and

$$\text{supp}(g) \subseteq S_{[-1, 1]} \text{supp}(k) \subseteq S_{[-1/\varepsilon_0 - 1, 1]}W,$$

which is disjoint from \mathcal{A} . It remains to show that $g \in D(\delta)$.

Given a net ω_{α} in $X \setminus X_0$ converging to a point $\omega_0 \in X_0$, we have to show that $\lim_{\alpha} \lambda(\omega_{\alpha}) \delta_0(g)(\omega_{\alpha}) = 0$. It suffices to show that any subnet of this net has in turn a subnet such that $\lambda \delta_0(g)$ has limit zero over the subnet. If $\delta_0(g)(\omega_{\alpha})$ is eventually zero, there is nothing to do; otherwise we can extract a subnet (also called ω_{α}) such that $\delta_0(g)(\omega_{\alpha}) \neq 0$ for all α . It then follows that $\nu(\omega_{\alpha}) < \varepsilon_0$ and $\omega_{\alpha} \in \text{Supp}(\delta_0(g)) \subseteq \text{Supp}(g) \subseteq S_{[-1/\varepsilon_0 - 1, 1]}W$. Hence for each α there is

$t_\alpha \in [-1, (1/\varepsilon_0)+1]$ such that $S_{t_\alpha}\omega_\alpha \in W$, and passing again to a subnet, we can arrange that $t_0 = \lim_\alpha t_\alpha$ exists, and therefore

$$S_{t_\alpha}\omega_\alpha \longrightarrow S_{t_0}\omega_0 = \omega_0.$$

But this means that $\omega_0 \in \overline{W} \subseteq V$, so that $\omega_\alpha \in V$ eventually. We can assume (by again going to a subnet) that for all α

$$\omega_\alpha \in V \cap \{\omega; \nu(\omega) < \varepsilon_0\}.$$

Since λ is bounded on this set and $\delta_0(g)(\omega_\alpha) \rightarrow 0$, we obtain the desired conclusion.

(c) It follows from (a) and (b) that the *-algebra $\mathcal{D}_\infty \cap D(\delta)$ separate points of X and is zero at no point of X . Thus (c) follows from the Stone-Weierstrass theorem.

(d) It follows from [9], Théorème 3.1, that there exists a finite number m of functions $\phi_i \in C^\infty(\mathbf{R})$ with $\text{supp}(\phi_i) \subseteq [-1, 1]$ and functions $h_i \in C^\infty(S_{[-2, 2]}\omega)$ such that

$$f(S_t\omega) = \sum_{i=1}^m \int_{-1}^1 ds \phi_i(s) h_i(S_{s+t}\omega)$$

for $|t| < 1$. Extend each h_i to a continuous function on X with compact support in $X \setminus X_0$ and define

$$g = \sum_{i=1}^m \int_{-1}^1 ds \phi_i(s) \sigma_s(h_i).$$

Then $g(S_t\omega) = f(S_t\omega)$ for $|t| \leq 1$, $g \in \mathcal{A}_\infty$, and g has compact support in $X \setminus X_0$. By part (a), $g \in \mathcal{D}_\infty \cap D(\delta)$.

This ends the proof of Lemma 2.7, and also establishes that $D(\delta)$ is dense in Theorem 2.6. Our next task is to prove uniqueness of the flow T constructed above. Therefore, let U be another flow on X such that the generator δ_U of the associated automorphism group extends δ . In order to show $U = T$ we need the following general lemma.

Lemma 2.8. *If U and S are general flows on a locally compact Hausdorff space X , and for each $\omega \in X$ there exists an $\varepsilon > 0$ such that $U_{\langle -\varepsilon, \varepsilon \rangle}\omega \subseteq S_R\omega$, then $U_R\omega \subseteq S_R\omega$ for all $\omega \in X$.*

Proof. Let $t \in \mathbf{R}$, we have to show $U_t\omega \subseteq S_R\omega$ for all $\omega \in X$. By compactness of $[-|t|, |t|]$ there is a finite subset t_1, \dots, t_n of $[-|t|, |t|]$ and positive constant $\varepsilon_1, \dots, \varepsilon_n$ such that

$$[-|t|, |t|] \subseteq \bigcup_k \langle t_k - \varepsilon_k, t_k + \varepsilon_k \rangle$$

and

$$U_{\langle t_k - \varepsilon_k, t_k + \varepsilon_k \rangle}\omega \subseteq S_R U_{t_k}\omega$$

But as two S-orbits are either equal or disjoint, it follows that if two of the intervals $\langle t_k - \varepsilon_k, t_k + \varepsilon_k \rangle$ and $\langle t_m - \varepsilon_m, t_m + \varepsilon_m \rangle$ overlap, $U_{\langle t_k - \varepsilon_k, t_k + \varepsilon_k \rangle} \omega$ and $U_{\langle t_m - \varepsilon_m, t_m + \varepsilon_m \rangle} \omega$ are contained in the same S-orbit. Since any two elements in $[-|t|, |t|]$ can be connected by a finite number of the intervals $\langle t_k - \varepsilon_k, t_k + \varepsilon_k \rangle$, it follows that all $U_{\langle t_k - \varepsilon_k, t_k + \varepsilon_k \rangle} \omega$ are contained in one S-orbit, namely $S_R \omega$. Thus $U_{[-|t|, |t|]} \omega \subseteq S_R \omega$ and hence $U_R \omega \subseteq S_R \omega$.

Returning to the proof of Theorem 2.6, let U be the flow on X whose generator δ_U extends δ .

Observation 3. $U_R \omega \subseteq S_R \omega$ for all $\omega \in X$.

Proof. We argue by contradiction. If the statement is false, it follows from Lemma 2.8 that there exist an $\omega \in X$ and a sequence $t_n \in \mathbf{R} \setminus \{0\}$ such that $t_n \rightarrow 0$ but $U_{t_n} \omega \in S_R \omega$ for $n=1, 2, \dots$. But then $S_R U_{t_n} \omega \cap S_R \omega = \emptyset$ for all n since two S-orbits are either equal or disjoint. Next set $\omega_n = U_{t_n} \omega$. Since $\omega_n \rightarrow \omega$ one sees by induction that there is a subsequence of ω_n , which we also denote by ω_n , such that

$$\omega_n \in \left(\bigcup_{k=1}^{n-1} S_{[-3, 3]} \omega_k \right) \cup S_{[-4, 4]} \omega.$$

But then all the closed sets $S_{[-1, 1]} \omega_n$ are disjoint and we may define a function f on

$$C = \left(\bigcup_n S_{[-1, 1]} \omega_n \right) \cup S_{[-2, 2]} \omega$$

by $f(\omega') = t_n$ if $\omega' \in S_{[-1, 1]} \omega_n$ and $f(\omega') = 0$ if $\omega' \in S_{[-2, 2]} \omega$. Since $\omega_n \rightarrow \omega$, the set C is compact and the function f is continuous on C . Again there are two cases.

Case 1. $\omega \in X \setminus X_0$.

Then $\overline{\lim} \nu(\omega_n) \leq \nu(\omega) < \infty$ and hence ν is uniformly bounded on C . By upper semi-continuity of ν and compactness of C it follows that ν is uniformly bounded in a neighbourhood of C . Let g be a continuous extension of f which vanishes outside this neighbourhood; then ν is uniformly bounded on $\text{supp}(g)$. Next let φ be a positive C^1 -function on \mathbf{R} with support in $[-1, 1]$ and total integral one. Define

$$h = \int dt \varphi(t) \sigma_t(g).$$

Then $h \in D(\delta_0)$ and ν , and hence λ , is uniformly bounded on $\text{supp}(h)$. Thus $h \in D(\delta)$. Also

$$\begin{aligned} h(\omega_n) &= \int dt \varphi(t) g(S_t \omega_n) \\ &= \int dt \varphi(t) t_n = t_n \end{aligned}$$

and as $h(S_t\omega)=0$ for $|t|<1$ we have

$$\begin{aligned} h(U_t\omega) &= h(\omega) + t(\delta h)(\omega) + o(t) \\ &= o(t). \end{aligned}$$

Since $h(U_{t_n}\omega)=t_n$ this is a contradiction. Thus $U_R\omega \subseteq S_R\omega$ if $\omega \in X \setminus X_0$.

Case 2. $\omega \in X_0$.

Let D be a neighbourhood of C with compact closure \bar{D} . By the assumption on λ , there exists an $\varepsilon > 0$ such that λ is uniformly bounded on

$$S_{[-1,1]}\bar{D} \cap \{\omega' ; \nu(\omega') < \varepsilon\}$$

By passing to subsequences of ω_n , we may consider three subcases.

Case 2.1. $\nu(\omega_n) < \varepsilon$ for all n .

In this case we extend f by first defining $f=0$ on the closed sets $\{\omega' | \nu(\omega') \geq \varepsilon\}$ and $X \setminus D$, and then extending f arbitrarily to a function in $C_0(X)$. Let ϕ be a positive C^1 -function on \mathbf{R} with support in $[-1, 1]$ and total integral one. Define

$$h = \int dt \phi(t) \sigma_t(g)$$

Then $h \in D(\delta_0)$, $\text{supp } h \subseteq S_{[-1,1]}\bar{D}$ and $h=0$ on $\{\omega' ; \nu(\omega') \geq \varepsilon\}$, and thus $\delta_0 h=0$ on the latter S -invariant set. It follows that λ is uniformly bounded on $\{\omega' ; \langle \delta_0 h \rangle(\omega') \neq 0\}$, and thus $h \in D(\delta)$. As $h(\omega_n)=t_n$, we deduce a contradiction as in Case 1.

Case 2.2. $\infty > \nu(\omega_n) > \varepsilon$ for all n .

Note that the argument in Case 1 actually established that if $\omega' \in X \setminus X_0$, there exists an $\varepsilon > 0$ such that $U_{\langle -\varepsilon, \varepsilon \rangle} \omega' \subseteq S_R \omega'$. Thus $\{t ; U_t \omega' \subseteq S_R \omega'\}$ is open. But if $\nu(\omega') \neq 0$, i.e. $S_R \omega'$ is closed and homeomorphic to a circle, then the set is also closed, and hence it is equal to \mathbf{R} . We have thus shown that $U_R \omega' \subseteq S_R \omega'$ if $\infty > \nu(\omega') > 0$. Hence Case 2.2. cannot occur, as ω is contained in the U_R -orbit through ω_n for any n .

Case 2.3. $\nu(\omega_n) = \infty$ for all n .

Then $\omega_n \in X_0$ for all n , and f extends to a function h in $D(\delta)$ by Lemma 2.7. b. As $h(\omega_n)=t_n$, we obtain a contradiction as in Case 1.

To finish the proof of $U=T$ we need another general lemma, which is known (see Appendix 2 in [13]).

Lemma 2.9. *If U and S are flows on X and $U_R \omega \subseteq S_R \omega$ for all $\omega \in X$, then*

there exists for each $\omega \in X$ a continuous function $y_\omega : \mathbf{R} \rightarrow \mathbf{R}$ such that $y_\omega(0) = 0$ and $U_t \omega = S_{y_\omega(t)} \omega$ for all $t \in \mathbf{R}$. The function y_ω is uniquely determined by the continuity requirement if $\omega \in X \setminus X_0$, and if $\omega \in X_0$ we may put $y_\omega(t) = 0$ for all t , where X_0 denotes the set of fixed points for the flow S .

Proof. If $\nu(\omega) > 0$, then $S_{\mathbf{R}} \omega$ is closed in X and is homeomorphic to the circle \mathbf{T} , and the restriction of U to $S_{\mathbf{R}} \omega$ is a one-parameter group of homeomorphisms of the circle, from which the existence and uniqueness of y_ω is immediate.

If $\nu(\omega) = 0$, then the map $t \rightarrow S_t \omega$ is one to one, and thus there exists a unique function $y_\omega(t)$ such that $U_t \omega = S_{y_\omega(t)} \omega$ for all $t \in \mathbf{R}$. Clearly $y_\omega(0) = 0$ and it remains to show that y_ω is continuous. But continuity is clear once we can show that for any $T > 0$ there is an $N > 0$ such that $U_{[-T, T]} \omega \subseteq S_{[-N, N]} \omega$, because the map $t \in [-N, N] \rightarrow S_t \omega$ is a homeomorphism (although the map $t \in \mathbf{R} \rightarrow S_t \omega$ is not necessarily a homeomorphism if the orbit $S_{\mathbf{R}} \omega$ is not closed in X). The proof of the existence of N does not follow from straightforward Baire category arguments, but reduces to the following topological lemma: The interval $[0, 1]$ is not a countable union of disjoint non-empty closed sets. See the proof of Theorem 2.50 in [13] for the complete argument.

We now finish the proof that $U = T$. Let $y_\omega(t)$ be the functions defining the flow U by Observation 3 and Lemma 2.9. It suffices to show that $y_\omega(t) = x_\omega(t)$ for all $\omega \in X$ and $t \in \mathbf{R}$. This is trivial if $\omega \in X_0$. If $\omega \in X \setminus X_0$, define

$$V = \{t \in \mathbf{R}; y_\omega(t) = x_\omega(t)\}$$

Then $0 \in V$ and V is closed, so if we can prove that V is open, then $V = \mathbf{R}$ and the theorem is proved. So let $t_0 \in V$ and put $\omega_0 = S_{x_{\omega_0}(t_0)} \omega = T_{t_0} \omega = U_{t_0} \omega$. We have to show that $T_t \omega_0 = U_t \omega_0$ for t in a neighbourhood of zero. But as $\omega_0 \in X \setminus X_0$, $t \rightarrow S_t \omega_0$ is 1-1 in a neighbourhood $[-\varepsilon, \varepsilon]$ of zero, and by Lemma 2.7. d, there exists a function $g \in D(\delta)$ such that $g(S_t \omega_0) = t$ for $|t| \leq \varepsilon$. Choose $\eta > 0$ so that $|y_{\omega_0}(t)| \leq \varepsilon$, $|x_{\omega_0}(t)| \leq \varepsilon$ for $|t| < \eta$. Then

$$y_{\omega_0}(t) = g(S_{y_{\omega_0}(t)} \omega_0) = g(U_t \omega_0)$$

and $x_{\omega_0}(t) = g(T_t \omega_0)$ for $|t| < \eta$. Since $g \in D(\delta) \subseteq D(\delta_U)$, it follows that y_{ω_0} is differentiable for $|t| \leq \eta$ and

$$\begin{aligned} y'_{\omega_0}(t) &= (\delta_U g)(U_t \omega_0) = (\delta g)(U_t \omega_0) \\ &= \lambda(U_t \omega_0)(\delta_0 g)(U_t \omega_0) \\ &= \lambda_{\omega_0}(y_{\omega_0}(t)) \end{aligned}$$

since $(\delta_0 g)(S_s \omega_0) = 1$ for $|s| \leq \varepsilon$. But the unique solution of this equation with $y_{\omega_0}(0) = 0$ is

$$y_{\omega_0}(t) = x_{\omega_0}(t)$$

by Lemma 2.5. Thus $U_t\omega_0 = T_t\omega_0$ for $|t| < \eta$, and thus $U = T$.

This concludes the proof of Theorem 2.6.

Although Theorem 2.6 establishes that δ has a unique generator extension δ_T and Lemma 2.7 gives some rudimentary information about $D(\delta_T)$, it is unclear whether the assumptions are sufficient to ensure that $\delta_T = \bar{\delta}$, the closure of δ . This stronger form of uniqueness follows, however, if one assumes a stronger smoothness property for λ . As a preliminary to deriving this result we prove the following lemmas.

Lemma 2.10. *Adopt the assumptions of Theorem 2.6, and let δ_T denote the unique generator extension of δ . Then for all $g \in D(\delta_T)$ and all $\omega \in X \setminus X_0$ such that $\lambda(\omega) \neq 0$, the limit*

$$\delta_0(g)(\omega) \equiv \lim_{t \rightarrow 0} (g(S_t\omega) - g(\omega))/t$$

exists, and furthermore

$$\delta_T(g)(\omega) = \lambda(\omega)\delta_0(g)(\omega).$$

Proof. Let g and ω be as in the statement of the lemma, and define $g_\omega(t) = g(S_t\omega)$ and $\lambda_\omega(t) = \lambda(S_t\omega)$. As in the proof of Theorem 2.6 let x_ω be the unique solution of the initial value problem

$$x'_\omega(t) = \lambda_\omega(x_\omega(t)), \quad x_\omega(0) = 0.$$

Then x_ω is a C^1 -function with non-zero derivative at $t=0$ and therefore has a C^1 -inverse y_ω in a neighbourhood of $t=0$. Now since $g \in D(\delta_T)$, $g_\omega(x_\omega(s)) = g(T_s\omega)$ is a C^1 -function of s and $(g_\omega \circ x_\omega)'(0) = \delta_T(g)(\omega)$. Therefore $g_\omega = (g_\omega \circ x_\omega) \circ y_\omega$ is a C^1 -function near zero whose derivative at zero is

$$g'_\omega(0) = \delta_T(g)(\omega) y'_\omega(0) = \delta_T(g)(\omega) / \lambda(\omega).$$

But $g'_\omega(0) = d/ds|_{s=0} g(S_s\omega)$, so both the existence of this derivative and the formula for $\delta_T(g)(\omega)$ are established.

Lemma 2.11. *Adopt the assumption of Theorem 2.6, but further assume that λ is differentiable in the sense that*

$$\delta_0(\lambda) \equiv \lim_{t \rightarrow 0} (\lambda(S_t\omega) - \lambda(\omega))/t$$

exists pointwise and is a continuous function of $\omega \in X \setminus X_0$.

(a) *The formula*

$$\lambda(T_t\omega) = \exp \left\{ \int_0^t ds (\delta_0(\lambda))(T_s\omega) \right\} \lambda(\omega)$$

is valid for $\omega \in X \setminus X_0$ and $t \in \mathbf{R}$.

(b) *If $f \in \mathcal{D}(\delta)$, then*

$$(*) \quad \delta_0(f \circ T_t)(\omega) = \exp \left\{ \int_0^t ds (\delta_0 \lambda)(T_s \omega) \right\} (\delta_0 f)(T_t \omega)$$

for all $\omega \in X \setminus X_0$, where the δ_0 on the left side is defined as in the heading of the lemma.

(c) If $f \in \mathcal{D}_1 \cap D(\delta)$, then $(f \circ T_t) \in \mathcal{D}_1 \cap D(\delta)$ for all $t \in \mathbf{R}$.

Remark. Our main purpose here is to establish that $\mathcal{D}_1 \cap D(\delta)$ is invariant under the group τ_t , and for this we need to show that for $f \in \mathcal{D}_1 \cap D(\delta)$ and $t \in \mathbf{R}$, $(f \circ T_t) \in D(\delta_0)$. But by Lemma 2.4 it suffices to show that the pointwise derivative $\delta_0(f \circ T_t)(\omega) \equiv \lim_{s \rightarrow 0} ((f \circ T_t)(S_s \omega) - f \circ T_t(\omega))/s$ exists and defines a continuous function on X . Since $f \in D(\delta) \subseteq D(\delta_T)$, $f \circ T_t$ also lies in $D(\delta_T)$ and Lemma 2.10 already shows that $\delta_0(f \circ T_t)(\omega) = \lambda(\omega)^{-1} \delta_T(f \circ T_t)(\omega)$ exists and is continuous on $Y = \{\omega \in X \setminus X_0; \lambda(\omega) \neq 0\}$. But in order to prove the existence and continuity of $\delta_0(f \circ T_t)(\omega)$ on all of X we have to establish the formula (*) in the statement of the lemma.

Proof.

(a) The hypothesis on λ implies that λ_ω is a C^1 -function with derivative $\lambda'_\omega = (\delta_0 \lambda)_\omega$. Thus by the chain rule,

$$\frac{d}{dt} \lambda_\omega(x_\omega(t)) = \lambda'_\omega(x_\omega(t)) x'_\omega(t) = \lambda'_\omega(x_\omega(t)) \lambda_\omega(x_\omega(t))$$

The unique solution of this equation with $\lambda_\omega(x_\omega(0)) = \lambda_\omega(0)$ is

$$\lambda_\omega(x_\omega(t)) = \exp \left\{ \int_0^t ds \lambda'_\omega(x_\omega(s)) \right\} \lambda_\omega(0).$$

On the space X the relation reads

$$\lambda(T_t \omega) = \exp \left\{ \int_0^t ds (\delta_0 \lambda)(T_s \omega) \right\} \lambda(\omega),$$

which proves the first formula in the statement of the lemma.

(b) If $f \in D(\delta) \subseteq D(\delta_T)$, $f \circ T_t$ lies in $D(\delta_T)$ and

$$\delta_T(f \circ T_t) = (\delta_T f) \circ T_t.$$

For $\omega \in Y = \{\omega' \in X \setminus X_0; \lambda(\omega') \neq 0\}$ we evaluate the left-hand side using Lemma 2.10 and obtain the equation

$$\begin{aligned} \lambda(\omega) \delta_0(f \circ T_t)(\omega) &= \lambda(T_t \omega) (\delta_0 f)(T_t \omega) \\ &= \lambda(\omega) \exp \left\{ \int_0^t ds (\delta_0 \lambda)(T_s \omega) \right\} (\delta_0 f)(T_t \omega). \end{aligned}$$

Cancelling the factor $\lambda(\omega)$ gives the desired formula (*) for all $\omega \in Y$.

Next suppose that $\omega \in X \setminus X_0$, but $\lambda(\omega) = 0$. Then $T_t \omega = \omega$ for all t . Let V be the flow on \mathbf{R} corresponding to the flow T on $S_{\mathbf{R}} \omega$, i. e. $V_t(y)$ is determined by the usual continuity requirements and

$$S_{V_t(y)}\omega = T_t S_y \omega, \quad t \in \mathbf{R}, \quad y \in \mathbf{R}.$$

Then

$$V_t(y) = x_{S_y(\omega)}(t) + y$$

and since V is the flow on \mathbf{R} determined by the vector field $\lambda_\omega(y)d/dy$, and $\lambda_\omega(0)=0$, we have

$$\frac{d}{dt} V_t(y) = \lambda_\omega(V_t(y)) = \lambda'_\omega(0)V_t y + o(V_t y)$$

where we used Taylors formula, and the fact that λ_ω is continuously differentiable. This formula can be written

$$\frac{d}{dt} (e^{-t\lambda'_\omega(0)} V_t(y)) = e^{-t\lambda'_\omega(0)} o(V_t(y))$$

where $o(\cdot)$ is a function depending only on λ_ω such that $\lim_{h \rightarrow 0} o(h)/h = 0$. Integrating, and using $V_0(y) = y$, we get

$$\begin{aligned} V_t(y) &= e^{t\lambda'_\omega(0)} y + e^{t\lambda'_\omega(0)} \int_0^t ds \, e^{-s\lambda'_\omega(0)} o(V_s(y)) \\ &= e^{t\lambda'_\omega(0)} \left[y + \int_0^t ds \, e^{-s\lambda'_\omega(0)} \left[\frac{o(V_s y)}{V_s y} \right] V_s y \right]. \end{aligned}$$

Feeding the expression for $V_s y$ back into the integral and iterating we arrive finally at the expression

$$V_t y = e^{t\lambda'_\omega(0)} y (1 + O(t, y))$$

where $O(\cdot)$ satisfies $\lim_{y \rightarrow 0} O(t, y) = 0$ for all t . Hence $\partial/\partial y|_{y=0} V_t y = e^{t\lambda'_\omega(0)}$. For $f \in D(\delta)$,

$$(f \circ T_t)(S_s \omega) = f(T_t S_s \omega) = f_\omega(V_t s),$$

where $f_\omega(x) = f(S_x \omega)$ as usual. Therefore by the chain rule

$$\begin{aligned} \delta_0(f \circ T_t)(\omega) &= \frac{d}{ds} \Big|_{s=0} (f \circ T_t)(S_s \omega) \\ &= f'_\omega(V_t 0) \frac{\partial}{\partial s} \Big|_{s=0} V_t s \\ &= f'_\omega(0) \exp\{t\lambda'_\omega(0)\} \\ &= (\delta_0 f)(\omega) \exp\{t\delta_0(\lambda)(\omega)\}, \end{aligned}$$

using the facts that $f \in D(\delta_0)$ and $V_t 0 = 0$ for all t . This establishes that $\delta_0(f \circ T_t)(\omega)$ exists, and since $T_s \omega = \omega$ for all s , $\delta_0(f \circ T_t)(\omega)$ is given by the formula (*) in this case as well.

(c) Let $f \in \mathcal{D}_1 \cap D(\delta)$ and $t \in \mathbf{R}$. First we show that $f \circ T_t \in D(\delta_0)$. By part (b), $\delta_0(f \circ T_t)(\omega)$ exists, as a pointwise derivative, at all $\omega \in X$ and is given by the formula

$$(*) \quad \delta_0(f \circ T_t)(\omega) = \begin{cases} \exp \left\{ \int_0^t ds (\delta_0 \lambda)(T_s \omega) \right\} (\delta_0 f)(T_t \omega) & \text{if } \omega \in X \setminus X_0, \\ 0 & \text{if } \omega \in X_0. \end{cases}$$

Since $f \in \mathcal{D}_1$, f has compact support, thus $f \circ T_t$ and then $\delta_0(f \circ T_t)$ have compact supports. Thus by Lemma 2.4, to show that $f \circ T_t \in D(\delta_0)$, it suffices to show the continuity of the right hand side of (*). As f is constant on orbits of frequency larger than a certain M , $(\delta_0 f)(T_t \omega) = 0$ if $\nu(\omega) \geq M$. Thus it suffices to verify

$$\lim_{\alpha} \delta_0(f \circ T_t)(\omega_{\alpha}) = \delta_0(f \circ T_t)(\omega)$$

for convergent nets $\omega_{\alpha} \rightarrow \omega$ such that $\nu(\omega_{\alpha}) < M$ for all α . The other cases are trivial due to the upper semicontinuity of ν . Thus two cases remain.

Case 1. $\nu(\omega) < \infty$.

Because of the formula (*) and the continuity of $(\delta_0 f) \circ T_t$ it suffices to show

$$\int_0^t ds (\delta_0 \lambda)(T_s \omega_{\alpha}) \longrightarrow \int_0^t ds (\delta_0 \lambda)(T_s \omega)$$

The integrands converge pointwise on $[0, t]$ by continuity of $\delta_0 \lambda$ on $X \setminus X_0$. Let ψ be a continuous function with compact support in $X \setminus X_0$ such that

$$\delta_0 \lambda(T_s \omega') = \psi(T_s \omega') = \tau_s(\psi)(\omega')$$

for all $\omega' \in \{\omega_{\alpha}\} \cup \{\omega\}$ and $s \in [0, t]$. Then the norm continuity of $s \rightarrow \tau_s \psi$ implies that the integrands are uniformly equicontinuous and therefore converge uniformly.

Case 2. $\nu(\omega) = \infty$.

Then $\omega \in X_0$ and $\delta_0(f \circ T_t)(\omega) = 0$. Note that

$$|\delta_0 \lambda(\omega')| \leq K(\nu(\omega'))$$

for $\omega' \in X \setminus X_0$ by the Lipschitz continuity of λ , and thus $\delta_0 \lambda$ is uniformly bounded on

$$\{\omega' \in X : \nu(\omega') < M\}$$

The uniform boundedness of $\exp \left\{ \int_0^t ds \delta_0 \lambda(T_s \omega_{\alpha}) \right\}$ together with the continuity of $(\delta_0 f) \circ T_t$ implies that

$$\lim_{\alpha} \delta_0(f \circ T_t)(\omega_{\alpha}) = 0 = \delta_0(f \circ T_t)(\omega).$$

This establishes that $\delta_0(f \circ T_t) \in C_0(X)$, and $(f \circ T_t) \in D(\delta_0)$.

Since clearly $f \circ T_t \in \mathcal{D}_0$, it follows that

$$f \circ T_t \in \mathcal{D}_0 \cap D(\delta_0) = \mathcal{D}_1.$$

Finally we prove that $f \circ T_t \in D(\delta)$. We already know that $f \circ T_t \in D(\delta_0)$, and

by parts (a) and (b)

$$\begin{aligned}
 (***) \quad \lambda(\omega) \delta_0(f \circ T_t)(\omega) &= \lambda(\omega) \exp \left\{ \int_0^t ds \langle \delta_0 \lambda \rangle (T_s \omega) \right\} (\delta_0 f)(T_t \omega) \\
 &= \lambda(T_t \omega) (\delta_0 f)(T_t \omega) = \delta(f)(T_t \omega)
 \end{aligned}$$

for all $\omega \in X$. But as T_t is a homeomorphism of X and $f \in D(\delta)$, the map

$$\omega \longrightarrow T_t \omega \longrightarrow \delta(f)(T_t \omega)$$

is in $C_0(X)$, and thus $f \circ T_t \in D(\delta)$. (Note that the formula (***) also formally follows by noting that the generator δ_T of the automorphism group τ defined by the flow T extends δ and commutes with τ , and hence

$$\delta_T(\tau_t f)(\omega) = \tau_t(\delta_T f)(\omega) = \tau_t(\delta f)(\omega) = \lambda(T_t \omega) (\delta_0 f)(T_t \omega).$$

This completes the proof of Lemma 2.11.

The following result is now easily established.

Theorem 2.12. *Let σ be a strongly continuous one-parameter group of *-automorphisms on an abelian C^* -algebra $\mathcal{A} = C_0(X)$ with generator δ_0 and associated flow S on X , and let $X_0 \subseteq X$ denote the fixed points of S . Assume that λ is a continuous (not necessarily bounded) function on $X \setminus X_0$ such that*

$$\langle \delta_0 \lambda \rangle (\omega) = \left. \frac{d}{dt} \right|_{t=0} \lambda(S_t \omega)$$

exists and is a continuous function of ω which is bounded on the sets $\{\omega \in X; \nu(\omega) < M\}$ for all $M > 0$. Assume also that for any compact subset $C \subseteq X$ there exists an $\epsilon > 0$ such that λ is uniformly bounded on

$$C \cap \{\omega \in X; \nu(\omega) < \epsilon\}.$$

*It follows that the derivation $\delta = \lambda \delta_0$ is closable, and its closure generates a one-parameter group τ of *-automorphisms of \mathcal{A} .*

Proof. By Theorem 2.6 it suffices to show that $D(\delta)$ is a core for δ_T . But according to Lemmas 2.7 and 2.11, $\mathcal{D}_1 \cap D(\delta)$ is dense in \mathcal{A} and $\tau_t(\mathcal{D}_1 \cap D(\delta)) = \mathcal{D}_1 \cap D(\delta)$ for all $t \in \mathbb{R}$. Therefore it follows from [7], Corollary 3.1.7, that $\mathcal{D}_1 \cap D(\delta)$ is a core for δ_T .

If λ and $\delta_0 \lambda$ are polynomially bounded in the frequency, the assumptions of Theorem 2.12 are automatically fulfilled. In this case $\mathcal{A}_\infty \subseteq D(\delta)$, but although \mathcal{A}_∞ is a common core for $\bar{\delta}$ and δ_0 , the domains of these derivations can be quite different. It is also possible that \mathcal{A}_∞ , and even \mathcal{A}_1 fails to be invariant under the group τ generated by $\bar{\delta}$. The following example shows that one can have $\tau(\mathcal{A}_\infty) \not\subseteq \mathcal{A}_1$ even if $\delta(\mathcal{A}_\infty) \subset \mathcal{A}_\infty$.

Example 2.13. Let $\mathcal{A}=C_0(\mathbf{R}^2)$ and σ the group defined by

$$(\sigma_t f)(r, \theta)=f(r, \theta+t/r).$$

Thus the orbits of the associated flow are concentric circles centred at the origin and the orbit of radius r has frequency $(2\pi r)^{-1}$; the origin is a fixed point. It follows that \mathcal{A}_∞ consists of those $f \in \mathcal{A}$ which are infinitely often differentiable in θ and such that the partial derivatives of f with respect to θ go to zero faster than any power of r as $r \rightarrow 0$, uniformly in θ . Next define δ on \mathcal{A}_∞ by

$$(\delta f)(r, \theta)=\frac{\sin \theta}{r^n} \frac{\partial f(r, \theta)}{\partial \theta}$$

for some $n > 1$. A simple calculation then shows that

$$(\tau_t f)(r, \theta)=f(r, 2 \tan^{-1}(e^{t/r^n} \tan \theta / 2)).$$

In particular

$$\frac{\partial(\tau_t f)}{\partial \theta}(r, 0)=\left(\frac{\partial f}{\partial \theta}\right)(r, 0)e^{t/r^n}.$$

It follows that $\delta(\mathcal{A}_\infty) \subset \mathcal{A}_\infty$ but $\tau(\mathcal{A}_\infty) \not\subseteq \mathcal{A}_1$. Moreover $D(\bar{\delta}) \not\subseteq D(\delta_0)$ and $D(\delta_0) \not\subseteq D(\bar{\delta})$.

We also remark that the hypotheses in Theorem 2.12 do not generally imply that $\mathcal{D}_1 \subseteq D(\delta)$. An example is obtained by modifying the definition of σ and δ above as follows

$$(\sigma_t f)(r, \theta)=f(r, \theta+t),$$

and

$$(\delta f)(r, \theta)=\frac{1}{r}(\delta_0 f)(r, \theta)=\frac{1}{r} \frac{\partial f(r, \theta)}{\partial \theta}.$$

Then $\lambda(r, \theta)=1/r$ is constant on S -orbits, so $\delta_0 \lambda=0$, and λ is bounded on $\{\omega | \nu(\omega) < 1/2\pi\} = \phi$, so all the hypotheses of Theorem 2.12 are satisfied. In this case $\mathcal{D}_1 = D(\delta_0)$, but $\mathcal{D}_1 \not\subseteq D(\delta)$, since for example, $f(r, \theta)=r \sin \theta$ is in $D(\delta_0)$, but not in $D(\delta)$.

Note that if the last assumption in Theorem 2.12 is replaced by “For any compact subset $C \subseteq X$ and any $M > 0$, λ is uniformly bounded on $C \cap \{\omega \in X; \nu(\omega) < M\}$ ”, then a simple argument establishes that $\mathcal{D}_1 \subseteq D(\delta)$. This is used in the proof of Theorem 3.1.

Finally we emphasize that the smoothness assumptions on λ adopted in Theorems 2.6 and 2.12 are only essential in a neighbourhood of the zeros of λ . These results can be easily generalized by use of the perturbation result mentioned in the introduction, e. g. if λ_1 satisfies the assumptions of Theorem 2.12 and λ_2 is bounded continuous on $X \setminus X_0$ and bounded away from zero then $\bar{\lambda}_1 \bar{\lambda}_2 \bar{\delta}_0$ is a generator.

§ 3. Smooth Derivations

In this section we prove the theorem on derivations stated in the introduction.

Theorem 3.1. *Let $(\mathcal{A}, \mathbf{R}, \sigma)$ be an abelian C^* -dynamical system and denote the generator of σ by δ_0 . Define $\mathcal{A}_n = D(\delta_0^n)$ and $\mathcal{A}_\infty = \bigcap_{n \geq 1} \mathcal{A}_n$.*

If $\delta : \mathcal{A}_\infty \rightarrow \mathcal{A}_1$ is a $$ -derivation then δ is closable and its closure $\bar{\delta}$ generates a strongly continuous one-parameter group τ of $*$ -automorphisms of \mathcal{A} .*

Proof. It follows from [6] Theorems 1.2 and 4.2 that the condition on δ implies that δ has the form $\delta = \lambda \delta_0$, where λ is a once differentiable function on $X \setminus X_0$ such that λ and $\delta_0 \lambda$ are continuous and polynomially bounded on $X \setminus X_0$. Thus λ satisfies the hypotheses of Theorem 2.12.

The polynomial growth of λ in the frequency implies that the natural domain of δ , the $D(\delta)$ defined in the statement of Theorem 2.6, contains \mathcal{A}_∞ . This follows because for $f \in \mathcal{A}_\infty$ and $n \in \mathbf{N}$ there exists a $K_n > 0$ such that

$$|\delta_0^n(f)(\omega)| \leq K_n \left(\frac{1}{1 + \nu(\omega)} \right)^n$$

by Observation 6 of [6].

Now the extension of δ to $D(\delta)$ has a unique generator extension δ_τ , and it follows from the argument used in the proof of Theorem 2.12 that $\mathcal{D}_1 \subseteq D(\delta)$ is a core for δ_τ . It remains only to show that \mathcal{A}_∞ is a core as well.

To this end, fix $f \in \mathcal{D}_1$ and let $h \in C_0(\mathbf{R})$ be a positive, infinitely often differentiable, function with support in $[-1, 1]$ and total integral one. Then defining

$$\begin{aligned} f_n &= n \int dt h(nt) \sigma_t f \\ &= \int dt h(t) \sigma_{t/n} f \end{aligned}$$

one has $f_n \in \mathcal{A}_\infty \cap \mathcal{D}_1$. Moreover, $f_n \rightarrow f$ and $\delta_0 f_n \rightarrow \delta_0 f$ by strong continuity of σ . But as f is constant on S -orbits of frequency larger than a certain M , the f_n are also constant on these orbits, and $(\delta_0 f_n)(\omega) = 0 = (\delta_0 f)(\omega)$ if $\nu(\omega) \geq M$. But λ is bounded on the subsets $\{\omega; \nu(\omega) \leq M\}$ and hence

$$\delta f_n = \lambda \delta_0 f_n \longrightarrow \lambda \delta_0 f = \delta f.$$

Consequently $\mathcal{A}_\infty \cap \mathcal{D}_1$ is a core for δ_τ or, equivalently $\delta_\tau = \bar{\delta}$ = the closure of δ .

§ 4. Local Dissipations

In this section we discuss various aspects of the generator problem for more general operators associated with $(\mathcal{A}, \mathbf{R}, \sigma)$, local dissipations.

An operator H from \mathcal{A}_∞ into \mathcal{A} is defined to be local if

$$\text{Supp}(Hf) \subseteq \text{Supp}(f)$$

for all $f \in \mathcal{A}_\infty$ and it is defined to be a dissipation, or semi-derivation, if $H\bar{f} = \overline{Hf}$ and

$$(H\bar{f}f) \leq (H\bar{f})f + \bar{f}(Hf)$$

for all $f \in \mathcal{A}_\infty$. In [6] Theorem 1.2B it was established that $H: \mathcal{A}_\infty \rightarrow \mathcal{A}$ is a local dissipation if, and only if,

$$H = -\lambda_2 \delta_0^2 + \lambda_1 \delta_0 + \lambda_0$$

where the real functions $\lambda_0, \lambda_1, \lambda_2$ satisfy the following: λ_0 is a bounded continuous function over X , λ_1 and λ_2 vanish on X_0 and are continuous functions on $X \setminus X_0$ polynomially bounded in the frequency, and $\lambda_0, \lambda_2 \geq 0$. We now argue that each local dissipation H is dissipative, hence closable, and then discuss properties of its closure \bar{H} as a generator.

Lemma 4.1. *Let $H: \mathcal{A}_\infty \rightarrow \mathcal{A}$ be a local dissipation. Then H is dissipative, hence closable.*

Proof. The operator H is defined to be dissipative if for each $f \in \mathcal{A}_\infty$

$$\text{Re } \mu(Hf) \geq 0$$

for at least one $\mu \in \mathcal{A}^*$ with $\|\mu\|=1$ such that $\mu(f) = \|f\|$, or, equivalently, if

$$\|(1 + \alpha H)f\| \geq \|f\|$$

for all $f \in \mathcal{A}_\infty$ and for all small $\alpha > 0$. (See for example, [2] Section 2.1). But by an argument of Kishimoto [14] (see [7], page 230, line 9-14) it suffices, for dissipations, to verify this condition for positive f . Now if $f \in \mathcal{A}_\infty$ and f is positive one can find $\omega \in X$ such that

$$f(\omega) = \|f\|$$

and choose μ to be the point measure at ω . Then $t \rightarrow (\sigma_t f)(\omega) = f(S_t \omega)$ must attain its maximum at $t=0$. Therefore $(\delta_0 f)(\omega) = 0$ and $-(\delta_0^2 f)(\omega) \geq 0$. But then

$$\mu(Hf) = \lambda_2(\omega)(-\delta_0^2 f)(\omega) + \lambda_1(\omega)(\delta_0 f)(\omega) + \lambda_0(\omega) \geq 0,$$

and H is dissipative. Finally it is a standard result, [7], Lemma 3.1.14, that a dissipative operator H is closable, and its closure \bar{H} is dissipative.

Next for each real $f \in \mathcal{A}$ define the positive and negative parts $f_\pm = (\pm f) \vee 0$ and introduce the half-norm N by $N(f) = \|f_+\|$. Now, a real operator K on \mathcal{A} is defined to be N -dissipative or dispersive if for each real $f \in D(K)$

$$\mu(Kf) \geq 0$$

for at least one $\mu \in \mathcal{A}^*$ with $\|\mu\|=1$ such that $\mu(f) = N(f)$ or, equivalently, if

$$N(1+\alpha K)f \geq N(f)$$

for all $f \in D(K)$ and all small $\alpha > 0$. ([2], Section 2.1)

Lemma 4.2. *Let $H: \mathcal{A}_\infty \rightarrow \mathcal{A}$ be a local dissipation. Then H is N -dissipative.*

Proof. Let $f \in \mathcal{A}_\infty$ be real. If $f \leq 0$ then $N(f) = 0$ and $N(1+\alpha H)f \geq 0$. Therefore we can assume $f_+ \neq 0$. Now choose $\omega \in X$ such that $f(\omega) = f_+(\omega) = \|f_+\|$ and again note that this implies that $t \rightarrow f(S_t\omega)$ has a maximum at $t=0$, hence $(\delta_0 f)(\omega) = 0$ and $-(\delta_0^2 f)(\omega) \geq 0$. Then if μ is the point measure at ω

$$\mu(Hf) = \lambda_2(\omega)(-(\delta_0^2 f)(\omega)) + \lambda_1(\omega)(\delta_0 f)(\omega) + \lambda_0(\omega) \geq 0.$$

But since

$$\mu(Hf) \leq (N((1+\alpha H)f) - N(f))/\alpha, \quad \alpha > 0$$

this proves that $N((1+\alpha H)f) \geq N(f)$ for all real $f \in \mathcal{A}_\infty$ and all $\alpha > 0$.

The following result is now a consequence of these dissipation properties and standard semigroup theory, see [8].

Proposition 4.3. *Let $H: \mathcal{A}_\infty \rightarrow \mathcal{A}$ be a local dissipation with closure \bar{H} . Then the following conditions are equivalent;*

1. $\overline{(1+\alpha H)(\mathcal{A}_\infty)} = \mathcal{A}$ for all small $\alpha > 0$.
2. \bar{H} generates a C_0 -semigroup,
3. \bar{H} generates a positive C_0 -semigroup of contractions.

Remark. It is unclear under what conditions the closure \bar{H} of a local dissipation is again a dissipation, e.g. it is not evident that $D(\bar{H})$ is an algebra. Note, however, that if H is any operator such that \bar{H} generates a positive C_0 -semigroup of contractions τ , then τ is strongly positive in the sense

$$\tau_t(\bar{f}f) \geq \tau_t(\bar{f})\tau_t(f)$$

for all $f \in \mathcal{A}$ and $t \in \mathbf{R}$, by the generalized Schwarz's inequality for abelian algebras, [7].

Finally we make some remarks on criteria for \bar{H} to be a generator. It is natural to conjecture, in analogy with Theorem 3.1, that if H is a local dissipation which maps \mathcal{A}_∞ into \mathcal{A}_2 then \bar{H} is a generator. But we have not been able to prove this.

It does follow that if $H: \mathcal{A}_\infty \rightarrow \mathcal{A}_2$ then the coefficients λ_i in the representation

$$H = -\lambda_2 \delta_0^2 + \lambda_1 \delta_0 + \lambda_0$$

satisfy the smoothness properties $\lambda_i \in D(\delta_0^2)$, and the derivatives $\delta_0 \lambda_i, \delta_0^2 \lambda_i$, are polynomially bounded in the frequency for $i=1, 2$ and bounded for $i=0$. This follows from [6], Theorem 4.2. These conditions then imply, by an argument which we sketch below, that the closure of $-\lambda_2 \delta_0^2 + \lambda_0$ is a generator. Moreover

the closure of $\lambda_1\delta_0$ is a generator by Theorem 2.12. Nevertheless it is unclear whether the sum of these two generators is a generator without additional assumptions. One such assumption which is sufficient to guarantee that \bar{H} is a generator is the condition

$$\lambda_2 \geq \varepsilon \lambda_1^2$$

for some $\varepsilon > 0$ or, equivalently, $\|\lambda_1/\sqrt{\lambda_2}\|_\infty < +\infty$. We also sketch the proof of this below.

Let us first consider the proof that the closure of $-\lambda_2\delta_0^2 + \lambda_0$ is a generator, but for simplicity assume that $\lambda_0, \lambda_2, \delta_0\lambda_2, \delta_0^2\lambda_2$, are bounded. The general case can then be handled by approximation arguments. But in this case it suffices to prove that the closure of $-\lambda_2\delta_0^2 = -(\sqrt{\lambda_2}\delta_0)^2 + (1/2)(\delta_0\lambda_2)\delta_0$ is a generator. Now $\sqrt{\lambda_2}\delta_0$ is the generator of a group of *-automorphisms τ by Theorem 2.12 and hence $-(\sqrt{\lambda_2}\delta_0)^2$ is the generator of a contraction semigroup ρ constructed by the algorithm

$$\rho_t = (4\pi t)^{-1/2} \int_{-\infty}^{\infty} ds e^{-s^2/4t} \tau_s.$$

Now consider the term $(\delta_0\lambda_2)\delta_0$. Since $\lambda_2 \in D(\delta_0^2)$ and $\|\delta_0^2\lambda_2\| < +\infty$ by our simplification assumption one has

$$0 \leq \lambda_2(S_t\omega) = \lambda_2(\omega) + t(\delta_0\lambda_2)(\omega) + \int_0^t dt_1 \int_0^{t_1} dt_2 (\delta_0^2\lambda_2)(S_{t_2}\omega)$$

and hence

$$0 \leq \lambda_2(\omega) + t(\delta_0\lambda_2)(\omega) + (t^2/2)\|\delta_0^2\lambda_2\|.$$

Consequently

$$|(\delta_0\lambda_2)(\omega)|^2 \leq 2\lambda_2(\omega)\|\delta_0^2\lambda_2\|.$$

Moreover if τ denotes the group generated by the derivation $\delta = -\sqrt{\lambda_2}\delta_0$ then for $f \in \mathcal{A}_\infty$

$$(\tau_t f)(\omega) = f(\omega) + t(\delta f)(\omega) + \int_0^t dt_1 \int_0^{t_1} dt_2 \tau_{t_2}((\delta^2 f)(\omega))$$

and hence

$$\|\delta f\| \leq (t/2)\|\delta^2 f\| + (2/t)\|f\|$$

by the triangle inequality. Combining these estimates gives

$$\begin{aligned} \|(\delta_0\lambda_2)(\delta_0 f)\| &\leq \|(\delta_0\lambda_2)/\sqrt{\lambda_2}\| \|(\sqrt{\lambda_2}\delta_0)(f)\| \\ &\leq \sqrt{2}\|\delta_0^2\lambda_2\|(\varepsilon\|(\sqrt{\lambda_2}\delta_0)^2(f)\| + (1/\varepsilon)\|f\|), \end{aligned}$$

for all $f \in \mathcal{A}_\infty$ and any $\varepsilon > 0$. Thus $(\delta_0\lambda_2)\delta_0$ is relatively bounded with respect to $-(\sqrt{\lambda_2}\delta_0)^2$ with relative bound zero. Hence the closure of the sum $-(\sqrt{\lambda_2}\delta_0)^2 + (1/2)(\delta_0\lambda_2)\delta_0 = -\lambda_2\delta_0^2$ is a generator.

Note that the same argument also shows that if $\lambda_2 \geq \varepsilon \lambda_1^2$, then $\lambda_1\delta_0$ is relatively

bounded with respect to $-(\sqrt{\lambda_2} \delta_0)^2$ with relative bound zero. Hence the closure of $-(\sqrt{\lambda_2} \delta_0)^2 + ((1/2)(\delta_0 \lambda_2) \delta_0 + \lambda_1 \delta_0) = -\lambda_2 \delta_0^2 + \lambda_1 \delta_0$ is a generator.

§ 5. Compact Group Actions

In this section we prove an analogue of Theorem 3.1, with the action S of \mathbf{R} on X replaced by an action of a compact Lie group. Thus we consider a locally compact Hausdorff space X , a compact group \mathbf{G} , and a topological transformation group (X, \mathbf{G}, S) , i. e., $g \rightarrow S_g$ is a homomorphism of \mathbf{G} into the group of homeomorphisms of X such that $(g, x) \rightarrow S_g(x)$ is jointly continuous. The corresponding automorphic action σ of \mathbf{G} on $\mathcal{A} = C_0(X)$ defined by $\sigma_g f(\omega) = f(S_{g^{-1}} \omega)$ is strongly continuous. For $n \geq 1$, \mathcal{A}_n denotes the algebra of functions $f \in \mathcal{A}$ such that $g \rightarrow \sigma_g(f)$ is a C^n function from \mathbf{G} to \mathcal{A} , and $\mathcal{A}_\infty = \bigcap_{n \geq 1} \mathcal{A}_n$. If X_1, \dots, X_d is a basis for the Lie algebra of \mathbf{G} , then $f \in \mathcal{A}_n$ if, and only if, f is in the domain of $\sigma(X_{i_1} \dots X_{i_n})$ for all choices of i_1, \dots, i_n , and \mathcal{A}_n is a Banach space with the norm

$$\|f\|_n = \sup\{\|\sigma(X_{i_1} \dots X_{i_k})f\|; 0 \leq k \leq n \text{ and } 1 \leq i_j \leq d\}.$$

\mathcal{A}_n is a Banach algebra in an equivalent norm and \mathcal{A}_∞ is a Frechet algebra, with topology generated by the norms $\|\cdot\|_n, n \geq 1$.

Theorem 5.1. *Let X be a locally compact Hausdorff space, $\mathcal{A} = C_0(X)$ and $\alpha: \mathbf{G} \rightarrow \text{Aut}(\mathcal{A})$ a strongly continuous action of a compact Lie group \mathbf{G} on \mathcal{A} . If $\delta: \mathcal{A}_\infty \rightarrow \mathcal{A}_1$ is a *-derivation, then δ is closable and its closure $\bar{\delta}$ generates a strongly continuous action of \mathbf{R} on \mathcal{A} . Furthermore, the orbits of the corresponding flow on X are contained in the orbits of the action of \mathbf{G} on X .*

Proof. Fix a \mathbf{G} -orbit M in X . Any function $f \in \mathcal{A}_\infty$ satisfying $f|_M = 0$ can be approximated in the \mathcal{A}_∞ -topology by functions of the form $f\varphi$, where $\varphi: X \rightarrow [0, 1]$ is an element of $C_0(X)$ which is constant on \mathbf{G} -orbits and zero in a neighbourhood of M . Then $\delta(f\varphi)|_M = 0$ because of the locality property of derivations defined on a dense domain with a C^∞ -functional calculus [3]. Consequently $\bar{\delta}(f)|_M = 0$ because $\bar{\delta}$ is automatically continuous with respect to the \mathcal{A}_∞ -topology [16, 5].

Thus $\bar{\delta}$ restricts to M ; that is the formula $\bar{\delta}_M(f|_M) = \bar{\delta}(f)|_M$ defines a *-derivation $\bar{\delta}_M$ in $C(M)$ with domain $\{f|_M; f \in \mathcal{A}_\infty\}$. It is convenient here to refer again to the theorem of Dixmier and Malliavin [9] which states that \mathcal{A}_∞ is the linear span of functions of the form

$$\varphi * f = \int_{\mathbf{G}} \varphi(g) \sigma_g(f) dg$$

where $\varphi \in C^\infty(\mathbf{G})$, and $f \in \mathcal{A}$. Applying this result also to the action of \mathbf{G} on $C(M)$, we see that $\{f|_M; f \in \mathcal{A}_\infty\}$ is all of the algebra of C^∞ -elements for the

action of G on $C(M)$. Now M can be identified with some coset space G/K via a G -equivariant homeomorphism. Under this identification, the algebra of C^∞ -elements for G acting on $C(M)$ is identified with $C^\infty(G/K)$ and δ_M becomes a derivation on $C^\infty(G/K)$. Since the range of δ is contained in \mathcal{A}_1 , it follows that δ_M maps $C^\infty(G/K)$ into $C^1(G/K)$, and δ_M is given by a C^1 -vectorfield on G/K . Now the basic existence and uniqueness theorem for ordinary differential equations implies that $\bar{\delta}_M$ generates a one-parameter group of automorphisms of $C(M)$, see [13], Theorem 3.43.

Rather than explicitly patching together the flows on the G -orbits generated by the vector fields δ_M , as in the proof of Theorem 2.6, we can use global criteria for $\bar{\delta}$ to be a generator. First it is easy to see that $\pm\delta$ are dissipative operators; in fact if f is real valued and achieves its maximum modulus at a point ω , then $\delta(f)(\omega)=0$, since $\delta_{G(\omega)}$ is given by a vector field. It remains to check that $(\text{id}\pm\delta)\mathcal{A}_\infty$ are dense subspaces of \mathcal{A} . For this, one can follow the argument in [11], Theorem 3.2. Since this argument involves a partition of unity on the locally compact Hausdorff space X/G , it is essential here again that G is compact.

Finally the statement regarding orbits: Let $\{\beta_t : t \in \mathbf{R}\}$ be the one-parameter group of homeomorphisms of X corresponding to the automorphism group $\exp(t\bar{\delta})$. Suppose that for some $\omega \in X$ the orbit $\{\beta_t(\omega)\}$ does not lie in the G -orbit $G(\omega)$. In this case there is a function $f \in \mathcal{A}_\infty$ which is constant on each G -orbit but not constant on $\{\beta_t(\omega)\}$. But by the first part of the proof, $\delta(f)|_M=0$ for each orbit M , $f \in \ker(\delta)$. Then f is analytic for δ and

$$\begin{aligned} f(\beta_t\omega) &= (e^{t\bar{\delta}}f)(\omega) \\ &= \left(f + \sum_{k \geq 1} \frac{t^k \delta^k(f)}{k!} \right)(\omega) \\ &= f(\omega), \end{aligned}$$

a contradiction. (The proof of the corresponding statement concerning orbits in [11], Theorem 3.2 was incorrect and should be replaced by the present proof.)

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Note added in proof: Some of the results of this paper have been refined and extended in:

- [18] Robinson, D.W., Smooth derivations on abelian D^* -dynamical systems, preprint (1985).
- [19] Robinson, D.W., Smooth cores of Lipschitz flows, preprint (1985).
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- [21] Batty, C.J.K., Derivations on the line and flows along orbits, preprint (1985).
- [22] Robinson, D.W., Commutators and generators II, preprint (1985).

The paper [18] contains a counterexample to the conjecture that if H is a local dissipation from A_∞ into A_2 , then \overline{H} is a generator.