

# A Nonlinear Neumann-Type Problem of a System of High Order Hyperbolic Integro-Differential Equations

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The paper concerns a nonlinear Neumann-type boundary value problem for a system of hyperbolic integro-differential equations of order  $2p$  with two independent variables. The problem is reduced to a system of integro-functional equations and hence the existence and uniqueness of a local solution is proved by using the Banach fixed point theorem.

*Key words:* Neumann problem, integro-differential equations, hyperbolic equations and systems, nonlinear boundary value problems

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## 0. Introduction

Neumann and mixed boundary value problems for second order hyperbolic equations and systems have been dealt with in many papers (cp. [6, 11, 16 - 19, 22] and the references therein). Papers devoted to higher order equations were not so numerous and, except paper [9] where the right-hand side of the equation may depend on the unknown function but not on its derivatives, concerned only linear problems (cp. [1, 2, 5, 7 - 10, 12 - 15, 21]). In most of these papers the domain considered is a half-space.

In this paper we examine a nonlinear Neumann-type problem for a system of hyperbolic integro-differential equations of order  $2p$  (where  $p$  is any positive integer) with two independent variables. The method of treating the problem is different from those in the quoted papers and similar to that in our paper [4] - we reduce the problem to a system of nonlinear integro-functional equations, via an auxiliary boundary value problem analogous to that in [20], and hence prove the existence of a local solution by using the Banach fixed point theorem.

To the best of our knowledge, the problem in question has not been examined so far.

## 1. The problem

Let  $n, p \in \mathbf{N}$  (where  $\mathbf{N}$  denotes the set of all positive integers), set  $\mathcal{D} = [0, A] \times [0, B]$  with  $0 < A, B < \infty$  and consider the class  $\mathcal{K}$  of all functions (vectors)  $u = (u^k): \mathcal{D} \rightarrow \mathbf{R}^n$  such that the derivatives  $D_x^r D_y^s u$  (where  $D_x^r = \partial^r / \partial x^r$  and  $D_y^s = \partial^s / \partial y^s$ ) exist for  $r, s = 0, 1, \dots, p$  and are continuous. We introduce the notation (cp. [20])

$$V = (v_r), \quad W = (w_r), \quad Z = (z_{rs}), \quad \Phi = (V, W), \quad (1.1)$$

where

$$v_r = D_x^p D_y^r u, \quad w_r = D_y^p D_x^r u, \quad z_{rs} = D_x^s D_y^r u \quad (1.2)$$

( $r, s = 0, 1, \dots, p-1$ ). We deal with the system of integro-differential equations

$$L^p u(x, y) = F[x, y, Z(x, y), \Phi(x, y), \Omega(x, y)] \quad (1.3)$$

where  $L = D_x^1 D_y^1$  and

$$\Omega(x, y) = \int_0^x \int_0^y g[x, y; t, \tau, Z(t, \tau), \Phi(t, \tau)] d\tau dt \quad (1.4)$$

with  $F$  and  $g$  being given functions. By a *solution* of this system in  $\mathcal{D}$  we mean a function  $u \in \mathcal{K}$  satisfying (1.3) at each point  $(x, y) \in \mathcal{D}$ .

Let us consider a system of  $2p$  curves

$$\Gamma_0, \Gamma_1, \dots, \Gamma_{p-1} \quad \text{and} \quad \tilde{\Gamma}_0, \tilde{\Gamma}_1, \dots, \tilde{\Gamma}_{p-1}$$

of equations  $y = f_i(x)$  and  $x = h_i(y)$ , respectively, where

$$f_i: [0, A] \rightarrow [0, B] \quad \text{and} \quad h_i: [0, B] \rightarrow [0, A] \quad (i = 0, 1, \dots, p-1)$$

are given functions of class  $C^1$ . Denote by  $\mathbf{n}_i$  and  $\tilde{\mathbf{n}}_i$  the unit vectors normal to  $\Gamma_i$  and  $\tilde{\Gamma}_i$ , respectively. We examine the following boundary value problem.

**Problem (P):** Find a solution  $u$  of system (1.3) in  $\mathcal{D}$  satisfying the boundary conditions

$$\begin{aligned} \left( \frac{d^{p-i}}{d\mathbf{n}^{p-i}} \right) L^i u[x, f_i(x)] &= M_i(x, Z[x, f_i(x)], \Phi[x, f_i(x)]) \\ \left( \frac{d^{p-i}}{d\tilde{\mathbf{n}}^{p-i}} \right) L^i u[h_i(y), y] &= N_i(y, Z[h_i(y), y], \Phi[h_i(y), y]) \end{aligned} \quad (1.5)$$

( $(x, y) \in \mathcal{D}; i = 0, 1, \dots, p-1$ ).

We make the following **assumptions I - IV**:

**I.** Let  $c_i, \tilde{c}_i > 0$  and  $s_i, \tilde{s}_i \geq 0$  ( $i = 0, 1, \dots, p-1$ ) be constants such that the inequalities

$$\max(s_i, \tilde{s}_i) \leq 1, \quad x^{1-s_i} \leq b_i c_i A^{\omega_i}, \quad y^{1-\tilde{s}_i} \leq \tilde{b}_i \tilde{c}_i B^{\omega_i} \quad (1.6)$$

$((x, y) \in \mathcal{D})$  are satisfied for  $i = 0, 1, \dots, p - 2$ , where  $b_i, \bar{b}_i$  and  $\omega_i, \bar{\omega}_i$  are positive constants. Moreover, let  $m_i, \bar{m}_i > 0$  and  $a_i, \bar{a}_i > 0$  ( $i = 0, 1, \dots, p - 1$ ) be constants such that

$$\max_{[0, A]} |f'_i(x)| \leq a_i, \quad \max_{[0, B]} |h'_i(y)| \leq \bar{a}_i \quad \text{and} \quad m_i < a_i^{-i/p}, \quad \bar{m}_i < \bar{a}_i^{-i/p}. \quad (1.7)$$

All the said constants except  $c_i$  and  $\bar{c}_i$  are required to be independent of  $A$  and  $B$ . We assume that the functions  $f_i$  and  $h_i$  are of class  $C^{p-i}$  and satisfy the conditions

$$f'_i(x) \geq \max(f_i(x)/m_i x, c_i x^{p_i}) \quad \text{and} \quad h'_i(y) \geq \max(h_i(y)/\bar{m}_i y, \bar{c}_i y^{\bar{p}_i}) \quad (1.8)$$

$(x \in (0, A), y \in (0, B), i = 0, 1, \dots, p - 1)$ .

II. The functions  $M_i: [0, A] \times \mathbf{R}^{\bar{n}} \rightarrow \mathbf{R}^n$  and  $N_i: [0, B] \times \mathbf{R}^{\bar{n}} \rightarrow \mathbf{R}^n$  (where  $\bar{n}$  denotes the total number of elements of  $Z, V$  and  $W$ ) are continuous and satisfy the conditions

$$\begin{aligned} |M_i(x, (\mathbf{0})_1, (\mathbf{0})_2)| &\leq K_1 x^{\alpha_1} \\ |N_i(y, (\mathbf{0})_1, (\mathbf{0})_2)| &\leq K_1 y^{\alpha_1} \\ |M_i(x, \xi, \eta) - M_i(x, \bar{\xi}, \bar{\eta})| &\leq K_2 (\Xi_1 + \Xi_2) \\ |N_i(y, \xi, \eta) - N_i(y, \bar{\xi}, \bar{\eta})| &\leq K_2 (\Xi_1 + \Xi_2) \end{aligned} \quad (1.9)$$

$(\xi = (\xi_{\nu, \mu}); \eta = (\vartheta, \omega)$  with  $\vartheta = (\vartheta_\nu); \omega = (\omega_\nu)$  ( $\nu, \mu = 0, 1, \dots, p - 1$ );  $\bar{\xi}, \bar{\eta}$  and  $\bar{\omega}$  are understood analogously, and  $(\mathbf{0})_1$  and  $(\mathbf{0})_2$  denote the appropriate systems of zeros), where

$$\begin{aligned} \Xi_1 &= \sum_{\nu, \mu} [\max(|\xi_{\nu, \mu}|, |\bar{\xi}_{\nu, \mu}|)]^{\alpha_2 - 1} |\xi_{\nu, \mu} - \bar{\xi}_{\nu, \mu}| \\ \Xi_2 &= \sum_{\nu} \left\{ [\max(|\vartheta_\nu|, |\bar{\vartheta}_\nu|)]^{\alpha_3 - 1} |\vartheta_\nu - \bar{\vartheta}_\nu| + [\max(|\omega_\nu|, |\bar{\omega}_\nu|)]^{\alpha_3 - 1} |\omega_\nu - \bar{\omega}_\nu| \right\}, \end{aligned} \quad (1.10)$$

the exponents  $\alpha_1, \alpha_2, \alpha_3$  fulfil the inequalities

$$\alpha_1 > p \max \left( 2, 1 + \frac{\hat{s}_{p-1}}{p} \right) \quad \text{and} \quad \min(\alpha_2, \alpha_3) > \max \left( 2, 1 + \frac{\hat{s}_{p-1}}{p} \right) \quad (1.11)$$

with  $\hat{s}_{p-1} = \max(s_{p-1}, \bar{s}_{p-1})$ , and  $K_1$  and  $K_2$  are positive constants. Moreover, at the common points of the curves considered, the functions  $M_i$  and  $N_i$  satisfy suitable compatibility conditions.

III. The function  $F: \mathcal{D} \times \mathbf{R}^{\bar{n}+n} \rightarrow \mathbf{R}^n$  is continuous and satisfies the conditions

$$|F(x, y, (\mathbf{0})_1, (\mathbf{0})_2), (\mathbf{0})_3| \leq K_3 (x^{\beta_1} + y^{\beta_1})$$

and

$$\begin{aligned} &|F(x, y, \xi, \eta, \zeta) - F(x, y, \bar{\xi}, \bar{\eta}, \bar{\zeta})| \\ &\leq K_4 \left\{ \sum_{\nu, \mu} [\max(|\xi_{\nu, \mu}|, |\bar{\xi}_{\nu, \mu}|)]^{\beta_2 - 1} |\xi_{\nu, \mu} - \bar{\xi}_{\nu, \mu}| \right. \\ &\quad + \sum_{\nu} \left\langle [\max(|\vartheta_\nu|, |\bar{\vartheta}_\nu|)]^{\beta_3 - 1} |\vartheta_\nu - \bar{\vartheta}_\nu| \right. \\ &\quad \left. \left. + [\max(|\omega_\nu|, |\bar{\omega}_\nu|)]^{\beta_3 - 1} |\omega_\nu - \bar{\omega}_\nu| \right\rangle + |\zeta - \bar{\zeta}|^{\beta_4 - 1} \right\} \end{aligned} \quad (1.12)$$

(( $\mathbf{0}$ )<sub>3</sub> is the system of  $n$  zeros). where the exponents fulfil the inequalities

$$\beta_1, 2\beta_4 > \max(p, p - (1 - \hat{s}_{p-1})) \quad \text{and} \quad \min_{r=2,3} \beta_r > \max(1, 1 - \frac{1 - \hat{s}_{p-1}}{p}) \quad (1.13)$$

and  $K_3$  and  $K_4$  are positive constants.

IV. The function  $g: \mathcal{D}^2 \times \mathbf{R}^{\bar{n}} \rightarrow \mathbf{R}^n$  is continuous and satisfies the conditions

$$\begin{aligned} |g(x, y; t, \tau, (\mathbf{0})_1, (\mathbf{0})_2)| &\leq K_5 \\ |g(x, y; t, \tau, \xi, \eta) - g(x, y; t, \tau, \bar{\xi}, \bar{\eta})| \\ &\leq K_6 \left[ \sum_{\nu, \mu} |\xi_{\nu, \mu} - \bar{\xi}_{\nu, \mu}| + \sum_{\nu} (|\vartheta_{\nu} - \bar{\vartheta}_{\nu}| + |\omega_{\nu} - \bar{\omega}_{\nu}|) \right] \end{aligned} \quad (1.14)$$

where  $K_5$  and  $K_6$  are positive constants.

**Corollary 1.1.** *It follows from Assumptions II - IV that the inequalities*

$$\begin{aligned} |M_i(x, \xi, \eta)| &\leq K_1 x^{\alpha_1} + K_2 \left[ \sum_{\nu, \mu} |\xi_{\nu, \mu}|^{\alpha_2} + \sum_{\nu} (|\vartheta_{\nu}|^{\alpha_3} + |\omega_{\nu}|^{\alpha_3}) \right] \\ |N_i(y, \xi, \eta)| &\leq K_1 y^{\alpha_1} + K_2 \left[ \sum_{\nu, \mu} |\xi_{\nu, \mu}|^{\alpha_2} + \sum_{\nu} (|\vartheta_{\nu}|^{\alpha_3} + |\omega_{\nu}|^{\alpha_3}) \right] \\ |F(x, y, \xi, \eta, \zeta)| &\leq K_3 (x^{\beta_1} + y^{\beta_1}) \\ &\quad + K_4 \left[ \sum_{\nu, \mu} |\xi_{\nu, \mu}|^{\beta_2} + \sum_{\nu} (|\vartheta_{\nu}|^{\beta_3} + |\omega_{\nu}|^{\beta_3}) + |\zeta|^{\beta_4} \right] \\ |g(x, y; t, \tau, \xi, \eta)| &\leq K_5 + K_6 \left[ \sum_{\nu, \mu} |\xi_{\nu, \mu}| + \sum_{\nu} (|\vartheta_{\nu}| + |\omega_{\nu}|) \right] \end{aligned} \quad (1.15)$$

are satisfied.

**Remark 1.1.** Let us assume that

$$\Gamma_i \equiv \Gamma_0, \tilde{\Gamma}_i \equiv \tilde{\Gamma}_0 \quad (i = 0, 1, \dots, p-1) \quad \text{and} \quad f_0(A) = B, h_0(B) = A$$

and that the curves  $\Gamma_0$  and  $\tilde{\Gamma}_0$  do not intersect one another apart from the points  $(0, 0)$  and  $(A, B)$ . Setting  $\Gamma = \Gamma_0 \cup \tilde{\Gamma}_0$  and denoting by  $\bar{\mathcal{D}}$  the domain bounded by  $\Gamma$ , we can assert that problem ( $\mathcal{P}$ ) is in the considered case a Neumann-type problem for the domain  $\bar{\mathcal{D}}$ , with the boundary conditions (1.5) given on its boundary  $\Gamma$ . The compatibility conditions for  $M_i$  and  $N_i$  are in this case

$$M_i(0, \xi, \eta) = N_i(0, \xi, \eta) \quad \text{and} \quad M_i(A, \xi, \eta) = N_i(B, \xi, \eta)$$

(( $\xi, \eta$ )  $\in \mathbf{R}^{\bar{n}}$ ;  $i = 0, 1, \dots, p-1$ ).

**Example 1.1.** We give an example of curves satisfying Assumption I. Let

$$\Gamma_i \equiv \Gamma_0, \tilde{\Gamma}_i \equiv \tilde{\Gamma}_0 \quad (i = 0, 1, \dots, p-1), \quad A = B \quad \text{and} \quad \gamma \in (1, 2].$$

Set  $f_0(x) = A^{1-\gamma}x^\gamma$  and

a)  $h_0(y) = A^{1-\gamma}y^\gamma$

b)  $h_0(y) = (A/\sin A^\gamma) \sin y^\gamma$ .

Assumption I is satisfied with

$$b_0 = 1/\gamma, c_0 = \gamma/A^{\gamma-1}, \omega_0 = 1, s_0 = \gamma - 1, m_0 = 1/\gamma, a_0 = \gamma$$

and

a) the same parameters as for  $f_0(x)$

b)  $\tilde{b}_0 = b_0, \tilde{c}_0 = c_0, \tilde{\omega}_0 = 1, \tilde{s}_0 = s_0, \tilde{m}_0 = 1/(\gamma(1 - \varepsilon)), \tilde{a}_0 = \gamma/(1 - \varepsilon)$ , where  $0 < \varepsilon < 1 - (1/\gamma)^{1/2p}$  (we assume that  $A$  is sufficiently small, so that  $0 < A < [\arccos(1 - \varepsilon^2)]^{1/\gamma}$ ).

### 2. Auxiliary considerations

We begin this section with the following lemma whose inductive proof will be omitted.

**Lemma 2.1.** *If  $m \in \mathbb{N}$ ,  $v \in C^m(\mathcal{D})$  and  $s$  is a non-zero vector, then*

$$\begin{aligned} & \frac{d^m}{ds^m} v \\ &= \sum_{k=0}^m \binom{m}{k} D_x^k D_y^{m-k} v \cos^k \alpha \cos^{m-k} \beta \\ &+ \sum_{\nu=0}^{m-2} \frac{d^\nu}{ds^\nu} \left[ \sum_{\mu=0}^{m-1-\nu} \binom{m-1-\nu}{\mu} D_x^\mu D_y^{m-1-\nu-\mu} v \frac{d}{ds} (\cos^\mu \alpha \cos^{m-1-\nu-\mu} \beta) \right] \end{aligned} \tag{2.1}$$

(as usual, we set  $\sum_{\nu=0}^{m-2} u_\nu = 0$  for  $m < 2$ ), where  $(x, y) \in \mathcal{D}$ , and  $\alpha$  and  $\beta$  are the angles of  $s$  with the positive directions of the axes  $Ox$  and  $Oy$ , respectively.

As an immediate consequence of Lemma 2.1, we get the following corollary (cp. relations (1.2)).

**Corollary 2.1.** *If  $u \in \mathcal{K}$ , then*

$$\begin{aligned} & \frac{d^{p-i}}{d\hat{n}_i^{p-i}} L^i u(x, y) \\ &= v_i(x, y) \cos^{p-i} \alpha_i + w_i(x, y) \cos^{p-i} \beta_i \\ &+ \sum_{k=1}^{p-i-1} \binom{p-i}{k} z_{p-k, k+i}(x, y) \cos^k \alpha_i \cos^{p-i-k} \beta_i \\ &+ \sum_{\nu=0}^{p-i-2} \frac{d^\nu}{d\hat{n}_i^\nu} \left[ \sum_{\mu=0}^{p-i-1-\nu} \binom{p-i-1-\nu}{\mu} z_{p-i-1-\nu-\mu, \mu+i}(x, y) \right. \\ &\quad \left. \times \frac{d}{d\hat{n}_i} (\cos^\mu \alpha_i \cos^{p-i-1-\nu-\mu} \beta_i) \right] \end{aligned} \tag{2.2}$$

$((x, y) \in \mathcal{D})$ , where  $\hat{\mathbf{n}}_i = \mathbf{n}_i, \tilde{\mathbf{n}}_i; \alpha_i = (0x, \hat{\mathbf{n}}_i)$  and  $\beta_i = (0y, \hat{\mathbf{n}}_i)$  ( $i = 0, 1, \dots, p-1$ ).

Now, let  $\mathcal{K}_1$  be the class of all functions  $u \in \mathcal{K}$  such that

$$v_i(0, 0) = w_i(0, 0) = z_{ij}(0, 0) = 0 \quad (2.3)$$

( $i, j = 0, 1, \dots, p-1$ ), and assume that the normal vectors  $\mathbf{n}_i$  and  $\tilde{\mathbf{n}}_i$  are directed so that

$$\cos(x, \mathbf{n}_i) = \frac{-f'_i(x)}{e_i(x)}, \cos(x, \tilde{\mathbf{n}}_i) = \frac{-1}{\tilde{e}_i(y)}, \cos(y, \mathbf{n}_i) = \frac{1}{e_i(x)}, \cos(y, \tilde{\mathbf{n}}_i) = \frac{h'(y)}{\tilde{e}_i(y)} \quad (2.4)$$

where

$$e_i(x) = \sqrt{1 + (f'_i(x))^2} \quad \text{and} \quad \tilde{e}_i(y) = \sqrt{1 + (h'_i(y))^2}. \quad (2.5)$$

Basing on Corollary 2.1 and using formulas (2.4), we can assert that, in the class  $\mathcal{K}_1$ , problem (P) is equivalent to the following problem ( $\Sigma$ ) (cp. with those in [3, 20]).

**Problem ( $\Sigma$ ):** Find a solution  $u \in \mathcal{K}_1$  of system (1.3) in  $\mathcal{D}$  satisfying the boundary conditions

$$v_i[x, f_i(x)] = G_\Phi^i(x) \quad \text{and} \quad w_i[h_i(y), y] = H_\Phi^i(y) \quad (2.6)$$

$((x, y) \in \mathcal{D})$ , where

$$\begin{aligned} G_\Phi^i(0) &= H_\Phi^i(0) = 0 \\ G_\Phi^i(x) &= \tilde{G}_\Phi^i(x) + \hat{G}_\Phi^i(x) \quad \text{for } x \in (0, A] \\ H_\Phi^i(y) &= \tilde{H}_\Phi^i(y) + \hat{H}_\Phi^i(y) \quad \text{for } y \in (0, B] \end{aligned} \quad (2.7)$$

with

$$\tilde{G}_\Phi^i(x) = -(-f'_i(x))^{i-p} w_i[x, f_i(x)], \quad \tilde{H}_\Phi^i(y) = -(-h'_i(y))^{i-p} v_i[h_i(y), y] \quad (2.8)$$

$$\begin{aligned} \hat{G}_\Phi^i(x) &= \left( \frac{-e_i(x)}{f'_i(x)} \right)^{p-i} \left\{ M_i(x, Z[x, f_i(x)], \Phi[x, f_i(x)]) \right. \\ &\quad - \sum_{k=1}^{p-i-1} \binom{p-i}{k} z_{p-k, k+i}[x, f_i(x)] \frac{(-f'_i(x))^k}{(e_i(x))^{p-i}} \\ &\quad - \sum_{\nu=0}^{p-i-2} \left( \frac{d^\nu}{dn_i^\nu} \left[ \frac{-f'_i(x)}{e_i(x)} \sum_{\mu=0}^{p-i-1-\nu} \binom{p-i-1-\nu}{\mu} \right. \right. \\ &\quad \left. \left. \times z_{p-i-1-\nu-\mu, \mu+i}(x, y) \left( \frac{(-f'_i(x))^\mu}{(e_i(x))^{p-i-1-\nu}} \right)' \right] \right) \Bigg|_{y=f_i(x)} \left. \right\} \end{aligned} \quad (2.9')$$

and

$$\begin{aligned}
 \hat{H}_\Phi^i(x) = & \left( \frac{\tilde{e}_i(y)}{h'_i(y)} \right)^{p-i} \left\{ N_i(y, Z[h_i(y), y], \Phi[h_i(y), y]) \right. \\
 & - \sum_{k=1}^{p-i-1} \binom{p-i}{k} z_{p-k, k+i}[h_i(y), y] (-1)^k \frac{(h'_i(y))^{p-i-k}}{(\tilde{e}_i(y))^{p-i}} \\
 & - \sum_{\nu=0}^{p-i-2} \left( \frac{d^\nu}{d\tilde{h}_i^\nu} \left[ \frac{-1}{\tilde{e}_i(y)} \sum_{\mu=0}^{p-i-1-\nu} \binom{p-i-1-\nu}{\mu} \right. \right. \\
 & \left. \left. \times z_{p-i-1-\nu-\mu, \mu+i}(x, y) \left( (-1)^\mu \frac{(h'_i(y))^{p-i-1-\nu-\mu}}{(\tilde{e}_i(y))^{p-i-1-\nu}} \right)' \right]_{x=h_i(y)} \right) \left. \right\}
 \end{aligned} \tag{2.9}''$$

( $i = 0, 1, \dots, p - 1$ ).

We shall use the following lemma whose validity follows from Taylor’s formula with the integral remainder.

**Lemma 2.2.** *If  $u \in \mathcal{K}_1$ , then*

$$\begin{aligned}
 z_{r,s}(x, y) = & \int_0^x \frac{(x - \xi)^{p-s-1}}{(p - s - 1)!} v_r(\xi, y) d\xi \\
 & + \sum_{k=0}^{p-s-1} \int_0^y \frac{(y - \eta)^{p-r-1}}{(p - r - 1)!} w_{s+k}(0, \eta) d\eta \frac{x^k}{k!} \\
 = & \int_0^y \frac{(y - \eta)^{p-r-1}}{(p - r - 1)!} w_s(x, \eta) d\eta \\
 & + \sum_{k=0}^{p-r-1} \int_0^x \frac{(x - \xi)^{p-s-1}}{(p - s - 1)!} v_{r+k}(\xi, 0) d\xi \frac{y^k}{k!}
 \end{aligned} \tag{2.10}$$

(( $x, y$ )  $\in \mathcal{D}$ ;  $r, s = 0, 1, \dots, p - 1$ ). *If, moreover,  $u$  is a solution of system (1.3) in  $\mathcal{D}$ , then*

$$\begin{aligned}
 v_r(x, y) = & \sum_{k=0}^{p-r-1} v_{r+k}(x, 0) \frac{y^k}{k!} \\
 & + \int_0^y \frac{(y - \eta)^{p-r-1}}{(p - r - 1)!} F[x, \eta, Z(x, \eta), \Phi(x, \eta), \Omega(x, \eta)] d\eta \\
 w_r(x, y) = & \sum_{k=0}^{p-r-1} w_{r+k}(0, y) \frac{x^k}{k!} \\
 & + \int_0^x \frac{(x - \xi)^{p-r-1}}{(p - r - 1)!} F[\xi, y, Z(\xi, y), \Phi(\xi, y), \Omega(\xi, y)] d\xi
 \end{aligned} \tag{2.11}$$

(( $x, y$ )  $\in \mathcal{D}$ ;  $r = 0, 1, \dots, p - 1$ ).

If  $z_{rs}$  ( $r, s = 0, 1, \dots, p-1$ ) are expressed in terms of  $\Phi$  by formulae (2.10), then we shall write  $Z = \Lambda_\Phi^1 = ({}^1\lambda_{\Phi}^{rs})$ . The expression  $\Omega$  (cp. (1.4)) with  $Z = \Lambda_\Phi^1$  will be denoted by  $\Lambda_\Phi^*$ . Finally,  $\Lambda_\Phi^2 = ({}^2\lambda_{\Phi}^{rs})$  and  $\Lambda_\Phi^3 = ({}^3\lambda_{\Phi}^{rs})$  will stand for  $V$  and  $W$ , respectively, with  $v_r$  and  $w_r$  given by (2.11) with  $Z = \Lambda_\Phi^1$  and  $\Omega = \Lambda_\Phi^*$ .

Now, let us consider the following system of integro-functional equations

$$v_i(x, y) = \mathbf{T}_\Phi^i(x, y), \quad w_i(x, y) = \hat{\mathbf{T}}_\Phi^i(x, y) \tag{2.12}$$

$((x, y) \in \mathcal{D}; i = 0, 1, \dots, p-1)$  with the unknown vector  $\Phi$  (cp. (1.1), (1.2)), where

$$\begin{aligned} \mathbf{T}_\Phi^i(x, y) &= \mathbf{G}_\Phi^i(x) + \int_{f_i(x)}^y \vartheta_\Phi^i(x, \eta) d\eta \\ \hat{\mathbf{T}}_\Phi^i(x, y) &= \mathbf{H}_\Phi^i(y) + \int_{h_i(y)}^x \hat{\vartheta}_\Phi^i(\xi, y) d\xi \end{aligned} \tag{2.13}$$

$(i = 0, 1, \dots, p-1)$ . Here

$$\mathbf{G}_\Phi^i(0) = \mathbf{H}_\Phi^i(0) = 0$$

and

$$\begin{aligned} \mathbf{G}_\Phi^i(x) &= \check{\mathbf{G}}_\Phi^i(x) + \hat{\mathbf{G}}_\Phi^i(x) && \text{for all } x \in (0, A) \\ \mathbf{H}_\Phi^i(y) &= \check{\mathbf{H}}_\Phi^i(y) + \hat{\mathbf{H}}_\Phi^i(y) && \text{for all } y \in (0, B) \end{aligned}$$

where  $\check{\mathbf{G}}_\Phi^i$  and  $\check{\mathbf{H}}_\Phi^i$  denote the expressions (2.8), respectively, with  $V = \Lambda_\Phi^2, W = \Lambda_\Phi^3$  (we set in (2.11)  $Z = \Lambda_\Phi^1; \Omega = \Lambda_\Phi^*$ ), and  $\hat{\mathbf{G}}_\Phi^i$  and  $\hat{\mathbf{H}}_\Phi^i$  the expressions (2.9), respectively, with  $Z = \Lambda_\Phi^1$ . Moreover,  $\vartheta_\Phi^i$  and  $\hat{\vartheta}_\Phi^i$  are given by

$$\vartheta_\Phi^i(x, \eta) = \begin{cases} v_{i+1}(x, \eta) & \text{for } i = 0, 1, \dots, p-2 \\ F[x, \eta, \Lambda_\Phi^1(x, \eta), \Phi(x, \eta), \Lambda_\Phi^*(x, \eta)] & \text{for } i = p-1 \end{cases} \tag{2.14}$$

$$\hat{\vartheta}_\Phi^i(\xi, y) = \begin{cases} w_{i+1}(\xi, y) & \text{for } i = 0, 1, \dots, p-2 \\ F[\xi, y, \Lambda_\Phi^1(\xi, y), \Phi(\xi, y), \Lambda_\Phi^*(\xi, y)] & \text{for } i = p-1 \end{cases} \tag{2.15}$$

The following lemma holds good, the validity of which follows from that of Lemma 8 in [3].

**Lemma 2.3.** *If  $u$  is a solution of problem  $(\Sigma)$ , then  $\Phi$  is a continuous solution of system (2.12). Conversely, if  $\Phi$  is a continuous solution of system (2.12), then the function  $z_{00} = {}^1\lambda_{\Phi}^{00}$  is a solution of problem  $(\Sigma)$ .*



### 3. Solution of the problem

In this section we shall prove the existence and uniqueness of a solution of problem  $(\Sigma)$  (and hence of problem  $(\mathcal{P})$ ) by using the Banach fixed point theorem.

Let  $\mathcal{S}$  be the set of all systems  $\Phi$  (cp. (1.1)), where the components

$$v_i: \mathcal{D}_* \rightarrow \mathbb{R}^n \quad \text{and} \quad w_i: \mathcal{D}_* \rightarrow \mathbb{R}^n \quad (\mathcal{D}_* = \mathcal{D} \setminus \{(0, 0)\}; i = 0, 1, \dots, p-1)$$

are continuous functions such that

$$B_\Phi := \max_{0 \leq i \leq p-1} \max \left( \sup_{\mathcal{D}_*} [(x^p + y^p)^{-1} |v_i(x, y)|], \sup_{\mathcal{D}_*} [(x^p + y^p)^{-1} |w_i(x, y)|] \right) < \infty.$$

We define the distance by the formula

$$d(\Phi, \bar{\Phi})^{\mathbb{R}} = B_{\Phi - \bar{\Phi}} = \max_{0 \leq i \leq p-1} \max \left( \sup_{\mathcal{D}_*} [(x^p + y^p)^{-1} |v_i(x, y) - \bar{v}_i(x, y)|], \sup_{\mathcal{D}_*} [(x^p + y^p)^{-1} |w_i(x, y) - \bar{w}_i(x, y)|] \right) \tag{3.1}$$

$(\Phi = (V, W)$  and  $\bar{\Phi} = (\bar{V}, \bar{W}))$ . It is easily observed that  $\mathcal{S}$  is a complete metric space. Let us consider the set  $\mathcal{Z}$  of all points  $\Phi \in \mathcal{S}$  such that

$$B_\Phi \leq \kappa, \tag{3.2}$$

where  $\kappa \in (0, 1)$ . This is a closed subset of  $\mathcal{S}$  and hence it is itself a complete metric space with the metric given by (3.1).

In view of system (2.12), we map  $\mathcal{Z}$  by the transformation  $\mathbf{T}$  defined by formulas (cp. (2.13) - (2.15))

$$\tilde{v}_i(x, y) = \mathbf{T}_\Phi^i(x, y) \quad \text{and} \quad \tilde{w}_i(x, y) = \hat{\mathbf{T}}_\Phi^i(x, y) \tag{3.3}$$

$((x, y) \in \mathcal{D}_*; i = 0, 1, \dots, p-1)$ . In the sequel,  $\tilde{\Phi}$  will denote the system  $(\tilde{V}, \tilde{W})$  where  $\tilde{V} = (\tilde{v}_i)$  and  $\tilde{W} = (\tilde{w}_i)$ . We shall find sufficient conditions for the inclusion  $\mathbf{T}(\mathcal{Z}) \subset \mathcal{Z}$ .

In order to estimate the functions  $\tilde{v}_i$  and  $\tilde{w}_i$ , let us first observe that the following inequality is valid (cp. (1.8), (2.10) and (3.2)):

$$|\lambda_\Phi^{r,s} [x, f_i(x)]| \leq \kappa \left[ x^{2p-s} (1 + (m_i a_i)^p) + x^{2p-r} (m_i a_i)^{2p-r} \sum_{k=0}^{p-s-1} \frac{A^k}{k!} \right] \tag{3.4}$$

$(r, s = 0, 1, \dots, p-1)$ , whence, and from Assumption I, Corollary 1.1 and relations (2.8), (2.11) and (3.2), we obtain the sequence of inequalities (in which, as well as in the sequel, const denotes a positive constant independent of  $\kappa$ )

$$\begin{aligned} |\tilde{\mathbf{G}}_\Phi^i(x)| &\leq (m_i a_i)^i m_i^{p-i} \left( 1 + \sum_{k=1}^{p-i-1} \frac{A^k}{k!} \right) \kappa x^p \\ &\quad + \text{const} \left( \frac{x}{f'_i(x)} \right)^{p-i} \left[ x^{\beta_1} + (f_i(x))^{\beta_1} + \kappa (x^{(p+1)\beta_2} + x^{p\beta_3} + x^{(p+1)\beta_4}) \right] \\ &\leq \left[ (m_i a_i)^i m_i^{p-i} \kappa + \text{const}(1 + \kappa) A^{\dot{\omega}_i} \right] x^p, \end{aligned} \tag{3.5}$$

where  $\tilde{\omega}_i = \min(\omega_i, 1)$  ( $i = 0, 1, \dots, p - 2$ ). For  $i = p - 1$ , we have

$$\begin{aligned} |\tilde{G}_\Phi^{p-1}(x)| &\leq (m_{p-1}a_{p-1})^{p-1} m_{p-1} \kappa x^p + \text{const} \left( \frac{x}{f_{p-1}'(x)} \right) \left[ x^{\beta_1} + (f_{p-1}(x))^{\beta_1} \right. \\ &\quad \left. + \kappa (x^{(p+1)\beta_2} + x^{p\beta_3} + x^{(p+1)\beta_4}) \right] \\ &\leq (m_{p-1}a_{p-1})^{p-1} m_{p-1} \kappa x^p + \text{const}(1 + \kappa)x^{(1-\sigma_{p-1}+\beta)}, \end{aligned} \tag{3.5'}$$

where  $\bar{\beta} = \min(\beta_1, (p + 1) \min(\beta_2, \beta_4), \beta_3)$ . Inequalities (1.13) and (3.5') yield

$$|\tilde{G}_\Phi^{p-1}(x)| \leq [(m_{p-1}a_{p-1})^{p-1} m_{p-1} \kappa + \text{const}(1 + \kappa)A^{\tilde{\omega}_{p-1}}] x^p, \tag{3.6}$$

where  $\tilde{\omega}_{p-1}$  is a positive constant, and using (3.5) and (3.6) we obtain

$$|\tilde{G}_\Phi^i(x)| \leq [(m_i a_i)^i m_i^{p-i} \kappa + \text{const}(1 + \kappa)A^{\theta'_i}] x^p \tag{3.7}$$

( $x \in (0, A]$ ;  $i = 0, 1, \dots, p - 1$ ), where  $\theta'_i$  are positive constants.

We proceed to the examination of  $\tilde{G}_\Phi^i(x)$  (cp. (2.9) and (2.13)). Let us observe that, by Assumption I, Corollary 1.1 and relations (2.5) and (3.4), we obtain

$$\left| \left( \frac{-e_i(x)}{f_i'(x)} \right)^{p-i} M_i(x, \Lambda_\Phi^1[x, f_i(x)], \Phi[x, f_i(x)]) \right| \leq \text{const}(1 + \kappa)A^{\theta''_i} x^p, \tag{3.8}$$

where  $\theta''_i$  are positive constants and  $i = 0, 1, \dots, p - 1$ . Moreover, basing on Assumption I and using formulae (2.10) and (3.2), we get the sequence of inequalities

$$\begin{aligned} &\left| \left( \frac{-e_i(x)}{f_i'(x)} \right)^{p-i} \sum_{k=1}^{p-i-1} \binom{p-i}{k} {}^1\lambda_{\Phi}^{\beta-k, k+i}[x, f_i(x)] \frac{(-f_i'(x))^k}{(e_i(x))^{p-i}} \right| \\ &\leq \text{const} \kappa \sum_{k=1}^{p-i-1} \binom{p-i}{k} \left[ \left( \frac{x}{f_i'(x)} \right)^{p-i-k} (x^p + (f_i(x))^p) + \frac{(f_i(x))^{p+k}}{(f_i'(x))^{p-i-k}} \right] \\ &\leq \text{const} \kappa \sum_{k=1}^{p-i-1} [(b_i A^{\omega_i})^{p-i-k} + A^k] x^p \\ &\leq \text{const} \kappa A^{\omega_i} x^p. \end{aligned} \tag{3.9}$$

Thus, it remains to estimate the expressions

$$\begin{aligned} \Delta_\Phi^i(x) &= \left( \frac{-e_i(x)}{f_i'(x)} \right)^{p-i} \sum_{\nu=0}^{p-i-2} \left\{ \frac{d^\nu}{d\mathbf{n}_i^\nu} \left[ \left( \frac{-f_i'(x)}{e_i(x)} \right)^{p-i-1-\nu} \sum_{\mu=0}^{p-i-1-\nu} \binom{p-i-1-\nu}{\mu} \right. \right. \\ &\quad \left. \left. \times {}^1\lambda_{\Phi}^{p-i-1-\nu-\mu, \mu+i}(x, y) \left( \frac{(-f_i'(x))^\mu}{(e_i(x))^{p-i-1-\nu}} \right)' \right] \right\}_{y=f_i(x)} \end{aligned} \tag{3.10}$$

( $i = 0, 1, \dots, p - 2$ ). Let us examine the part of  $\Delta_{\Phi}^i(x)$  given by

$$\begin{aligned} \tilde{\Delta}_{\Phi}^i(x) &= \left(\frac{-e_i(x)}{f_i'(x)}\right)^{p-i} \sum_{\nu=0}^{p-i-2} \left\{ D_y^{\nu} \left[ \left(\frac{-f_i'(x)}{e_i(x)}\right)^{p-i-1-\nu} \binom{p-i-1-\nu}{\mu} \right. \right. \\ &\quad \left. \left. \times {}^1\lambda_{\Phi}^{p-i-1-\nu-\mu, \mu+i}(x, y) \right] \left(\frac{(-f_i'(x))^{\mu}}{(e_i(x))^{p-i-1-\nu}}\right)' (e_i(x))^{-\nu} \right\}_{y=f_i(x)} \end{aligned} \tag{3.11}$$

Evidently,

$$|\tilde{\Delta}_{\Phi}^i(x)| \leq \tilde{\delta}_{\Phi}^i(x) + \hat{\delta}_{\Phi}^i(x), \tag{3.12}$$

where

$$\tilde{\delta}_{\Phi}^i(x) = (f_i'(x))^{p+i+1} \sum_{\nu=0}^{p-i-2} (p-i-1-\nu) \left| {}^1\lambda_{\Phi}^{p-i-2, i+1}[x, f_i(x)] f_i''(x) \right| \tag{3.13}$$

and

$$\begin{aligned} \hat{\delta}_{\Phi}^i(x) &= (f_i'(x))^{p+i+1} \\ &\quad \times \sum_{\nu=0}^{p-i-2} \left\{ \sum_{\mu=0}^{p-i-1-\nu} \binom{p-i-1-\nu}{\mu} \right. \\ &\quad \times \left| {}^1\tilde{\lambda}_{\Phi}^{p-i-1-\mu, \mu+i}[x, f_i(x)] \right| \frac{p-i-1-\nu}{(e_i(x))^2} (f_i'(x))^{\mu+1} \\ &\quad + \sum_{\mu=2}^{p-i-1-\nu} \binom{p-i-1-\nu}{\mu} \\ &\quad \left. \times \left| {}^1\lambda_{\Phi}^{p-i-1-\mu, \mu+i}[x, f_i(x)] \right| \mu (f_i'(x))^{\mu-1} \right\} |f_i''(x)|. \end{aligned} \tag{3.14}$$

Basing on Assumption I and relations (2.5), (2.10) and (3.2), we have

$$\tilde{\delta}_{\Phi}^i(x) \leq \text{const } \kappa \left[ \left(\frac{x}{f_i'(x)}\right)^{p-i-1} + x^{i+1} \right] x^p,$$

whence (cp. the derivation of (3.9)) we get

$$\tilde{\delta}_{\Phi}^i(x) \leq \text{const } \kappa A^{\tilde{\omega}_i} x^p \tag{3.15}$$

with  $\tilde{\omega}_i$  being understood as in (3.5). In the same way we obtain

$$\hat{\delta}_{\Phi}^i(x) \leq \text{const } \kappa \left[ \left(\frac{x}{f_i'(x)}\right)^{p-i-\mu} + x^{i+1} \right] x^p \leq \text{const } \kappa A^{\hat{\omega}_i} x^p. \tag{3.16}$$

Thus, by (3.12) - (3.16), the expression  $\tilde{\Delta}_{\Phi}^i$  (cp. (3.11)) satisfies the inequality

$$|\tilde{\Delta}_{\Phi}^i(x)| \leq \text{const } \kappa A^{\tilde{\omega}_i} x^p \tag{3.17}$$

( $i = 0, 1, \dots, p-2$ ).

Using a similar argument and basing on the inequality (cp. (2.4))  $|\cos(x, \mathbf{n}_i)| \leq f'_i(x)$ , we can conclude that (cp. (3.10) and (3.11))

$$|\Delta_{\Phi}^i(x) - \tilde{\Delta}_{\Phi}^i(x)| \leq \text{const } \kappa A^{\omega_i} x^p. \quad (3.18)$$

On joining relations (3.8) - (3.11), (3.17) and (3.18), we get

$$|\hat{\mathbf{G}}_{\Phi}^i(x)| \leq \text{const}(1 + \kappa) A^{\theta_i'''} x^p \quad (3.19)$$

( $x \in (0, A]$ ;  $i = 0, 1, \dots, p-1$ ), where  $\theta_i'''$  are positive constants, and (3.7) and (3.19) yield the following estimate of the first term in the first of relations (2.13) (cp. (2.7)):

$$|\mathbf{G}_{\Phi}^i(x)| \leq \left[ (m_i a_i)^i m_i^{p-i} \kappa + \text{const}(1 + \kappa) A^{\theta_i} \right] x^p \quad (3.20)$$

( $x \in [0, A]$ ;  $i = 0, 1, \dots, p-1$ ), where  $\theta_i$  are positive constants.

As for the second term in the first of relations (2.13), we easily conclude, basing on Assumptions I, III, IV and formulae (2.15), (3.2), that

$$\left| \int_{f_i(x)}^y \vartheta_{\Phi}^i(x, \eta) d\eta \right| \leq \text{const}(1 + \kappa) \mathbf{A}(x^p + y^p) \quad (3.21)$$

(( $x, y$ )  $\in \mathcal{D}_*$ ), where  $\mathbf{A} = \max(A, B)$ . As a consequence of (3.3), (2.13), (3.20) and (3.21), we have

$$|\tilde{v}_i(x, y)| \leq \left[ (m_i a_i)^i m_i^{p-i} \kappa + \text{const}(1 + \kappa) \mathbf{A}^{\theta_i} \right] (x^p + y^p) \quad (3.22)$$

(( $x, y$ )  $\in \mathcal{D}_*$ ;  $i = 0, 1, \dots, p-1$ ). By a similar argument we show that (cp. (3.3))

$$|\tilde{w}_i(x, y)| \leq \left[ (\tilde{m}_i \tilde{a}_i)^i \tilde{m}_i^{p-i} \kappa + \text{const}(1 + \kappa) \mathbf{A}^{\theta_i} \right] (x^p + y^p) \quad (3.23)$$

(( $x, y$ )  $\in \mathcal{D}_*$ ;  $i = 0, 1, \dots, p-1$ ). It follows from (3.22) and (3.23) that the functions  $\tilde{v}_i$  and  $\tilde{w}_i$  satisfy relations (3.2) if the inequality

$$\max(m_i^p a_i^i, \tilde{m}_i^p \tilde{a}_i^i) \kappa + C(1 + \kappa) \mathbf{A}^{\theta} \leq \kappa \quad (3.24)$$

( $i = 0, 1, \dots, p-1$ ) is fulfilled, where  $\theta = \min_{0 \leq i \leq p-1} \theta_i$  and  $C$  is a positive constant independent of  $\kappa$ . It is evident (cp. (1.7)) that inequality (3.24) holds if  $\mathbf{A}$  is sufficiently small, so that

$$\mathbf{A} < \left\{ \frac{\kappa [1 - \max(m_i^p a_i^i, \tilde{m}_i^p \tilde{a}_i^i)]}{C(1 + \kappa)} \right\}^{1/\theta} \quad (3.25)$$

Moreover, by the definition of  $\mathcal{Z}$  and relations (2.7), (2.14) - (2.16), (3.3) and (3.24), we can assert that  $\tilde{v}_i$  and  $\tilde{w}_i$  ( $i = 0, 1, \dots, p-1$ ) are continuous in  $\mathcal{D}_*$ . Thus, inequality (3.25) implies the inclusion  $\mathbf{T}(\mathcal{Z}) \subset \mathcal{Z}$ .

Now, assuming the validity of (3.25), we shall find sufficient conditions under which the transformation  $\mathbf{T}$  (cf. (3.3)) is a contraction.

Let  $\Phi = (V, W)$  and  $\bar{\Phi} = (\bar{V}, \bar{W})$  be arbitrary points of  $\mathcal{Z}$ , and  $\tilde{\Phi} = (\tilde{V}, \tilde{W})$  and  $\hat{\Phi} = (\hat{V}, \hat{W})$  their images, respectively, in the transformation  $\mathbf{T}$ . In order to estimate the expression  $|\tilde{v}_i - \hat{v}_i|$ , let us observe that by (1.8), (2.10) and (3.1) the following inequalities are valid (cf. (3.4)):

$$\begin{aligned} & \left| {}^1\lambda_{\Phi}^{rs}[x, f_i(x)] - {}^1\lambda_{\bar{\Phi}}^{rs}[x, f_i(x)] \right| \\ & \leq \int_0^x \frac{(x-\xi)^{p-s-1}}{(p-s-1)!} (\xi^p + (f_i(x))^p) d\xi \\ & \quad + \sum_{k=0}^{p-s-1} \int_0^{f_i(x)} \frac{(f_i(x)-\xi)^{p-r-1}}{(p-r-1)!} \eta^p d\eta \frac{x^k}{k!} d(\Phi, \bar{\Phi}) \tag{3.26} \\ & \leq \left[ x^{2p-s}(1 + (m_i a_i)^p) + x^{2p-r}(m_i a_i)^{2p-r} \sum_{k=0}^{p-s-1} \frac{A^k}{k!} \right] d(\Phi, \bar{\Phi}) \end{aligned}$$

( $r, s = 0, 1, \dots, p-1$ ), whence and from Assumptions I, III, IV, and relations (2.8), (2.11), (2.12) we obtain (cf. (3.7))

$$|\hat{G}_{\Phi}^i(x) - \hat{G}_{\bar{\Phi}}^i(x)| \leq \left[ (m_i a_i)^i m_i^{p-i} + \text{const } A^{\theta_i} \right] x^p d(\Phi, \bar{\Phi}) \tag{3.27}$$

( $x \in (0, A]; i = 0, 1, \dots, p-1$ ). Furthermore, basing on Assumptions I-IV and formulas (2.9), (2.13) and (3.26), we get the inequality

$$|\hat{G}_{\Phi}^i(x) - \hat{G}_{\bar{\Phi}}^i(x)| \leq \text{const } A^{\theta_i'''} x^p d(\Phi, \bar{\Phi}) \tag{3.28}$$

( $x \in (0, A]; i = 0, 1, \dots, p-1$ ), where  $\theta_i'''$  are as in (3.19). On joining (3.27) and (3.28) we have (cp. (2.7))

$$|\mathbf{G}_{\Phi}^i(x) - \mathbf{G}_{\bar{\Phi}}^i(x)| \leq \left[ (m_i a_i)^i m_i^{p-i} + \text{const } A^{\theta_i} \right] x^p d(\Phi, \bar{\Phi}) \tag{3.29}$$

( $x \in [0, A]; i = 0, 1, \dots, p-1$ ), where  $\theta_i$  are as in (3.20).

As for the second term in (2.3), we easily conclude that (cf. (3.21))

$$\left| \int_{f_i(x)}^y \sigma_{\Phi}^i(x, \eta) d\eta - \int_{f_i(x)}^y \sigma_{\bar{\Phi}}^i(x, \eta) d\eta \right| \leq \text{const } A(x^p + y^p) d(\Phi, \bar{\Phi}) \tag{3.30}$$

(( $x, y \in \mathcal{D}_{\bullet}$ ), whence, and from (2.7), (2.13), (3.3) and (3.29), we obtain

$$|\tilde{v}_i(x, y) - \hat{v}_i(x, y)| \leq \left[ (m_i a_i)^i m_i^{p-i} + \text{const } A^{\theta_i} \right] (x^p + y^p) d(\Phi, \bar{\Phi}) \tag{3.31}$$

(( $x, y \in \mathcal{D}_{\bullet}; i = 0, 1, \dots, p-1$ ). By a similar argument we show that

$$|\tilde{w}_i(x, y) - \hat{w}_i(x, y)| \leq \left[ (\tilde{m}_i \tilde{a}_i)^i \tilde{m}_i^{p-i} + \text{const } A^{\theta_i} \right] (x^p + y^p) d(\Phi, \bar{\Phi}) \tag{3.32}$$

$((x, y) \in \mathcal{D}_*$ ;  $i = 0, 1, \dots, p-1$ ), and using (3.1), (3.31) and (3.32) we can conclude that

$$d(\tilde{\Phi}, \bar{\Phi}) \leq \left[ \max((m_i a_i)^i m_i^{p-i}, (\tilde{m}_i \tilde{a}_i)^i \tilde{m}_i^{p-i}) + \text{const } \mathbf{A}^{\theta_i} \right] d(\Phi, \bar{\Phi}). \quad (3.33)$$

It follows from (3.33) that the transformation  $\mathbf{T}$  (see (3.3)) is a contraction if the inequality

$$\max((m_i a_i)^i m_i^{p-i}, (\tilde{m}_i \tilde{a}_i)^i \tilde{m}_i^{p-i}) + \tilde{C} \mathbf{A}^\theta < 1 \quad (3.34)$$

( $i = 0, 1, \dots, p-1$ ) is fulfilled, where  $\theta$  is as in (3.24) and  $\tilde{C}$  is a positive constant independent of  $\mathbf{A}$ . Evidently (cp. (1.7)), inequality (3.34) holds good if  $\mathbf{A}$  is so small that

$$\mathbf{A} < \left[ \frac{1 - \max(m_i^p a_i^i, \tilde{m}_i^p \tilde{a}_i^i)}{\tilde{C}} \right]^{1/\theta} \quad (3.35)$$

So, if inequalities (3.25) and (3.35) are fulfilled, then by the Banach fixed point theorem applied to the space  $\mathcal{Z}$  and transformation  $\mathbf{T}$ , there is a unique system  $\Phi^0 = (V^0, W^0) \in \mathcal{Z}$  satisfying the system of integral-functional equations (2.12) in  $\mathcal{D}_*$ . Setting

$$V^* = (v_r^*) \quad \text{where} \quad v_r^*(x, y) = \begin{cases} 0 & \text{for } x = y = 0 \\ v_r^0(x, y) & \text{for } (x, y) \in \mathcal{D}_* \end{cases}$$

and

$$W^* = (w_r^*) \quad \text{where} \quad w_r^*(x, y) = \begin{cases} 0 & \text{for } x = y = 0 \\ w_r^0(x, y) & \text{for } (x, y) \in \mathcal{D}_* \end{cases}$$

( $r = 0, 1, \dots, p-1$ ), we get a system  $\Phi^* = (V^*, W^*)$  of continuous functions satisfying (2.12) in  $\mathcal{D}$ . As a result (cp. Lemma 2.3), problem  $(\Sigma)$  has a unique solution  $z_{00}^* = {}^1\lambda_{\Phi^*}^{00} \in \mathcal{K}_1$  which, by the equivalence of problems  $(\mathcal{P})$  and  $(\Sigma)$ , is also a unique solution of problem  $(\mathcal{P})$ .

Thus, we can formulate the following final theorem.

**Theorem.** *If Assumptions I - IV are satisfied and  $\mathbf{A} = \max(A, B)$  is sufficiently small, so that inequalities (3.25) and (3.35) hold good, then problem  $(\mathcal{P})$  has a solution. This solution is unique in the class  $\mathcal{K}_1$ .*

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