

---

## **Short note      Construction of a quadrilateral from its sides and the diagonal angle**

---

Lorenz Halbeisen, Norbert Hungerbühler and Juan Läuchli

### **1 Introduction**

In [1], the authors challenged the readers by posing the task of constructing a convex quadrilateral from its four vertex angles and the angle between its diagonals. This problem was solved in [4]. A similar open problem was recently posed in [2]: construct a quadrilateral from its sides and the angle between its diagonals. Allowed are the classical tools compass and ruler. In the present short note, we show such a construction. As explained in [2], if the diagonals are orthogonal, then there is a continuum of solutions for given side lengths and the construction is elementary. We will therefore assume that the diagonals are not orthogonal.

### **2 The setup**

We choose a Cartesian coordinate system with origin in a vertex such that one diagonal lies on the  $x$ -axis. The quadrilateral may be non-convex or self-intersecting (see Figure 1). The sides and their lengths are denoted by  $c_1, c_2, c_3, c_4$ , the diagonals and their lengths by  $d$  and  $e$ . The coordinates of the vertices of the quadrangle are  $P_1 = (0, 0)$ ,  $P_2 = (x_2, y_2)$ ,  $P_3 = (d, 0)$  and  $P_4 = (x_4, y_4)$ . The angle between the diagonals is  $\varepsilon$ . By considering a mirror image of the quadrilateral if necessary, we may assume that  $\varepsilon < \pi/2$ .

We consider first the case of a convex quadrilateral. Then we have  $y_2 < 0 < y_4$ . The aim is to find an algebraic expression for  $d$  which involves only square roots and arithmetic operations on the side lengths  $c_i$  and  $\tan \varepsilon$ . Then  $d$  and subsequently the quadrilateral can be constructed by ruler and compass. We start with the equations

$$c_4^2 = x_4^2 + y_4^2, \tag{1}$$

$$c_3^2 = (d - x_4)^2 + y_4^2. \tag{2}$$

We can solve the difference of (1) and (2) for  $x_4$  and obtain

$$x_4 = \frac{1}{2d}(c_4^2 - c_3^2 + d^2). \tag{3}$$

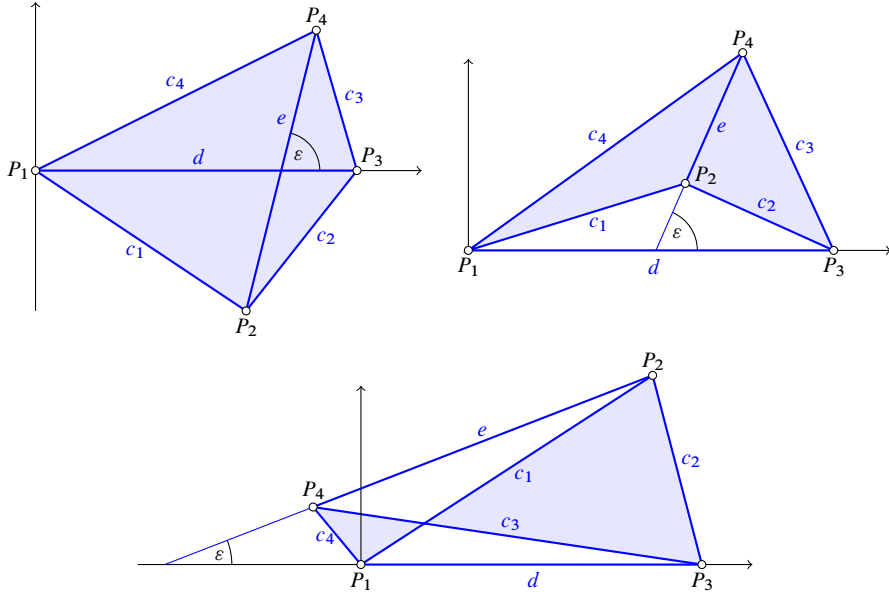


Figure 1. A coordinate system adapted to the quadrilateral.

If we plug in this expression for  $x_4$  in equation (1) and solve for  $y_4$ , we get

$$y_4 = \sqrt{c_4^2 - \frac{1}{4d^2}(c_4^2 - c_3^2 + d^2)^2}. \quad (4)$$

Similarly, we find

$$x_2 = \frac{1}{2d}(c_1^2 - c_2^2 + d^2) \quad (5)$$

and

$$y_2 = -\sqrt{c_1^2 - \frac{1}{4d^2}(c_1^2 - c_2^2 + d^2)^2}. \quad (6)$$

Using the expressions in (3)–(6), we can compute

$$\tan \varepsilon = \frac{y_4 - y_2}{x_4 - x_2} = \frac{\sqrt{4c_1^2d^2 - (c_1^2 - c_2^2 + d^2)^2} + \sqrt{4c_4^2d^2 - (c_4^2 - c_3^2 + d^2)^2}}{c_2^2 - c_1^2 + c_4^2 - c_3^2}. \quad (7)$$

Solving (7) directly for  $d$  by hand or a computer algebra system leads to an extremely unpleasant expression. We are therefore taking a different approach.

Equation (7) is an equation for  $x := d^2$  of the form

$$a = \sqrt{bx - (c + x)^2} + \sqrt{fx - (g + x)^2}$$

with

$$a = (c_2^2 - c_1^2 + c_4^2 - c_3^2) \tan \varepsilon, \quad b = 4c_1^2, \quad c = c_1^2 - c_2^2, \quad f = 4c_4^2, \quad g = c_4^2 - c_3^2. \quad (8)$$

**Lemma.** A solution  $x > 0$  of  $a = \sqrt{bx - (c + x)^2} \pm \sqrt{fx - (g + x)^2}$  is also a solution of the quadratic equation  $A + Bx + Cx^2 = 0$  with

$$\begin{aligned} A &= 2g^2(a^2 - c^2) + (a^2 + c^2)^2 + g^4, \\ B &= 2(a^2(2c - b - f + 2g) + (c^2 - g^2)(2c - b + f - 2g)), \\ C &= 4a^2 + (b - 2c - f + 2g)^2. \end{aligned}$$

*Proof.* Set  $u + v = bx - (c + x)^2$ ,  $u - v = fx - (g + x)^2$ , i.e.,

$$u = \frac{1}{2}(x(b - 2c + f - 2g) - 2x^2 - c^2 - g^2), \quad (9)$$

$$v = \frac{1}{2}(x(b - 2c - f + 2g) - c^2 + g^2). \quad (10)$$

Observe that if  $a = \sqrt{u + v} \pm \sqrt{u - v}$ , then  $a$  is a solution of

$$a^4 - 4a^2u + 4v^2 = 0 \quad (11)$$

(plug in, or see [3]). Using the expressions (9) and (10) for  $u$  and  $v$  in (11) and expanding, we get a quadratic equation  $A + Bx + Cx^2 = 0$  with the desired coefficients  $A, B, C$ . ■

Suppose that the given side lengths and the diagonal angle come from a convex quadrilateral. Then we can now formulate the construction.

**Construction 1.** Choose a unit length  $l$ . Then proceed as follows.

- (1) Construct with the intercept theorems line segments of lengths  $a, b, c, f, g$  as given in (8).
- (2) Construct with the intercept theorems line segments of lengths  $\frac{A}{C}, \frac{B}{C}$  for the values  $A, B, C$  as given in the lemma.
- (3) Construct the solutions of  $\frac{A}{C} + \frac{B}{C}x + x^2 = 0$  using the intersecting chords theorem or the intersecting secants theorem (see [3]). Obtain one or two solutions in form of a line segment of length  $x$ .
- (4) Transform the rectangle with sides  $x$  and  $l$  into a square of equal area with side length  $d$ , using the right triangle altitude theorem.
- (5) Construct the quadrilateral with diagonal  $d$  and sides  $c_1, c_2, c_3, c_4$ .

Note that there is only one solution if and only if the quadrilateral is cyclic [2, Corollary 1].

For the non-convex or the self-intersecting case, the sign in the numerator on the right of equation (7) changes to a minus:

$$\tan \varepsilon = \frac{y_4 - y_2}{x_4 - x_2} = \frac{\sqrt{4c_1^2d^2 - (c_1^2 - c_2^2 + d^2)^2} - \sqrt{4c_4^2d^2 - (c_4^2 - c_3^2 + d^2)^2}}{c_2^2 - c_1^2 + c_4^2 - c_3^2}.$$

As the lemma also covers this case, the formulas and the construction remain unchanged.

## References

- [1] H. Humenberger, [Similarity of quadrilaterals as starting point for a geometric journey to orthocentric systems and conics \(with an appendix by Ivan Izmetiev and Arseniy Akopyan\)](#). *Elem. Math.* **79** (2024), no. 4, 148–158 Zbl [07961610](#) MR [4817557](#)
- [2] H. Humenberger, [Two further characterizations of orthodiagonal quadrilaterals](#). *Elem. Math.* **81** (2026), 8–17
- [3] N. Hungerbühler, [An alternative quadratic formula](#). *Math. Semesterber.* **67** (2020), no. 1, 85–95 Zbl [1452.12003](#) MR [4067206](#)
- [4] N. Hungerbühler and J. Läuchli, [Construction of a quadrilateral from its vertex angles and the diagonal angle](#). *Elem. Math.* **79** (2024), no. 4, 159–166 Zbl [07961611](#) MR [4817558](#)

Lorenz Halbeisen  
Department of Mathematics  
ETH Zentrum  
Rämistr. 101  
8092 Zürich, Switzerland  
[lorenz.halbeisen@math.ethz.ch](mailto:lorenz.halbeisen@math.ethz.ch)

Norbert Hungerbühler  
Department of Mathematics  
ETH Zentrum  
Rämistr. 101  
8092 Zürich, Switzerland  
[norbert.hungerbuehler@math.ethz.ch](mailto:norbert.hungerbuehler@math.ethz.ch)

Juan Läuchli (corresponding author)  
Fachschaft Mathematik  
Kantonsschule Frauenfeld  
Ringstr. 10  
8500 Frauenfeld, Switzerland  
[juan.laeuchli@kftg.ch](mailto:juan.laeuchli@kftg.ch)