

Berezin transform and Stratonovich–Weyl correspondence for the multi-dimensional Jacobi group (addendum)

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ABSTRACT – We extend the results of [13] to the holomorphic representations of the non-scalar type of the multi-dimensional Jacobi group.

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1. Introduction

We use the notation of [13], Section 2. In particular, we denote by G the multi-dimensional Jacobi group and by K the subgroup of G consisting of all elements of the form $((0, 0), c, \begin{pmatrix} P & 0 \\ 0 & \bar{P} \end{pmatrix})$ where $c \in \mathbb{R}$ and $P \in U(n)$.

Recall that the unitary representations of G considered in [13] are holomorphically induced from a unitary character of K . Here we consider, more generally, the unitary representations of G which are holomorphically induced from a unitary representation ρ of K , see [18], p. 515, and we extend the results of [13] to these representations. The main tool is then the generalized Berezin calculus for a reproducing kernel Hilbert space of vector-valued holomorphic functions, see [2], [17] and [12]. Most of the proofs are similar to those of [13] so we just sketch them briefly.

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2. Representations

Let $\gamma \in \mathbb{R}$ and let ρ_0 be a unitary irreducible representation of $U(n)$ on a (finite-dimensional) complex vector space \mathcal{V} . Let ρ be the representation of K on \mathcal{V} defined by

$$\rho((0, 0), c, \begin{pmatrix} P & 0 \\ 0 & \bar{P} \end{pmatrix}) = e^{i\gamma c} \rho_0(P).$$

We also denote by ρ_0 and ρ the corresponding representations of $GL_n(\mathbb{C})$ and K^c .

Let $M_n(\mathbb{C}) = \mathfrak{n}^+ \oplus \mathfrak{h}_0 \oplus \mathfrak{n}^-$ be the usual triangular decomposition of $M_n(\mathbb{C})$. Then ρ_0 is associated with a dominant integral weight of the form

$$\Lambda_{m_1, m_2, \dots, m_n} : \text{Diag}(a_1, a_2, \dots, a_n) \longrightarrow \sum_{i=1}^n m_i a_i$$

where $m_1 \geq m_2 \geq \dots \geq m_n$ and $m_i \in \mathbb{Z}$ [15], p. 274. Let $m = \sum_{i=1}^n m_i$. Then we have $\rho_0(zI_n) = z^m I_{\mathcal{V}}$ for each $z \in \mathbb{C}^\times$.

Recall that for each $y \in \mathbb{C}^n$ and $Y \in M_n(\mathbb{C})$ such that $Y^t = Y$, we denote

$$a(y, Y) := ((y, 0), 0, \begin{pmatrix} 0 & Y \\ 0 & 0 \end{pmatrix}) \in \mathfrak{p}^+$$

and

$$\mathcal{D} := \{a(y, Y) \in \mathfrak{p}^+ : I_n - Y\bar{Y} > 0\} \cong \mathbb{C}^n \times \mathcal{B}$$

where $\mathcal{B} := \{Y \in M_n(\mathbb{C}) : Y^t = Y, I_n - Y\bar{Y} > 0\}$.

Now we will apply the general considerations of [18] and [12] to the particular case of the multi-dimensional Jacobi group. Following [18], p. 497, we set $K(Z, W) := \rho(\kappa(\exp W^* \exp Z))^{-1}$ for $Z, W \in \mathcal{D}$ and $J(g, Z) := \rho(\kappa(g \exp Z))$ for $g \in G$ and $Z \in \mathcal{D}$ and we introduce the Hilbert space \mathcal{H} of all holomorphic functions on \mathcal{D} with values in \mathcal{V} such that

$$\|f\|_{\mathcal{H}}^2 := \int_{\mathcal{D}} \langle K(Z, Z)^{-1} f(Z), f(Z) \rangle_{\mathcal{V}} d\mu(Z) < +\infty$$

where μ denotes the G -invariant measure on \mathcal{D} defined in [13], Section 2.

Let π be the unitary representation of G on \mathcal{H} defined by

$$(\pi(g)f)(Z) = J(g^{-1}, Z)^{-1} f(g^{-1} \cdot Z).$$

In [12], we verified that π is obtained by holomorphic induction from ρ , that is, π corresponds to the natural action of G on the square-integrable holomorphic sections of the Hilbert G -bundle $G \times_{\rho} \mathcal{V}$ over $G/K \cong \mathcal{D}$. Moreover, π is irreducible since ρ is irreducible, see [18], p. 515.

The evaluation maps $K_Z: \mathcal{H} \rightarrow \mathcal{V}, f \rightarrow f(Z)$ are continuous [18], p. 539. The vector coherent states of \mathcal{H} are the maps $E_Z = K_Z^*: \mathcal{V} \rightarrow \mathcal{H}$ defined by $\langle f(Z), v \rangle_{\mathcal{V}} = \langle f, E_Z v \rangle_{\mathcal{H}}$ for $f \in \mathcal{H}$ and $v \in \mathcal{V}$.

We have the following result, see [18], p. 540.

PROPOSITION 2.1. (1) *There exists a constant $c_\rho > 0$ such that*

$$E_Z^* E_W = c_\rho K(Z, W)$$

for each $Z, W \in \mathcal{D}$.

(2) *For $g \in G$ and $Z \in \mathcal{D}$,*

$$E_{g \cdot Z} = \pi(g) E_Z J(g, Z)^*.$$

Now we give explicit formulas for K and J and we compute c_ρ (see Lemma 3.1 in [13]).

PROPOSITION 2.2. (1) *Let $Z = a(y, Y) \in \mathcal{D}$ and $W = a(v, V) \in \mathcal{D}$. We set*

$$E(y, v, Y, V) := 2y^t (I_n - \bar{V}Y)^{-1} \bar{v} + y^t (I_n - \bar{V}Y)^{-1} \bar{V}y + \bar{v}^t Y (I_n - \bar{V}Y)^{-1} \bar{v}.$$

Then,

$$K(Z, W) = \exp\left(\frac{\gamma}{4} E(y, v, Y, V)\right) \rho_0(I_n - Y\bar{V}).$$

(2) *$\mathcal{H} \neq (0)$ if and only if $\gamma > 0$ and $m + n + 1/2 < 0$. In this case,*

$$c_\rho = \text{Dim}(\mathcal{V}) \left(\frac{\gamma}{2\pi}\right)^n J_n(-m - n - 3/2)^{-1}.$$

(3) *For each $g = ((z_0, \bar{z}_0), c_0, \left(\frac{P}{Q} \frac{Q}{P}\right)) \in G$ and each $Z = a(y, Y) \in \mathcal{D}$, we have*

$$\begin{aligned} J(g, Z) = e^{i\gamma c_0} \exp\left(\frac{\gamma}{4} (z_0^t \bar{z}_0 + 2\bar{z}_0^t P y + y^t P^t \bar{Q} y \right. \\ \left. - (\bar{z}_0 + \bar{Q} y)^t (P Y + Q) (\bar{Q} y + \bar{P})^{-1} (\bar{z}_0 + \bar{Q} y)\right) \\ \rho_0((\bar{Q} Y + \bar{P})^t)^{-1}. \end{aligned}$$

PROOF. (1) and (3) are simple calculations. To prove (2), we use the formula

$$(I_n - \bar{Y}Y)^{-1} = \text{Det}(I_n - \bar{Y}Y)^{-1} C(I_n - \bar{Y}Y)^t$$

for each $Y \in \mathcal{B}$, where $C(A)$ denotes the cofactor matrix of a matrix A . From this formula, we deduce

$$\text{Tr } \rho_0(I_n - \bar{Y}Y)^{-1} = \text{Det}(I_n - \bar{Y}Y)^{-m} \text{Tr } \rho_0(C(I_n - \bar{Y}Y)^t)$$

and then we can prove (2) by following the same lines as in the proof of Proposition 3.2 of [13], using Theorem XII.5.6 of [18]. \square

Proposition 3.4 of [13] can be generalized as follows.

PROPOSITION 2.3. *For $X \in \mathfrak{g}^c$, $f \in \mathcal{H}$ and $Z \in \mathcal{D}$,*

$$d\pi(X)f(Z) = d\rho(p_{\mathfrak{k}^c}(e^{-\text{ad } Z} X)) f(Z) - (df)_Z(p_{\mathfrak{p}^+}(e^{-\text{ad } Z} X)).$$

In particular,

- (1) *if $X \in \mathfrak{p}^+$, then $d\pi(X)f(Z) = -(df)_Z(X)$;*
- (2) *if $X \in \mathfrak{k}^c$, then $d\pi(X)f(Z) = d\rho(X)f(Z) + (df)_Z([Z, X])$;*
- (3) *if $X \in \mathfrak{p}^-$, then*

$$\begin{aligned} d\pi(X)f(Z) &= (d\rho \circ p_{\mathfrak{k}^c})\left(-[Z, X] + \frac{1}{2}[Z, [Z, X]]\right) f(Z) \\ &\quad - (df)_Z \circ p_{\mathfrak{p}^+}\left(-[Z, X] + \frac{1}{2}[Z, [Z, X]]\right). \end{aligned}$$

Let (E_k) be a basis of \mathfrak{p}^+ . Then, for each $f \in \mathcal{H}$ and each k , we denote

$$(\partial_k f)(Z) = \frac{d}{dt} f(Z + tE_k)|_{t=0}.$$

From the preceding proposition we deduce the following result.

PROPOSITION 2.4. *For each $X_1, X_2, \dots, X_q \in \mathfrak{g}^c$, $d\pi(X_1 X_2 \cdots X_q)$ is a sum of terms of the form $P(Z)\partial_{k_1} \partial_{k_2} \cdots \partial_{k_r}$ where $r \leq q$ and $P(Z)$ is a polynomial of degree $\leq 2q$.*

3. Berezin calculus

First we introduce the Berezin quantization map associated with ρ_0 , see [3], [4], [1], [5], and [19].

Let $\tilde{\varphi}_0$ be the linear form on $M_n(\mathbb{C})$ defined by $\tilde{\varphi}_0 = -i \Lambda_{m_1, m_2, \dots, m_n}$ on \mathfrak{h}_0 and $\tilde{\varphi}_0 = 0$ on \mathfrak{n}^\pm . We denote by φ_0 the restriction of $\tilde{\varphi}_0$ to $\mathfrak{u}(n)$. Then the orbit $o(\varphi_0)$ of φ_0 under the coadjoint action of $U(n)$ is then said to be associated with ρ_0 .

Note that the stabilizer of φ_0 for the coadjoint action of $U(n)$ contains the torus

$$H_0 := \{\text{Diag}(ia_1, ia_2, \dots, ia_n) : a_j \in \mathbb{R}\}.$$

We say that such an element φ_0 is *regular* if the stabilizer of φ_0 is equal to H_0 , see [5]. Then we can verify that φ_0 is regular if and only if one has $m_1 > m_2 > \dots > m_n$. In the rest of the paper, we assume that φ_0 is regular.

Note also that a complex structure on $o(\varphi_0)$ is then defined by the diffeomorphism $o(\varphi_0) \simeq U(n)/H_0 \simeq \text{GL}_n(\mathbb{C})/H_0^c N^-$ where N^- is the analytic subgroup of $\text{GL}_n(\mathbb{C})$ with Lie algebra \mathfrak{n}^- .

Without loss of generality, we can assume that \mathcal{V} is the space of holomorphic functions on (a dense open set of) $o(\varphi_0)$ as in [5]. For $\varphi \in o(\varphi_0)$ there exists a unique function $e_\varphi \in \mathcal{V}$ (called a coherent state) such that $a(\varphi) = \langle a, e_\varphi \rangle_{\mathcal{V}}$ for each $a \in \mathcal{V}$. The Berezin calculus on $o(\varphi_0)$ associates with each operator B on \mathcal{V} the complex-valued function $s(B)$ on $o(\varphi_0)$ defined by

$$s(B)(\varphi) = \frac{\langle B e_\varphi, e_\varphi \rangle_{\mathcal{V}}}{\langle e_\varphi, e_\varphi \rangle_{\mathcal{V}}}$$

which is called the symbol of B . Then we have the following proposition, see [14], [1] and [5].

PROPOSITION 3.1. (1) *The map $B \rightarrow s(B)$ is injective.*

(2) *For each operator B on \mathcal{V} , we have $s(B^*) = \overline{s(B)}$.*

(3) *For each $\varphi \in o(\varphi_0)$, $k \in U(n)$ and $B \in \text{End}(\mathcal{V})$, we have*

$$s(B)(\text{Ad}^*(k)\varphi) = s(\rho_0(k)^{-1} B \rho_0(k))(\varphi).$$

(4) *For each $A \in \mathfrak{u}(n)$ and $\varphi \in o(\varphi_0)$, we have $s(d\rho_0(A))(\varphi) = i \langle \varphi, A \rangle$.*

We also need the following result, see [10] and [12].

PROPOSITION 3.2. *Let $Z \in \mathcal{D}$. There exists a unique element k_Z in K^c such that $k_Z^* = k_Z$ and $k_Z^2 = \kappa(\exp Z^* \exp Z)^{-1}$. Each $g \in G$ such that $g \cdot 0 = Z$ is then of the form $g = \exp(-Z^*) \zeta(\exp Z^* \exp Z) k_Z^{-1} h$ where $h \in K$. Consequently, the map $Z \rightarrow g_Z := \exp(-Z^*) \zeta(\exp Z^* \exp Z) k_Z^{-1}$ is a section for the action of G on \mathcal{D} .*

More explicitly, for each $Z = a(y, Y) \in \mathcal{D}$, we have

$$k_Z = \left((0, 0), -\frac{i}{8} E(y, y, Y, Y), \begin{pmatrix} (I_n - Y \bar{Y})^{1/2} & 0 \\ 0 & (I_n - \bar{Y} Y)^{-1/2} \end{pmatrix} \right)$$

and

$$g_Z = \left((-\bar{w}, -w), \frac{i}{8} (y^t (I_n - \bar{Y}Y)^{-1} \bar{Y}y - \bar{y}^t Y (I_n - \bar{Y}Y)^{-1} \bar{y}), M(Y) \right)$$

where $w := -(I_n - \bar{Y}Y)^{-1}(\bar{y} + \bar{Y}y)$ and

$$M(Y) := \begin{pmatrix} (I_n - Y\bar{Y})^{-1/2} & Y(I_n - \bar{Y}Y)^{-1/2} \\ \bar{Y}(I_n - Y\bar{Y})^{-1/2} & (I_n - \bar{Y}Y)^{-1/2} \end{pmatrix}.$$

Now, following [17], [2], [12], we define the pre-symbol $S_0(A)$ of an operator A by

$$S_0(A)(Z) = c_\rho^{-1} \rho(k_Z^{-1}) E_Z^* A E_Z \rho(k_Z^{-1})^*$$

and the Berezin symbol $S(A)$ of A is defined as the complex-valued function on $\mathcal{D} \times o(\varphi_0)$ given by

$$S(A)(Z, \varphi) = s(S_0(A)(Z))(\varphi).$$

For each $g \in G$ and $Z \in \mathcal{D}$, let $k(g, Z) := g_Z^{-1} g^{-1} g_{g \cdot Z} \in K$. Then we can write

$$k(g, Z) = \left((0, 0), c(g, Z), \begin{pmatrix} P(g, Z) & 0 \\ 0 & P(g, Z) \end{pmatrix} \right),$$

where $c(g, Z) \in \mathbb{R}$ and $P(g, Z) \in U(n)$.

We have the following properties of S , see [12].

- PROPOSITION 3.3. (1) Each operator A is determined by $S(A)$.
- (2) For each operator A , we have $S(A^*) = \overline{S(A)}$.
- (3) We have $S(I_{\mathfrak{H}}) = 1$.
- (4) For each operator A , $g \in G$, $Z \in \mathcal{D}$ and $\varphi \in o(\varphi_0)$, we have

$$S(A)(g \cdot Z, \varphi) = S(\pi(g)^{-1} A \pi(g))(Z, \text{Ad}^*(P(g, Z))\varphi).$$

Now, we give some formulas for the Berezin pre-symbol of $\pi(g)$ for $g \in G$ and for the Berezin symbol of $d\pi(X)$ for $X \in \mathfrak{g}^c$. For $\varphi \in u(n)^*$, we denote by φ^s the linear form on \mathfrak{s} defined by

$$\left\langle \varphi^s, \begin{pmatrix} P & Q \\ \bar{Q} & \bar{P} \end{pmatrix} \right\rangle = \langle \varphi, P \rangle$$

and by φ^e the linear form on \mathfrak{g} defined by

$$\left\langle \varphi^e, \left((z, \bar{z}), c, \begin{pmatrix} P & Q \\ \bar{Q} & \bar{P} \end{pmatrix} \right) \right\rangle = \langle \varphi, P \rangle + \gamma c.$$

We also denote by φ^s and φ^e the extensions of φ^s and φ^e to \mathfrak{s}^c and \mathfrak{g}^c .

PROPOSITION 3.4 ([12]). (1) For $g \in G$ and $Z \in \mathcal{D}$, we have

$$S_0(\pi(g))(Z) = \rho(k_Z^{-1} \kappa(\exp Z^* g^{-1} \exp Z)^{-1} (k_Z^{-1})^*).$$

(2) For each $X \in \mathfrak{g}$, $Z \in \mathcal{D}$ and $\varphi \in o(\varphi_0)$, we have

$$S(d\pi(X))(Z, \varphi) = i \langle \text{Ad}^*(g_Z)\varphi^e, X \rangle.$$

Recall that $\xi_0 \in \mathfrak{g}^*$ is said to be *regular* if the stabilizer $G(\xi_0)$ of ξ_0 for the coadjoint action is connected and if the Hermitian form $(Z, W) \rightarrow \langle \xi_0, [Z, W^*] \rangle$ is not isotropic [12].

LEMMA 3.5. The linear form φ_0^e is regular if and only if we have $m_j > 0$ for each j or $m_j < 0$ for each j .

PROOF. On the one hand, by using the formula for the coadjoint action of G given in [13], Section 2, we can verify that $G(\varphi_0^e)$ consists of all matrices of the form $((0, 0), c, \begin{pmatrix} P & 0 \\ 0 & P \end{pmatrix})$ where $c \in \mathbb{R}$ and $P \in U(n)$ is such that $\text{Ad}^*(P)\varphi_0 = \varphi_0$. Since φ_0 is assumed to be regular as an element of $u(n)^*$, we get $P \in H_0$. Hence $G(\varphi_0^e) \cong \mathbb{R} \times H_0$ is connected.

On the other hand, for each $Z = a(y, Y) \in \mathcal{D}$, we have

$$\begin{aligned} \langle \varphi_0^e, [Z, Z^*] \rangle &= -\langle \varphi_0, Y\bar{Y} \rangle - \frac{i}{2}\gamma|y|^2 \\ &= -\sum_j m_j |Y_j|^2 - \frac{i}{2}\gamma|y|^2 \end{aligned}$$

where Y_1, Y_2, \dots, Y_n denote the columns of Y . The result hence follows. □

Let us assume that φ_0^e is regular and denote by $\mathcal{O}(\varphi_0^e)$ the orbit of φ_0^e for the coadjoint action of G . Then we have the following proposition, see [12].

PROPOSITION 3.6. The map $\Psi: \mathcal{D} \times o(\varphi_0) \rightarrow \mathfrak{g}^*$ defined by

$$\Psi(Z, \varphi) = \text{Ad}^*(g_Z)\varphi^e$$

is a diffeomorphism from $\mathcal{D} \times o(\varphi_0)$ onto $\mathcal{O}(\varphi_0^e)$ such that

$$\Psi(g \cdot Z, \varphi) = \text{Ad}^*(g) \Psi(Z, \text{Ad}^*(P(g, Z))(\varphi))$$

for each $g \in G$, $Z \in \mathcal{D}$ and $\varphi \in o(\varphi_0)$.

More precisely, with the notation of [13], we have

$$\Psi(Z, \varphi) = \left(\gamma(\bar{w}, w), \gamma, \text{Ad}^*(M(Y))\varphi^s - \frac{\gamma}{2}(\bar{w}, w) \times (\bar{w}, w) \right)$$

where $Z = a(y, Y) \in \mathcal{D}$ and $w := -(I_n - \bar{Y}Y)^{-1}(\bar{y} + \bar{Y}y)$.

4. Berezin transform and Stratonovich–Weyl correspondence

Here we introduce the Berezin transform associated with S and the corresponding Stratonovich–Weyl correspondence, following [12].

We fix a K -invariant measure ν on $o(\varphi_0)$ normalized as in [5], Section 2. Then the measure $\tilde{\mu} := \mu \otimes \nu$ on $\mathcal{D} \times o(\varphi_0)$ is invariant under the action of G on $\mathcal{D} \times o(\varphi_0)$ given by $g \cdot (Z, \varphi) := (g \cdot Z, \text{Ad}^*(P(g, Z))^{-1}\varphi)$ and the measure $\mu_{\mathcal{O}(\varphi_0^e)} := (\Psi^{-1})^*(\tilde{\mu})$ is a G -invariant measure on $\mathcal{O}(\varphi_0^e)$.

We denote by $\mathcal{L}_2(\mathcal{H})$ the space of Hilbert-Schmidt operators on \mathcal{H} endowed with the Hilbert-Schmidt norm. We also endow $\text{End}(\mathcal{V})$ with the Hilbert-Schmidt norm. We denote by $L^2(\mathcal{D} \times o(\varphi_0))$ (respectively $L^2(\mathcal{D}), L^2(o(\varphi_0)), L^2(\mathcal{O}(\varphi_0^e))$) the space of functions on $\mathcal{D} \times o(\varphi_0)$ (respectively $\mathcal{D}, o(\varphi_0), \mathcal{O}(\varphi_0^e)$) which are square-integrable with respect to the measure $\tilde{\mu}$ (respectively $\mu, \nu, \mu_{\mathcal{O}(\varphi_0^e)}$). Then we have the following result, see for instance [6].

PROPOSITION 4.1. *The Berezin transform $b := ss^*$ is given by*

$$b(a)(\psi) = \int_{o(\varphi_0)} a(\varphi) \frac{|\langle e_\psi, e_\varphi \rangle_\nu|^2}{\langle e_\varphi, e_\varphi \rangle_\nu \langle e_\psi, e_\psi \rangle_\nu} d\nu(\varphi)$$

for each $a \in L^2(o(\varphi_0))$

Similarly, we have the following proposition.

PROPOSITION 4.2. *The Berezin transform $B := SS^*$ is a bounded operator of $L^2(\mathcal{D} \times o(\varphi_0))$ and that, for each $f \in L^2(\mathcal{D} \times o(\varphi_0))$, we have the following integral formula*

$$B(f)(Z, \psi) = \int_{\mathcal{D} \times o(\varphi_0)} k(Z, W, \psi, \varphi) f(W, \varphi) d\mu(W) d\nu(\varphi)$$

where

$$k(Z, W, \psi, \varphi) := \frac{|\langle \rho(\kappa(gZ^{-1}gW))^{-1}e_\psi, e_\varphi \rangle_\nu|^2}{\langle e_\varphi, e_\varphi \rangle_\nu \langle e_\psi, e_\psi \rangle_\nu}.$$

Consider the left-regular representation τ of G on $L^2(\mathcal{D} \times o(\varphi_0))$ defined by

$$(\tau(g)(f))(Z, \varphi) = f(g^{-1} \cdot (Z, \varphi)).$$

Clearly, τ is unitary. Moreover, since S is G -equivariant, we immediately verify that for each $f \in L^2(\mathcal{D} \times o(\varphi_0))$ and each $g \in G$, we have $B(\tau(g)f) = \tau(g)(B(f))$.

Now, we introduce the polar decomposition of $S: \mathcal{L}_2(\mathcal{H}) \rightarrow L^2(\mathcal{D} \times o(\varphi_0))$. We can write $S = (SS^*)^{1/2}W = B^{1/2}W$ where $W := B^{-1/2}S$ is a unitary operator from $\mathcal{L}_2(\mathcal{H})$ to $L^2(\mathcal{D} \times o(\varphi_0))$. Then we have the following proposition, see [12]. The main point is that W is G -equivariant since S (hence B) is G -equivariant.

PROPOSITION 4.3. (1) $W: \mathcal{L}_2(\mathcal{H}) \rightarrow L^2(\mathcal{D} \times o(\varphi_0))$ is a Stratonovich–Weyl correspondence for the triple $(G, \pi, \mathcal{D} \times o(\varphi_0))$.

(2) The map \mathcal{W} from $\mathcal{L}_2(\mathcal{H})$ to $L^2(\mathcal{O}(\varphi_0^e))$ defined by $\mathcal{W}(f) = W(f \circ \Psi)$ is a Stratonovich–Weyl correspondence for the triple $(G, \pi, \mathcal{O}(\varphi_0^e))$.

5. Extension of the Berezin transform

Here we generalize Proposition 5.2 of [13], that is, we extend B to a class of functions which contains $S(d\pi(X))$ for $X \in \mathfrak{g}^c$, in particular in order to define $W(d\pi(X))$.

For $Z, W \in \mathcal{D}$, we set $l_Z(W) := \log \eta(\exp Z^* \exp W) \in \mathfrak{p}^-$. We need the following lemma which is the direct generalization of Lemma 5.1 of [13].

LEMMA 5.1. (1) For each $Z, W \in \mathcal{D}, V \in \mathfrak{p}^+$ and $v \in \mathcal{V}$,

$$\begin{aligned} & \frac{d}{dt} (E_Z v)(W + tV) \Big|_{t=0} \\ &= -c_\rho(d\rho \circ p_{\mathfrak{k}^c}) \left([l_Z(W), V] + \frac{1}{2} [l_Z(W), [l_Z(W), V]] \right) (E_Z v)(W). \end{aligned}$$

(2) For $Z, W \in \mathcal{D}$ and $V \in \mathfrak{p}^+$,

$$\frac{d}{dt} l_Z(W + tV) \Big|_{t=0} = p_{\mathfrak{p}^-} \left([l_Z(W), V] + \frac{1}{2} [l_Z(W), [l_Z(W), V]] \right).$$

(3) The function $(\partial_{k_1} \partial_{k_2} \cdots \partial_{k_q} E_Z v)(W)$ is of the form $Q(l_Z(W))(E_Z v)(W)$ where Q is a polynomial of degree $\leq 2q$ with values in $\text{End}(\mathcal{V})$.

(4) For each $X_1, X_2, \dots, X_q \in \mathfrak{g}^c$, the function $S_0(d\pi((X_1 X_2 \cdots X_q)))$ is a sum of terms of the form $\rho(k_Z)^{-1} P(Z) Q(l_Z(Z)) \rho(k_Z)$ where P and Q are polynomials of degree $\leq 2q$ with values in $\text{End}(\mathcal{V})$.

By combining the arguments of the proof of Proposition 6.5 in [8] with those of the proof of Proposition 5.2 in [13], we then obtain the following result. Recall that $m := \sum_i m_i$.

PROPOSITION 5.2. *If $q < \frac{1}{4}(-m - 2n)$ then for each $X_1, X_2, \dots, X_q \in \mathfrak{g}^c$, the Berezin transform of $S(d\pi(X_1 X_2 \cdots X_q))$ is well-defined.*

We have then generalized Proposition 5.2 of [13]. However, it seems difficult to obtain here an explicit expression for $W(d\pi(X))$, $X \in \mathfrak{g}$, as in [13], Section 6.

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